devals@andrew.cmu.edu

# EDUCATION

## Carnegie Mellon University - School of Computer Science

Master of Science in Robotic Systems Development

Pittsburgh, PA

(412) 626-1266

May 2021

## Birla Institute of Technology and Science, Pilani

Bachelor of Engineering in Electrical and Electronics

Hyderabad, India

Jul 2016

## Coursework

• Computer Vision, Deep Reinforcement Learning, Introduction to Deel Learning, Robot Localization and Mapping, Manipulation Estimation and Control, Introduction to Robotics Business, Systems Engineering and Management for Robotics

#### **PROJECTS**

#### Traffic behaviour prediction for realistic simulation

Pittsburgh, PA

Ridecell and Carnegie Mellon University | Simulation Lead | Rotating Project Manager

Sep 2019 - Present

• Developing upon CARLA simulator (Unreal Engine 4) to support with smart actors (cars, pedestrians), where their behavior is more realistic and interactive based on real-world data.

#### EduSense | Practical Classroom Sensing at Scale

Pittsburgh, PA

HCII, Carnegie Mellon University | Research Assistant | Summer Research Assistant

Jan 2020 - Sep 2020

• Created 3D digital-twin of classrooms (instrumentation free) to provide 6DOF Gaze for students and the teacher in real-time.

#### PROFESSIONAL EXPERIENCE

#### Aitech Robotics and Automation Pte Ltd

Singapore

Robotics Engineer

Apr 2019 - Jul 2019

• Developed prototype of fully autonomous forklift (tricycle drive) using off-the-shelf packages like Google's Cartographer, in Robot Operating System(ROS) leading to a successful deal with the customer.

#### GreyOrange Robotics Pte Ltd

Gurugram, India

Embedded Engineer

Sep 2016 - Feb 2019

- Worked on marker-less navigation for a fleet of automatic guided vehicle (AGV) in shared space with humans.
- Worked extensively on autonomous navigation algorithms to achieve sub-centimeter accuracies in AGV.
- Developed algorithm for a low-cost 3D-dimensioning system with 5 mm accuracy.
- Created a complete software-in-loop test automation framework for AGVs on Gazebo with ROS to reduce hardware dependency for testing.

#### Google Summer of Code Student with RTEMS

prize in BioAsia Healthcare Devthon.

Remote

Student Developer

May 2016 - Aug 2016

• Added USB and Ethernet support to Raspberry Pi Board for a Real-Time Executive for Multiprocessor Systems (RTEMS) and developed Human Interface Device drivers.

#### Tonbo Imaging

Bangalore, India

Intern

Jul 2015 - Dec 2015

• Interfaced thermal camera system, laser sensor, and OLED Display with a media processor and developed user-firmware for thermal imaging monocular camera *Foxhound*.

# user-firmware for thermal imaging monocular camera Foxhound. MIT-Media Lab with Srujana Innovation Centre, L.V. Prasad Eye Hospital Hyderabad, India

Intern

• Dec 2014 - March 2015

• Developed a low cost wearable and modular headset platform called Pupil+ for eye diagnosis which secured 3rd

# SKILLS

- Programming Languages: C, C++, Python, Bash Scripting, MATLab
- Framework and Tools: Git, OpenCV, Robot Operating System (ROS), Gazebo, RTOS, TensorFlow, PyTorch