

# **Team Minutes for Dolphin Tanks**

Team Members' Names	
Alexander Miles	
Devin EA	
Travis Aga	
Yuxi wakeshima	

#### Meeting 1

Meeting Date: 2/14/2022	Start Time: 12:00 End Time: 12:45 Summary of Meeting Started overall discussion and talked about future plans.
1. Attendance	All members present
2. Purpose of Meeting	To discuss about mini project 1.
3. Discuss work completed since last meeting.	This is our first team meeting, so far there hadn't been any work accomplished yet
4. Summarize work completed during meeting	We finished the team charter, read the mini project handout, talked about what we each need to do and the due dates.
5. Review action items to be completed after meeting	Everyone needs to start doing what their assign roles job according to the mini project handout
6. Schedule next meeting	Student center ballroom/Brown 304
7. Recording secretary	Recording secretary is yuxi wakeshima, the date circulated by email is Feb/14/2022.

<b>Meeting Date:</b>	Start Time: 1:00pm
Put date here	Record time meeting started
	End Time: 2:20pm
	Record meeting end time
	Summary of Meeting

	We focused on doing our individual parts, sharing our work together and discussing how to put everyone's project together for the demonstration.
1. Attendance	All members present
2. Purpose of Meeting	To see where everyone is at their individual project as well as gathering what we need from each other.
3. Discuss work	Reading the handouts, figuring out pins, understanding what's
completed since	going on as well as working on individual parts.
last meeting.	
4. Summarize	Encoder Arduino code finished; motor assembly finished.
work completed	
during meeting	
5. Review	Continuing each person's respective jobs.
action items to	
be completed	
after meeting	
6. Schedule	FEB 25th, brown 304/student center
next meeting	
7. Recording	Yuxi wakeshima, date circulated by email is FEB/18/2022
secretary	

Meeting Date: 03/04/2022	Start Time: 12:15 End Time: 12:45 Summary of Meeting We defined our roles, and set goals to be done before next week.
1. Attendance	All members present
2. Purpose of Meeting	We need to solidify each member's contributions to this project.
3. Discuss work completed since last meeting.	Since last meeting, we finished and demonsrated the miniproject.
4. Summarize work completed during meeting	Our roles are going to be:  Devin – Calculate encoder for turns according to input state  Travis – Implement chessboard algorithm  Yuxi – Work on step response relative to the velocity, and tune the PI controller  Alex – work on state machine from camera and encoder.
5. Review action items to be completed after meeting	Finalize the robot shape and get the wheels turning according to an input state. Also, get camera/pi to define the states.
6. Schedule next meeting	03/11/22 12pm in student center
7. Recording	Devin Ea

secretary	
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Meeting Date: 03/11/2022	Start Time: 11:59am End Time: 12:30pm Summary of Meeting Discuss finalizing robot physical design and motor control.
1. Attendance	All members present
2. Purpose of Meeting	Discuss finalizing demo one
3. Discuss work	MATLAB stuff done
completed since	Robot design nearing finalization
last meeting.	Encoder counts to real life math
	Camera outputs correct angle
4. Summarize	Planned function for robot to call for its rotation. Review
work completed	camera angle and adjust according to current FOV.
during meeting	
5. Review	Finalize robot function, i.e. turning and start/stop. Test camera
action items to	and optimize output time and quality. Angle camera down
be completed	more on the robot.
after meeting	
6. Schedule	In student center, date TBD
next meeting	
7. Recording	Devin ea
secretary	

Meeting Date: 04/01/2022	Start Time: 12:00Pm End Time: 12:30PM Summary of Meeting We discussed what we are going to need for Demo 2, which is connecting of pi and arduino
1. Attendance	All members preseny
2. Purpose of Meeting	Discuss beginning and planning of demo 2
3. Discuss work completed since last meeting.	We successfully demo'd Demo 1 stuff
4. Summarize work completed during meeting	We need to make parameters for the pi to send data to the Arduino to move and stop
5. Review action items to be completed after meeting	<ul> <li>Error-free I2C connection</li> <li>Robot movement function consistency</li> <li>Movement parameter definitions</li> </ul>
6. Schedule next meeting	Student Center, one week from now

7. Recording	Devin Ea
secretary	

Meeting Date: 04/08/2022	Start Time: 12:15PM End Time: 12:30PM Summary of Meeting Discussed the refinements needed before Demo 2 day
1. Attendance	All members present
2. Purpose of Meeting	We needed to see what's left to do, and what improvements are going to be needed.
3. Discuss work completed since last meeting.	Robot is connected, and can function autonomously. Battery holder implemented, less movement of robot bits.
4. Summarize work completed during meeting	We said that we are going to modify the camera settings and the position of the camera itself to create a more consistent environment for blue tape detection.
5. Review action items to be completed after meeting	Get camera adjusted. Adjust Arduino code if needed, but avoid modifying it, and adjust Pi code instead. Add small changes as needed.
6. Schedule next meeting	Student center, date TBD
7. Recording secretary	Devin Ea

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