

Computational Problems

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Lecture 3

1 Introduction

This article will cover the computational problems involved in the Lattices. We will look at the Shortest Vector Problem in detail and a way to solve it computationally. In the first part, we will define the problems, and subsequently, we will look at the way the mechanism to solve them evolved.

2 Exact Computational Problems

2.1 Shortest Vector problem(SVP)

Input: Basis of lattice B

Output: $v \in \mathcal{L}$ such that

$$||v|| = \lambda_1$$

2.1.1 Optimisation Version of SVP

Input: Basis of lattice B

Output: $\lambda_1(\mathcal{L}(B))$

2.1.2 Decision Version of SVP

Input: Basis of lattice B and $d \in \mathbb{R}$

Output: Yes if $\lambda_1 \leq d$ else No

2.2 Closest vector Problem(CVP)

Input: Basis of lattice B and a target vector $t \in \mathbb{R}^n$ in the ambient space.

Output: $v \in \mathcal{L}$ such that

$$v = \min_{u \in \mathcal{L}} ||u - t||$$

2.3 Shortest Integer vector Problem(SIVP)

Input: Basis of lattice B

Output: $||v_1|| \leq ||v_2|| \leq \dots \leq ||v_d|| \leq \lambda_d$

3 Approximation Computational Problems

The γ -approximate shortest vector problem, where $\gamma = \gamma(n) \geq 1$ is a function of dimension n . It has the following variants

3.1 Decision(GapSVP $_{\gamma}$)

Input: Basis of lattice B and $d \in \mathbb{Z}^+$

Output: $\lambda_1(\mathcal{L}) \leq d$ or $\lambda_1(\mathcal{L}) > \gamma \cdot d$

3.2 Estimation(EstSVP $_{\gamma}$)

Input: Basis of lattice B

Output: $\lambda_1(\mathcal{L})$ up to a factor γ and return $d \in [\lambda_1(\mathcal{L}), \gamma \cdot \lambda_1(\mathcal{L})]$

3.3 Search(SVP $_{\gamma}$)

Input: Basis of lattice B

Output: $v \in \mathcal{L}(B)$ such that $0 < \|v\| \leq \gamma \cdot \lambda_1(\mathcal{L})$

Open Problem 3.1. Prove or disprove $SVP_{\gamma} \leq GapSVP_{\gamma}$

4 Basis Reduction

Given a lattice \mathcal{L} and its basis B , if we can find a basis B' such that $\mathcal{L}(B) = \mathcal{L}(B')$ and B' contains comparatively smaller lattice vectors than B , we call B' a reduced basis. Minkowski gave an upper bound for the shortest lattice vector. However, in 1805, Gauss gave a working algorithm that solved the SVP **exactly** in 2 dimensions. During 1982, the LLL Basis Reduction algorithm was proposed by Arjen Lenstra, Hendrick Lenstra Jr. and László Lovász, which gives an **approximation** to the shortest vector and works on the technique of basis reduction. It is a generalisation of Gauss's Algorithm.

Definition 4.1. A basis $[b_1, b_2]$ in \mathbb{R}^2 is said to be reduced if

1. $\|b_1\| \leq \|b_2\|$

2. $|\mu_{2,1}| \leq 1/2$

Where, $\mu_{1,2} = \frac{\langle b_2, b_1 \rangle}{\langle b_1, b_1 \rangle}$

The above reduced condition is also called the Gaussian reduced basis form.

References

- [1] Oded Regev, *Lecture Notes on Lattices in Computer Science*, Tel Aviv University, Fall 2009.
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- [3] Deng, Xinyue *An Introduction to Lenstra-Lenstra-Lovasz Lattice Basis Reduction Algorithm*, Massachusetts Institute of Technology, 2016