

Nomenclature

Table of variables in Section 3

α	Biot constant
ϵ	total strain
ϵ^c	creep strain
ϵ^p	plastic strain
ϵ^T	thermal strain
ρ	fluid density
σ	Cauchy (total) stress
$\tilde{\sigma}$	effective stress
c_0	specific storage coefficient
\mathbf{D}	fourth-order elasticity tensor
\mathbf{f}	body force
\mathbf{g}	gravity vector
\mathbf{I}	second-order unity tensor
\mathbf{K}	rock permeability tensor divided by fluid viscosity
\mathbf{n}	outward unit normal vector
p	fluid pressure
q	source or sink term
\mathbf{u}	displacement vector
\mathbf{z}	Darcy velocity

Table of variables in Section 7.1

μ_α	viscosity of phase α
ξ_i^α	molar fraction of component i in phase α
ρ_α	density of phase α
ϕ	porosity at current configuration
ϕ_0	reference porosity
Φ_i^α	fugacity coefficient of component i in phase α
c_r	rock compressibility constant
f_i^α	fugacity of component i in phase α
\mathbf{g}	gravity vector
$k_{r\alpha}$	relative permeability of phase α
\mathbf{K}	absolute permeability tensor
n_c	number of hydrocarbon components
N_i	molar concentration of component i
p	reference phase pressure
p_0	reference pressure
p_α	pressure of phase α
$p_{c\alpha}$	capillary pressure of phase α
q_i	source or sink term for component i
S_α	saturation of phase α
T	reservoir temperature
\mathbf{u}_α	Darcy velocity of phase α

Table of variables in Section 7.2

ϕ^*	effective porosity at current configuration
M	Biot's modulus
\mathbf{u}_0	initial displacement at reference pressure p_0

Table of variables in Section 7.3

α, γ, A, e, R	constants related to the shapes of the shear envelope and cap portion
$\tilde{\alpha}$	$[\Delta^*]_n / [\Delta]_n$
β	friction angle
Γ	cohesion
$[\Delta]_n$	normal displacement jump at which normal traction reaches maximum
$[\Delta]_t$	tangential displacement jump at which tangential traction reaches maximum
$[\Delta]^*$	$[\Delta^*]_n = [u]_n _{t_n=0}$
ϵ^p	plastic strain
λ	nonnegative consistency parameter
$\boldsymbol{\sigma}$	Cauchy (total) stress
σ_0	material shear-related strength
$\tilde{\boldsymbol{\sigma}}$	effective stress
$\boldsymbol{\tau}$	shear stress
Φ	interfacial potential
Ψ	ratio of tri-axial extension strength to compression strength
Ψ_n	$\Psi_n = e\sigma_{\max}[\Delta]_n$
Ψ_t	$\Psi_t = \sqrt{e/2}\tau_{\max}[\Delta]_t$
F	flow potential
H	Heaviside function
I_1	first invariant of effective stress tensor
II	fourth-order identity tensor
J_2	second invariant of effective stress tensor
J_3	third invariant of effective stress tensor
K_0	intersection coordinate of the shear and cap portions
\mathbf{n}	outward unit norm vector
q	Ψ_n / Ψ_t
\mathbf{t}	traction at prescribed boundary
t_n	normal traction
t_t	tangential traction
$[\mathbf{u}]$	displacement jump across interface
$[u]_n$	$[u]_n = [\mathbf{u}] \cdot \mathbf{n}$
$[u]_t$	$[u]_t = \ (II - \mathbf{n} \otimes \mathbf{n})[\mathbf{u}]\ _2$
x	$x = [u]_n / [\Delta]_n$
X_0	material compaction strength
γ	$\gamma = [u]_t / [\Delta]_t$
Y	material yielding function
Y_s	shear envelop yielding function