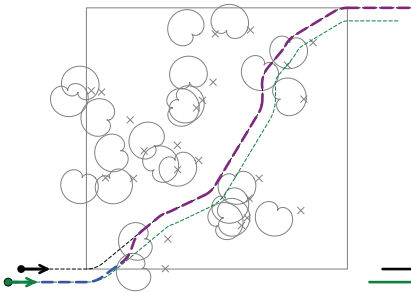
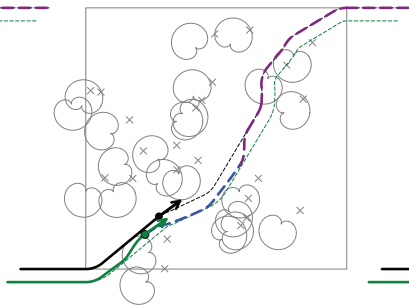


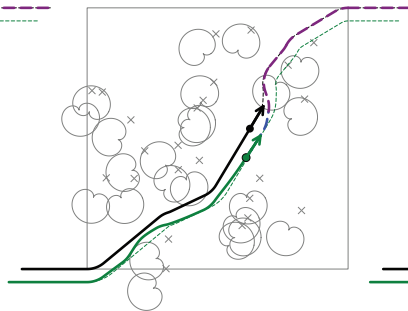
a)

 $t = 0.0$ 


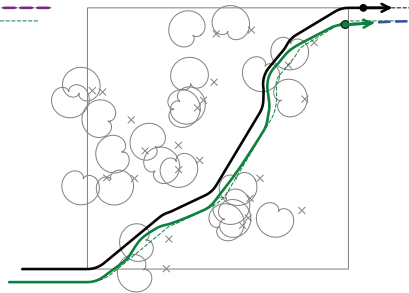
b)

 $t = 0.6$ 

c)

 $t = 1.1$ 

d)

 $t = 1.8$  Engagement Zone Leader Robot Follower Robot

--- Leader's Desired Trajectory

--- Follower's Desired Trajectory

--- Leader's Executed Trajectory

--- Follower's Executed Trajectory

--- Follower's Nominal Trajectory

--- Follower's Backup Trajectory