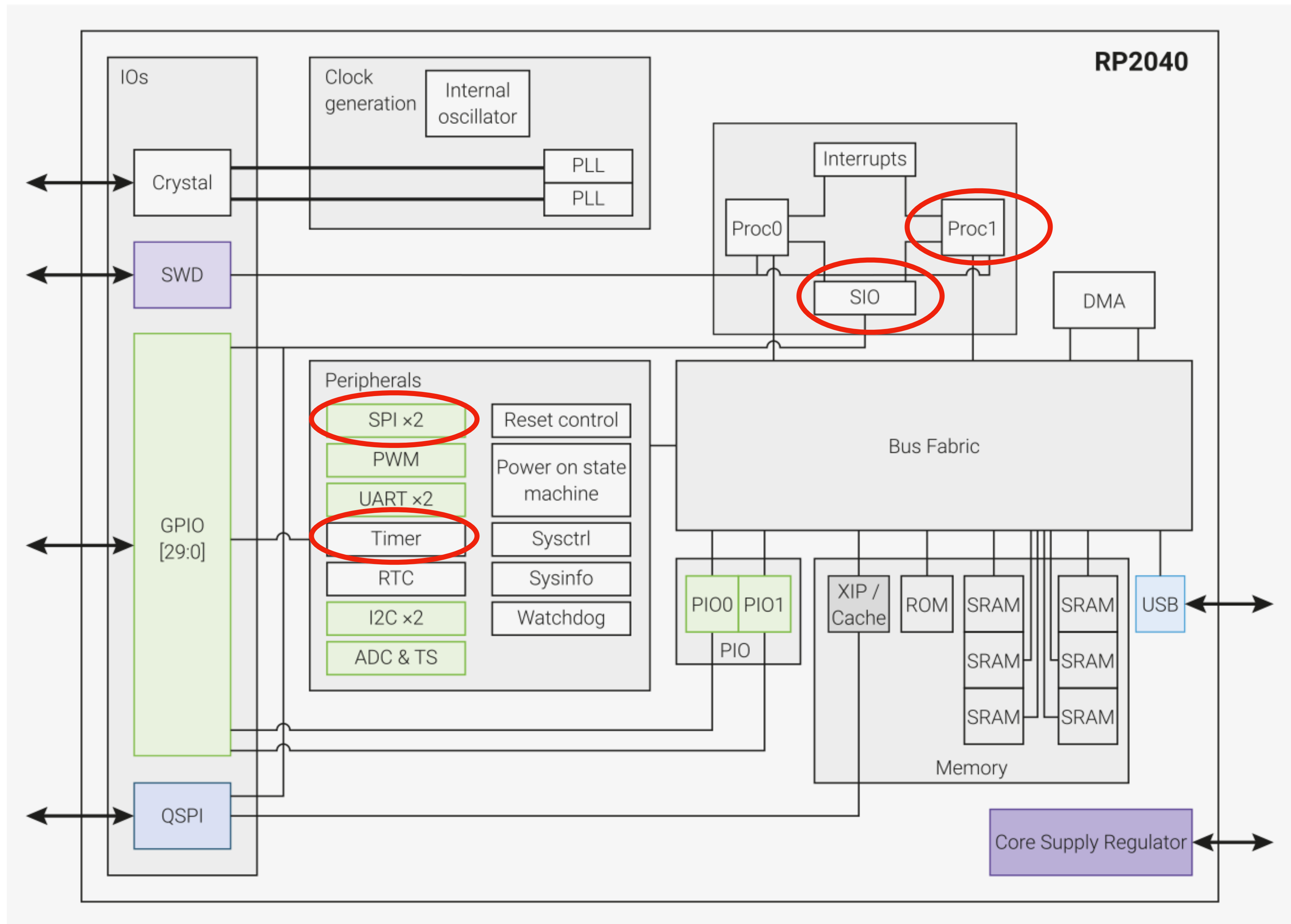


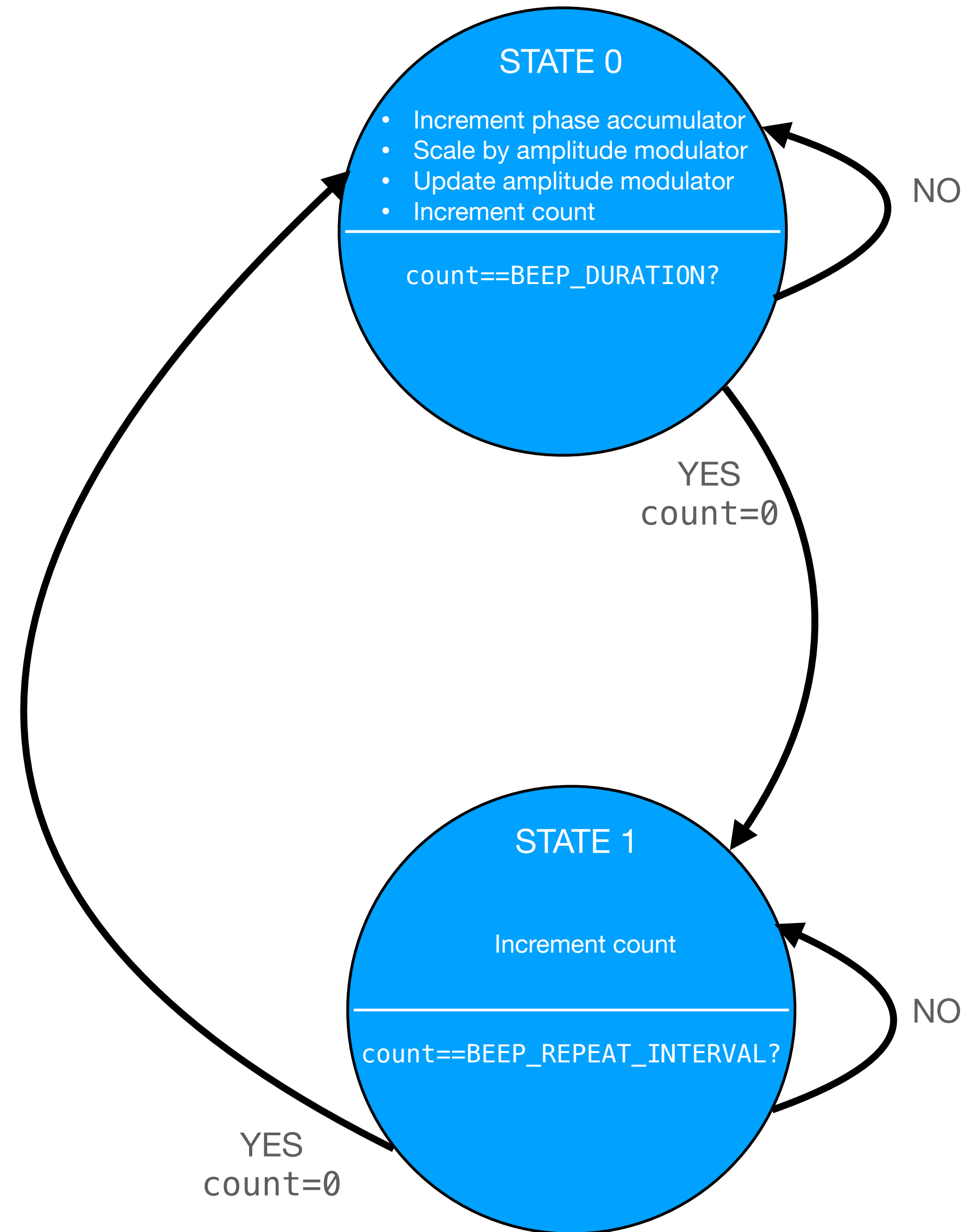
# Raspberry Pi Pico (RP2040)

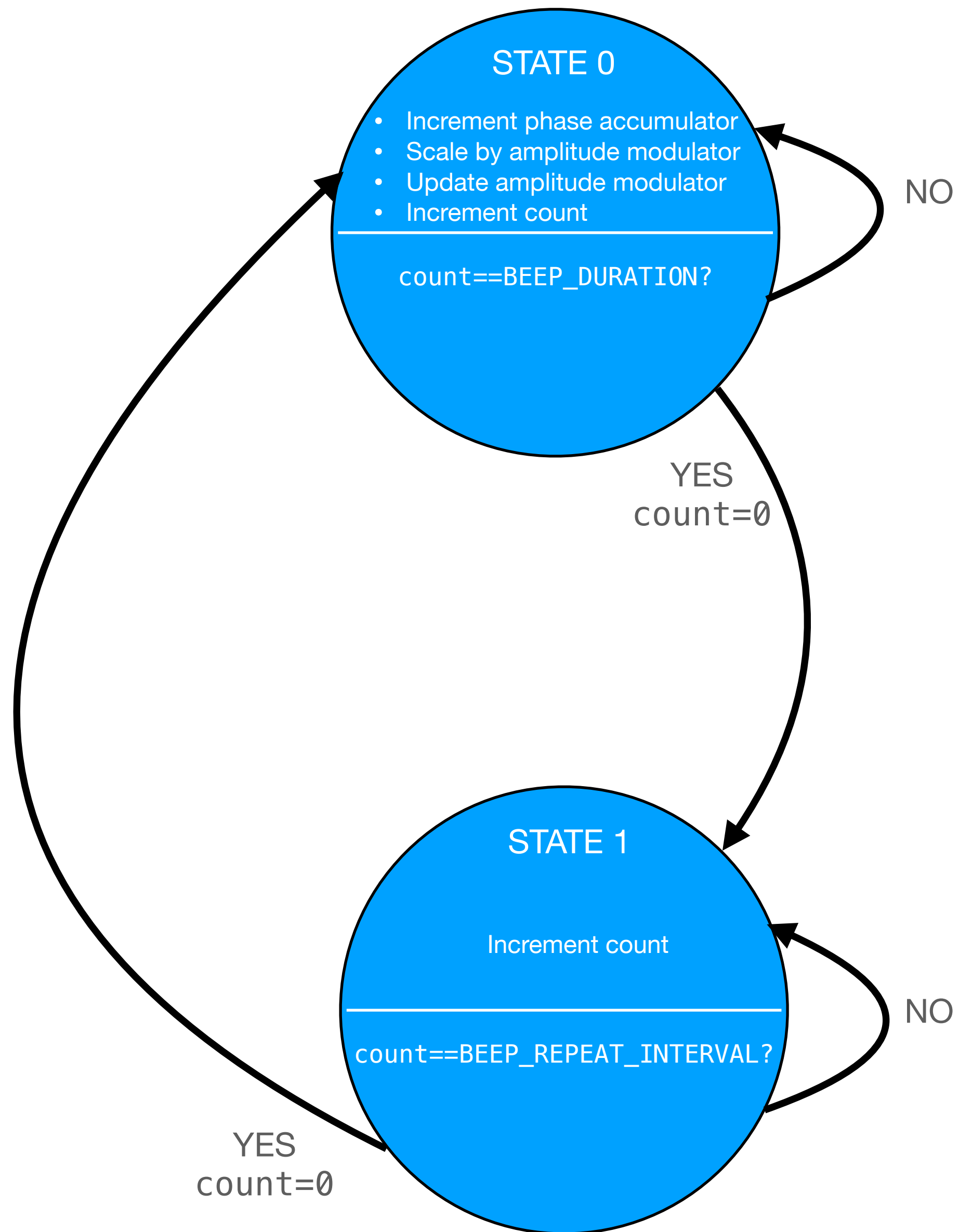
## **Lecture 5:** Multicore and Protothreads



# Today's objectives:

- Multicore
- Protothreads





## How will you augment this?

- **3 states:** chirp, syllable pause, chirp pause
- Both syllable pause and chirp pause always transition to chirp
- chirp transitions to one or the other based on the number of syllables it has already produced



# Protothreads

a lightweight, stackless threading library created by Adam Dunkels

# Threading libraries

A non-threaded microcontroller program generally has the following structure:

- Includes
- Global variable declarations and macros
- ISR's
- (Maybe) some helper functions
- Main - configures hardware peripherals, then repeatedly executes a set of instructions

# Threading libraries

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- Main - configures hardware peripherals, then repeatedly executes a set of instructions

A *threaded* microcontroller program generally has the following structure:

- Includes
- Global variable declarations and macros
- ISR's
- (Maybe) some helper functions
- Threads - a collection of *separate* execution environments
- Main - configures hardware peripherals, and adds threads to the scheduler, which context switches among threads



# When are threading libraries nice?

Suppose that you are writing a complicated concurrent program, like in this class.

In such a program, you want for certain pieces of code to only execute when certain conditions are met (e.g. a user has entered a value, a certain amount of time has passed, a variable has assumed some value, etc.).

You could accomplish this with a state machine, but those can grow cumbersome.

A threading library makes your code more modular, and makes it easier to add conditional code to your application.

# Protothreads

- Non-preemptive
- Stackless
- Based on C macros that utilize *Duff's Device*

To the code!