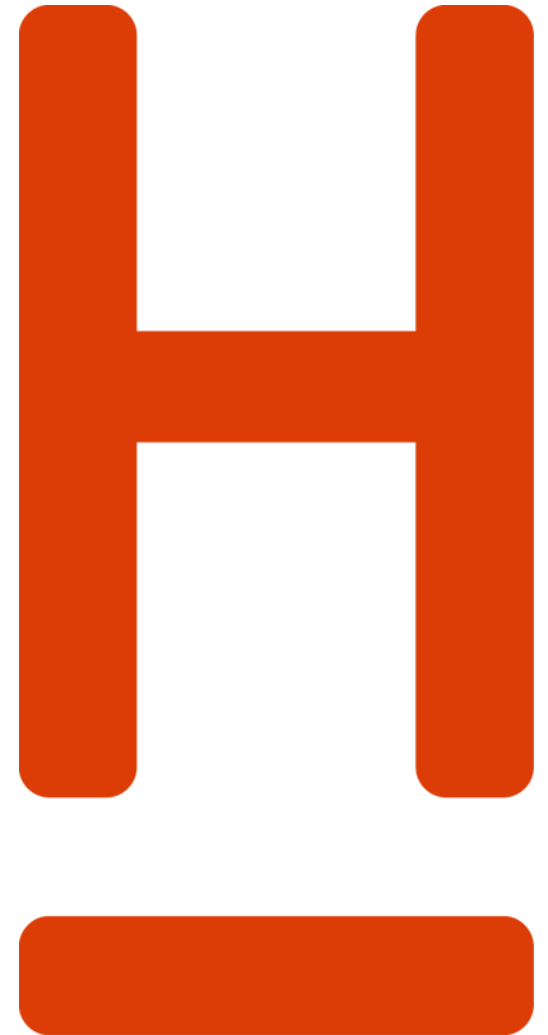


5G for V2X Communication

Lecture 9: Fahrzeugvernetzung – V2X



Lecture 9

Previous Lecture

- ▶ Cellular Network Basics
- ▶ Device-to-Device Communication
- ▶ C-V2X Communication
- ▶ C-V2X Communication Modes
- ▶ Sensing-based Semi-Persistent Scheduling
- ▶ C-V2X Decentralized Congestion Control



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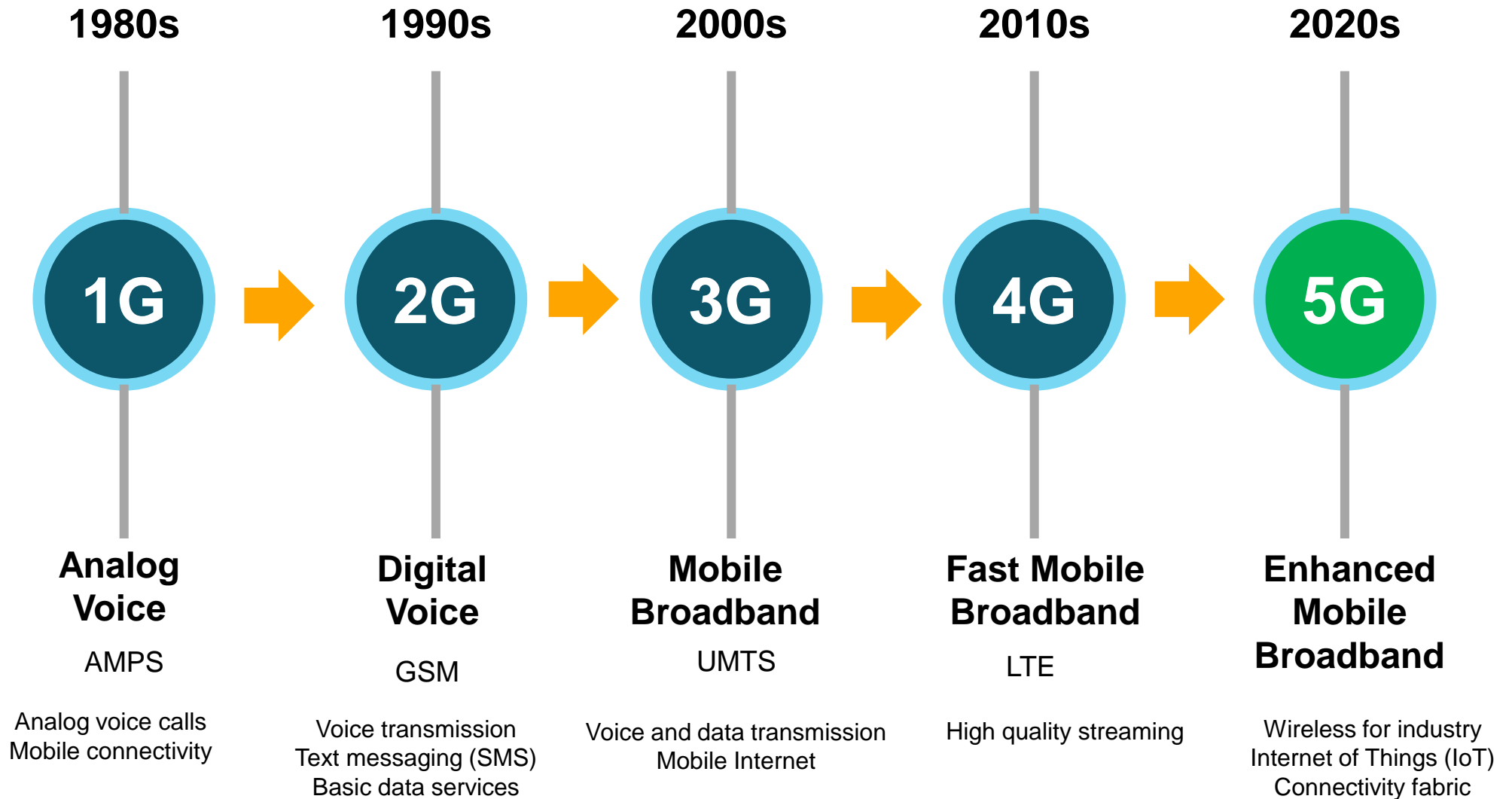
Outline

- ▶ 5G Communication Basics
- ▶ 5G Communication Usage Scenarios
- ▶ 5G New Radio (NR)
- ▶ 5G-V2X Features
- ▶ 5G-V2X Sidelink Modes
- ▶ Coexistence of C-V2X and 5G-V2X
- ▶ V2X Applications supported by 5G-V2X



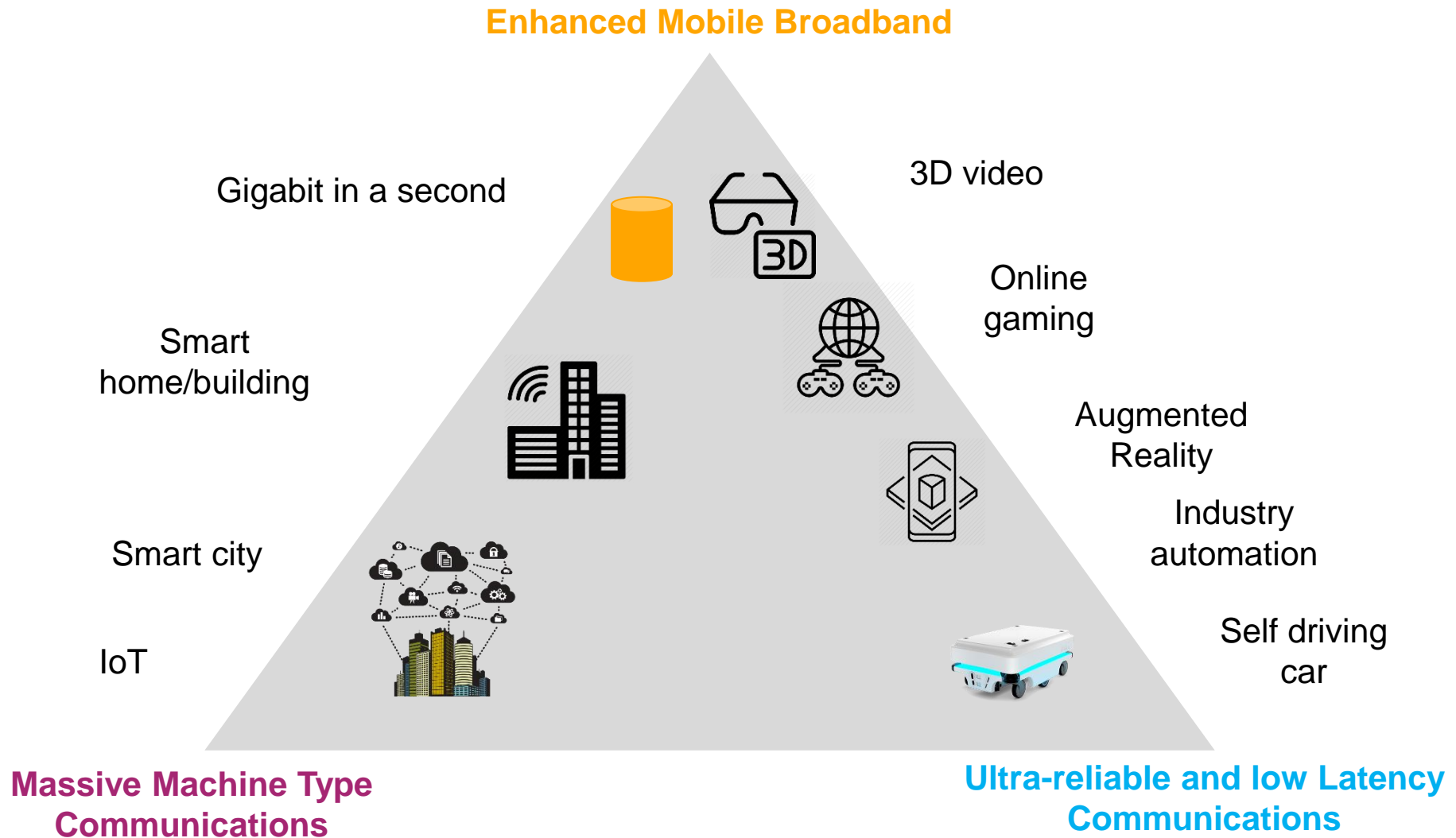
Lecture 9

Towards the fifth Generation of Cellular Network Technology 5G



Lecture 9

5G Promises



Lecture 9

5G Usage Scenarios - Enhanced Mobile Broadband (eMBB)

- ▶ Address the **human-centric use cases** for access to **multi-media content** and services
- ▶ New application areas and requirements for an increasingly **seamless user experience**
 - ▶ Augmented reality (AR)
 - ▶ 360° video streaming
 - ▶ Truly immersive Virtual Reality (VR)
- ▶ **Requirements:**
 - ▶ **Higher capacity:** broadband access must be available in **densely populated** areas, both indoors and outdoors, like city centres, office buildings or public venues like **stadiums** or conference **centres**
 - ▶ **Enhanced connectivity:** broadband access must be **available everywhere** to provide a consistent user experience
 - ▶ **Higher user mobility:** mobile broadband services in **moving vehicles** including cars, buses, trains and planes

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5G Usage Scenarios - Ultra-reliable and low latency communications (uRLLC)

- ▶ uRLLC Address the **stringent requirements** for capabilities such as throughput, latency and availability
- ▶ **New application areas**
 - ▶ Autonomous driving
 - ▶ Wireless control of industrial manufacturing or production processes
 - ▶ Remote medical surgery / Remote driving
- ▶ **Two challenging requirements**
 - ▶ **Ultra-low latency** < 1 millisecond
 - ▶ **Ultra-high reliability** $< 10^{-5}$ packet drop rate
 - ▶ **Trade-off latency and reliability** → try to improve the reliability required the use of more resources for **signaling**, **re-transmission** and **redundancy** resulting in an **increase** of the **latency**



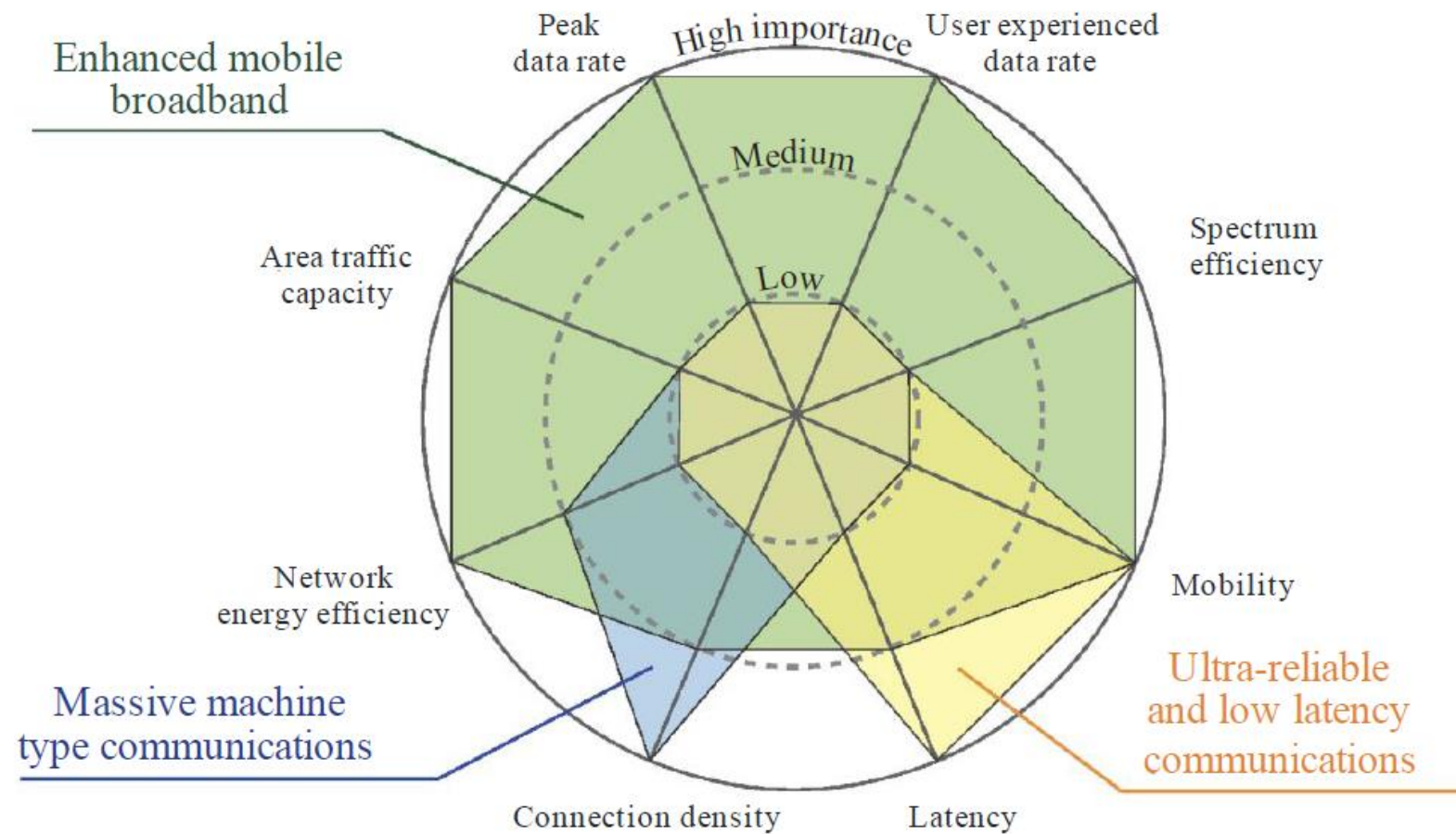
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5G Usage Scenarios-Massive Machine Type Communications (mMTC)

- ▶ mMTC is characterized by **a very large number** of connected devices typically transmitting a relatively **low volume** of **non-delay-sensitive** data
 - ▶ Provide wireless connectivity to **tens of billions** of often **low-complexity low-power** machine-type devices
 - ▶ Devices are required to have a **very long battery life**
- ▶ **New application areas**
 - ▶ Smart cities (smart networked household)
 - ▶ Networked internet of things (smart agriculture)
- ▶ **Requirements**
 - ▶ **Scalable** and **efficient connectivity** for a massive number of devices sending very short packets
 - ▶ **Low latency** and **High reliability**
 - ▶ **Availability**

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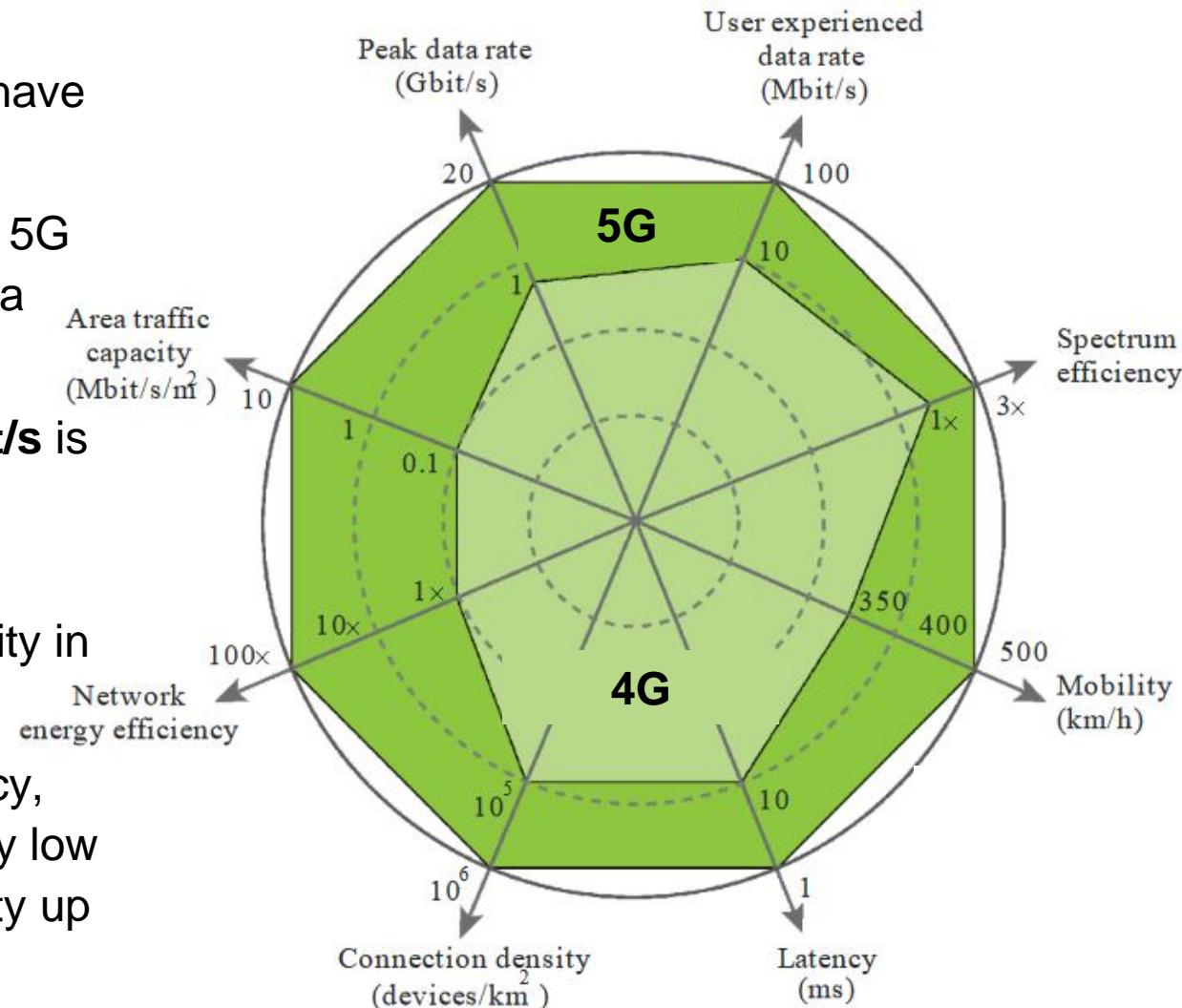
5G Usage Scenarios



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5G Performance Targets

- ▶ Targets for research and investigation have to be further developed
- ▶ Under certain conditions and scenarios 5G would support up to **20 Gbit/s** peak data rate
- ▶ User experienced data rate of **100 Mbit/s** is expected to be enabled for wide area coverage cases
- ▶ Support **10Mbit/s/m²** area traffic capacity in hot spots (stadium, etc.)
- ▶ Able to provide **1 ms** over-the-air latency, capable of supporting services with very low latency requirements under high mobility up to **500 km/h**



Lecture 9

5G Deployment Scenarios

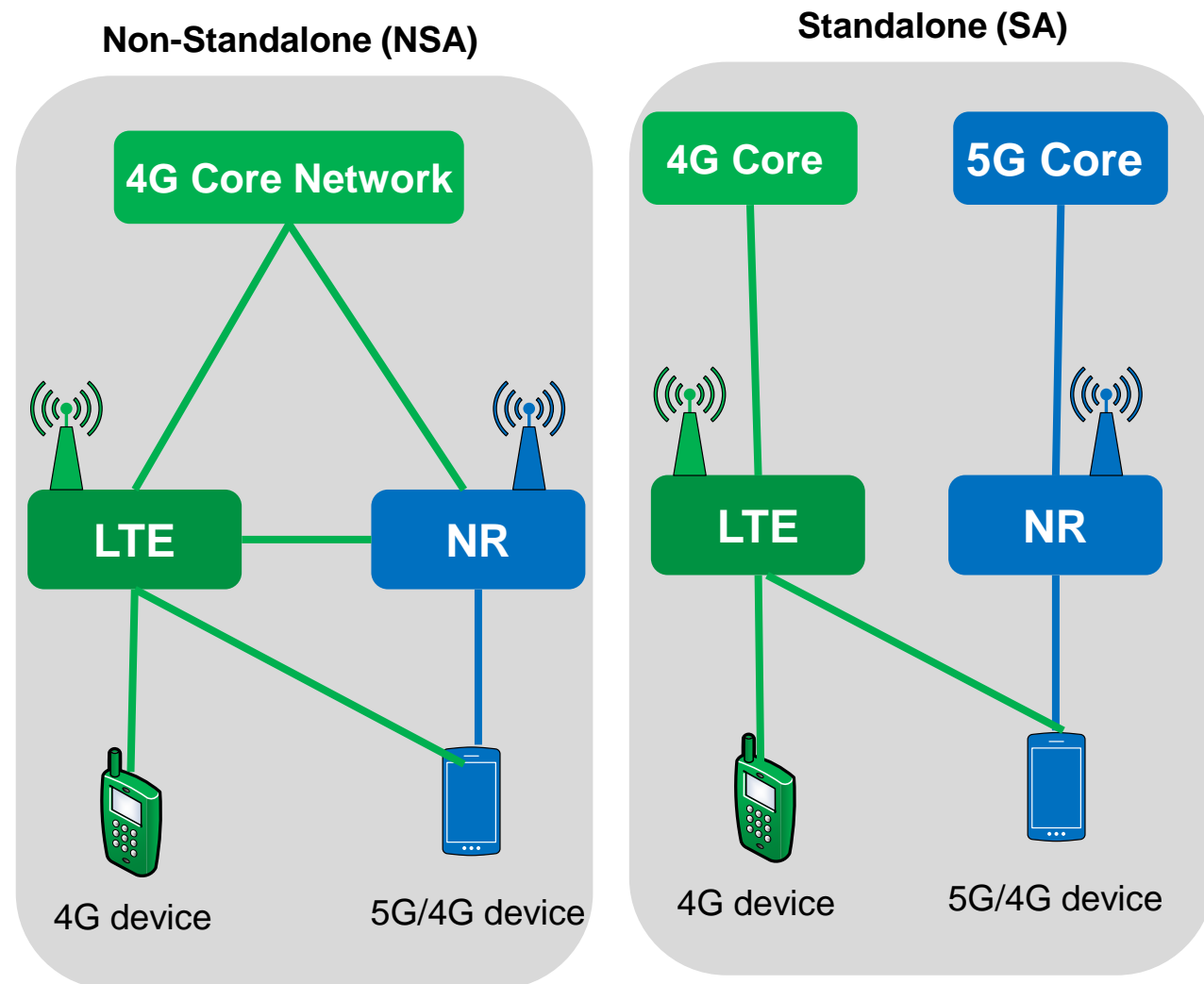
► 5G Non-Standalone (NSA)

- 5G will be aided by existing 4G infrastructure

► 5G Standalone (SA)

- Easier and better efficiency reducing the cost of the devices

- First roll-out of 5G networks and devices will be brought under Non-Standalone (NSA)



NR: New Radio

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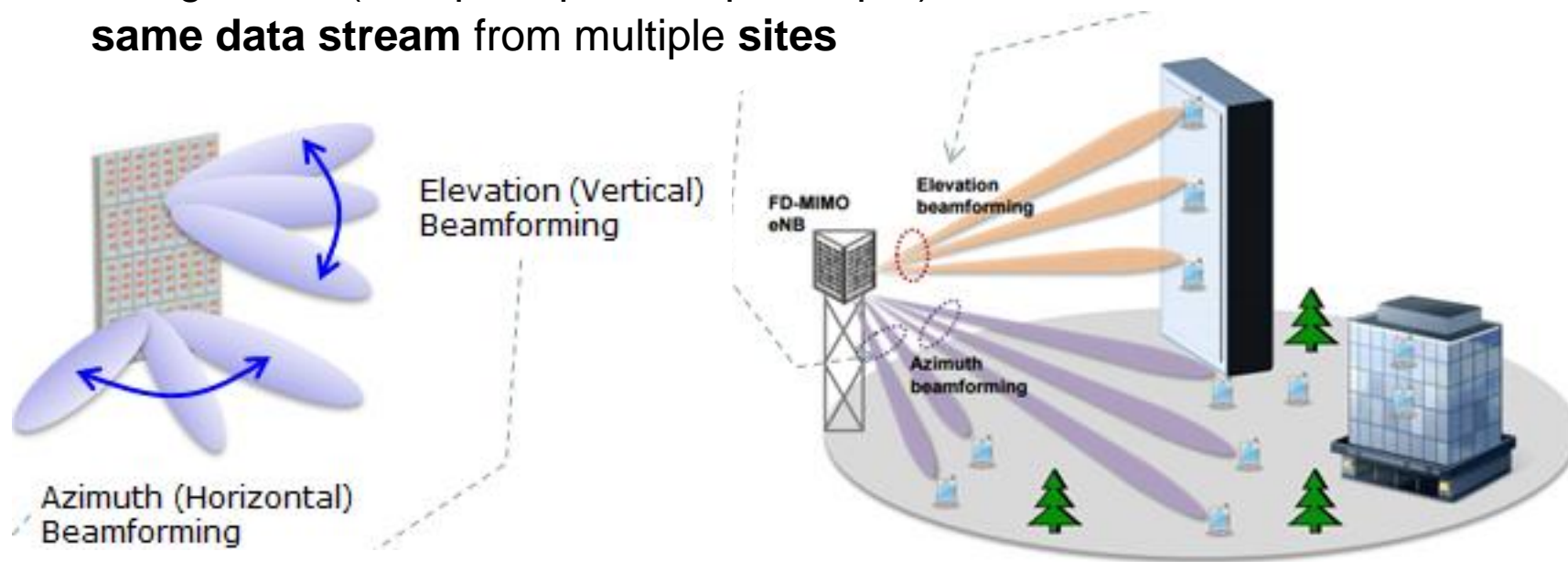
5G-New Radio (NR)

- ▶ **5G NR** includes major advances over LTE
- ▶ It encompasses agile **frame structure**, **high frequencies**, new **multiple access techniques** for
 - ▶ **High capacity**
 - ▶ **Massive connectivity**
 - ▶ **Ultra-low latency**
 - ▶ **High reliability of autonomous driving use cases**
- ▶ 5G NR supports **adaptive** bandwidth
 - ▶ Devices move to a **low-bandwidth, low-power** configuration when appropriate, and gearing up to **higher bandwidths** only when necessary
 - ▶ Very **low average power devices** that can still deliver **high performance**
→ IoT networks

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5G-New Radio (NR) - Beamforming

- ▶ Manipulation of the **signals** fed to and received from complex antennas to **create beams** in space that **focus power** in a particular **direction**
- ▶ Beamforming will mostly be used at high bands to **increase range** by energy focus
- ▶ Beamforming will be used at the **mid** and **low bands** below **6GHz** to **increase bandwidth** for multiple devices in the same area
- ▶ Using MIMO (Multiple input multiple output) where a user can receive **different parts** of the **same data stream** from multiple **sites**



Source: Sharetechnote.com

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5G-NR - Millimeter Wave (mmWave)

- ▶ MmWave refers to the spectrum between **30 and 300 GHz**
 - ▶ Licensed band: **28, 37 and 39 GHz**
 - ▶ Unlicensed spectra: **64 to 71 GHz**
- ▶ **Large** number of **antennas** at the **transmitter** and the **receiver** to form sharp transmit and receive beams
 - ▶ **Small wavelengths** of mmWave frequencies → **Ease** the deployment of a large number of antennas in a **small form factor**
- ▶ Enable a **large bandwidth** and **high throughput** for
 - ▶ V2V communications between **very close vehicles**
 - ▶ to support for e.g. cooperative sensing in a high-density platoon
 - ▶ V2I communications for **bulk data transfer**
 - ▶ for e.g. object detection and recognition, real-time high-definition maps to/from an RSU
- ▶ Available to consumers in the form of IEEE 802.11ad

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5G-NR - Millimeter Wave (mmWave)

► Challenges for V2X environments:

- Overhead for the **beam training** under high mobility
 - Once beams **are properly aligned**, standard communication protocols, i.e., effective channel estimation and data transmission, can be performed using sufficient link margin

► Blockage effect by e.g., pedestrian bodies



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Path towards 5G-V2X

D2D

- ▶ LTE Release 12/13
- ▶ Device-to-device communication
- ▶ Foundation for direct V2X communication over cellular

C-V2X

- ▶ C-V2X 14/15
- ▶ Enhance communication performance
 - ▶ Low latency
 - ▶ High reliability for V2X safety applications
 - ▶ Extended communication range

5G for V2X

- ▶ C-V2X 16
- ▶ Ultra-high throughput
- ▶ Ultra-low latency
- ▶ Ultra-high reliability
- ▶ Foundation for autonomous driving

Lecture 9

Evolution of C-V2X to 5G-NR V2X

- ▶ Design objective of 5G-NR V2X is to **supplement** C-V2X in supporting those **use cases** that **cannot** be supported by **C-V2X**
 - ▶ Built atop of 5G NR
- ▶ C-V2X and 5G-V2X have to **coexist** in the same geographical region, where **newer vehicles** will have both C-V2X and NR V2X capabilities
- ▶ Designed to support V2X applications that have **varying** degrees of **latency**, **reliability** and **throughput** requirements
 - ▶ Some **basic use cases** require the transmission of **periodic traffic**
 - ▶ Large number of 5G-V2X **use cases** are based on reliable delivery of **aperiodic messages**



Lecture 9

Objectives of 5G-V2X

- ▶ **Enhanced sidelink design:** Re-design sidelink procedures in order to support advanced V2X applications
- ▶ **Uu interface enhancements:** Identify enhancements to the NR Uu interface to support advanced V2X applications
- ▶ **Uu interface based sidelink allocation/configuration:** Identify enhancements for configuration/allocation of sidelink resources using the NR Uu interface
- ▶ **RAT/Interface selection:** Study mechanisms to identify the best interface (among C-V2X sidelink, 5G sidelink, LTE Uu) for given V2X message transmission
- ▶ **QoS Management:** Study solutions that meet the QoS requirements of different radio interfaces
- ▶ **Coexistence:** Feasibility study and technical solutions for the coexistence of C-V2X and NR V2X within a single device, also referred to as in-device coexistence

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5G-V2X Sidelink Feedback Channel

- ▶ Blind re-transmission is used to **increase** the **success probability** of transmitting a message with low delay penalty
 - ▶ A node just **proactively retransmits** for a predetermined **number of attempts** rather than stop and wait for a **feedback upon** each transmission
- ▶ Such **blind re-transmissions** are resource **inefficient** if the initial transmission is successful

- ▶ **New features:**
 - ▶ Channel state of the destination can be leveraged to **adapt transmission parameters** → Source UE should have access to the channel state information of its receiving nodes
 - ▶ New feedback channel **Physical Sidelink Feedback Channel (PSFCH)** is introduced to enable **feedback-based re-transmissions** and **channel state information acquisition**

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5G-V2X Slot, Mini-Slot and Multi-Slot Scheduling

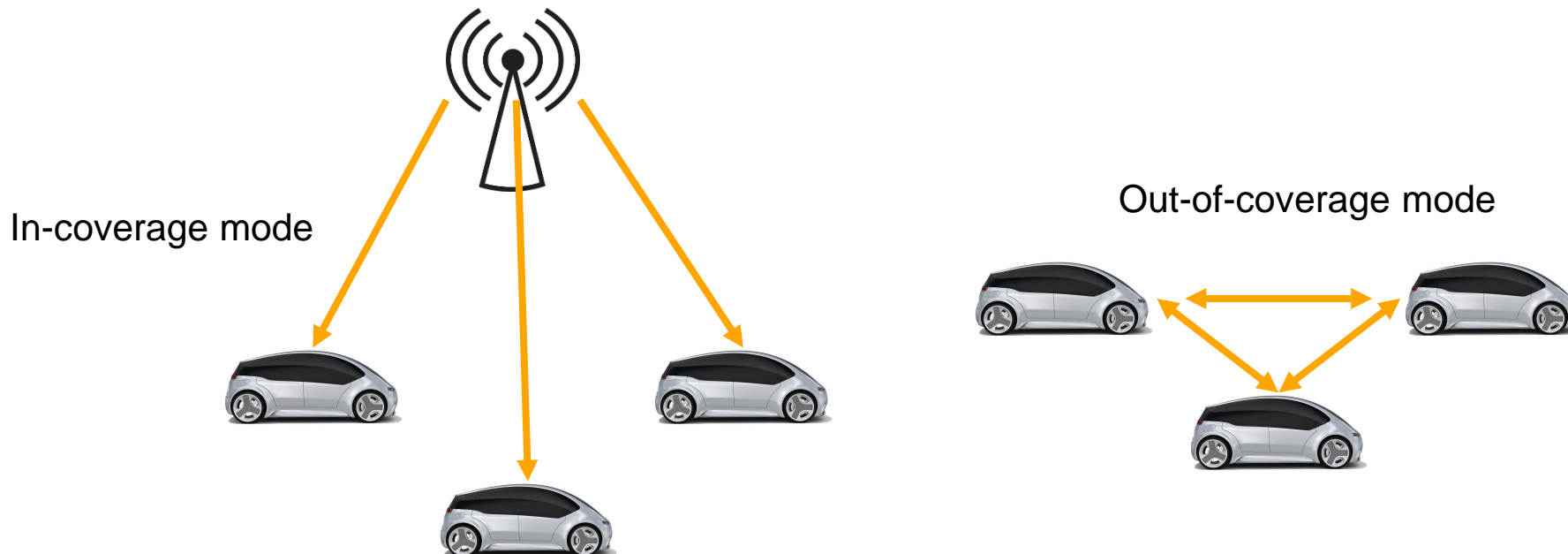
- ▶ In LTE and C-V2X, the transmission time is **tightly coupled** to the **sub-frame** duration
 - ▶ All UEs always transmit for a duration of **1 sub-frame (1 msec)**
 - ▶ In situations where a UE has **only a small amount of data** to send, allocating the entire slot for its transmission is **resource inefficient**
 - ▶ Whenever a packet is ready to be transmitted, the UE **has to wait until** the beginning of the **next slot** to **begin transmitting**

- ▶ **New Features:**
 - ▶ **Mini-slot** scheduling is used for **latency-critical** transmissions
 - ▶ **Slot-aggregation** - combining two or more slots to form a **multi-slot** - could be used to cater to use-cases that require exchange of **large-sized packets**

Lecture 9

5G-V2X Sidelink Modes

- ▶ 5G-NR V2X has defined two sidelink modes:
 - ▶ Sidelink mode 1: Mechanisms that allow **direct** vehicular **communications within gNodeB coverage**
 - ▶ Sidelink mode 2: Support **direct** vehicular **communications in the out-of-coverage scenario**



Lecture 9

5G-V2X Sub-Modes of Sidelink Mode 2

- ▶ New introduced sub-modes of sidelink mode 2:
 - ▶ **Mode 2 (a):** Each UE **autonomously** selects its resources
 - ▶ This mode is similar to C-V2X sidelink **mode 4**
 - ▶ **Mode 2 (b):** UEs **assist** other UEs in performing **resource selection**
 - ▶ Receiver UE, which can potentially **notify** the **transmitting** UE of its **preferred resources** using the PSFCH
 - ▶ **Mode 2 (c):** UEs use **pre-configured sidelink grants** to transmit their messages
 - ▶ This sub-mode will be facilitated through the design of two-dimensional time-frequency patterns
 - ▶ **Mode 2 (d):** UEs select resources for other UEs

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5G-V2X Sidelink Mode 2(a)

- ▶ Transmitting UE must select its resources in an **autonomous** fashion
- ▶ C-V2X sidelink mode 4 **resource reservation algorithm** leverages the periodicity and **fixed-size** assumption of basic safety **messages**

- ▶ **Enhancements** to the C-V2X sidelink mode 4 algorithm:
 - ▶ Flexible **duration of the sensing window** based on vehicular mobility
 - ▶ Elimination of **RSSI averaging procedure** might improved the performance of **long-term sensing**
- ▶ **Long-term** and **short-term** sensing can be configured so that UEs perform sensing and resource exclusion over the sensing window and select a transmission resource within the selection window
 - ▶ However, before transmitting, the UE must perform **short-term sensing** to detect the presence of **other signals** on its **selected resource**
 - Using e.g., **Listen Before Talk** protocol

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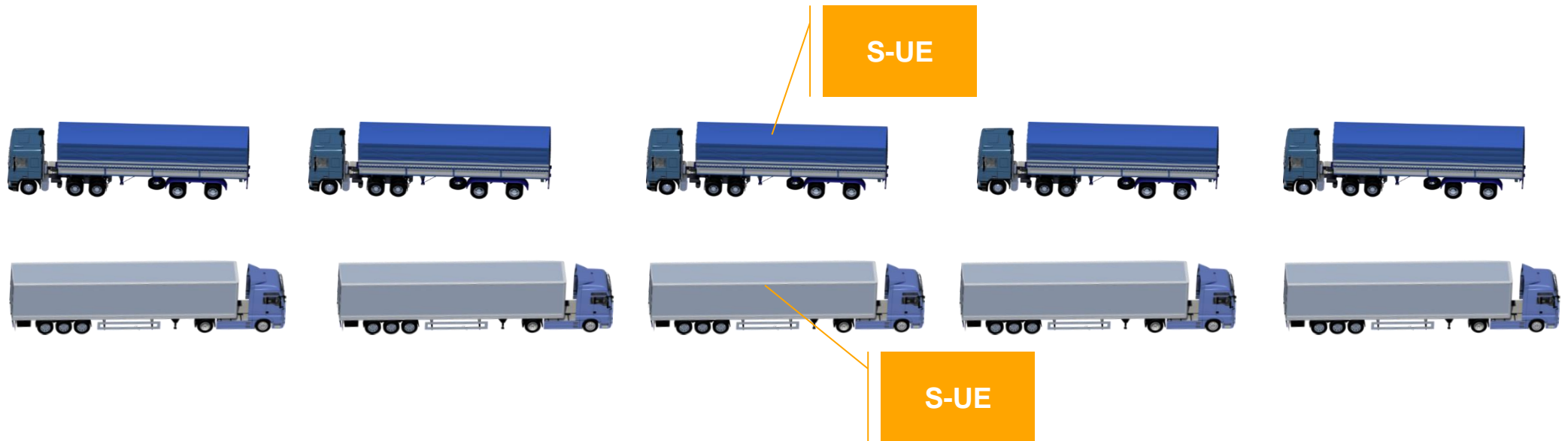
5G-V2X Sidelink Mode 2(b)

- ▶ UE performs **resource allocation** for a group of **UEs** in its vicinity
 - ▶ UE performing **resource allocation** is referred as **scheduling UE (S-UE)**
- ▶ Useful especially in **platooning applications** where vehicles move along the **same direction** with **small relative velocities**
- ▶ This mode can significantly **reduce the number of collisions** between group member as the S-UE can reserve the resources of UEs within its group
- ▶ **How to select the S-UE?**
 - ▶ **Geo-location based selection of S-UE:** Beneficial in platooning applications, where the vehicle **at the center of the platoon** is more likely to have an accurate estimate of radio environments of all vehicles in the platoon
 - ▶ **Pre-configuration based S-UE selection:** Vehicles with **additional hardware/processing capabilities** can take on the responsibility of resource allocation for surrounding vehicles

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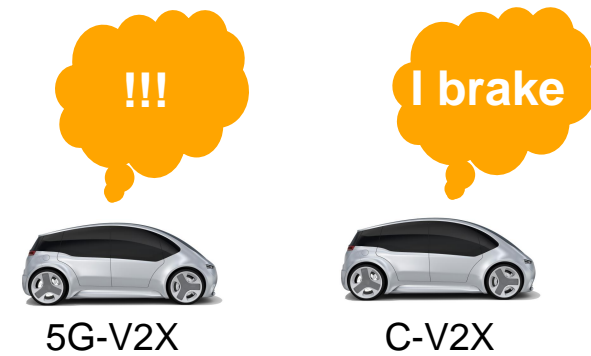
5G-V2X Sidelink Mode 2(b) - Challenges

- ▶ **Coexistence** of S-UE and other UEs using **mode 2 (a)**
- ▶ **Interference mitigation** between neighboring **UEs** that are assigned resources by different **S-UEs**
 - ▶ Platoons catch-up



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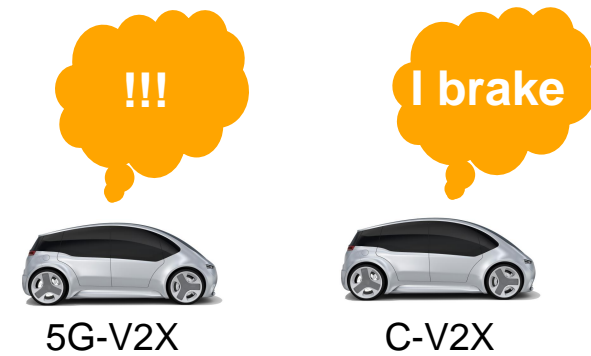
Coexistence of C-V2X and 5G-V2X (1/2)



- ▶ C-V2X device operating at **15 kHz** sub-carrier spacing, cannot decode messages transmitted using the **30** or **60 kHz** spacing
- ▶ Newer vehicles have to be equipped with modules of **both technologies C-V2X and 5G-V2X**
- ▶ Design of effective **coexistence mechanisms** is required in scenarios where C-V2X and 5G-V2X operate in **different channels**
 - ▶ **Frequency division multiplexing (FDM)**
 - ▶ (+) Transmissions can overlap in time → no need for tight time synchronization between the C-V2X and 5G-V2X modules
 - ▶ (-) Leakage due to out-of-band emissions from one radio terminal will impair the reception
 - ▶ Adjustment of the transmit power across the two technologies based on packet priorities

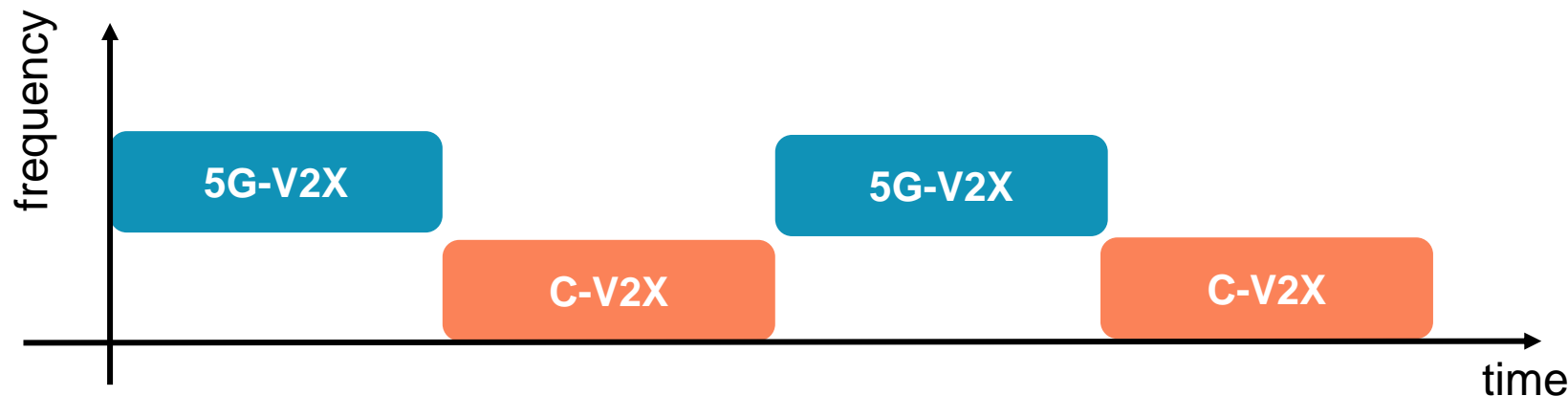
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Coexistence of C-V2X and 5G-V2X (2/2)



► Time division multiplexing (TDM)

- Transmissions on the two technologies occur in **different channels** and at **different time** instants
- Maximum permissible transmission power can be used by both technologies as **only one interface** transmits at **any given time**
- (+) No leakage across channels
- (-) Increased **delays** as for latency critical use-cases one interface may **be off**
- (-) severe restrictions on **time synchronization** between both technologies



Lecture 9

Spectrum Management Issues (1/3)

► Coexistence between C-V2X and ITS-G5/DSRC

► C-V2X and ITS-G5/DSRC are not compatible with each other

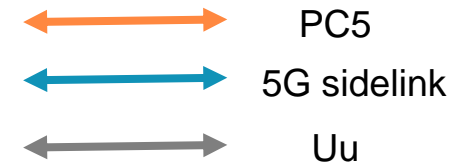
- Vehicles using a WiFi-based technology (ITS-G5/DSRC) will be **unable** to communicate with those using 5G-V2X/C-V2X

► **Potential Solution:** Within a given geographical region, **regulatory agencies** must permit only one **V2X technology** (either DSRC or C-V2X) to operate in a vehicle



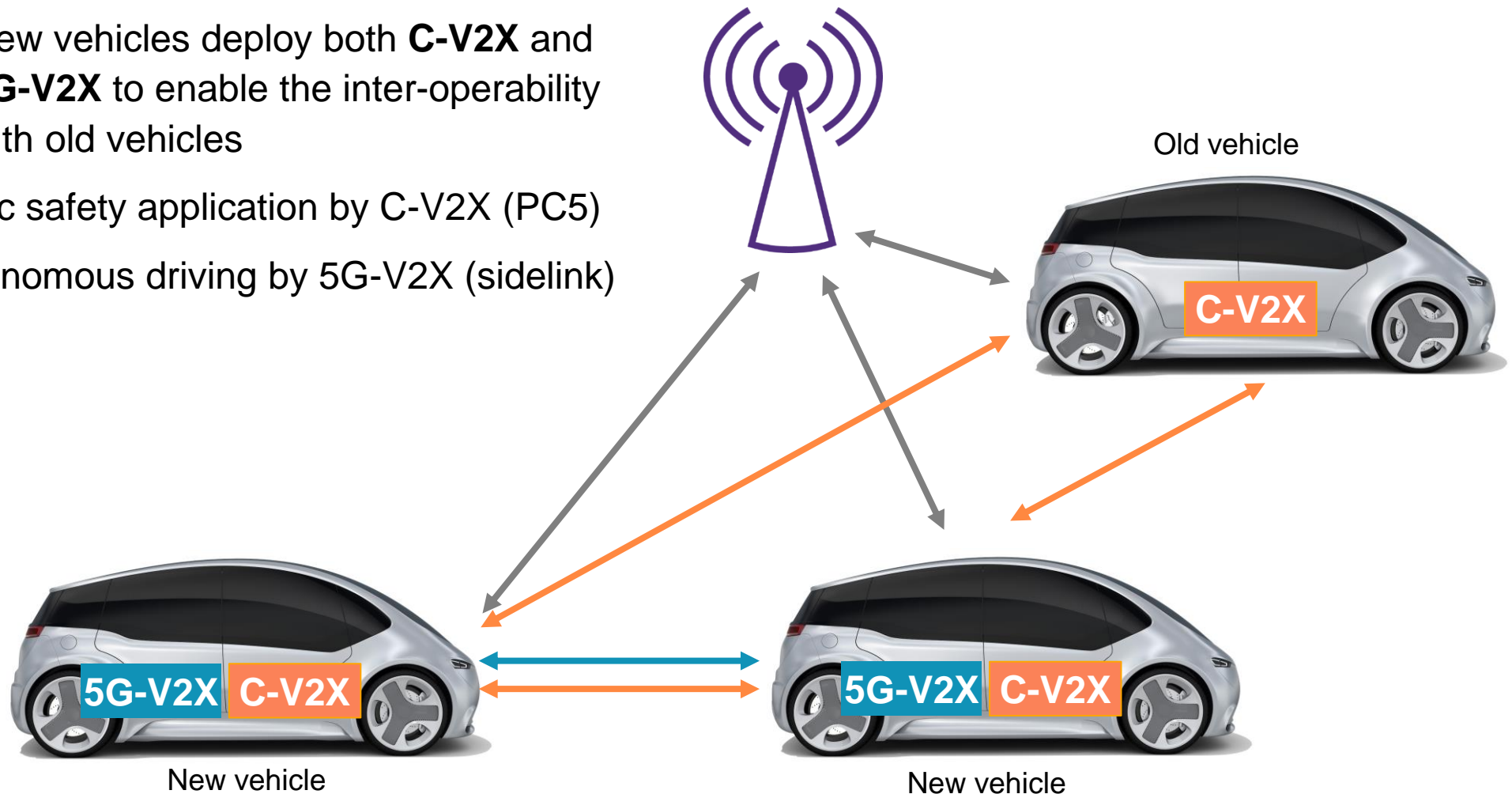
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Selection between C-V2X and 5G-V2X (1/2)



► Enable **inter-operability**

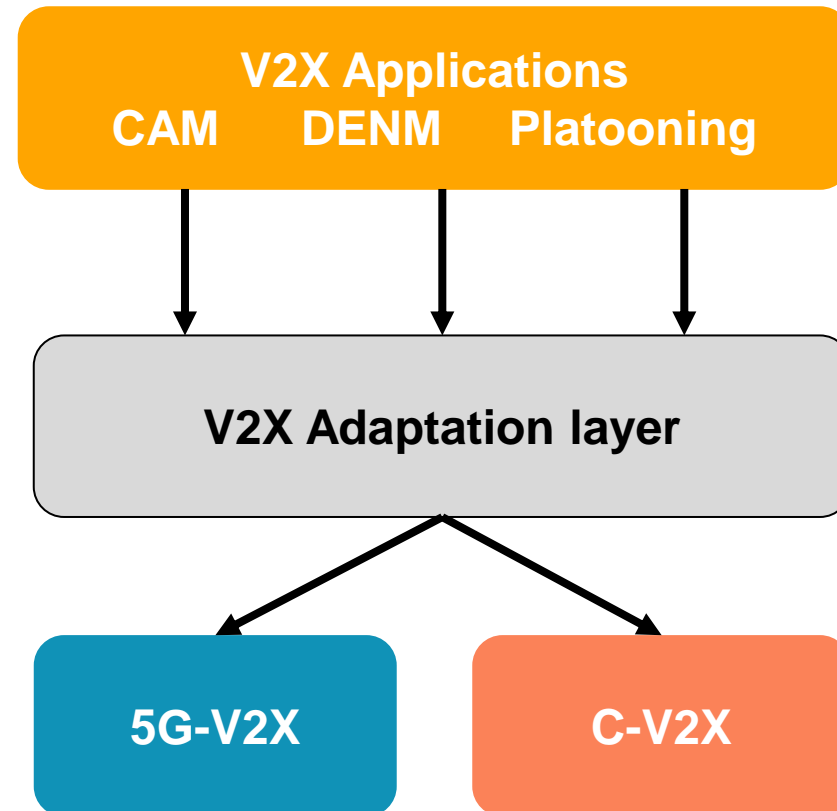
- New vehicles deploy both **C-V2X** and **5G-V2X** to enable the inter-operability with old vehicles
- Basic safety application by C-V2X (PC5)
- Autonomous driving by 5G-V2X (sidelink)



Lecture 9

Selection between C-V2X and 5G-V2X (2/2)

- ▶ Adaptation **cross-layer** required
 - ▶ Provide policies/criteria to UE to assist **radio technology selection**
 - ▶ V2X application type
 - ▶ QoS requirements



Lecture 9

Spectrum Management Issues (2/3)

► Coexistence with Wi-Fi

- 5.9 GHz band has been explored for Wi-Fi-like secondary operations
 - Because V2X applications demand **high reliability**, unlicensed Wi-Fi operations can be **permitted only** if they do not **cause interference** to the primary V2X technologies

► Potential solution for ITS-G5 and Wi-Fi

- Similarities in the MAC protocols of Wi-Fi and DSRC
- **Adaption of MAC protocol:** Increase of the Contention Window size and/or Inter-frame space of Wi-Fi so that the priority of Wi-Fi transmissions is **reduced**

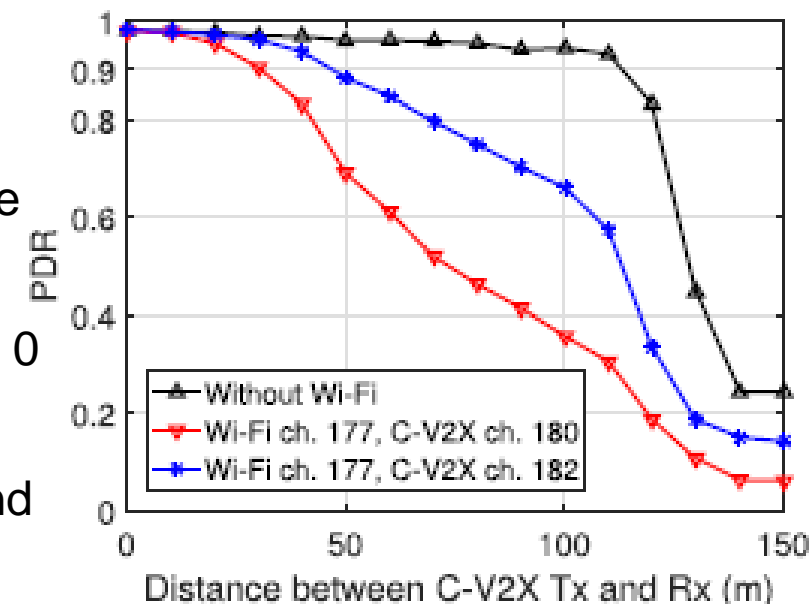
► Coexistence between **C-V2X** and **Wi-Fi** has not been well investigated

- C-V2X uses a considerably different MAC protocol from Wi-Fi

Lecture 9

Spectrum Management Issues (2/3)

- ▶ **Interference from adjacent band**
 - ▶ if a Wi-Fi device operating in the **adjacent channel** is located very close to the V2X receiver, the noise floor of that receiver will be elevated
 - ▶ It inevitably leads to a **loss** in its **performance of V2X**
- ▶ Communication **performance** depends on the **frequency separation** between Wi-Fi and the ITS channel
- ▶ **Packet delivery ratio (PDR)** of C-V2X against the distance between the C-V2X transmitter and receiver
- ▶ The frequency separation between Wi-Fi and C-V2X is 0 and 10MHz for channels 180 and 182, respectively
- ▶ **90% PDR** range is reduced from approx. 115 m to 45 m and 25m for channels 182 and 180, respectively



Lecture 9

5G-V2X as Support for fully automated Driving

- ▶ **Connected** and fully **automated** vehicles combined to
 - ▶ improve road traffic safety
 - ▶ enhance traffic flow with the support of the roadside infrastructure
 - ▶ lower environmental impact
- ▶ **5G-V2X** might create a **vehicle's collective perception** of the surrounding environment
 - ▶ Help making more **informed decisions**, based on exchanged **local views** and **planned maneuvers** from nearby **vehicles**
 - ▶ **Instead** of relying on **local awareness** built upon on-board sensors only
 - ▶ Camera, radar, LIDAR
 - ▶ From a **simple awareness** to a fully **collective perception**



Lecture 9

Qos Requirements of Advanced V2X Applications

- Advanced V2X use-cases improve road safety and assist in better traffic management and cater to the infotainment needs of passengers

Use case group	Max. latency [msec]	Payload size [Bytes]	Reliability [%]	Data rate [Mbps]	Min. Range [meters]
Vehicle platooning	10 - 500	50 - 6000	90 - 99.99	50 - 65	80 - 350
Advanced Driving	3 - 100	300 - 12000	90 - 99.999	10 - 50	360 - 500
Extended Sensors	3 - 100	1600	90 - 99.999	10 - 1000	50 - 1000
Remote driving	5	-	99.999	UL: 25 DL: 1	-



Lecture 9

High Density Platooning

- ▶ Platooning, or the operation of a group of vehicles in a closely linked manner such that the vehicles move like a train
 - ▶ By **reducing distance** between vehicles following can be achieved
 - Reduced overall **fuel consumption**
 - Reduced **number of needed drivers**
- ▶ To support the platooning use case, vehicles **need to share status information** such as speed, heading and **intentions** such as **braking, acceleration**



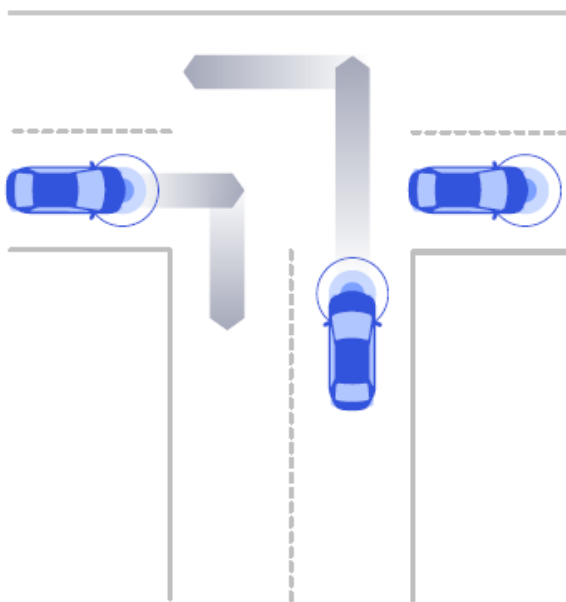
Level 2 for partial driving automation

In level 4 vehicles can operate in self-driving mode

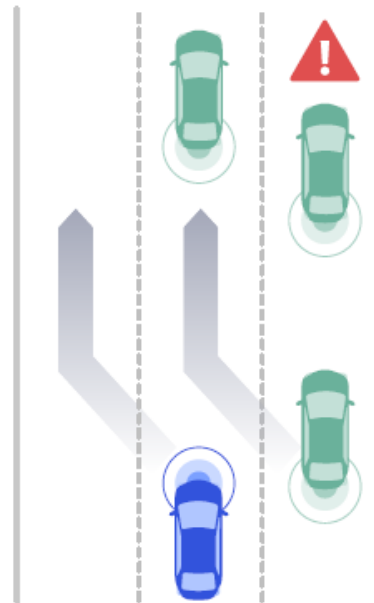
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Advanced Driving

- ▶ Advanced Driving enables **semi-automated** or **fully-automated driving**
- ▶ Each vehicle and/or RSU **shares** data obtained from **its local sensors** with vehicles in proximity
 - ▶ This allows vehicles to **coordinate** their **trajectories** or **maneuvers**
 - ▶ Each vehicle shares **its driving intention** with vehicles in proximity

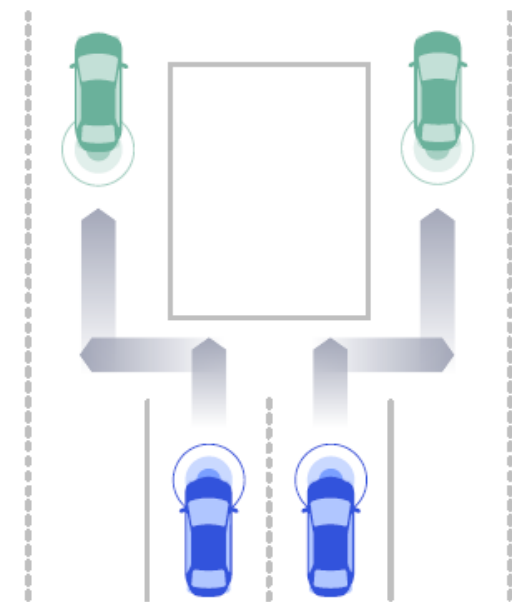


Efficient maneuvers



Advanced path planning

Sudden braking
and lane change
on a freeway



Coordinated driving

source: Qualcomm

Lecture 9

Remote Driving

- ▶ Remote driving enables a **remote driver** or a **V2X application** to operate a remote vehicle for those passengers who **cannot drive themselves** or a remote vehicle **located** in **dangerous** environments
 - ▶ Driving based on cloud computing can be used for a case where variation is limited and routes are predictable, such as public transportation
 - ▶ Access to cloud-based **backend service platform** is required
- ▶ Message exchange between a UE supporting V2X application and V2X application server for an absolute **speed of up to 250 km/h** shall be achievable
- ▶ Remote operator needs **HD video streamed** by the car from cameras located on the front, rear and side of the vehicle

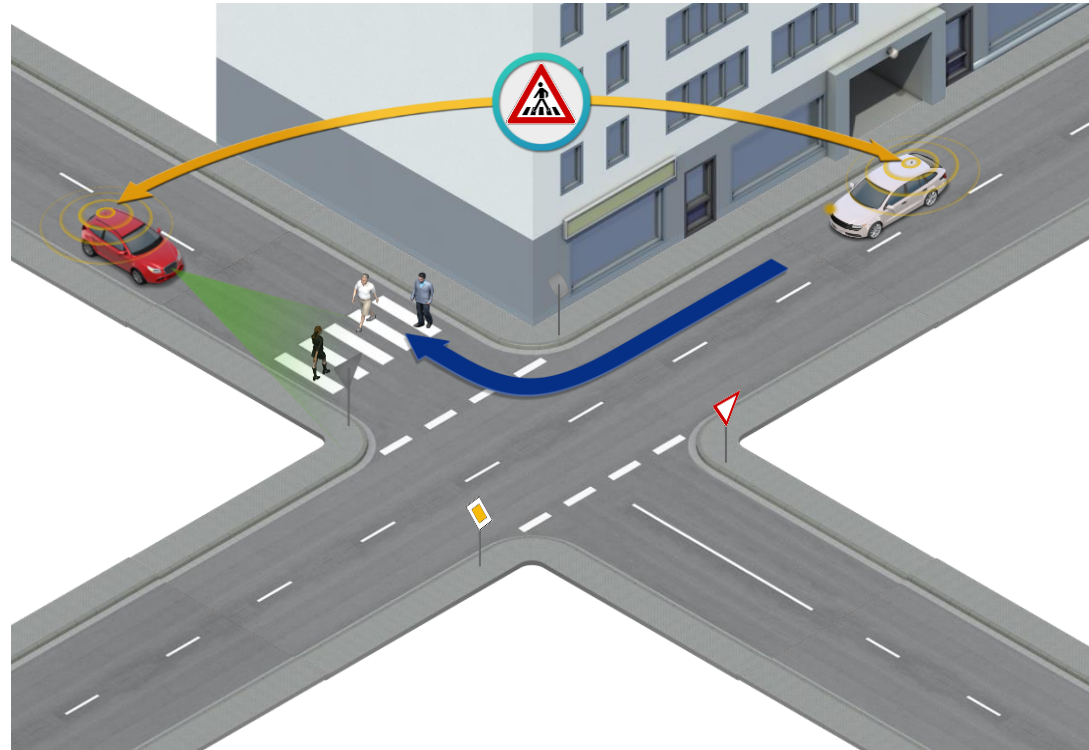


source: 5GAA

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Extended Sensors and Intention Sharing

- ▶ Extended Sensors enables the **exchange of raw or processed data** gathered through local sensors or live video data **among vehicles**, RSUs, devices of pedestrians and **V2X application servers**
- ▶ Vehicles can enhance the **perception of their environment** beyond what their own sensors can detect and have a more holistic view of the local situation
→ **Collective perception**
- ▶ Red vehicle's **local perception sensor** has a **line-of-sight** to pedestrians in a crosswalk
- ▶ Without collective perception, the ADAS applications of the white vehicle would not be aware of pedestrians until the vehicle's own sensors **perceive the object themselves**



Lecture 9

Challenges of connected and autonomous Driving

- ▶ Hard-to-meet **computing** and **communication demands** beyond current radio access technologies
 - ▶ Ultra-low latency **< 5 ms**
 - ▶ Ultra-high reliability near **100%** → intolerance to **packet losses**
 - ▶ High data rate in the order of **Gbps**

- ▶ Some future advanced V2X applications with stringent communication requirements
 - ▶ **Cooperative sensing and maneuvering**
 - ▶ **High-density platooning**
 - ▶ **Tele-operated driving**
 - ▶ **See-Through**
 - ▶ **Birds Eye View**



Lecture 9

Literature

- ▶ G. Naik et al.: “IEEE 802.11bd & 5G NR V2X: Evolution of Radio Access Technologies for V2X Communications”, 2019
- ▶ J. Choi et al.: “Millimeter Wave Vehicular Communication to Support Massive Automotive Sensing”, 2016
- ▶ ITU-R M.2083-0: “IMT Vision – Framework and overall objectives of the future development of IMT for 2020 and beyond”, 2015
- ▶ Maxime Flament: “Path towards 5G for the automotive sector”, 5GAA, 2018

