MIPLIB 2010

Mixed Integer Programming Library version 5

Thorsten Koch · Tobias Achterberg · Erling Andersen · Oliver Bastert · Timo Berthold · Robert E. Bixby · Emilie Danna · Gerald Gamrath · Ambros M. Gleixner · Stefan Heinz · Andrea Lodi · Hans Mittelmann · Ted Ralphs · Domenico Salvagnin · Daniel E. Steffy · Kati Wolter

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Abstract This paper reports on the fifth version of the Mixed Integer Programming Library. The MIPLIB 2010 is the first MIPLIB release that has been assembled by a large group from academia and from industry, all of whom work in integer programming. There was mutual consent that the concept of the library had to be expanded in order to fulfill the needs of the community. The new version comprises 361 instances sorted into several groups. This includes the main benchmark test set of 87 instances, which are all solvable by today's codes, and also the challenge test set with 164 instances, many of which are currently unsolved. For the first time,

Thorsten Koch, Timo Berthold, Gerald Gamrath, Ambros M. Gleixner, Stefan Heinz, Daniel E. Steffy, Kati Wolter

Zuse Institute Berlin, Takustr. 7, 14195 Berlin, Germany

E-mail: {koch,berthold,gamrath,gleixner,heinz,steffy,wolter}@zib.de

Tobias Achterberg

IBM Deutschland, E-mail: achterberg@de.ibm.com

Erling Andersen

MOSEK, E-mail: e.d.andersen@mosek.com

Oliver Bastert

FICO, E-mail: oliverbastert@fico.com

Robert E. Bixby

Gurobi, E-mail: bixby@gurobi.com

Emilie Danna

 $Google, \ E\text{-mail: edanna@google.com}$

Andrea Lodi

University of Bologna, E-mail: andrea.lodi@unibo.it

Hans Mittelmann

Arizona State University, E-mail: mittelmann@asu.edu

Ted Ralphs

Lehigh University, E-mail: ted@lehigh.edu

Domenico Salvagnin

Università degli Studi di Padova, E-mail: salvagni@dei.unipd.it

we include scripts to run automated tests in a predefined way. Further, there is a solution checker to test the accuracy of provided solutions using exact arithmetic.

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1 Introduction

The MIPLIB is now going into its fifth incarnation. Starting in 1992 with the first two versions by Bixby, Boyd, and Indovina [?], the update to MIPLIB 3 by Bixby, McZeal, Ceria, and Savelsbergh [?] in 1996, and the compilation of MIPLIB 2003 by Achterberg, Koch, and Martin [?], we have finally arrived at MIPLIB 2010. The motivation for this update is the same as in the previous versions: the continuous progress in the field of mixed integer programming.

A mixed integer (linear) program (MIP) is an optimization problem in which a linear objective function is minimized subject to linear constraints over real- and integer-valued variables. For details on mixed integer programming, see, e.g., [?,?]. The MIPLIB is a diverse collection of challenging real-world MIP instances from various academic and industrial applications suited for benchmarking and testing of MIP solution algorithms.

In this paper, we provide a detailed description of the instances in MIPLIB 2010, including their origin, information on the coefficient matrices, and the types of constraints and variables they contain. The complete library is available online at http://miplib.zib.de, where we have collected further information, such as references to papers that have used the MIPLIB as a test set for their algorithms. If available, we also provide a problem description in an algebraic modeling language, such as AMPL [?] or ZIMPL [?]. In addition to the role of MIPLIB as a test suite for integer programming algorithms, we strongly encourage investigation of alternative models for the given problems.

MIPLIB classifies instances into three categories: easy for those that can be solved within an hour on a contemporary PC with a state-of-the-art solver, hard for those that are solvable but take a longer time or require specialized algorithms, and finally open instances for which the optimal solution is not known. This classification is kept up-to-date on the website, and we ask for notification whenever an optimal solution is determined for an open instance. The website also contains details if specific settings have been used to solve an instance.

The progress in solving real-world MIP instances has been exceptional over the last decades. It is recorded in various articles [?,?,?] and numerous talks. One example is the solvability of the MIPLIB 2003 instances. As shown in Figure 1, at the start of MIPLIB 2003 there were 22 easy, three hard, and 35 open instances. By the end of 2010, 41 were classified as easy, 15 as hard, and only four open instances remained.

Another showcase is the speedup of commercial MIP solvers. Figure 2 depicts the progress made by two of the commercial solver vendors with long traditions, CPLEX and XPRESS. These figures are based on their internal test sets and record purely the speedup due to algorithmic improvements. For CPLEX the geometric mean of the speedup is drawn and for XPRESS the reduction in total solution time.

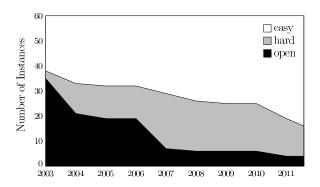


Fig. 1: Number of MIPLIB 2003 instances classified as easy, hard, and open over time

Though these measures cannot be compared directly, they both show the impressive performance improvements gained during the last years.

Combining a pure algorithmic speedup of 55,000 with the speedup in computing machinery, we see that solving MIPs has become something like 100 million times faster in the last 20 years.

This easily translates into the difference between considering an instance to be trivial versus unsolvable.

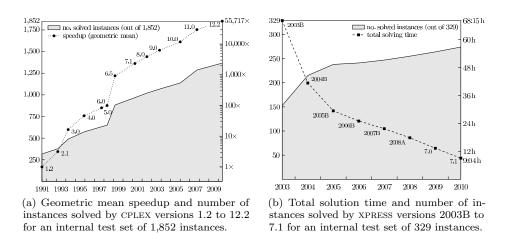


Fig. 2: Performance improvements of CPLEX and XPRESS

This might give the misleading impression that all mixed integer programs are easy to solve nowadays. However, keep in mind that practitioners often experiment with tractable instances. In this sense, MIP codes tend to be tuned to more efficiently solve those models that are already known to be solvable. In order to compensate

Table 1: Overview of different test sets and the number of instances contained in each of them

B BENCHMARK (87 instances)

contains only instances that can be solved to optimality by at least one solver within two hours on a high-end ${
m PC}$. Except for the test sets ${
m CHALLENGE}$ and ${
m UNSTABLE}$, at least one instance from each of the other test sets is included in this one.

I INFEASIBLE (20 instances)

contains instances that are infeasible.

P PRIMAL (40 instances)

contains instances for which the solution of the root LP relaxation has the same objective value as the optimal solution, i.e., the solver "only" has to find an optimal solution; the proof of optimality comes for free.

X XXL (11 instances)

contains very large instances with respect to the number of variables, constraints, and non-zeros.

R REOPTIMIZE (66 instances)

contains instances for which the reoptimization of the sub-LPs takes an unusually long time.

T TREE (52 instances)

contains instances that (empirically) lead to large enumeration trees.

U UNSTABLE (21 instances)

contains instances that have bad numerical properties and are likely to cause numerical troubles in the solver. This set is intended to test solver robustness.

C CHALLENGE (164 instances)

is a compilation of hard-to-solve instances as well as instances that to our knowledge have not been solved to optimality. There are 21 instances in this set for which we have not yet been able to compute any feasible solution. Some of these may of course be infeasible.

for this, we added a large set of instances to MIPLIB 2010 that are out-of-scope for today's solvers. As of this writing, the 361 instances of MIPLIB 2010 are classified as follows: 185 easy, 42 hard, and 134 open.

2 The test sets

During the initial discussions among the authors, it became evident that a single test set that also includes many very hard or even unsolved instances was not going to be sufficient. Researchers have often focused their attention on subsets of the MIPLIB 2003 instances that were suited to their particular topic of study. This often resulted in inadequate test sets because the full library only contained 60 instances, and added restrictions further reduced this size.

Therefore, we identified several areas for which dedicated test sets should be made available. Please note that a particular instance can be part of more than one test set. Table 1 gives an overview of all test sets.

2.1 What are the sources of the instances?

We started a call for instances on March 26, 2010. Submission was closed in October 2010. In total we received over 1,108 instances from 57 contributors. Thanks to all of them! All contributed instances, unchanged, can be found at the MIPLIB homepage¹. Additionally, we had access to a large number of instances from the NEOS server.

http://miplib.zib.de/contrib/submission2010

Table 2: Origin of instances

MIPLIB	2
MIPLIB 3 (excluding those from MIPLIB)	7
MIPLIB 2003 (excluding those from MIPLIB 3)	17
other publicly available	180
new contributions	155

Problems submitted to the solvers SCIP, FEASPUMP, QSOPT_EX in various formats were translated to MPS format. For problems originally stated as AMPL model files, these files are preserved on the MIPLIB website.

Finally, we collected publicly available instances from the internet including instances available from the Berkeley Computational Optimization Lab [?], the Computational Optimization Research at Lehigh test set (cor@l) [?], and the DEIS – Operations Research Group Library of Instances [?]. Table 2 shows the distribution of instances according to their origin.

2.2 How were the instances selected?

In the following sections, we often mention that instances can be solved within certain time limits. Unless mentioned otherwise, this refers to experiments that were performed on dual core Intel Xeon E5420 $2.5\,\mathrm{GHz}$ computers with $4\,\mathrm{MB}$ cache and $16\,\mathrm{GB}$ of main memory, running Linux in $64\,\mathrm{bit}$ mode.

After the submission of contributed instances was closed and the data mining of the public domain was finished, the initial candidate set contained about 2,000 instances.

Exclusion of trivial instances and (near) duplicates. In a first filtering step, duplicates were eliminated, homogeneous problem subsets were reduced, and instances which were too easy, i.e., could be solved by either SCIP or CBC in less than one minute, were removed. The typical case for homogeneous test sets was that many variations of the same model with different data were submitted. When comprising these sets of similar problems, we tried to keep the variety while reducing the set to less than ten instances.

Examination and pre-selection by eight groups. The 659 remaining instances were examined independently by eight teams formed by the authors. Two instances entered the final test sets on short notice, as it was realized that certain classes of problems were not well represented in the candidate set. These were unitcal.7, a unit commitment model, and cov1075, a highly symmetric problem. Except for these two, all instances contained in the final test sets were part of this list of 659.

After the responses from the different groups had been evaluated, a first proposal of 100 instances plus 45 potential substitutes for the BENCHMARK set was compiled and circulated again. The minimal requirements for the BENCHMARK set were that first every instance could be solved to proven optimality within 24 hours by at least one solver and second that each of the other test sets except the UNSTABLE and the CHALLENGE set, were represented in the BENCHMARK set by at least one instance.

Final refinement of the benchmark set. Starting from this proposal, several instances had to be exchanged or eliminated for one of the following reasons:

- problem classes were over- or underrepresented,
- instances proved to be too easy or too hard when checking them on different machines with the current developer versions of the involved software, or
- instances were discovered to be numerically difficult.

In cases where we had to choose between two instances, newly contributed ones were favored and instances for which the application was unknown, e.g., instances that have been provided via the Neos server, were disfavored. Also, instances that showed a stable performance (see also Section 5) were favored. Finally, we tried to keep the overall running time of the BENCHMARK set reasonable.

It was far easier to exclude instances for the reasons named above than to include new ones that fulfilled all hard and soft requirements. We are satisfied to have arrived at a final BENCHMARK set with 87 instances. We believe that this test set is well-suited for benchmarking purposes: nearly all instances can be solved in less than one hour by at least one solver, but only a few of them can be solved within less than a minute by any current solver.

Most of the other test sets were created by predefined rules rather than dynamically, as with the BENCHMARK set. Because many criteria at least partially depend on the computational environment, e.g., number of simplex iterations, the numbers listed in the following paragraphs are only guiding values. The different test sets were double checked with different software packages on different machines to minimize the risk that some instance entered a particular test set just by chance.

The REOPTIMIZE test set. Warm-starting the simplex algorithm is one of the key requirements for efficiency in LP-based branch-and-bound algorithms. Often, reoptimizing an LP after changing a bound can be done in less than ten simplex iterations, whereas the initial LP solve takes thousands of iterations. However, there are a few cases when this advantage of the simplex vanishes. The REOPTIMIZE set is a collection of them. It contains instances for which LP reoptimization takes at least 500 simplex iterations on average. This does not include simplex iterations that have been performed at the root node. Furthermore, instances were only included if they required at least 100 nodes to solve.

The TREE test set. In the development of MIP solvers, many algorithmic improvements aim at reducing the size of the branch-and-bound tree. As a consequence, MIP solvers are often able to solve instances to proven optimality in the root node or after only a few hundred nodes. The test set TREE, however, comprises instances for which state-of-the-art MIP solvers perform a large amount of enumeration. The criterion applied for this test set was that the branch-and-bound tree created when solving the instance contains at least 1,000,000 nodes.

The XXL test set. Predicting the performance of a MIP solver just by knowing the dimensions of an instance is impossible. The markshare examples [?] show that problems with 60 variables and 6 constraints may be extremely hard to solve for state-of-the-art software packages. On the other hand, there are instances that contain 100,000 or more variables that can be solved in less than a minute. The test set XXL is dedicated to MIPs that are large-scale, but not too easy. It

consists of problems with either more than a million variables, more than a million constraints, or more than 10 million non-zeros. Instances for which the majority of the variables and constraints can be eliminated by standard presolving methods were not considered.

The PRIMAL and INFEASIBLE test sets. A typical experience in solving a MIP is that finding an optimal solution is often much easier than proving its optimality. The test set PRIMAL is set up for instances for which the reverse holds. We included problems for which the bound given by the initial LP relaxation after presolving is equal to the MIP optimum. The only thing left for the solver to do is to find an optimal solution—the proof of optimality comes for free. We only included instances for which this appeared to be challenging.

Most MIP solvers are tuned for optimization problems, typically not for feasibility problems, such as the PRIMAL instances, and to our knowledge not at all for infeasible problems. The test set infeasible should help to investigate the behavior of MIP solvers for this kind of problem setting.

The CHALLENGE and UNSTABLE test sets. The new submissions contained several instances that are currently rather hard to solve. The CHALLENGE set contains problems that we could not solve in less than two hours with any of the solvers. For some of them, the optimal solution is known; for many, it is not. As of this writing, no feasible solution is known, if one exists, for 21 of these instances.

Finally, we compiled the numerics test set unstable. Mips are identified as numerically unstable if they exhibit some of the following properties: ill-conditioned basis matrices, large coefficients close to the internal numerical infinity values of the solvers, drastic performance changes with different choices of numerical tolerances, or different results reported by different solvers. See also the Paragraph 'Condition numbers and numerical reliability' on Page 18.

3 The solution checker

Together with the MIPLIB, a consistency checker is provided to validate the answers produced by floating-point based MIP solvers. It tries to recognize incorrect results, while, to a certain extent taking into account the different feasibility policies of the codes.

3.1 Floating-point arithmetic and tolerances

Most MIP solvers (in particular, all codes considered in this paper) are based on floating-point arithmetic and work with tolerances to check solutions for feasibility and to decide on optimality. In their feasibility tests, solvers typically consider absolute tolerances for the integrality constraints and relative ones for linear constraints. Some normalize the activity of linear constraints individually, others directly scale the constraint matrix.

The tolerances affect solution times and solution accuracy, normally in opposite ways, and the solvers apply different strategies here. As an example, consider the instance rocll-4-11. Some solvers compute an optimal objective function value of

-6.6556387, while others report -6.65275574. If one fixes all integer variables from the reported solution to the closest integer value and recomputes the continuous variables by solving the resulting LP with exact arithmetic, some of these post-processed solutions turn out to be infeasible with respect to exact arithmetic and zero tolerances.

It should be clear that this does *not* mean that any of the solvers made a mistake. It only means that the computed solution lies outside the feasible area described by the input file, but inside the extended feasible area created by reading in the problem and introducing tolerances. It is only solutions that are feasible in the latter sense that solvers attempt to deliver, and those are the solutions the checker checks. More precisely, the operation that rounds the reported value of the integer variables to the closest integer is *only* applied to compute fully reliable primal bounds for the MIPs as described in the paragraph 'MIP and LP solution values' in Section 6.

3.2 What do MIP solvers actually try to solve?

A binary double-precision number is represented in the form

$$(-1)^{sign} \cdot (1 + \sum_{i=1}^{52} 2^{-i}b_i) \cdot 2^e$$

where sign is a single bit indicating the sign, b_i are 52 binary digits used to represent the significant figures of the number i digits after the first binary digit and e defines the exponent, taking integer values in $e \in [-1022, 1023]$. The IEEE [?] standard defines which results should be returned by the basic arithmetic operations in order to maintain consistent behavior across different platforms.

Floating-point computations can be performed quickly on computers but the limited size of this representation has its disadvantages. The error incurred by a single operation is usually small but algorithms requiring many operations can accumulate and propagate these small errors, leading to errors of significant magnitude. A survey of the issues that can arise in floating-point computation can be found in [?]. MIP solvers implement techniques to handle these issues. We now discuss those techniques relevant to the solution checker for that phase of the process that precedes the actual solution of the problem.

The MPS file format which is used as a standard to define MIP instances requires the input numbers to be written in base 10 ASCII representation. Furthermore, the definition of the MPS file format specifies that each entry uses only 12 characters, so if a problem cannot be expressed exactly in this format, even the input file will be an approximation of the intended problem. Suppose a problem is defined in an MPS file as having the feasible region

$$\{x: Ax \le b, x \ge 0, x \in \mathbb{Z}^n\}$$
.

As this problem is read in by the solver, the entries in A, b will be transformed to a binary representation, possibly modifying their values and changing the feasible region to $\{x: \widetilde{A}x \leq \widetilde{b}, x \geq 0, x \in \mathbb{Z}^n\}$.

In addition, due to inexact floating-point computation, the solvers need to introduce tolerances, hence relaxing (introducing a perturbation of) the feasible

region. Typically relative tolerances are used. In order to do this efficiently and to improve the numerical properties of the model, the constraint matrix is usually scaled. As a result, solvers operate on something similar to

$$\left\{x: (\widetilde{Q\widetilde{A}})x \leq \widetilde{\widetilde{Qb}} + \mathbf{1}\varepsilon, x \geq -\mathbf{1}\varepsilon, x \in (\mathbb{Z} + [-\delta, \delta])^n \right\},\,$$

where ε and δ are tolerances for feasibility and integrality and 1 is the vector of all ones. As we can see, even the steps of parsing and scaling the problem can change its description. The entire solution procedure is then applied to this transformed problem.

Note that we have not even mentioned other preprocessing techniques that are applied by the solver in order to simplify the problem, such as removing redundant constraints and variables, tightening bounds and coefficients, or aggregating variables. All of this may lead to further modifications of the problem *before* the branch-and-bound and cutting plane phases are actually started.

In this regard, it is important to note that even though an instance is infeasible, it can become feasible by the extension of the feasible area due to the tolerances. This is one of the reasons why the solution checker does not try to test optimality and infeasibility but makes all tests by using solutions as returned by the solvers and with respect to the tolerances. Some different practice-oriented tests performed outside the checker are described in Section 4.

3.3 What does the solution checker test?

Given a linear programming problem, the combinatorial nature of the bases provides an efficient way to check both the optimality and the feasibility of a given solution: this is not the case for mixed integer programming problems. In the MIP setting, we cannot expect polynomially sized certificates of optimality to exist in general (assuming $\mathcal{P} \neq \mathcal{NP}$). However, it is possible to check the feasibility of a given solution in polynomial time and this is exactly the goal of our solution checker. Although conceptually simple, the implementation of such a checker still poses some questions:

- In which kind of arithmetic should we perform our calculations?
- Should we take our data from the internal floating-point representation of a solver or should we use the original text-based one?
- What tolerances should we use?

Concerning the first two questions, we decided to perform all of our computation with an arbitrary precision arithmetic package, namely GMP [?], taking the problem specification from a text-based file. In particular, we decided to use the industry standard MPS format. Note that reading the input from the MPS file, we perform no risky or potentially unsafe simplification of the coefficients; for example, if the input file contains the coefficient 0.3333333 we do not try to infer the "nicer" rational representation ¹/3, but we stick to the original ^{3,333,333}/10,000,000. As far as the solution to check is concerned, in order to keep the solution checker independent of the particular solvers and the language in which they are implemented, we decided also to read the solution from a text-based input file, whose very simple format is described in the MIPLIB package.

The solution checker performs two tests: a feasibility test of the computed solution and a consistency check of the corresponding objective value. For the feasibility test, we followed the common habit of using two, possibly different, absolute tolerances. One tolerance is used to check the satisfaction of linear constraints, including bounds on the variables, and the other tolerance is used to check integrality constraints. For its default settings, the code uses an absolute tolerance of 10^{-4} for both cases. In addition to the solution computed by the solver, the solution file contains the computed objective value. Checking its precision is conceptually trivial, at least for pure integer programming problems. However, given the potentially large absolute value of the objective function coefficients, sometimes larger than 10¹⁰, it quickly becomes a delicate matter, if one insists on using only absolute tolerances. Therefore, the checker accepts the objective value if the absolute value of the difference between the objective value computed by the checker and that read from the input file is less than 10^{-4} or if the relative error, i. e., the absolute error divided by the maximum of the absolute value of the checker's result and 1, is less than 10^{-7} .

Finally, the solution checker reports the maximum violation of the linear and integrality constraints and the absolute value of the difference between the solver's and checker's objective values.

4 How to run a test, add a solver, and what the scripts do

For the first time, MIPLIB comes with a test engine to run different solvers in a defined way, to check the answers for consistency, and to generate a table summarizing the results. In this section, we briefly explain how this engine works, enabling users to incorporate new solvers, and to adjust the scripts to their needs.

In order to allow meaningful benchmarks, the test engine runs each solver in deterministic mode² if possible and applies comparable termination criteria, i. e., the relative gap cutoff is set to 0. Concerning the performance evaluation, the wall-clock time is measured externally and solution times are reported rounded up to the second. This means the time for parsing the input file and creating the model is included. The primal-dual gap at termination is computed, assuming minimization, as

$$\mathrm{gap} = \frac{pb - db}{\inf\{|z|, z \in [db, pb]\}}$$

where pb and db are primal bound and dual bound, respectively. In case either no feasible solution was found, the problem was reported as infeasible, or $db \le 0 \le pb$, the gap is not computed and is marked as "--". In case db = pb = 0 a gap of 0 is reported. We chose this gap calculation since it is monotonically decreasing if the dual bound increases and the primal bound decreases. Moreover, this measure gives a worst case bound on the relative gap normalized by the optimal solution value.

The resulting table presents for each instance the name, the primal and dual bound along with the gap at termination, the number of branch-and-bound nodes,

² That is, given the same machine and the same settings the solver should perform identical runs. Especially in a multi-thread environment special care has to be taken to achieve this since all dependencies on the relative timing of the threads have to be removed.

and the solution time. Additionally, the status of the MIP solver and the result of the solution check are displayed. The solver status is ok for instances where the solver claims optimality, stopped if the solving process was stopped due to imposed limits, and abort otherwise, e.g., for termination due to errors in the MIP solver. Each solver is expected to write the best solution found into a solution file. If a solution file was generated, the solution gets checked and the solution status is ok or fail depending on whether or not the solution passed all tests of the solution checker (see Section 3). In case no solution was found, e.g., for infeasible problems, we report "--" as the solution status.

Optionally, a file with known primal bounds can be given. If such a file is provided and only after the solution passed the tests of the solution checker, the primal bound reported by the solver will be compared with the value given in the file. If a finite primal bound is stated in the file and the solver reports either infeasibility or an optimal solution with a significantly worse objective value, the solution status is set to mismatch. In case the solution file reports infeasibility, but the solver returns a solution within the tolerances of the solution checker, no mismatch is reported. Finally, if the solution checker code encountered internal problems, the solution status is set to error.

It is important to note that the comparison with respect to a primal solution from a file is independent of the solution checker, and requires a primal bound that is fully reliable. Here we computed the primal bounds by rounding the integer variables to the closest integer and then used exact arithmetic for solving the resulting LPs as described in Paragraph 'MIP and LP solution values' of Section 6.

At the end, we state how many instances were solved to optimality and passed the solution tests (solved), the number of failed instances (solution process was aborted or solution test failed), and the remaining number of stopped instances.

We now briefly sketch how the test engine is organized. The engine assumes a Linux environment, adoption to other UNIX-like operating systems should be possible with minor modifications. The main folder contains the files "Makefile" and "README" and the folders "bin", "checker", "instances", "scripts", and "testsets". After running the first automated test, there will be a folder named "results". The "Makefile" provides all the functionality of the test engine and the "README" is an introduction to the environment. The folder "bin" should contain the solver binaries or a (soft) link to them. The environment will check this folder for the requested solver binary. The sources for the solution checker, mentioned in Section 3, are stored in the folder "checker". The solution checker can be compiled via the provided "Makefile" of the test engine using the command make checker. All MIPLIB 2010 instances are stored in "instances". The folder "testsets" includes, for each test set described in Section 2, a file with the location of its instances, and for the BENCHMARK set a file with known primal bounds that are believed to be optimal. Log files and solution files of test runs and corresponding tables will be stored in a folder called "results" and all relevant scripts can be found in the folder "scripts".

The complete evaluation process is triggered by the test target in "Makefile". For example,

make SOLVER=xyz TEST=benchmark TIME=3600 test

runs solver XYZ on the benchmark test set with a time limit of one hour. More precisely, in this way, the main driver "run.sh" is invoked. It calls the MIP solver

for every instance listed in the file "benchmark.test", asks for the best solution, and applies the solution checker. However, the solver-specific part, such as setting the time limit and getting the solution, is encapsulated in a separate script "run_xyz.sh". After running the solver, "run.sh" starts "parse.awk", which parses the generated log file and produces the summary table. The evaluation, including primal-dual gap computation, time measurements, and determination of the solution status, is standardized and directly implemented in "parse.awk", whereas the information from the solver-specific log files, e.g., dual bound and node count, is actually obtained via auxiliary scripts such as "parse_xyz.awk".

Currently, we support CBC, CPLEX, GUROBI, MOSEK, SCIP, and XPRESS. In order to include other MIP solvers, only the solver-specific information for running the solver and evaluating its log files have to be provided by "run_mysolver.sh" and "parse_mysolver.awk". The template files "parse_xyz.awk" and "run_xyz.sh" can be used as a basis. They are located in the "scripts" folder. In order to test instances that are not shipped with MIPLIB 2010 a file "mytestset.test" with their locations has to be added to the "testsets" folder.

5 Variability of MIP Solver performance

When running computational experiments, we often experience differences in behavior on different platforms when optimizing the same model with the same solver. The input format, e.g., the order of the constraints, can also change the solution process. We use the term *performance variability* [?] to denote such changes in performance measures for the same problem that are caused by seemingly performance-neutral changes in the environment or the input format. Loosely speaking, performance variability comprises unexpected changes in performance.

Note that other changes, such as minor variations in the model formulation, also affect performance in a way that is difficult to predict. Adding or removing redundant constraints or variable bounds can have a major impact on the performance of modern MIP solvers [?]. Some of these changes are also automatically applied by preprocessing, in which case their effects are compounded with other sources of variability.

5.1 Reasons for performance variability

One root cause of performance variability is imperfect tie-breaking. When solving a MIP, most decisions are taken by computing a score for several candidates and choosing the candidate with the highest score. For example, a score based on pseudocosts may be computed for several variables that are candidates for branching and the variable with the highest score is chosen [?]. If there is a tie among the top candidates, then a series of secondary criteria should be used to make the final decision [?]. If tie-breaking is imperfect, selections may be made arbitrarily, based on the order in which the candidates are considered or influenced by rounding errors in the score computation, which will differ from platform to platform. Similarly, some decisions consider a subset of candidates: for example, strong branching [?] is typically applied to the top N branching variable candidates according to some criterion. If there are more than N candidates tied for the

best score, then the order in which candidates are considered will determine the variables for which strong branching is performed. Another factor is that compiler optimizations may reorder arithmetic operations and influence the outcome of floating-point computations; this might introduce a tie-breaking effect for values that should be equal or it might lead to tied values that should not be the same.³

Once the path in the branch-and-cut tree diverges, the entire subsequent resolution is affected. Altering the choice of a single branching variable may cause entirely different subtrees to be explored; the LP solutions at the child nodes could be different, leading to different cuts and different starting points for primal heuristics, which in turn leads to different integer solutions being found, the objective cutoff being updated differently, different nodes being pruned, etc. As we see from such a cascade of events, even a small divergence may lead to a completely different behavior of the solver and hence to a significant performance difference.

Also, for many models, the optimal basis of the root LP is not unique. If the LP basis is different, then cuts and LP-based primal heuristics applied at the nodes to find additional feasible solutions will be applied differently, and consequently the whole solution process will change. It is currently unknown whether the variability is correlated in any way with the number of alternate optimal LP bases for the root node.

Performance variability also depends on the intrinsic characteristics of the model; some structures may create more variability than others. It also depends on the characteristics of the MIP solver; some solvers may have more robust tie-breaking mechanisms or more sophisticated algorithms to recover from a bad decision. Many questions are open. In particular, what is the importance of each factor to variability and how should we change MIP solvers and MIP models so as to reduce variability. It is not even clear whether performance variability should exclusively be seen as a disturbing factor. For massive parallel MIP solvers, see, e.g., [?], it can even be exploited.

5.2 Generating and measuring performance variability

In order to study performance variability, we need a way to generate a large number of observations for the same model. Clearly, it is neither sufficient nor practical to run experiments on many different computers. Previous studies [?] have shown that a good variability generator is to permute columns and rows in the original model. This generator affects all types of problems and all components of a typical MIP solver. For instances of practically relevant size, many different permutations can be applied to create as many observations as needed.

For comparison reasons, it is desirable to summarize the performance variability into one number per model and solver. We choose as the *performance variability score* the coefficient of variation of X, where X is the random variable representing the performance of the given solver for the given model. For example, the performance can be measured as the solution time to optimality or the time to the first

 $^{^3}$ While it can be expected that the same binary will run identically on similar CPUs in general, modern compilers, e.g., the Intel C/C++ compilers [?], can detect the precise type of the CPU and use different instructions depending on the particular CPU. Since the internal precision of x86 type CPUs can differ depending on the instruction set used, the rounding of the last digit can be different.

solution. The coefficient of variation is simply the standard deviation divided by the average: it captures the variations in performance and its normalization allows us to compare the variability independent of the computational difficulty of the model. This definition is quite natural and allows us to interpret the variability score in relationship with the probability of a given performance degradation.

In practice, the coefficient of variation is estimated on a sample of observations provided by solving multiple permutations of the model: the quality of the estimate increases with the number of permutations. Given n permutations and corresponding running times t_i , i = 1, ..., n, we compute the variability score VS as follows:

$$VS = \frac{1}{\sum_{i=1}^{n} t_i} \cdot \sqrt{\sum_{i=1}^{n} \left(t_i - \frac{\sum_{i=1}^{n} t_i}{n}\right)^2}.$$

In Column VS of Table ?? starting on Page ?? the performance variability score for time to optimality with SCIP/SPX is shown. It is sampled from 100 different permutations for each model. However, we calculated the score only for models that SCIP/SPX could solve in less than four hours, using the original formulation. In addition, we imposed a time limit of ten hours, which, of course, influences the variability score whenever a permutation hits this limit. In Table ?? those scores that are affected by the time limit are printed in *italic*.

We present variability for solution time rather than number of simplex iterations, as in [?], because time is easier to compare across solvers. Indeed, solvers may count iterations differently; for example, iterations in sub-MIPs may or may not be counted, which makes the comparison difficult. Besides, not all the work done in a MIP solver is based on the simplex algorithm, so counting iterations gives a less comprehensive picture than measuring time.

Note that the variability score is an estimator over a limited sample of the true variability. Therefore, small differences in variability scores should not be given too much consideration.

5.3 Results on performance variability

Performance variability due to permutations can be observed for all tested instances. There was no instance for which all 100 permutations showed the same behavior. The minimum observed impact was for the instance mik-250-1-100-1, where the ratio of the maximal and the minimal solution times was 1.29. The largest ratio was 915 for the instance tanglegram2; the fastest permutation took a few seconds, the slowest nearly two hours.

The total running time of all 67 original, unpermuted instances for which we performed this test was 45.1 hours. If we had an oracle that, hypothetically, always selected the best permutation for each individual instance, the total running time would be reduced to 25.5 hours, which corresponds to a speedup factor of 1.77. On the other hand, always using the worst permutation would increase the running time by a factor of 3.82. This indicates that the negative outliers are more "extreme", i. e., the distribution is not symmetric.

It seems to be a natural question whether the original formulation has an advantage over the permuted ones. Indeed, if we compare the solution time of the unpermuted instances to the average solution time taken over the 100 permutations,

we observe a speedup of 14%. There is evidence that this might be mainly due to the more extreme behavior of negative outliers. If we compare the performance of the original formulations to the median, this advantage shrinks to 4% improvement. Said differently, the probability of improving performance by permuting the instance is about as high as the probability to deteriorate performance, but the average improvement is smaller than the average deterioration.

Overall, the range of variability scores is between 0.05 for the instance mik-250-1-100-1 and 2.23 for neos-916792, as can be seen in Column VS of Table ??. Figures 3a to 3e show the distribution of performance for specific instances. For the instances ex9, pg5.34, neos13, bnatt350, and enlight13, each of the dots in the corresponding diagram depicts the performance of one permutation when being solved with SCIP/SPX. They have been sorted by non-decreasing solution time; the black dot corresponds to the performance of the original formulation.

In Figure 3a, the vast majority of the permuted instances perform very similar, with only a few outliers. The original formulation is superior to the others. The most common case, however, is illustrated in Figure 3b. The different solution times are nearly uniformly distributed around the median value. There are a few negative outliers. The original formulation is "somewhere in the middle". Figure 3c shows the interesting case of clusters. Most of the permutations need around 12 minutes, but there is a significant accumulation point at 1:40 h. In order to have a smaller scale to make the accumulation point better visible in the picture, all permutations that took three hours or longer are treated as if they hit a time limit of three hours. Figures 3d and 3e depict bad cases for which permuting the model can lead to nearly arbitrary changes in the performance. For the instance enlight13, the best ten permutations need less than three minutes, but nearly twenty percent hit the time limit of ten hours.

Another source of variability is depicted in Figure 4, which shows the performance variability of a single instance depending on the number of threads. The computations where done on a 32 core machine with 8 AMD Opteron 8384 processors at 2.7GHz. As can be seen, both performance measures go up and down quite arbitrary with no visible pattern. If we compare neighboring bars, we see that adding one additional thread leads to fewer evaluated nodes in 17 cases, in 14 cases it results in more search nodes. The same holds for the solution time: in 14 cases the solver got faster when using one more thread, in 17 cases it slowed down.

5.4 Consequences for benchmarking

Performance variability affects all standard objectives of benchmarking, such as comparing different solvers, comparing different parameter settings for the same solver, or comparing a new algorithm to an existing algorithm. In particular, it is important to take performance variability into account during the analysis of experimental results when the performance difference is small, the variability of the models is high, or the stopping criterion is highly variable. Small test sets are more prone to disturbances caused by performance variability. This is one reason why MIPLIB 2010 provides more instances than its predecessors.

Performance is not deterministic. Instead, it is a random variable that can be sampled with computational experiments. In order to isolate the signal from the noise and draw robust conclusions, performance needs to be studied with

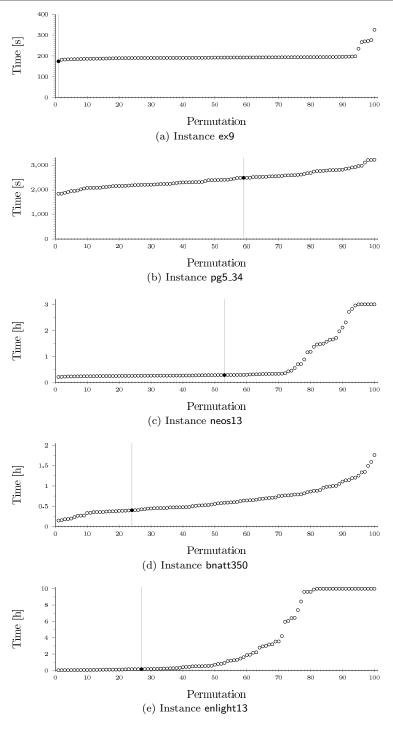
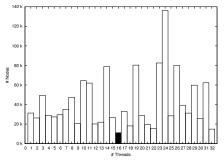
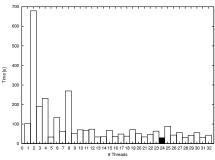


Fig. 3: Solution times for 100 permutations





(a) Total number of nodes explored (CPLEX)

(b) Wall clock solution time (GUROBI)

Fig. 4: Example of performance variability depending on the number of threads. Instance roll3000 on a 32 core computer. Filled bar indicates minimum

appropriate statistical tools. First, it is useful to obtain a large data sample, by running experiments on a large set of models or by artificially multiplying the number of observations by running experiments on permuted models for multiple permutations. Secondly, descriptive statistics such as the average or the geometric mean give limited insights. Instead, robust indicators such as truncated averages and rank statistics are more resistant to outliers. Performance profiles [?] are also useful. Finally, inferential statistics, such as statistical tests and confidence intervals, give the most insight and allow questions such as "how likely is it that the performance change is created by variability rather than by genuine algorithmic changes?" to be answered.

Variability should be taken into account not only when studying performance, but also when studying the correctness of computation. A different path in the branch-and-cut tree often leads the MIP solver to find a different integral solution because most models have several alternate optimal solutions. In all cases, the integral solution returned should have the expected objective value and respect all tolerances. It is a good idea to verify this on several permutations of the same model.

6 The instance catalog

In this section, we give an overview of all MIPLIB 2010 instances. Table ?? on Page ?? provides information about their origin and application. For each instance, we list originators or submitters, a short description of the application and references to publications in which the instance was used. Additionally, there are a large number of instances from Neos and COR@L for which, unfortunately, no information is available to us. Instances with the same originator and application are grouped in one row. The 26 instances from previous versions of MIPLIB are marked by *italic* names.

Problem statistics. Table ?? starting on Page ?? gives statistics about the instances. In particular, for each instance, we give the number of Rows, Columns, and Non-

Zeros. Furthermore, the number of variables is divided into the number of Binary, general Integer, and Continuous variables. Table 3 shows a distribution of instances based upon variables types. Only 13 instances do not have any binary variables, while only 72 of 361 instances have general integer variables.

Table 3: Distribution of instances based upon variable types

Туре	Binary	Integer	Continuous	Instances
Binary Programs	Х			116
Integer Programs		X		1
	Χ	X		29
Mixed Integer Programs	Χ		X	173
		Χ	X	12
	Χ	X	X	30

MIP and LP solution values. If known, the objective values of an optimal MIP Solution and the LP relaxation (LP Solution) are listed. The rational LP solver QSOPT_EX [?,?,?] was used to solve the LP relaxation of the instances with exact arithmetic. We report up to 16 digits, last digit rounded, in the table. For those instances that could not be solved by QSOPT_EX within a reasonable amount of time, we print the optimal solution value of the LP relaxation reported by CPLEX in italic. Note that we used the pure LP relaxation without applying MIP presolving, so the root LP bound computed during MIP solution might be better, even before cutting planes are added.

Although first steps have been taken in developing exact MIP solvers [?,?], current implementations are not yet capable of computing provably optimal solutions for most of the instances in MIPLIB 2010. Therefore, we post-processed the MIP solutions generated by the inexact solvers. The solution values of all integer variables were rounded and fixed to the nearest integer. The remaining LP was solved with QSOPT_EX. This does not give an optimality proof, but can provide a MIP solution that is truly feasible. Again, if this LP could not be solved by QSOPT_EX, we state in *italic* the objective value of an inexact optimal solution that passed the test of the solution checker. Instances where no optimal MIP solution is known, i. e., *open* instances, are labeled with a question mark '?'.

For the instances in the challenge set, we invested limited time to try to solve them with one of the available solvers. Four instances, 50v-10, probportfolio, reblock354, and rmatr200-p20, could be solved by ug[scip/spx] [?], a distributed massively parallel version of scip run on 2,000 cores at the HLRN-II super computer facility. To finally solve reblock354 about 42 billion nodes had to be processed. This took approximately 36 CPU years.

Condition numbers and numerical reliability. Column ATT.-LEVEL lists the numerical attention level calculated using the set mip strategy kappastats 2 command of CPLEX 12.2.0.2. This gathers statistics about the condition numbers of sub-problem basis matrices during CPLEX's solution process and is explained below in more detail. Vaguely speaking, a higher attention level indicates larger condition numbers of LP basis matrices, which in turn points to a higher probability of numerical

instabilities during the solution process. A node limit of 1,000 and a time limit of two days was used to get a reliable data base for this computation. Those few instances that did not finish the root node within this time limit, are marked by "—", for those instances with attention level 0.0, the value is omitted.

The condition number $\kappa(A_B)$ is a well-known measure of how errors in the input of a linear system of equations $A_B x = b$ are propagated to the solution x; for further details see, e.g., [?]. The condition numbers $\kappa(A_B)$ of the basis matrices A_B that are used to calculate optimal solutions of the sub-problem LP relaxations provide some insight into the origin of potential numerical inaccuracies that may have arisen during the solution process.

Double-precision arithmetic, as employed in the solvers at hand, provides roughly 16 significant decimal digits. Given that we used a feasibility tolerance of 10^{-6} , condition numbers larger than 10^{10} suggest that the errors encountered when calculating optimal LP solutions of the sub-problems may be larger than the feasibility tolerance. CPLEX classifies the condition numbers by the following four categories and outputs a histogram of the condition number distribution of optimal LP bases encountered during the MIP search:

```
- stable if \kappa(A_B) < 10^7,

- suspicious if \kappa(A_B) \in [10^7, 10^{10}),

- unstable if \kappa(A_B) \in [10^{10}, 10^{14}), and

- ill-posed if \kappa(A_B) \ge 10^{14}.
```

The attention level $AL \in [0,1]$ summarizes this histogram as

$$AL = p_{\text{ill-posed}} + 0.3 \cdot p_{\text{unstable}} + 0.01 \cdot p_{\text{suspicious}}$$

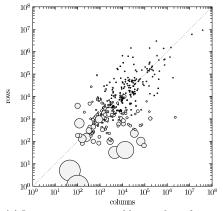
with $p_{...}$ being the relative frequencies of the sampled condition number categories. Thus, the attention level provides an estimate of the probability that the solver has encountered numerical issues during the solution process and their severity.

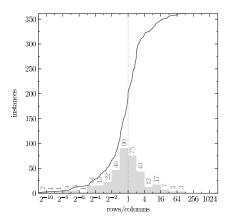
The attention level is not a property inherent to the model, but a measure for a specific algorithm applied to a certain instance and will even vary for one solver when different parameter settings are used. Since all solvers tested are based on the same paradigm of branch-and-bound-and-cut, we still believe that the attention level is a measure that can be of use in predicting numerical difficulties during the solution of an instance, though by no means the only one.

Category and status. The last two columns denote the test sets in which an instance is contained by giving the first letter of Benchmark, Challenge, Infeasible, Primal, Unstable, Resolve, Tree, XXL, as well as the status of the instance as of this writing, i.e., easy (solvable within one hour), hard (solvable in a longer time or with a specialized algorithm), or open (optimal solution unknown).

Size, structure and sparsity. The coefficient matrices vary largely in size and proportion. Figure ?? shows their distribution according to number of rows and columns. It can be seen that instances with more columns than rows are slightly in the majority (199 vs. 160 instances). Two instances, namely ramos3 and go19, have an equal number of columns and rows.

Apart from all the randomness involved, the instances typically show a strong structure, see, e.g., [?]. To underline this, we provide pictures representing the





- (a) Instances as scattered by number of rows vs. number of columns. The area of each bubble corresponds to the density of the instance. Densities smaller than 0.05 are drawn in uniform size
- (b) Cumulative distribution function of number of rows divided by number of columns and corresponding histogram over a \log_2 scale

Fig. 5: Size distribution of instances in MIPLIB 2010

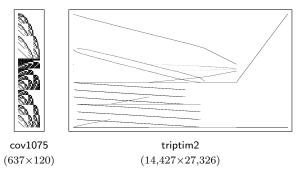


Fig. 6: Two examples of sparsity patterns

non-zero distribution in the coefficient matrices on the MIPLIB website. Figure ?? shows the sparsity patterns for instances cov1075 and triptim2.

Note that the structure shown in the pictures is intensified, i.e., the instances are usually sparser than they appear here. This is especially true for large instances where the ratio of zero to non-zero elements of the matrix is as small as $2.3 \cdot 10^6$ to one (for instance zib02). Only 11 instances show a density larger than 10% and the average density over all 361 instances is 1.6%; see also Figure ??.

7 State-of-the-art MIP solving

In this section, we try to provide a snapshot of the state-of-the art in MIP solving as of March 2011. We emphasize that the goal of this section is *not* to compare the

performance of the solvers, but rather to introduce the instances of the MIPLIB 2010 test set. We hope to reveal characteristics of the problems and give an impression of what is possible with today's codes, giving a point of reference for future research and investigation.

All of the solvers are in continuous development, often experiencing significant improvements from release to release. After having assembled a preliminary version of the test sets between December 2010 and mid January 2011, each development group was asked to send the latest version of their code, even if it was not yet officially released. While it is relatively easy for CBC and SCIP to make new releases on short notice, the commercial vendors require more thorough testing. For GUROBI, we used the very latest beta and from XPRESS, the first release candidate. Both will be officially released soon. CPLEX provided its most recent public version, which was released in January 2011. Table ?? lists the solvers used.

Solver	Version	Status	Website
CBC	2.6.4 R1630	Release	http://projects.coin-or.org/Cbc
CPLEX	12.2.0.2	Release	http://www.cplex.com
GUROBI	4.5 beta0	Beta	http://www.gurobi.com
SCIP/SPX	2.0.1.3/1.5.0.3	Internal Version	http://zibopt.zib.de
XPRESS	7.2 RC	Release Candidate	http://www.fico.com/xpress

Table 4: Solvers used for the computations

We also investigated other solvers like GLPK [?] and LP_SOLVE [?], but since neither of them was able to solve more than 20% of the instances within the time limit and no multithreaded versions were available, we omitted the results. For a recent survey of MIP software we refer to [?].

For computations in this section, a computer with two Intel Xeon X5680 cpus, each providing 6 cores at 3.33 GHz, was used. Hyperthreading and Turboboost were disabled. The machine has 32 gb ram. All computations were done using the Benchmark test set.

Table ??, starting on Page ??, lists the results for computations using one thread with a time limit of one hour and a memory limit of 8 GB. The solvers are ordered by release date, commercial ones first, non-commercial ones in a second block. For each solver, the number of branch-and-bound nodes used and the wall clock time in seconds are listed. If the time limit was reached before the solver finished, the optimality gap is given instead. If the gap at termination is infinite, i. e., if no primal solution was found or if $0 \in [db, pb]$ and $db \neq pb$, we write inf%. Italics indicate that the solution (as printed in the output file by the solver) did not pass the tolerances for the solution checker described in Section 3. If a solver aborted, we write abort across the columns for nodes and time. In the latter two cases, a footnote gives details, if available.

The column *Best* lists the minimum number of nodes and the best time taken over all solvers that solved the instance to optimality and provided a solution accepted by the solution checker. In this respect, minimum tree size and solution times may have been taken from *different* solvers. The column *VS* lists the variability score of the instance as described in Section 5. Higher numbers indicate higher performance variability. In order to indicate special properties of the instances, the

additional test sets containing an instance, other than BENCHMARK, are listed in column Sets.

While each solver hits the time limit for at least 12 instances, there are only four BENCHMARK instances that none of the solvers was capable of solving within one hour, using only one thread. These are iis-bupa-cov, m100n500k4r1, neos-1337307, and newdano. Furthermore, for each solver there is at least one instance for which this solver is faster than all the other solvers. The geometric mean of the times in the Best column actually is less than half of the geometric mean of the numbers in any of the solvers Time columns.

Table ??, starting on Page ??, gives the results for computations using 12 threads with a time limit of one hour and a memory limit of 24 gb. Except for the last column, we list the same numbers as for the single thread computations. The last column lists the speedup between the *Best Time* column from the single thread and from the 12 thread results.

Using 12 threads, all instances with the exception of m100n500k4r1 can be solved by at least one of the solvers within one hour. The speedup between the best of all solvers and any particular solver is now even more significant. The average overall speedup for going from 1 to 12 threads is approximately a factor of 3. In some of the cases where the speedup is less than 1 this is due to rounding the time up to the second on instances which do not benefit from using multiple threads. This rounding is also the reason for the super linear speedup reported for binkar10.1.

We purposely refrained from directly comparing the individual solvers based on measures of average solution times. There are a number of reasons for this:

- As stated in Section 5, we would have to sample over a sufficient number of permuted instances to decrease the impact of performance variability. When redoing the single thread computations on a 14% faster machine with a different memory/cache system, the speedup of the geometric mean solution time was between 8.5% and nearly 20%, depending on the particular solver. When redoing the 12 thread computations, even though the codes ran in deterministic mode on an empty machine, differences in wall clock time up to 73 seconds between two runs of the same instance could be observed.
- The result depends on several quite arbitrary choices, like the time limit, the number of threads, and the particular computer system. If we changed any of them, the results would change.
- The fact that each solver was the single fastest on some instances and only a few instances could not be solved by any solver, strongly indicates that if one wants to know which solver is the fastest for a particular problem, the only way to find out is to try them all.
- While the geometric mean of the solution times in the 12 thread setting for the commercial solvers is the same within measurement precision, the ratio between the slowest and the fastest of the three solvers can be over 1,000 on an individual instance. The geometric mean of this ratio is over 5, and the median is more than 3, i.e., for more than half of the instances the fastest solver is at least three times faster than the slowest one. (We are not giving precise numbers here because due to the time limit there are several possibilities for computing the numbers or lower bounds.)

- We were "only" using default settings. Each of the solvers has at least 50 parameters to tune it. This often allows considerable improvements in performance, especially on instances were a certain solver has difficulties.

- Finally, there are many performance measures that could be used to decide which solver is best, like lowest number of timeouts, highest number of fastest solves, minimum total time, lowest geometric mean of solution time, etc. Interestingly, regarding the commercial solvers, depending on the measure and the number of threads used, each solver wins at least once.

8 Final remarks

Since the first release of MIPLIB, nearly 20 years ago, we have seen impressive advances in computational mixed integer programming. To support the ongoing progress, we have compiled MIPLIB 2010 to help provide a basis for evaluating future developments and to stimulate continuing algorithmic improvements.

The common efforts of collecting, experimenting with, selecting, and categorizing relevant problem instances have proven to be very insightful. Getting everybody involved and agreeing on common limits and tolerances for testing already led to beneficial discussions, code improvements, and new ideas. Last but not least, one important insight after literally spending decades of CPU time is that one should not try to boil down the result tables to a single number. We hope that our detailed computational experiments provide an accurate snapshot of the current state-of-the-art in mixed integer programming.

To be continued...

Acknowledgments

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Thanks to Jeff Linderoth for his efforts in putting together the cor@L test suite from instances called from Neos and elsewhere. This effort contributed directly to the construction of MIPLIB 2010.

Emilie Danna worked on performance variability in mixed integer programming from 2008 to 2010 while she was employed at ILOG then IBM.

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Table 5: Descriptions and references for MIPLIB instances. Instances coming from a previous version of MIPLIB are listed in italic

Name	Originator and description
30n20b8	E. Coughlan, M. Lübbecke, J. Schulz [?] Multi-mode resource leveling with availability constraints; precedence and resource constrained scheduling problem
30_70_45_095_100	J. Walser [?,?] Geographic radar station allocation
50v-10	S. Bisaillon Network loading instance
a1c1s1, b2c1s1	M. Vyve, Y. Pochet [?,?] Lot sizing instances
acc-tight4, acc-tight5, acc-tight6	J. Walser [?,?] ACC basketball scheduling instances
aflow40b	T. Achterberg [?] Arborescence flow problem on a graph with 40 nodes and edge density 0.9
air04	G. Astfalk [?] Airline crew scheduling set partitioning problem
app1-2	E. Danna Undisclosed industrial application from Google
ash608gpia-3col	M. Pfetsch Infeasible and highly symmetric graph 3-coloring assignment formulation
atlanta-ip, msc98-ip	E-Plus, D. Bienstock, A. Bley, R. Wessäly [?] Min-cost network dimensioning problems with a finite set of link capacities for each bidirected link, unsplittable shortest path routing, path restoration for single node failures, and routing path length restrictions
atm20-100	M. Galati [?] ATM cash management problem
bab1	E. Swarat, L. Traverso, J. Buwaya Integrated vehicle routing and crew scheduling of toll inspectors on German highways
bab3, bab5	E. Swarat Vehicle routing with profits and an integrated crew scheduling problem formulated by two coupled multi-commodity flow problems
beasleyC3, g200×740i, k16×240, mc11, p80×400b, p100×588b, r80×800	F. Ortega, L. Wolsey [?] Fixed cost network flow problems
berlin_5_8_0, usAbbrv-8-25_70	G. Klau [?] Railway optimization problems
bg512142, dg012142	A. Miller [?,?,?] Multilevel lot-sizing instances
biella1, dc1c, dc1l, dolom1, nsr8k, siena1	Double-Click SAS [?,?] Crew scheduling instances
bienst2, binkar10_1	H. Mittelmann Relaxed versions of problems bienst and binkar10
bley_xl1	$\begin{array}{lll} \text{A. Bley} \\ \text{Min-cost network dimensioning problem with finite sets of link capacities} \\ \text{and unsplittable flow routing} \end{array}$

Table ?? continued	
Name	Originator and description
blp-ar98, blp-ic97	M. Lübbecke [?,?] Railway line planning instances
bnatt350, bnatt400	T. Akutsu [?] Model to identify a singleton attractor in a Boolean network, applications in computational systems biology
buildingenergy	K. Pruitt Model to determine the minimum cost design and dispatch of a distributed generation system for a commercial building
cdma	S. Bisaillon 3G wireless multiplexing communication model
circ10-3	[?] Instance from the 2010 SAT conference pseudo-Boolean competition
co-100	A. Werner [?] Model from optical access network planning
core2536-691, core4872-1529	A. Caprara, M. Fischetti, P. Toth [?] Set covering instances coming from Italian railway models
cov1075	F. Margot [?,?] Problem of selecting a minimum collection of 7-subsets containing all 5-subsets of a ground set of 10 elements.
csched007, csched008, csched010	T. Yunes [?] Cumulative scheduling problem instances
d10200, d20200, leo1, leo2	${ m COR@L}$ test set [?] Instances coming from the ${ m COR@L}$ test set with unknown origin
dano3mip, danoint, newdano	D. Bienstock [?] Telecommunications applications
datt256	J. Dattorro [?,?] Model to find solution to the "Eternity II" puzzle [?]
dfn-gwin-UUM, germany50-DBM, janos-us-DDM, nobel-eu-DBE, zib54-UUE	C. Raack [?,?] Network design, link dimensioning models for problems in the SNDlib [?,?]
ds-big	R. Borndörfer [?] Bus driver duty scheduling problem
eil33-2, eilA101-2, eilB101	J. Linderoth [?,?] Set partitioning problem approximations for capacitated vehicle routing problem instances from TSPLIB
enlight9, enlight13, enlight14, enlight15, enlight16	A. Zymolka Model to solve instances of a combinatorial game "EnLight"
ex9, ex10	I. Ober Formulations of Boolean SAT instances
ex1010-pi	\cite{Model} Logic synthesis problem from the 2010 SAT conference pseudo-Boolean competition
f2000, hanoi5	\cite{Model} Reformulated SAT instances from the 2010 SAT conference pseudo-Boolean competition

Table ?? continued						
Name	Originator and description					
ger50_17_trans	C. Raack [?] Multi-layer network design problem using a link-flow formulation over a path-flow formulation					
germanrr	Q. Chen [?] Model from a German railroad company					
glass4	I. Luzzi [?] Nesting instance					
gmu-35-40, gmu-35-50, gmut-75-50, gmut-77-40	N. Konnyu Timber harvest scheduling models					
go19	R. Miyashiro, Y. Yano, M. Muramatsu [?] Instance of the maximum string problem in the Go board game: to find a position of stones that maximizes the number of live "strings" on the board					
harp2	M. Savelsbergh [?] Unknown application					
hawaiiv10-130	J. van Dinter Unit commitment model					
ic97_potential	L. Peeters [?] A model for cyclic railway timetable optimization					
iis-100-0-cov, iis-bupa-cov, iis-pima-cov	$\begin{tabular}{ll} M. & Pfetsch \end{tabular} \begin{tabular}{ll} Pfe$					
in	A. Fügenschuh Packing of paths, multicommodity flow formulation					
ivu06-big, ivu52, rvb-sub	S. Weider [?,?] Set partitioning instances resulting from a column generation algorithm used for duty scheduling in public transportation					
lectsched-1, lectsched-1-obj, lectsched-2, lectsched-3, lectsched-4-obj	H. Schilly [?] University lecture scheduling instances					
liu	X. Liu [?] Floorplan and placement problem in the physical design of VLSI circuits					
lotsize	D. Gade, S. Küçükyavuz [?] Multi-item lot sizing with service level constraints					
Irsa120	M. Atlihan Model to break a 120 bit RSA key					
m100n500k4r1	L. Torres [?] Set packing problem with 4 ones per column					
macrophage, methanosarcina, tanglegram1, tanglegram2, toll-like	F. Hüffner $\cite{[}$ P. Balanced subgraph instances coming from applications in bio-informatics: finding monotone subsystems in gene regulatory networks and finding optimal layouts of tanglegrams					
map06, map10, map14, map18, map20	K. Ahmadizadeh [?,?] Land parcel selection problems motivated by Red-Cockaded Woodpecker conservation problem					
markshare_5_0	G. Cornuéjols, M. Dawande [?,?] Market sharing problem					

Table ?? continued	
Name	Originator and description
maxgasflow, transportmoment	G. Gamrath Transport momentum maximization in a capacitated gas network, transportmoment forbids cycles by pseudo pressures
mcsched, npmv07	Q. Chen [?] Unknown application
mik-250-1-100-1	A. Atamtürk [?,?] Problem with mixed integer knapsack constraints
mine-90-10, mine-166-5, reblock67, reblock166, reblock354, reblock420	A. Bley [?] Multi-period mine production scheduling instances
mining	K. Eurek Unspecified mining application
mkc	J. Kalagnanam, M. Dawande [?,?] Multiple knapsack problem with color constraints
momentum1, momentum2, momentum3	T. Koch [?] Snapshot based UMTS planning problems, having a very wide dynamic range in the matrix coefficients and tending to be numerically unstable
mspp16	P. Troubil, P. Holub, M. Liška, H. Rudová [?,?] Media Streams Planning Problem - A network optimization problem regarding routing of multiple concurrent multimedia streams with bandwidth close to capacity of network links
mzzv11	S. Lukac [?] Railway slot allocation problems
n3-3, n4-3, n9-3, n15-3	A. Atamtürk [?,?] Capacitated network design problems
n370a, n3700, n3705, ran14×18, ran14×18-disj-8, ran16×16	J. Aronson [?] Fixed charge transportation problems
n3div36, n3seq24	R. Meirich [?] Static line planning models on the Dutch IC network
nag	N. Shenoy [?] Unknown Application
nb10tb	S. Bisaillon Forestry industry model
net12	P. Belotti [?,?] Network design instance
netdiversion	C. Cullenbine [?] Directed network diversion problem
noswot	J. Gregory, L. Schrage [?] Unknown application
ns4-pr3, ns4-pr9, nu60-pr9, nu120-pr3	A. Atamtürk, D. Rajan [?,?] Multicommodity flow capacitated network design problems
ns1111636, ns1158817	H. Mittelmann, NEOS Server [?] Network routing problems
ns1631475, ns2137859	H. Mittelmann, NEOS Server [?] Traveling salesman problem models
	H. Mittelmann, NEOS Server [?] Vehicle routing problems

Table ?? continued	
Name	Originator and description
ns1853823, ns1854840	H. Mittelmann, NEOS Server [?] Network flow problems
ns1856153, ns1904248	H. Mittelmann, NEOS Server [?] Sensor placement problems
ns2081729	H. Mittelmann, NEOS Server [?] Short-term scheduling in a multiproduct sequence dependent facility
ofi	L. Poderico Natural gas supply portfolio optimization
opm2-z7-s2, opm2-z10-s2, opm2-z11-s8, opm2-z12-s7, opm2-z12-s14	D. Espinoza Problems coming from precedence constrained knapsacks arising in mining applications
p2m2p1m1p0n100	B. Krishnamoorthy, G. Pataki A 0-1 knapsack problem constructed to be difficult
p6b	B. Borchers Maximum independent set problem on a component of the graph $1et.2048$ from the collection of N. Sloane [?]
pb-simp-nonunif	[?] Retrieving haplotype information from DNA samples using Haplotype Inference by Pure Parsimony
pg, pg5_34	M. Dawande [?] Multiproduct partial shipment models
pigeon-10, pigeon-11, pigeon-12, pigeon-13, pigeon-19	S. Allen [?] Instances of 3D packing (container loading) problems
probportfolio	S. Ahmed, S. Dey, F. Qiu Sample average approximation formulation of a probabilistic portfolio optimization problem
protfold	A. Fügenschuh [?] Protein folding instance
pw-myciel4	A. Koster Model to compute the pathwidth of Mycielski-4 instance from DIMACS graph coloring database
qiu	Y. Chiu, J. Eckstein [?,?,?] Fiber-optic network design, logical SONET ring level
queens-30	A. Mahajan [?] Models the problem of placing as many queens on a 30 by 30 chess board as possible so that each queen threatens at most one other queen
rail01, rail02, rail03	T. Schlechte [?] Track allocation problem modeled as arc coupling problem
rail507	A. Caprara, M. Fischetti, P. Toth [?,?] Railway crew scheduling
ramos3	F. Ramos Set covering problem from a product manufacturing application
rmatr100-p5, rmatr100-p10, rmatr200-p5, rmatr200-p10, rmatr200-p20	D. Krushinsky $\cite{Trushinsky}$ [?] Instances coming from a formulation of the p -Median problem using square cost matrices

Table ?? continued Name	Oviginator and description
	Originator and description
rmine6, rmine10, rmine14, rmine21, rmine25	D. Espinoza Set of instances coming from open pit mining over a cube considering multiple time periods and two knapsack constraints per period
rococoB10-011000, rococoC10-001000, rococoC11-011100, rococoC12-111000	A. Chabrier, E. Danna, C. Le Pape, L. Perron [?] Models for dimensioning the arc capacities in a telecommunication network
rocll-4-11, rocll-7-11, rocll-9-11	J. Rambau Optimal control of opinion dynamics
roll3000	L. Kroon [?] Rolling stock and line planning instances
satellites1-25, satellites2-60, satellites2-60-fs, satellites3-40, satellites3-40-fs	A. Ceselli, R. He Satellite scheduling instances
sct1, sct5, sct32	Siemens Assembly line balancing for printed circuit board production
set3-10, set3-15, set3-20	K. Akartunalı, A. Miller [?,?,?] Multi-item lot-sizing with backlogging
seymour	$\mbox{W. Cook, P. Seymour}$ A set-covering problem that arose from work related to the proof of the 4-color theorem
seymour-disj-10	M. Ferris, G. Pataki, S. Schmieta [?] The <i>seymour</i> instance after adding 10 rounds of disjunctive cuts
shipsched	E. Günther, M. Lübbecke A ship scheduling problem on the Kiel Canal
shs1023	C. Helmberg \cite{Matter} C. Helmberg \cite{Matter} Joint online truck scheduling and inventory management for multiple warehouses
sing2, sing161, sing245, sing359, uc-case3, uc-case11	D. Espinoza Unit commitment problems (electricity production planning problems) coming from the Chilean electricity system, they have either one or two week planning horizons, and include constraints on minimum on-off time for the power plants, ensure some <i>reserve</i> energy in the system, and minimize global operation costs.
sp97ar, sp98ic, sp98ir	J. Goessens, S. v. Hoessel, L. Kroon [?,?] Railway line planning instances
splan1	C. Helmberg, A. Lau [?] University course timetabling instances
stockholm	L. Bai, P. Rubin [?,?] Toll booth placement problem
stp3d	T. Koch [?] Steiner tree packing instance in a 3 dimensional grid-graph, LP relaxation is highly degenerate
sts405, sts729	J. Linderoth [?] Steiner triple system problems
swath	D. Panton [?] Model arising from the defense industry, involves planning missions for radar surveillance

Lab	le ??	continued

Name	Originator and description
t1717, t1722	R. Borndörfer [?,?] Vehicle scheduling set partitioning problems from Berlin's Telebus handicapped people's transportation system
timtab1	C. Liebchen, R. Möhring [?] Public transport scheduling problems
triptim1, triptim2, triptim3	R. Borndörfer [?] Trip timetable optimization problems
tw-myciel4	A. Koster Model to compute the treewidth of the Mycielski-4 instance from the DIMACS graph coloring database
uct-subprob	G. Lach Subproblem of a university course timetabling problem
umts	C. Polo [?,?] Telecommunications network model
unitcal_7	R. O'Neill California seven day unit commitment problem
van	C. Mannino, E. Parrello [?] Telecommunications network model
vpphard, vpphard2	C. Cardonha Vehicle positioning problem instances
wachplan	S. Orlowski Shift planning model to assign crew members to shifts for a sail training trip
wnq-n100-mw99-14	[?] Weighted n-queens problem with an additional separation constraint
zib01, zib02	T. Koch Group channel routing on a 3D grid graph

neos6, neos13, neos15, neos16, neos18, neos-476283, neos-506422, neos-506428, neos-520729, neos-555424, neos-631710, neos-686190, neos-693347, neos-738098, neos-777800, neos-785912, neos788725, neos-799711, neos-807456, neos808444, neos-820146, neos-820157, neos-824661, neos-824695, neos-826650, neos-826694, neos-826812, neos-826841, neos-847302, neos-849702, neos858960, neos-859770, neos-885086, neos-885524, neos-911880, neos-916792, neos-932816, neos-933638, neos-933966, neos-934278, neos-935627, neos-935769, neos-937511, neos-937815, neos-941262, neos-941313, neos-942830, neos-948126, neos-952987, neos-957389, neos-984165, neos-1109824, neos-1112782, neos-1112787, neos-1140050, neos-1171692, neos-1171737, neos-1224597, neos-1225589, neos-1311124, neos-1337307, neos-1396125, neos-1426635, neos-1426662, neos-1429212, neos-1436709, neos-1440225, neos-1440460, neos-1442119, neos-1442657, neos-1601936, neos-1605061, neos-1605075, neos-1616732, neos-1620770, ns894236, ns894244, ns894786, ns894788, ns903616, ns930473, ns1116954, ns1208400, ns1456591, ns1606230, ns1644855, ns1663818, ns1685374, ns1686196, ns1688347, ns1696083, ns1745726, ns1758913, ns1766074, ns1769397, ns1778858, ns1830653, ns1952667, ns2124243, ns2017839

Instances coming from the ${\ensuremath{{\rm NEOS}}}$ Server [?] with unknown applications

Table 6: Problem statistics

							oblem statis					
Name	Rows	Columns	Non-Z	Zeros Bin	ary Inte	eger	Continuous	MIP Solution	LP Solution	Attlevel	Sets	Status
30_70_45_09	5_100	12,526	10,976	46,640	10,975		1	3		3	Р	easy
30n20b8		576	18,380	109,706	11,036	7,344		302	1.5664	08	В	easy
50v-10		233	2,013	2,745	1,464	183	366	3311.179984123	2879.0656	87	C	hard
a1c1s1		3,312	3,648	10,178	192		3,456	11503.444125	997.5295	83	C	hard
acc-tight4		3,285	1,620	17,073	1,620			0		0	RP	easy
acc-tight5		3,052	1,339	16,134	1,339			0		0	BRP	easy
acc-tight6		3,047	1,335	16,108	1,335			0		0 0.001	. RP	easy
aflow40b		1,442	2,728	6,783	1,364		1,364	1168	1005.6648	17	В	easy
air04		823	8,904	72,965	8,904			56137	55535.4363	88	В	easy
app1-2		53,467	26,871	199,175	13,300		13,571	-41	-264.6016	51 0.001	В	easy
ash608gpia-3	3col	24,748	3,651	74,244	3,651			infeasible		2	BI	easy
atlanta-ip		21,732	48,738	257,532	46,667	106	1,965	90.009878614	81.2431	99	C	hard
atm20-100		4,380	6,480	58,878	2,220		4,260	?	2141734.6848	78 0.006	C	open
b2c1s1		3,904	3,872	11,408	288		3,584	?	4034.2183	33	C	open
bab1		60,680	61,152	854,392	61,152			?	-286923.8242	23	C	open
bab3		23,069	393,800	3,301,838	393,800			?	-733091.1804	43	C	open
bab5		4,964	21,600	155,520	21,600			-106411.8401	-124657.6414	13	В	easy
beasleyC3		1,750	2,500	5,000	1,250		1,250	754	40.4268	29	В	easy
berlin_5_8_0		1,532	1,083	4,507	794		289	?		52	C	open
bg512142		1,307	792	3,953	240		552	?	144364.0738	15	C	open
biella1		1,203	7,328	71,489	6,110		1,218	3065005.78	3060037.4307	63	В	easy
bienst2		576	505	2,184	35		470	54.6	11.7241	38	В	easy
binkar10_1		1,026	2,298	4,496	170		2,128	6742.200024	6637.1880	27	В	easy
bley_xl1		175,620	5,831	869,391	5,831			190	154.39	02	В	easy
blp-ar98		1,128	16,021	200,601	15,806		215	6205.2147104	5891.226	58	Т	easy
blp-ic97		923	9,845	118,149	9,753		92	?	3846.3586	67	C	open
bnatt350		4,923	3,150	19,061	3,150			0		0	BRP	easy
bnatt400		5,614	3,600	21,698	3,600			1		0	CR	hard
buildingener	gy	277,594	154,978	788,969		26,287	128,691	?	33246		C	open
cdma		9,095	7,891	168,227	4,235		3,656	?	-6.38289e +			open
circ10-3		42,620	2,700	307,320	2,700			?		40 0.003		open
co-100		2,187	48,417	1,995,817	48,417			2639942.06	917102.2144	27	C	hard
core2536-69		2,539	15,293	177,739	15,284		9	689	688.4760		В	easy
core4872-15	29	4,875	24,656	218,762	24,645		11	?	1509.7185		C	open
cov1075		637	120	14,280	120			20	17.1428	57	В	easy
csched007		351	1,758	6,379	1,457		301	351	269.2515		T	easy
csched008		351	1,536	5,687	1,284		252	173	1	71	RT	easy

Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuous	MIP Solution	LP Solution	Attlevel	Sets	Status
csched010	351	1,758	6,376	1,457		301	408	332.422727		В	easy
d10200	947	2,000	57,637	733	1,267		?	12425.583005		C	open
d20200	1,502	4,000	189,389	3,181	819		?	12229.625788		C	open
dano3mip	3,202	13,873	79,655	552		13,321	?	576.23162	0.005	CR	open
danoint	664	521	3,232	56		465	65.666666667	62.63728		В	easy
datt256	11,077	262,144	1,503,732	262,144			?	256	_	C	oper
dc1c	1,649	10,039	121,158	8,380		1,659	?	1754946.863638		C	open
dc1l	1,653	37,297	448,754	35,638		1,659	?	1744591.692942		C	open
dfn-gwin-UUM	158	938	2,632		90	848	38752	27467.257235		В	easy
dg012142	6,310	2,080	14,795	640		1,440	?	757818.480114		C	open
dolom1	1,803	11,612	190,413	9,720		1,892	?	6556066.068315		C	open
ds-big	1,042	174,997	4,623,442	174,997			?	86.820068		CR	open
eil33-2	32	4,516	44,243	4,516			934.007916	811.278996		В	easy
eilA101-2	100	65,832	959,373	65,832			880.920108	803.373888		C	hard
eilB101	100	2,818	24,120	2,818			1216.920174	1075.247691		В	easy
enlight13	169	338	962	169	169		71	0		В	easy
enlight14	196	392	1,120	196	196		infeasible	0		BI	easy
enlight15	225	450	1,290	225	225		ő 69	0		Т	easy
enlight16	256	512	1,472	256	256		infeasible	0		IT	easy
enlight9	81	162	450	81	81		infeasible	0		1	easy
ex1010-pi	1,468	25,200	102,114	25,200			?	220.670087		C	open
ex10	69,608	17,680	1,162,000	17,680			100	100	0.001	Р	easy
ex9	40,962	10,404	517,112	10,404			81	81		BP	easy
f2000	10,500	4,000	29,500	4,000			?	133	1	CR	ope
g200×740i	940	1,480	2,960	740		740	?	2292.46	5	C	ope
ger50_17_trans	499	22,414	172,035		18,062	4,352	?	6850.62862	3 0.01	CU	
germanrr	10,779	10,813	175,547	5,288	5,286	239	?	45980135.41639	9	C	ope
germany50-DBM	2,526	8,189	24,479		88	8,101	?	43802	18	C	ope
glass4	396	322	1,815	302		20	1200012600	80000240	0	BT	eas
gmu-35-40	424	1,205	4,843	1,200		5	-2406733.3688	-2406943.55634	.3	ВТ	eas
gmu-35-50	435	1,919	8,643	1,914		5	-2607958.33	-2608070.31574	-3	Т	eas
gmut-75-50	2,565	68,865	571,475	68,859		6	?	-14182312.66173	0.001	C	
gmut-77-40	2,554	24,338	159,902	24,332		6	?	-14173396.63685	2 0.002	C	ope
go19	441	441	1,885	441			84	76.53022	2	CT	
nanoi5	16,399	3,862	39,718	3,862			?	146	7	CR	ope
narp2	112	2,993	5,840	2,993			-73899798	-74353341.502	:3	U	
hawaiiv10-130	1,388,052	685,130	183,263,061	578,444		106,686	?	52281537.59495		CXU	ope
c97_potential	1,046	728	3,138	450	73	205	3942	386		C	
iis-100-0-cov	3,831	100	22,986	100			29	16.66666		В	eas
iis-bupa-cov	4,803	345	38,392	345			36	26.49721		В	eas

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuo	s MIP Solution	LP Solution	Attlevel	Sets	Status
iis-pima-cov	7,201	768	71,941	768			33	26.62038	9	В	easy
in	1,526,202	1,449,074	6,811,639	1,489		1,447,585	?		? —	CRX	open
ivu06-big	1,177	2,277,736	23,125,770	2,277,736			?	135.42	8	CRX	open
ivu52	2,116	157,591	2,179,476	157,591			?	480.25043	8 0.001	CR	open
anos-us-DDM	760	2,184	6,384		84	2,100	?	1488134.7	5	C	open
k16×240	256	480	960	240		240	10674	2769.83	8	Т	easy
ectsched-1	50,108	28,718	310,792	28,236	482		0		0	Р	easy
ectsched-1-obj	50,108	28,718	310,792	28,236	482		?		0	C	open
lectsched-2	30,738	17,656	186,520	17,287	369		0		0	Р	easy
ectsched-3	45,262	25,776	279,967	25,319	457		0		0	Р	easy
ectsched-4-obj	14,163	7,901	82,428	7,665	236		4		0	В	easy
eo1	593	6,731	131,218	6,730		1	404227536.16	388573315.50960	8	Т	easy
eo2	593	11,100	219,959	11,099		1	404077441.12	386421293.20891	9	C	hard
liu	2,178	1,156	10,626	1,089		67	?	34	6	C	open
otsize	1,920	2,985	6,565	1,195		1,790	1480195	348385.34655	1 0.009	C	hard
rsa120	14,521	3,839	39,956	120	119	3,600	?	2	9	C	open
m100n500k4r1	100	500	2,000	500			-25	-2	5	BP	hard
macrophage	3,164	2,260	9,492	2,260			374		0	В	easy
map06	328,818	164,547	549,920	146		164,401	-289	-406.18117	3	R	easy
map10	328,818	164,547	549,920	146		164,401	-495	-602.17618	1	R	easy
map14	328,818	164,547	549,920	146		164,401	-674	-778.54932	4	R	easy
map18	328,818	164,547	549,920	146		164,401	-847	-932.78268	5	BR	easy
map20	328,818	164,547	549,920	146		164,401	-922	-998.83641	9	В	easy
narkshare_5_0	5	45	203	40		5	1		0	Т	easy
naxgasflow	7,160	7,437	19,717	2,456		4,981	?	-7092953	5.9 0.0	1 CT	oper
nc11	1,920	3,040	6,080	1,520		1,520	11689	608.844	134	Т	easy
ncsched	2,107	1,747	8,088	1,731	14	2	211913	193774.7537	'07	В	easy
nethanosarcina	14,604	7,930	43,812	7,930			?		0	C	oper
nik-250-1-100-1	151	251	5,351	100	150	1	-66729	-79842.4236	35	В	easy
nine-166-5	8,429	830	19,412	830			-566395707.87083	-821763677.6731	.39	В	easy
nine-90-10	6,270	900	15,407	900			-784302337.633173	-887165318.5102	226	В	easy
nining	661,133	348,921	3,844,879	348,920		1	?	-949724584.6968	851 -	– c	oper
nkc	3,411	5,325	17,038	5,323		2	-563.846	-611	.85	C	hard
nomentum1	42,680	5,174	103,198	2,349		2,825	109143	72793.3452	255 0.01	.7 CT	hard
nomentum2	24,237	3,732	349,695	1,808	1	1,923	12314.1	7225.440	0.06	i9 U	easy
nomentum3	56,822	13,532	949,495	6,598	1	6,933	?	91952.3923	0.01	.4 CR	oper
nsc98-ip	15,850	21,143	92,918	20,237	53	853	19839497.005874302	19520966.1516	61	BR	easy
nspp16	561,657	29,280	27,678,735	29,280			363	3	841	BX	
nzzv11	9,499	10,240	134,603	9,989	251		-21718	-22945.2396	0.00	1 B	easy
15-3	29,494	153,140	611,000		780	152,360	?	23703.9411	.76 0.00	7 CR	oper

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuou	us MIP Solution	LP Solution	Attlevel	Sets	:	Status
eos-506428	129,925	42,981	343,466	42,981			583780		45945		R	easy
eos-520729	31,178	91,149	322,203	30,708		60,441	-1385000	-1391291.6		0.185	U	easy
eos-555424	2,676	3,815	15,667	3,800	15		1286800	1196312.			Ρ	easy
eos-631710	169,576	167,056	834,166	167,056			?		188.25		CR	oper
eos-686190	3,664	3,660	18,085	3,600	60		6730	5134.	.81383		В	easy
eos-693347	3,192	1,576	113,472	1,405		171	234		234		Ρ	easy
ieos6	1,036	8,786	251,946	8,340		446	83		83		Ρ	easy
eos-738098	25,849	9,093	101,360	8,946		147	-1099		-1099		Ρ	easy
eos-777800	479	6,400	32,000	6,400			-80		-80		Ρ	easy
eos-785912	1,714	1,380	16,610	1,380			infeasible		42		- 1	easy
eos788725	433	352	4,912	352			infeasible		-44.65		- 1	easy
eos-799711	59,218	41,998	147,164	910		41,088	-11170211.73363777	-11228065.1	.53797	0.056	U	easy
eos-807456	840	1,635	4,905	1,635			?			0.005	C	oper
eos808444	18,329	19,846	120,512	19,846			0		0		Р	easy
eos-820146	830	600	3,225	600			infeasible		0		IT	easy
eos-820157	1,015	1,200	4,875	1,200			infeasible		Ō		İT	easy
eos-824661	18,804	45,390	138,890	15,640		29,750	33		33		Р	easy
eos-824695	9,576	23,970	72,590	8,500		15,470	31		31		P	easy
eos-826650	2.414	5,912	20,440	5,792		120	29		28		Т	easy
eos-826694	6,904	16,410	59,268	16,290		120	58		58		P	easy
eos-826812	6,844	15,864	53,808	10,350		5,514	58.011		58.011		P	easy
eos-826841	2,354	5,516	18,460	3,488		2,028	29.0082		8.0082		Ť	easy
eos-847302	609	737	9,566	729		8	4	2,	0		Ť	hard
eos-849702	1,041	1,737	19,308	1,737		O	0			0.001	BP.	easy
eos858960	132	160	2,770	160			infeasible		1	0.001	IT	easy
eos-859770	2,065	2,504	880.736	2.504			infeasible		4500		''i	easy
eos-885086	11,574	4,860	248,310	2,430		2,430	-243		-243		P	
eos-885524	11,574	91,670	258,309	91,670		2,430	12320.092	1170	-243 54.885		P	easy
eos-911880	83	888	2,568	840		48	54.76	1173	23.26		T	easy
eos-911660 eos-916792	1,909	000 1,474	2,506 134,442	717		46 757	31.870398371	26.2		0.001	В	easy
eos-910792 eos-932816	30,823	21,007	484,926	20,566		441	15376		2285.5	0.001	Р	easy
eos-932610 eos-933638							276	4	276		P	easy
	13,658	32,417	187,173	28,637		3,780					P	easy
eos-933966	12,047	31,762	180,618	27,982		3,780	318		318		•	easy
eos-934278	11,495	23,123	125,577	19,955		3,168	260		259.5		В	easy
eos-935627	7,859	10,301	40,476	7,522		2,779	2598		2598		RP	easy
eos-935769	6,741	9,799	36,447	7,020		2,779	3010		3010		Р	easy
eos-937511	8,158	11,332	44,237	8,562		2,770	3510		3510		Р	easy
eos-937815	9,251	11,646	48,013	8,876		2,770	?		2837		CR	oper
eos-941262	6,703	9,480	35,659	6,710		2,770	2791	2	2790.5		R	easy
eos-941313	13,189	167,910	484,080	167,910			9361		9361		Р	easy

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuous	MIP Solution	LP Solution	Attlevel	Sets	:	Status
eos-942830	803	882	13,290	834		48	16		12		Т	eas
eos-948126	7,271	9,551	38,219	6,965		2,586	2607		2602		R	hard
eos-952987	354	31,329	90,384	31,329			?	1327.3	3714		C	opei
eos-957389	5,115	6,036	355,372	6,036			1.5		1.5		Р	eas
eos-984165	6,962	8,883	36,742	6,478		2,405	?		2186		CR	opei
et12	14,021	14,115	80,384	1,603		12,512	214	17.24	9479		BR	eas
etdiversion	119,589	129,180	615,282	129,180			242		230.8		В	eas
iewdano	576	505	2,184	56		449	65.666666667	11.72			В	eas
obel-eu-DBE	879	3,771	11,313	1,639		2,132	608910	5706	87.5		Т	hard
oswot	182	128	735	75	25	28	-41		-43		ВТ	eas
pmv07	76,342	220,686	859,614	1,880		218,806	1.0481e + 11	104809667051.	7079	0.007	U	hard
s1111636	13,895	360,822	568,444	13,200		347,622	?	g	96.25	0.015	CR	opei
s1116954	131,991	12,648	410,582	7,482		5,166	0		0		Р	eas
s1158817	68,455	1,804,022	2,842,044	66,022		1,738,000	infeasible	infea	sible	0.01	I	eas
s1208400	4,289	2,883	81,746	2,880		3	2		0		В	eas
s1456591	1,997	8,399	199,862	8,000	19	380	?	361.93	9022	0.001	CT	opei
s1606230	3,503	4,173	92,133	3,633		540	21	13	3.225		R	eas
s1631475	24,496	22,696	116,733	22,470	211	15	?	817.19	3748		CR	opei
s1644855	40,698	30,200	2,110,696	10,000		20,200	-1524.333333333	-1524.33	3333	0.039	R	hard
s1663818	172,017	124,626	20,433,649	124,626			?		1	_	CX	opei
s1685374	44,121	10,000	220,859	10,000			-13	-51.80	0913		R	hard
s1686196	4,055	2,738	68,529	2,738			infeasible		2		- 1	eas
s1688347	4,191	2,685	66,908	2,685			27		2		В	eas
s1696083	11,063	7,982	384,129	7,982			?		2	0.003	CR	opei
s1702808	1,474	804	5,856	666		138	infeasible		1700		- 1	eas
s1745726	4,687	3,208	90,278	3,208			infeasible		3		- 1	eas
s1758913	624,166	17,956	1,283,444	17,822		134	-1454.671755	-1501.18	3256		В	eas
s1766074	182	100	666		90	10	infeasible	58	33.8		BIT	eas
s1769397	5,527	3,772	117,383	3,772			infeasible		3	0.001	- 1	eas
s1778858	10,666	4,720	32,673	4,720			?	-28931833.44	6612		C	opei
s1830653	2,932	1,629	100,933	1,458		171	20622		6153		В	eas
s1853823	224,526	213,440	1,489,480	213,440			?	601	82.9	800.0	C	opei
s1854840	143,616	135,754	856,994	135,280	474		?	12	2000		C	opei
s1856153	35,407	11,998	105,882	11,956		42	?		0		CR	opei
s1904248	149,437	38,458	378,770	38,416		42	?		0	0.007	C	ope
s1905797	51,884	18,192	239,700	17,676	4	512	?	11.7	5098		C	opei
s1905800	8,289	3,228	38,100	3,030	3	195	?	6.	4366		C	ope:
s1952667	41	13,264	335,643	•	13,264		0		0		Ρ	eas
s2017839	54,510	55,224	317,840	12		55,212	7.70305e+13	7702563956752	20.05	0.01	U	eas
s2081729	1,190	661	5,680	600		61	9		4.6		Т	eas

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuous	MIP Solution	LP Solution	Attlevel	Sets		Status
s2118727	163,354	167,440	646,864	159,514		7,926	in feasible	260.7	51793	0.002	IR	easy
s2122603	24,754	19,300	77,044	7,588		11,712	in feasible		0	1	IU	hard
s2124243	139,280	156,083	429,032	16,447		139,636	?	53998.33	33333		C	open
s2137859	206,726	103,361	923,682	103,041		320	?		24629		C	open
s4-pr3	2,210	8,601	25,986		61	8,540	?	;	36073		C	open
s4-pr9	2,220	7,350	22,176		42	7,308	?	;	35175		C	open
s894236	8,218	9,666	41,067	9,666			?	12.30	05229		CR	open
s894244	12,129	21,856	90,864	21,856			15	12.32	26616	0.006	R	easy
s894786	16,794	27,278	113,575	27,278			?	6.08	80533	0.001	CR	open
s894788	2,279	3,463	14,381	3,463			7	6.30	04802		Т	easy
s903616	18,052	21,582	91,641	21,582			?	14.75	50147	0.001	CR	open
s930473	23,240	11,328	121,764	11,176		152	?		0	0.001	CR	open
sr8k	6,284	38,356	371,608	32,040		6,316	?	17500809.53	11815	0.001	CR	open
u120-pr3	2,210	8,601	25,986	8,540	61		28130	21306.44	42308		C	hard
iu60-pr9	2,220	7,350	22,176	7,308	42		24940		22850		C	hard
· fi	422,587	420,434	1,778,754	18,632	11,073	390,729	6.15538e+09	6131846109.62	23997	0.168	U	hard
pm2-z10-s2	160,633	6,250	371,243	6,250			?	-49308.2	78601	0.001	C	open
pm2-z11-s8	223,082	8,019	510,283	8,019			?	-62971.93	30395		CR	open
pm2-z12-s14	319,508	10,800	725,376	10,800			?	-91524.	54224	0.001	CR	open
pm2-z12-s7	319,508	10,800	725,385	10,800			?	-90514.28	85842	0.001	CR	open
pm2-z7-s2	31,798	2,023	79,762	2,023			-10280	-12879.68	86897		В	easy
100×588b	688	1,176	2,352	588		588	?	5554.0			C	open
2m2p1m1p0n100	1	100	100	100			infeasible		80424		IT	easy
6b	5,852	462	11,704	462			?		-231		C	open
80×400b	480	800	1,600	400		400	39667	6	418.8		Т	easy
b-simp-nonunif	1,451,912	23,848	4,366,648	23,848			?			0.001	CX	open
g5_34	225	2,600	7,700	100		2,500	-14339.353446926	-16646.58	86017		В	easy
g	125	2,700	5,200	100		2,600	-8674.342607117	-11824.6			Т	easy
igeon-10	931	490	8,150	400		90	-9000		10000		ВТ	easy
igeon-11	1,123	572	9,889	473		99	-10000		11000		Ť	easy
igeon-12	1,333	660	11,796	552		108	-11000		12000		СŤ	hard
igeon-13	1,561	754	13,871	637		117	?		13000		C	open
igeon-19	3,307	1,444	29,849	1,273		171	7		19000		Č	open
robportfolio	302	320	6,620	300		20	16.734246764	•	5		č	hard
rotfold	2,112	1,835	23,491	1,835			-31	-41.9		0.01	Ř	hard
w-myciel4	8,164	1,059	17,779	1,058	1		10	11.5	0	2.01	В	easy
iu	1,192	840	3,432	48	-	792	-132.873136947	-931.63	-		В	easy
ueens-30	960	900	93,440	900		132	7	-70.9			C	open
80×800	880	1,600	3,200	800		800	?		51.48		Č	open
ail01	46.843	117,527	392,086	117.527		000	-70.5699643			0.002	R	easy

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuou	s MIP Solution	LP Solution	Attlevel	Set	ts	Status
rail02	95,791	270,869	756,228	270,869			-200.449907667	-206	5.6102	0.01	CR	hard
rail03	253,905	758,775	1,728,451	758,775			?	-92	0.274	0.025	CR	open
rail507	509	63,019	468,878	63,009		10	174	172.1	45567		В	
ramos3	2,187	2,187	32,805	2,187			?		145.8		CR	open
ran14×18-disj-8	447	504	10,277	252		252	3735	3444.4	21066		Т	
ran14×18	284	504	1,008	252		252	3712	3016.9	44354		Т	
ran16×16	288	512	1,024	256		256	3823	3116.4	29512		В	
reblock166	17,024	1,660	39,442	1,660			-6.00052e+08	-886882876.9	65829		Т	
reblock354	19,906	3,540	52,901	3,540			-39280521.2281657	-39641692.4	52292		C	
reblock420	62,800	4,200	138,670	4,200			-5.17793e + 08	-886535897.5	22137		C	hard
reblock67	2,523	670	7,495	670		-	-34630648.43833169	-39339910.9	23037		В	
rmatr100-p10	7,260	7,359	21,877	100		7,259	423	360.5	93308		В	
rmatr100-p5	8,685	8,784	26,152	100		8,684	976	762.0	40054		В	easy
rmatr200-p10	35,055	35,254	105,362	200		35,054	?	1550.6	20783		C	open
rmatr200-p20	29,406	29,605	88,415	200		29,405	837	688.3	57943		C	
rmatr200-p5	37,617	37,816	113,048	200		37,616	4521	3283.6	53831		C	
rmine10	65,274	8,439	162,264	8,439			?	-1926.	86382		C	open
rmine14	268,535	32,205	660,346	32,205			?	-4310.6	94704	0.002	C	open
rmine21	1,441,651	162,547	3,514,884	162,547			?	-10	679.2	0.01	CX	open
rmine25	2,953,849	326,599	7,182,744	326,599			?	-15	667.9	_	CX	open
rmine6	7,078	1,096	18,084	1,096			-457.18614	-462.3	05727		В	
rocll-4-11	21,738	9,234	243,106	9,086		148	-6.652756	-11.9	37162		В	
rocll-7-11	37,215	16,101	423,661	15,851		250	?	-11.9	64093		C	
rocll-9-11	47,533	20,679	544,031	20,361		318	?	-11.9	72072		C	open
rococoB10-011000	1,667	4,456	16,517	4,320	136		19449	8350.1	99468		C	
rococoC10-001000	1,293	3,117	11,751	2,993	124		11460	7515.2	71029		В	easy
rococoC11-011100	2,367	6,491	30,472	6,325	166		?	9024.2	05406		CR	open
rococoC12-111000	10,776	8,619	48,920	8,432	187		?	27337.3	57381		C	open
roll3000	2,295	1,166	29,386	246	492	428	12890	11097.1	27677		В	
rvb-sub	225	33,765	984,143	33,763		2	?	11.2	06514		C	
satellites1-25	5,996	9,013	59,023	8,509		504	-5		-20	0.016	В	
satellites2-60-fs	16,516	35,378	125,048	34,324		1,054	-19		-30	0.051	R	easy
satellites2-60	20,916	35,378	283,668	34,324		1,054	-19		-30	0.143	CRU	hard
satellites3-40-fs	35,553	81,681	291,161	79,961		1,720	?		-39	0.292	CRU	open
satellites3-40	44,804	81,681	698,176	79,961		1,720	?		-39	0.3	CRU	open
sct1	12,154	22,886	105,571	9,044	1,268	12,574	?	-218.1	39003		C	
sct32	5,440	9,767	109,654	6,396	1,332	2,039	?	-62.9	90833		C	
sct5	13,304	37,265	147,037	20,702	2,302	14,261	?	-228.1	76552		CR	open
set3-10	3,747	4,019	13,747	1,424		2,595	?	788.8	90655		C	open
set3-15	3,747	4,019	13,747	1,424		2,595	?	8364.0	40745		C	open

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Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuous	MIP Solution	LP Solution A	Attlevel	Set	5 5	Status
set3-20	3,747	4,019	13,747	1,424		2,595	?	10347.38108	37		С	oper
seymour	4,944	1,372	33,549	1,372			423	403.8464	74		C	hard
seymour-disj-10	5,108	1,209	64,704	1,209			?	280.81783	18		C	oper
shipsched	45,554	13,594	121,571	10,549		3,045	?		0		C	open
shs1023	133,944	444,625	1,044,725	1,296	440,899	2,430	?	12121.3581	13 0	0.001	C	open
siena1	2,220	13,741	258,915	11,775		1,966	?	10163179.2290	02		C	open
sing161	455,631	770,102	2,072,500	733,244		36,858	?	19071259.1139	27		C	open
sing245	143,161	235,146	652,817	220,692		14,454	?	25024015.7540	83 C	0.001	CR	open
sing2	28,891	31,630	149,712	23,377		8,253	?	17150914.716	94		C	open
sing359	437,116	713,762	1,975,605	674,643		39,119	?	22534478.9624	98 C	0.001	CR	open
sp97ar	1,761	14,101	290,968	14,101			660705645.76	652560391.2475	64		C	hard
sp98ic	825	10,894	316,317	10,894			449144758.4	444277568.9341	52		В	easy
sp98ir	1,531	1,680	71,704	871	809		219676790.4	216663444.5899	36		В	easy
splan1	572,800	1,317,382	5,233,840	90,810	1,978	1,224,594	?	-2018	99	_	CXU	open
stockholm	57,346	20,644	171,076	962		19,682	?	0.7556	13 0	0.001	C	open
stp3d	159,488	204,880	662,128	204,880			493.71965	481.8777	86 C	0.006	CR	hard
ts405	27,270	405	81,810	405			?	1	35		C	open
ts729	88,452	729	265,356	729			?	2	43 C	0.001	CR	open
swath	884	6,805	34,965	6,724		81	467.407491	334.4968	58		C	hard
:1717	551	73,885	325,689	73,885			?	134531.0214	28		C	open
:1722	338	36,630	133,096	36,630			?	98815.4076	11		C	open
anglegram1	68,342	34,759	205,026	34,759			5182		0		В	easy
anglegram2	8,980	4,714	26,940	4,714			443		0		В	easy
imtab1	171	397	829	64	107	226	764772	286	594		BT	easy
oll-like	4,408	2,883	13,224	2,883			?		0		C	oper
ransportmoment	9,616	9,685	29,541	2,456		7,229	?	-70929535815.379	999 (0.325	CU	oper
riptim1	15,706	30,055	515,436	20,451	9,597	7	22.8681	22.8680	88(0.01	BP	easy
riptim2	14,427	27,326	521,898	20,771	6,548	7	?	10.8663	359	0.01	CR	oper
riptim3	14,939	28,440	524,124	21,621	6,812	7	?	13.5117	741	0.011	CR	oper
w-myciel4	8,146	760	27,961	759	1		?	3.8380	028		C	oper
ıc-case11	51,438	34,134	202,042	3,898	302	29,934	?	611267.0130	004	0.001	C	oper
ıc-case3	52,003	37,749	273,618	11,256		26,493	?	7181.2641	L77		C	oper
ict-subprob	1,973	2,256	10,147	379		1,877	314	2	242		C	hard
ımts	4,465	2,947	23,016	2,802	72	73	30090328	29129565.1613	344		Т	easy
initcal_7	48,939	25,755	127,595	2,856		22,899	19635558.2440195	19387553.3812	271	0.002	В	easy
ısAbbrv-8-25_70	3,291	2,312	9,628	1,681		631	?		95		C	oper
ran e	27,331	12,481	487,296	192		12,289	?	1.723	352		C	oper
pphard2	198,450	199,999	648,340	199,999			?		0		C	oper
pphard	47,280	51,471	372,305	51,471			5		0		В	easy
wachplan	1,553	3,361	89,361	3,360	1		-8		-9		Т	easy

Table ?? continued

Name	Rows	Columns	Non-Zeros	Binary	Integer	Continuous	MIP Solution	LP Solution	Attlevel	Sets	S St	atus
wnq-n100-mw99-14	656,900	10,000	1,333,400	10,000			?	185.2	263158		CT	open
zib01	5,887,041	12,471,400	49,877,768	12,471,400			?		64697	_	CX	open
zib02	9,049,868	37,709,944	146,280,582	37,709,944			infeasible	$inf\epsilon$	easible	_	CIX	hard
zib54-UUE	1,809	5,150	15,288	81		5,069	10334015.82	3875862.8	362589		В	easy

Table 7: Results for the Benchmark-Set using 1 thread, time limit 1 hour. Time is given in seconds, if the time limit was reached the optimality gap is given instead. *Italic* indicates that the solution did not pass the feasibility check. *Best* lists the minimum number of nodes and time over all solvers providing a feasible solution. Nodes and Time may have *not* been taken from the same solver. *VS* lists the variability score of the instance as described in Section 5.2. Higher numbers indicate higher performance variability. The additional test sets containing each instance, other than BENCHMARK, are listed in *Sets*

additiona	ıı test s						ENCHMARK	, are i		Deis	ggip /s	IDV I	Best	. 1	
Name	Sets	Nodes	PLEX Time	Nodes	PRESS Time	Nod	GUROBI es Tim		CBC lodes	Time	SCIP/S Nodes	Time	Nodes	Time	VS
	Jets	Noues				1		e 10		ı					
30n20b8			96.7k	20.3%	2.3M	74.8%	87.7k	804	213.1k	60.2%	8.2k	332.5%	87654	804	
acc-tight5		RP	9	5	487	75	1.4k	121	1.2k	303	497	137	9	5	0.72
aflow40b			98.3k	376	134.8k	399	166.7k	738	367.9k	5.3%	278.7k	2400	98349	376	0.39
air04			225	6	121	12	125	10	456	55	76	65	76	6	0.14
app1-2			30.0k	1420	33.6k	125	64	65	2.7k	inf%	1	inf%	64	65	
ash608gpia	a-3col	I	9	53	15	180	5	221	1	567	7	47	1	47	0.20
bab5			55.1k	1722	27.3k	0.7%	9.5k	662	22.7k	inf%	7.5k	1.4%		662	
beasleyC3			544.9k	1.1%	11.2k	89	729	13	170.1k	21.6%	504.8k	22.3%	729	13	
biella1			11.2k	899	5.5k	424	1.2k	238	16.0k	0.0%	1.7k	682	1162	238	0.29
bienst2			70.1k	63	101.8k	121	97.6k	33	90.8k	1312	89.6k	290	70054	33	0.21
$binkar10_{-}1$			8.7k	15	5.5k	14	51.5k	35	59.0k	481	199.4k	406	5461	14	0.50
$bley_{-}xl1$			43	17	1	8	1	17	50	891	38	305	1	8	0.26
bnatt350		RP	16.5k	3408	82.9k	inf%	36.1k	inf%	7.4k	inf%	6.6k	1191	6567	1191	0.50
core2536-6	591		748	57	183	81	771	194	869	275	308	377	183	57	0.67
cov1075			4.7k	19	185.9k	8.7%	342	6	138.6k	8.9%	529.5k	8.9%	1	6	0.06
csched010			400.3k	3.9%	136.3k	1176	621.6k	2.8%	549.1k	18.9%	466.4k	5.2%	136309	1176	0.26
danoint			528.9k	2.4%	514.7k	3398	819.9k	3.0%	210.1k	2.7%	507.6k	3.1%		3398	0.09
dfn-gwin-U	JUM		36.4k	72	150.9k	264	242.3k	225	332.5k	1132	14.5k	54	14491	54	0.23
eil33-2			10.8k	58	15.7k	125	10.1k	110	8.8k	307	11.1k	180	8792	58	0.15
eilB101			10.5k	160	2.3k	80	22.0k	231	23.8k	1570	3.0k	680	2305	80	0.23
enlight13			84.2k	397	39.1k	13	62.0k	307	237.6k	inf%	622.6k	413	39107	13	1.22
enlight14		ı	663.8k	inf%	142.0k	42	571.5k	inf%	183.1k	inf%	738.2k	665	142035	42	0.82
ex9		Р	1	2102	1	17	1	227	1	inf%	1	85	1	17	0.11
glass4		Т	4.4M	1537	1.7M	26.6%	496.3k	280	221.8k	47.5%	4.0M	100.0%	496349	280	
gmu-35-40		Т	1.6M	893	3.6M	0.0%	13.0M	1898	1.8M	0.0%	4.9M	0.0%	1578834	893	
iis-100-0-c	ov		386.8k	3233	83.4k	1882	144.0k	1515	30.1k	12.1%	103.9k	1808	83425	1515	0.09

Table ?? continued
Name
iis-bupa-cov

		CP	LEX	XPI	RESS	GU	GUROBI		CBC		/SPX	Be	st	
Name	Sets	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	VS
iis-bupa-cov		154.1k	8.6%	54.1k	7.5%	164.2k	5.9%	25.2k	11.3%	85.0k	10.0%	_	- 1	0.06
iis-pima-cov		27.0k	869	17.2k	1014	7.9k	318	15.9k	10.2%	11.1k	864	7917	318	0.21
lectsched-4-obj		1.5k	9	1	1	108	5	8.4k	1544	9.4k	265	1	1	1.04
m100n500k4r1	Р	1.8M	4.2%	1.6M	4.2%	4.3M	4.2%	1.0M	4.2%	3.9M	4.2%	_	_	
macrophage		8.6k	131	641	43	418.2k	1.4%	6.1k	20.6%	308.1k	27.1%	641	43	
map18	R	809	190	513	147	1.1k	203	1.2k	1485	544	764	513	147	0.15
map20		575	138	521	177	1.2k	177	1.0k	1339	550	580	521	138	0.20
mcsched		111.8k	479	427.7k	2769	28.6k	198	117.4k	2.4%	23.1k	337	23111	198	0.16
mik-250-1-100-1		118.1k	14	79.7k	37	97.2k	18	441.8k	0.5%	415.1k	176	79739	14	0.05
mine-166-5		5.4k	24	249	7	6.7k	24	4.7k	157	6.1k	76	249	7	0.24
mine-90-10		345.9k	1350	142.5k	216	1.1M	1144	130.8k	1965	56.2k	264	56177	216	0.75
msc98-ip	R	2.4k	5.0%	21.0k	1.3%	4.7k	700	294	inf%	118	inf%	4734	700	
mspp16	X	53	635	1	253	1	1840	abo	ort	abor	t ¹	1	253	
mzzv11		869	51	69	8	6	17	739	187	2.4k	591	6	8	0.21
n3div36	ĺ	286.3k	6.0%	190.3k	1.2%	501.7k	3358	120.4k	0.5%	84.7k	11.2%	501686	3358)
n3seq24		491	61	1	181	40.8k	677	268	1495	348	0.4%	1	61	
n4-3		8.5k	328	47.6k	1979	120.6k	2110	293.2k	18.7%	81.5k	1052	8467	328	0.34
neos-1109824		8.7k	30	2.1k	14	10.5k	109	22.0k	428	10.8k	119	2071	14	0.30
neos-1337307		67.5k	0.1%	439.5k	0.0%	220.7k	0.0%	12.4k	0.1%	167.4k	0.0%	_	_	
neos-1396125		26.4k	82	12.6k	79	8.2k	135	54.9k	24.0%	49.8k	3338	8175	79	0.25
neos-1601936	R	6.3k	1759	695	31	333	56	8.9k	996	8.9k	66.7%	333	31	0.81
neos-476283		1.0k	243	777	149	515	142	710	1561	453	322	453	142	0.16
neos-686190		4.3k	29	6.7k	52	5.3k	47	5.5k	154	5.6k	95	4298	29	0.27
neos-849702	Р	44.9k	inf%	43.9k	409	104.6k	1066	152.6k	inf%	244.3k	inf%	43941	409	1.59
neos-916792		122.8k	569	42.1k	208	67.2k	1525	106.0k	4.3%	67.4k	367	42060	208	2.23
neos-934278		101	230	199	82	1	82	400	649	2.1k	2.9%	1	82	
neos13		4.1k	58	65	26	711	47	28.1k	2.7%	283	657	65	26	1.72
neos18		13.7k	27	20.0k	55	13.7k	65	abo	ort	9.9k	68	9854	27	0.39
net12	R	2.5k	22.1%	2.5k	92	1.3k	290	1.4k	35.3%	5.0k	57.6%	1348	92	0.33
netdiversion		28	74	9	76	123	628	847	1.4%	51	inf%	9	74	
newdano		170.6k	34.7%	372.4k	4.8%	683.3k	11.0%	81.9k	23.7%	1.5M	31.0%	_	_	0.21
noswot	Т	6.9M	950	1.7M	344	566.3k	72	1.0M	2194	605.0k	210	566273	72	0.34
ns1208400		2.9k	88	221.6k	inf%	623	81	57.8k	inf%	3.0k	526	623	81	0.70

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		CPI	LEX	XPI	RESS	GU	ROBI	0	CBC	SCI	P/SPX	Bes	st	
Name	Sets	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	VS
ns1688347		7.3k	139	2.5k	25	868	31	3.6k	inf%	4.2k	1027	868	25	0.79
ns1758913		24	158	1	37	1	44	1	inf%	1	inf%	1	37	
ns1766074	ΙT	870.3k	133	520.8k	141	1.1M	110	189.9k	592	945.4k	668	189900	110	0.12
ns1830653		10.9k	206	31.9k	394	26.9k	427	20.7k	95.0%	47.0k	638	10915	206	0.42
opm2-z7-s2		2.0k	282	2.5k	501	639	67	3.5k	1039	1.5k	660	639	67	0.17
pg5_34		107.8k	244	88.6k	376	187.0k	439	97.3k	1787	257.0k	1247	88573	244	0.13
pigeon-10	Т	5.8M	985	7.8M	2561	4.0M	558	685.7k	11.1%	3.7M	11.1%	3984370	558	
pw-myciel4		33.1k	159	108.6k	1121	4.7M	11.1%	35.5k	66.7%	309.9k	42.9%	33124	159	0.51
qiu		2.2k	11	8.3k	55	3.4k	18	13.1k	222	14.5k	98	2157	11	0.19
rail507		3.5k	207	2.8k	911	1.5k	123	7.6k	1458	1.3k	1252	1259	123	
ran16×16		64.3k	73	69.9k	88	81.8k	76	195.6k	785	344.3k	291	64322	73	0.20
reblock67		588.1k	766	234.5k	342	636.6k	651	305.1k	3275	139.6k	373	139635	342	0.32
rmatr100-p10		2.0k	76	917	56	1.0k	28	2.9k	157	863	322	863	28	0.08
rmatr100-p5		1.2k	94	681	107	1.2k	107	1.4k	167	419	991	419	94	0.12
rmine6		917.2k	1979	416.7k	1032	404.4k	476	459.9k	0.1%	546.9k	0.1%	404406	476	0.19
rocll-4-11		175.6k	271	47.3k	318	33.8k	205	19.2k	0.3%	27.6k	381	27610	205	0.32
rococoC10-001000		45.5k	597	35.9k	420	1.7M	0.4%	36.3k	1345	462.5k	2493	35937	420	0.42
roll3000		31.3k	138	1.9k	16	6.8k	68	34.5k	2284	593.9k	3399	1947	16	0.54
satellites1-25		3.5k	200	2.3k	120	634	102	14.5k	$1582^{\ 2}$	8.6k	197.0%	634	102	0.53
sp98ic		196.3k	1166	23.3k	563	32.8k	289	86.5k	0.3%	35.0k	3.5%	23317	289	
sp98ir		6.5k	39	2.6k	38	6.9k	126	6.9k	103	4.8k	78	2641	38	0.20
tanglegram1	ĺ	31	1791	35	157	23	287	203	inf%	1	9954.4%	23	157)
tanglegram2		3	59	3	2	7	17	302	216	15	1306	3	2	0.41
timtab1	T	855.6k	797	307.8k	373	3.4M	1568	233.4k	24.8%	700.0k	415	307773	373	0.43
triptim1	Р	1	39	33	60	1	59	1	123	118	0.1%	1	39	0.48
unitcal_7		2.0k	108	39	18	3.1k	189	3.3k	1511	12.3k	1479	39	18	1.05
vpphard		13.6k	2481	149.3k	inf%	12.8k	inf%	6.4k	inf%	4.3k	inf%	13580	2481	
zib54-UUE		22.1k	1818	164.0k	1527	31.3k	2397	79.3k	6.5%	431.0k	9.9%	22093	1527	0.28

¹ out-of-memory; ² constraint violation, absolute error: 0.0003

Table 8: Results for the Benchmark-Set using 12 cores, time limit 1 hour. Time is given in seconds, if the time limit was reached the optimality gap is given instead. *Italic* indicates that the solution did not pass the feasibility check. *Best* lists the minimum number of nodes and time over all solvers providing a feasible solution. Nodes and Time may have *not* been taken from the same solver. *SU* gives the speedup as the ratio between the best solution times for 1 thread and 12 threads. The additional test sets containing each instance, other than BENCHMARK, are listed in *Sets*

	1	CF	LEX	3	KPRESS		GUROBI		CBC		UG[SCIP	SPX]	E	3est	
Name :	Sets	Nodes	Time	Node	s Time	Noc	les Tim	ne N	lodes	Time	Nodes	Time	Nodes	Time	SU
30n20b8			158.7k	401	7.9M	19.4%	61.2k	173	abo	ort^1	361	200.0%	61204	173	4.6
acc-tight5		RP	53	6	743	13	235	13	395	45	151	66	53	6	0.8
aflow40b			67.1k	45	218.8k	139	535.9k	159	abo	ort^1	28.9k	233	28947	45	8.4
air04			765	9	122	11	214	9	1.1k	34	35	70	35	9	0.7
app1-2			378.0k	1545	330.3k	276	36	61	10.9k	3443	282	490.3%	36	61	1.1
ash608gpia-3	3col	ļ	1	14	15	203	5	222	1	571	7	94	1	14	3.4
bab5			230.5k	1048	350.6k	0.1%	25.1k	277	465.7k	8.6%	2.0k	0.9%	25086	277	2.4
beasleyC3			1.6M	1088	31.7k	29	2.2k	11	1.5M	21.5%	557.4k	22.3%	2248	11	1.2
biella1			10.8k	101	17.0k	128	2.8k	178	22.0k	371	1.5k	723	1496	101	2.4
bienst2			72.0k	9	99.5k	14	102.6k	5	104.7k	104	115.5k	128	71998	5	6.6
binkar10_1			16.5k	6	9.5k	4	2.5k	1	36.6k	67	28.3k	35	2516	1	14.0
bley_xl1			18	12	1	6	1	17	21	563	1	178	1	6	1.3
bnatt350		RP	12.5k	357	256.0k	1237	128.7k	1650	108.3k	inf%	1.4k	344	1398	344	3.5
core2536-691	1		1.1k	47	639	49	3.6k	122	1.1k	125	54	359	54	47	1.2
cov1075			8.7k	6	1.6M	3415	342	3	748.2k	7.0%	1.6M	1601	342	3	2.0
csched010			590.4k	391	280.4k	319	2.3M	1158	4.8M	14.1%	1.0M	1307	280429	319	3.7
danoint			472.3k	239	479.8k	336	1.6M	598	abo	ort^1	754.8k	599	472286	239	14.2
dfn-gwin-UU	IM		31.2k	12	181.2k	65	245.7k	23	91.1k	73	12.2k	57	12202	12	4.5
eil33-2			10.6k	16	10.7k	60	8.4k	38	9.5k	175	8.1k	163	8145	16	3.6
eilB101			6.2k	18	2.8k	34	41.7k	53	28.5k	231	2.2k	445	2202	18	4.4
enlight13			1.5M	273	106.6k	6	1.5M	274		ort^1	3.1M	931	106585	6	2.2
enlight14		I	7.3M	2617	234.6k	13	14.7M	inf%	2.3M	inf%	114.7k	193	114658	13	3.2
ex9		Р	1	376	1	16	1	226	1	inf%	1	87	1	16	1.1
glass4		T	2.2M	$20.8\%^{2}$	6.5M	718	1.6M	45		ort^1	4.3M	570	1622146	45	6.2
gmu-35-40		Т	1.2M	55	19.6M	0.0%	103.2M	3482		ort^1		ort^3	1240043	55	16.2
iis-100-0-cov			147.6k	149	88.2k	257	149.8k	215	113.2k	7.5%	50.0k	718	49991	149	10.2

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		CPI	LEX	XPF	RESS	GUI	ROBI	(CBC	UG[SCI	IP/SPX]		Best	
Name	Sets	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	SU
iis-bupa-cov		770.5k	1576	300.3k	1246	224.1k	612	355.3k	5.6%	126.8k	1350	126850	612	>5.9
iis-pima-cov		30.8k	142	36.2k	244	20.3k	149	32.3k	695	7.3k	889	7304	142	2.2
lectsched-4-obj		5.7k	8	393	2	547	4	12.7k	170	697	121	393	2	0.5
m100n500k4r1	Р	19.8M	4.2%	12.3M	4.2%	47.8M	4.2%	3.8M	4.2%	8.0M	4.2%	_	_	-
macrophage		248.1k	355	725	29	1.6M	1102	159.6k	15.8%	4.4k	27.0%	725	29	1.5
map18	R	1.1k	124	2.0k	78	1.5k	48	1.3k	733	375	1531	375	48	3.1
map20		1.1k	103	3.1k	113	1.4k	36	1.1k	625	332	1292	332	36	3.8
mcsched		117.8k	58	324.0k	263	26.7k	50	76.2k	389	15.5k	269	15487	50	4.0
mik-250-1-100-1		46.1k	2	77.1k	8	195.5k	5	256.5k	210	96.1k	19	46052	2	7.0
mine-166-5		6.2k	9	253	7	24.0k	18	2.0k	92	2.6k	67	253	7	1.0
mine-90-10		314.0k	124	172.2k	44	1.4M	270	120.0k	320	63.2k	154	63248	44	4.9
msc98-ip	R	4.7k	1342	169.9k	0.7%	6.6k	215	1.1k	inf%	29	57.0%	4737	215	3.3
mspp16	X	22	659	1	254	1	1844	abo	ort	abor	t^3	1	254	1.0
mzzv11		828	25	141	8	1	13	621	98	2.1k	850	1	8	1.0
n3div36	ĺ	2.1M	3.6%	578.5k	3268	1.3M	1342	155.4k	1167	50.1k	11.0%	155362	1167	2.9
n3seq24		539	69	1	183	3.1k	187	599	1243	11	20.0%	1	69	0.9
n4-3		12.7k	116	75.7k	359	65.5k	224	808.6k	16.1%	20.1k	441	12681	116	2.8
neos-1109824		11.1k	9	2.2k	6	3.0k	3	19.7k	72	4.4k	169	2167	3	4.7
neos-1337307		252.2k	1024	818.7k	1094	638.9k	1051	175.5k	0.0%	1.2M	0.1%	252150	1024	>3.5
neos-1396125		96.6k	31	34.1k	50	28.2k	25	126.3k	521	23.9k	1278	23883	25	3.2
neos-1601936	R	1.6k	273	2.5k	19	4.8k	213	537.4k	200.0%	2.0k	1223	1558	19	1.6
neos-476283		832	143	537	104	905	106	408	1169	486	878	408	104	1.4
neos-686190		6.3k	11	17.2k	24	10.0k	20	4.6k	43	2.5k	81	2533	11	2.6
neos-849702	P	241.0k	1685	11.9k	19	1.8M	3160	107.2k	187	25.6k	412	11877	19	21.5
neos-916792		98.9k	83	205.5k	210	69.8k	183	467.9k	7.1%	898.4k	15.7%	69764	83	2.5
neos-934278		606	151	4.5k	119	1	82	abo	ort	58	4.0%	1	82	1.0
neos13		3.9k	33	23	14	2.1k	55	8.5k	563	510	655	23	14	1.9
neos18		7.9k	5	24.8k	10	14.3k	20	28.4k	224	6.3k	65	6293	5	5.4
net12	R	3.5k	562	909	11	4.1k	229	2.2k	1010	1.7k	44.9%	909	11	8.4
netdiversion		27	96	17	67	54	550	229	1652	15	inf%	17	67	1.1
newdano		938.0k	1321	797.7k	506	950.0k	373	741.4k	1197	3.4M	924	741404	373	>9.7
noswot	Т	1.6M	28	2.1M	94	382.4k	7	788.5k	182	1.5M	191	382411	7	10.3
ns1208400		8.6k	248	2.0M	inf%	3.1k	47	835.8k	inf%	141.3k	inf%	3142	47	1.7

		CPI	LEX	XPI	RESS	GU	GUROBI		CBC		UG[SCIP/SPX]		Best	
Name	Sets	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	Nodes	Time	SU
ns1688347		2.5k	23	2.9k	6	1.3k	20	29.2k	34.7%	23.4k	671	1271	6	4.2
ns1758913		1	118	1	45	1	44	1	inf%	1	inf%	1	44	3.0
ns1766074	ΙΤ	845.6k	18	521.9k	22	1.1M	14	191.0k	75	925.5k	2366	191024	14	7.9
ns1830653		12.0k	35	20.0k	40	53.0k	284	22.8k	237	22.5k	308	12003	35	5.9
opm2-z7-s2		6.5k	236	2.8k	374	868	42	1.2k	459	1.2k	1572	868	42	1.6
pg5_34		108.1k	43	108.4k	62	156.0k	50	57.6k	190	87.9k	377	57638	43	5.7
pigeon-10	Т	5.8M	118	9.2M	399	3.4M	51	abo	rt^1	1.6M	11.1%	3405798	51	10.9
pw-myciel4		10.9k	15	75.3k	93	711.5k	126	268.6k	3351	434.3k	1242	10893	15	10.6
qiu		5.6k	3	13.6k	11	4.1k	5	12.2k	36	10.0k	70	4143	3	3.7
rail507		3.0k	39	20.2k	685	4.2k	26	abo	rt^1	1.2k	3054	1250	26	4.7
ran16×16		56.4k	10	89.8k	19	238.1k	24	59.7k	52	134.6k	54	56408	10	7.3
reblock67		572.2k	84	485.1k	95	817.8k	160	114.3k	369	115.7k	86	114337	84	4.1
rmatr100-p10		1.8k	15	791	12	1.8k	8	3.0k	39	809	397	791	8	3.5
rmatr100-p5		441	10	421	19	881	12	1.7k	63	419	1535	419	10	9.4
rmine6		944.8k	278	584.9k	220	487.9k	137	262.2k	585	474.8k	354	262168	137	3.5
rocll-4-11		250.8k	75	42.7k	45	29.7k	73	51.6k	1266	27.3k	374^{4}	27259	45	4.6
rococoC10-001000		70.9k	91	69.1k	91	1.7M	309	40.5k	154	164.7k	370	40502	91	4.6
roll3000		32.0k	19	2.1k	5	69.4k	52	22.7k	233	672.0k	1440	2117	5	3.2
satellites1-25		4.2k	90	4.8k	45	2.5k	97	18.9k	176^{5}	14.7k	240.0%	2496	45	2.3
sp98ic		213.5k	200	39.0k	215	14.2k	73	380.4k	2292	1.2M	0.4%	14212	73	4.0
sp98ir		6.3k	12	5.0k	18	9.9k	39	6.8k	16	4.4k	82	4376	12	3.2
tanglegram1		31	514	23	65	54	196	549	inf%	1	0.0%	23	65	2.4
tanglegram2		1	3	3	2	15	16	519	46	47	2153	1	2	1.0
timtab1	Т	842.8k	62	403.8k	63	1.7M	106	abo	ort^1	1.5M	174	403805	62	6.0
triptim1	Р	1	159	119	57	1	60	1	125	2	3011	1	57	0.
unitcal_7		3.2k	97	45	16	3.7k	128	3.7k	664	4.5k	0.1%	45	16	1.:
vpphard		18.5k	1340	511.8k	inf%	78.0k	66.7%	abo		409	inf%	18514	1340	1.9
zib54-UUE		16.2k	353	292.5k	317	40.9k	312	263.3k	1148	360.7k	811	16156	312	4.9

¹ segmentation fault; ² early termination after 90 s due to bug in CPLEX 12.2.0.2, will be fixed in CPLEX 12.3; ³ out-of-memory; ⁴ objective function mismatch; ⁵ constraint violation, absolute error: 0.0003