RTOS-HW1

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[PART I] EDF Scheduler Implementation [70%]

The correctness of schedule results of examples. Note the testing task set might not be the same as the given example task set. (20%)

Example Task Set $1 = \{\tau_1(1, 0, 4, 11), \tau_2(2, 0, 3, 9)\}$:

| Tick | Event | CurrentTask ID | NextTask ID | ResponseTime | #of ContextSwitch | PreemptionTime | OSTimeDly |
|------|------------|----------------|--------------|--------------|-------------------|----------------|-----------|
| 3 | Completion | task(2)(0) | task(1)(0) | | | | 6 |
| 7 | Completion | task(1)(0) | task(63) | | 2 | | 4 |
| 9 | Preemption | task(63) | task(2)(1) | | | | |
| 12 | Completion | task(2)(1) | task(1)(1) | | 2 | | 6 |
| 16 | Completion | task(1)(1) | task(63) | 5 | 2 | | 6 |
| 18 | Preemption | task(63) | task(2)(2) | | | | |
| 21 | Completion | task(2)(2) | task(63) | | 2 | | 6 |
| 22 | Preemption | task(63) | task(1)(2) | | | | |
| 26 | Completion | task(1)(2) | task(63) | 4 | 2 | 0 | 7 |
| 27 | Preemption | task(63) | task(2)(3) | | | | |
| 30 | Completion | task(2)(3) | task(63) | 3 | 2 | 0 | 6 |
| 33 | Preemption | task(63) | task(1)(3) | | | | |
| 37 | Completion | task(1)(3) | task(2)(4) | 4 | 2 | 0 | 7 |
| 40 | Completion | task(2)(4) | task(63) | 4 | 2 | | 5 |

Example Task Set $2 = \{\tau_1(1, 0, 2, 6), \tau_2(2, 0, 3, 8)\}$:

| Tick | Event | CurrentTask ID | NextTask ID | ResponseTime | #of ContextSwitch | PreemptionTime | OSTimeDly |
|------|------------|----------------|--------------|--------------|-------------------|----------------|-----------|
| 2 | Completion | task(1)(0) | task(2)(0) | 2 | | | 4 |
| 5 | Completion | task(2)(0) | task(63) | 5 | 2 | | |
| 6 | Preemption | task(63) | task(1)(1) | | | | |
| 8 | Completion | task(1)(1) | task(2)(1) | 2 | 2 | | 4 |
| 11 | Completion | task(2)(1) | task(63) | | 2 | | 5 |
| 12 | Preemption | task(63) | task(1)(2) | | | | |
| 14 | Completion | task(1)(2) | task(63) | 2 | 2 | | 4 |
| 16 | Preemption | task(63) | task(2)(2) | | | | |
| 18 | Preemption | task(2)(2) | task(1)(3) | | | | |
| 20 | Completion | task(1)(3) | task(2)(2) | 2 | 2 | | 4 |
| 21 | Completion | task(2)(2) | task(63) | 5 | 4 | 2 | |
| 24 | Preemption | task(63) | task(1)(4) | | | | |
| 26 | Completion | task(1)(4) | task(2)(3) | 2 | 2 | | 4 |
| 29 | Completion | task(2)(3) | task(63) | 5 | 2 | | |
| 30 | Preemption | task(63) | task(1)(5) | | | | |
| 32 | Completion | task(1)(5) | task(2)(4) | 2 3 | 2 | | 4 |
| 35 | Completion | task(2)(4) | task(63) | | 2 | | 5 |
| 36 | Preemption | task(63) | task(1)(6) | | | | |
| 38 | Completion | task(1)(6) | task(63) | 2 | 2 | | 4 |
| 40 | Preemption | task(63) | task(2)(5) | | | | |

Example Task Set $3 = \{\tau_1(1, 0, 2, 5), \tau_2(2, 0, 4, 8), \tau_3(3, 1, 2, 6)\}$:

| Tick | Event | CurrentTask ID | NextTask ID | ResponseTime | #of ContextSwitch | PreemptionTime | OSTimeDly | • |
|------|--------------|----------------|--------------|--------------|-------------------|----------------|-----------|---|
| 2 | Completion | task(1)(0) | task(3)(0) | 2 | | | | |
| 4 | Completion | task(3)(0) | task(2)(0) | | 2 | | | |
| 8 | Completion | task(2)(0) | task(1)(1) | | 2 | | | |
| 10 | Completion | task(1)(1) | task(3)(1) | 5 | 2 | | | |
| 12 | Completion | task(3)(1) | task(1)(2) | 5 | 2 | | | |
| 14 | Completion | task(1)(2) | task(2)(1) | 4 | 2 | | | |
| 16 | MissDeadline | task(2)(1) | | | | | | ı |

■ Implement and describe how to handle the missing deadline situation under EDF. (10%)

此表格內容在下一頁。

在 OS_SchedNew() 裡面加入判斷式,若系統時間大於等於 deadline 的話,將會被分成兩個情況,一種是現在的任務工作剛好做完,那麼就讓系統在 OSIntExit() 裡暫時不要更新最高優先權,避免任務被其他人搶佔,另外一種情況則是任務還沒做完的情況,那麼就直接宣告 MissDeadline,將會直接關閉系統。

A report that describes your implementation (please attach the screenshot of the code and MARK the modified part). (40%)

```
ptch = OSTCRList:
                                                 /* Point at first TCB in TCB list
hptcb = OSTCBPrioTb1[0];
                    /* Go through all TCBs in TCB list
while (ptcb != 0) {
   OS_ENTER_CRITICAL();
    int x = ptcb->OSTCBId;
   if (ptcb->OSTCBPrio == 63) {
       ptcb->OSTCBDeadLine = 10000;
   if ((ptcb->OSTCBStat & OS_STAT_SUSPEND) == OS_STAT_RDY && ptcb->OSTCBDly == 0) {
          (ptcb->OSTCBDly == 0 && hptcb->OSTCBDly != 0 || ptcb->OSTCBStat != OS_STAT_RDY) {
       else if (ptcb->OSTCBDeadLine <= hptcb->OSTCBDeadLine && ptcb->OSTCBEvecutionTime) {
          if (ptcb->OSTCBDeadLine == hptcb->OSTCBDeadLine && ptcb->OSTCBId < hptcb->OSTCBId)
              hptcb = ptcb:
           else if (ptcb->OSTCBDeadLine < hptcb->OSTCBDeadLine)
              hptcb = ptcb:
       else if (OSTimeGet() == hptcb->OSTCBDeadLine && ptcb->OSTCBDeadLine < hptcb->OSTCBDeadLine + hptcb->OSTCBPe
           hptcb = ptcb;
   ptcb = ptcb->OSTCBNext;
                                                /* Point at next TCB in TCB list
   OS_EXIT_CRITICAL();
```

EDF 的概念是越接近 Deadline 的 Task 優先權越大,因此在 OS_SchedNew() 裡面更改演算法,並將 Deadline 最小的設置為最高優先權。

首先進入 TCBList 中,比較當前 task 與目前最高優先權的 task,要注意的是,必須將 idle task 的 Deadline 設為最長(綠色部分),接下來是設定最高優先權的部分(橘色方框),比較的順序為:

1.若當前 task 的 delay = 0 而當前最高 delay != 0 ,則把當前最高更新為

當前 task 。

- 2.若當前的任務 Deadline 短於目前最高的 deadline,且當前任務尚未完成,則更新最高優先權任務,需注意的是,當任務的 Deadline 相同時, ID 較靠前的 Task 較高。
- 3. 若最高優先權的任務已經到 Deadline Time,若當前的任務 Deadline < 最高優先權的下一個 Deadline ,則更新最高優先權。

[PART II] CUS Scheduler Implementation [30%]

The correctness of schedule results of examples. Note the testing task set might not be the same as the given example task set. (15%)

Periodic Task Set = $\{\tau_1 (1, 0, 2, 8), \tau_2 (2, 0, 3, 10), \tau_3 (3, 0, 4, 15), \tau_4_ServerSize (4, 25\%)\}$ Aperiodic Jobs Set = $\{j_0 (0, 12, 3, 26), j_1 (1, 14, 2, 34)\}$

```
        Fick
        Event
        CurrentTask ID
        NextTask ID
        ResponseTime
        #of ContextSwitch
        PreemptionTime
        OSTimeDly

        2
        Completion
        task(1)(0)
        task(2)(0)
        2
        1
        0
        6

        5
        Completion
        task(2)(0)
        task(3)(0)
        5
        2
        0
        5

        9
        Completion
        task(3)(0)
        task(1)(1)
        9
        2
        0
        6

        11
        Completion
        task(3)(0)
        task(2)(1)
        3
        2
        0
        5

        12
        Aperiodic job(0)
        arrives and sets CUS server's deadline as 24.
        4
        Aperiodic job(1)
        arrives and sets CUS server's deadline as 24.

        14
        Aperiodic job(1)
        arrives and sets CUS server's deadline as 24.
        4
        2
        0
        6

        16
        Preemption
        task(4)(0)
        task(4)(0)
        4
        2
        0
        6

        16
        Preemption
        task(4)(1)
        task(3)(1)
        7
        4
        2
        N/A

        18
        Completion
        task(4)(1)
        task(2)(2)
        1
```

■ A report that describes your implementation (please attach the screenshot of the code and MARK the modified part). (15%)

```
if (TaskParameter[j].TaskExecutionTime = 0) {
    TaskParameter[j].CusUti = TaskParameter[j].TaskArriveTime;
    TaskParameter[j].TaskArriveTime = 0;
    cus++;
}

A Z 遠野 CUS 好 答料 ,在 InputFile(),故 在特別 加 上 判斷 ,若 當 份 任 發
```

為了讀取 CUS 的資料,在 InputFile() 內有特別加上判斷,若當前的任務執行時間是 0 的話,並記錄 CUS 的 seversize 到 CusUti。

```
void AInputFile() {
    errno_t err;
    if ((err = fopen_s(&fp, AINPUT_FILE_NAME, "r")) = 0) { ... }
    else { ... }

    char* ptr;
    char* pTmp = NULL;
    int TaskInfo[INFO], i = 0, j = 0;
    ATASK_NUMBER = 0;
    while (!feof(fp)) { ... }

    fclose(fp);
}
```

為了讀取非週期任務的資料,有另外寫一個 AInputFile,內容只是讀的檔案不同,並把原本的 TaskParameter 改為 ATaskParameter,以區分一般任務和非週期任務。

```
OSTaskCreateExt(CUS,
    &TaskParameter[TASK_NUMBER-1],
    &&Task_STK[TASK_NUMBER-1][TASK_STACKSIZE - 1],
    TASK_NUMBER-1,
    TaskParameter[TASK_NUMBER-1].TaskID,
    &Task_STK[TASK_NUMBER-1][0],
    TASK_STACKSIZE,
    &TaskParameter[TASK_NUMBER-1],
    (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR),
    TaskParameter[TASK_NUMBER-1].TaskExecutionTime,
    TaskParameter[TASK_NUMBER-1].TaskArriveTime,
    TaskParameter[TASK_NUMBER-1].TaskPeriodic,
    TaskParameter[TASK_NUMBER-1].CusUti);
```

```
void CUS(void* p_arg) {
   while (1)
       while (1) {
           if (OSTCBCur->OSTCBStartTime = 0 && OSTCBCur->OSTCBWorkTime = 0) {
               OSTCBCur->OSTCBStartTime = OSTimeGet();
           if (OSTimeGet() = OSTCBCur->OSTCBDeadLine) {
               OS_Sched();
           if (OSTCBCur->OSTCBWorkTime = OSTCBCur->OSTCBExecutionTime) {
               OSTCBCur->OSTCBStat = OS_STAT_SUSPEND;
               printf("%2d Aperiodic job(%d) is finished.\n",OSTimeGet(), completeNumber);
               if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) = 0)
                   fprintf(Output_fp, "%2d Aperiodic job(%d) is finished.\n", OSTimeGet(), completeNumber);
                  fclose(Output_fp);
              completeNumber++;
               OS_Sched();
               break;
```

在 main() 裡面 CUS task 的創立是分開的,目的只是要將 task 裡面做的事情分開,主要是 CUS 做完後要把 Task 的狀態設為 SUSPEND,而且要 printf 其他訊息比較方便,當任務完成時,紀錄 cus 完成件數的 completeNumber 也會 +1。

```
2281 if(CusUti!=0)
2282 ptcb->OSTCBStat = OS_STAT_SUSPEND;
```

在 OS_TCBInit() 裡面,若當前任務是 Cus,那麼先將任務狀態設為暫停以免被排程。

此表格內容在下一頁。

```
void OS_Cusevent (void) {
   OS ENTER CRITICAL();
   OS TCB* ptcb;
   ptcb = OSTCBPrioTb1[TASK_NUMBER-1];
   for (int n = completeNumber; n < ATASK_NUMBER; n++) {
       if (OSTimeGet() = ATaskParameter[n].TaskArriveTime) {
           printf("%2d
                        Aperiodic job(%d) arrives",OSTimeGet(),n);
           if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) = 0)
               fprintf(Output_fp, "%2d Aperiodic job(%d) arrives", OSTimeGet(
               fclose(Output_fp);
           if (ptcb->OSTCBStat != OS_STAT_SUSPEND) {
               printf(" . Do nothing.\n");
               if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) = 0)
                   fprintf(Output_fp, " . Do nothing.\n");
                   fclose(Output_fp);
```

OS_Cusevent()是自己創的 function,它的功能是在檢查是否有非週期任務抵達,並且 printf 訊息,這邊把 n 設為 completeNumber,因此做完任務的不會被考慮,以下兩個表格都是 OS_Cusevent()的內容。

```
if (OSTimeGet() >= ATaskParameter[n].TaskArriveTime && ptcb->OSTCBStat == OS_STAT_SUSPEND) {
   ptcb->OSTCBExecutionTime = ATaskParameter[n].TaskExecutionTime;
   if (ptcb->OSTCBDeadLine == 0 ){
      ptcb->OSTCBDeadLine = OSTimeGet() + ptcb->OSTCBExecutionTime / (ptcb->OSTCBCusUti / 1)
      printf(" and sets CUS server's deadline as %2d.\n", ptcb->OSTCBDeadLine);
      if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) == 0)
      {
            fprintf(Output_fp, " and sets CUS server's deadline as %2d.\n", ptcb->OSTCBDeadLine);
            }
            ptcb->OSTCBStat = OS_STAT_RDY;
      }
}
```

接著判斷非週期任務是否抵達,且現在 cus 的狀態是否為暫停,這可以避免其他非週期的任務覆蓋當前任務,接著依照講義上的公式設判斷式: 1.若當前 deadline 為 0 ,則把 cus 的 deadline 設為當前時間加上執行時間除於利用率,且將 cus 的狀態改為 ready。

- 2.若當前的時間大於目前 cus 的 deadline,而且 cus 狀態為 suspend 時 a.先判斷新的非週期任務在這個時間點是否已經抵達,若已經抵達的話 cus 的 deadline 設為原本的 deadline 加上執行時間除於利用率。 b.若不符合上述條件,代表新的非週期任務尚未抵達,則只需要在抵達 時更新 deadline,更新時 cus 的 deadline 設為當前時間加上執行時間除於利用率。
- OS Cusevent()的內容到這邊結束。

```
static void OS_SchedNew (void)
#if OS_LOWEST_PRIO <= 63u
                                               /* See if we support up to 64 tasks
   INTSU y;
   OS_Cusevent();
if (OSTCBCur->OSTCBCusUti != 0) {
   if OSTimeGet() >= ATaskParameter[completeNumber].TaskPeriodid) {
       if (OSTCBCur->OSTCBWorkTime == OSTCBCur->OSTCBExecutionTime) {
          exitflag = 1:
       else {
          printf("%2d MissDeadline ", OSTimeGet());
          printf("task(%2d)(%2d) -----\n", OSTCBCur->OSTCBId, OSTCBCur->OSTCBJobNum);
          if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) == 0)
              fprintf(Output_fp, "%2d MissDeadline ", OSTimeGet());
              fprintf(Output_fp, "task(%2d)(%2d) ------\n", OSTCBCur->OSTCBId, OSTCBCur->OSTCB
              fclose(Output_fp);
          exit(0);
```

最後,把 OS_Cusevent()放入 OS_SchedNew()裡面,讓每次要更新優先權時都先去 check 非週期任務的狀態,然後,因為非週期任務除了系統 Deadline 以外還有自己的 Deadline,所以在判斷 Deadline 這裡有特別加上去。(非週期任務的 deadline 是存在 TaskPeriodic 裡面)