NEW TOOLS The Ticker class The Timer class

EW309 Turret Subsystem

Logging Experimental Data

Goal

We are now at a point where we may wish to save measurements from our encoder, export those measurements from the Mbed, and then analyze them in MATLAB. To aid in the analysis, it is beneficial to capture measurements at a specified rate and for a certain duration of time. The Ticker class will allow you to repeatedly execute a function at a specified interval whereas the Timer class allows you to create timers and measure small times (between microseconds and seconds).

Ticker Class

The Ticker class in Mbed interface is used to setup a recurring interrupt to repeatedly call a function at a specified rate. You may create any number of Ticker objects, allowing multiple outstanding interrupts at the same time. The function can be a static function, or a member function of a particular object.

Go to the link https://os.mbed.com/handbook/Ticker and run the simple program that setups a Ticker to invert an LED. Notice where the Ticker object is declared and the Ticker function defined.

Timer Class

The Timer interface is used to create, start, stop and read a timer for measuring small times (between microseconds and seconds). Any number of Timer objects can be created, and can be started and stopped independently

Go to the link https://os.mbed.com/handbook/Timer and run the Timer_HelloWorld program. Observer the Timer object declaration as well as the syntax for starting and stopping the timer. Try adding a second timer and see observe the results.

Bringing It All Together

Use the Ticker and Timer classes to complete the steps below.

- 1. Measure <u>exactly 5.0(sec)</u> of a *manually* moved (approximate) sinusoidal motion of the rotor displacement angle θ .
- 2. Measurements should be taken at a rate of 100.0(Hz).
- 3. Save/log displacement angle θ and the TIME at which it was logged.
- 4. Export the data from your program in an efficient manner for plotting in MATLAB.
- 5. Import the data into MATLAB.
- 6. Plot the displacement angle θ vs. time in a MATLAB figure.