

Assignment - I

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Q1. Write codes to perform, LU, LDU, QR, and SV Decomposition.

A. LU - Decomposition:

Program:

```
import numpy as np
import copy

def inputMatrix():          # Function to take matrix input from user
    print("Enter the size of matrix: ")
    n= int(input())

    A= np.zeros((n,n),dtype=float)
    print("Now enter elements of matrix 'A':")
    for i in range(n):
        print("Enter elements for row:",i+1)
        for j in range(n):
            A[i][j]=int(input())
    return A

def printMatrix(V):         # Function to print Matrix
    for i in range(n):
        for j in range(n):
            print(f'{V[i][j]:15.08f}', end=" ")
        print()
    print()

def LUDecomposition(A):    #LU-Decomposition function definition

    n = len(A)

    L= np.zeros((n,n),dtype=float)
    for i in range(len(L)):
        L[i][i]=1

    U = copy.copy(A)  # copying matrix A into U

    for i in range(0,n-1):
        for j in range(i+1,n):
            L[j][i]= (U[j][i]/U[i][i])
            U[j][:]=U[j][:]-L[j][i]*U[i][:]

    return L,U

# Default input
n = 3

A = np.array([
```

```

    [1,2,4],
    [3,8,14],
    [2,6,13]
])

# Uncomment below line to take input from user
# A = inputMatrix()

# Calling Function of matrix A
L,U = LUDecomposition(A)

# Printing Results
print("A = ")
printMatrix(A)

print("L = ")
printMatrix(L)

print("U = ")
printMatrix(U)

```

Output:

```

A =
    1.00000000    2.00000000    4.00000000
    3.00000000    8.00000000   14.00000000
    2.00000000    6.00000000   13.00000000

L =
    1.00000000    0.00000000    0.00000000
    3.00000000    1.00000000    0.00000000
    2.00000000    1.00000000    1.00000000

U =
    1.00000000    2.00000000    4.00000000
    0.00000000    2.00000000    2.00000000
    0.00000000    0.00000000    3.00000000

```

B. LDU – Decomposition

Program:

```

import numpy as np
import copy

def inputMatrix():          # Function to take matrix input from user
    print("Enter the size of matrix: ")
    n= int(input())

    A= np.zeros((n,n),dtype=float)
    print("Now enter elements of matrix 'A':")

```

```

    for i in range(n):
        print("Enter elements for row:",i+1)
        for j in range(n):
            A[i][j]=int(input())
    return A

def printMatrix(V):          # Function to print matrix
    for i in range(n):
        for j in range(n):

            print(f'{V[i][j]:15.08f}', end=" ")
        print()
    print()

def LUDecomposition(A):      # LDU – Decomposition Function Definition

    n = len(A)

    L= np.zeros((n,n),dtype=float)
    D = np.zeros((n,n),dtype=float)

    for i in range(len(L)):
        L[i][i]=1

    U = copy.copy(A)  # copying matrix A into U

    for i in range(0,n-1):
        for j in range(i+1,n):
            L[j][i]= (U[j][i]/U[i][i])
            U[j][:]=U[j][:]-L[j][i]*U[i][:]

    for i in range(n):
        if(U[i][i]!=0):
            D[i][i] = copy.copy(U[i][i])
            U[i,:]= copy.copy(U[i,:]/U[i][i])

    return L,D,U

# Default Input
n = 3

A = np.array([
    [1,2,4],
    [3,8,14],
    [2,6,13]
])

```

```
# Calling LDU decomposition function
L, D, U = LUDecomposition(A)
```

```
print("A = ")
printMatrix(A)
```

```
print("L = ")
printMatrix(L)
```

```
print("D = ")
printMatrix(D)
```

```
print("U = ")
printMatrix(U)
```

Output:

```
A =
  1.00000000    2.00000000    4.00000000
  3.00000000    8.00000000   14.00000000
  2.00000000    6.00000000   13.00000000
```

```
L =
  1.00000000    0.00000000    0.00000000
  3.00000000    1.00000000    0.00000000
  2.00000000    1.00000000    1.00000000
```

```
D =
  1.00000000    0.00000000    0.00000000
  0.00000000    2.00000000    0.00000000
  0.00000000    0.00000000    3.00000000
```

```
U =
  1.00000000    2.00000000    4.00000000
  0.00000000    1.00000000    1.00000000
  0.00000000    0.00000000    1.00000000
```

C. QR – Decomposition

Program:

```
import numpy as np
```

```
def matrixInput():
    m = int(input("Enter row size :"))
    n = int(input("Enter column size :"))
```

```
    A = np.zeros((m,n), dtype=float)
```

```

print("Enter elements of matrix: ")
for i in range(m):
    for j in range(n):
        A[i][j] = float(input())

return A

def Normalize(v):
    sum = 0.0
    for i in v:
        sum+=i**2
    v=v/(sum**0.5)
    return v

def QRDecomp(A):

    n = len(A[0]) # Columns/Vectors
    m = len(A)    # Rows/Components
    q = []

    q.append(Normalize(A[:,0].reshape(m,1)))

    for i in range(1,n):

        vec = A[:,i].astype('float64').reshape(m,1)
        temp = np.zeros((m,1),dtype=float)

        for j in range(i):

            multiplier = (((vec.transpose()).dot((q[j]))))/(q[j].transpose().dot(q[j]))
            temp -= (multiplier)*q[j]

        vec = vec + temp
        normalizedvec = Normalize(vec)
        q.append(normalizedvec)

    Q = np.array(q).transpose().reshape(m,n) # typecasting python list to numpy array and taking
    np.array's transpose

    # Calculating R
    R = np.zeros((n,n))
    for i in range(n):
        for j in range(n):
            if i<=j:
                R[i][j] = A[:,j].transpose().dot(Q[:,i])

    return Q,R

```

```

def printMatrix(V):
    m = len(V)
    n = len(V[0])
    for i in range(m):
        for j in range(n):
            print(f'{V[i][j]:10.05f}' , end=" ")
        print()
    print()

# Default Input

A = np.array(((
    (1, -1, 4),
    (1, 4, -2),
    (1, 4, 2),
    (1, -1, 0)
)))

# Uncomment following lines for custom input
# A = matrixInput()

# Calling QR-decomposition function
Q,R = QRDecomp(A)

print("A = ")
printMatrix(A)

print("Q =")
printMatrix(Q)

print("R =")
printMatrix(R)

```

Output:

```

A =
1.00000  -1.00000   4.00000
1.00000   4.00000  -2.00000
1.00000   4.00000   2.00000
1.00000  -1.00000   0.00000

Q =
0.50000  -0.50000   0.50000
0.50000   0.50000  -0.50000
0.50000   0.50000   0.50000
0.50000  -0.50000  -0.50000

R =
2.00000   3.00000   2.00000

```

```
0.00000  5.00000 -2.00000
0.00000  0.00000  4.00000
```

D. SVD

Program:

```
# # SVD Implementation
```

```
# ## Importing libraries
```

```
# In[1]:
```

```
import numpy as np
```

```
import copy
```

```
# ## SVD function Definition
```

```
# In[2]:
```

```
def printMatrix(V):
```

```
    m = len(V)
```

```
    n = len(V[0])
```

```
    for i in range(m):
```

```
        for j in range(n):
```

```
            print(f'{V[i][j]:10.05f}', end=" ")
```

```
        print()
```

```
    print()
```

```
def SVD(A):
```

```
    m = len(A)
```

```
    n = len(A[0])
```

```
    At = A.transpose()
```

```
    AtA = np.matmul(At,A)
```

```
    AAt = np.matmul(A,At)
```

```
    # Finding Eigen Values and Vectors of AAt and AtA
```

```
    eigValuesAAt, eigVectorsAAt = np.linalg.eig(AAt)
```

```
    eigValuesAtA, eigVectorsAtA = np.linalg.eig(AtA)
```

```
    # Forming U, D and VT
```

```
    U = eigVectorsAAt
```



```
# Sorting eigen values in descending order and also changing position of corresponding eigen vectors
```

```
    idx = eigValuesAAAt.argsort()[::-1]
    eigValuesAAAt = eigValuesAAAt[idx]
    eigVectorsAAAt = eigVectorsAAAt[:,idx]
    eigVectorsAtA = eigVectorsAtA[:,idx]
```

```
    D = np.zeros((m,n))
    for i in range(m):
        for j in range(n):
            if i==j:
                D[i][j] = (eigValuesAAAt[i])** (1/2)
            else:
                D[i][j] = 0
```

```
    Vt = eigVectorsAtA.transpose()
```

```
    return U,D,Vt
```

```
# In[3]:
```

```
A = np.array(((
    (1,2,3),
    (4,5,6),
    (7,8,9)
)))
```

```
# A = np.array(((
#   (1, -1, 4),
#   (1, 4, -2),
#   (1, 4, 2),
#   (1, -1, 0)
# )))
```

```
# Calling SVD-decomposition function
U,D,Vt = SVD(A)
```

```
# In[4]:
```

```
print("A = ")
printMatrix(A)
print("U = ")
printMatrix(U)
print("D = ")
printMatrix(D)
```

```
print("VT = ")  
printMatrix(Vt)
```

Output:

A =

1.00000	2.00000	3.00000
4.00000	5.00000	6.00000
7.00000	8.00000	9.00000

U =

-0.21484	-0.88723	0.40825
-0.52059	-0.24964	-0.81650
-0.82634	0.38794	0.40825

D =

16.84810	0.00000	0.00000
0.00000	1.06837	0.00000
0.00000	0.00000	0.00000

VT =

-0.47967	-0.57237	-0.66506
-0.77669	-0.07569	0.62532
0.40825	-0.81650	0.40825

Q2.1 PCA of Yale Face Database

Importing Libraries

```
In [1]: import numpy as np
from matplotlib.image import imread
import matplotlib.pyplot as plt
import scipy.io
import copy

plt.rcParams['figure.figsize'] = [8,4]
```

Importing Yale Faces Database from .mat file

scipy.io.loadmat() function imports .mat file as dictionary

```
In [2]: data = scipy.io.loadmat('./Yale_64x64.mat')
print(type(data))

<class 'dict'>
```

Dictionary to Numpy Array

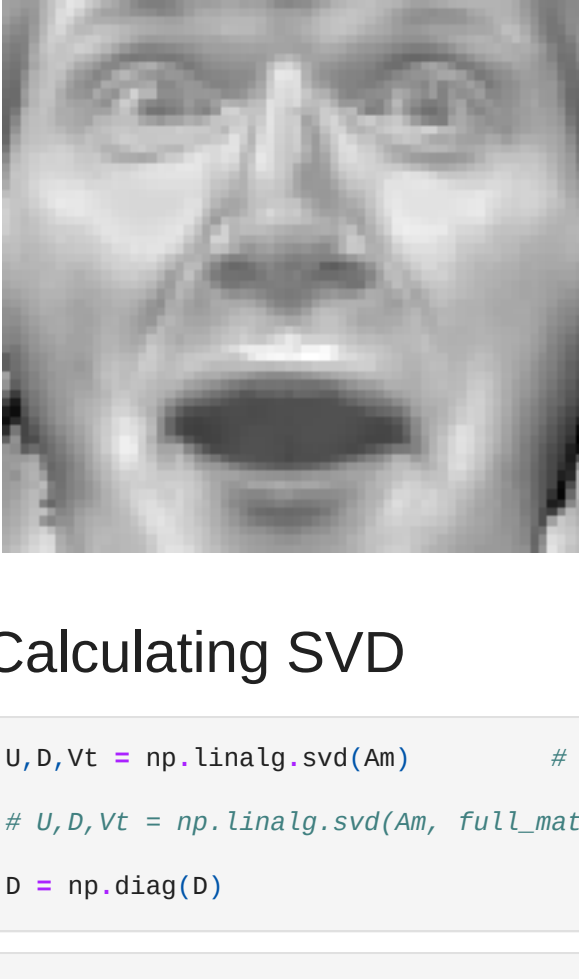
```
In [3]: A = np.array(data['fea']).T
```

```
In [4]: print(A.shape)

(4096, 165)
```

Sample Image/Face from database

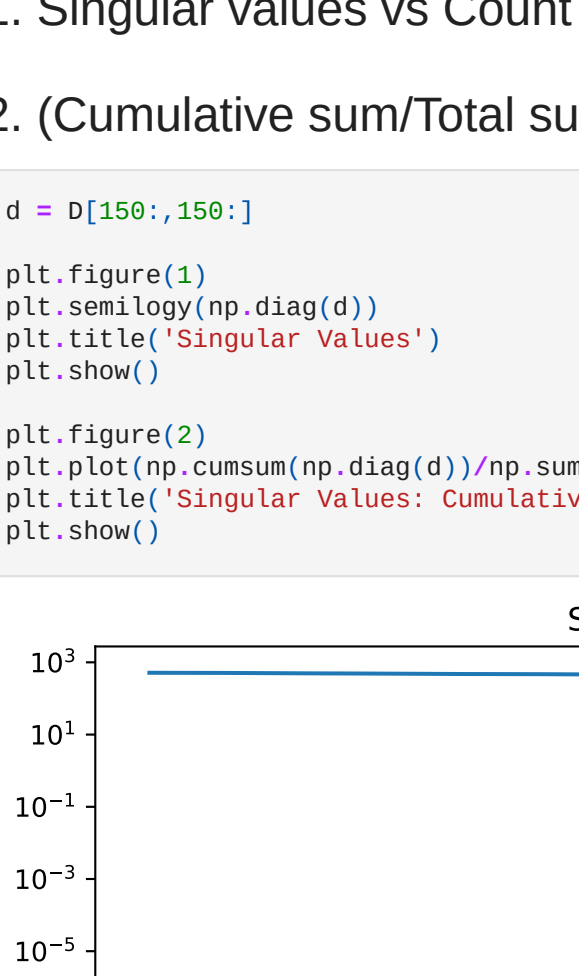
```
In [5]: img = plt.imshow(A[:,1].reshape(64,64).transpose())
img.set_cmap('gray')
plt.axis('off')
plt.show()
```



Forming Covariance-Matrix

```
In [6]: Amean = A.mean(axis=1, keepdims=True)
Am = A - Amean
```

```
In [7]: img = plt.imshow(Am[:,1].reshape(64,64).transpose())
img.set_cmap('gray')
plt.axis('off')
plt.show()
```



Calculating SVD

```
In [8]: U,D,Vt = np.linalg.svd(Am) # Complete SVD i.e. calculation corresponding to zero
# U,D,Vt = np.linalg.svd(Am, full_matrices=False) # Economy SVD i.e. Calculations corresponding to non-zero
D = np.diag(D)
```

```
In [9]: print(U.shape, D.shape, Vt.shape)

(4096, 4096) (165, 165) (165, 165)
```

Finding number of eigen values with least significance

```
In [10]: i = 0
n = len(D)
while(i<n):
    if abs(D[i][1]) < 10:
        break
    i += 1
eig_vals_with_least_significance = n - i
```

```
In [11]: print(eig_vals_with_least_significance)

3
```

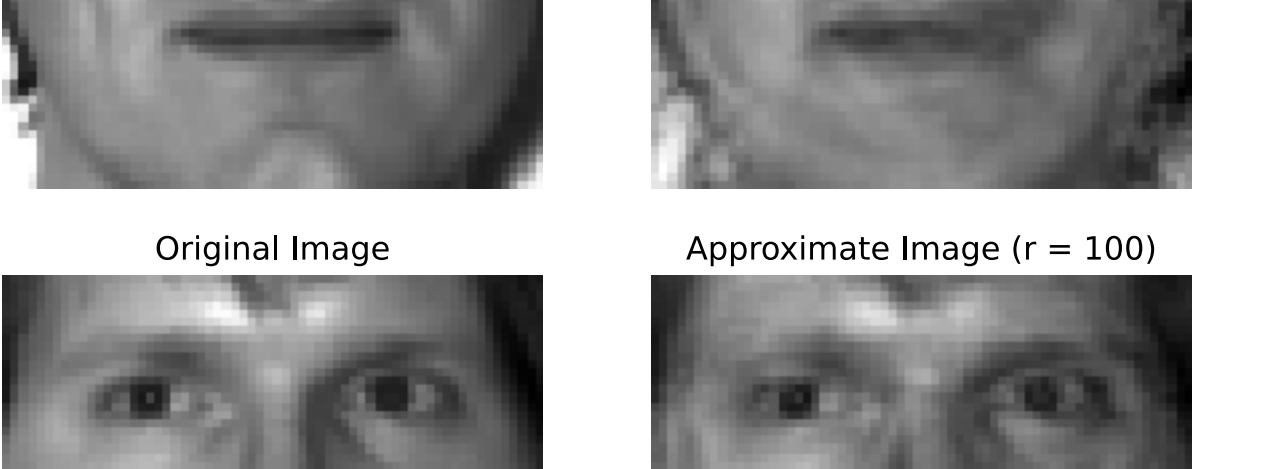
Visualizing singular values by plotting graph

1. Singular values vs Count

2. (Cumulative sum/Total sum) vs Count

```
In [12]: d = D[150:,150:]

plt.figure(1)
plt.semilogy(np.diag(d))
plt.title('Singular Values')
plt.show()
```



```
plt.figure(2)
plt.plot(np.cumsum(np.diag(d))/np.sum(np.diag(d)))
plt.title('Singular Values: Cumulative Sum')
plt.show()
```



In Sample Projection and Prediction

```
In [13]: sample_size = 150

def InSampleProjectionAndReconstruction(image_number):
    j = 0

    for r in (50, 100, 200, 500, 800, 2000, 4096, 4096-eig_vals_with_least_significance):
        # Construct approximate image
        u = U[:, :r]

        # Projection
        A_train_model = np.matmul(u.T, A[:, :sample_size])

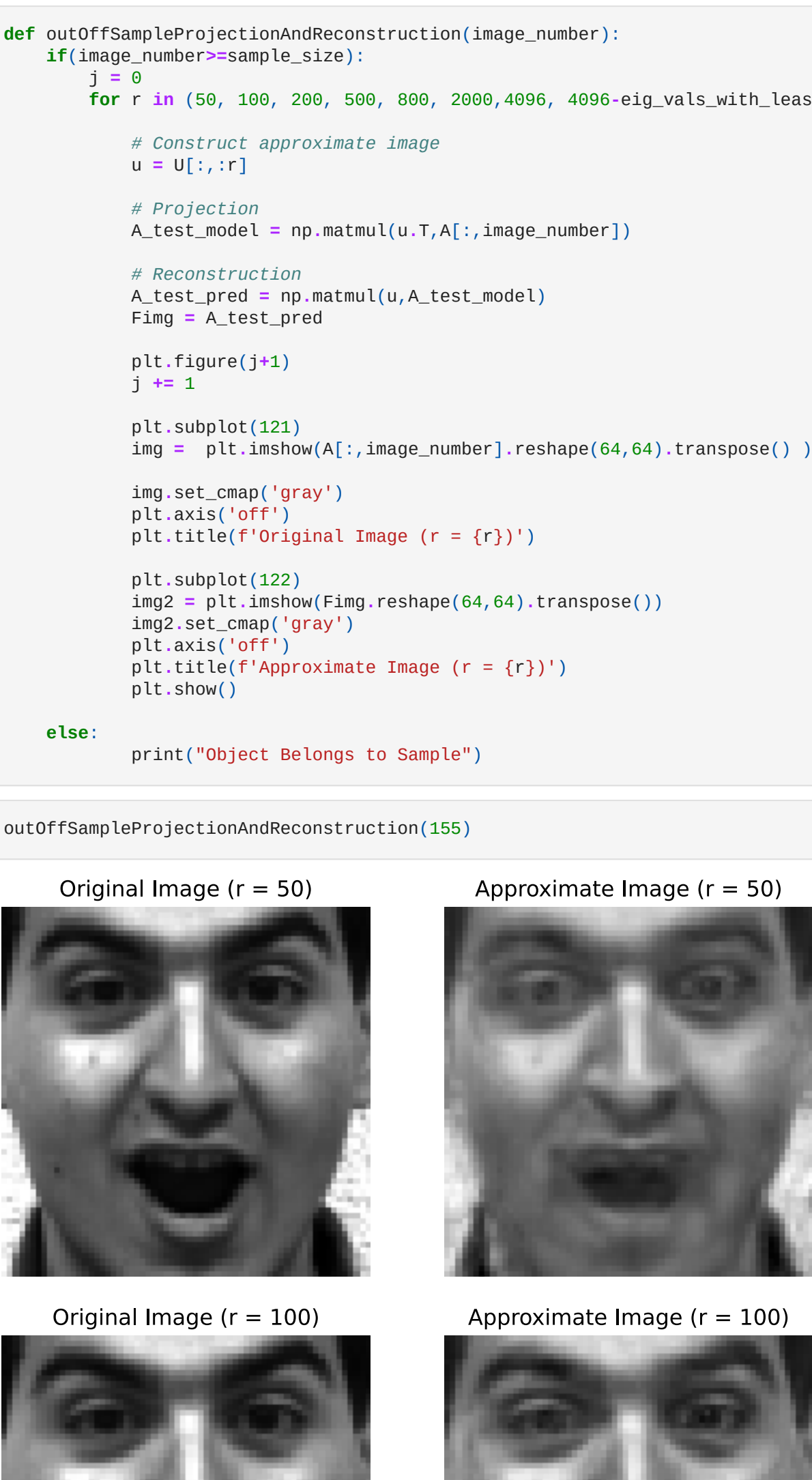
        # Reconstruction
        A_train_pred = np.matmul(u, A_train_model)
        Fimg = A_train_pred

        plt.figure(j+1)
        j += 1

        plot1 = plt.subplot(121)
        img = plt.imshow(A[:, image_number].reshape(64,64).transpose())
        img.set_cmap('gray')
        plt.title(f'Original Image')
        plt.axis('off')

        plot2 = plt.subplot(122)
        img2 = plt.imshow(Fimg[:, image_number].reshape(64,64).transpose())
        img2.set_cmap('gray')
        plt.axis('off')
        plt.title(f'Approximate Image (r = {r})')
        plt.show()
```

```
In [14]: InSampleProjectionAndReconstruction(0)
```



Out off Sample Projection and Prediction

```
In [15]: def outOffSampleProjectionAndReconstruction(image_number):
    if(image_number>=sample_size):
        j = 0
        for r in (50, 100, 200, 500, 800, 2000, 4096, 4096-eig_vals_with_least_significance):
            # Construct approximate image
            u = U[:, :r]

            # Projection
            A_test_model = np.matmul(u.T, A[:, image_number])

            # Reconstruction
            A_test_pred = np.matmul(u, A_test_model)
            Fimg = A_test_pred

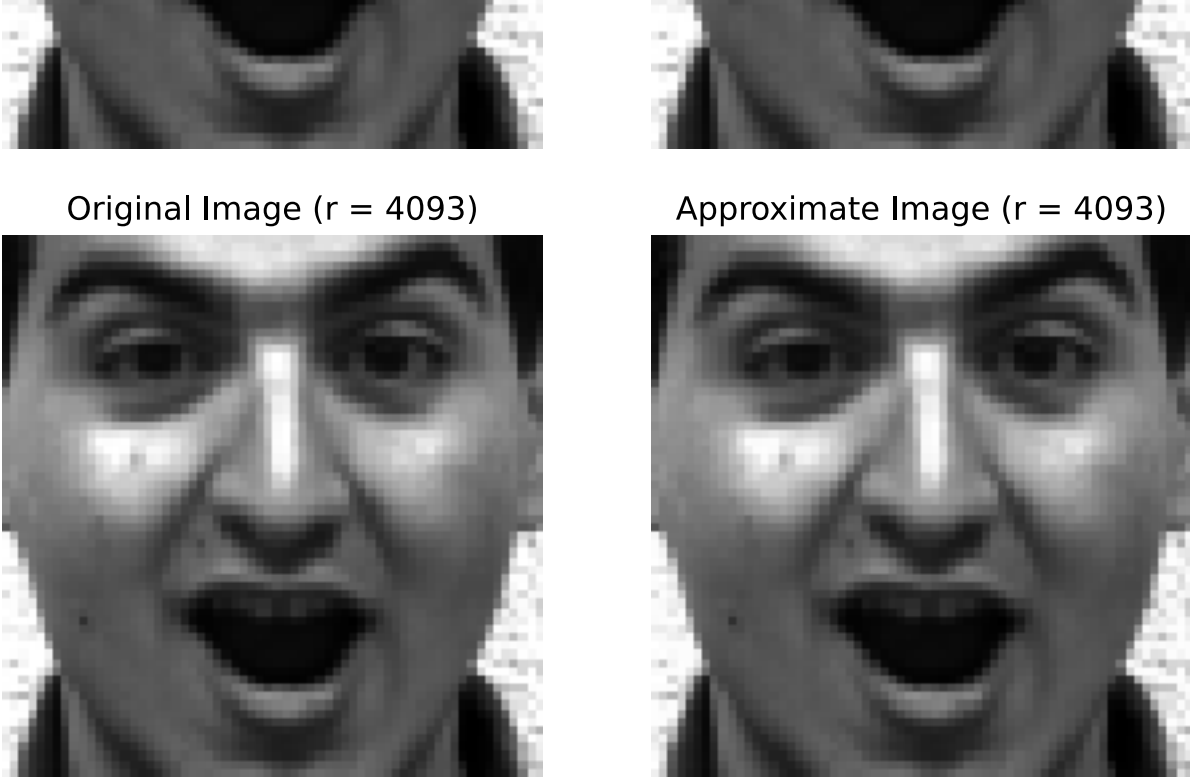
            plt.figure(j+1)
            j += 1

            plt.subplot(121)
            img = plt.imshow(A[:, image_number].reshape(64,64).transpose() )
            img.set_cmap('gray')
            plt.axis('off')
            plt.title(f'Original Image (r = {r})')

            plt.subplot(122)
            img2 = plt.imshow(Fimg.reshape(64,64).transpose())
            img2.set_cmap('gray')
            plt.axis('off')
            plt.title(f'Approximate Image (r = {r})')
            plt.show()

        else:
            print("Object Belongs to Sample")

In [16]: outOffSampleProjectionAndReconstruction(155)
```



Q2.2 Dual PCA of Yale Face Database

Importing Libraries

```
In [35]: import numpy as np
import matplotlib.pyplot as plt
import scipy.io

plt.rcParams['figure.figsize'] = [10,5]
```

Importing Yale Face Database

```
In [36]: data = scipy.io.loadmat('./YaleFaceDataBase/Yale_64x64.mat')
```

In Dual PCA if A has dimensions n by t then $n \gg t$

Taking only t-number of samples for Analysis

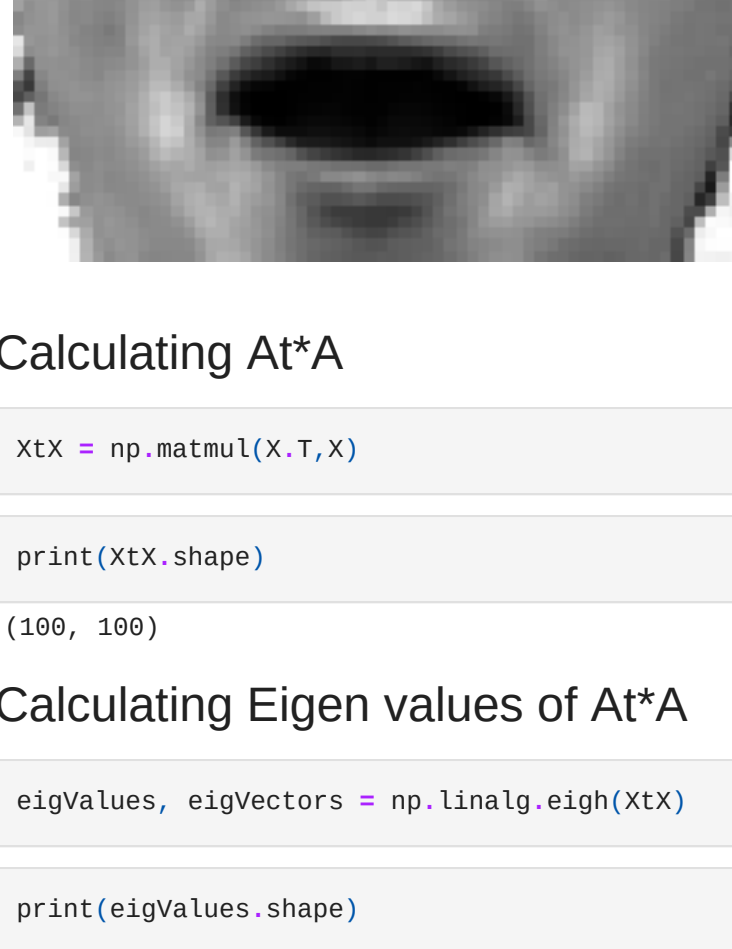
```
In [37]: t = 100
X = np.array(data['fea'])[:t,:].T
```

```
In [38]: print(X.shape)

(4096, 100)
```

Visualizing one of the sample image

```
In [39]: img = plt.imshow(X[:,1].reshape(64,64).transpose())
img.set_cmap('gray')
plt.axis('off')
plt.show()
```



Calculating $A^T A$

```
In [40]: XtX = np.matmul(X.T,X)
```

```
In [41]: print(XtX.shape)

(100, 100)
```

Calculating Eigen values of $A^T A$

```
In [42]: eigValues, eigVectors = np.linalg.eigh(XtX)
```

```
In [43]: print(eigValues.shape)

(100,)
```

```
In [44]: print(eigValues)
```

```
[-1.44213332e+03 -1.32446410e+03 -1.30623412e+03 -1.24429096e+03
-1.21678564e+03 -1.19797082e+03 -1.11729236e+03 -1.06525344e+03
-1.05588651e+03 -1.04058313e+03 -9.76025720e+02 -9.18680023e+02
-8.97465034e+02 -8.84722094e+02 -8.75651691e+02 -8.37038678e+02
-8.14724711e+02 -7.79495263e+02 -7.38948305e+02 -7.15844200e+02
-6.91368810e+02 -6.71493309e+02 -6.58297084e+02 -6.00216821e+02
-5.79281157e+02 -5.36942209e+02 -5.10119884e+02 -5.03721547e+02
-4.50460504e+02 -4.40144652e+02 -4.31936255e+02 -4.05144336e+02
-3.76509059e+02 -3.47656317e+02 -3.10738072e+02 -2.98757430e+02
-2.82611833e+02 -2.2261329e+02 -2.11557931e+02 -1.90942705e+02
-1.68230865e+02 -1.63777417e+02 -1.15412219e+02 -8.18540193e+01
-6.54047420e+01 -4.83431968e+01 -3.63863311e+01 -2.96248105e+01
4.63655445e-14 1.78288084e-13 1.11059645e+01 4.91114620e+01
6.64342907e+01 9.25994971e+01 1.01413404e+02 1.48782785e+02
1.87128456e+02 2.21946170e+02 2.34283584e+02 2.62349975e+02
2.80922163e+02 2.92709212e+02 2.99399922e+02 3.39613235e+02
3.58319602e+02 4.04102718e+02 4.23277169e+02 4.38690758e+02
4.72931541e+02 5.07492373e+02 5.11577217e+02 5.40440401e+02
5.62420730e+02 5.90376424e+02 6.19289307e+02 6.23520739e+02
6.62120820e+02 6.80666083e+02 6.87894811e+02 7.19088198e+02
7.34998271e+02 7.85210254e+02 7.99554795e+02 8.40891654e+02
8.59706496e+02 9.04948515e+02 9.23290090e+02 9.70877545e+02
9.86387520e+02 1.04280301e+03 1.07430711e+03 1.09354195e+03
1.13845770e+03 1.21809307e+03 1.27040551e+03 1.30376543e+03
1.39149840e+03 1.40632623e+03 1.49057913e+03 1.28139567e+04]
```

Sorting eigen values in descending values and changing order of

eigen vectors correspondingly

```
In [45]: idx = eigValues.argsort()[::-1]
eigValues = eigValues[idx]
eigVectors = eigVectors[:,idx]
```

```
In [46]: print(eigValues)
```

```
[ 1.28139567e+04  1.49057913e+03  1.40632623e+03  1.39149840e+03
 1.30376543e+03  1.27040551e+03  1.21809307e+03  1.13845770e+03
 1.10354195e+03  1.07430711e+03  1.01280301e+03  9.86367520e+02
 9.70877545e+02  9.23290090e+02  9.04948515e+02  8.59706496e+02
 8.40891654e+02  7.99554795e+02  7.85210254e+02  7.34998271e+02
 7.19088198e+02  6.87894811e+02  6.80666083e+02  6.62120820e+02
 6.23520739e+02  6.19289307e+02  5.90376424e+02  5.62420730e+02
 5.40440401e+02  5.11577217e+02  5.07492373e+02  4.72931541e+02
 4.38690758e+02  4.23277169e+02  4.04102718e+02  3.58319602e+02
 3.39613235e+02  2.99399922e+02  2.92709212e+02  2.80922163e+02
 2.62349975e+02  2.34283584e+02  2.21946170e+02  1.87128456e+02
 1.48782785e+02  1.01413404e+02  9.25994971e+01  6.64342907e+01
 4.91114620e+01  1.11059645e+01  1.78288084e-13  4.63655445e-14
-2.96248105e+01 -3.63863311e+01 -4.83431968e+01 -6.54047420e+01
-8.18540193e+01 -1.15412219e+02 -1.63777417e+02 -1.68230865e+02
-1.90942705e+02 -2.11557931e+02 -2.2261329e+02 -2.82611833e+02
-2.98757430e+02 -3.10738072e+02 -3.47656317e+02 -3.76509059e+02
-4.05144336e+02 -4.31936255e+02 -4.40144652e+02 -4.50460504e+02
-5.03721547e+02 -5.10119884e+02 -5.03721547e+02 -5.79281157e+02
-6.00216821e+02 -6.58297084e+02 -6.71493309e+02 -6.91368810e+02
-7.15844200e+02 -7.38948305e+02 -7.79495263e+02 -8.14724711e+02
-8.37038678e+02 -8.75651691e+02 -8.84722094e+02 -8.97465034e+02
-9.18680023e+02 -9.76025720e+02 -1.04058313e+03 -1.05588651e+03
-1.06525344e+03 -1.11729236e+03 -1.19797082e+03 -1.21678564e+03
-1.24429096e+03 -1.30623412e+03 -1.32446410e+03 -1.44213332e+03]
```

```
In [47]: eigVals = eigValues.copy()
```

Finding out number of least significant eigen Values

```
In [48]: r = 0
index_of_small_eig_values = []
while(r<len(eigValues)):
    if eigValues[r]<1:
        index_of_small_eig_values.append(eigValues[r])
        r += 1
```

Here that number turns out to be 50

```
In [49]: small_eig_vals = len(index_of_small_eig_values)
print(small_eig_vals)

50
```

```
In [50]: eigVals = np.array(eigVals)
```

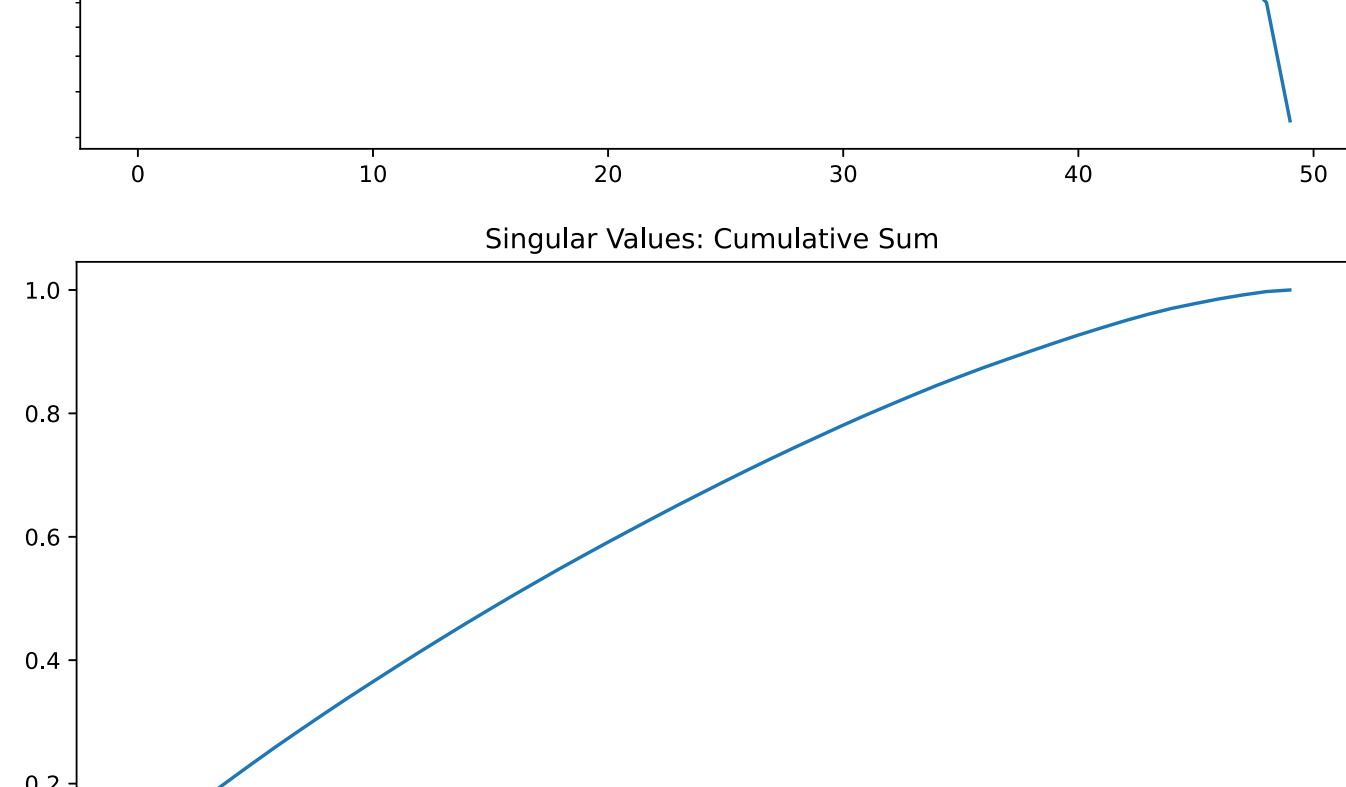
Creating Singular value matrix

```
In [51]: D = eigVals[:~small_eig_vals]**(1/2)
```

Visualizing Singular values matrix pattern

```
In [52]: plt.figure(1)
plt.semilogy(D)
plt.title('Singular Values')
plt.show()

plt.figure(2)
plt.plot(np.cumsum(D)/np.sum(D))
plt.title('Singular Values: Cumulative Sum')
plt.show()
```



Formint $V^T \cdot \text{transpose}()$ Matrix

```
In [53]: Vt = eigVectors.copy().T
```

Reconstruction of Training data

$x_{cap} = X V V^T$

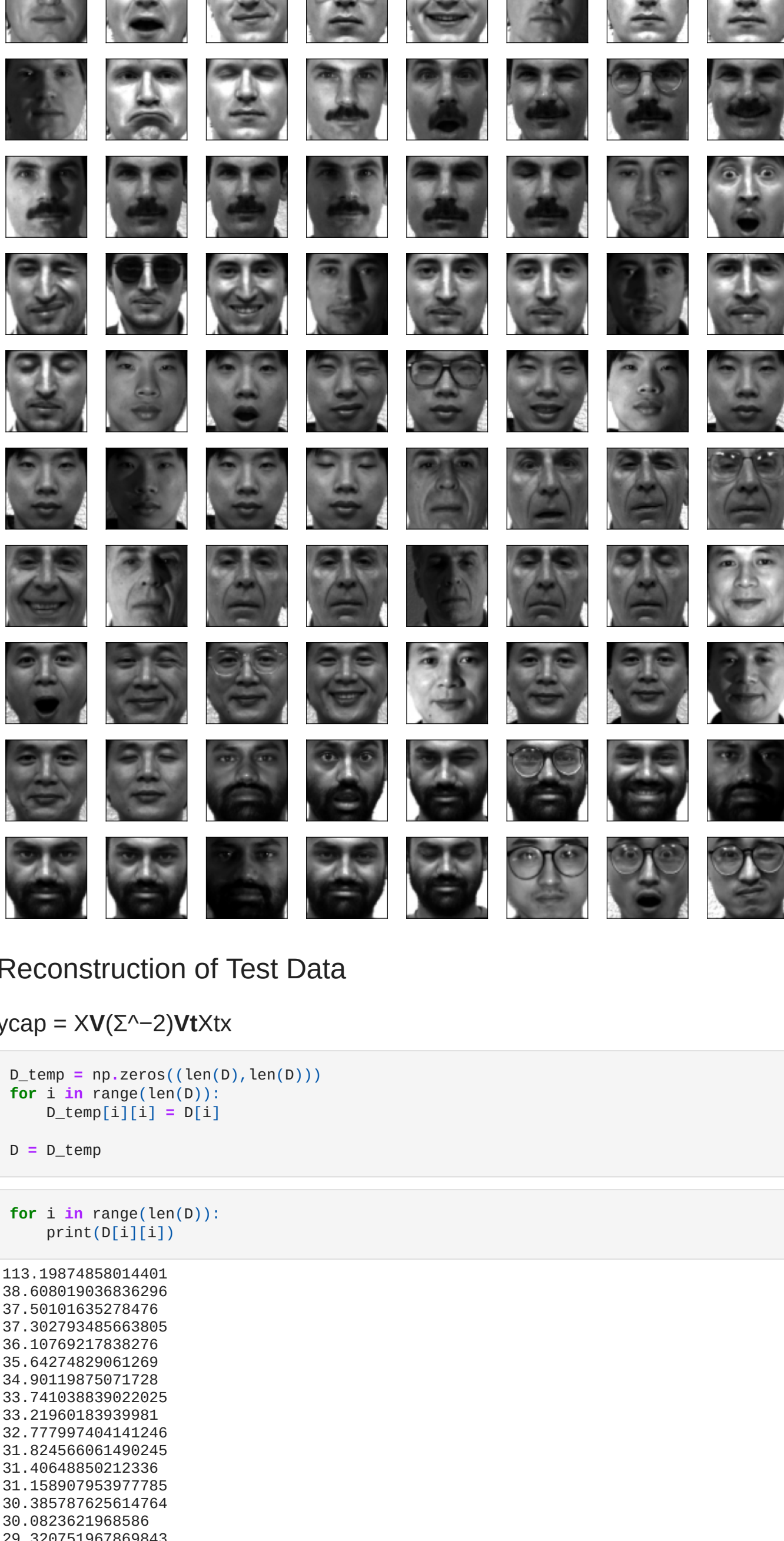
```
In [54]: Xcap = (X.dot(Vt.T)).dot(Vt)
```

```
In [55]: print(Xcap.shape)

(4096, 100)
```

Visualizing Reconstructed Data

```
In [56]: plt.figure(figsize=(16,20))
for i in range(1,81):
    img = plt.imshow(Xcap[:,i-1].reshape(64,64).T.astype('uint8'), cmap='gray')
    plt.plot()
```



Reconstruction of Test Data

$y_{cap} = X V (\Sigma^{-2}) V^T x_{cap}$

```
In [57]: D_temp = np.zeros((len(D),len(D)))
for i in range(len(D)):
    D_temp[i][i] = D[i]

D = D_temp
```

```
In [58]: for i in range(len(D)):
    print(D[i][i])

113.19874858014401
38.608019036836296
37.50101635278476
37.302793485663805
36.10769217838276
35.64274829061269
34.90119875071728
33.741038839022025
32.21960183939981
32.777997404141246
31.824566001490245
31.40648950212336
31.158907953977785
30.385787625614764
30.0823621968586
29.320751967869843
28.998131908246993
28.276399955960777
28.021603345223525
27.11085153717597
26.81581991334121
26.227748880385747
26.089578056453934
25.731708462098233
24.970397256256746
24.885524047988394
24.297062930858185
23.715411233093413
23.24737407555087
22.618072787836233
22.527591375113797
21.746989243648752
20.944945890945384
20.573700896829767
20.102306292414788
18.929331786546687
18.428598304297516
17.303176645659565
17.108746638795072
16.76073275974999
16.19722121171101
15.306324960958053
14.897857891115656
13.679490330037773
12.1976548994009132
10.0704222643836
9.622863246118387
8.10723329888473
7.007957045914438
3.3325612515534706
```

```
In [59]: invD_sq = np.linalg.inv(np.matmul(D,D))
```

```
In [60]: print(invD_sq)
```

```
[[7.80399080e-05 0.00000000e+00 0.00000000e+00 ... 0.00000000e+00
 0.00000000e+00 0.00000000e+00]
[0.00000000e+00 6.70880182e-04 0.00000000e+00 ... 0.00000000e+00
 0.00000000e+00 0.00000000e+00]
[0.00000000e+00 0.00000000e+00 7.11072567e-04 ... 0.00000000e+00
 0.00000000e+00 0.00000000e+00]
...
[0.00000000e+00 0.00000000e+00 0.00000000e+00 ... 1.50524675e-02
 0.00000000e+00 0.00000000e+00]
[0.00000000e+00 0.00000000e+00 0.00000000e+00 ... 0.00000000e+00
 2.03618455e-02 0.00000000e+00]
[0.00000000e+00 0.00000000e+00 0.00000000e+00 ... 0.00000000e+00
 0.00000000e+00 9.00417069e-02]]
```

```
In [61]: print(X.shape)
print(Vt.T.shape)
print(invD_sq.shape)
print(Vt.shape)
print(X.T.shape)
print(X.shape)

(4096, 100)
(100, 100)
(50, 50)
(100, 100)
(100, 4096)
(4096, 100)
```

```
In [62]: X_approx = X[:,~small_eig_vals]
Vt_approx = Vt[:,~small_eig_vals,~small_eig_vals]
```

```
In [63]: print(X_approx.shape)
print(Vt_approx.T.shape)
print(invD_sq.shape)
print(Vt_approx.shape)
print(X_approx.T.shape)
print(X_approx.shape)

(4096, 50)
(50, 50)
(50, 50)
(50, 50)
(50, 4096)
(4096, 50)
```

```
In [64]: UUT = np.matmul(X_approx[:,~small_eig_vals],np.matmul(Vt_approx.T,np.matmul(invD_sq,np.matmul(Vt_approx.T,X_approx))))
```

```
In [65]: y = np.matmul(UUT,X[:,~small_eig_vals])
```

```
In [66]: print(y.shape)

(4096,)
```

```
In [67]: img = plt.imshow(y.reshape(64,64).astype('uint8').T)
img.set_cmap('gray')
```



In Dual PCA, in most cases reconstruction of test data

i.e. out of sample reconstruction is not possible

Q3.1 Linear Least Square Fitting

Importing Libraries

```
In [1]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from prettytable import PrettyTable as ptbl
```

Importing Database

```
In [2]: data = pd.read_csv('Salary_Data.csv')
```

```
In [3]: data.describe()
```

Out[3]:

	YearsExperience	Salary
count	30.000000	30.000000
mean	5.313333	76003.000000
std	2.837888	27414.429785
min	1.100000	37731.000000
25%	3.200000	56720.750000
50%	4.700000	65237.000000
75%	7.700000	100544.750000
max	10.500000	122391.000000

Extracting Dependent and independent data from database int X and y variables

```
In [4]: x = data.iloc[:,0].values
y = data.iloc[:,1].values
```

Function for Linear Least Square Fitting

$y = mx + b$

```
In [5]: def linearfitting(x,y):
n = len(x)
x_sq_sum = sum(x**2)
x_sum = sum(x)
yx_sum = sum(x*y)
y_sum = sum(y)

A = np.array([
    [x_sq_sum,x_sum],
    [x_sum,n]
])

b = np.array([
    [yx_sum],
    [y_sum]
])

invA = np.linalg.inv(A)
M = np.matmul(invA,b)

return M
```

Calling Linear Least Square fitting function on given database

```
In [6]: M = linearfitting(X,y)
m = M[0][0]
b = M[1][0]
```

Visualizing Calculated Coefficient and constant

```
In [7]: print("m = ",m,"\tb = ",b)
```

m = 9449.962321455096 b = 25792.200198668637

Calculating Approximate Values

```
In [8]: y_pred = m*X + b
```

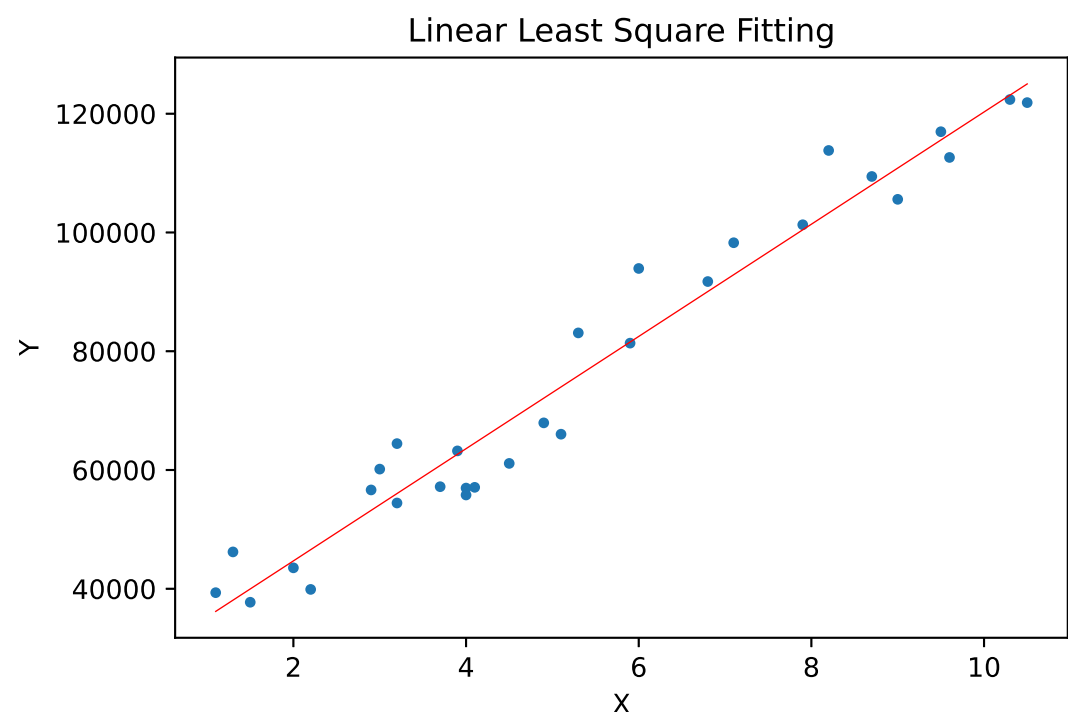
Table of actual values and predicted values

```
In [9]: table = ptbl(['X','y','y-predicted'])
for i in range(len(X)):
    table.add_row([X[i],y[i],y_pred[i]])
print(table)
```

X	y	y-predicted
1.1	39343.0	36187.15875226924
1.3	46205.0	38077.15121656026
1.5	37731.0	39967.14368085128
2.0	43525.0	44692.12484157883
2.2	39891.0	46582.11730586985
2.9	56642.0	53197.090930888415
3.0	60150.0	54142.087163033924
3.2	54445.0	56032.07962732494
3.2	64445.0	56032.07962732494
3.7	57189.0	60757.06078805249
3.9	63218.0	62647.05325234351
4.0	55794.0	63592.04948448902
4.0	56957.0	63592.04948448902
4.1	57081.0	64537.04571663453
4.5	61111.0	68317.03064521657
4.9	67938.0	72097.0155737986
5.1	66029.0	73987.00803808963
5.3	83088.0	75877.00050238064
5.9	81363.0	81546.9778952537
6.0	93940.0	82491.97412739921
6.8	91738.0	90051.94398456329
7.1	98273.0	92886.93268099982
7.9	101302.0	100446.9025381639
8.2	113812.0	103281.89123460042
8.7	109431.0	108006.87239532797
9.0	105582.0	110841.8610917645
9.5	116969.0	115566.84225249205
9.6	112635.0	116511.83848463756
10.3	122391.0	123126.81210965612
10.5	121872.0	125016.80457394714

Visualizing Best Fit Line

```
In [10]: plt.scatter(X,y, marker = '.')
plt.plot(X,y_pred,color = 'red',linewidth = 0.5)
plt.title('Linear Least Square Fitting')
plt.xlabel('X')
plt.ylabel('Y')
plt.show()
```



Evaluating Error in reconstruction

```
In [11]: max_error = max(abs(y-y_pred)/y)
print(max_error)
```

0.17590842513666785

Q3.2 Quadratic Least Square Fitting

Importing Libraries

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from prettytable import PrettyTable as ptbl
```

Importing database

```
In [2]: data = pd.read_csv('Quadratic_curve_fitting_dataset.csv')
```

Visualizing database

```
In [3]: data.head()
```

Out[3]:

	x	y
0	2	5
1	5	140
2	8	455
3	11	950
4	14	1625

Extracing Dependent and independent variables from database in X and y variables respectively

```
In [4]: x = data.iloc[:,0].values
y = data.iloc[:,1].values
```

Quadratic Least square fitting function

$y = c1x^2 + c2x + c3$

```
In [5]: def QuadraticFitting(x,y):

    x_four_sum = sum(x**4)
    x_three_sum = sum(x**3)
    x_sq_sum = sum(x**2)
    x_sum = sum(x)
    n = len(x)

    y_xsq_sum = sum(y*(x**2))
    yx_sum = sum(x*y)
    y_sum = sum(y)

    A = np.array([
        [x_four_sum, x_three_sum, x_sq_sum],
        [x_three_sum, x_sq_sum, x_sum],
        [x_sq_sum, x_sum, n],
    ])

    b = np.array([
        [y_xsq_sum],
        [yx_sum],
        [y_sum]
    ])

    invA = np.linalg.inv(A)
    M = np.matmul(invA,b)

    return M
```

Calling Quadratic least square fitting function on given database

```
In [6]: c1, c2, c3 = QuadraticFitting(X,y)
```

Visualizing coefficients and constants

```
In [7]: print(c1,c2,c3)
```

[9.99671939] [-24.47209128] [-0.008132]

Calculating Approximate Values

```
In [8]: y_pred = c1*(x**2) + c2*x + c3
```

Table of actual values and predicted values

```
In [9]: table = ptbl(['X', 'y', 'y-predicted'])
for i in range(len(X)):
    table.add_row([X[i],y[i],y_pred[i]])
print(table)
```

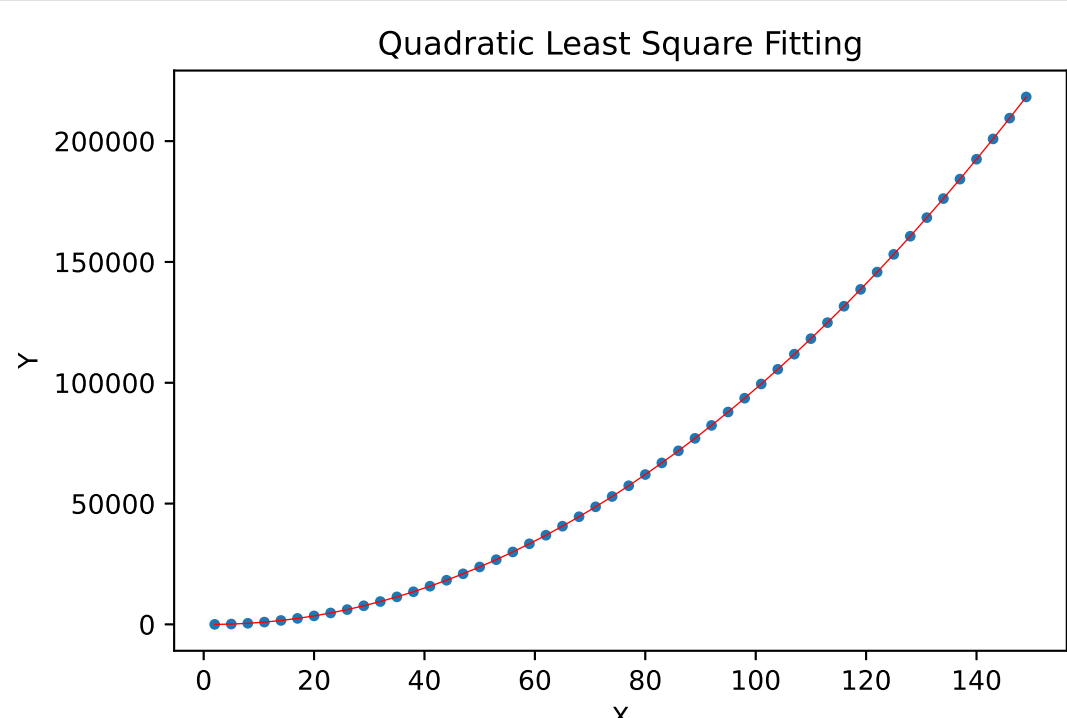
X	y	y-predicted
2	5	-8.965437008384214
5	140	127.54939634349978
8	455	444.00517872570873
11	950	940.4019101382426
14	1625	1616.7395905811015
17	2480	2473.0182200542854
20	3515	3509.2377985577946
23	4730	4725.3983260916275
26	6125	6121.499802655787
29	7700	7697.5422282502695
32	9455	9453.52560287508
35	11390	11389.449926530213
38	13505	13505.31519921567
41	15800	15801.121420931455
44	18275	18276.868591677565
47	20930	20932.556711454
50	23765	23768.18578026076
53	26780	26783.75579809784
56	29975	29979.26676496525
59	33350	33354.718680862985
62	36905	36910.11154579104
65	40640	40645.44535974943
68	44555	44560.72012273813
71	48650	48655.93583475717
74	52925	52931.09249580652
77	57380	57386.190105886206
80	62015	62021.22866499622
83	66830	66836.20817313655
86	71825	71831.12863030721
89	77000	77005.99003650818
92	82355	82360.7923917395
95	87890	87895.53569600113
98	93605	93610.2199492931
101	99500	99504.84515161537
104	105575	105579.41130296799
107	111830	111833.91840335092
110	118265	118268.36645276417
113	124880	124882.75545120776
116	131675	131677.08539868164
119	138650	138651.3562951859
122	145805	145805.56814072045
125	153140	153139.72093528532
128	160655	160653.81467888053
131	168350	168347.84937150608
134	176225	176221.82501316193
137	184280	184275.74160384812
140	192515	192509.5991435646
143	200930	200923.39763231145
146	209525	209517.1370700886
149	218300	218290.8174568961

Visualizing Best Fit Curve

Note: The database used here was generated by me using Microsoft EXCEL

that's why the actual points are perfectly overlapping with approximate line

```
In [10]: plt.scatter(X,y, marker = '.')
plt.plot(X,y_pred,color = 'red',linewidth = 0.5)
plt.title('Quadratic Least Square Fitting')
plt.xlabel('X')
plt.ylabel('Y')
plt.show()
```



Evaluating Error in reconstruction

```
In [11]: max_error = max(abs(y-y_pred)/y)
print(max_error)
```

2.7930874016768428

here the first approximate value is way off from the actual value

that's why the error is too large

```
In [12]: for i in range(5):
print(f"y[{i}] = {y[i]}\ty_predict[{i}] = {y_pred[i]}")
```

```
y[0] = 5          y_predict[0] = -8.965437008384214
y[1] = 140        y_predict[1] = 127.54939634349978
y[2] = 455        y_predict[2] = 444.00517872570873
y[3] = 950        y_predict[3] = 940.4019101382426
y[4] = 1625       y_predict[4] = 1616.7395905811015
```

Also it can be seen that as we go on calculating the approximate values the error goes on decreasing

Q4. Denoising Using L2-Regularisation

```
In [1]: from matplotlib.image import imread
import matplotlib.pyplot as plt
import numpy as np
import os
plt.rcParams['figure.figsize'] = [12,6]
```

Importing and Visualizing input image

```
In [2]: 0img = imread('dog.jpg')
print(0img.shape)
img = plt.imshow(0img)
plt.axis('off')
img.set_cmap('gray')
plt.title("Original Image")
```

(2000, 1500, 3)

Out[2]: Text(0.5, 1.0, 'Original Image')

Original Image



```
In [3]: 0img = np.mean(0img,-1)           # Converting to Grayscale
```

Adding Gaussian Noise

```
In [4]: mean = 0
sigma = 3

Noise = np.random.normal(mean, sigma, (0img.shape[0],0img.shape[1])).astype('uint8')
0imgNoisey = 0img + Noise           # Add some noise
```

Visualizing Noise and original image

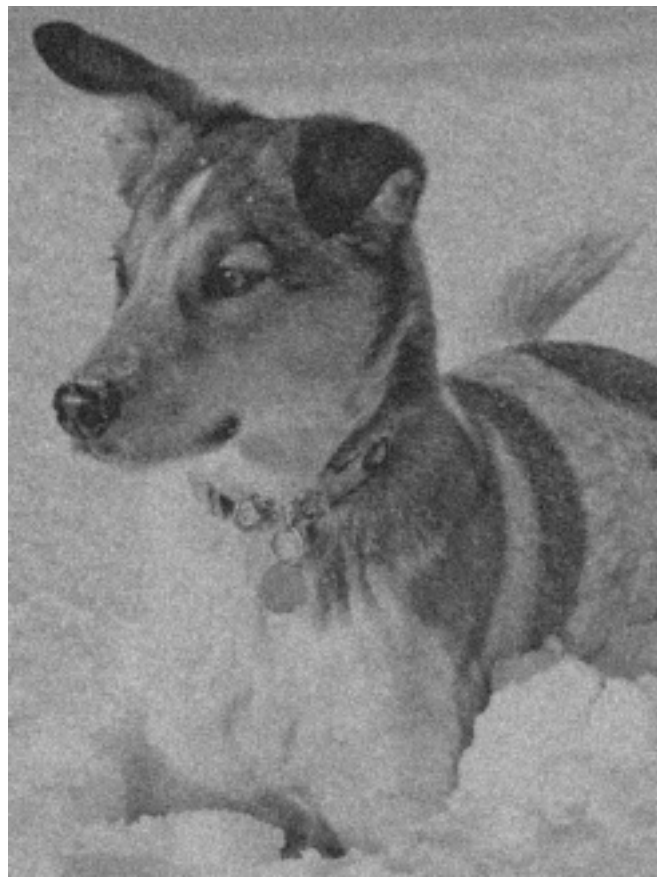
```
In [5]: plt.figure(1)
plt.subplot(121)
img = plt.imshow(0img)
plt.axis('off')
img.set_cmap('gray')
plt.title("Original Image")

plt.subplot(122)
img2 = plt.imshow(0imgNoisey)
plt.axis('off')
img2.set_cmap('gray')
plt.title("Noisy Image")
plt.show()
```


Original Image



Noisy Image



L2-regularisation Function

In [6]: `def L2Regularisation(NoisyInput, ExpectedOutput, factor):`

```

    n = len(ExpectedOutput)
    I = np.identity(n)
    A = I
    At = A.T
    AtA = np.matmul(At,A)
    M = (AtA - factor*I)

    T = np.matmul(np.linalg.inv(M),At)
    pred = np.matmul(T,NoisyInput)

    plt.figure()
    plt.subplot(131)
    img1 = plt.imshow(NoisyInput)
    img1.set_cmap('gray')
    plt.axis('off')
    plt.title(f'Noisy Image')

    plt.subplot(132)
    img2 = plt.imshow(pred)
    img2.set_cmap('gray')
    plt.axis('off')
    plt.title(f'Denoised Image (lambda = {factor})')

    plt.subplot(133)
    img3 = plt.imshow(ExpectedOutput)
    img3.set_cmap('gray')
    plt.axis('off')
    plt.title('Original Image')
    plt.show()

```

In [7]: `fact = np.arange(0,1,0.2)`
`for i in fact:`
 `L2Regularisation(0imgNoisy,0img,i)`

Noisy Image



Denoised Image (lambda = 0.0)



Original Image



Noise Image



Denoised Image (lambda = 0.2)



Original Image



Noise Image



Denoised Image (lambda = 0.4)



Original Image



Noise Image



Denoised Image (lambda = 0.6000000000000001)



Original Image



