

Scientific Operations and Data Processing for Wide-Angle Polarimetric Camera (PolCam) onboard Danuri



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Introduction

- **Danuri**: South Korea's first lunar orbiter was launched on Aug. 5, 2022.
- **PolCam**: The wide-angle **Pol**arimetric **Camera** is the first payload to measure the polarimetric properties of the Moon.
- It operated in high-resolution mode (about 34 m/pixel) from 1 Apr. to 30 Nov., 2023.
- We introduce
- (1) a brief overview of the operational progress until November this year,
- (2) the overall procedure of data processing software, and
- (3) data formats for the upcoming public release.

Public Data Release

- The data is available from 1 Apr.
 (We operated test observation before Apr.)
- Format: PDS4
- Included 2D information
 - ✓ Raw data
- ✓ Longitude & Latitude
 - ✓ Incidence angle
- ✓ Emission angle
- ✓ Phase angle

Future Work

- Radiometric calibration
- Photometric calibration with lunar topography
- Maximum polarization (P_{max}) measurement
- Grain size distribution using P_{max} and albedo

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Routine Operations

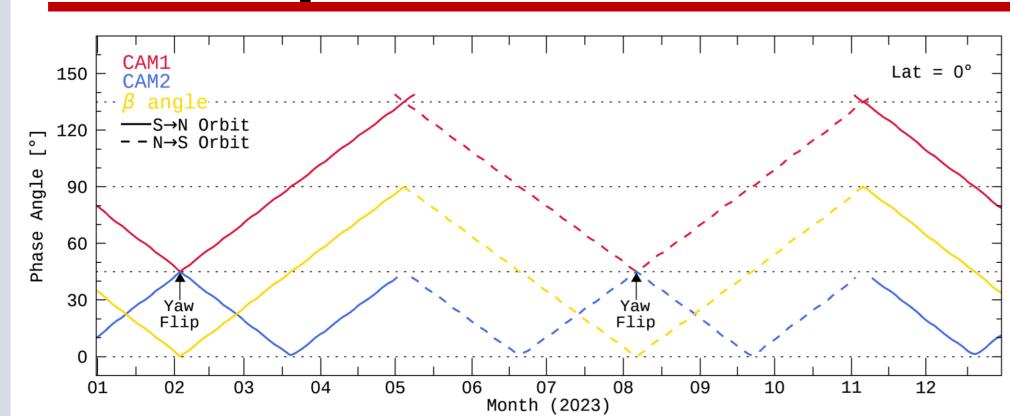


Fig. 1. Phase angle of the PolCam and sun-beta angle for one year.

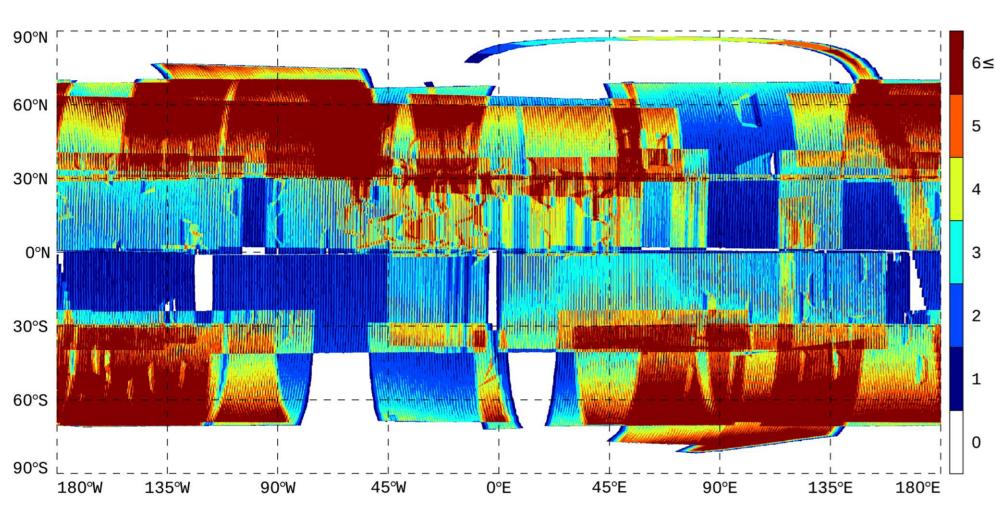
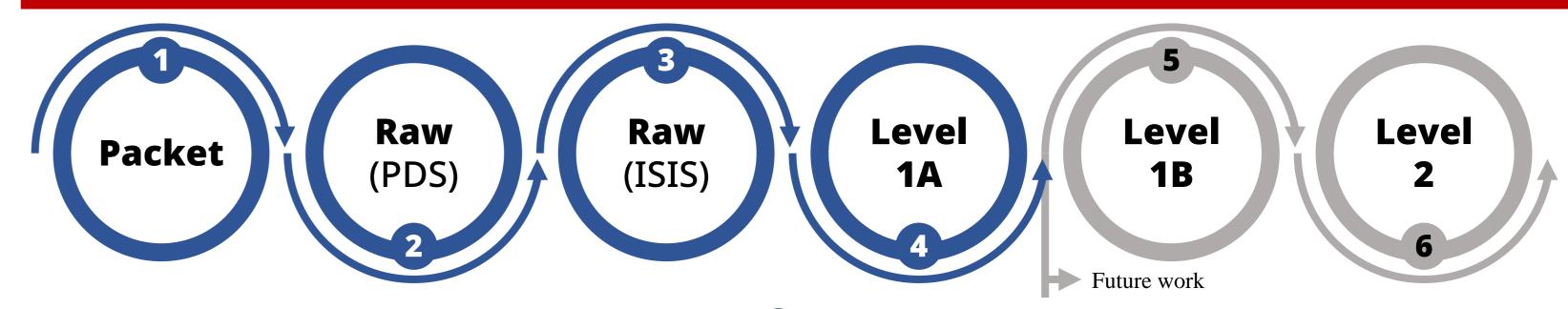


Fig. 2. The number of the PolCam observation on the lunar surface from 1 Apr. to 30 Nov., 2023.

Data Processing Pipeline (with SPICE kernels)



- Pipeline = [IDL or Python] programs
 - + the SPICE toolkit
 - + the ISIS applications

Geometric Correction

(with Digital Shape Kernel)

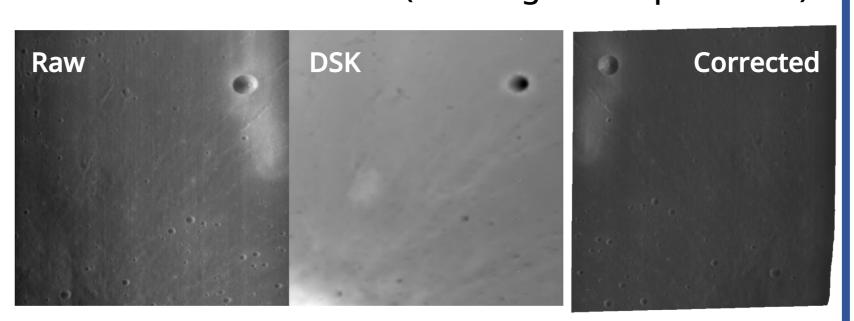


Fig. 6. Raw, elevation from Digital Shape Kernel (DSK), and geometric corrected data.

Flat-field Correction

• Flats were generated with reference to the ISIS application, lromakeflat.

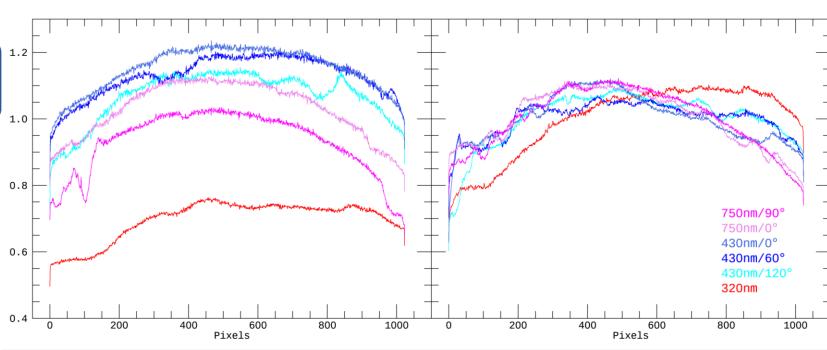


Fig. 5. Flats for each channel (Left) measured in a ground laboratory and (Right) created by observation data.

• On developing the ISIS application...

polcam2isis & Camera model class of the PolCam

Frame & Instrument Kernels Adjustment

Tilted angle

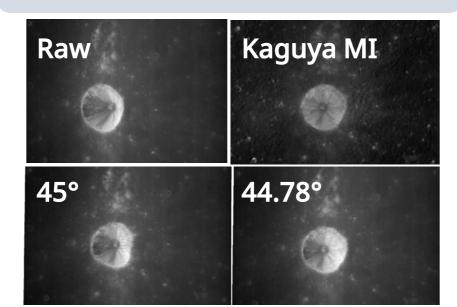


Fig. 3. Results of geometric correction (a) before and (b) after adjusting tilted angle from 45° (designed value) to 44.78° (estimated value)

Field of View (FoV)

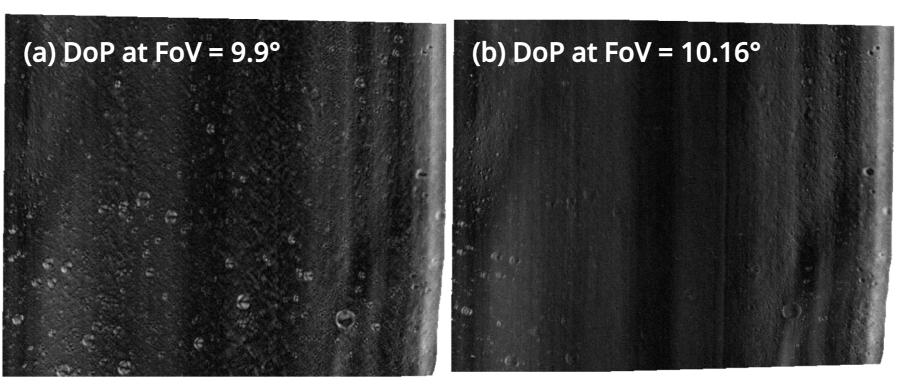


Fig. 4. Degree of polarization (a) before and (b) after adjusting FoV from 9.9° (designed value) to 10.16° (estimated value).

Global Mapping

