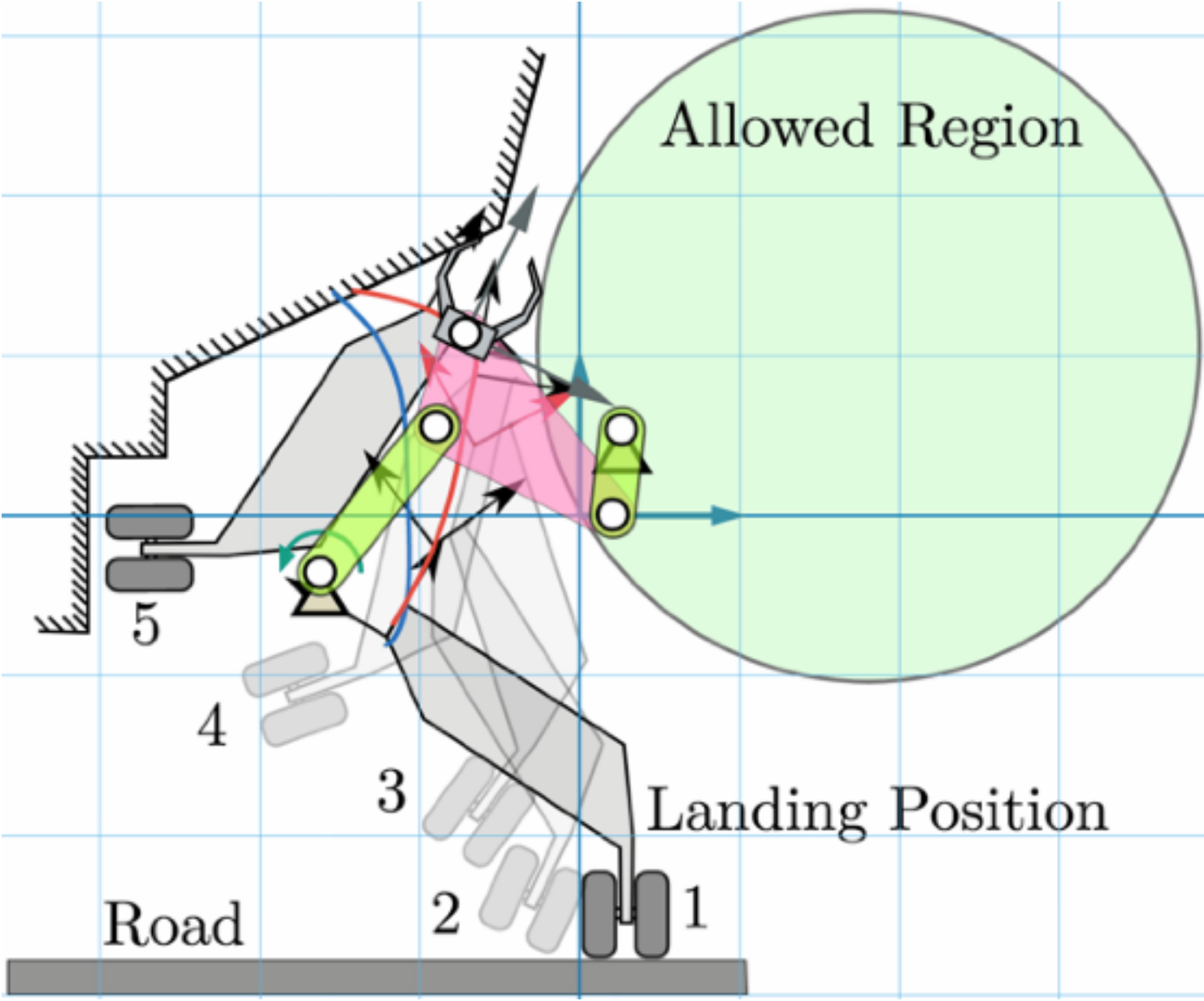
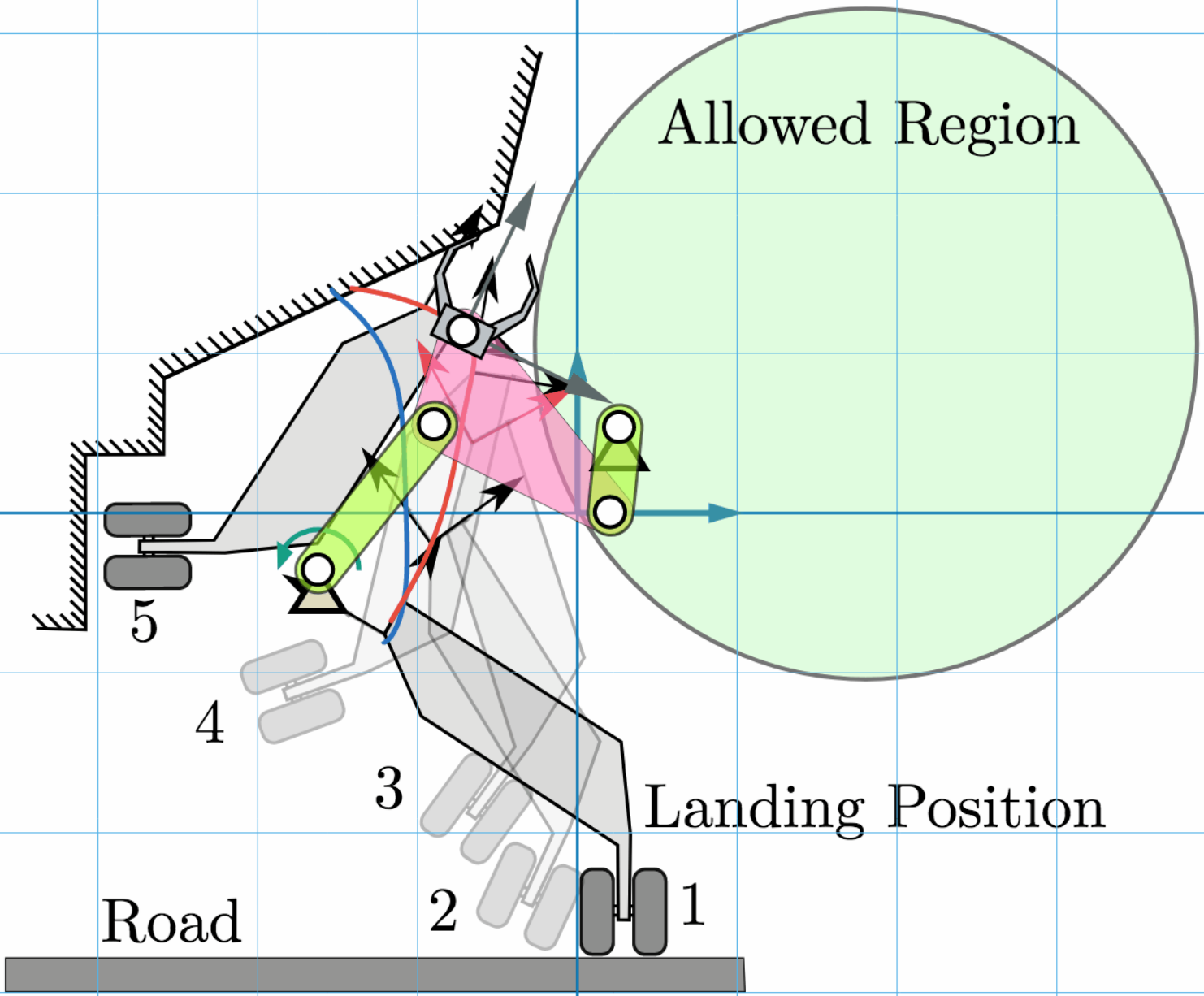


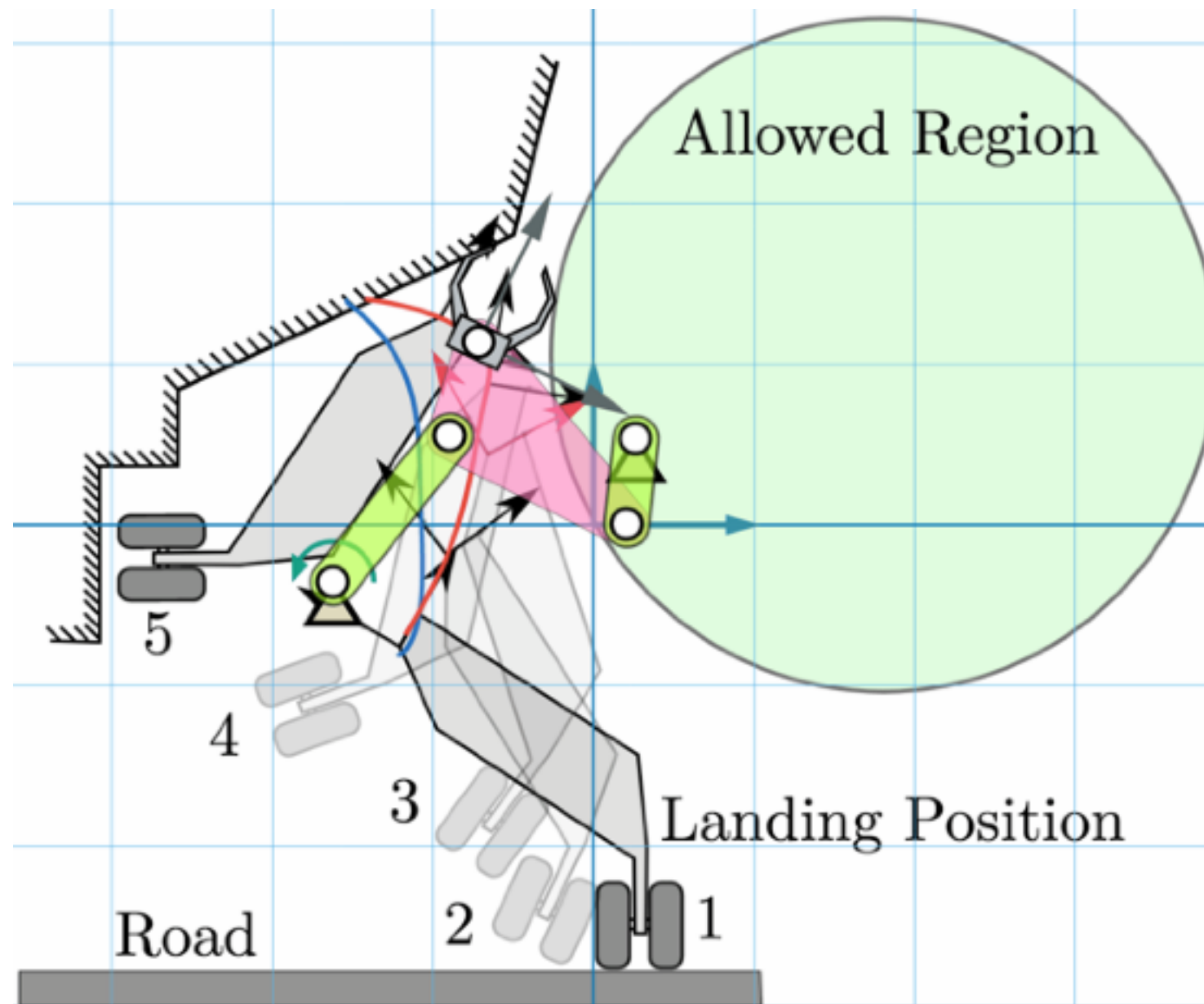
Solutions for Relaxed Third-Party

- Six dyads obtained which in combination make up to 15 linkages.



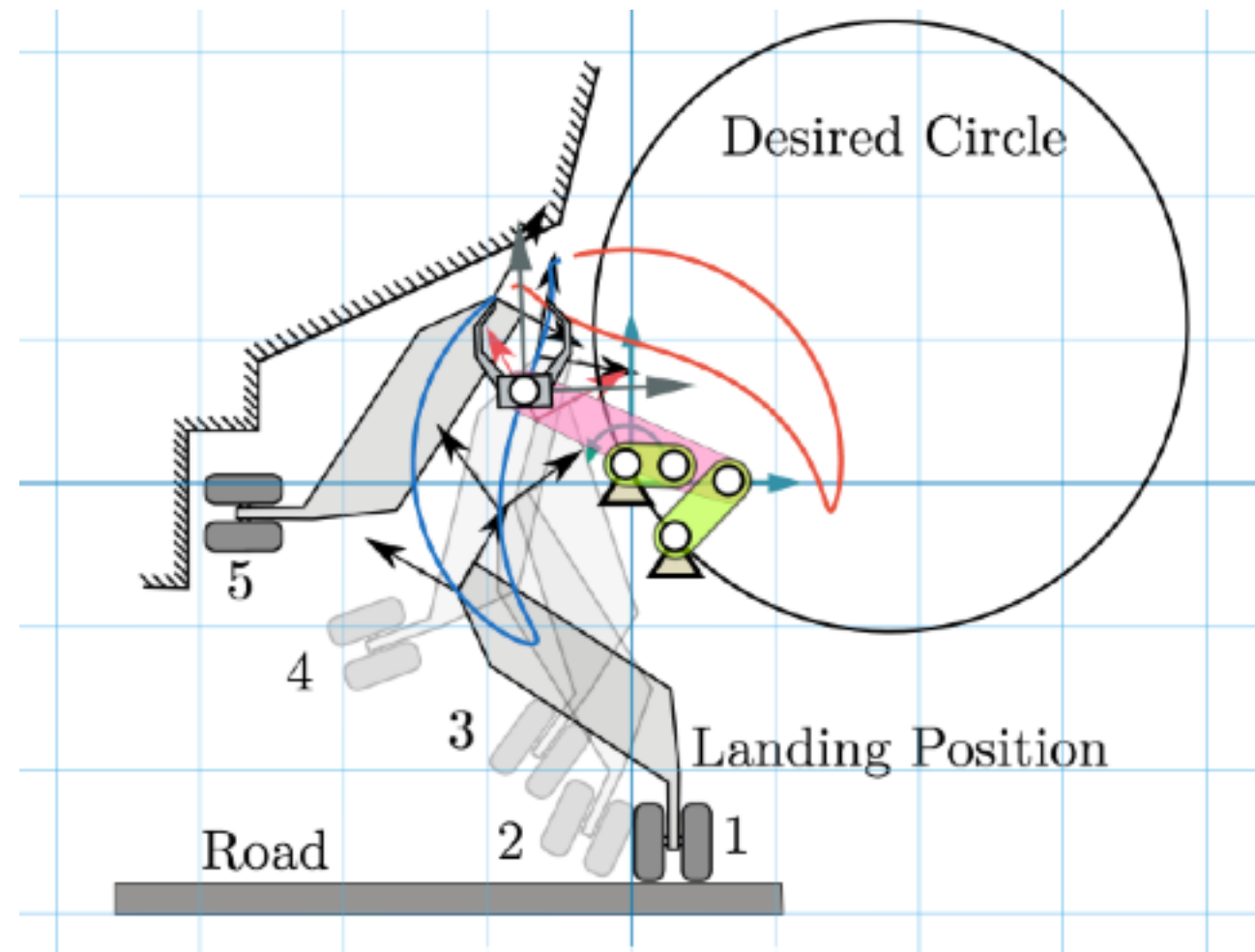
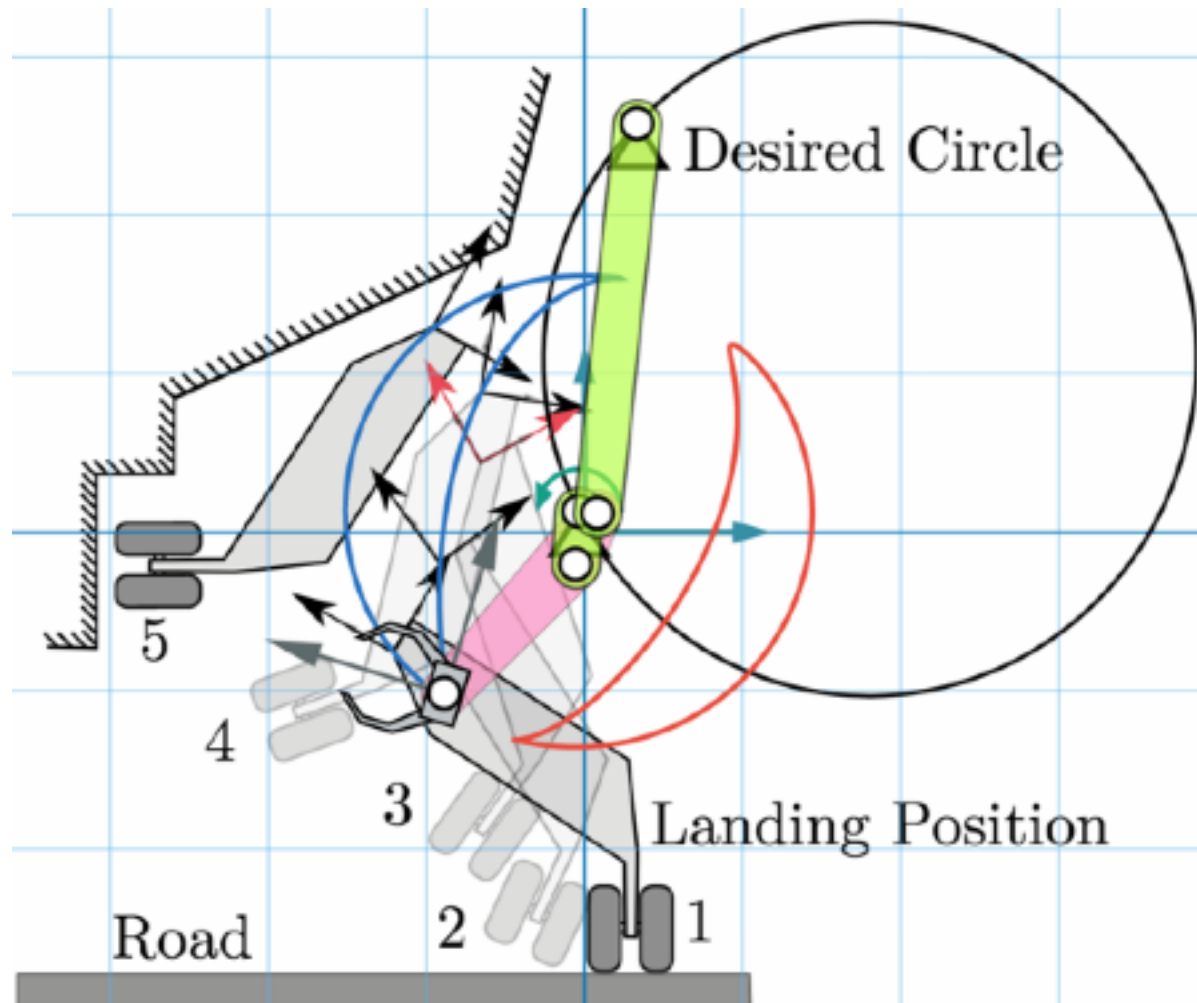


Solutions for Relaxed Third Pose



- Six dyads obtained which in combination make up to 15 linkages.

Strict Circle Constraint



- Three dyads with fixed pivots exactly on desired circle are obtained.
- First Mechanism is Grashof crank-rocker Mechanism