🕴 Devakumar Thammisetty

- 🔻 Trivandrum, Kerala, India
- Scientist, ISRO (9+ years)
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Strengths

- Mathematical modeling, Control, Optimization
- Experienced Rocket propulsion engineer (9+ years)
- Excellent analytical & programming aptitude (Python)
- Mechanical and Aerospace Engineer

Education

July -Sep'19

2018- 2020 Master in Mechanical Engineering, EPFL (GPA: 5.51/6)

École Polytechnique Fédérale de Lausanne, Switzerland

Focus: Control & Automation, Minor in Management and Technology

Thesis: Development of Multi-phase Optimal Control Software (Automatic Control Laboratory, Thesis Director: Prof. Colin Jones, Grade: 6/6, [MPOPT])

2008 – 2012 Bachelors in Aerospace Engineering, IIT Bombay (GPA : 8.72/10)

Indian Institute of Technology Bombay, India

Project: Conceptual design of 2-seater solar powered airplane.

Professional Experience

2012 -till date Scientist, Indian Space Research Organisation (ISRO), India (9+ years)

Focus: Modeling and simulation of Liquid Rocket Engine Performance, System engineering of rocket propulsion systems.

Project I: Technical lead, Cryogenic Engine Development (Modeling)

Mathematical modeling of engine dynamics, thrust control algorithms, software development in python, data analysis and synthesis, system engineering.

Project II: Moon lander thrust control algorithm development (Control) *Developed real-time thrust control algorithm for ISRO's Moon lander*.

Engineering Internship, Asyril SA, Switzerland (Computer Vision, OpenCV)

Skills: OpenCV 4.1, Python programming, Machine Learning, Agile software dev. Developed and tested various vision algorithms for object localization and recognition using OpenCV. Feature identification, large scale in-house databases.

May – July'11 Software developer internship, Fluidyn-India, Bangalore (C++, Qt4)

Project: Development of modules for CFD post-processing software in C++

Projects and Internship Experience

Feb - Jun'19

Semester project: Interdisciplinary EPFL robotics competition (Team of 3)

Skills: Arduino, Raspberry pi, computer vision(Direction: Prof. Auke Jan Ijspeert). Built a mobile robot which autonomously localizes and navigates in a given terrain [Video]. Programmed various vision based algorithms in Raspberry Pi. Implemented Kalman Filtering, State Machine and control with sensor feedback.

Sep-Dec'19

Semester project: Embedded Real time optimization of a fuel cell system

Skills: Optimization of constrained nonlinear systems in real time, Quadratic Programming, C++, Model Predictive Control. (Direction: Prof. Colin Jones, LA3) *Optimizing performance index of a fuel cell system subject to constraints.* numerical optimization methods, nonlinear system dynamics, Sequential Quadratic Programming(SQP) along with ADMM based QP solver.

Skills

Technical

- Nonlinear Optimization, Control, MPC, Computer Vision, System engineering
- Work experience in rocket propulsion, mathematical modeling and simulations
- Machine learning, Data science, Operations management
- Excellent analytical and programming skills

IT

- Python numpy, scipy, pandas, scikit-learn, OpenCV, PyQt4, Django
- MATLAB/Simulink, OpenFOAM, ParaView, Gmsh
- C++, Eigen, CasADi, Qt4
- Data analysis and documentation: Microsoft Excel, Word, Power point, LaTeX
- Version control: git, hg(Mercurial)

Language

- English (Fluent), Hindi (Fluent) Read, Write, Listen and Speak
- French (Beginner) A1 level course work at EPFL
- Telugu (Mother tongue) Read, Write, Listen and Speak
- Malayalam (Medium) Read, Listen & Speak

T Awards

- Young Engineer Award by Indian National Academy of Engineering (INAE)[Profile].
- ISRO Team Excellence Award for contribution towards maiden launch of GSLV-MkIII rocket.

Extra-curricular activities

Sports Other

- Table Tennis (Ping-pong), Cricket
- Travel, hiking, reading non-fiction

Personal details

Citizenship Civil Status

- Indian
- Married