Calibration results
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Camera-system parameters:
cam0 (/left/image_raw):
   type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
   distortion: [-0.22008226 0.06032327 0.00041749 0.00129712] +- [0.00064455 0.00039897 0.00008894 0.00013298]
   projection: [905.20388744 904.29493074 766.70215471 569.93646636] +- [0.24736429 0.23290815 0.88917765 0.52807727]
   reprojection error: [0.000183, -0.000030] +- [0.411928, 0.356333]

cam1 (/middle/image_raw):
   type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
   distortion: [-0.22417698 0.06373024 0.00016808 0.00006043] +- [0.00075408 0.0005265 0.00008172 0.00011206]
   projection: [913.04616953 911.73104118 777.11553789 581.6499745] +- [0.3136627 0.31003935 0.87401148 0.44501895]
   reprojection error: [-0.000044, -0.000069] +- [0.474879, 0.450606]

cam2 (/right/image_raw):
   type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
   distortion: [-0.21792947 0.05923033 0.00087385 -0.00069215] +- [0.00066913 0.00044227 0.00012018 0.00014638]
   projection: [906.13030768 905.03129772 770.6513601 577.88012713] +- [0.21865874 0.2017673 0.42169773 0.7440536]
   reprojection error: [-0.000129, 0.000157] +- [0.480461, 0.431093]

baseline T_1_0:
   q: [-0.03034881 0.2286898   0.03649435 0.97234155] +- [0.00066273 0.00109184 0.00021817]
   t: [-0.60723815 0.10088439 -0.12106321] +- [0.00029886 0.00013531 0.0005754]

baseline T_2_1:
   q: [0.0480869 0.2779485 0.02116101 0.95915822] +- [0.00115965 0.00111981 0.00048232]
   t: [-0.85996164 -0.08389406 -0.30279685] +- [0.00145022 0.00100808 0.0019561]

Target configuration
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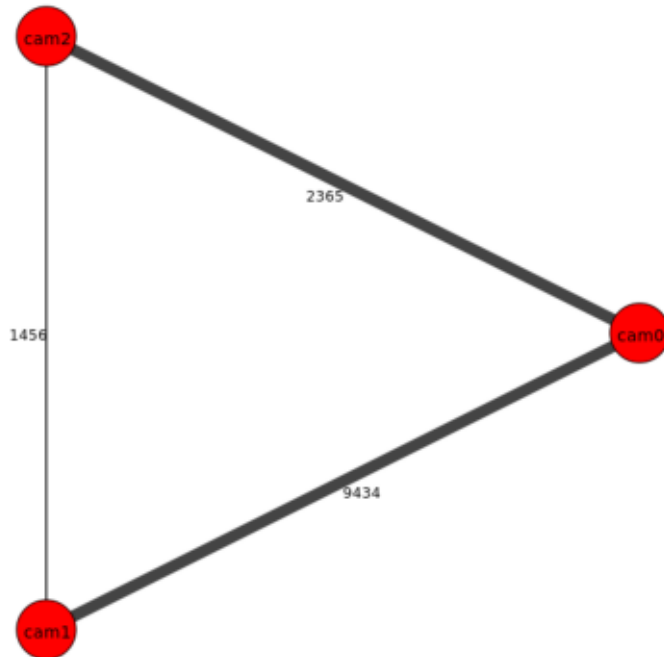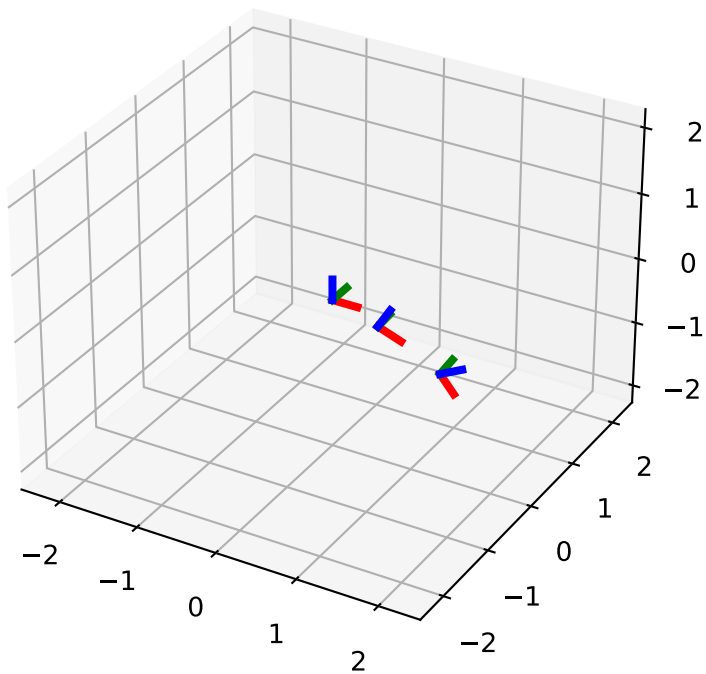 Type: aprilgrid

Tags:
  Rows: 6
  Cols: 6
  Size: 0.099 [m]
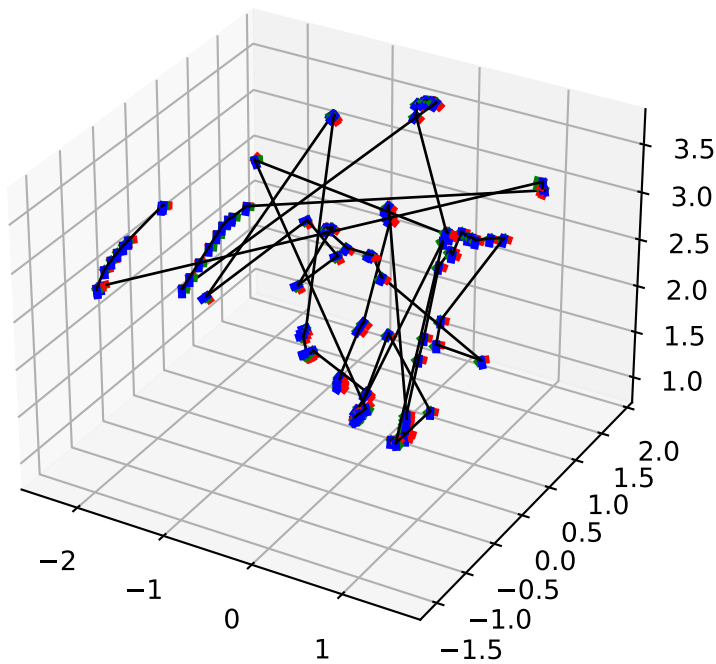 Spacing 0.0299999997 [m]

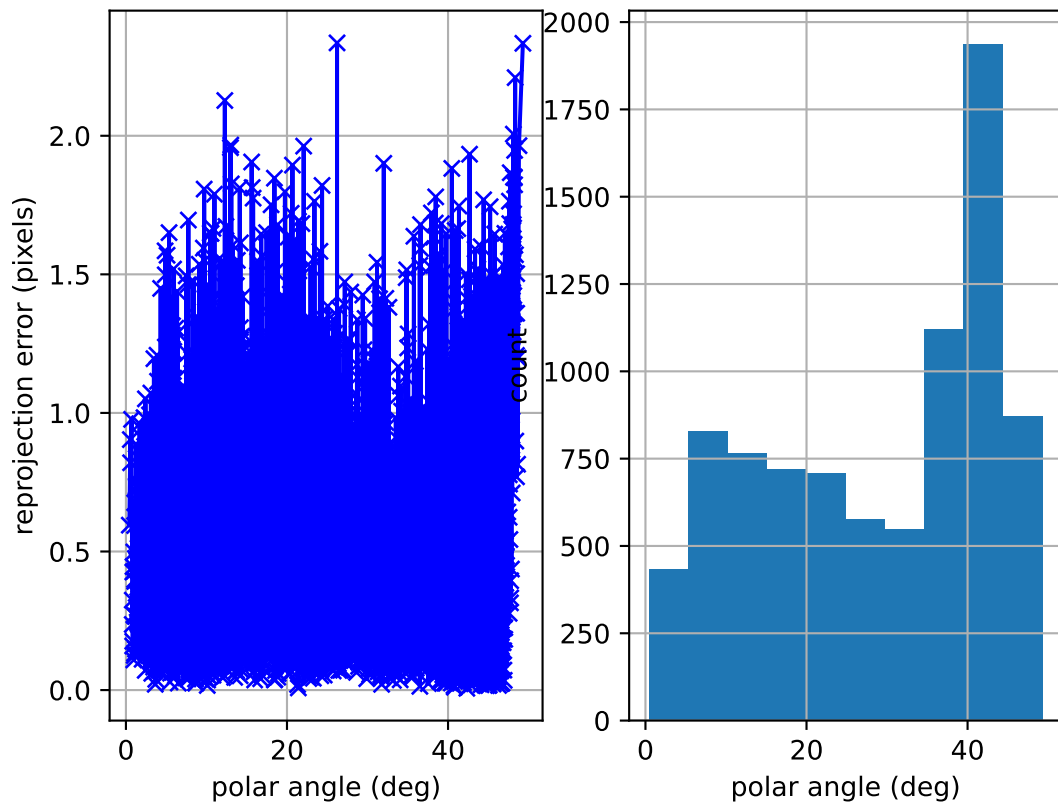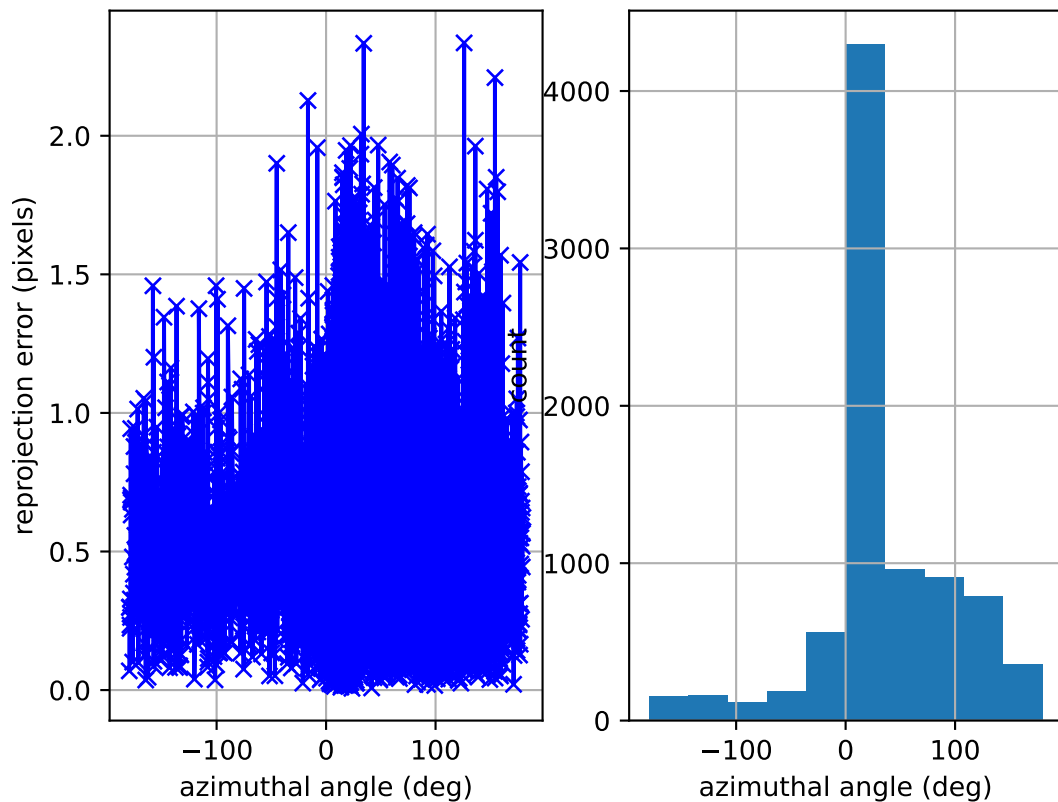Inter-camera observations graph (edge weight=#mutual obs.)
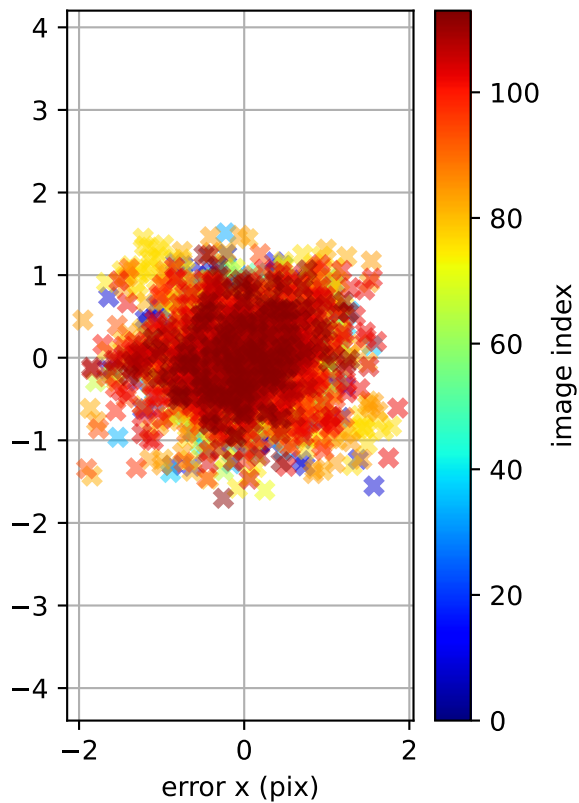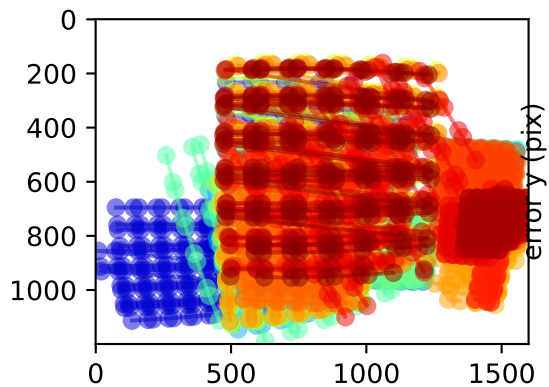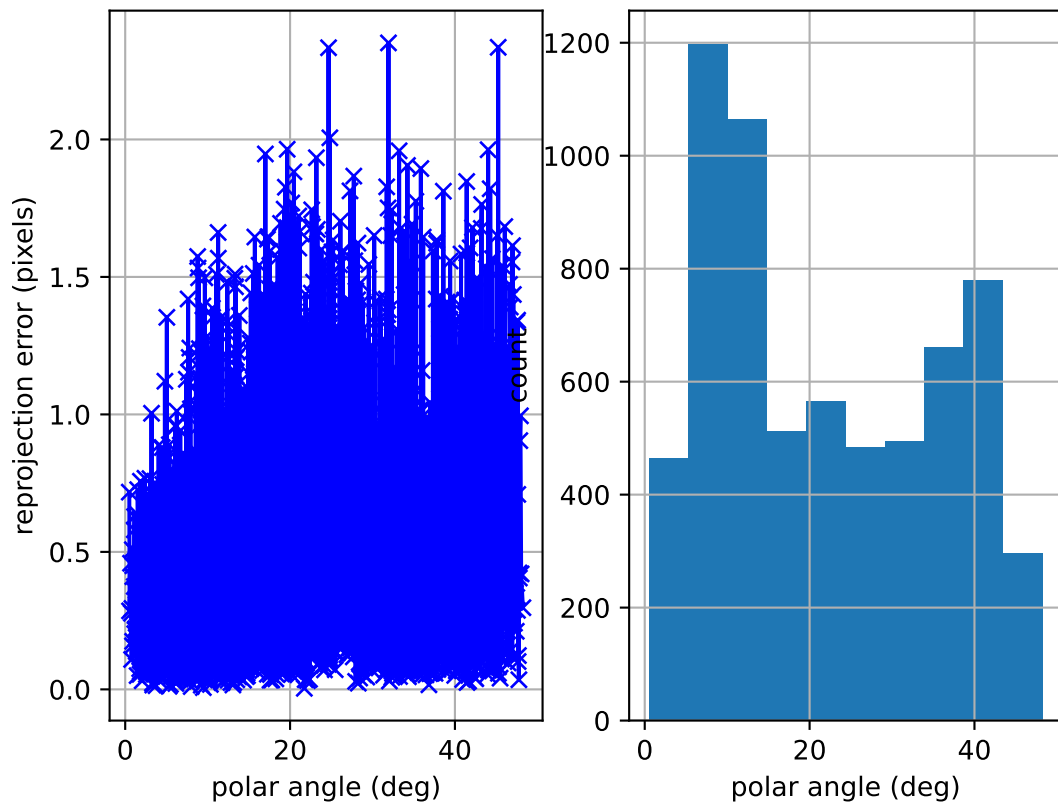
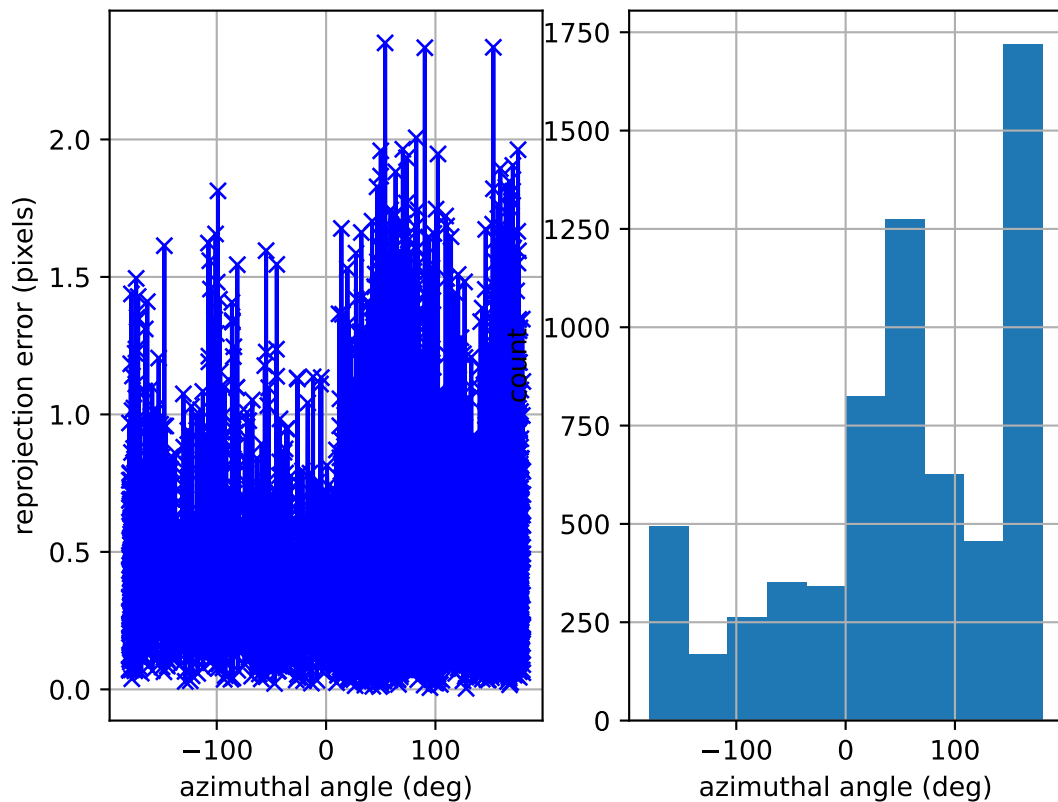camera system

cam0: estimated poses

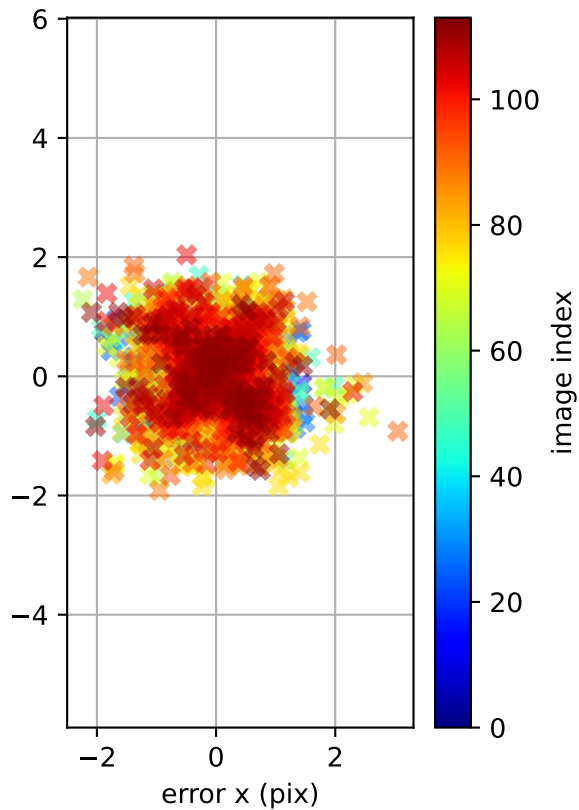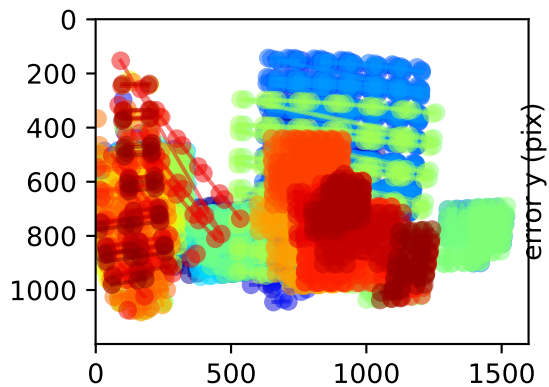cam0: polar error

cam0: azimuthal error

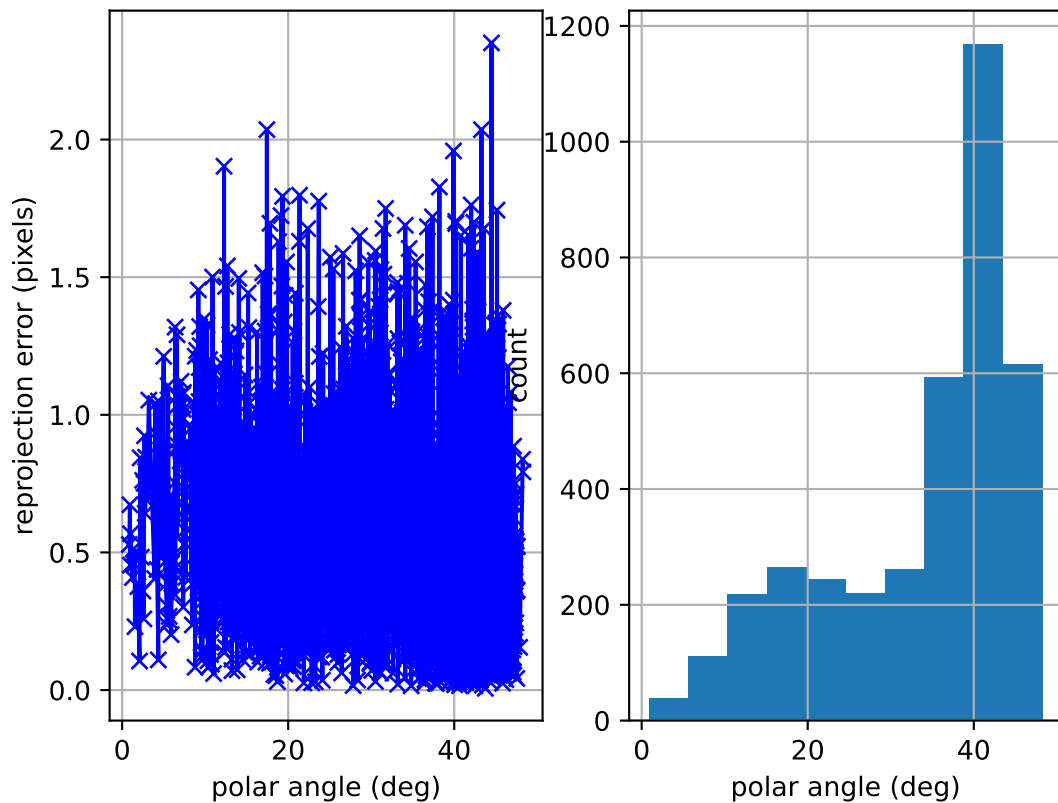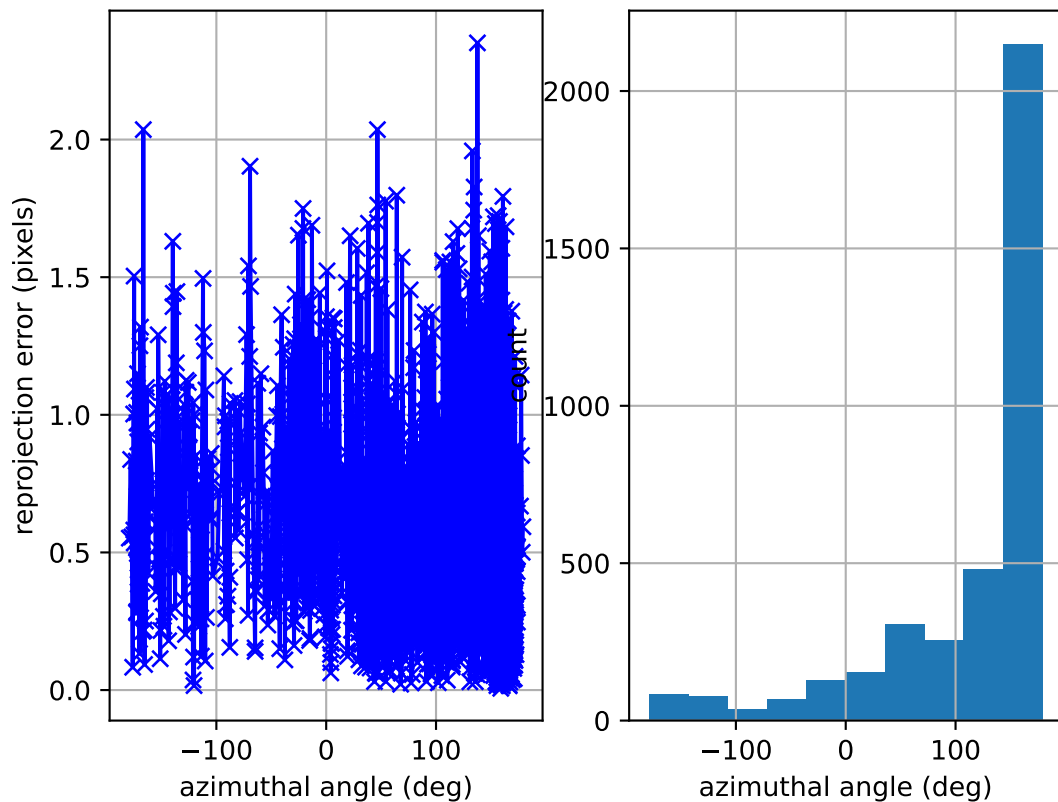cam0: reprojection errors

cam1: polar error

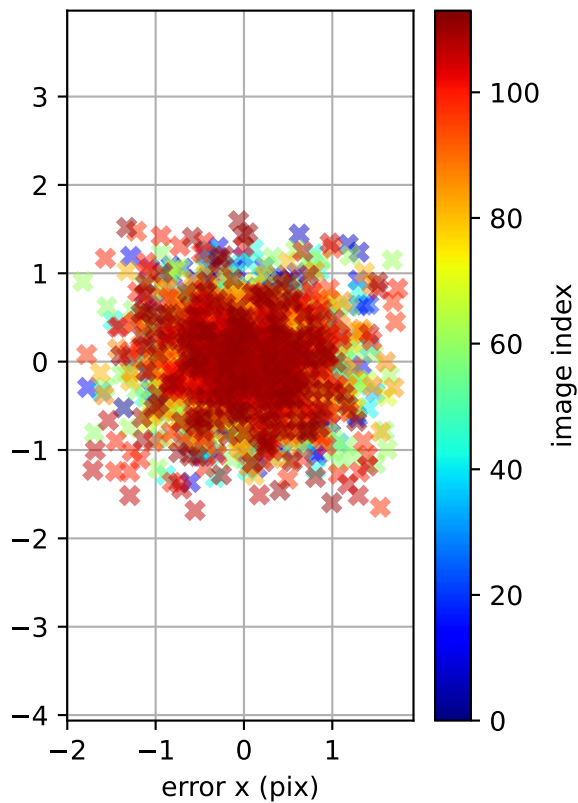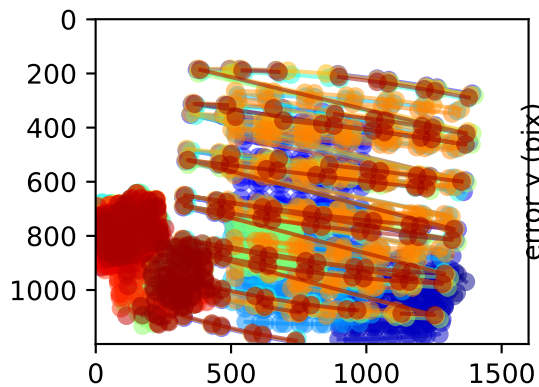cam1: azimuthal error

cam1: reprojection errors

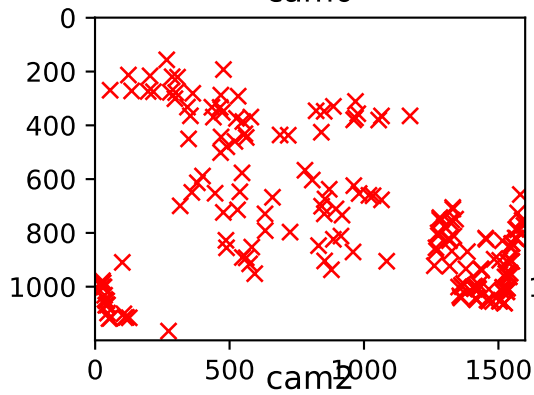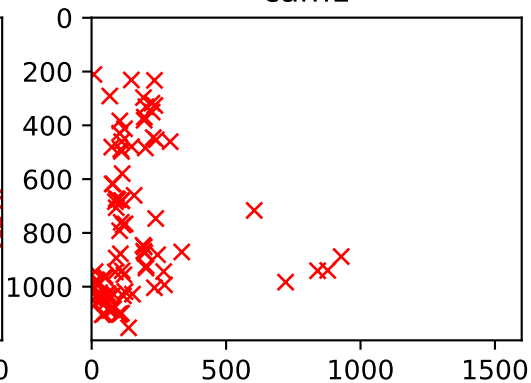cam2: polar error

cam2: azimuthal error

cam2: reprojection errors

Location of removed outlier corners