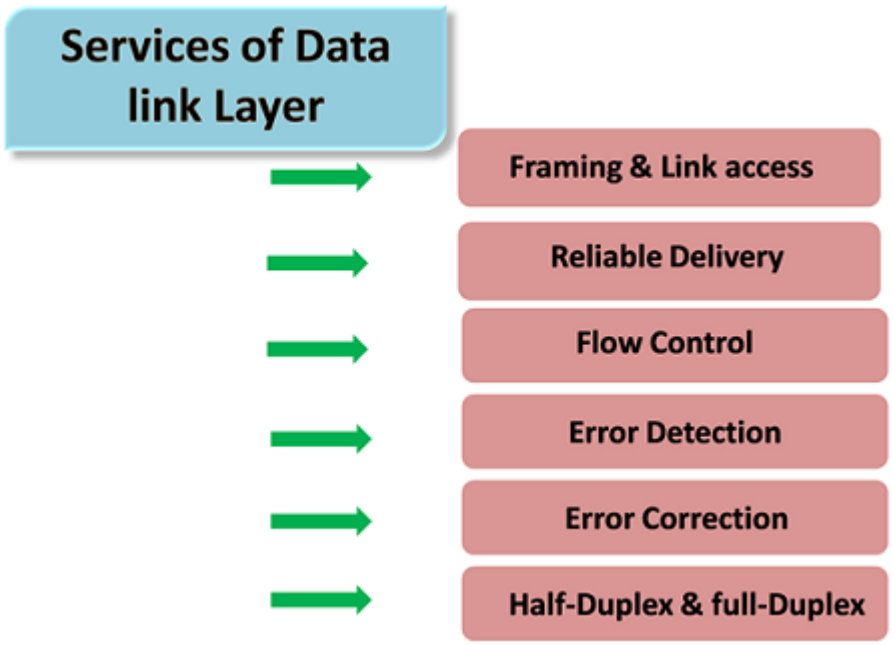
Data Link Layer Notes

- In the OSI model, the data link layer is a 6th layer from the top and 2nd layer from the bottom.
- The communication channel that connects the adjacent nodes is known as links, and in order to move the datagram from source to the destination, the datagram must be moved across an individual link.
- The main responsibility of the Data Link Layer is to transfer the datagram across an individual link.
- The Data link layer protocol defines the format of the packet exchanged across the nodes as well as the actions such as Error detection, retransmission, flow control, and random access.
- The Data Link Layer protocols are Ethernet, token ring, FDDI and PPP.
- An important characteristic of a Data Link Layer is that datagram can be handled by different link layer protocols on different links in a path. For example, the datagram is handled by Ethernet on the first link, PPP on the second link.

Following services are provided by the Data Link Layer:



- **Framing & Link access:** Data Link Layer protocols encapsulate each network frame within a Link layer frame before the transmission across the link. A frame consists of a data field in which network layer datagram is inserted and a number of data fields. It specifies the structure of the frame as well as a channel access protocol by which frame is to be transmitted over the link.
- **Reliable delivery:** Data Link Layer provides a reliable delivery service, i.e., transmits the network layer datagram without any error. A reliable delivery service is accomplished with transmissions and acknowledgements. A data link layer mainly provides the reliable delivery service over the links as they have higher error rates and they can be corrected locally, link at which an error occurs rather than forcing to retransmit the data.
- **Flow control:** A receiving node can receive the frames at a faster rate than it can process the frame. Without flow control, the receiver's buffer can overflow, and frames can get lost. To overcome this problem, the data link layer uses the flow control to prevent the sending node on one side of the link from overwhelming the receiving node on another side of the link.

- **Error detection:** Errors can be introduced by signal attenuation and noise. Data Link Layer protocol provides a mechanism to detect one or more errors. This is achieved by adding error detection bits in the frame and then receiving node can perform an error check.
- **Error correction:** Error correction is similar to the Error detection, except that receiving node not only detect the errors but also determine where the errors have occurred in the frame.
- **Half-Duplex & Full-Duplex:** In a Full-Duplex mode, both the nodes can transmit the data at the same time. In a Half-Duplex mode, only one node can transmit the data at the same time.

Various kind of Framing in Data link layer

Framing is function of Data Link Layer that is used to separate message from source or sender to destination or receiver or simply from all other messages to all other destinations just by adding sender address and destination address. The destination or receiver address is simply used to represent where message or packet is to go and sender or source address is simply used to help recipient to acknowledge receipt.
Frames are generally data unit of data link layer that is transmitted or transferred among various network points. It includes complete and full addressing, protocols that are essential, and information under control. Physical layers only just accept and transfer stream of bits without any regard to meaning or structure. Therefore it is up to data link layer to simply develop and recognize frame boundaries.

This can be achieved by attaching special types of bit patterns to start and end of the frame. If all of these bit patterns might accidentally occur in data, special care is needed to be taken to simply make sure that these bit patterns are not interpreted incorrectly or wrong as frame delimiters.

Framing is simply point-to-point connection among two computers or devices that consists or includes wire in which data is transferred as stream of bits. However, all of these bits should be framed into discernible blocks of information.

Methods of Framing:

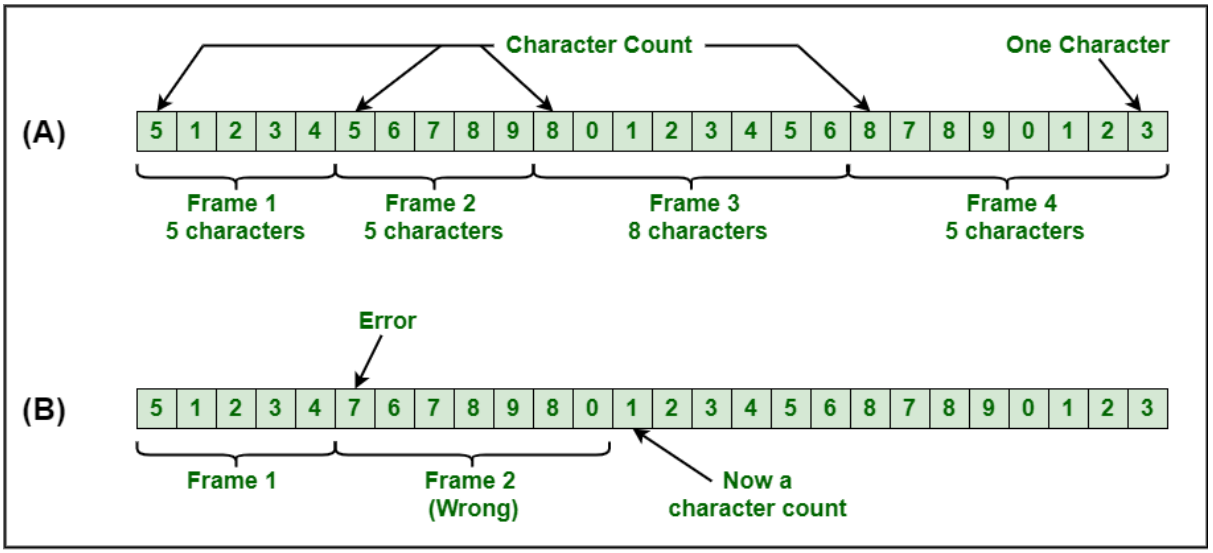
There are basically four methods of framing as given below –
1. Character Count
2. Flag Byte with Character Stuffing
3. Starting and Ending Flags, with Bit Stuffing
4. Encoding Violations

These are explained as following below.

1. **Character Count:**

   This method is rarely used and is generally required to count total number of characters that are present in frame. This is be done by using field in header. Character count method ensures data link layer at the receiver or destination about total number of characters that follow, and about where the frame ends.

There is disadvantage also of using this method i.e., if anyhow character count is disturbed or distorted by an error occurring during transmission, then destination or receiver might lose synchronization. The destination or receiver might also be not able to locate or identify beginning of next frame.

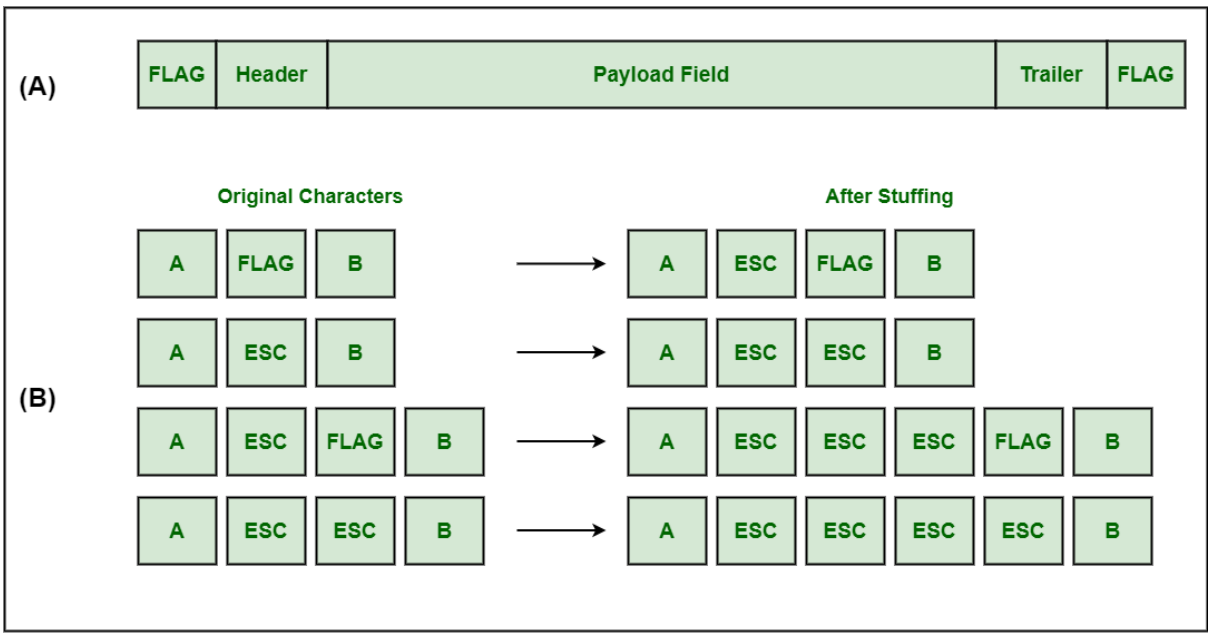


A Character Stream

(A) Without Errors
(B) With one Error

2. Character Stuffing **:**

Character stuffing is also known as byte stuffing or character-oriented framing and is same as that of bit stuffing but byte stuffing actually operates on bytes whereas bit stuffing operates on bits. In byte stuffing, special byte that is basically known as ESC (Escape Character) that has predefined pattern is generally added to data section of the data stream or frame when there is message or character that has same pattern as that of flag byte.
But receiver removes this ESC and keeps data part that causes some problems or issues. In simple words, we can say that character stuffing is addition of 1 additional byte if there is presence of ESC or flag in text.



A Character Stuffing

(A) A frame delimited by flag bytes
(B) Four examples of byte sequences before and after byte stuffing

3. **Bit stuffing:**

- Allows frame to contain arbitrary number of bits and arbitrary character size. The frames are separated by separating flag.
- Each frame begins and ends with a special bit pattern, 01111110 called a flag byte. When five consecutive l's are encountered in the data, it automatically stuffs a '0' bit into outgoing bit stream.
- In this method, frames contain an arbitrary number of bits and allow character codes with an arbitrary number of bits per character. In his case, each frame starts and ends with a special bit pattern, 01111110.
- In the data a 0 bit is automatically stuffed into the outgoing bit stream whenever the sender's data link layer finds five consecutive 1s.
- This bit stuffing is similar to byte stuffing, in which an escape byte is stuffed into the outgoing character stream before a flag byte in the data.
- When the receiver sees five consecutive incoming i bits, followed by a o bit, it automatically destuffs (i.e., deletes) the 0 bit. Bit Stuffing is completely transparent to network layer as byte stuffing. The figure1 below gives an example of bit stuffing.
- This method of framing finds its application in networks in which the change of data into code on the physical medium contains some repeated or duplicate data. For example, some LANs encodes bit of data by using 2 physical bits.

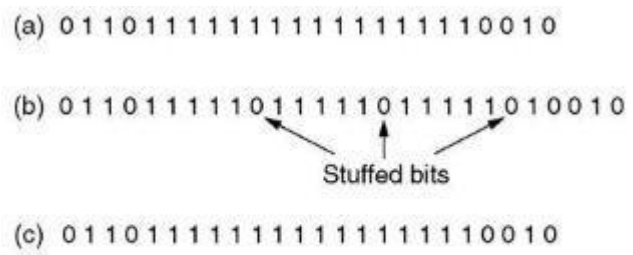
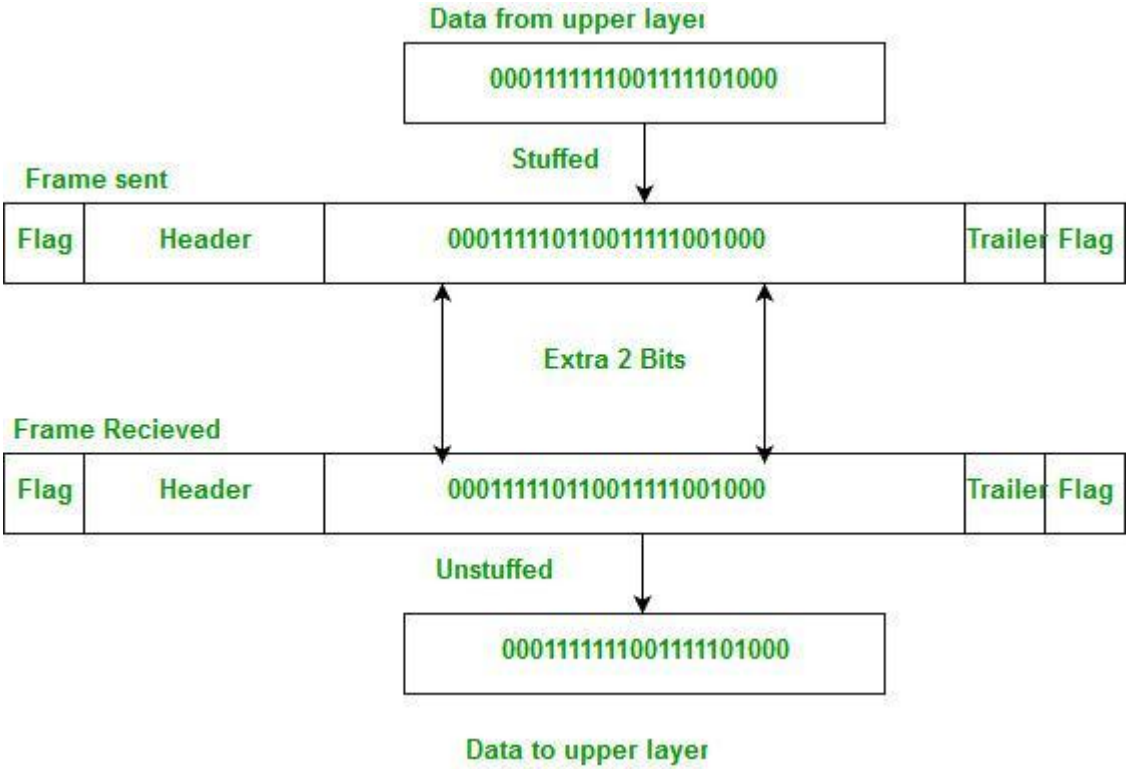
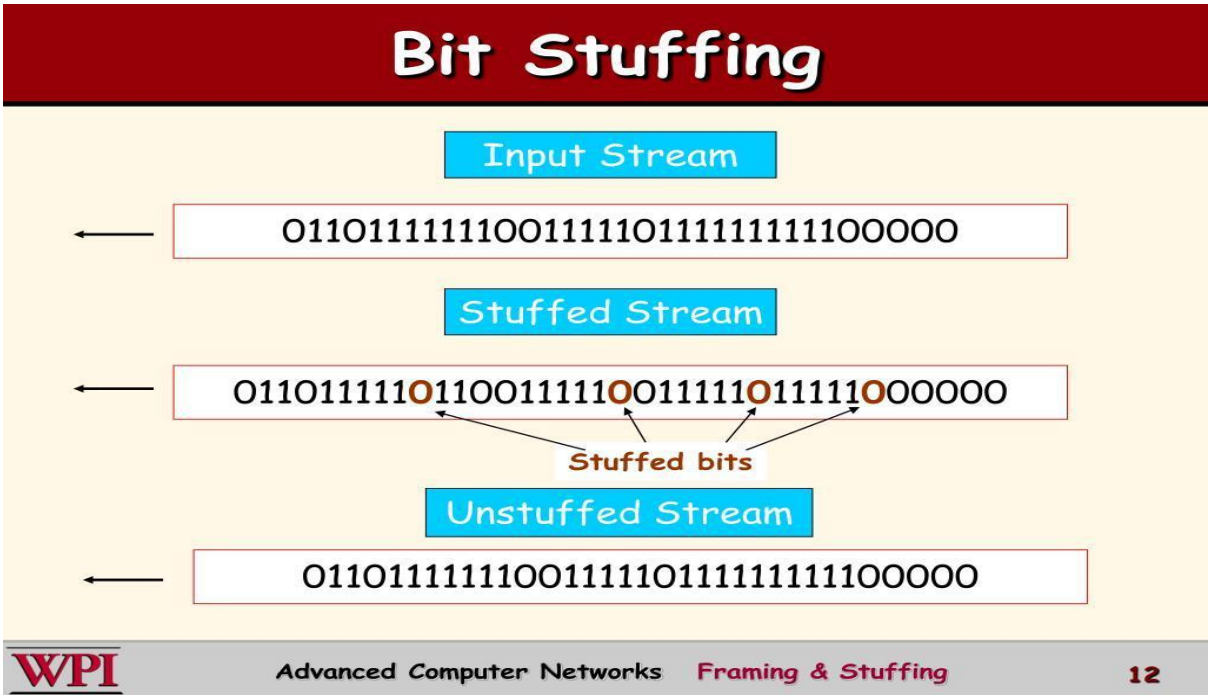


Fig1: Bit stuffing





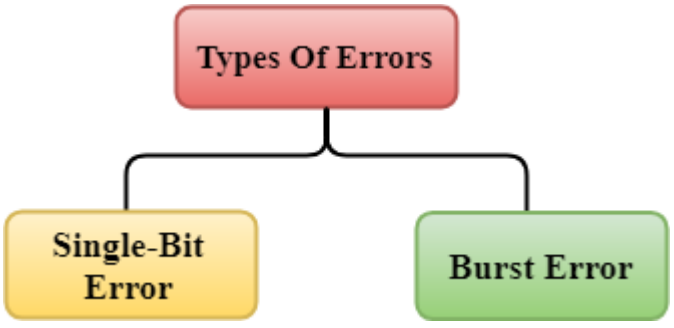
4. **Physical Layer Coding Violations:**

   Encoding violation is method that is used only for network in which encoding on physical medium includes some sort of redundancy i.e., use of more than one graphical or visual structure to simply encode or represent one variable of data.

Error Detection

When data is transmitted from one device to another device, the system does not guarantee whether the data received by the device is identical to the data transmitted by another device. An Error is a situation when the message received at the receiver end is not identical to the message transmitted.

Types Of Errors

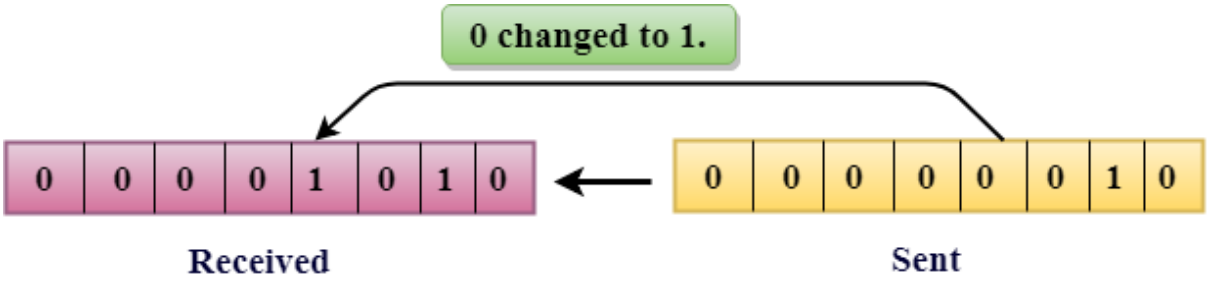


Errors can be classified into two categories:

- Single-Bit Error
- Burst Error

Single-Bit Error:

The only one bit of a given data unit is changed from 1 to 0 or from 0 to 1.



In the above figure, the message which is sent is corrupted as single-bit, i.e., 0 bit is changed to 1.

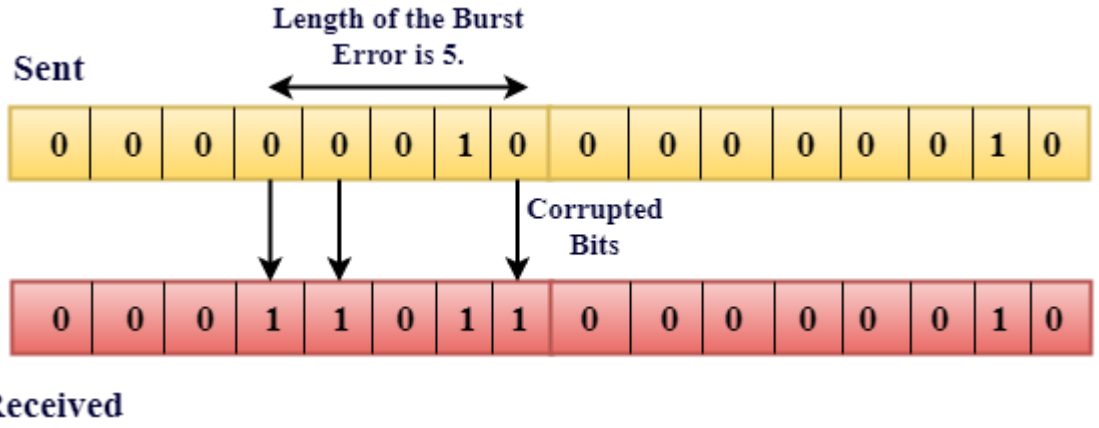
Single-Bit Error does not appear more likely in Serial Data Transmission. For example, Sender sends the data at 10 Mbps, this means that the bit lasts only for 1 ?s and for a single-bit error to occurred, a noise must be more than 1 ?s.

Single-Bit Error mainly occurs in Parallel Data Transmission. For example, if eight wires are used to send the eight bits of a byte, if one of the wire is noisy, then single-bit is corrupted per byte.

Burst Error:

The two or more bits are changed from 0 to 1 or from 1 to 0 is known as Burst Error.

The Burst Error is determined from the first corrupted bit to the last corrupted bit.



The duration of noise in Burst Error is more than the duration of noise in Single-Bit.

Burst Errors are most likely to occurr in Serial Data Transmission.

The number of affected bits depends on the duration of the noise and data rate.

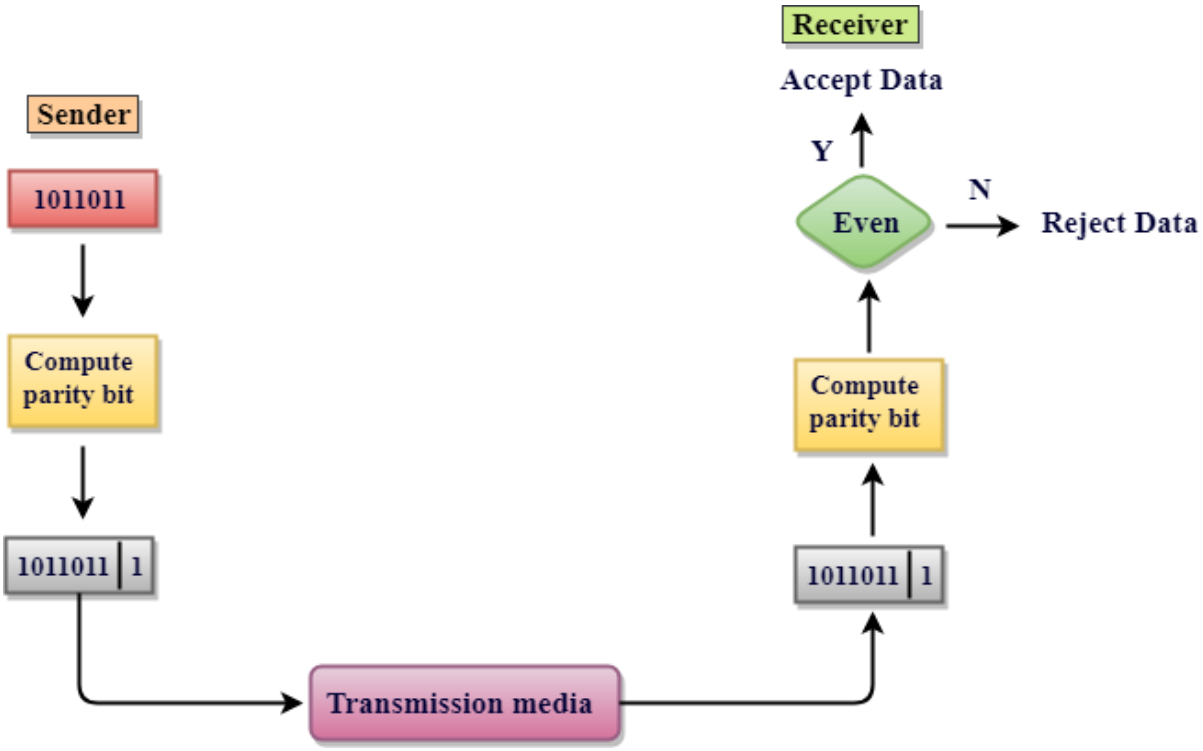
Error Detecting Techniques:

The most popular Error Detecting Techniques are:

- Single parity check
- Two-dimensional parity check
- Checksum
- Cyclic redundancy check

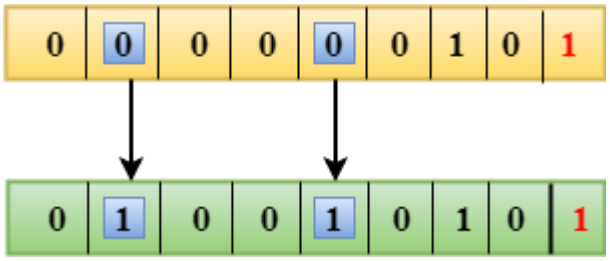
Single Parity Check

- Single Parity checking is the simple mechanism and inexpensive to detect the errors.
- In this technique, a redundant bit is also known as a parity bit which is appended at the end of the data unit so that the number of 1s becomes even. Therefore, the total number of transmitted bits would be 9 bits.
- If the number of 1s bits is odd, then parity bit 1 is appended and if the number of 1s bits is even, then parity bit 0 is appended at the end of the data unit.
- At the receiving end, the parity bit is calculated from the received data bits and compared with the received parity bit.
- This technique generates the total number of 1s even, so it is known as even-parity checking.



Drawbacks Of Single Parity Checking

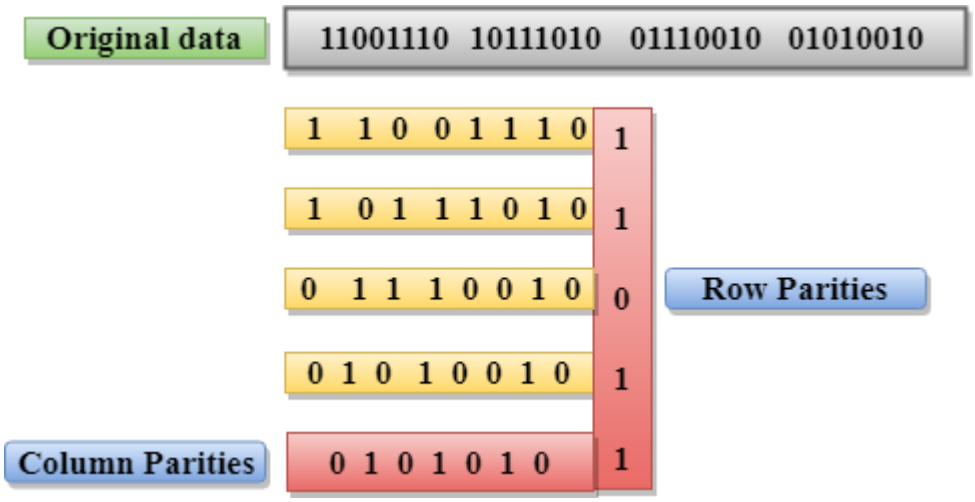
- It can only detect single-bit errors which are very rare.
- If two bits are interchanged, then it cannot detect the errors.



Two-Dimensional Parity Check

- Performance can be improved by using **Two-Dimensional Parity Check** which organizes the data in the form of a table.

- Parity check bits are computed for each row, which is equivalent to the single-parity check.
- In Two-Dimensional Parity check, a block of bits is divided into rows, and the redundant row of bits is added to the whole block.
- At the receiving end, the parity bits are compared with the parity bits computed from the received data.



Drawbacks Of 2D Parity Check

- If two bits in one data unit are corrupted and two bits exactly the same position in another data unit are also corrupted, then 2D Parity checker will not be able to detect the error.
- This technique cannot be used to detect the 4-bit errors or more in some cases.

Checksum

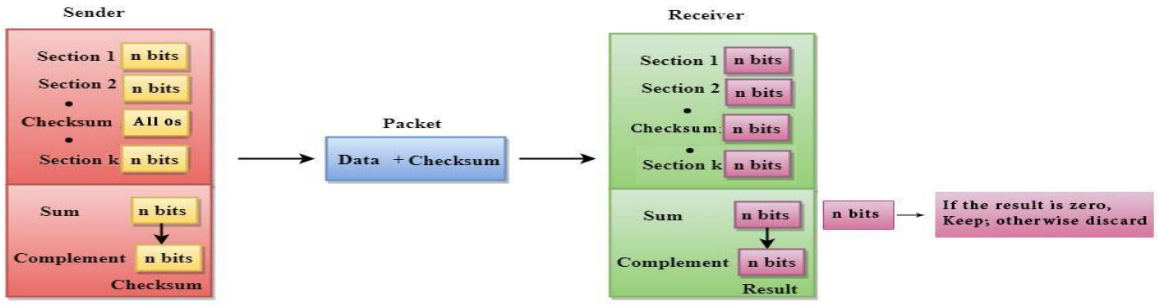
A Checksum is an error detection technique based on the concept of redundancy.

It is divided into two parts:

Checksum Generator

A Checksum is generated at the sending side. Checksum generator subdivides the data into equal segments of n bits each, and all these segments are added together by using one's complement arithmetic. The sum is complemented and appended to the original data, known as checksum field. The extended data is transmitted across the network.

Suppose L is the total sum of the data segments, then the checksum would be ?L



1. The Sender follows the given steps:

2. The block unit is divided into k sections, and each of n bits.
3. All the k sections are added together by using one's complement to get the sum.
4. The sum is complemented, and it becomes the checksum field.
5. The original data and checksum field are sent across the network.

Checksum Checker

A Checksum is verified at the receiving side. The receiver subdivides the incoming data into equal segments of n bits each, and all these segments are added together, and then this sum is complemented. If the complement of the sum is zero, then the data is accepted otherwise data is rejected.

1. The Receiver follows the given steps:
2. The block unit is divided into k sections and each of n bits.
3. All the k sections are added together by using one's complement algorithm to get the sum.
4. The sum is complemented.
5. If the result of the sum is zero, then the data is accepted otherwise the data is discarded.

Cyclic Redundancy Check (CRC)

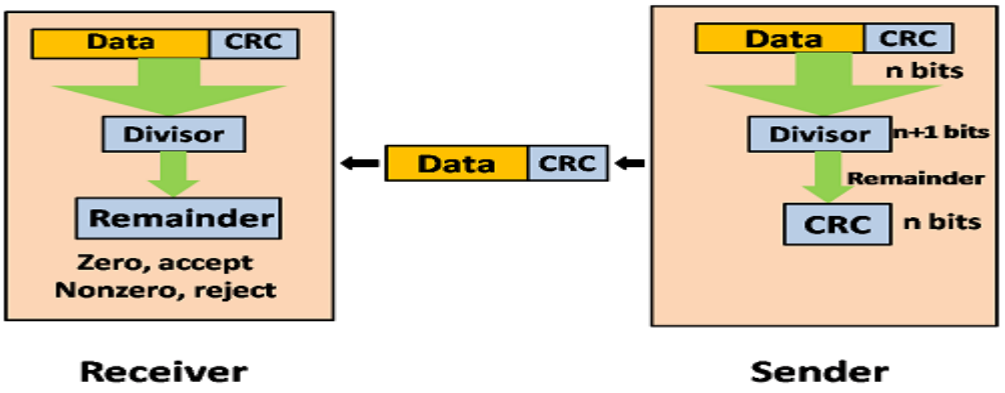
CRC is a redundancy error technique used to determine the error.

Following are the steps used in CRC for error detection:

- In CRC technique, a string of n 0s is appended to the data unit, and this n number is less than the number of bits in a predetermined number, known as division which is n+1 bits.
- Secondly, the newly extended data is divided by a divisor using a process is known as binary division. The remainder generated from this division is known as CRC remainder.
- Thirdly, the CRC remainder replaces the appended 0s at the end of the original data. This newly generated unit is sent to the receiver.
- The receiver receives the data followed by the CRC remainder. The receiver will treat this whole unit as a single unit, and it is divided by the same divisor that was used to find the CRC remainder.

If the resultant of this division is zero which means that it has no error, and the data is accepted.

If the resultant of this division is not zero which means that the data consists of an error. Therefore, the data is discarded.

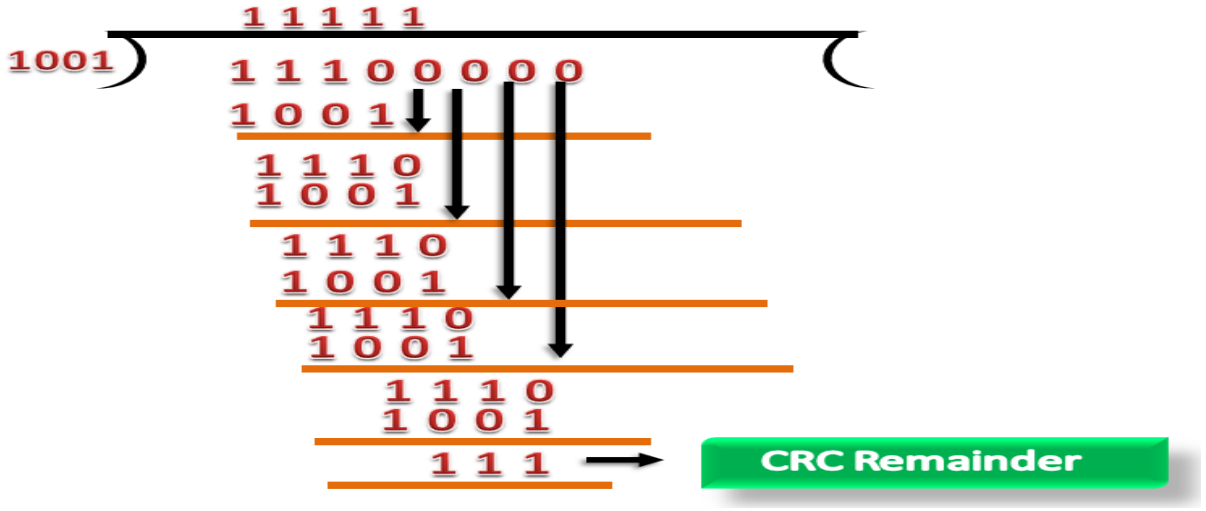


Let's understand this concept through an example:

Suppose the original data is 11100 and divisor is 1001.

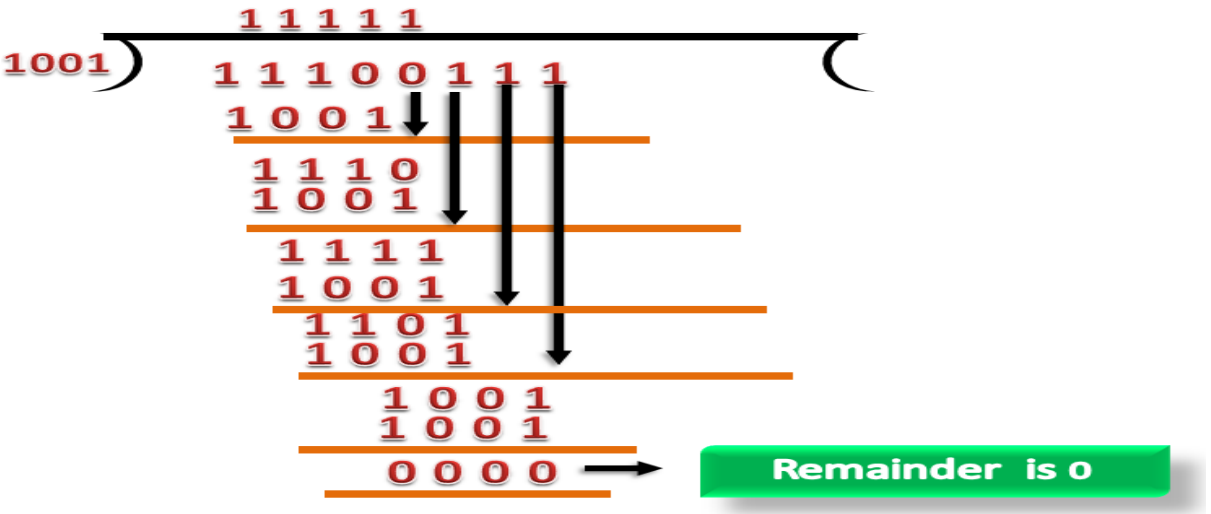
CRC Generator

- A CRC generator uses a modulo-2 division. Firstly, three zeroes are appended at the end of the data as the length of the divisor is 4 and we know that the length of the string 0s to be appended is always one less than the length of the divisor.
- Now, the string becomes 11100000, and the resultant string is divided by the divisor 1001.
- The remainder generated from the binary division is known as CRC remainder. The generated value of the CRC remainder is 111.
- CRC remainder replaces the appended string of 0s at the end of the data unit, and the final string would be 11100111 which is sent across the network.



CRC Checker

- The functionality of the CRC checker is similar to the CRC generator.
- When the string 11100111 is received at the receiving end, then CRC checker performs the modulo-2 division.
- A string is divided by the same divisor, i.e., 1001.
- In this case, CRC checker generates the remainder of zero. Therefore, the data is accepted.



Error Correction

Error Correction codes are used to detect and correct the errors when data is transmitted from the sender to the receiver.

Error Correction can be handled in two ways:

- **Backward error correction:** Once the error is discovered, the receiver requests the sender to retransmit the entire data unit.
- **Forward error correction:** In this case, the receiver uses the error-correcting code which automatically corrects the errors.

A single additional bit can detect the error, but cannot correct it.

For correcting the errors, one has to know the exact position of the error. For example, If we want to calculate a single-bit error, the error correction code will determine which one of seven bits is in error. To achieve this, we have to add some additional redundant bits.

Suppose r is the number of redundant bits and d is the total number of the data bits. The number of redundant bits r can be calculated by using the formula:

$2^r >= d+r+1$

The value of r is calculated by using the above formula. For example, if the value of d is 4, then the possible smallest value that satisfies the above relation would be 3.

To determine the position of the bit which is in error, a technique developed by R.W Hamming is Hamming code which can be applied to any length of the data unit and uses the relationship between data units and redundant units.

Hamming Code

Parity bits: The bit which is appended to the original data of binary bits so that the total number of 1s is even or odd.

Even parity: To check for even parity, if the total number of 1s is even, then the value of the parity bit is 0. If the total number of 1s occurrences is odd, then the value of the parity bit is 1.

Odd Parity: To check for odd parity, if the total number of 1s is even, then the value of parity bit is 1. If the total number of 1s is odd, then the value of parity bit is 0.

Algorithm of Hamming code:

- An information of 'd' bits are added to the redundant bits 'r' to form d+r.
- The location of each of the (d+r) digits is assigned a decimal value.
- The 'r' bits are placed in the positions $1,2,.....2^{k-1}$.
- At the receiving end, the parity bits are recalculated. The decimal value of the parity bits determines the position of an error.

Relationship b/w Error position & binary number.

Error Position	Binary Number
0	000
1	001
2	010
3	011
4	100
5	101
6	110
7	111

Let's understand the concept of Hamming code through an example:

Suppose the original data is 1010 which is to be sent.

Total number of data bits 'd' = 4

Number of redundant bits r : $2^r >= d+r+1$

$2^r >= 4+r+1$

Therefore, the value of r is 3 that satisfies the above relation.

Total number of bits = d+r = 4+3 = 7;

Determining the position of the redundant bits

The number of redundant bits is 3. The three bits are represented by r1, r2, r4. The position of the redundant bits is calculated with corresponds to the raised power of 2. Therefore, their corresponding positions are **1, 2^1, 2^2**.

1. The position of r1 = 1
2. The position of r2 = 2
3. The position of r4 = 4

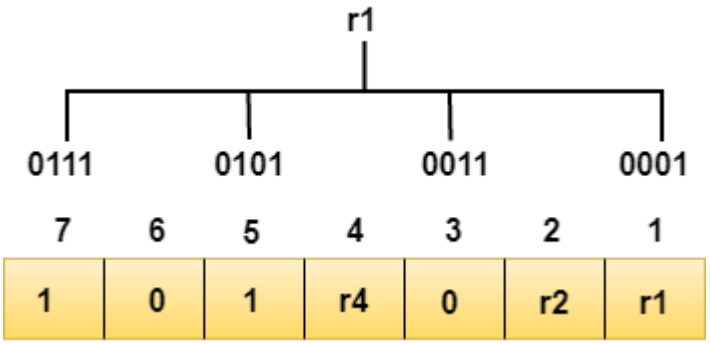
Representation of Data on the addition of parity bits:

7	6	5	4	3	2	1
1	0	1	r4	0	r2	r1

Determining the Parity bits

Determining the r1 bit

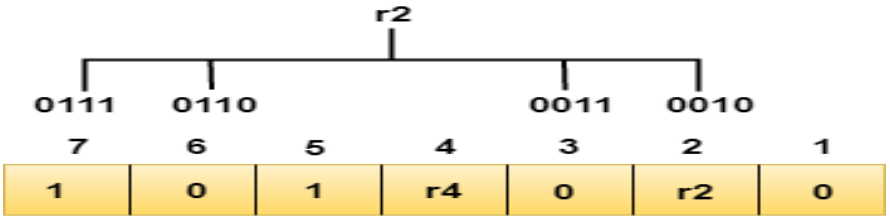
The r1 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the first position.



We observe from the above figure that the bit positions that includes 1 in the first position are 1, 3, 5, 7. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r1 is **even, therefore, the value of the r1 bit is 0**.

Determining r2 bit

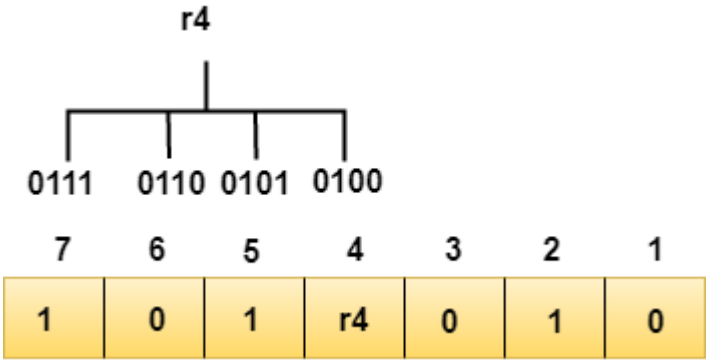
The r2 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the second position.



We observe from the above figure that the bit positions that includes 1 in the second position are **2, 3, 6, 7**. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r2 is **odd, therefore, the value of the r2 bit is 1**.

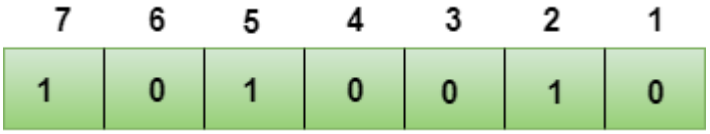
Determining r4 bit

The r4 bit is calculated by performing a parity check on the bit positions whose binary representation includes 1 in the third position.



We observe from the above figure that the bit positions that includes 1 in the third position are **4, 5, 6, 7**. Now, we perform the even-parity check at these bit positions. The total number of 1 at these bit positions corresponding to r4 is **even, therefore, the value of the r4 bit is 0**.

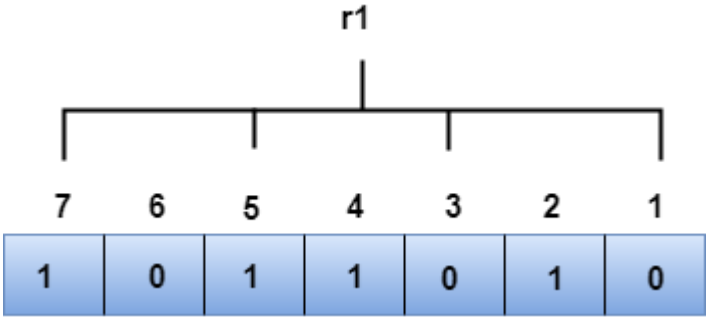
Data transferred is given below:



Suppose the 4th bit is changed from 0 to 1 at the receiving end, then parity bits are recalculated.

R1 bit

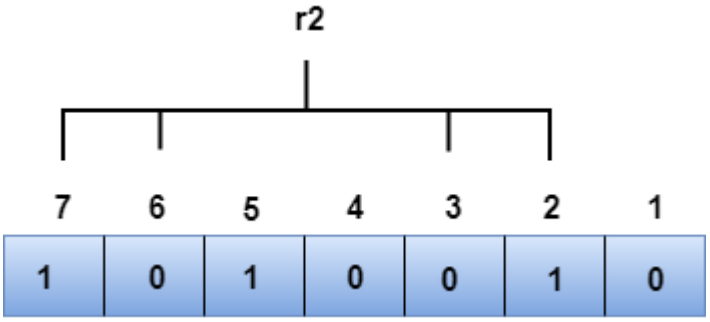
The bit positions of the r1 bit are 1,3,5,7



We observe from the above figure that the binary representation of r1 is 1100. Now, we perform the even-parity check, the total number of 1s appearing in the r1 bit is an even number. Therefore, the value of r1 is 0.

R2 bit

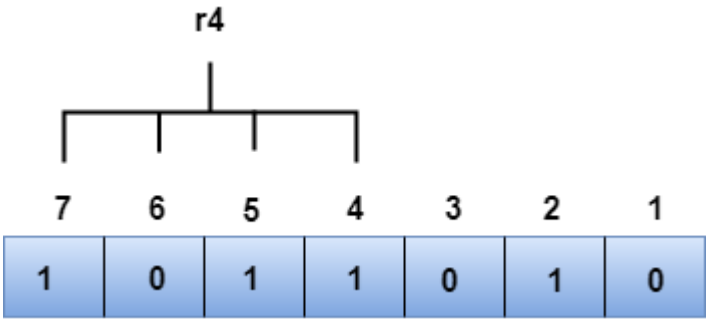
The bit positions of r2 bit are 2,3,6,7.



We observe from the above figure that the binary representation of r2 is 1001. Now, we perform the even-parity check, the total number of 1s appearing in the r2 bit is an even number. Therefore, the value of r2 is 0.

R4 bit

The bit positions of r4 bit are 4,5,6,7.



We observe from the above figure that the binary representation of r4 is 1011. Now, we perform the even-parity check, the total number of 1s appearing in the r4 bit is an odd number. Therefore, the value of r4 is 1.

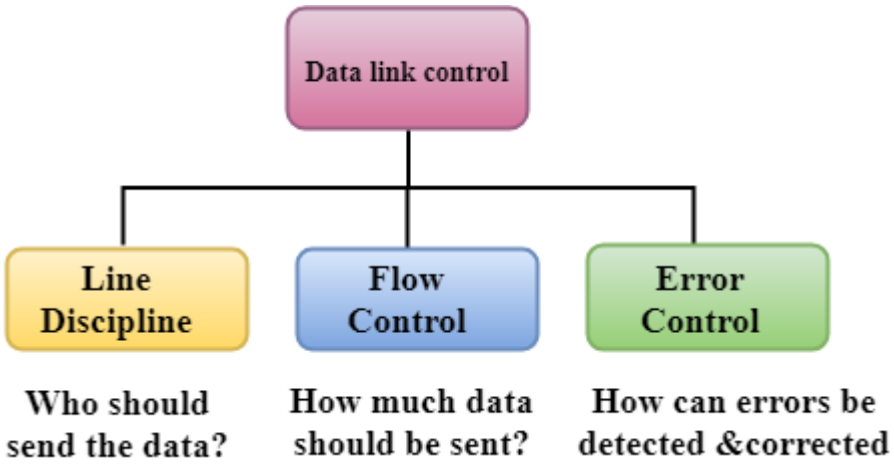
- *The binary representation of redundant bits, i.e., r4r2r1 is 100, and its corresponding decimal value is 4. Therefore, the error occurs in a 4th bit position. The bit value must be changed from 1 to 0 to correct the error.*

Data Link Controls

Data Link Control is the service provided by the Data Link Layer to provide reliable data transfer over the physical medium. For example, In the half-duplex transmission mode, one device can only transmit the data at a time. If both the devices at the end of the links transmit the data simultaneously, they will collide and leads to the loss of the information. The Data link layer provides the coordination among the devices so that no collision occurs.

The Data link layer provides three functions:

- Line discipline
- Flow Control
- Error Control



Line Discipline

- Line Discipline is a functionality of the Data link layer that provides the coordination among the link systems. It determines which device can send, and when it can send the data.

Line Discipline can be achieved in two ways:

- ENQ/ACK
- Poll/select

END/ACK

END/ACK stands for Enquiry/Acknowledgement is used when there is no wrong receiver available on the link and having a dedicated path between the two devices so that the device capable of receiving the transmission is the intended one.

END/ACK coordinates which device will start the transmission and whether the recipient is ready or not.

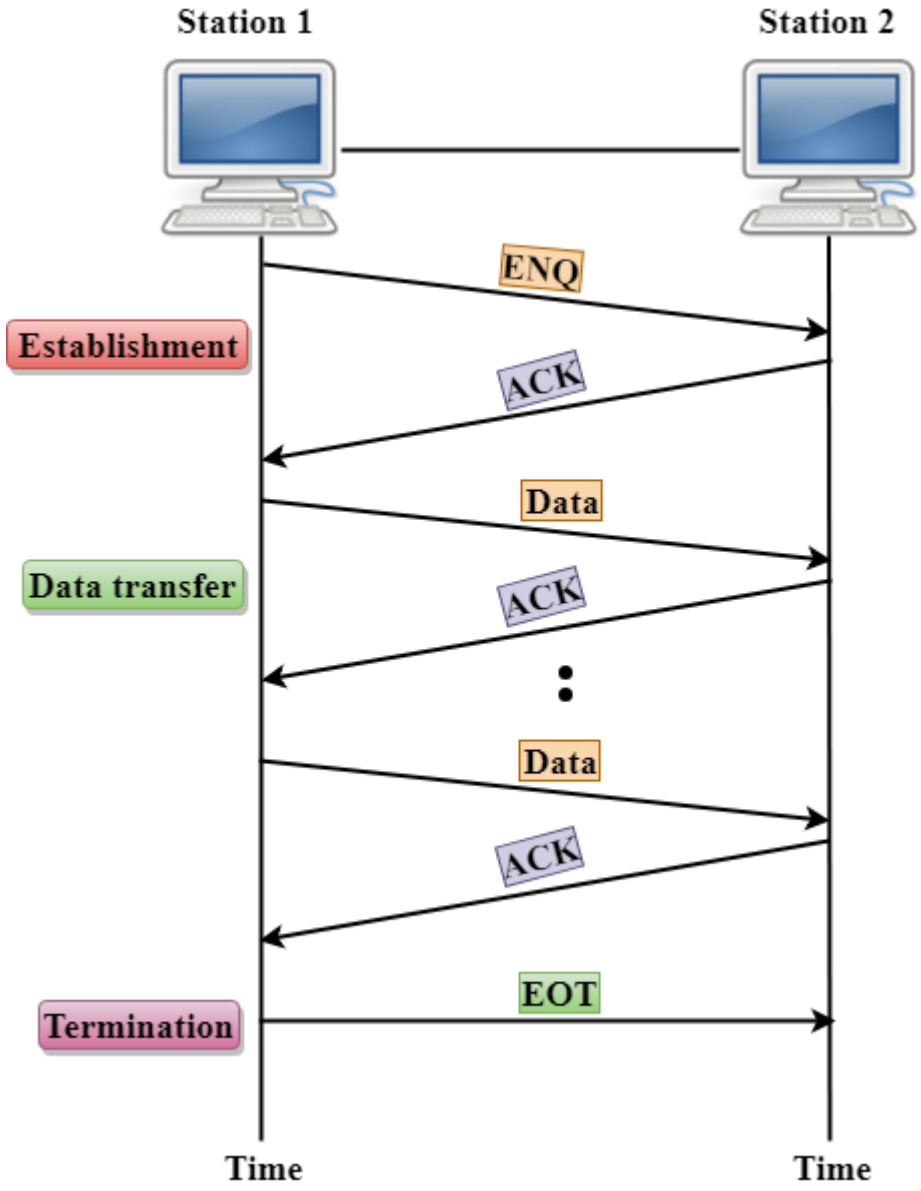
Working of END/ACK

The transmitter transmits the frame called an Enquiry (ENQ) asking whether the receiver is available to receive the data or not.

The receiver responses either with the positive acknowledgement(ACK) or with the negative acknowledgement(NACK) where positive acknowledgement means that the receiver is ready to receive the transmission and negative acknowledgement means that the receiver is unable to accept the transmission.

Following are the responses of the receiver:

- If the response to the ENQ is positive, the sender will transmit its data, and once all of its data has been transmitted, the device finishes its transmission with an EOT (END-of-Transmission) frame.
- If the response to the ENQ is negative, then the sender disconnects and restarts the transmission at another time.
- If the response is neither negative nor positive, the sender assumes that the ENQ frame was lost during the transmission and makes three attempts to establish a link before giving up.



Poll/Select

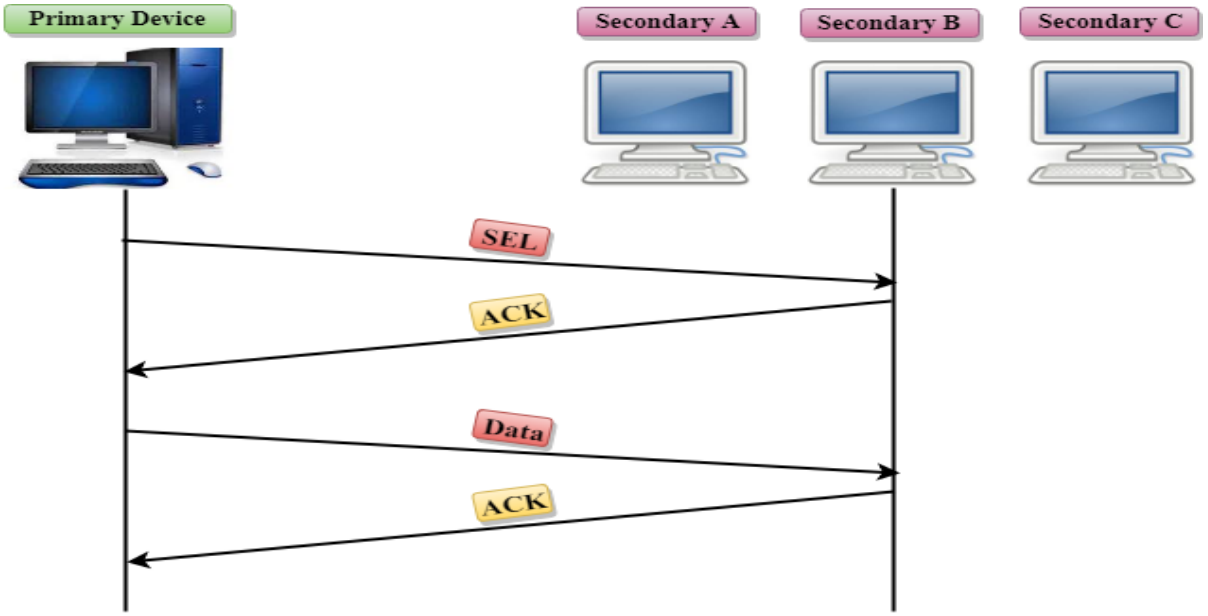
The Poll/Select method of line discipline works with those topologies where one device is designated as a primary station, and other devices are secondary stations.

Working of Poll/Select

- In this, the primary device and multiple secondary devices consist of a single transmission line, and all the exchanges are made through the primary device even though the destination is a secondary device.
- The primary device has control over the communication link, and the secondary device follows the instructions of the primary device.
- The primary device determines which device is allowed to use the communication channel. Therefore, we can say that it is an initiator of the session.
- If the primary device wants to receive the data from the secondary device, it asks the secondary device that they anything to send, this process is known as polling.
- If the primary device wants to send some data to the secondary device, then it tells the target secondary to get ready to receive the data, this process is known as selecting.

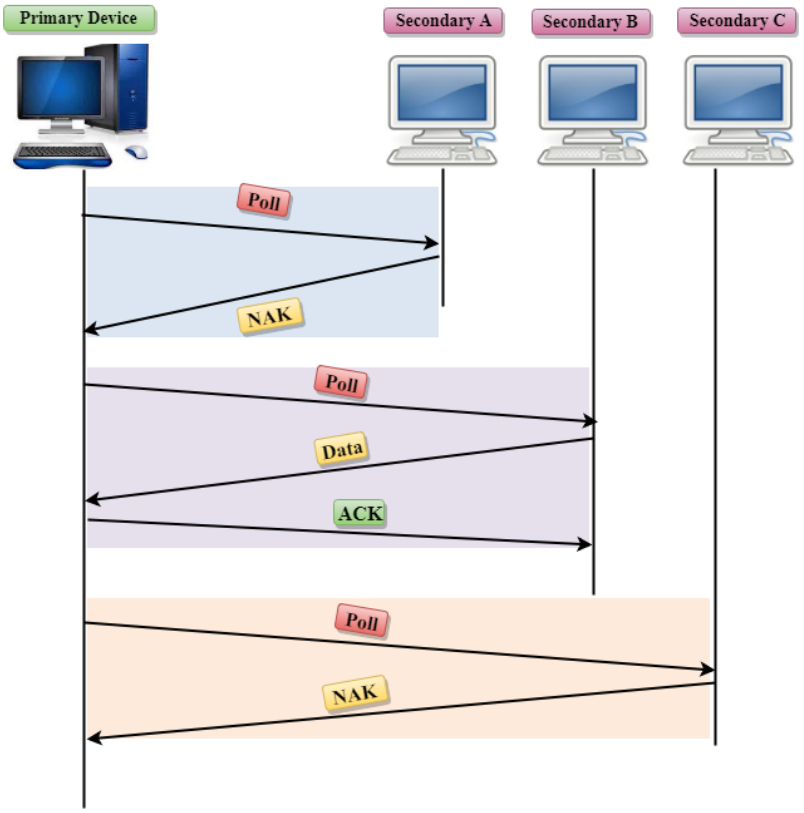
Select

- The select mode is used when the primary device has something to send.
- When the primary device wants to send some data, then it alerts the secondary device for the upcoming transmission by transmitting a Select (SEL) frame, one field of the frame includes the address of the intended secondary device.
- When the secondary device receives the SEL frame, it sends an acknowledgement that indicates the secondary ready status.
- If the secondary device is ready to accept the data, then the primary device sends two or more data frames to the intended secondary device. Once the data has been transmitted, the secondary sends an acknowledgement specifies that the data has been received.



Poll

- The Poll mode is used when the primary device wants to receive some data from the secondary device.
- When a primary device wants to receive the data, then it asks each device whether it has anything to send.
- Firstly, the primary asks (poll) the first secondary device, if it responds with the NACK (Negative Acknowledgement) means that it has nothing to send. Now, it approaches the second secondary device, it responds with the ACK means that it has the data to send. The secondary device can send more than one frame one after another or sometimes it may be required to send ACK before sending each one, depending on the type of the protocol being used.



Flow Control:

Flow control coordinates the amount of data that can be sent before receiving an acknowledgment and is one of the most important duties of the data link layer. In most protocols, flow control is a set of procedures that tells the sender how much data it can transmit before it must wait for an acknowledgment from the receiver.

Any receiving device has a limited speed at which it can process incoming data and a limited amount of memory in which to store incoming data. The receiving device must be able to inform the sending device before those limits are reached and to request that the transmitting device send fewer frames or stop temporarily. Incoming data must be checked and processed before they can be used. The rate of such processing is often slower than the rate of transmission. For this reason, each receiving device has a block of memory, called a buffer, reserved for storing incoming data until they are processed. If the buffer begins to fill up, the receiver must be able to tell the sender to halt transmission until it is once again able to receive.

Framing and Framing Protocols

The data link layer, on the other hand, needs to pack bits into frames, so that each frame is distinguishable from another. Framing in the data link layer separates a message from one source to a destination, or from other messages to other destinations, by adding a sender address and a destination address. The destination address defines where the packet is to go; the sender address helps the recipient acknowledge the receipt.

Although the whole message could be packed in one frame, that is not normally done. One reason is that a frame can be very large, making flow and error control very inefficient. When a message is carried in one very large frame, even a single-bit error would require the

retransmission of the whole message. When a message is divided into smaller frames, a single-

bit error affects only that small frame.

Frames can be of fixed or variable size.

Fixed size framing:

In fixed-size framing, there is no need for defining the boundaries of the frames; the size itself can be used as a delimiter. An example of this type of framing is the ATM wide-area network, which uses frames of fixed size called cells.

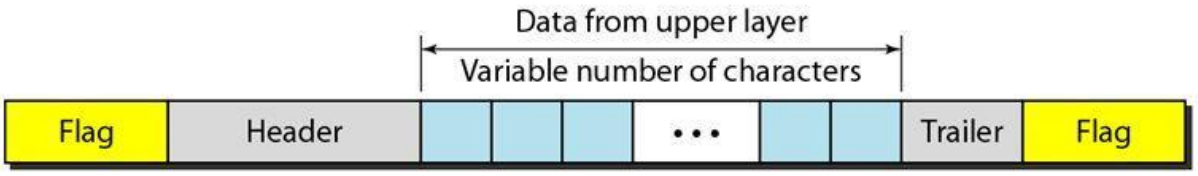
Variable-Size Framing:

In variable-size framing, we need to define the end of the frame and the beginning of the next. There are two approaches which are used for this purpose: *A character-oriented approach* and *A bit-oriented approach*.

Character-Oriented Protocols:

In a character-oriented protocol, data to be carried are 8-bit characters from a coding system such as ASCII (see Appendix A). The header, which normally carries the source and destination addresses and other control information, and the trailer, which carries error detection or error correction redundant bits, are also multiples of 8 bits.

To separate one frame from the next, an 8- bit (I-byte) flag is added at the beginning and the end of a frame. The flag, composed of protocol-dependent special characters, signals the start or end of a frame. The following figure shows the format of a frame in a character-oriented protocol.



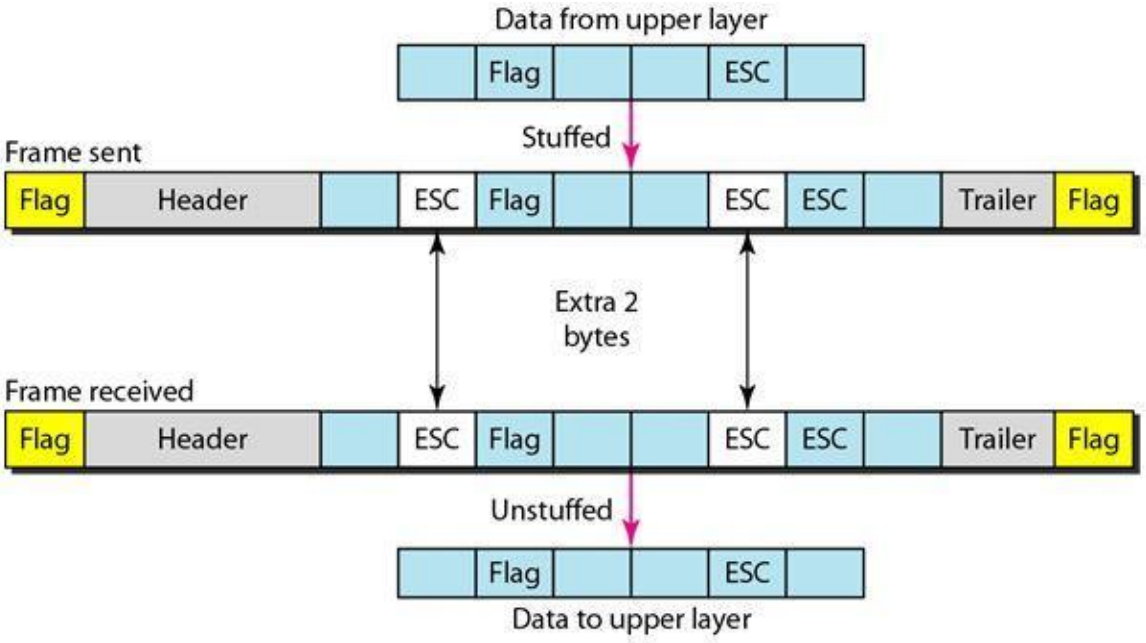
Character-oriented framing was popular when only text was exchanged by the data link layers. The flag could be selected to be any character not used for text communication.

However, if we send other types of information such as graphs, audio, and video. Any pattern used for the flag could also be part of the information. If this happens, the receiver, when it encounters this pattern in the middle of the data, thinks it has reached the end of the frame.

To fix this problem, a byte-stuffing strategy was added to character-oriented framing. In byte stuffing (or character stuffing), a special byte is added to the data section of the frame when there is a character with the same pattern as the flag. The data section is stuffed with an extra byte. This byte is usually called the escape character (ESC), which has a predefined bit pattern. Whenever the receiver encounters the ESC character, it removes it from the data

section and treats the next character as data, not a delimiting flag.

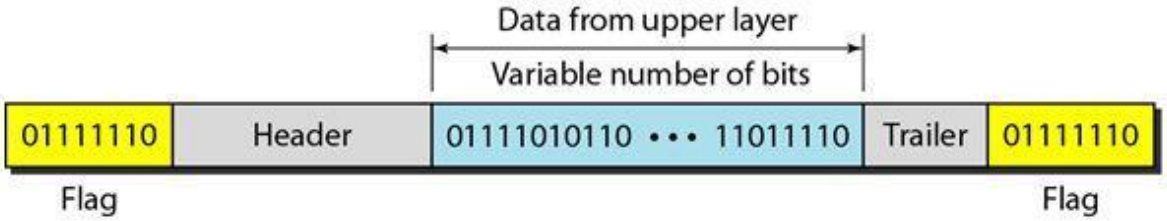
Byte stuffing by the escape character allows the presence of the flag in the data section of the frame, but it creates another problem. What happens if the text contains one or more escape characters followed by a flag? The receiver removes the escape character, but keeps the flag, which is incorrectly interpreted as the end of the frame. To solve this problem, the escape characters that are part of the text must also be marked by another escape character. In other words, if the escape character is part of the text, an extra one is added to show that the second one is part of the text. The following figure shows the situation.



Character-oriented protocols present another problem in data communications. The universal coding systems in use today, such as Unicode, have 16-bit and 32-bit characters that conflict with 8-bit characters. We can say that in general, the tendency is moving toward the bit-oriented protocols.

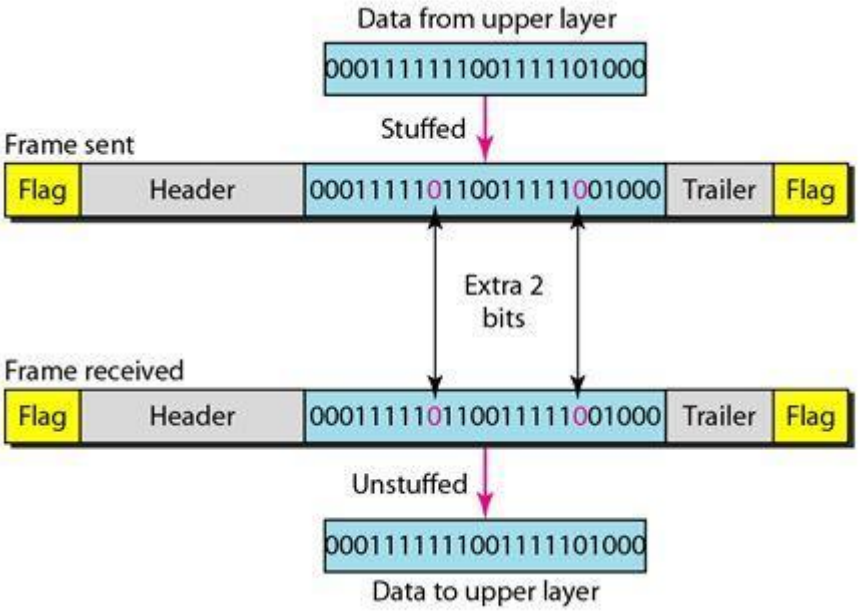
Bit-Oriented Protocols:

In a bit-oriented protocol, the data section of a frame is a sequence of bits to be interpreted by the upper layer as text, graphic, audio, video, and so on. However, in addition to headers (and possible trailers), we need a delimiter to separate one frame from the other. Most protocols use a special 8-bit pattern flag 01111110 as the delimiter to define the beginning and the end of the frame, as shown in the following figure.



This flag can create the same type of problem we saw in the byte-oriented protocols. That is, if the flag pattern appears in the data, we need to somehow inform the receiver that this is not the end of the frame. We do this by stuffing 1 single bit (instead of 1 byte) to prevent the pattern from looking like a flag. The strategy is called bit stuffing. In bit stuffing, if 0 and five consecutive 1 bits are encountered, an extra 0 is added. This extra stuffed bit is eventually removed from the data by the receiver. Note that the extra bit is added after one 0 followed by five 1s regardless of the value of the next bit. This guarantees that the flag field sequence does not inadvertently appear in the frame.

The following figure shows bit stuffing at the sender and bit removal at the receiver. Note that even if we have a 0 after five 1s, we still stuff a 0. The 0 will be removed by the receiver.



This means that if the flag like pattern 01111110 appears in the data, it will change to 011111010 (stuffed) and is not mistaken as a flag by the receiver. The real flag 01111110 is not stuffed by the sender and is recognized by the receiver.

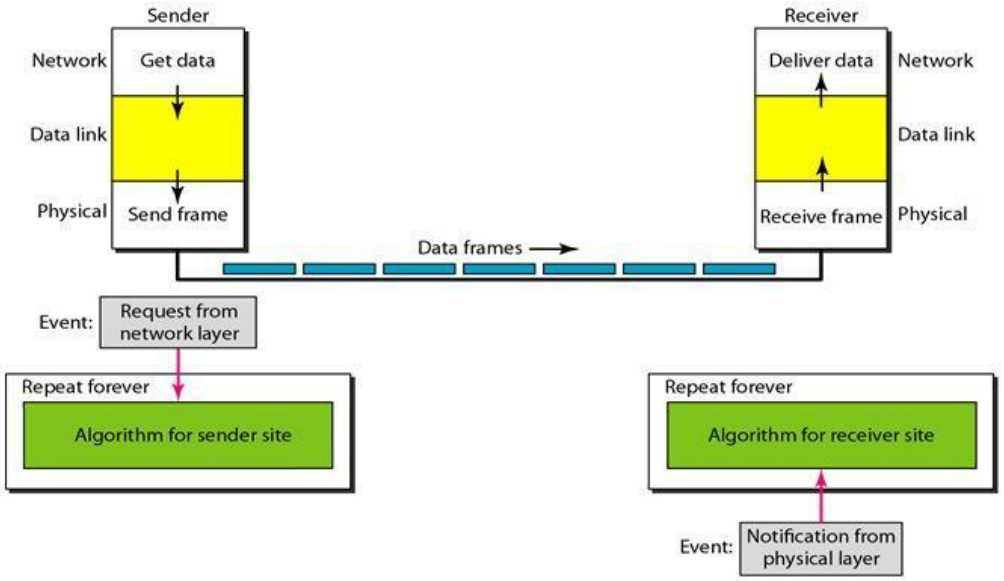
Simplest Protocol:

Simplest Protocol is one that has no flow or error control and it is a unidirectional protocol in which data frames are traveling in only one direction-from the sender to receiver. We assume that the receiver can immediately handle any frame it receives with a processing time that is

small enough to be negligible. The data link layer of the receiver immediately removes the header from the frame and hands the data packet to its network layer, which can also accept the packet immediately.

Design:

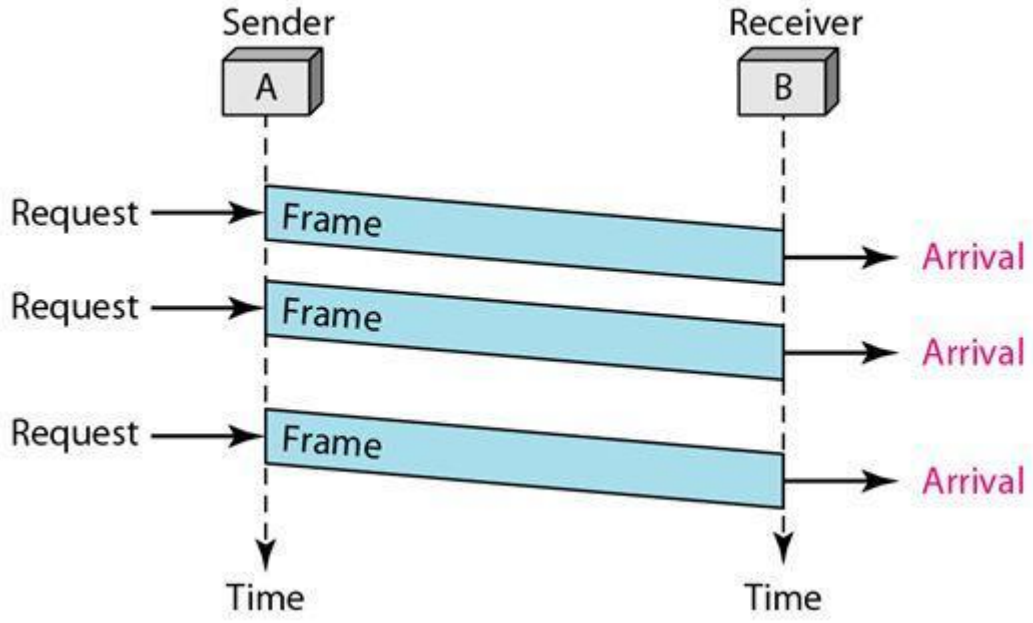
There is no need for flow control in this scheme. The data link layer at the sender site gets data from its network layer, makes a frame out of the data, and sends it. The data link layer at the receiver site receives a frame from its physical layer, extracts data from the frame, and delivers the data to its network layer. The data link layers of the sender and receiver provide transmission services for their network layers. The data link layers use the services provided by their physical layers (such as signaling, multiplexing, and so on) for the physical transmission of bits. The following figure shows a design.



The sender site cannot send a frame until its network layer has a data packet to send. The receiver site cannot deliver a data packet to its network layer until a frame arrives. If the protocol is implemented as a procedure, we need to introduce the idea of events in the protocol.

The procedure at the sender site is constantly running; there is no action until there is a request from the network layer. The procedure at the receiver site is also constantly running, but there is no action until notification from the physical layer arrives. Both procedures are constantly running because they do not know when the corresponding events will occur.

The following figure shows an example of communication using this protocol. It is very simple. The sender sends a sequence of frames without even thinking about the receiver. To send three frames, three events occur at the sender site and three events at the receiver site. Note that the data frames are shown by tilted boxes; the height of the box defines the transmission time difference between the first bit and the last bit in the frame.



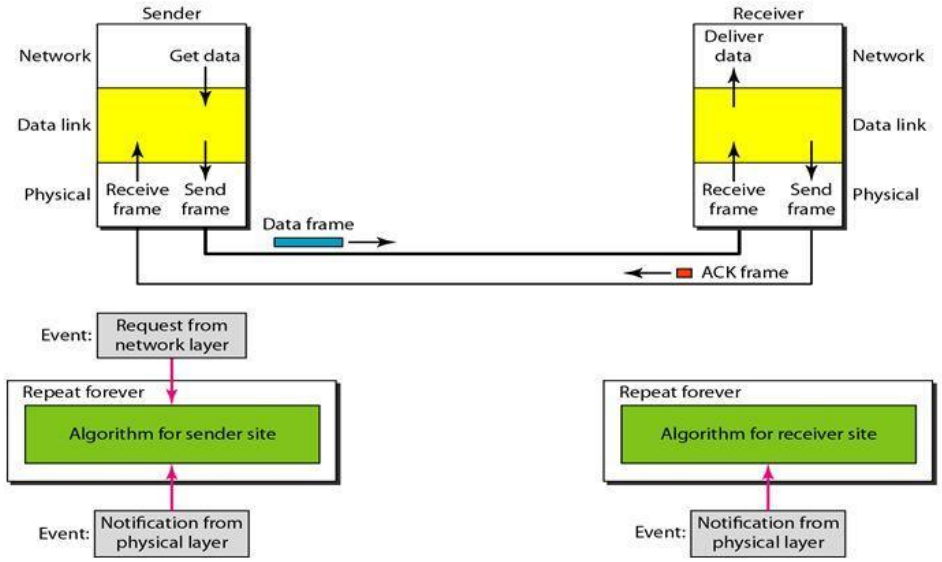
Stop-and-Wait Protocol

If data frames arrive at the receiver site faster than they can be processed, the frames must be stored until their use. Normally, the receiver does not have enough storage space, especially if it is receiving data from many sources. This may result in either the discarding of frames or denial of service. To prevent the receiver from becoming overwhelmed with frames, we somehow need to tell the sender to slow down. There must be feedback from the receiver to the sender.

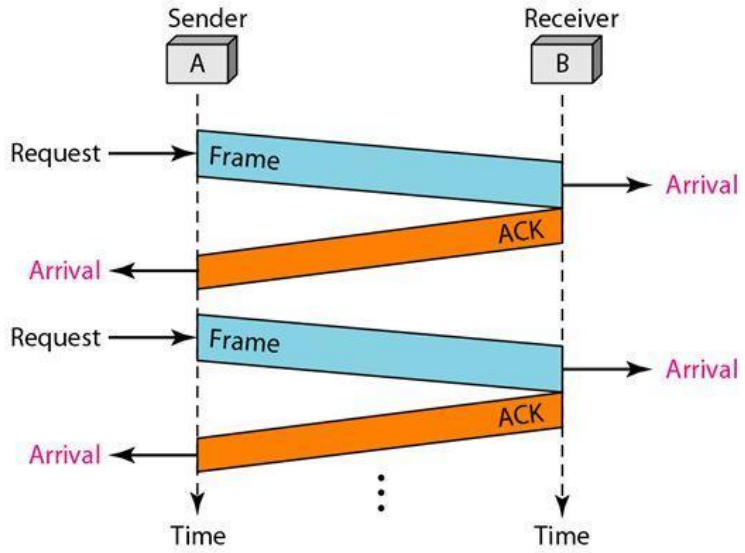
In Stop-and-Wait Protocol, the sender sends one frame, stops until it receives confirmation from the receiver (okay to go ahead), and then sends the next frame. We still have unidirectional communication for data frames, but auxiliary ACK frames (simple tokens of acknowledgment) travel from the other direction. We added flow control to the Simplest protocol.

Design

The following figure illustrates the mechanism. We can see the traffic on the forward channel (from sender to receiver) and the reverse channel. At any time, there is either one data frame on the forward channel or one ACK frame on the reverse channel. We therefore need a half-duplex link.



In this protocol, the sender sends one frame and waits for feedback from the receiver. When the ACK arrives, the sender sends the next frame. Note that sending two frames in the protocol involves the sender in four events and the receiver in two events.



Stop and Wait with ARQ Protocol

The Stop-and-Wait Automatic Repeat Request (Stop-and Wait ARQ), adds a simple error control mechanism to the Stop-and-Wait Protocol.

To detect and correct corrupted frames, we need to add redundancy bits to our data frame. When the frame arrives at the receiver site, it is checked and if it is corrupted, it is silently discarded. The detection of errors in this protocol is manifested by the silence of the receiver.

Lost frames are more difficult to handle than corrupted ones. In our previous protocols, there was no way to identify a frame. The received frame could be the correct one, or a duplicate,

or a frame out of order. The solution is to number the frames. When the receiver receives a data frame that is out of order, this means that frames were either lost or duplicated.

The corrupted and lost frames need to be resent in this protocol. If the receiver does not respond when there is an error, how can the sender know which frame to resend? To remedy this problem, the sender keeps a copy of the sent frame. At the same time, it starts a timer. If the timer expires and there is no ACK for the sent frame, the frame is resent, the copy is held, and the timer is restarted. Since the protocol uses the stop-and-wait mechanism, there is only one specific frame that needs an ACK even though several copies of the same frame can be in the network.

Since an ACK frame can also be corrupted and lost, it too needs redundancy bits and a sequence number. The ACK frame for this protocol has a sequence number field. In this protocol, the sender simply discards a corrupted ACK frame or ignores an out-of-order one.

Sequence Numbers:

In this protocol frames need to be numbered. This is done by using sequence numbers. A field is added to the data frame to hold the sequence number of that frame. One important consideration is the range of the sequence numbers. Since we want to minimize the frame size, we look for the smallest range that provides unambiguous communication.

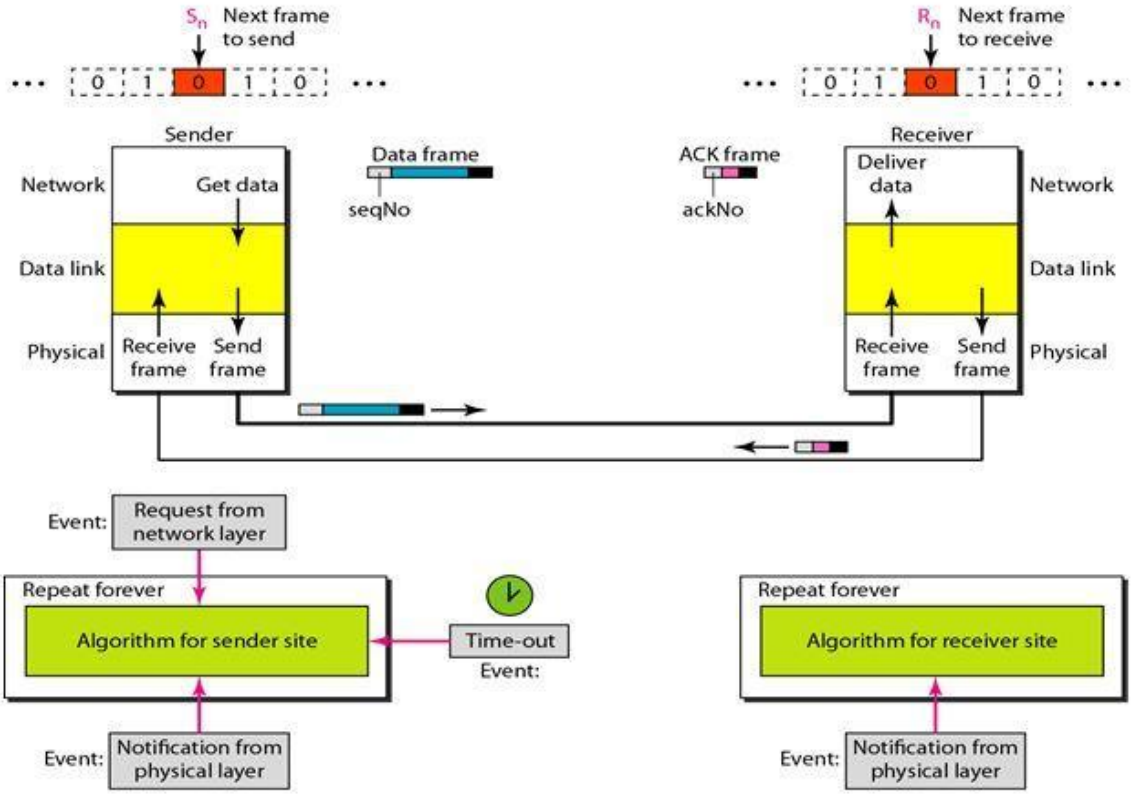
For example, if we decide that the field is m bits long, the sequence numbers start from 0, go to2m - 1, and then are repeated.

Acknowledgment Numbers:

Since the sequence numbers must be suitable for both data frames and ACK frames, we use this convention: The acknowledgment numbers always announce the sequence number of the next frame expected by the receiver. For example, if frame 0 has arrived safe and sound, the receiver sends an ACK frame with acknowledgment 1 (meaning frame 1 is expected next). If frame 1 has arrived safe and sound, the receiver sends an ACK frame with acknowledgment 0 (meaning frame 0 is expected).

Design

The following figure shows the design of the Stop-and-Wait ARQ Protocol. The sending device keeps a copy of the last frame transmitted until it receives an acknowledgment for that frame. A data frames uses a seqNo (sequence number); an ACK frame uses an ackNo (acknowledgment number). The sender has a control variable, which we call Sn (sender, next frame to send), that holds the sequence number for the next frame to be sent (0 or 1).



The receiver has a control variable, which we call Rn (receiver, next frame expected), that holds the number of the next frame expected. When a frame is sent, the value of Sn is incremented (modulo-2), which means if it is 0, it becomes 1 and vice versa. When a frame is received, the value of Rn is incremented (modulo-2), which means if it is 0, it becomes 1 and vice versa. Three events can happen at the sender site; one event can happen at the receiver site. Variable Sn points to the slot that matches the sequence number of the frame that has been sent, but not acknowledged; Rn points to the slot that matches the sequence number of the expected frame.

Efficiency

The Stop-and-Wait ARQ discussed in the previous section is very inefficient if our channel is thick and long. By thick, we mean that our channel has a large bandwidth; by long, we mean the round-trip delay is long. The product of these two is called the band width delay product.

We can think of the channel as a pipe. The bandwidth-delay product then is the volume of the pipe in bits. The pipe is always there. If we do not use it, we are inefficient. The bandwidth-delay product is a measure of the number of bits we can send out of our system while waiting for news from the receiver.

Go-Back-N ARQ Protocol

Go-Back-N Automatic Repeat Request (ARQ) Protocol

To improve the efficiency of transmission (filling the pipe), multiple frames must be in transition while waiting for acknowledgment. In Go-Back-N Automatic Repeat Request, we can send several frames before receiving acknowledgments; we keep a copy of these frames until the acknowledgments arrive.

Sequence Numbers

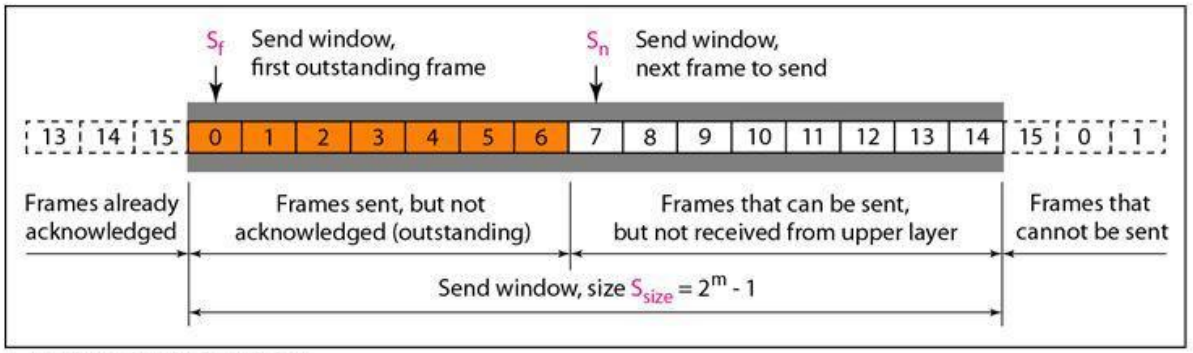
Frames from a sending station are numbered sequentially. If the header of the frame allows m bits for the sequence number, the sequence numbers range from 0 to 2^m- 1. For example, if m is 4, the only sequence numbers are 0 through 15 inclusive. However, we can repeat the sequence. So the sequence numbers are
0, 1,2,3,4,5,6, 7,8,9, 10, 11, 12, 13, 14, 15,0, 1,2,3,4,5,6,7,8,9,10, 11, ...

In other words, the sequence numbers are modulo-2 m.

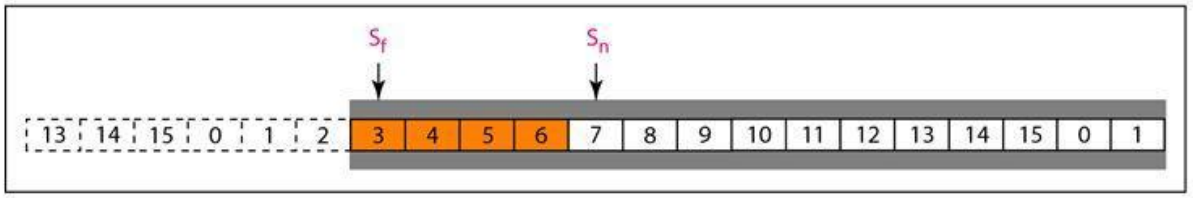
Sliding Window

In this protocol (and the next), the sliding window is an abstract concept that defines the range of sequence numbers that is the concern of the sender and receiver. In other words, the sender and receiver need to deal with only part of the possible sequence numbers. The range which is the concern of the sender is called the send sliding window; the range that is the concern of the receiver is called the receiver sliding window.

The send window is an imaginary box covering the sequence numbers of the data frames which can be in transit. In each window position, some of these sequence numbers define the frames that have been sent; others define those that can be sent. The maximum size of the window is $2^m - 1$. The size can be fixed and set to the maximum value. The following figure shows a sliding window of size 15 (m =4).



a. Send window before sliding



b. Send window after sliding

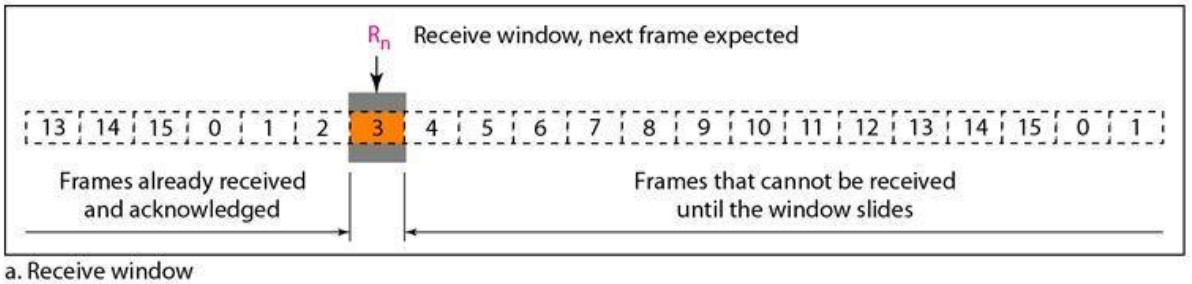
The window at any time divides the possible sequence numbers into four regions. The first region, from the far left to the left wall of the window, defines the sequence numbers belonging to frames that are already acknowledged. The sender does not worry about these frames and keeps no copies of them.

The second region, colored in the above figure- a, defines the range of sequence numbers belonging to the frames that are sent and have an unknown status. The sender needs to wait to find out if these frames have been received or were lost. We call these outstanding frames. The third range, white in the figure, defines the range of sequence numbers for frames that can be sent; however, the corresponding data packets have not yet been received from the network layer. Finally, the fourth region defines sequence numbers that cannot be used until the window slides, as we see next.

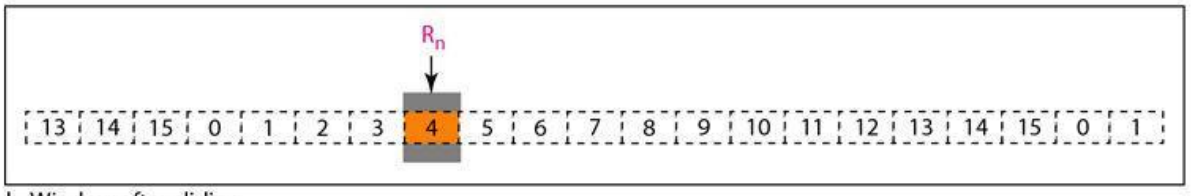
The window itself is an abstraction; three variables define its size and location at any time. We call these variables Sf(send window, the first outstanding frame), Sn (send window, the next frame to be sent), and Ssize (send window, size). The variable Sf defines the sequence number of the first (oldest) outstanding frame. The variable Sn holds the sequence number that will be assigned to the next frame to be sent. Finally, the variable Ssize defines the size of the window, which is fixed in our protocol.

The Figure-b shows how a send window can slide one or more slots to the right when an acknowledgment arrives from the other end. The acknowledgments in this protocol are cumulative, meaning that more than one frame can be acknowledged by an ACK frame. In in the figure-b, frames 0, 1, and 2 are acknowledged, so the window has slid to the right three slots. Note that the value of Sf is 3 because frame 3 is now the first outstanding frame.

The receive window makes sure that the correct data frames are received and that the correct acknowledgments are sent. The size of the receive window is always I. The receiver is always looking for the arrival of a specific frame. Any frame arriving out of order is discarded and needs to be resent. The following figure shows the receive window.



a. Receive window



b. Window after sliding

Note that we need only one variable Rn (receive window, next frame expected) to define this abstraction. The sequence numbers to the left of the window belong to the frames already

received and acknowledged; the sequence numbers to the right of this window define the frames that cannot be received. Any received frame with a sequence number in these two regions is discarded. Only a frame with a sequence number matching the value of Rn is accepted and acknowledged. The receive window also slides, but only one slot at a time. When a correct frame is received (and a frame is received only one at a time), the window slides.

Timers:

Although there can be a timer for each frame that is sent, in this protocol we use only one. The reason is that the timer for the first outstanding frame always expires first; we send all outstanding frames when this timer expires.

Acknowledgment:

The receiver sends a positive acknowledgment if a frame has arrived safe and sound and in order. If a frame is damaged or is received out of order, the receiver is silent and will discard all subsequent frames until it receives the one it is expecting. The silence of the receiver causes the timer of the unacknowledged frame at the sender site to expire.

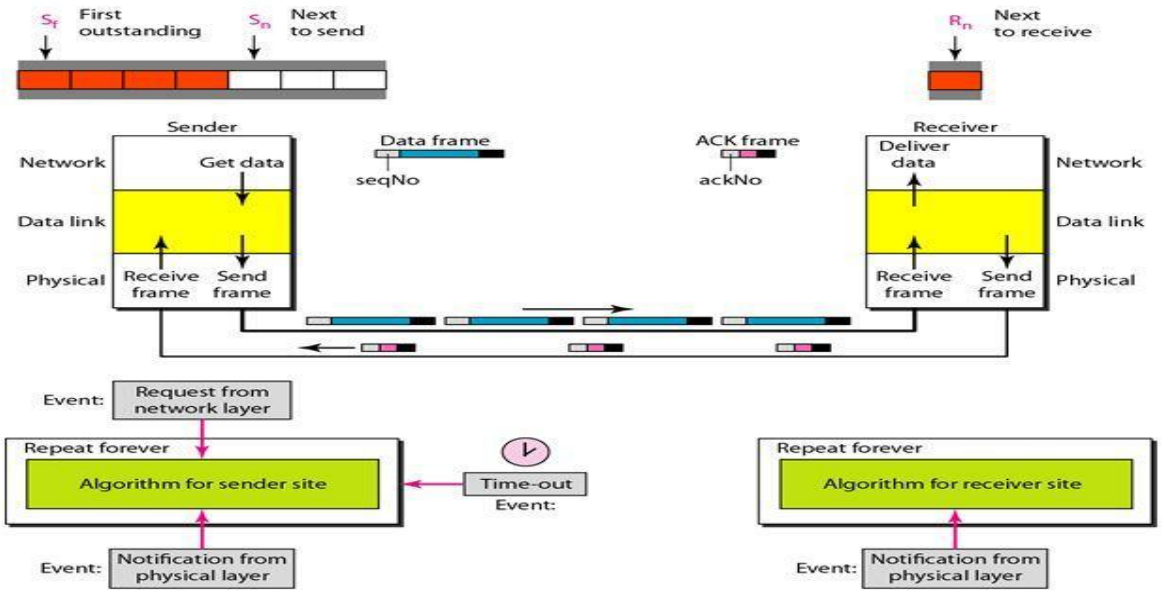
This, in turn, causes the sender to go back and resend all frames, beginning with the one with the expired timer. The receiver does not have to acknowledge each frame received. It can send one cumulative acknowledgment for several frames.

Resending a Frame:

When the timer expires, the sender resends all outstanding frames. For example, suppose the sender has already sent frame 6, but the timer for frame 3 expires. This means that frame 3 has not been acknowledged; the sender goes back and sends frames 3, 4, 5, and 6 again. That is why the protocol is called Go-Back-N ARQ.

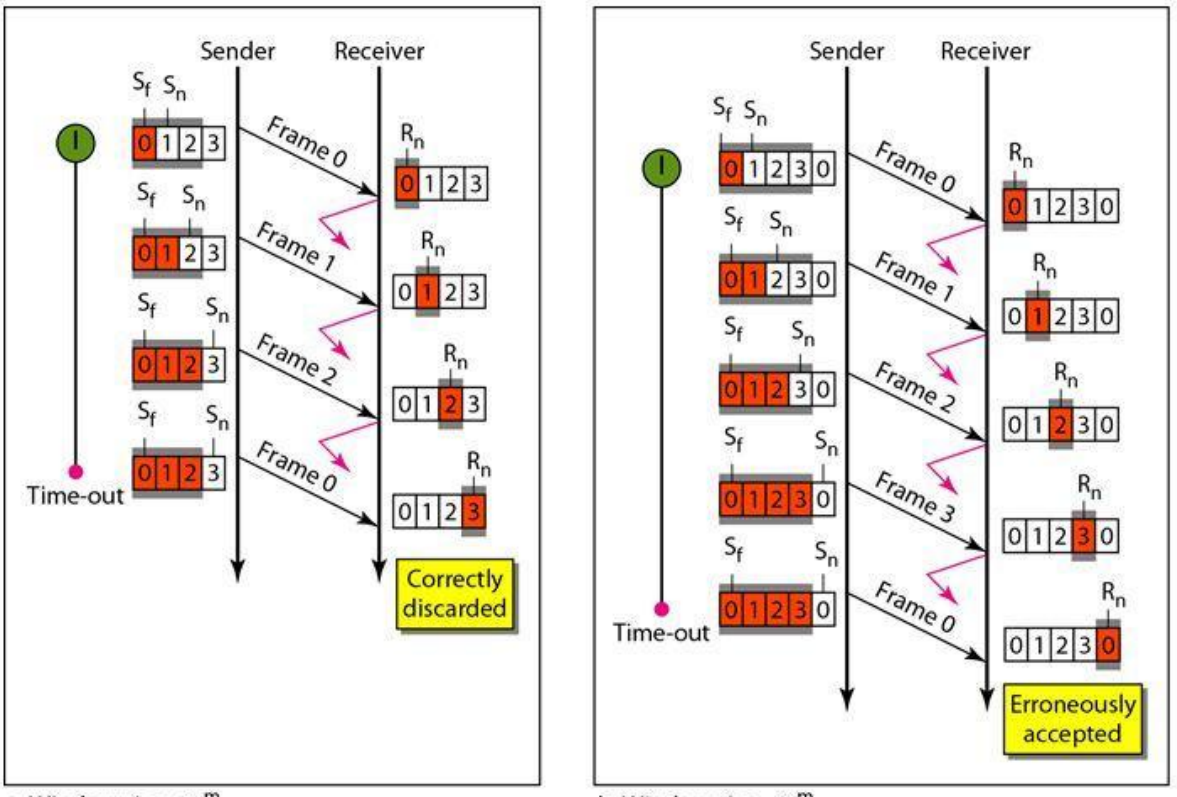
Design:

The following figure shows the design for this protocol. As we can see, multiple frames can be in transit in the forward direction, and multiple acknowledgments in the reverse direction. The idea is similar to Stop-and-Wait ARQ; the difference is that the send window allows us to have as many frames in transition as there are slots in the send window.



Send Window Size:

We can now show why the size of the send window must be less than 2m. As an example, we choose m =2, which means the size of the window can be 2m - 1, or 3. The following figure compares a window size of 3 against a window size of 4. If the size of the window is 3 (less than 22) and all three acknowledgments are lost, the frame timer expires and all three frames are resent. The receiver is now expecting frame 3, not frame 0, so the duplicate frame is correctly discarded. On the other hand, if the size of the window is 4 (equal to 22) and all acknowledgments are lost, the sender will send a duplicate of frame 0. However, this time the window of the receiver expects to receive frame 0, so it accepts frame 0, not as a duplicate, but as the first frame in the next cycle. This is an error.



a. Window size < 2^m

b. Window size = 2^m

Selective Repeat ARQ Protocol

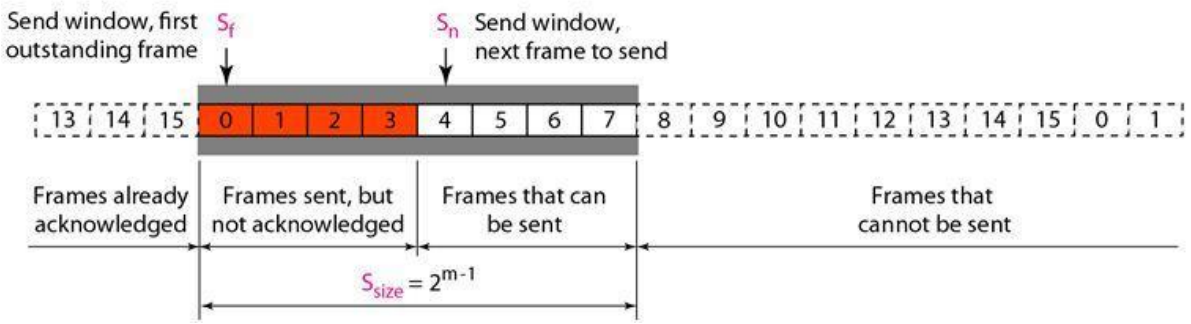
Selective Repeat Automatic Repeat Request (ARQ) Protocol

Go-Back-N ARQ simplifies the process at the receiver site. The receiver keeps track of only one variable, and there is no need to buffer out-of-order frames; they are simply discarded. However, this protocol is very inefficient for a noisy link.

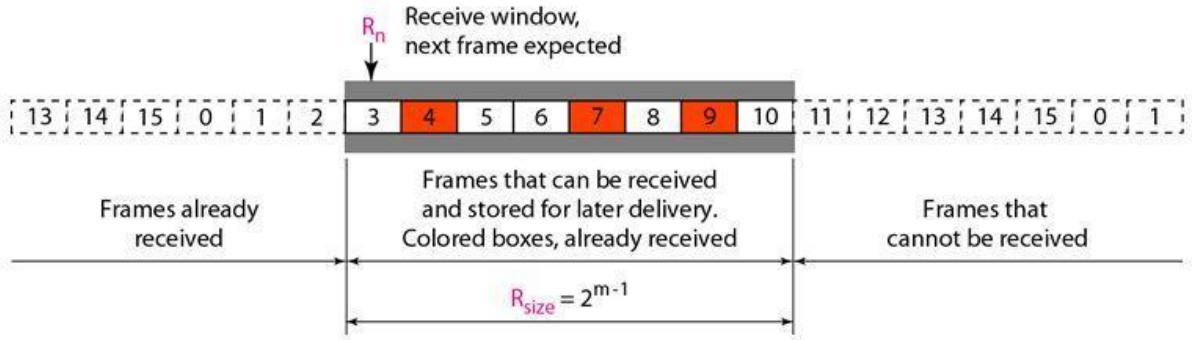
In a noisy link a frame has a higher probability of damage, which means the resending of multiple frames. This resending uses up the bandwidth and slows down the transmission. For noisy links, there is another mechanism that does not resend N frames when just one frame is damaged; only the damaged frame is resent. This mechanism is called Selective Repeat ARQ. It is more efficient for noisy links, but the processing at the receiver is more complex.

The Selective Repeat Protocol also uses two windows: a send window and a receive window. However, there are differences between the windows in this protocol and the ones in Go-Back-N. First, the size of the send window is much smaller; it is $2^m - 1$.

The send window maximum size can be $2^m - 1$. The smaller window size means less efficiency in filling the pipe, but the fact that there are fewer duplicate frames can compensate for this.



The Selective Repeat Protocol allows as many frames as the size of the receive window to arrive out of order and be kept until there is a set of in-order frames to be delivered to the network layer. Because the sizes of the send window and receive window are the same, all the frames in the send frame can arrive out of order and be stored until they can be delivered. We need, however, to mention that the receiver never delivers packets out of order to the network layer.



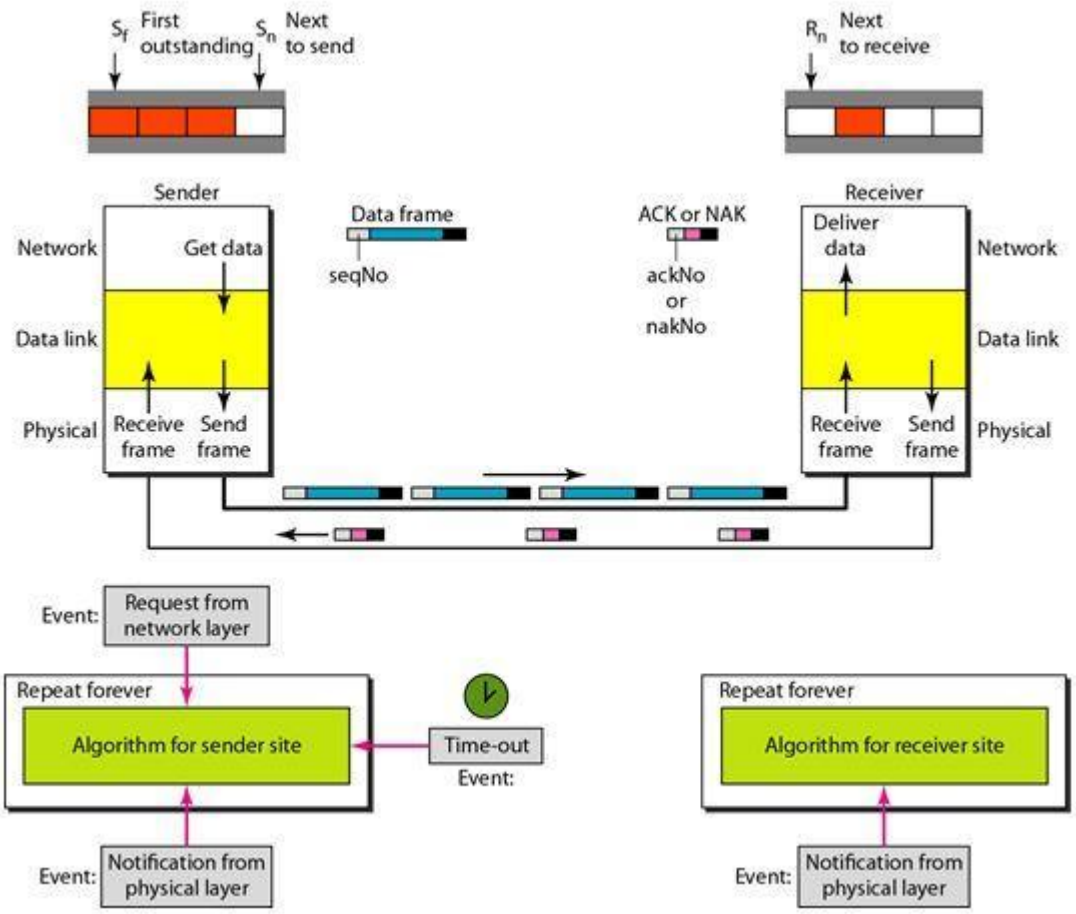
The above figure shows the receive window in this protocol. Those slots inside the window that are colored define frames that have arrived out of order and are waiting for their neighbours to arrive before delivery to the network layer.

Design:

The design in this case is to some extent similar to the one we described for the Go Back-N, but more complicated, as shown in the following figure.

Window Sizes:

We can now show why the size of the sender and receiver windows must be at most one half of 2m. For an example, we choose m = 2, which means the size of the window is $2^m/2$, or 2. The following figure compares a window size of 2 with a window size of 3.



If the size of the window is 2 and all acknowledgments are lost, the timer for frame 0 expires and frame 0 is resent. However, the window of the receiver is now expecting frame 2, not frame 0, so this duplicate frame is correctly discarded.

When the size of the window is 3 and all acknowledgments are lost, the sender sends a duplicate of frame 0. However, this time, the window of the receiver expects to receive frame 0 (0 is part of the window), so it accepts frame 0, not as a duplicate, but as the first frame in the next cycle. This is clearly an error.

What is piggybacking?

• In all practical situations, the transmission of data needs to be bi-directional. This is called full-duplex transmission.

• We can achieve this full duplex transmission *i.e.* by having two separate channels-one for forward data transfer and the other for separate transfer *i.e.* for acknowledgements.

• A better solution would be to use each channel (forward & reverse) to transmit frames both ways, with both channels having the same capacity. If A and B are two users. Then the data frames from A to Bare intermixed with the acknowledgements from A to B.

• One more improvement that can be made is piggybacking. The concept is explained as follows:

In two way communication, Whenever a data frame is received, the received waits and does not send the control frame (acknowledgement) back to the sender immediately.

The receiver waits until its network layer passes in the next data packet. The delayed acknowledgement is then attached to this outgoing data frame.

This technique of temporarily delaying the acknowledgement so that it can be hooked with the next outgoing data frame is known as piggybacking.

• The major advantage of piggybacking is better use of available channel bandwidth.

• The disadvantages of piggybacking are:

1. Additional complexity.

2. If the data link layer waits too long before transmitting the acknowledgment, then retransmission of the frame would take place.

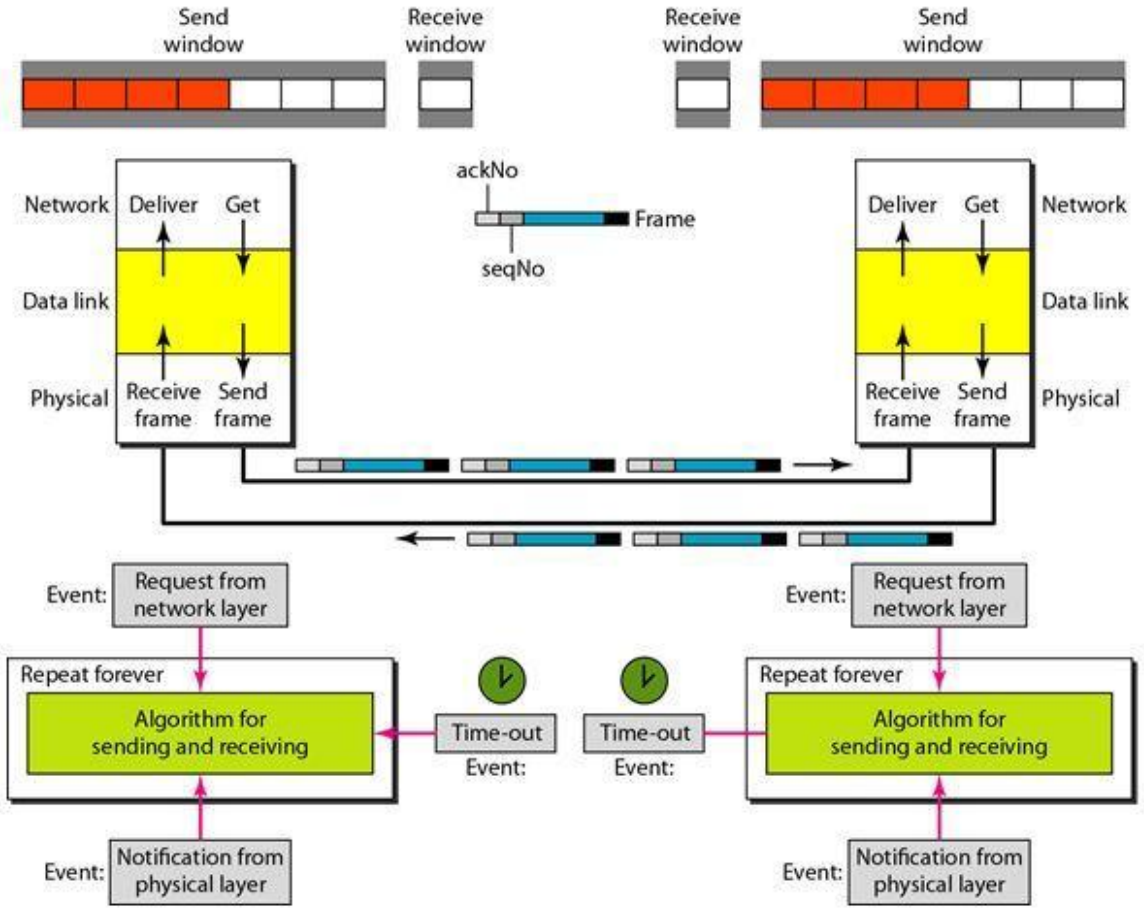
Piggybacking Protocol

In some protocols data frames flow in only one direction although control information such as ACK and NAK frames can travel in the other direction. In real life, data frames are normally flowing in both directions, from node A to node B and from node B to node A. This means that the control information also needs to flow in both directions.

A technique called piggybacking is used to improve the efficiency of the bidirectional protocols.

When a frame is carrying data from A to B, it can also carry control information about arrived (or lost) frames from B; when a frame is carrying data from B to A, it can also carry control information about the arrived (or lost) frames from A.

The design for a Go-Back-N ARQ using piggybacking is in the following figure.



Note that each node now has two windows: one send window and one receive window. Both also need to use a timer. Both are involved in three types of events: request, arrival, and time-out. However, the arrival event here is complicated; when a frame arrives, the site needs to handle control information as well as the frame itself. Both of these concerns must be taken care of in one event, the arrival event. The request event uses only the send window at each site; the arrival event needs to use both windows.

An important point about piggybacking is that both sites must use the same algorithm. This algorithm is complicated because it needs to combine two arrival events into one.

Flow Control

- It is a set of procedures that tells the sender how much data it can transmit before the data overwhelms the receiver.
- The receiving device has limited speed and limited memory to store the data. Therefore, the receiving device must be able to inform the sending device to stop the transmission temporarily before the limits are reached.
- It requires a buffer, a block of memory for storing the information until they are processed.

Two methods have been developed to control the flow of data:

- Stop-and-wait

- Sliding window

Stop-and-wait

- In the Stop-and-wait method, the sender waits for an acknowledgement after every frame it sends.
- When acknowledgement is received, then only next frame is sent. The process of alternately sending and waiting of a frame continues until the sender transmits the EOT (End of transmission) frame.

Advantage of Stop-and-wait

The Stop-and-wait method is simple as each frame is checked and acknowledged before the next frame is sent.

Disadvantage of Stop-and-wait

Stop-and-wait technique is inefficient to use as each frame must travel across all the way to the receiver, and an acknowledgement travels all the way before the next frame is sent. Each frame sent and received uses the entire time needed to traverse the link.

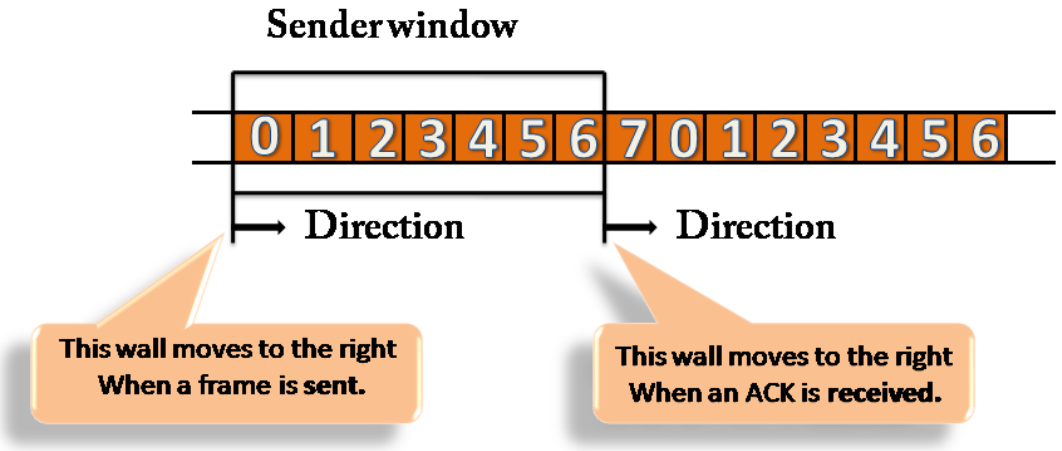
Sliding Window

- The Sliding Window is a method of flow control in which a sender can transmit the several frames before getting an acknowledgement.
- In Sliding Window Control, multiple frames can be sent one after the another due to which capacity of the communication channel can be utilized efficiently.
- A single ACK acknowledge multiple frames.
- Sliding Window refers to imaginary boxes at both the sender and receiver end.
- The window can hold the frames at either end, and it provides the upper limit on the number of frames that can be transmitted before the acknowledgement.
- Frames can be acknowledged even when the window is not completely filled.
- The window has a specific size in which they are numbered as modulo-n means that they are numbered from 0 to n-1. For example, if n = 8, the frames are numbered from 0,1,2,3,4,5,6,7,0,1,2,3,4,5,6,7,0,1.....
- The size of the window is represented as n-1. Therefore, maximum n-1 frames can be sent before acknowledgement.
- When the receiver sends the ACK, it includes the number of the next frame that it wants to receive. For example, to acknowledge the string of frames ending with frame number 4, the receiver will send the ACK containing the number 5. When the sender sees the ACK with the number 5, it got to know that the frames from 0 through 4 have been received.

Sender Window

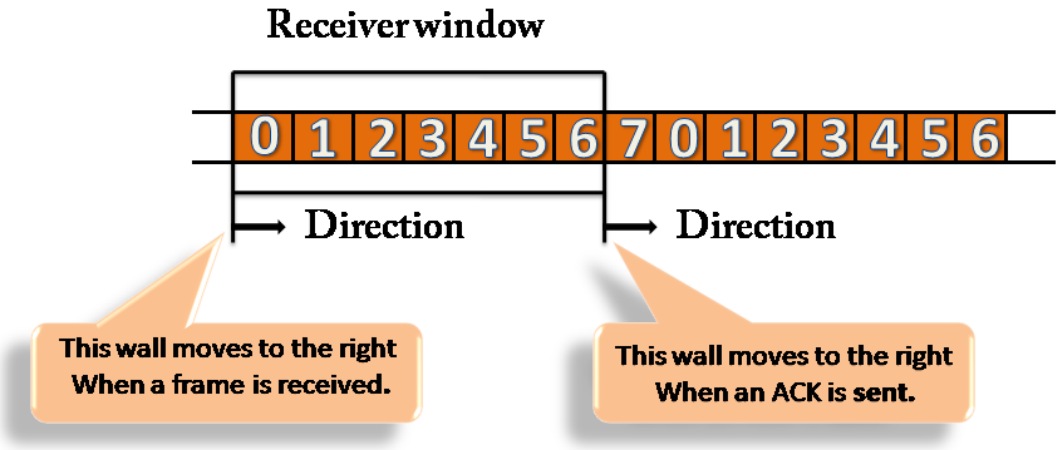
- At the beginning of a transmission, the sender window contains n-1 frames, and when they are sent out, the left boundary moves inward shrinking the size of the window. For example, if the size of the window is w if three frames are sent out, then the number of frames left out in the sender window is w-3.
- Once the ACK has arrived, then the sender window expands to the number which will be equal to the number of frames acknowledged by ACK.
- For example, the size of the window is 7, and if frames 0 through 4 have been sent out and no acknowledgement has arrived, then the sender window contains only two frames, i.e., 5 and 6. Now, if ACK has arrived with a number 4 which means that 0 through 3 frames have arrived

undamaged and the sender window is expanded to include the next four frames. Therefore, the sender window contains six frames (5,6,7,0,1,2).



Receiver Window

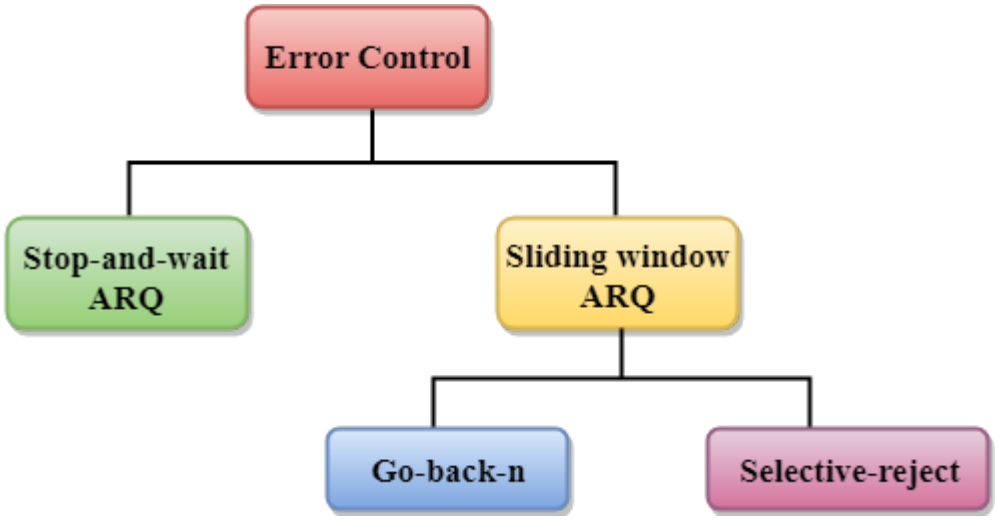
- At the beginning of transmission, the receiver window does not contain n frames, but it contains n-1 spaces for frames.
- When the new frame arrives, the size of the window shrinks.
- The receiver window does not represent the number of frames received, but it represents the number of frames that can be received before an ACK is sent. For example, the size of the window is w, if three frames are received then the number of spaces available in the window is (w-3).
- Once the acknowledgement is sent, the receiver window expands by the number equal to the number of frames acknowledged.
- Suppose the size of the window is 7 means that the receiver window contains seven spaces for seven frames. If the one frame is received, then the receiver window shrinks and moving the boundary from 0 to 1. In this way, window shrinks one by one, so window now contains the six spaces. If frames from 0 through 4 have sent, then the window contains two spaces before an acknowledgement is sent.



Error Control

Error Control is a technique of error detection and retransmission.

Categories of Error Control:



Stop-and-wait ARQ

Stop-and-wait ARQ is a technique used to retransmit the data in case of damaged or lost frames.

This technique works on the principle that the sender will not transmit the next frame until it receives the acknowledgement of the last transmitted frame.

Four features are required for the retransmission:

- The sending device keeps a copy of the last transmitted frame until the acknowledgement is received. Keeping the copy allows the sender to retransmit the data if the frame is not received correctly.
- Both the data frames and the ACK frames are numbered alternately 0 and 1 so that they can be identified individually. Suppose data 1 frame acknowledges the data 0 frame means that the data 0 frame has been arrived correctly and expects to receive data 1 frame.
- If an error occurs in the last transmitted frame, then the receiver sends the NAK frame which is not numbered. On receiving the NAK frame, sender retransmits the data.
- It works with the timer. If the acknowledgement is not received within the allotted time, then the sender assumes that the frame is lost during the transmission, so it will retransmit the frame.

Two possibilities of the retransmission:

- **Damaged Frame:** When the receiver receives a damaged frame, i.e., the frame contains an error, then it returns the NAK frame. For example, when the data 0 frame is sent, and then the receiver sends the ACK 1 frame means that the data 0 has arrived correctly, and transmits the data 1 frame. The sender transmits the next frame: data 1. It reaches undamaged, and the receiver returns ACK 0. The sender transmits the next frame: data 0. The receiver reports an error and returns the NAK frame. The sender retransmits the data 0 frame.
- **Lost Frame:** Sender is equipped with the timer and starts when the frame is transmitted. Sometimes the frame has not arrived at the receiving end so that it can be acknowledged neither positively nor negatively. The sender waits for acknowledgement until the timer goes off. If the timer goes off, it retransmits the last transmitted frame.

Sliding Window ARQ

SlidingWindow ARQ is a technique used for continuous transmission error control.

Three Features used for retransmission:

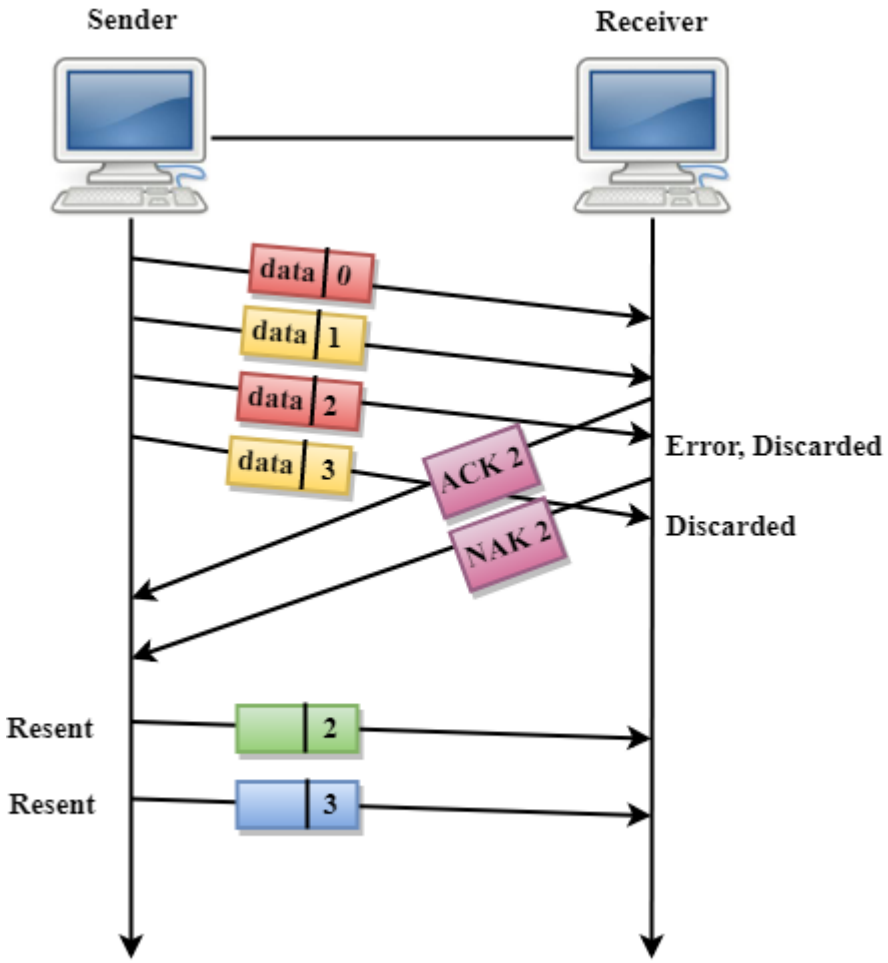
- In this case, the sender keeps the copies of all the transmitted frames until they have been acknowledged. Suppose the frames from 0 through 4 have been transmitted, and the last acknowledgement was for frame 2, the sender has to keep the copies of frames 3 and 4 until they receive correctly.
- The receiver can send either NAK or ACK depending on the conditions. The NAK frame tells the sender that the data have been received damaged. Since the sliding window is a continuous transmission mechanism, both ACK and NAK must be numbered for the identification of a frame. The ACK frame consists of a number that represents the next frame which the receiver expects to receive. The NAK frame consists of a number that represents the damaged frame.
- The sliding window ARQ is equipped with the timer to handle the lost acknowledgements. Suppose then n-1 frames have been sent before receiving any acknowledgement. The sender waits for the acknowledgement, so it starts the timer and waits before sending any more. If the allotted time runs out, the sender retransmits one or all the frames depending upon the protocol used.

Two protocols used in sliding window ARQ:

- **Go-Back-n ARQ:** In Go-Back-N ARQ protocol, if one frame is lost or damaged, then it retransmits all the frames after which it does not receive the positive ACK.

Three possibilities can occur for retransmission:

- **Damaged Frame:** When the frame is damaged, then the receiver sends a NAK frame.



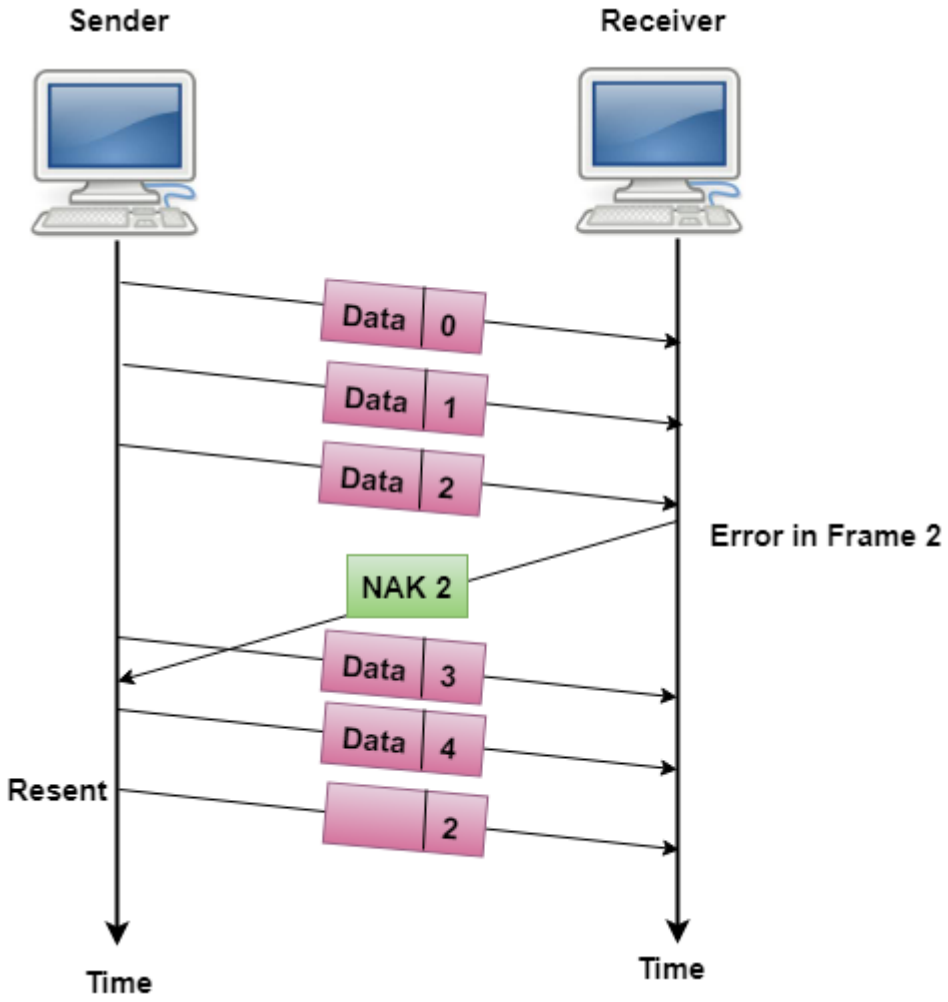
In the above figure, three frames have been transmitted before an error discovered in the third frame. In this case, ACK 2 has been returned telling that the frames 0,1 have been received successfully without any error. The receiver discovers the error in data 2 frame, so it returns the NAK 2 frame. The frame 3 is also discarded as it is transmitted after the damaged frame. Therefore, the sender retransmits the frames 2,3.

- **Lost Data Frame:** In Sliding window protocols, data frames are sent sequentially. If any of the frames is lost, then the next frame arrive at the receiver is out of sequence. The receiver checks the sequence number of each of the frame, discovers the frame that has been skipped, and returns the NAK for the missing frame. The sending device retransmits the frame indicated by NAK as well as the frames transmitted after the lost frame.
- **Lost Acknowledgement:** The sender can send as many frames as the windows allow before waiting for any acknowledgement. Once the limit of the window is reached, the sender has no more frames to send; it must wait for the acknowledgement. If the acknowledgement is lost, then the sender could wait forever. To avoid such situation, the sender is equipped with the timer that starts counting whenever the window capacity is reached. If the acknowledgement has not been received within the time limit, then the sender retransmits the frame since the last ACK.

Selective-Reject ARQ

- Selective-Reject ARQ technique is more efficient than Go-Back-n ARQ.
- In this technique, only those frames are retransmitted for which negative acknowledgement (NAK) has been received.
- The receiver storage buffer keeps all the damaged frames on hold until the frame in error is correctly received.

- The receiver must have an appropriate logic for reinserting the frames in a correct order.
- The sender must consist of a searching mechanism that selects only the requested frame for retransmission.



Difference Between Go-Back-N and Selective Repeat Protocol

Both Go-Back-N Protocol and Selective Repeat Protocol are the types of sliding window protocols.
The main difference between these two protocols is that after finding the suspect or

damage in sent frames go-back-n protocol re-transmits all the frames whereas selective repeat protocol re-transmits only that frame which is damaged.
Now, we shall see the difference between them:

S.NO	Go-Back-N Protocol	Selective Repeat Protocol
1.	In Go-Back-N Protocol, if the sent frame are find suspected then all the frames are re-transmitted from the lost packet to the last packet transmitted.	In selective Repeat protocol, only those frames are re-transmitted which are found suspected.
2.	Sender window size of Go-Back-N Protocol is N.	Sender window size of selective Repeat protocol is also N.
3.	Receiver window size of Go-Back-N Protocol is 1.	Receiver window size of selective Repeat protocol is N.
4.	Go-Back-N Protocol is less complex.	Selective Repeat protocol is more complex.
5.	In Go-Back-N Protocol, neither sender nor at receiver need sorting.	In selective Repeat protocol, receiver side needs sorting to sort the frames.
6.	In Go-Back-N Protocol, type of Acknowledgement is cumulative.	In selective Repeat protocol, type of Acknowledgement is individual.
7.	In Go-Back-N Protocol, Out-of-Order packets are NOT Accepted (discarded) and the entire window is re-transmitted.	In selective Repeat protocol, Out-of-Order packets are Accepted.
8.	In Go-Back-N Protocol, if Receives receives a corrupt packet, then also, the entire window is re-transmitted.	In selective Repeat protocol, if Receives receives a corrupt packet, it immediately sends a negative acknowledgement and hence only the selective packet is retransmitted.
9.	Efficiency of Go-Back-N Protocol is N/(1+2*a)	Efficiency of selective Repeat protocol is also N/(1+2*a)

Following are the important differences between Go-Back-N and Selective Repeat Protocols.

Sr. No.	Key	Go-Back-N	Selective Repeat
1	Definition	In Go-Back-N if a sent frame is found suspected or damaged then all the frames are retransmitted till the last packet.	In Selective Repeat, only the suspected or damaged frames are retransmitted.
2	Sender Window Size	Sender Window is of size N.	Sender Window size is same as N.
3	Receiver Window Size	Receiver Window Size is 1.	Receiver Window Size is N.
4	Complexity	Go-Back-N is easier to implement.	In Selective Repeat, receiver window needs to sort the frames.
5	Efficiency	Efficiency of Go-Back-N = N / (1 + 2a).	Efficiency of Selective Repeat = N / (1 + 2a).
6	Acknowledgement	Acknowledgement type is cumulative.	Acknowledgement type is individual.

Multiple access protocol- ALOHA, CSMA, CSMA/CA and CSMA/CD

Data Link Layer

The data link layer is used in a computer network to transmit the data between two devices or nodes. It divides the layer into parts such as **data link control** and the **multiple access resolution/protocol**. The upper layer has the responsibility to flow control and the error control in the data link layer, and hence it is termed as **logical of data link control**. Whereas the lower sub-layer is used to handle and reduce the collision or multiple access on a channel. Hence it is termed as **media access control** or the multiple access resolutions.

Data Link Control

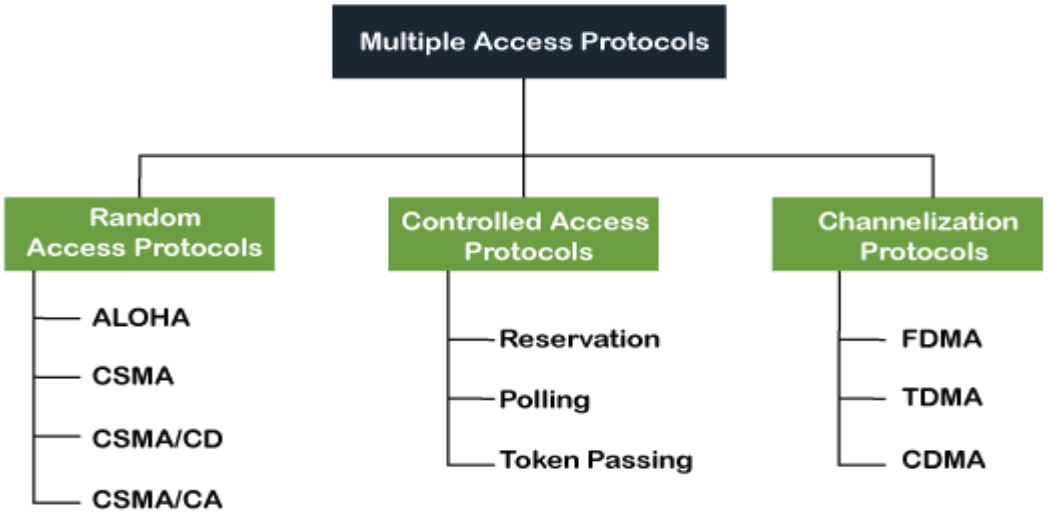
A data link control is a reliable channel for transmitting data over a dedicated link using various techniques such as framing, error control and flow control of data packets in the computer network.

What is a multiple access protocol?

When a sender and receiver have a dedicated link to transmit data packets, the data link control is enough to handle the channel. Suppose there is no dedicated path to communicate or transfer the data between two devices. In that case, multiple stations access the channel and simultaneously transmits the data over the channel. It may create collision and cross talk. Hence, the multiple access protocol is required to reduce the collision and avoid crosstalk between the channels.

For example, suppose that there is a classroom full of students. When a teacher asks a question, all the students (small channels) in the class start answering the question at the same time (transferring the data simultaneously). All the students respond at the same time due to which data is overlap or data lost. Therefore it is the responsibility of a teacher (multiple access protocol) to manage the students and make them one answer.

Following are the types of multiple access protocol that is subdivided into the different process as:



A. Random Access Protocol

In this protocol, all the station has the equal priority to send the data over a channel. In random access protocol, one or more stations cannot depend on another station nor any station control another station. Depending on the channel's state (idle or busy), each station transmits the data frame. However, if more than one station sends the data over a channel, there may be a collision or data conflict. Due to the collision, the data frame packets may be lost or changed. And hence, it does not receive by the receiver end.

Following are the different methods of random-access protocols for broadcasting frames on the channel.

- Aloha
- CSMA

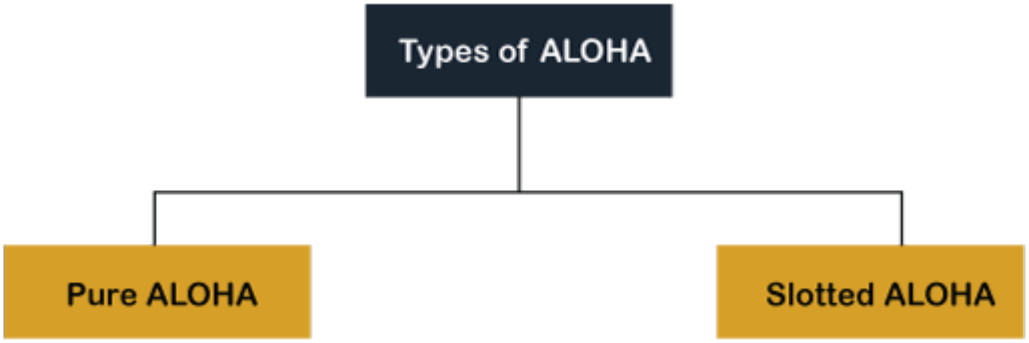
- CSMA/CD
- CSMA/CA

ALOHA Random Access Protocol

It is designed for wireless LAN (Local Area Network) but can also be used in a shared medium to transmit data. Using this method, any station can transmit data across a network simultaneously when a data frameset is available for transmission.

Aloha Rules

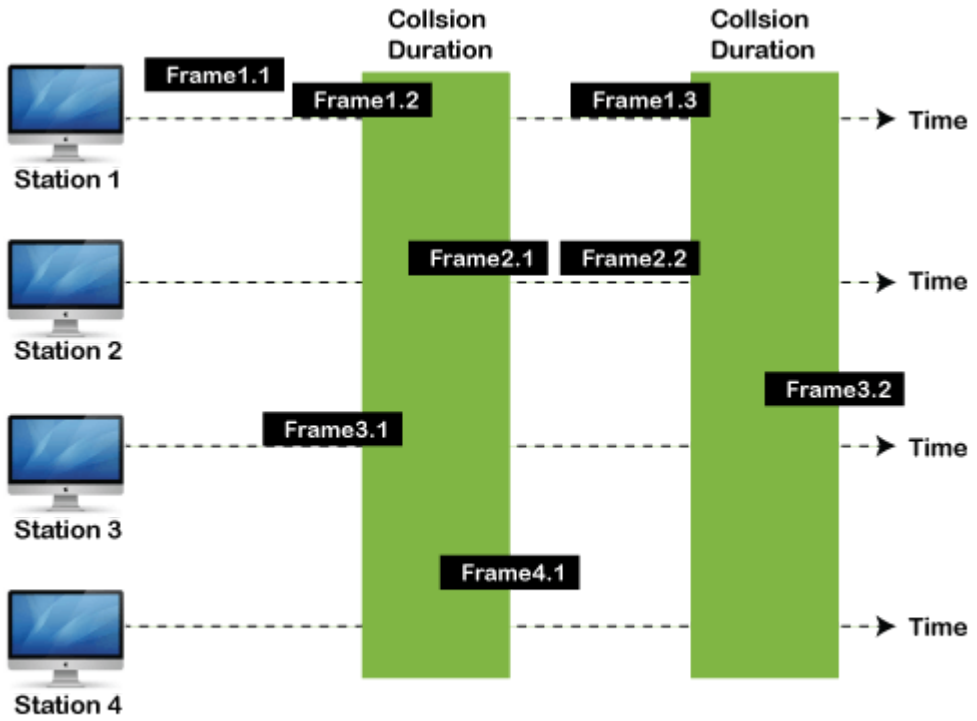
1. Any station can transmit data to a channel at any time.
2. It does not require any carrier sensing.
3. Collision and data frames may be lost during the transmission of data through multiple stations.
4. Acknowledgment of the frames exists in Aloha. Hence, there is no collision detection.
5. It requires retransmission of data after some random amount of time.



Pure Aloha

Whenever data is available for sending over a channel at stations, we use Pure Aloha. In pure Aloha, when each station transmits data to a channel without checking whether the channel is idle or not, the chances of collision may occur, and the data frame can be lost. When any station transmits the data frame to a channel, the pure Aloha waits for the receiver's acknowledgment. If it does not acknowledge the receiver end within the specified time, the station waits for a random amount of time, called the backoff time (Tb). And the station may assume the frame has been lost or destroyed. Therefore, it retransmits the frame until all the data are successfully transmitted to the receiver.

1. The total vulnerable time of pure Aloha is 2 * Tfr.
2. Maximum throughput occurs when G = 1/ 2 that is 18.4%.
3. Successful transmission of data frame is S = G * e ^ - 2 G.



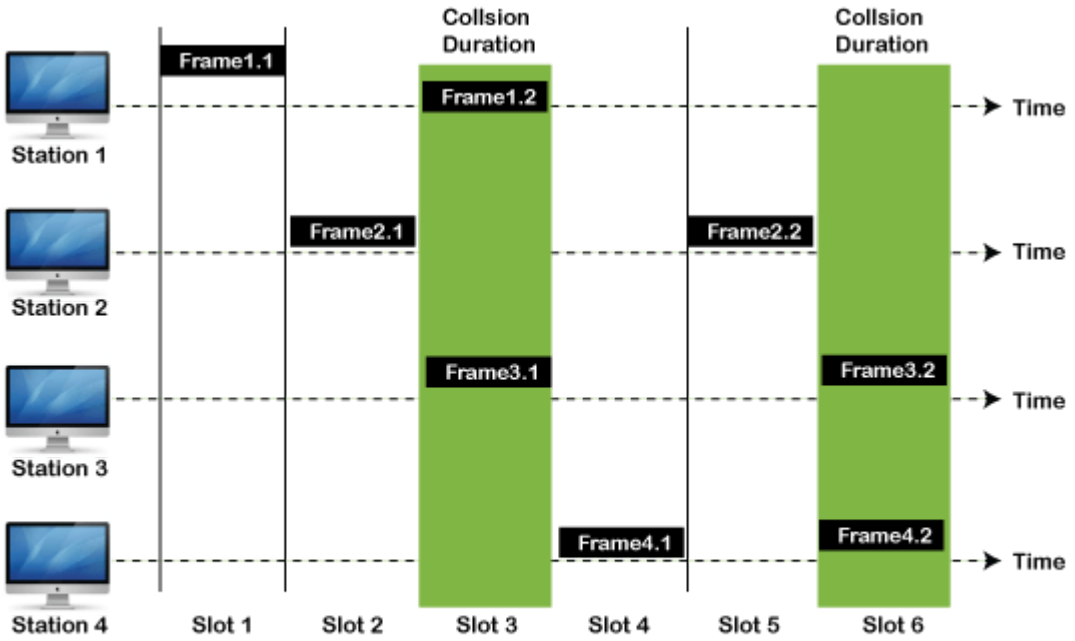
Frames in Pure ALOHA

As we can see in the figure above, there are four stations for accessing a shared channel and transmitting data frames. Some frames collide because most stations send their frames at the same time. Only two frames, frame 1.1 and frame 2.2, are successfully transmitted to the receiver end. At the same time, other frames are lost or destroyed. Whenever two frames fall on a shared channel simultaneously, collisions can occur, and both will suffer damage. If the new frame's first bit enters the channel before finishing the last bit of the second frame. Both frames are completely finished, and both stations must retransmit the data frame.

Slotted Aloha

The slotted Aloha is designed to overcome the pure Aloha's efficiency because pure Aloha has a very high possibility of frame hitting. In slotted Aloha, the shared channel is divided into a fixed time interval called **slots**. So that, if a station wants to send a frame to a shared channel, the frame can only be sent at the beginning of the slot, and only one frame is allowed to be sent to each slot. And if the stations are unable to send data to the beginning of the slot, the station will have to wait until the beginning of the slot for the next time. However, the possibility of a collision remains when trying to send a frame at the beginning of two or more station time slot.

1. Maximum throughput occurs in the slotted Aloha when G = 1 that is 37%.
2. The probability of successfully transmitting the data frame in the slotted Aloha is S = G * e ^ - 2 G.
3. The total vulnerable time required in slotted Aloha is Tfr.



Frames in Slotted ALOHA

CSMA (Carrier Sense Multiple Access)

It is a **carrier sense multiple access** based on media access protocol to sense the traffic on a channel (idle or busy) before transmitting the data. It means that if the channel is idle, the station can send data to the channel. Otherwise, it must wait until the channel becomes idle. Hence, it reduces the chances of a collision on a transmission medium.

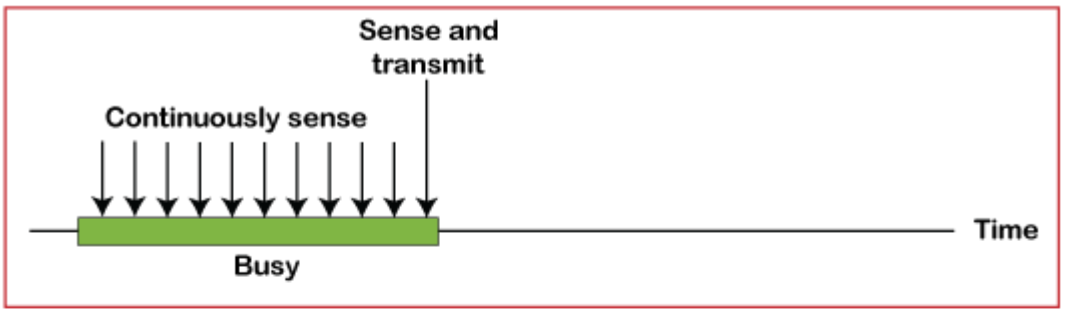
CSMA Access Modes

1-Persistent: In the 1-Persistent mode of CSMA that defines each node, first sense the shared channel and if the channel is idle, it immediately sends the data. Else it must wait and keep track of the status of the channel to be idle and broadcast the frame unconditionally as soon as the channel is idle.

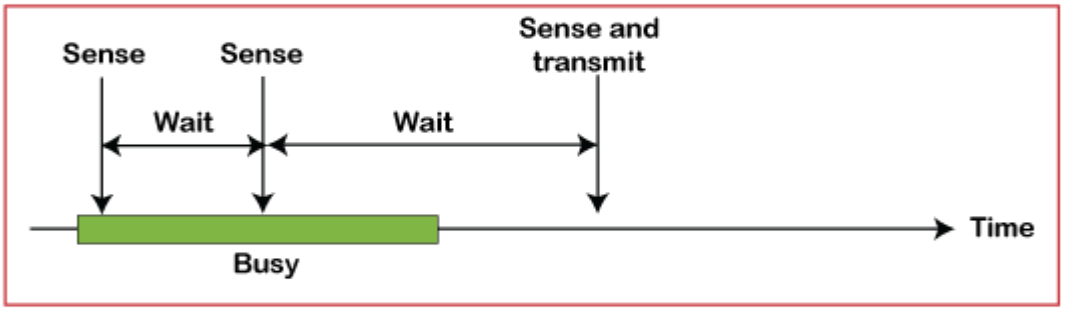
Non-Persistent: It is the access mode of CSMA that defines before transmitting the data, each node must sense the channel, and if the channel is inactive, it immediately sends the data. Otherwise, the station must wait for a random time (not continuously), and when the channel is found to be idle, it transmits the frames.

P-Persistent: It is the combination of 1-Persistent and Non-persistent modes. The P-Persistent mode defines that each node senses the channel, and if the channel is inactive, it sends a frame with a **P** probability. If the data is not transmitted, it waits for a (**q = 1-p probability**) random time and resumes the frame with the next time slot.

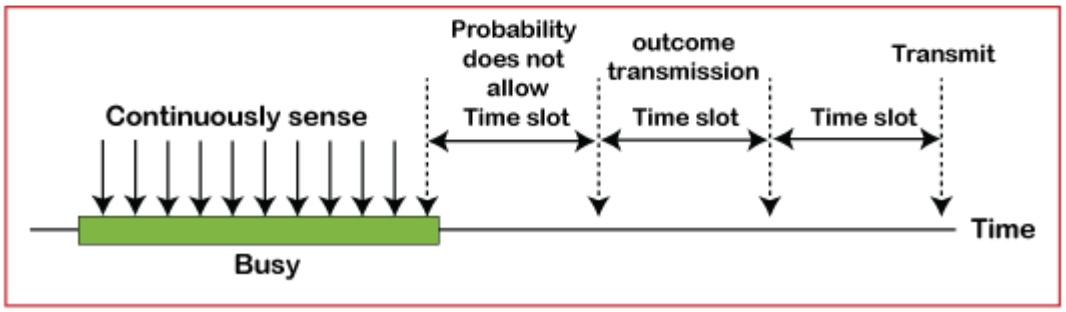
O- Persistent: It is an O-persistent method that defines the superiority of the station before the transmission of the frame on the shared channel. If it is found that the channel is inactive, each station waits for its turn to retransmit the data.



a. 1-persistent



b. Nonpersistent



c. p-persistent

CSMA/ CD

It is a **carrier sense multiple access/ collision detection** network protocol to transmit data frames. The CSMA/CD protocol works with a medium access control layer. Therefore, it first senses the shared channel before broadcasting the frames, and if the channel is idle, it transmits a frame to check whether the transmission was successful. If the frame is successfully received, the station sends another frame. If any collision is detected in the CSMA/CD, the station sends a jam/ stop signal to the shared channel to terminate data transmission. After that, it waits for a random time before sending a frame to a channel.

CSMA/ CA

It is a **carrier sense multiple access/collision avoidance** network protocol for carrier transmission of data frames. It is a protocol that works with a medium access control layer. When a data frame is sent to a channel, it receives an acknowledgment to check whether the channel is clear. If the station receives only a single (own) acknowledgments, that means the data frame has been successfully transmitted to the receiver. But if it gets two signals (its own and one more in which the collision of frames), a collision of the frame occurs in the shared channel. Detects the collision of the frame when a sender receives an acknowledgment signal.

Following are the methods used in the CSMA/ CA to avoid the collision:

Interframe space: In this method, the station waits for the channel to become idle, and if it gets the channel is idle, it does not immediately send the data. Instead of this, it waits for some time, and this time period is called the **Interframe** space or IFS. However, the IFS time is often used to define the priority of the station.

Contention window: In the Contention window, the total time is divided into different slots. When the station/ sender is ready to transmit the data frame, it chooses a random slot number of slots as **wait time**. If the channel is still busy, it does not restart the entire process, except that it restarts the timer only to send data packets when the channel is inactive.

Acknowledgment: In the acknowledgment method, the sender station sends the data frame to the shared channel if the acknowledgment is not received ahead of time.

B. Controlled Access Protocol

It is a method of reducing data frame collision on a shared channel. In the controlled access method, each station interacts and decides to send a data frame by a particular station approved by all other stations. It means that a single station cannot send the data frames unless all other stations are not approved. It has three types of controlled access: **Reservation, Polling**, and **Token Passing**.

C. Channelization Protocols

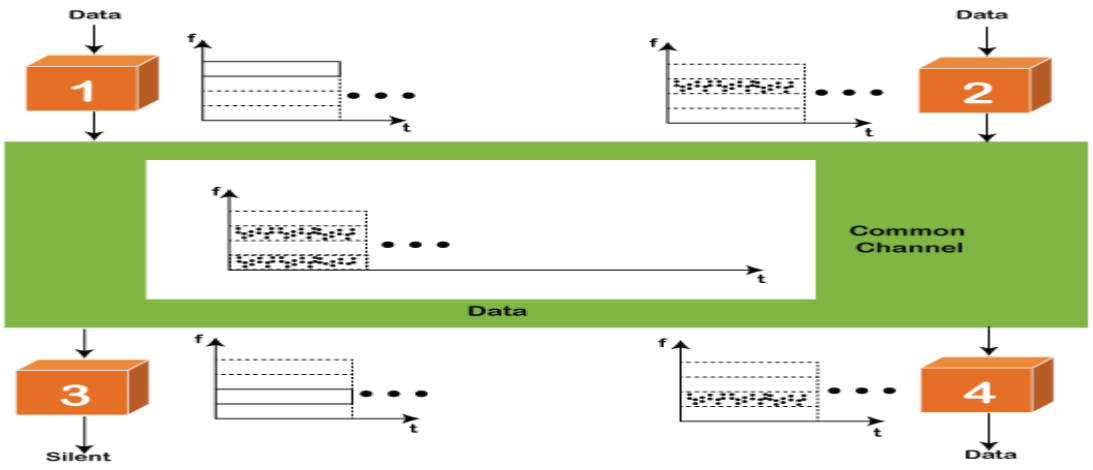
It is a channelization protocol that allows the total usable bandwidth in a shared channel to be shared across multiple stations based on their time, distance and codes. It can access all the stations at the same time to send the data frames to the channel.

Following are the various methods to access the channel based on their time, distance and codes:

1. FDMA (Frequency Division Multiple Access)
2. TDMA (Time Division Multiple Access)
3. CDMA (Code Division Multiple Access)

FDMA

It is a frequency division multiple access (**FDMA**) method used to divide the available bandwidth into equal bands so that multiple users can send data through a different frequency to the subchannel. Each station is reserved with a particular band to prevent the crosstalk between the channels and interferences of stations.



TDMA

Time Division Multiple Access (**TDMA**) is a channel access method. It allows the same frequency bandwidth to be shared across multiple stations. And to avoid collisions in the shared channel, it divides the channel into different frequency slots that allocate stations to transmit the data frames. The same **frequency** bandwidth into the shared channel by dividing the signal into various time slots to transmit it. However, TDMA has an overhead of synchronization that specifies each station's time slot by adding synchronization bits to each slot.

CDMA

The code division multiple access (CDMA) is a channel access method. In CDMA, all stations can simultaneously send the data over the same channel. It means that it allows each station to transmit the data frames with full frequency on the shared channel at all times. It does not require the division of bandwidth on a shared channel based on time slots. If multiple stations send data to a channel simultaneously, their data frames are separated by a unique code sequence. Each station has a different unique code for transmitting the data over a shared channel. For example, there are multiple users in a room that are continuously speaking. Data is received by the users if only two-person interact with each other using the same language. Similarly, in the network, if different stations communicate with each other simultaneously with different code language.

Difference between CSMA CA and CSMA CD

CSMA is a mechanism that senses the state of the shared channel to prevent or recover data packets from a collision. It is also used to control the flow of data packets over the network so that the packets are not get lost, and data integrity is maintained. In CSMA, when two or more data packets are sent at the same time on a shared channel, the chances of collision occurred. Due to the collision, the receiver does not get any information regarding the sender's data packets. And the lost information needs to be resented so that the receiver can get it. Therefore we need to sense the channel before transmitting data packets on a network. It is divided into two parts, **CSMA CA** (Collision Avoidance) and **CSMA CD** (Collision Detection).

CSMA CD

The **Carrier Sense Multiple Access/ Collision Detection** protocol is used to detect a collision in the media access control (**MAC**) layer. Once the collision was detected, the CSMA CD immediately stopped the transmission by sending the signal so that the sender does not waste all the time to send the data packet. Suppose a collision is detected from each station while broadcasting the packets. In that case, the CSMA CD immediately sends a jam signal to stop transmission and waits for a random time context before transmitting another data packet. If the channel is found free, it immediately sends the data and returns it.

Advantage and Disadvantage of CSMA CD

Advantages of CSMA CD:

1. It is used for collision detection on a shared channel within a very short time.
2. CSMA CD is better than CSMA for collision detection.
3. CSMA CD is used to avoid any form of waste transmission.
4. When necessary, it is used to use or share the same amount of bandwidth at each station.
5. It has lower CSMA CD overhead as compared to the CSMA CA.

Disadvantage of CSMA CD

1. It is not suitable for long-distance networks because as the distance increases, CSMA CD' efficiency decreases.
2. It can detect collision only up to 2500 meters, and beyond this range, it cannot detect collisions.
3. When multiple devices are added to a CSMA CD, collision detection performance is reduced.

CSMA/CA

CSMA stands for **Carrier Sense Multiple Access** with **Collision Avoidance**. It means that it is a network protocol that uses to avoid a collision rather than allowing it to occur, and it does not deal with the recovery of packets after a collision. It is similar to the CSMA CD protocol that operates in the media access control layer. In CSMA CA, whenever a station sends a data frame to a channel, it checks whether it is in use. If the shared channel is busy, the station waits until the channel enters idle mode. Hence, we can say that it reduces the chances of collisions and makes better use of the medium to send data packets more efficiently.

Advantage and Disadvantage of CSMA CA

Advantage of CSMA CA

1. When the size of data packets is large, the chances of collision in CSMA CA is less.
2. It controls the data packets and sends the data when the receiver wants to send them.
3. It is used to prevent collision rather than collision detection on the shared channel.
4. CSMA CA avoids wasted transmission of data over the channel.
5. It is best suited for wireless transmission in a network.
6. It avoids unnecessary data traffic on the network with the help of the RTS/ CTS extension.

The disadvantage of CSMA CA

1. Sometime CSMA/CA takes much waiting time as usual to transmit the data packet.
2. It consumes more bandwidth by each station.
3. Its efficiency is less than a CSMA CD.

Difference between CSMA CA and CSMA CD

S. No	CSMA CD	CSMA CA
1.	It is the type of CSMA to detect the collision on a shared channel.	It is the type of CSMA to avoid collision on a shared channel.
2.	It is the collision detection protocol.	It is the collision avoidance protocol.
3.	It is used in 802.3 Ethernet network cable.	It is used in the 802.11 Ethernet network.
4.	It works in wired networks.	It works in wireless networks.

5.	It is effective after collision detection on a network.	It is effective before collision detection on a network.
6.	Whenever a data packet conflicts in a shared channel, it resends the data frame.	Whereas the CSMA CA waits until the channel is busy and does not recover after a collision.
7.	It minimizes the recovery time.	It minimizes the risk of collision.
8.	The efficiency of CSMA CD is high as compared to CSMA.	The efficiency of CSMA CA is similar to CSMA.
9.	It is more popular than the CSMA CA protocol.	It is less popular than CSMA CD.