Module 4 Quiz

TOTAL POINTS 8

| 1. | What is the name of the Python package used to control the Raspberry Pi camera module? | 1 point |
|----|--|---------|
| | picameracamerapicamrpicamera | |
| 2. | What function in the camera library is used to take a picture? | 1 point |
| | o capture() | |
| | photo() | |
| | picture() | |
| | snap() | |
| 3. | What is a "duty cycle"? | 1 point |
| | The duration of the high pulse of a square wave | |
| | The fraction of time a square wave is high | |
| | The frequency of a square wave | |
| | The period of a square wave | |

| | It is used to control the Raspberry Pi camera module | |
|----|---|---------|
| | It can be used to read data from camera sensors | |
| | It can be used to mimic an analog signal | |
| | It is commonly used to transmit video data | |
| | | |
| 5. | How many input wires does a servo have? | 1 point |
| | | |
| | O 2 | |
| | 3 | |
| | | |
| | <u> </u> | |
| | | |
| 6. | Why is it common to use an external power supply to drive a servo? | 1 point |
| | | |
| | AC power is needed to drive a servo | |
| | A servo needs more voltage than a microcontroller can provide | |
| | A servo needs more current than a microcontroller can provide | |
| | A servo requires power in the form of a square wave | |
| | | |
| 7. | The CSI camera interface of the Raspberry Pi needs to be activated before using the | 1 point |
| | camera module. | |
| | | |
| | True | |
| | False | |

Why is pulse width modulation useful?

| 8. The speed of a servo motor is easily controlled. | 1 point |
|---|---------|
| | |
| True | |
| (False) | |

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