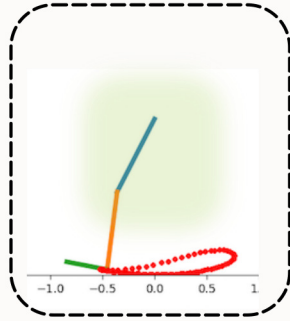
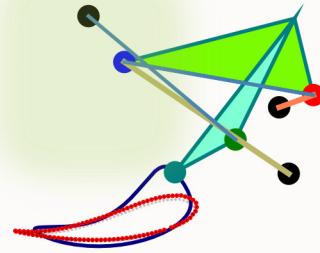


Path (Y)

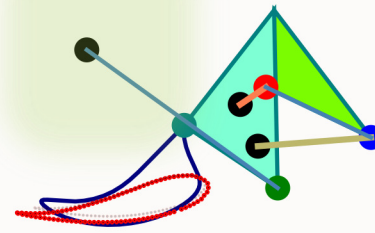


Generated Six-Bars ($\hat{X} = G(z, Y)$)

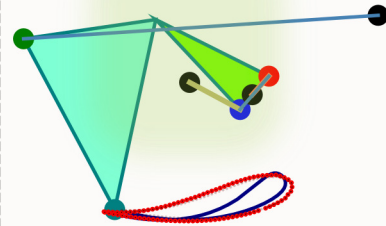
1)



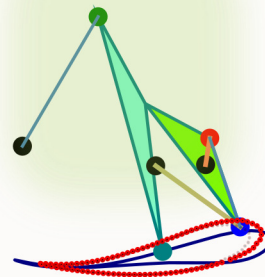
2)



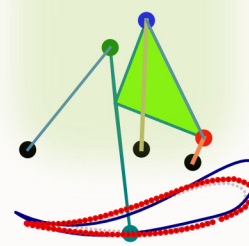
3)



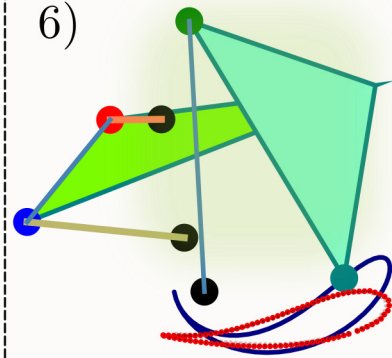
4)



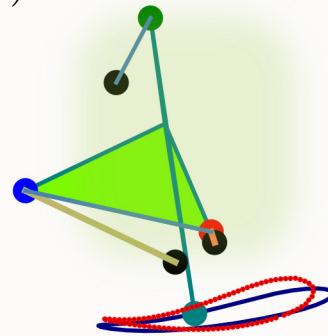
5)



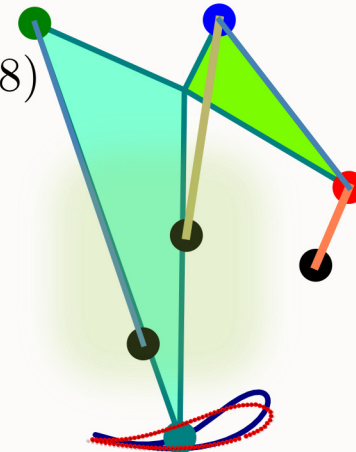
6)



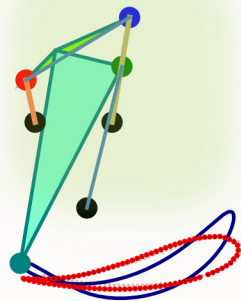
7)



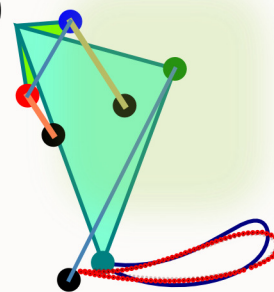
8)



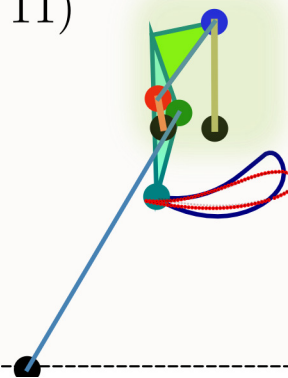
9)



10)



11)



Designs for Gait Rehabilitation Device

