CPE 400: Software Defined Network 1.00

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Contents

1	CPE	400			1
2	Hier	archical	Index		5
	2.1	Class I	Hierarchy		5
3	Clas	s Index			7
	3.1	Class I	_ist		7
4	File	Index			9
	4.1	File Lis	st		9
5	Clas	s Docu	mentation	1	11
	5.1	Centra	lCompute	Node Class Reference	11
		5.1.1	Detailed	Description	12
		5.1.2	Construc	ctor & Destructor Documentation	12
			5.1.2.1	CentralComputeNode()	12
			5.1.2.2	~CentralComputeNode()	12
		5.1.3	Member	Function Documentation	12
			5.1.3.1	buildSubnetToIndexTable()	12
			5.1.3.2	changeRoad()	13
			5.1.3.3	computeRoute()	13
			5.1.3.4	directTraffic()	14
			5.1.3.5	getMapIndex()	14
			5.1.3.6	joinNetwork()	14
			E 1 0 7	logueNotwork()	15

ii CONTENTS

		5.1.3.8	queueJob()	15
		5.1.3.9	setMap()	16
		5.1.3.10	setSubnetProperties()	16
5.2	Job St	ruct Refere	ence	16
	5.2.1	Detailed	Description	17
	5.2.2	Construc	tor & Destructor Documentation	17
		5.2.2.1	Job()	17
		5.2.2.2	~Job()	17
5.3	Route	Struct Refe	erence	18
	5.3.1	Detailed	Description	18
	5.3.2	Construc	tor & Destructor Documentation	18
		5.3.2.1	Route()	18
		5.3.2.2	~Route()	19
5.4	Threac	dSafeObjec	ct Class Reference	19
	5.4.1	Detailed	Description	19
5.5	Vehicle	e Class Re	ference	20
	5.5.1	Detailed	Description	21
	5.5.2	Construc	tor & Destructor Documentation	21
		5.5.2.1	Vehicle() [1/3]	21
		5.5.2.2	Vehicle() [2/3]	21
		5.5.2.3	Vehicle() [3/3]	22
		5.5.2.4	\sim Vehicle()	22
	5.5.3	Member	Function Documentation	22
		5.5.3.1	clearRoute()	22
		5.5.3.2	getDest()	23
		5.5.3.3	getID()	23
		5.5.3.4	getNextDestination()	23
		5.5.3.5	getSource()	23
		5.5.3.6	getTotalTime()	24
		5.5.3.7	getTravelTime()	24
		5.5.3.8	hasNode()	24
		5.5.3.9	hasRoute()	24
		5.5.3.10	requestRoute()	25
		5.5.3.11	setDepartTime()	25
		5.5.3.12	setRoute()	25
		5.5.3.13	setStartTime()	26
		5.5.3.14	timeRemainingToNextDestination()	26
		5.5.3.15	tryRoadChange()	26

CONTENTS

6	File	e Documentation 29		29
	6.1	Centra	IComputeNode.cpp File Reference	29
		6.1.1	Detailed Description	29
		6.1.2	Function Documentation	30
			6.1.2.1 GetCheapestNode()	30
	6.2	Centra	IComputeNode.h File Reference	30
		6.2.1	Detailed Description	31
	6.3	main.c	pp File Reference	31
		6.3.1	Detailed Description	32
		6.3.2	Function Documentation	32
			6.3.2.1 Car()	32
			6.3.2.2 ComputeNode()	32
			6.3.2.3 EndSimulator()	33
			6.3.2.4 FetchInput()	33
			6.3.2.5 RunSimulator()	33
			6.3.2.6 WaitFor()	35
	6.4	Thread	SafeObject.cpp File Reference	35
		6.4.1	Detailed Description	35
	6.5	Thread	JSafeObject.h File Reference	35
		6.5.1	Detailed Description	36
	6.6	Vehicle	e.cpp File Reference	36
		6.6.1	Detailed Description	36
	6.7	Vehicle	e.h File Reference	36
		6.7.1	Detailed Description	37
Inc	dex			39

Chapter 1

CPE400

A repository for the CPE400 Networking Programming Project
Building and Running on Linux
Building:
make
Running:
./SDN Input.txt
Cleaning:
make clean
Network Structure
Vehicles
Each vehicle on the network is an abstraction of a network packet. This allows each one to hold and share only basic information, such as identification, source, and destination addresses. The majority of routing of these packets

is therefore completed by the intersection routers. The amount of time spend between each node is recorded by the packet, which is then read by the router and passed to the central device. This information helps the Central Node

determine wait times at each individual node; this in turn allows it to scale and reroute packets accordingly.

Class Vehicle:

2 CPE400

* Methods:

- * Constructor
- * Parameterized Constructor
- * Destructor
- * Set Start Time
- * Set Depart Time
- * Get Travel Time
- * Get Total Time
- * Get Next Destination
- * Time Remaining To Next Destination
- * Clear Route
- * Has Route
- * Has Node
- * Get ID
- * Get Source
- * Get Dest
- * Request Route
- * Set Route
- * Try Road Change
- * Get Lock
- * Release Lock

* Properties:

- * Device id
- * Source address
- * Dest address
- * Travel Time
- * Total Time
- * Travel Time Left
- * Route (a list of subnets to traverse)
- * Route Requested
- * mutex

Central Compute Node

The central compute node is responsible for routing all traffic.

Class CentralComputeNode:

- * Methods:
 - * Constructor
 - * Destructor
 - * Build Subnet To Index Table
 - * Get Map Index
 - * Set Map
 - * Set Subnet Properties
 - * Queue Job
 - * Compute Route
 - * Direct Traffic
 - * Join Network
 - * Leave Network
 - * Change Road
 - * Get Lock * Release Lock
 - * AStar
 - * Reconstruct Path
 - * Expand Node
- * Properties:
 - \star Vehicle ID to Vehicle Object (the abstracted "route" to that vehicle)
 - * Subnet Capacity
 - * Vehicles at each subnet (map)
 - * City Map (adjacency matrix)
 - * Subnet To Index Table
 - * Jobs (a queue of routes to be computed)
 - * mutex

Input Structure

The structure of the input file is fairly straight forward. Each object on the network has its own keyword that is recognized by the program:

· Car:

- This keyword is used to specify a vehicle on the network.
- car car-name source destination

· Intersect:

- The intersection command specified a node within the network.
- The command must contain an intersect name, as well as the maximum capacity of the node.
- intersect intersect-name capacity

· Neighbor:

- The neighbor keyword details a neighbor node to the preceding intersect.
- The referenced neighbor node can be detailed either through a direct reference to the object, or by its index.
- Along with a reference to the neighbor node, the length of time between the nodes must also be specified.
- neighbor [node-index]|node-title timespan

The input file also allows for the use of comments, which begin with '#' at the beginning of the comment.

1 CPE400

Chapter 2

Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

Job	1
Route	1
ThreadSafeObject	1
CentralComputeNode	1
Vehicle	2

6 Hierarchical Index

Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

CentralComputeNode

	The centralized compute node for the entire network	-11
Job		
	Request structure passed to the Compute Node	16
Route		
	Route object that contains a clear path between nodes	18
ThreadS	SafeObject	
	Inherited by others to allow for objects to lock their resources between threads	19
Vehicle		
	This class represents the vehicles that make up the network of the SDN	20

8 Class Index

Chapter 4

File Index

4.1 File List

Here is a list of all documented files with brief descriptions:

CentralComputeNode.cpp	
Implementation file for the CentralComputeNode class	29
CentralComputeNode.h	
Definition file for the CentralComputeNode class	30
main.cpp	
Main processing file for the Software Defined Network simulator	31
ThreadSafeObject.cpp	
Implementation file for the ThreadSafeObject class	35
ThreadSafeObject.h	
Definition file for the ThreadSafeObject class	35
Vehicle.cpp	
Implementation file for the Vehicle class	36
Vehicle.h	
Definition file for the Vehicle class	36

10 File Index

Chapter 5

Class Documentation

5.1 CentralComputeNode Class Reference

The centralized compute node for the entire network.

#include "CentralComputeNode.h"

Inheritance diagram for CentralComputeNode:



Public Member Functions

• CentralComputeNode ()

Default constructor.

∼CentralComputeNode ()

Default destructor.

void buildSubnetToIndexTable (std::vector< std::string > &subnets)

Populates the subnetToIndexTable.

• int getMapIndex (const std::string &name)

Returns index of ID.

void setMap (std::vector< std::vector< double > > &map)

Assign new map to object.

void setSubnetProperties (std::string &name, int capacity)

Assign properties to submet.

• void queueJob (Job &job)

Adds a new job.

• bool computeRoute (Route &route)

Computes route.

void directTraffic (std::atomic bool &running)

Process waiting jobs for routes.

void joinNetwork (Vehicle *vehicle)

Add vehicle to network.

• void leaveNetwork (const std::string &id, const std::string &lastNode)

Allow Vehicle to leave network.

• bool changeRoad (std::string &id, std::string ¤tRoad, std::string &newRoad)

Changes current road of vehicle.

5.1.1 Detailed Description

The centralized compute node for the entire network.

The CentralComputeNode class is the central computer of the network. It manages all incoming requests to it, and updates routes according to network conditions.

5.1.2 Constructor & Destructor Documentation

```
5.1.2.1 CentralComputeNode()
```

```
CentralComputeNode::CentralComputeNode ( )
```

Default constructor.

Constructs an empty CentralComputeNode object

Note

None

5.1.2.2 ∼CentralComputeNode()

```
CentralComputeNode::~CentralComputeNode ( )
```

Default destructor.

Destroys a CentralComputeNode object

Note

None

5.1.3 Member Function Documentation

5.1.3.1 buildSubnetToIndexTable()

```
void CentralComputeNode::buildSubnetToIndexTable ( std::vector < std::string > \& subnets \;)
```

Populates the subnetToIndexTable.

Associates an index value to each subnet ID.

Parameters

in	subnets	Vector of subnet IDS to assign
----	---------	--------------------------------

Note

None

5.1.3.2 changeRoad()

Changes current road of vehicle.

Determines whether to allow Vehicle to change road, and if so, update vehicle location and count, else return false

Parameters

in	id	vehicle ID
in	currentRoad	road vehicle is currently on
in	newRoad	road vehicle is requesting to switch to

Note

None

5.1.3.3 computeRoute()

Computes route.

Computes the best route from start to end, and returns it

Parameters

out	route	route to be computed and returned

Note

None

5.1.3.4 directTraffic()

Process waiting jobs for routes.

Processes all pending jobs in the queue, and if there are no vehicles present on the network, end the simulator.

Parameters

Note

None

5.1.3.5 getMapIndex()

Returns index of ID.

Gets and returns the associated index to the ID provided

Parameters

```
in name ID to be searched for
```

Note

None

5.1.3.6 joinNetwork()

Add vehicle to network.

Appends vehicle to the vehicle map

Parameters

in vehicle Vehicle to add to the ne	work
-------------------------------------	------

Note

None

5.1.3.7 leaveNetwork()

Allow Vehicle to leave network.

Removes vehicle ID from network

Parameters

in	id	ID of vehicle to remove
in	lastNode	last known node vehicle is at

Note

None

5.1.3.8 queueJob()

Adds a new job.

Appends a new job to the end of the queue

Parameters

in	job	job to be appended
----	-----	--------------------

Note

None

5.1.3.9 setMap()

```
void CentralComputeNode::setMap ( {\tt std::vector} < {\tt std::vector} < {\tt double} \ > \ \& \ {\tt map} \ )
```

Assign new map to object.

Set a new city map within the object

Parameters

in	тар	vector of vector of doubles that detail the distance from each node in the map
----	-----	--

Note

None

5.1.3.10 setSubnetProperties()

Assign properties to submet.

Sets the subnet capacity specified by name

Parameters

in	name	ID to be searched for
in	capacity	capacity of the subnet to assign

Note

None

The documentation for this class was generated from the following files:

- CentralComputeNode.h
- CentralComputeNode.cpp

5.2 Job Struct Reference

Request structure passed to the Compute Node.

#include <CentralComputeNode.h>

5.2 Job Struct Reference 17

Public Member Functions

• Job ()

Default job constructor.

• ~Job ()

Default job desructor.

Public Attributes

- std::string start
- std::string dest
- std::string id

5.2.1 Detailed Description

Request structure passed to the Compute Node.

Object that is passed by Vehicles to the Compute Node to be processed.

5.2.2 Constructor & Destructor Documentation

```
5.2.2.1 Job()
```

Job::Job ()

Default job constructor.

Constructs a job object

Note

None

```
5.2.2.2 \simJob()
```

 $Job::\sim Job$ ()

Default job desructor.

Destroys job object

Note

None

The documentation for this struct was generated from the following files:

- CentralComputeNode.h
- CentralComputeNode.cpp

5.3 Route Struct Reference

Route object that contains a clear path between nodes.

```
#include <CentralComputeNode.h>
```

Public Member Functions

• Route ()

Route default constructor.

• ∼Route ()

Default route destructor.

Public Attributes

- std::string start
- std::string dest
- std::list< std::pair< std::string, double >> route

5.3.1 Detailed Description

Route object that contains a clear path between nodes.

This object holds both a starting and end node, with a route that is computed by the Compute Node.

5.3.2 Constructor & Destructor Documentation

5.3.2.1 Route()

Route::Route ()

Route default constructor.

Initializes route object

Note

None

```
5.3.2.2 ∼Route()
```

Route::~Route ()

Default route destructor.

Destroys route object

Note

None

The documentation for this struct was generated from the following files:

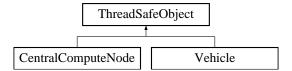
- · CentralComputeNode.h
- · CentralComputeNode.cpp

5.4 ThreadSafeObject Class Reference

The ThreadSafeObject class is inherited by others to allow for objects to lock their resources between threads.

```
#include "ThreadSafeObject.h"
```

Inheritance diagram for ThreadSafeObject:



Public Member Functions

- void getLock ()
- void releaseLock ()

5.4.1 Detailed Description

The ThreadSafeObject class is inherited by others to allow for objects to lock their resources between threads.

This class provides two methods, one to lock the resource, and one to release it.

The documentation for this class was generated from the following files:

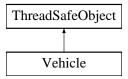
- · ThreadSafeObject.h
- ThreadSafeObject.cpp

5.5 Vehicle Class Reference

This class represents the vehicles that make up the network of the SDN.

```
#include "Vehicle.h"
```

Inheritance diagram for Vehicle:



Public Member Functions

• Vehicle ()

Default constructor.

• Vehicle (std::string newID, std::string newSource, std::string newDest)

Vehicle Constructor.

Vehicle (const Vehicle &other)

Vehicle Copy Constructor.

∼Vehicle ()

Vehicle destructor.

void setStartTime ()

Sets the time the vehicle begins its journey.

void setDepartTime ()

Set the depart time of the vehicle.

std::chrono::duration< double > getTravelTime () const

Get the current travel time between nodes.

std::chrono::duration< double > getTotalTime () const

Get the total travel time.

• std::string getNextDestination () const

Get the next vehicle destination.

bool timeRemainingToNextDestination () const

Shows whether the vehicle has arrived at a node.

• void clearRoute ()

Clears the vehicle route.

• bool hasRoute () const

Show whether the vehicle has a route.

• bool hasNode (const std::string &node) const

Determine whether vehicle is traveling to node.

· std::string getID ()

Get Vehicle ID.

std::string getSource ()

Get the source.

• std::string getDest ()

Get the destination.

void requestRoute (CentralComputeNode &ccn)

Request a new route from ccn.

void setRoute (std::list< std::pair< std::string, double >> newRoute)

Sets the vehicle route.

bool tryRoadChange (CentralComputeNode &ccn)

Try to do a road change.

5.5.1 Detailed Description

This class represents the vehicles that make up the network of the SDN.

Each Vehicle is able to navigate between nodes from start to finish along a route precomputed for it by the Compute Node.

5.5.2 Constructor & Destructor Documentation

```
5.5.2.1 Vehicle() [1/3] Vehicle::Vehicle ( )
```

Default constructor.

Constructs Vehicle object

Note

None

5.5.2.2 Vehicle() [2/3]

```
Vehicle::Vehicle (
          std::string newID,
          std::string newSource,
          std::string newDest )
```

Vehicle Constructor.

Constructs vehicle object with the specified values

Parameters

in	newID	id to assign to object
in	newSource	source of the new object
in	newDest	destination of the new object

Note

None

```
5.5.2.3 Vehicle() [3/3]
```

Vehicle Copy Constructor.

Create a copy of the passed vehicle object

Parameters

in	other	Vehicle to make a copy of
----	-------	---------------------------

Note

None

5.5.2.4 \sim Vehicle()

```
Vehicle::~Vehicle ( )
```

Vehicle destructor.

Destroys vehicle object and data within

Note

None

5.5.3 Member Function Documentation

```
5.5.3.1 clearRoute()
```

```
void Vehicle::clearRoute ( )
```

Clears the vehicle route.

Deletes the current vehicle route

Note

None

```
5.5.3.2 getDest()
std::string Vehicle::getDest ( )
Get the destination.
Returns where the vehicle is going
Note
     None
5.5.3.3 getID()
std::string Vehicle::getID ( )
Get Vehicle ID.
Returns the vehicle ID
Note
     None
5.5.3.4 getNextDestination()
std::string Vehicle::getNextDestination ( ) const
Get the next vehicle destination.
Returns the next route node if not null
Note
     None
5.5.3.5 getSource()
std::string Vehicle::getSource ( )
Get the source.
Returns where the vehicle began from
Note
     None
```

5.5.3.6 getTotalTime()

```
std::chrono::duration< double > Vehicle::getTotalTime ( ) const
```

Get the total travel time.

Returns the totalTime

Note

None

5.5.3.7 getTravelTime()

```
std::chrono::duration< double > Vehicle::getTravelTime ( ) const
```

Get the current travel time between nodes.

Returns the difference between now and the travelTime

Note

None

5.5.3.8 hasNode()

Determine whether vehicle is traveling to node.

Returns whether the node is within the vehicle route

Parameters

in	node	node to search for in the route

Note

None

5.5.3.9 hasRoute()

```
bool Vehicle::hasRoute ( ) const
```

Show whether the vehicle has a route.

Returns if route is null

Note

None

5.5.3.10 requestRoute()

Request a new route from ccn.

Send a job request to ccn to set a new route

Parameters

in	ccn	Central compute node
----	-----	----------------------

Note

None

5.5.3.11 setDepartTime()

```
void Vehicle::setDepartTime ( )
```

Set the depart time of the vehicle.

Sets the travel time to the current time

Note

None

5.5.3.12 setRoute()

Sets the vehicle route.

Sets the route object to the new route

Parameters

in newRoute new route to set the data

Note

None

5.5.3.13 setStartTime()

```
void Vehicle::setStartTime ( )
```

Sets the time the vehicle begins its journey.

Sets the total time to the current time

Note

None

5.5.3.14 timeRemainingToNextDestination()

```
bool Vehicle::timeRemainingToNextDestination ( ) const
```

Shows whether the vehicle has arrived at a node.

Returns whether the travel time is less than the time left

Note

None

5.5.3.15 tryRoadChange()

Try to do a road change.

If the object can change its current road do so, else wait

Parameters

in	ccn	Central compute node to send requests to	1
----	-----	--	---

Note

None

The documentation for this class was generated from the following files:

- Vehicle.h
- Vehicle.cpp

Chapter 6

File Documentation

6.1 CentralComputeNode.cpp File Reference

Implementation file for the CentralComputeNode class.

```
#include "CentralComputeNode.h"
#include <atomic>
```

Macros

• #define **_INFINITY** 9999999

Functions

template<typename Type >
bool GetCheapestNode (std::unordered_set< Type > &set, std::map< Type, double > &fScore, Type &lowest)

Finds the cheapest node.

6.1.1 Detailed Description

Implementation file for the CentralComputeNode class.

Author

Andrew Frost, Richard Millar

Version

1.00

30 File Documentation

6.1.2 Function Documentation

6.1.2.1 GetCheapestNode()

Finds the cheapest node.

Scans the opened set to find the least f-score node.

Parameters

in	set	set to be scanned for node
in	fScore	map of node IDs and associated f-scores
out	lowest	Cheapest node found

Note

None

6.2 CentralComputeNode.h File Reference

Definition file for the CentralComputeNode class.

```
#include <unordered_set>
#include <vector>
#include <list>
#include <map>
#include <string>
#include <atomic>
#include "Vehicle.h"
#include "ThreadSafeObject.h"
```

Classes

• class CentralComputeNode

The centralized compute node for the entire network.

struct Job

Request structure passed to the Compute Node.

• struct Route

Route object that contains a clear path between nodes.

6.2.1 Detailed Description

Definition file for the CentralComputeNode class.

Author

Andrew Frost, Richard Millar

Version

1.00

6.3 main.cpp File Reference

Main processing file for the Software Defined Network simulator.

```
#include <iostream>
#include <fstream>
#include <sstream>
#include <cstdlib>
#include <chrono>
#include <thread>
#include <atomic>
#include <functional>
#include <vector>
#include <string>
#include "ThreadSafeObject.h"
#include "Vehicle.h"
#include "CentralComputeNode.h"
```

Functions

- bool FetchInput (const char *fileName, CentralComputeNode &ccn, std::vector< Vehicle > &cars)
 Process input file.
- void RunSimulator (CentralComputeNode &ccn, std::vector< Vehicle > &vehicles)

Run the simulator until end.

void EndSimulator (std::vector< std::thread > &simulatorThreads)

End the simulator.

void WaitFor (long long timeMS)

Wait for a specified time.

void ComputeNode (CentralComputeNode &ccn, std::atomic_bool &running, ThreadSafeObject &console ← Lock)

Begins the compute node processing.

void Car (CentralComputeNode &ccn, std::atomic_bool &running, ThreadSafeObject &consoleLock, Vehicle car, long long timeStep)

Operations done by each Vehicle object.

int main (int argc, char *argv[])

32 File Documentation

6.3.1 Detailed Description

Main processing file for the Software Defined Network simulator.

Takes in user input file and starts the simulator, processing each vehicle route until all are finished

Author

Andrew Frost, Richard Millar

Version

1.00

6.3.2 Function Documentation

6.3.2.1 Car()

Operations done by each Vehicle object.

This function runs the car and all its operations.

Parameters

in	ccn	central compute node
in	running	flag to show simulator is running
in	consoleLock	lock for the console output
in	car	main thread object
in	timeStep	time from beginning of sim to start of car

6.3.2.2 ComputeNode()

Begins the compute node processing.

Runs the compute node and checks for open jobs periodically

Parameters

in	ccn	Main compute node of simulator
in	running	flag to show that the simulator is running
in	consoleLock	Lock assigned to the console for output

6.3.2.3 EndSimulator()

```
void EndSimulator ( {\tt std::vector} < {\tt std::thread} > {\tt \& \it simulatorThreads} \ )
```

End the simulator.

Wait for each thread to join

Parameters

	in	simulatorThreads	list of threads
--	----	------------------	-----------------

6.3.2.4 FetchInput()

Process input file.

Parses out input file and places the data into the compute node

Parameters

in	fileName	file to parse
in	ccn	Central node
in	cars	List of vehicles

6.3.2.5 RunSimulator()

34 File Documentation

Run the simulator until end.

Initializes the simulator by launching the vehicle threads and starting the compute node.

Parameters

in	ccn	Compute Node of the simulator
in	vehicles	List of vehicles in the simulator

6.3.2.6 WaitFor()

```
void WaitFor ( long\ long\ timeMS\ )
```

Wait for a specified time.

puts the current thread to sleep

Parameters

in	timeMS	time period to wait in milliseconds
----	--------	-------------------------------------

6.4 ThreadSafeObject.cpp File Reference

Implementation file for the ThreadSafeObject class.

```
#include "ThreadSafeObject.h"
```

6.4.1 Detailed Description

Implementation file for the ThreadSafeObject class.

Author

Andrew Frost, Richard Millar

Version

1.00

6.5 ThreadSafeObject.h File Reference

Definition file for the ThreadSafeObject class.

```
#include <mutex>
```

36 File Documentation

Classes

• class ThreadSafeObject

The ThreadSafeObject class is inherited by others to allow for objects to lock their resources between threads.

Typedefs

• using Lock = std::unique_lock < std::mutex >

6.5.1 Detailed Description

Definition file for the ThreadSafeObject class.

Author

Andrew Frost, Richard Millar

Version

1.00

6.6 Vehicle.cpp File Reference

Implementation file for the Vehicle class.

```
#include "Vehicle.h"
#include "CentralComputeNode.h"
```

6.6.1 Detailed Description

Implementation file for the Vehicle class.

Author

Andrew Frost, Richard Millar

Version

1.00

6.7 Vehicle.h File Reference

Definition file for the Vehicle class.

```
#include <list>
#include <string>
#include <chrono>
#include "ThreadSafeObject.h"
#include "CentralComputeNode.h"
```

37

Classes

• class Vehicle

This class represents the vehicles that make up the network of the SDN.

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38 File Documentation

Index

\sim CentralComputeNode	Vehicle, 22
CentralComputeNode, 12	getID
~Job	Vehicle, 23
Job, 17	getMapIndex
\sim Route	CentralComputeNode, 14
Route, 18	getNextDestination
\sim Vehicle	Vehicle, 23
Vehicle, 22	getSource
	Vehicle, 23
buildSubnetToIndexTable	getTotalTime
CentralComputeNode, 12	Vehicle, 23
	getTravelTime
Car	Vehicle, 24
main.cpp, 32	
CentralComputeNode, 11	hasNode
~CentralComputeNode, 12	Vehicle, 24
buildSubnetToIndexTable, 12	hasRoute
CentralComputeNode, 12	Vehicle, 24
changeRoad, 13	
computeRoute, 13	Job, 16
directTraffic, 14	\sim Job, 17
getMapIndex, 14	Job, 17
joinNetwork, 14	joinNetwork
leaveNetwork, 15	CentralComputeNode, 14
queueJob, 15	
setMap, 15	leaveNetwork
setSubnetProperties, 16	CentralComputeNode, 15
CentralComputeNode.cpp, 29	main ann 01
GetCheapestNode, 30	main.cpp, 31
CentralComputeNode.h, 30	Carry table do 20
changeRoad	ComputeNode, 32
CentralComputeNode, 13	EndSimulator, 33
clearRoute	FetchInput, 33
Vehicle, 22	RunSimulator, 33
ComputeNode	WaitFor, 35
main.cpp, 32	queueJob
computeRoute	CentralComputeNode, 15
CentralComputeNode, 13	Gentral Computer vode, 13
V T. (f)	requestRoute
directTraffic	Vehicle, 25
CentralComputeNode, 14	Route, 18
EndSimulator	∼Route, 18
	Route, 18
main.cpp, 33	RunSimulator
FetchInput	main.cpp, 33
main.cpp, 33	
	setDepartTime
GetCheapestNode	Vehicle, 25
CentralComputeNode.cpp, 30	setMap
aetDest	CentralComputeNode, 15

40 INDEX

```
setRoute
     Vehicle, 25
setStartTime
    Vehicle, 26
setSubnetProperties
    CentralComputeNode, 16
ThreadSafeObject, 19
ThreadSafeObject.cpp, 35
ThreadSafeObject.h, 35
timeRemainingToNextDestination
     Vehicle, 26
tryRoadChange
     Vehicle, 26
Vehicle, 20
     \sim Vehicle, 22
    clearRoute, 22
    getDest, 22
    getID, 23
    getNextDestination, 23
    getSource, 23
    getTotalTime, 23
    getTravelTime, 24
    hasNode, 24
    hasRoute, 24
    requestRoute, 25
    setDepartTime, 25
    setRoute, 25
    setStartTime, 26
    timeRemainingToNextDestination, 26
    tryRoadChange, 26
     Vehicle, 21
Vehicle.cpp, 36
Vehicle.h, 36
WaitFor
     main.cpp, 35
```