

# Parcial I Señales y sistemas

Demostración

1-  $x(t) = 20 \sin(7t - \pi/2) - 3 \cos(5t) + 2 \cos(70t)$

Entrada:  $-3.3 \rightarrow 5$  [V]

B1: 5

$$-20 \cos(7t) - 3 \cos(5t) + 2 \cos(70t)$$

$$\omega_1 = 7 \quad T_1 = \frac{2\pi}{7} \rightarrow 7\pi \quad F_1 = 7/2\pi = 1.174 \text{ Hz}$$

$$\omega_2 = 5$$

$$\omega_3 = 10 \quad T_2 = \frac{2\pi}{5} \rightarrow 74\pi \quad F_2 = \frac{5}{2\pi} = 0.796 \text{ Hz}$$

$$T_3 = \frac{2\pi}{10} \rightarrow \pi/5 \rightarrow 7\pi \quad F_3 = \frac{10}{2\pi} = 1.592 \text{ Hz}$$

$$\text{Amplitud}_{\max} = 20 + 3 + 2 = 25$$

$$y = mx + b$$

$$f_{\max} = 2 \text{ max alto}$$

$$C = 0 \rightarrow \text{pendiente} = \frac{5 - (-3.3)}{25 - (-25)} = \frac{0.3}{50} \quad f_{\max} = 2 \left( \frac{10}{2\pi} \right) = \frac{10}{\pi} = 3.184 \text{ Hz}$$

$$-3.3 = \frac{0.3}{50} (-25) + b$$

$$\text{Intercepto} = \frac{77}{20} = b$$

$$0.166x(t) + 0.65 = v^c(t)$$

$$\frac{v^c(t) - (-3.3v)}{0.2594}$$

## Demonstración del punto 2

Se procede a realizar el cambio de la variable del tiempo dado la siguiente ecuación.

$$t = n/f_s$$

La señal para discretizarla

$$x[n/f_s] = 3 \cos[1000\pi(\frac{n}{f_s})] + 5 \sin[2000\pi(\frac{n}{f_s})] + 7 \cos - (17000\pi(\frac{n}{f_s}))$$

$$x[n/f_s] = 3 \cos[1000\pi(\frac{n}{5000})] + 5 \sin[2000\pi(\frac{n}{5000})] + 7 \cos - [17000\pi(\frac{n}{5000})]$$

$$x[n/f_s] = 3 \cos[\frac{\pi}{5}n] + 5 \sin[\frac{2\pi}{5}n] + 7 \cos[\frac{17\pi}{5000}n]$$

Para este último coseno su frecuencia no se halla en  $[-\pi, \pi]$ , lo que nos indica que es un alias y hace falta hallar la frecuencia original. Entonces se resta  $2\pi$  para dejarlo en el intervalo ( $\omega_0 = \omega_0' + k2\pi$ ).

$$\omega_3 = \frac{17\pi}{5} \notin [-\pi, \pi]$$

$$\omega_3 - 2\pi = \frac{17\pi}{5} - \frac{10\pi}{5} = \frac{\pi}{5}$$

Lo siguiente es volver a llamar esta frecuencia al coseno que consideramos, el cual quedaría con su frecuencia original de discretización.

$$x[n/f_s] = 3 \cos[\frac{\pi}{5}n] + 5 \sin[\frac{2\pi}{5}n] + 7 \cos[\frac{\pi}{5}n]$$

Quedó con la misma frecuencia angular que el primero se procede a sumarlos.

Se concluye que la señal obtenida en tiempo discreto por el conversor analógico digital es:

$$x[n/f_s] = 73 \cos[\frac{\pi}{5}n] + 5 \sin[\frac{2\pi}{5}n]$$

## Demonstración punto 3

Los intervalos de  $x_2(t)$ , se tiene que dividir la integral en 3 partes

$$\bar{P}x_1 - x_2 = \lim_{T \rightarrow \infty} \frac{1}{T} \left[ \int_0^{T/4} (A\cos(\omega t) - T)^2 dt + \int_{T/4}^{3T/4} (A\cos(\omega t) + T)^2 dt \right]$$

Utilizaremos factorización y los términos de cada una.

$$\begin{aligned} \bar{P}x_1 - x_2 &= \lim_{T \rightarrow \infty} \frac{1}{T} \left[ \int_0^{T/4} (A^2 \cos^2(\omega t) - 2A\cos(\omega t) + T^2) dt \right. \\ &\quad \left. + \int_{T/4}^{3T/4} (A^2 \cos^2(\omega t) + 2A\cos(\omega t) + T^2) dt \right. \\ &\quad \left. + \int_{3T/4}^T (A^2 \cos^2(\omega t) - 2A\cos(\omega t) + T^2) dt \right] \end{aligned}$$

Resolvemos primero para  $0 \leq t \leq T/4$

$$\int_0^{T/4} (A^2 \cos^2(\omega t) - 2A\cos(\omega t) + T^2) dt \rightarrow \cos^2(\omega t) = \frac{t + \cos(2\omega t)}{2}$$

$$A^2 \cos^2(\omega t) = \frac{A^2}{4} (2t + \cos(2\omega t))$$

$$\frac{A^2}{2} \int_0^{T/4} (2t + \cos(2\omega t)) dt = \frac{A^2}{2} \left[ t^2 + \frac{1}{2} \sin(2\omega t) \right]_0^{T/4} = \frac{A^2}{2} \left[ \left( \frac{T^2}{16} \right) + \frac{1}{2} \sin(\omega T) \right]$$



Separar la integral

$$\begin{aligned} \cdot \int_0^{T/4} I dt &= \boxed{\frac{T}{4}} \cdot \int_0^{T/4} \cos(2\omega_0 t) dt = \left[ \frac{\sin(2\omega_0 t)}{2\omega_0} \right]_0^{T/4} \\ &= \frac{I}{2\omega_0} (\sin(\frac{T}{2}\omega_0) - \sin(0)) = \frac{I}{2\omega_0} (\sin(\frac{T}{2} \cdot \frac{2\pi}{T}) - \sin(0)) \\ &= \boxed{0} \end{aligned}$$

$$\begin{aligned} \cdot \int_0^{T/4} \cos(\omega_0 t) dt &= \left[ \frac{\sin(\omega_0 t)}{\omega_0} \right]_0^{T/4} = \frac{I}{\omega_0} (\sin(\omega_0 \frac{T}{4}) \\ &- \sin(0)) = \frac{I}{\omega_0} (\sin(\frac{2\pi}{T} \cdot \frac{T}{4})) = \frac{I}{\omega_0} (\sin(\frac{\pi}{2})) = \frac{I}{\omega_0} \rightarrow \boxed{\frac{I}{2\pi}} \end{aligned}$$

$$\cdot \int_0^{T/4} 1 dt = \boxed{T/4}$$

Sustituir los términos

$$\frac{A^2}{2} \cdot \frac{I}{4} + \frac{A^2}{2} \cdot 0 - 2A \cdot \frac{I}{2\pi} + \frac{I}{4} = \boxed{\frac{A^2 T}{8} - \frac{AT}{\pi} + \frac{T}{4}}$$

Luego para  $T/4 \leq t \leq 3T/4$

$$\int_{T/4}^{3T/4} (A^2 \cos^2(\omega_0 t) + 2A \cos(\omega_0 t) \cdot 1) dt$$

$$\cdot \int_{T/4}^{3T/4} \cos^2(\omega_0 t) dt = T/4$$

$$\cdot \int_{T/4}^{3T/4} \cos(\omega_0 t) dt = \frac{I}{\omega_0} [\sin(\omega_0 t)]_{T/4}^{3T/4}$$

$$= \frac{I}{\omega_0} (\sin(3\pi/2) - \sin(\pi/2))$$

$$\frac{I}{\omega_0} (-T - T) = -\frac{2T}{2\pi}$$

$$I_2 = A^2 \cdot \frac{T}{4} - 2H \cdot \frac{T}{\pi} + \frac{T}{2},$$

se suman los resultados

$$\bar{P}_{x_1+x_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \left[ \left( \frac{A^2 T}{8} - \frac{4T}{\pi} + \frac{T}{4} \right) + \left( \frac{A^2 T}{4} - \frac{2AT}{\pi} + \frac{T}{2} \right) + \left( \frac{A^2}{4} + \frac{AT}{\pi} + \frac{T}{9} \right) \right]$$

$$\lim_{T \rightarrow \infty} \frac{T}{\pi} \left[ \frac{A^2 T}{2} - \frac{4T}{\pi} + \pi \right] = \boxed{\frac{A^2 T}{2} - \frac{4T}{\pi} + \pi}$$



## 4-7 Demostración

$$C_n = \frac{1}{T} \int_{t_i}^{t_F} x(t) e^{-jnw_0 t} dt \Rightarrow x(t) = \sum_n C_n e^{jnw_0 t}$$

$$x'(t) = \frac{d}{dt} x(t) = \frac{d}{dt} \left\{ \sum_n C_n e^{jnw_0 t} \right\} = \sum_n (n w_0) C_n e^{jnw_0 t}$$

$$x''(t) = \frac{d}{dt} \left\{ \sum_n (n w_0) C_n e^{jnw_0 t} \right\} = \sum_n (n w_0)^2 C_n e^{jnw_0 t}$$

$$\tilde{C}_n = \frac{\langle x''(t), e^{jnw_0 t} \rangle}{\| e^{jnw_0 t} \|_2^2} = \int_{t_i}^{t_F} \frac{x''(t) e^{-jnw_0 t} dt}{T}; T = t_F - t_i$$

$$\tilde{C}_n = (n w_0)^2 = \int_{t_i}^{t_F} \frac{x''(t) e^{-jnw_0 t} dt}{T}$$

$$C_n = \frac{1}{(t_F - t_i)(n^2 w_0^2)} \int_{t_i}^{t_F} x''(t) e^{-jnw_0 t} dt$$

$$= \frac{1}{(t_i - t_F)n^2 w_0^2} \int_{t_i}^{t_F} x''(t) e^{-jnw_0 t} dt$$

$$x(t) = a_0 + \sum_{n=1}^N a_n \cos(nw_0 t) + b_n \sin(nw_0 t)$$

$$x'(t) = \sum_{n=1}^N a_n (-nw_0) \sin(nw_0 t) + b_n (nw_0) \cos(nw_0 t)$$

$$x''(t) = \sum_{n=1}^N a_n (-nw_0)^2 \cos(nw_0 t) + b_n (-nw_0)^2 \sin(nw_0 t)$$

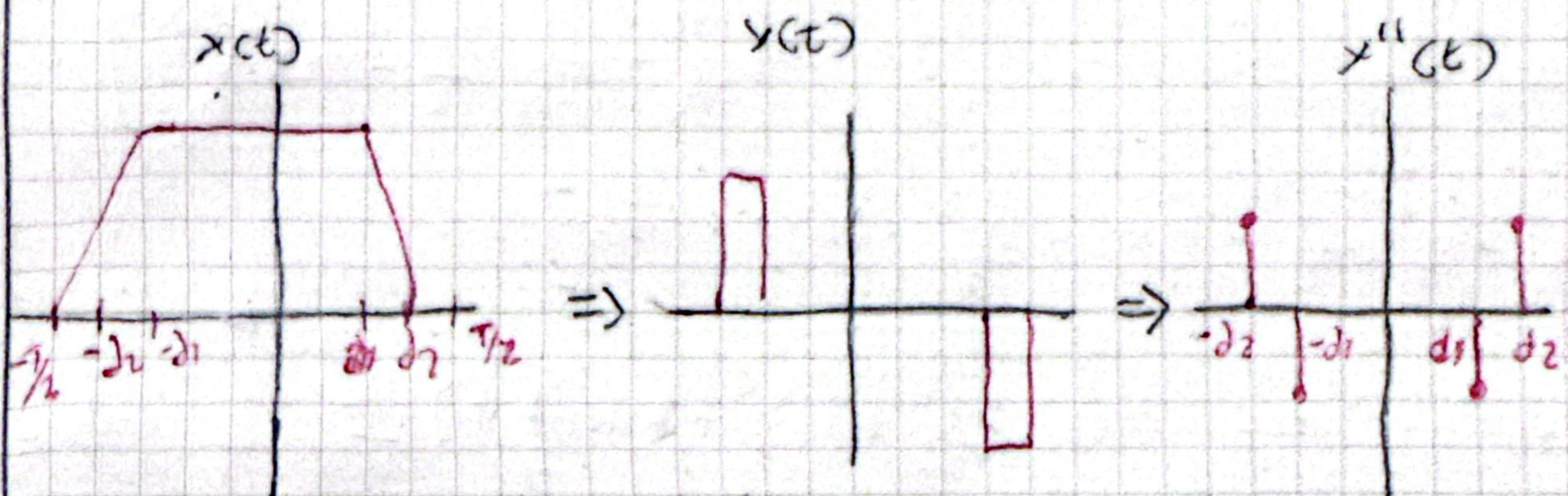
$$\tilde{a}_n = \frac{2}{T} \int_{t_i}^{t_F} x''(t) \cos(n\omega_0 t) dt; \quad \tilde{b}_n = \frac{2}{T} \int_{t_i}^{t_F} x''(t) \sin(n\omega_0 t) dt$$

$$a_n(-n^2\omega_0^2) = \frac{2}{T} \int_{t_i}^{t_F} x''(t) \cos(n\omega_0 t) dt$$

$$a_n = \frac{2}{-T n^2 \omega_0^2} \int_{t_i}^{t_F} x''(t) \cos(n\omega_0 t) dt$$

$$\tilde{b}_n(-n^2\omega_0^2) = \frac{2}{T} \int_{t_i}^{t_F} x''(t) \sin(n\omega_0 t) dt$$

$$b_n = \frac{2}{T n^2 \omega_0^2} \int_{t_i}^{t_F} x''(t) \sin(n\omega_0 t) dt$$



$$x''(t) = A\delta(t+d_2) - A\delta(t+d_1) - A\delta(t-d_1) + A\delta(t-d_2)$$

$$c_n = \frac{1}{-T n^2 \omega_0^2} \int_{-T/2}^{T/2} A[\delta(t+d_2) - \delta(t+d_1) - \delta(t-d_1) + \delta(t-d_2)] e^{-jn\omega_0 t} dt$$

$$c_n = -\frac{A}{T n^2 \omega_0^2} (e^{jn\omega_0 d_2} + e^{-jn\omega_0 d_2} - e^{jn\omega_0 d_1} - e^{-jn\omega_0 d_1})$$

$$C_n = -\frac{A}{\pi n^2 \omega_0^2} (2\cos(n\omega_0 t) - 2\cos(n\omega_0 t)) = -\frac{2A}{\pi n^2 4\pi^2}$$

$$C \cos(Cn \frac{2\pi}{T} \delta_c) - \cos(Cn \frac{2\pi}{T} \delta_i))$$

$$C_n = -\frac{A}{\frac{2\pi n^2}{T}} (\cos(Cn \frac{2\pi}{T} \delta_c) - \cos(Cn \frac{2\pi}{T} \delta_i))$$

$$C_0 = \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt = \frac{1}{T} \int_{-\delta_2}^{-\delta_1} \frac{A}{\delta_2 - \delta_1} (t + \delta_2) dt + \frac{1}{T} \int_{\delta_1}^{\delta_2} -\frac{A}{\delta_2 - \delta_1} (e^{-\alpha t}) dt$$

$$= \frac{1}{T} \left[ \frac{A}{\delta_2 - \delta_1} \left( \frac{t^2}{2} + \delta_2 t \right) \left[ \frac{\delta_1}{\delta_2} + A t \left[ \frac{\delta_1}{\delta_1} - \frac{A}{\delta_2 - \delta_1} \left( \frac{t^2}{2} - \delta_2 t \right) \right] \right] \right]$$

$$= \frac{1}{T} \left[ \frac{A}{\delta_2 - \delta_1} \left( \frac{\delta_1^2}{2} - \delta_1 \delta_2 - \frac{\delta_2^2}{2} + \delta_2^2 \right) + 2A\delta_1 \right]$$

$$\frac{1}{T} \left[ \frac{A}{\delta_2 - \delta_1} \left( \frac{\delta_1^2}{2} - \delta_1 \delta_2 - \frac{\delta_2^2}{2} + \delta_2^2 \right) + iA(\delta_1 + \delta_2) - \frac{A}{\delta_2 - \delta_1} \left( \frac{\delta_2^2}{2} - \delta_2 \delta_1 - \frac{\delta_1^2}{2} + \delta_1 \delta_2 \right) \right]$$

$$\text{Si: } A=7 \quad \delta_1=7 \quad \delta_2=2 \quad y T=2\delta_2=4$$

$$C_n = -\frac{1}{\frac{7\pi^2 n^2}{4\pi^2}} (\cos(Cn \cdot \frac{T\pi}{4} \cdot t) - \cos(Cn \frac{2\pi}{T} \cdot t))$$

$$= -\frac{1}{\frac{\pi^2 n^2}{2}} (\cos(Cn\pi) - \cos(Cn \frac{\pi}{2}))$$

$$G_0 = \frac{1}{4} \left[ -\frac{2+7}{7} \left( \frac{1}{2} - 2 - 2 + 4 \right) + 2 \cdot 1 \cdot 1 \right] = \frac{1}{4} \left[ 2 \left( \frac{3}{2} \right) + 2 \right] \\ = \frac{1}{4} \cdot 3 = \frac{3}{4}$$

$$P_X = \frac{1}{4} \int_{-\pi/2}^{\pi/2} (x(\epsilon))'^2 d\epsilon = \frac{2}{7} \int_{-\pi/2}^0 (x(\epsilon))'^2 d\epsilon \\ = \frac{2}{7} \cdot \int_{-\delta_2}^{-\delta_1} \left( \frac{A}{\delta_2 \delta_1} \right)^2 (\epsilon + \delta_2)^2 d\epsilon$$

$$\times \frac{2}{7} \int_{-\delta_1}^0 A^2 d\epsilon \Rightarrow P_X = \frac{2}{7} \left( \frac{A}{\delta_2 \delta_1} \right)^2 (\epsilon^2 + 2\epsilon \delta_2 + \delta_2^2) \Big|_{-\delta_2}^{\delta_1}$$

$$+ \frac{2}{7} A^2 \epsilon \Big|_{-\delta_1}^0$$

$$P_X = \frac{2}{7} \left( \frac{A}{\delta_2 \delta_1} \right)^2 (\delta_1^2 -$$

