ECEN 743: Reinforcement Learning

Exploration in RL

Dileep Kalathil
Assistant Professor
Department of Electrical and Computer Engineering
Texas A&M University

References

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- [Posterior Sampling Algorithm] Chapter 36, Tor Lattimore and Csaba Szepesvári, "Bandit algorithms". Cambridge University Press, 2020.

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 - ► This is one of the fundamental (research) problems of RL

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Restaurant Selection



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- How to select arms if the mean values are unknown a priori?







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- Objective: select actions to maximize the expected cumulative reward

$$\max_{(a_t)_{t=1}^T} \ \mathbb{E}[\sum_{t=1}^T r(a_t)]$$

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- Can we get a regret: $O(T^2)$? O(T)? $O(\sqrt{T})$? $O(\log T)$?
- What is the fundamental lower bound? Is there any algorithm that achieves the lower bound?

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 - Explore always, with the same epsilon probability (linear regret)

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• Let $n_k(t)$ be th number of times arm k has been selected until t.

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 - ► Can get sublinear regret. But need additional information

• Fundamental lower bound [Lai and Robbins, 1985]: Assume that $X_k(t) \sim P_k$ (i.e., P_k is the distribution of the rewards from arm k). Then,

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Upper Confidence Bound (UCB) Algorithm

• Let $\hat{\mu}_k(t) = \frac{1}{n_k(t)} \sum_{\tau=1}^t r(a_\tau) \; \mathbb{I}\{a_\tau = k\}$ be the empirical mean reward obtained from arm k until t

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Under UCB algorithm,

$$\operatorname{Reg}(T) \le 8 \sum_{k=2}^{K} \frac{\log T}{(\mu_1 - \mu_k)} + 4K$$

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Lemma (Hoeffding's inequality)

Let $\hat{\mu}(t) = \frac{1}{t} \sum_{\tau=1}^{t} X_{\tau}$, where X_{τ} s are i.i.d. random variables with $\mathbb{E}[X_{\tau}] = \mu$. Also, let $b_l \leq X_{\tau} \leq b_h$. Then,

$$\mathbb{P}(|\hat{\mu}(t) - \mu| \ge \epsilon) \le 2 \, \exp\left(-\frac{2t\epsilon^2}{(b_h - b_l)^2}\right)$$

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• So, we can bound the probability of the fist set as

$$\mathbb{P}(\{\mu_1 \ge \min_t g_1(t)\}) \le 2T\delta$$

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- Now, we can bound the probability of the second set as

$$\begin{split} \mathbb{P}(\left\{g_{k,m_{k}} \geq \mu_{1}\right\}) &= \mathbb{P}(\left\{\hat{\mu}_{k,m_{k}} + \sqrt{\frac{\log(1/\delta)}{2m_{k}}} \geq \mu_{1}\right\}) = \mathbb{P}(\left\{\hat{\mu}_{k,m_{k}} - \mu_{k} + \sqrt{\frac{\log(1/\delta)}{2m_{k}}} \geq \mu_{1} - \mu_{k}\right\}) \\ &= \mathbb{P}(\left\{\hat{\mu}_{k,m_{k}} - \mu_{k} \geq \Delta_{k} - \sqrt{\frac{\log(1/\delta)}{2m_{k}}}\right\}) \leq \mathbb{P}(\left\{\hat{\mu}_{k,m_{k}} - \mu_{k} \geq \frac{\Delta_{k}}{2}\right\}) \\ &\leq 2 \mathrm{exp}(-2m_{k}\frac{\Delta_{k}^{2}}{4}) = 2 \mathrm{exp}(-\log(1/\delta)) = 2\delta \end{split}$$

• We will bound $G_k^c = \{\mu_1 \leq \min_t g_1(t)\}^c \cup \left\{g_{k,m_k} \leq \mu_1\right\}^c$

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- Combining the probability bound for the first and second term, we get

$$\mathbb{P}(G_k^c) \le 2T\delta + 2\delta = 2(T+1)\delta$$

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Now, using the definition of regret

$$\mathsf{Reg}(T) = \sum_{k=1}^K \Delta_k \mathbb{E}[n_k(T)] \leq \sum_{k=1}^K \frac{4}{\Delta_k} \log(T) + 4K$$

• For UCB Algorithm we first proved that, $\mathbb{E}[n_k(T)] \leq \frac{4\log(T)}{\Delta_k^2} + 4$. Using, this, we concluded that $\operatorname{Reg}(T) = \sum_{k=1}^K \Delta_k \mathbb{E}[n_k(T)] \leq \sum_{k=1}^K \frac{4}{\Delta_k} \log(T) + 4K$.

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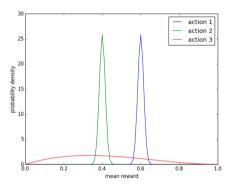
exploration

$$\operatorname{Reg}(T) = \min\{\frac{4K}{\Delta_{\min}} \log T, \ 5\sqrt{KT}\}$$

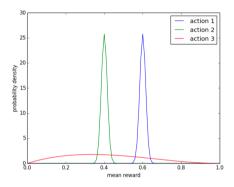
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Posterior Sampling Algorithm

• Which arm will you select?

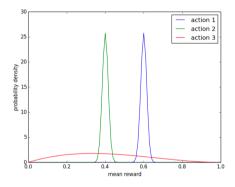


• Which arm will you select?



ullet Can we select an arm k proportional to the probability that μ_k is the maximum?

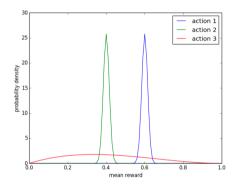
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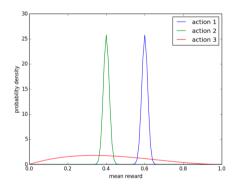
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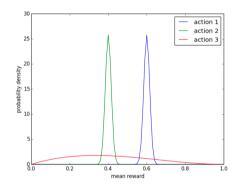
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- Exact probability matching is computationally challenging
- Posterior Sampling (also known as Thompson Sampling) overcomes this difficulty by sampling

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Prior, likelihood, and posterior

$$\underbrace{p(\theta = y|x_1)}_{\text{posterior}} \propto \underbrace{p(x_1|\theta = y)}_{\text{likelihood}} \underbrace{p_{\text{prior}}(\theta = y)}_{\text{prior}}$$

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- For example, exponential families have conjugate priors

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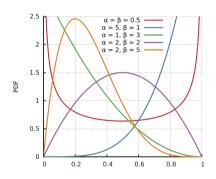
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• Similarly, if R=0, posterior is $Beta(\alpha, \beta+1)$

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 - ▶ This is a useful model, for example in modeling advertisement placement based on click through rate
- Assume the prior distribution on θ as Beta (α, β)
- Suppose we get a reward R = 1. What is the posterior?

$$\begin{split} p(\theta = y|R = 1) &\propto p(R = 1|\theta = y) \ p(\theta = y|(\alpha,\beta)) \\ &= y \ \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} y^{(\alpha-1)} (1-y)^{\beta-1} \\ &\propto y^{((\alpha+1)-1)} (1-y)^{\beta-1} &\propto \mathrm{Beta}(\alpha+1,\beta) \end{split}$$

- Similarly, if R = 0, posterior is Beta $(\alpha, \beta + 1)$
- So, Bernoulli and Beta are conjugate priors

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Algorithm 6 Posterior Sampling Algorithm

```
1: for t=1,2,\ldots do

2: # sample the parameter

3: for k=1,\ldots,K do

4: \theta_k \sim \operatorname{Beta}(\alpha_k,\beta_k)

5: end for

6: # select action

7: a_t = \operatorname{arg} \max_k \theta_k

8: Observe the reward R_t

9: # update the posterior

10: (\alpha_{at},\beta_{at}) \leftarrow (\alpha_{at}+R_t,\beta_{at}+R_t)
```

11: end for

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• Recall the regret definition

$$\operatorname{Reg}(T) = \mu_1 T - \mathbb{E}[\sum_{t=1}^{T} r(a_t)] = \mu_1 T - \mathbb{E}[\sum_{t=1}^{T} \sum_{k=1}^{K} \mathbb{1}\{a(t) = k\} X_k(t)]$$

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- Let $\theta = (\theta_1, \theta_2, \dots, \theta_K)$ be the parameter of the reward distribution, i.e., $X_k \sim p(\cdot | \theta_k)$. Denote $\mu^*(\theta) = \max_k \{\mu_k(\theta_k)\}$ where $\mu_k(\theta_k)$ is the mean reward from arm k.

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- We can then define the regret when parameter is θ as

$$\mathsf{Reg}(T;\theta) = \mu^*T - \mathbb{E}_{p(\cdot|\theta)}[\sum_{t=1}^T r(a_t)]$$

Bayesian regret is defined as

$$\mathsf{Bayes\text{-}Reg}(T) = \mathbb{E}_{\theta \sim p_{\mathrm{prior}}}[\mathsf{Reg}(T;\theta)]$$

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Performance of Posterior Sampling Algorithm

Theorem

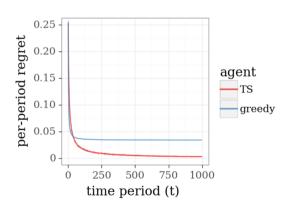
Under posterior sampling algorithm,

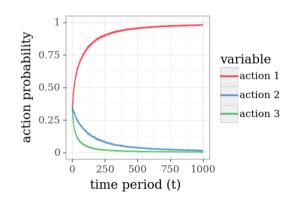
$$\begin{aligned} \textit{Reg}(T;\theta) &= O(\frac{K}{\Delta_{\min}} \log T) \\ \textit{Bayes-Reg}(T) &= \mathbb{E}_{\theta \sim p_{\text{prior}}}[\textit{Reg}(T;\theta)] = O(\sqrt{KT \log T}) \\ \max_{\theta} \; \textit{Reg}(T;\theta) &= O(\sqrt{KT \log T}) \end{aligned}$$

Performance of Posterior Sampling Algorithm

Theorem

Under posterior sampling algorithm, $\operatorname{Reg}(T) = O(K \log T)$





Exploration in Deep RL

Hard Exploration Problems

• An RL algorithm learns a policy using the reward feedback

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- This works well if rewards are dense

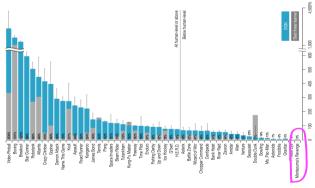
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- Probability of getting a reward exponentially decreases with the length of the sequence
- Random exploration is unlikely to get a reward signal in such problems

Some References

- Count-based exploration
 - ▶ [Strehl and Littman, 2008, Bellemare et al., 2016, Tang et al., 2017]
- Prediction-based exploration
 - ► [Schmidhuber, 1991, Pathak et al., 2017, Burda et al., 2018a, Houthooft et al., 2016, Burda et al., 2018b]
- Memory-based exploration
 - ▶ [Badia et al., 2019, 2020]
- For a good survey of exploration in deep RL, see [Weng, 2020]

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