

Exploring MCU: ~~Interfacing~~ Technologies

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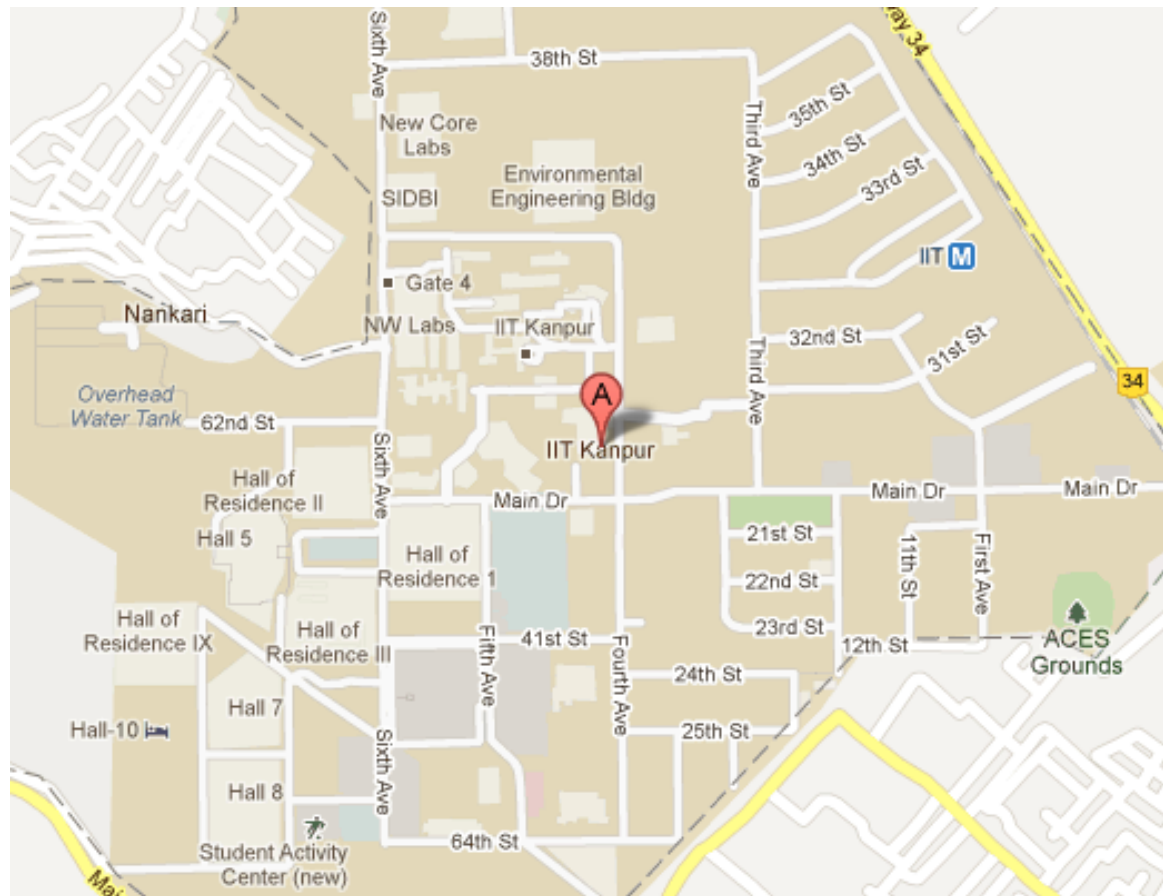
RFID Bands



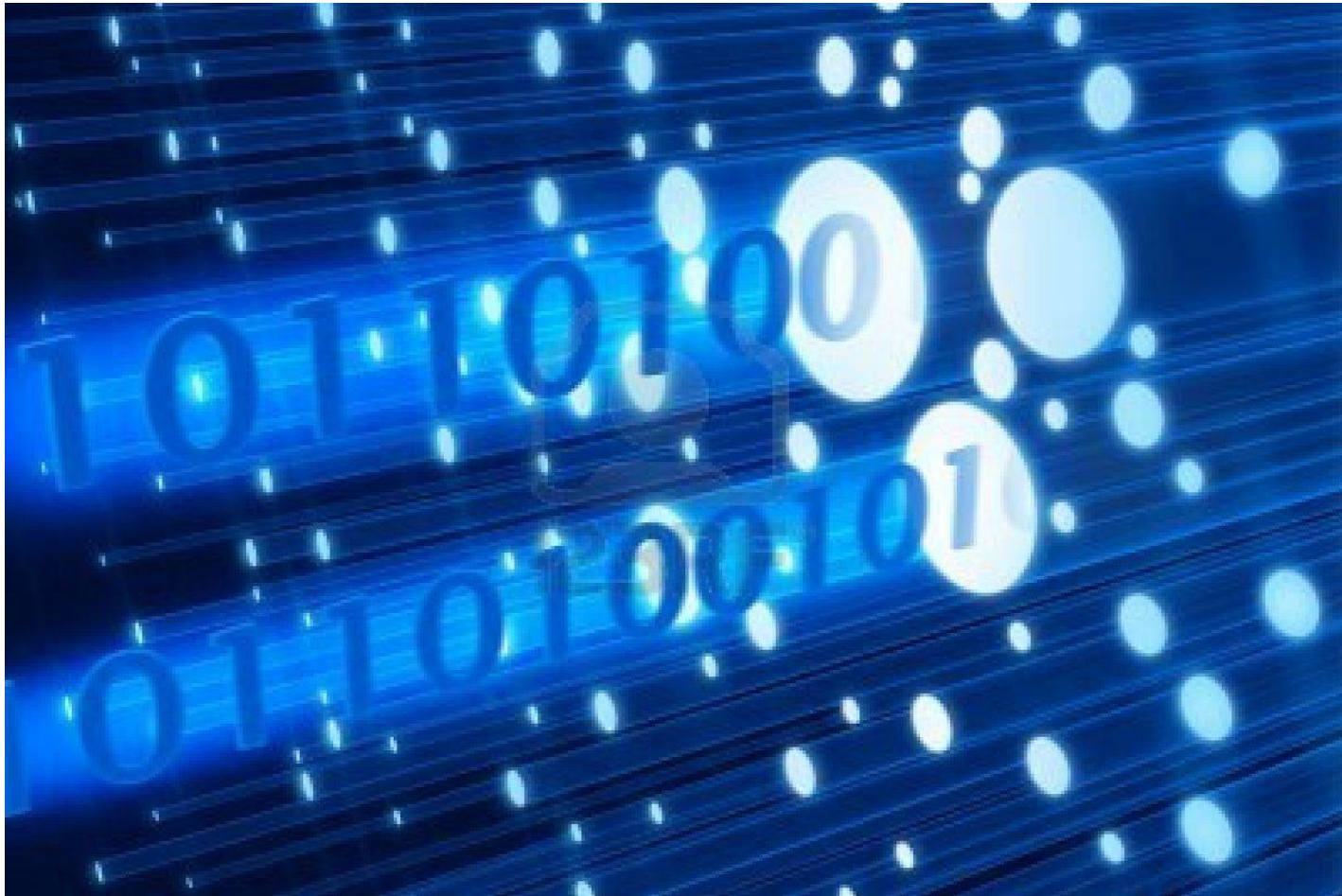
GSM



GPS



Communicating with an MCU



Communication in MCU's

Three modes are possible:

- Simplex
- Half-Duplex
- Full-Duplex

UART: Universal Asynchronous Receiver Transmitter

- What makes it 'universal' ?
 - Its parameters (format,speed ..) are configurable.
- Why 'asynchronous' ?
 - It doesn't have a clock

UART Basics

- Baud Rate:
 - No. of bits transmitted/received per second = _____bits/sec.
- Format of Communication

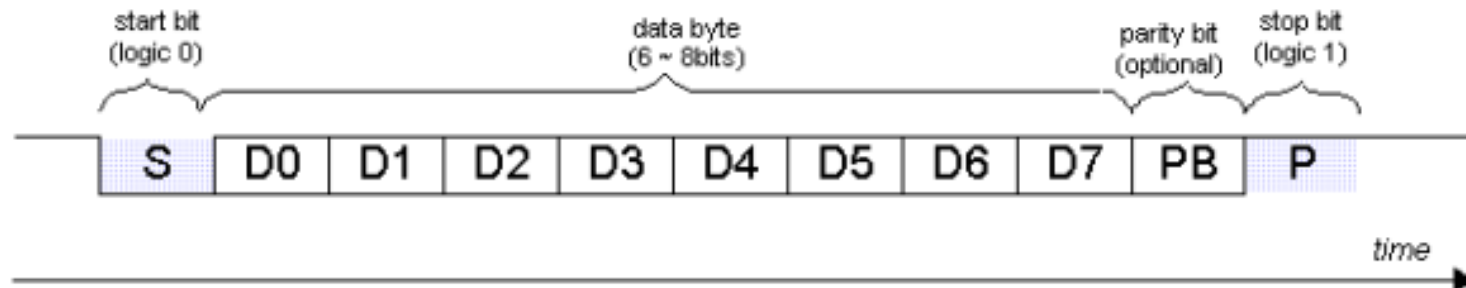
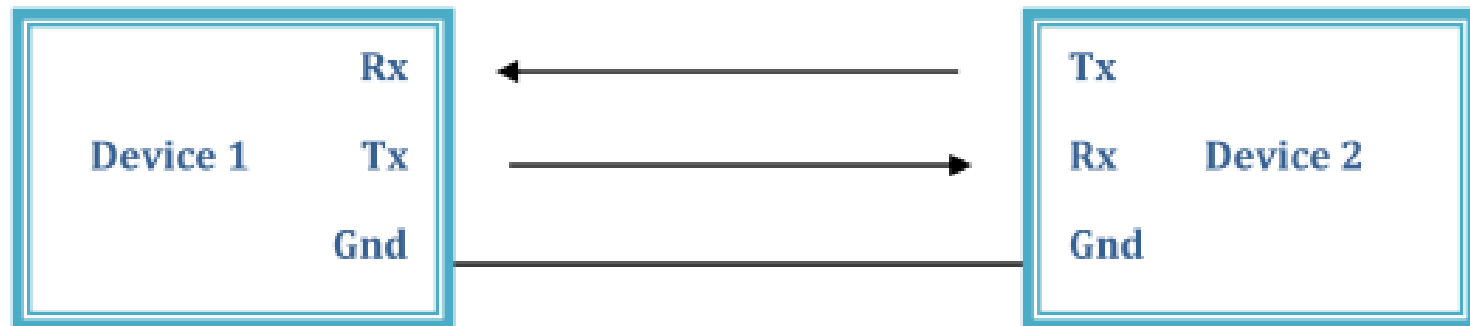
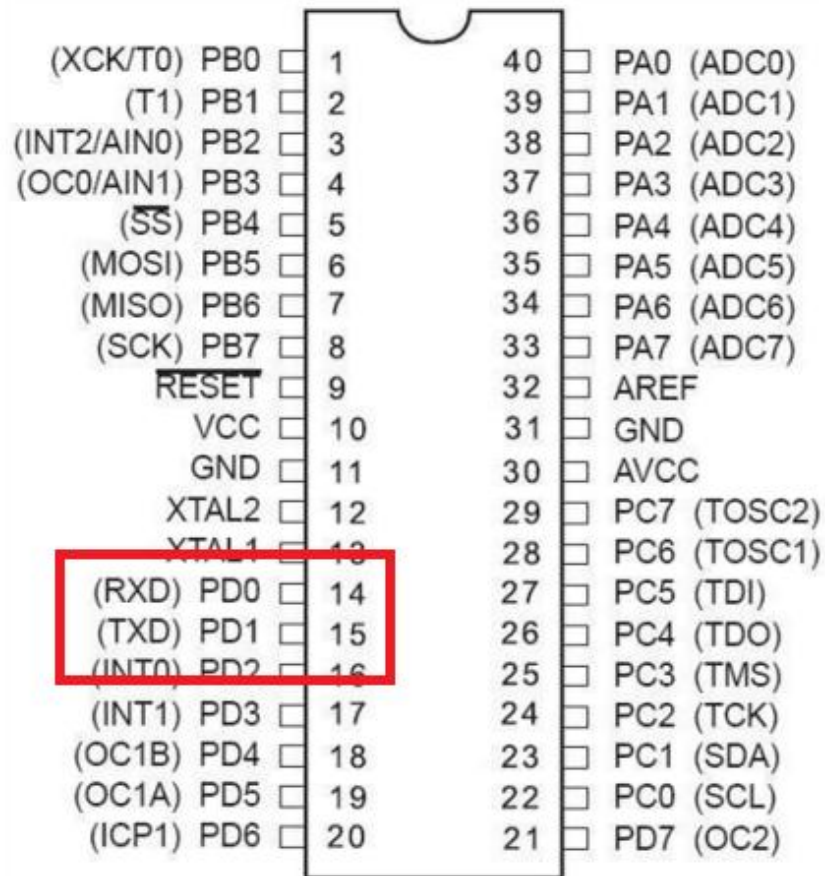


Figure 17: Basic UART packet format: 1 start bit, 8 data bits, 1 parity bit, 1 stop bit.

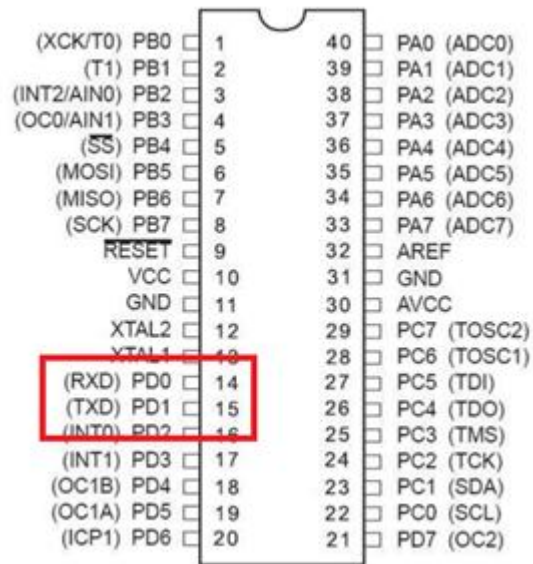
Connections for UART



UART in AtMega16

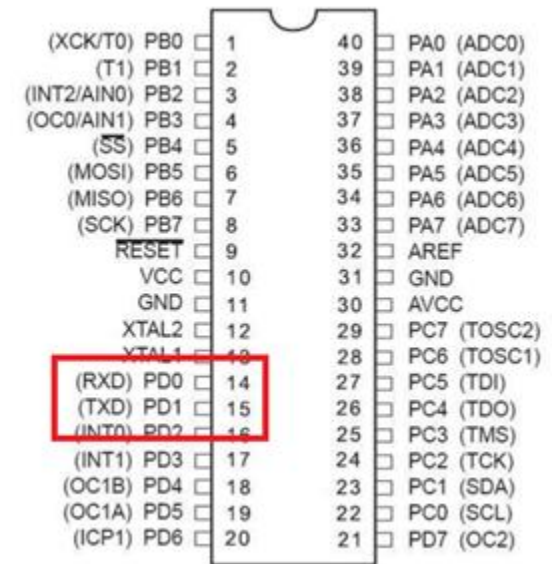


Connecting AtMega16's with UART



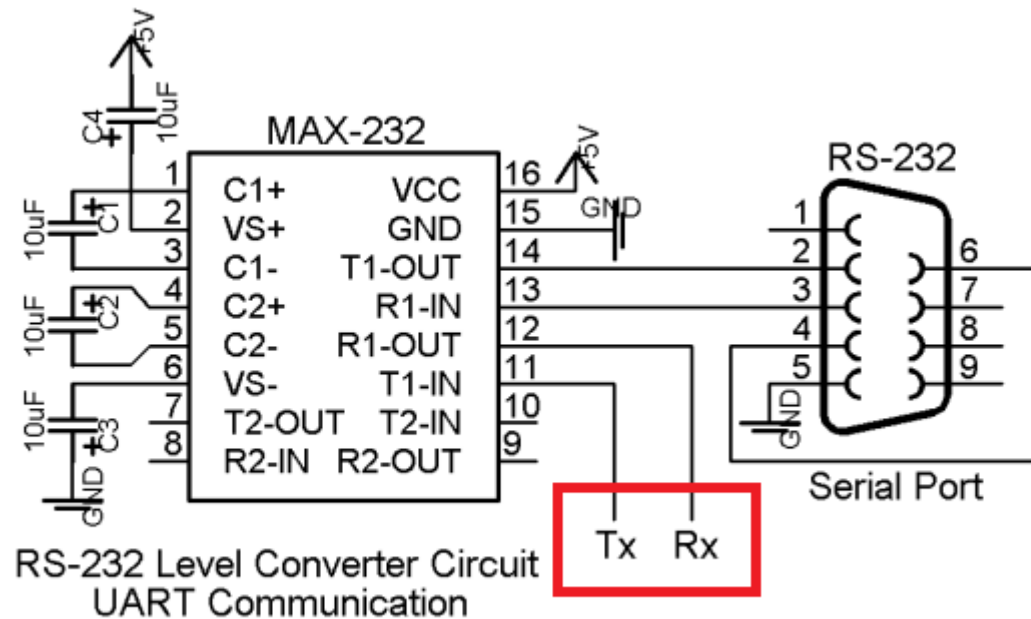
Device 1

Rx ? Tx
Tx ? Rx
GND ? GND



Device 2

MAX-232 and USB-Serial



Connecting AtMega16 with Computer

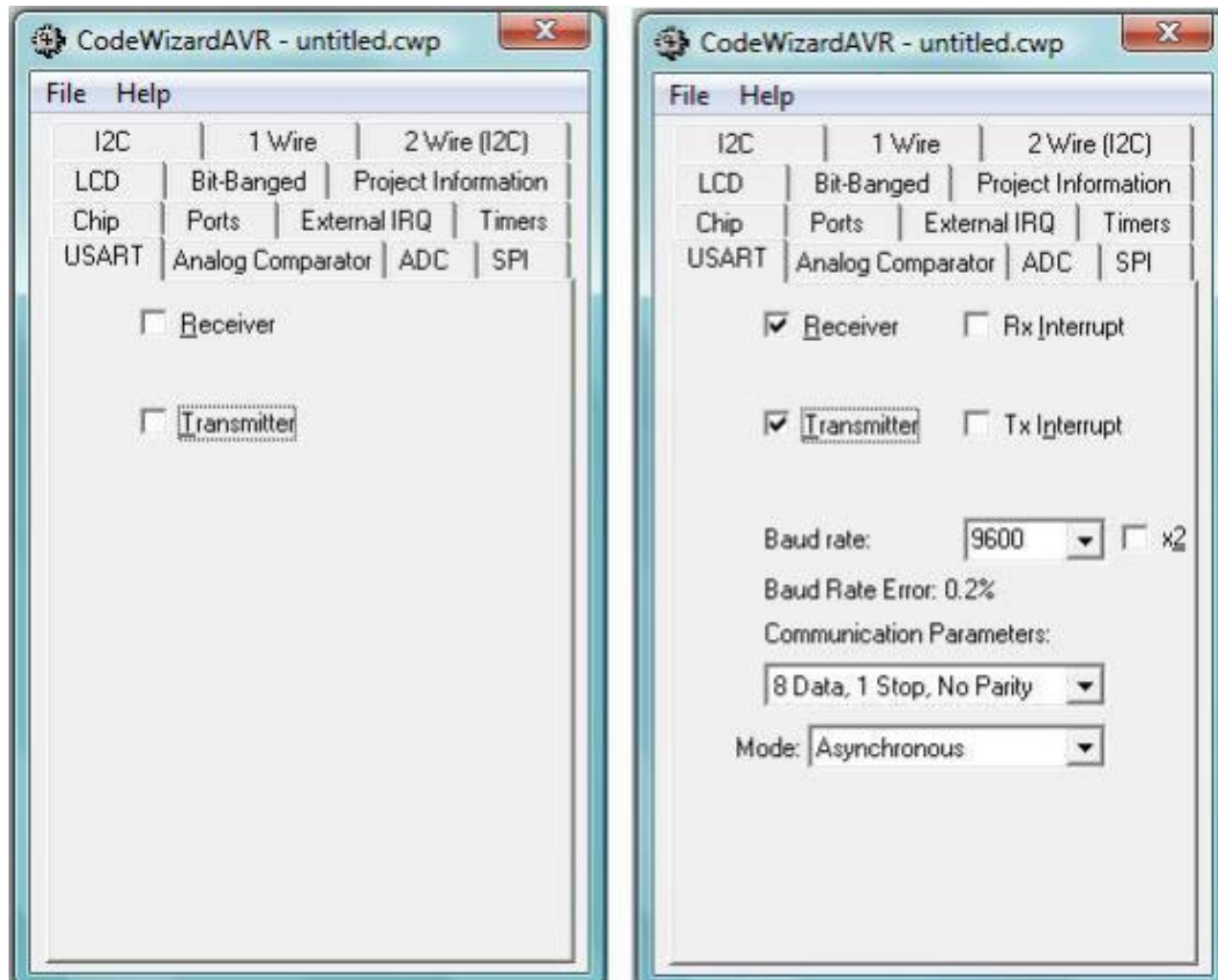
- Latest Direct Way :



Coding with UART

- Three simple commands :
 - `putchar(char);`
sends 8-bit characters through UART
 - `getchar();`
receives 8-bit characters via UART
 - `puts(string);`
sends a constant string

Where do we code.. ?



Sample Code for UART

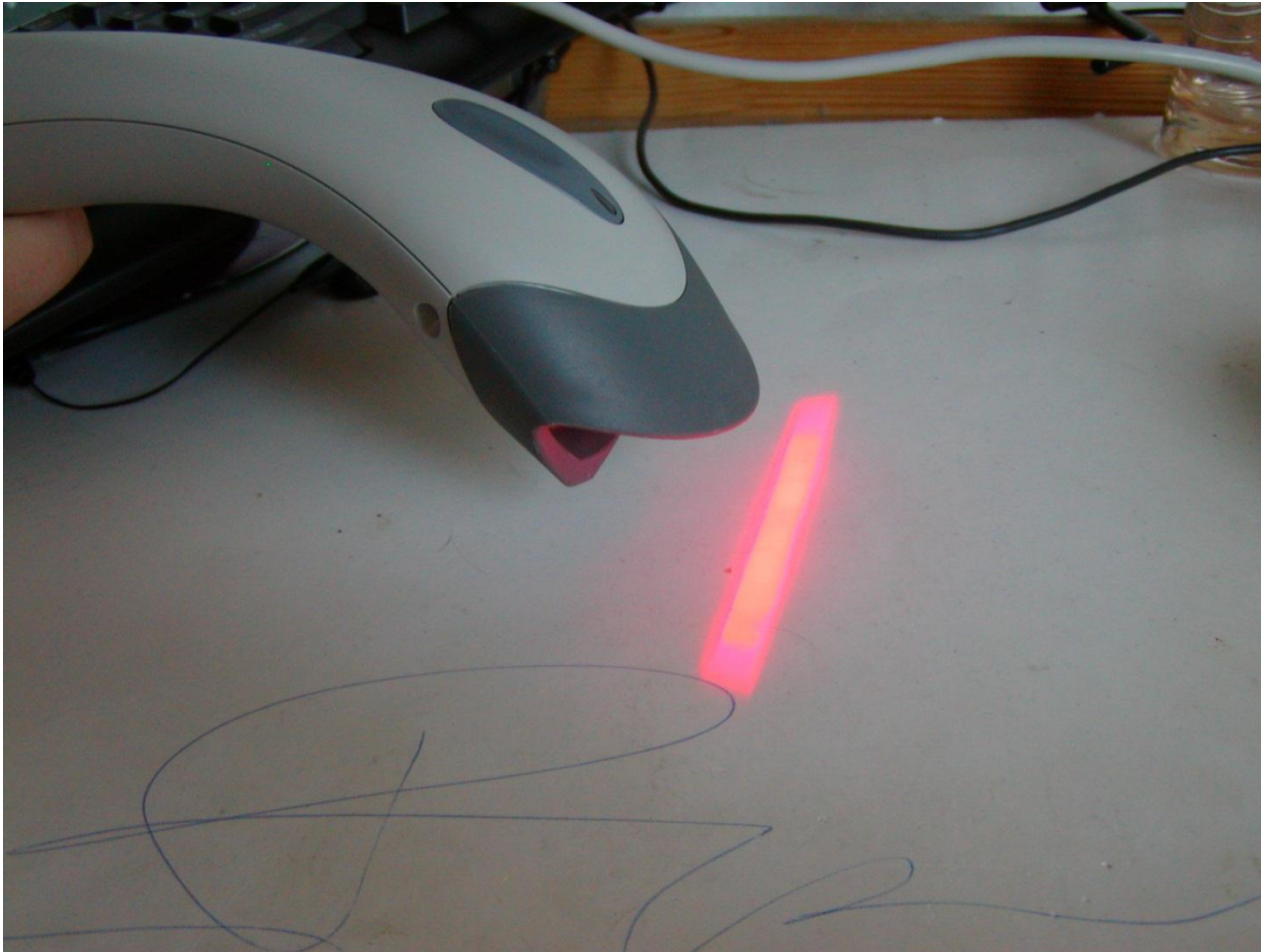
- Transmitter Code:

```
if(PORTA.1 == '0')  
    putchar('a');
```

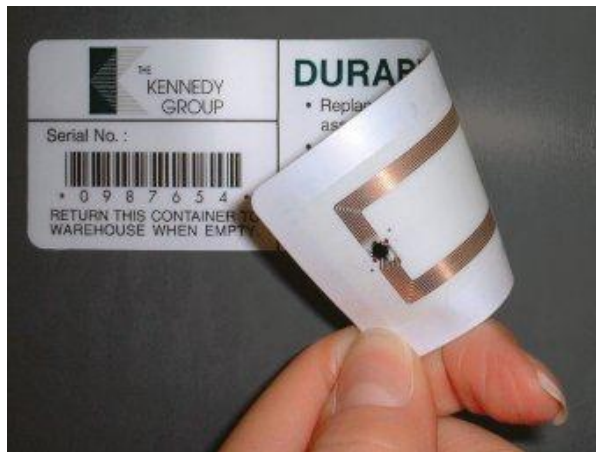
- Receiver Code:

```
c = getchar();  
lcd_putchar(c);
```

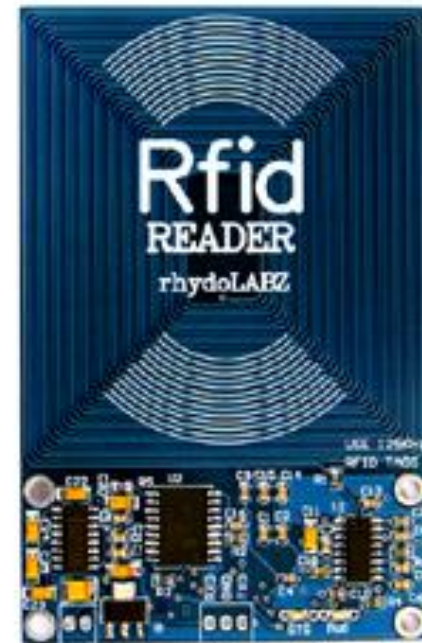

Barcode Scanner



RFID: Radio Frequency Identification



1. Tag



2. Reader

RFID Tags

- A Tag is a tiny silicon chip(IC) with an antenna.
- Types of tags :
 - Active
 - Battery Assisted Passive (BAP)
 - Passive

RFID: MCU Interface



Device 1

Rx	?	Tx
Tx	?	Rx
GND	?	GND

(XCK/T0) PB0	1	40	PA0 (ADC0)
(T1) PB1	2	39	PA1 (ADC1)
(INT2/AIN0) PB2	3	38	PA2 (ADC2)
(OC0/AIN1) PB3	4	37	PA3 (ADC3)
(SS) PB4	5	36	PA4 (ADC4)
(MOSI) PB5	6	35	PA5 (ADC5)
(MISO) PB6	7	34	PA6 (ADC6)
(SCK) PB7	8	33	PA7 (ADC7)
RESET	9	32	AREF
VCC	10	31	GND
GND	11	30	AVCC
XTAL2	12	29	PC7 (TOSC2)
XTAL1	13	28	PC6 (TOSC1)
(RXD) PD0	14	27	PC5 (TDI)
(TXD) PD1	15	26	PC4 (TDO)
(INT0) PD2	16	25	PC3 (TMS)
(INT1) PD3	17	24	PC2 (TCK)
(OC1B) PD4	18	23	PC1 (SDA)
(OC1A) PD5	19	22	PC0 (SCL)
(ICP1) PD6	20	21	PD7 (OC2)

Device 2

RFID: MCU Coding

- Enable UART buffer before you code.
- `char ID[15];`

.....

.....

```
for( i = 0, i <= ; i++) {  
  ID[i] = getchar();  
  lcd_puts(ID); }
```

UART buffer settings in CVAVR will soon be uploaded.

Cool Applications

GSM: Global System for Mobile Communications

- It is a standard set for 2G cellular networks.



GSM Module



1. Modem



2. SIM card

Only for the Geeks !!

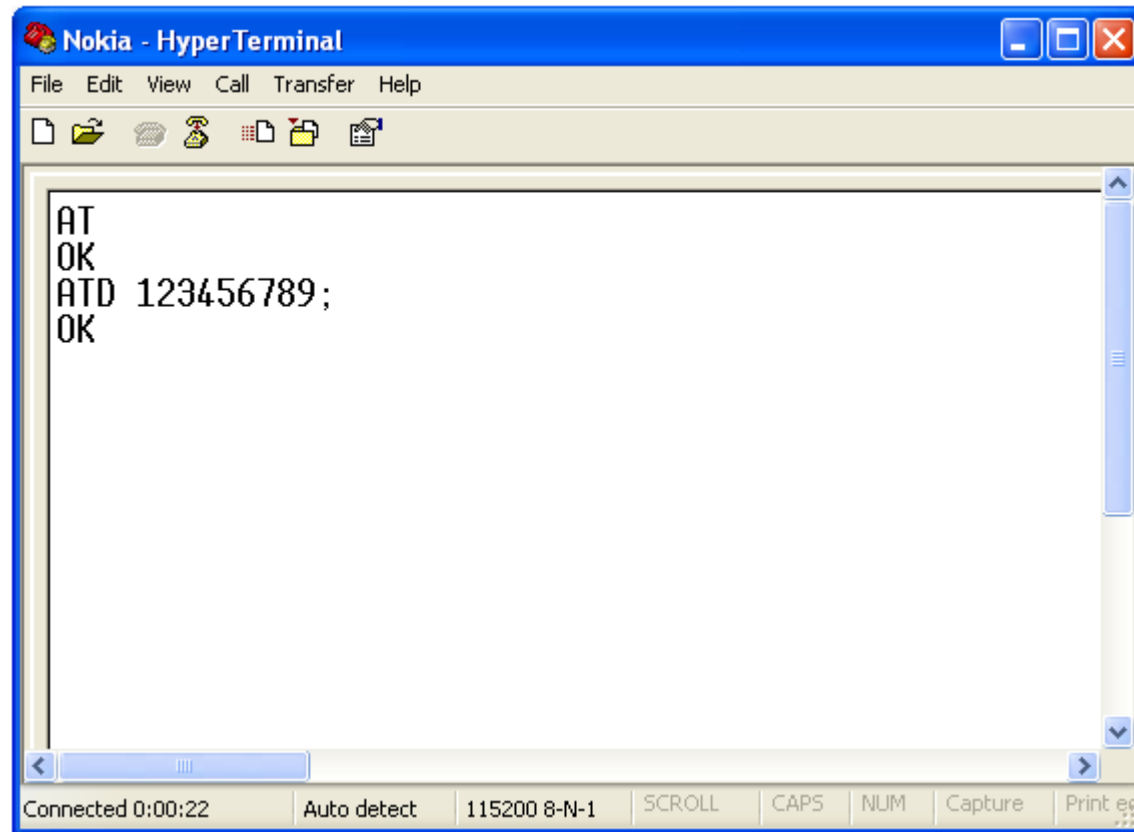


SIM300 IC

Features Supported

- SMS
- Voice Calling
- GPRS
- Support for Speaker

GSM Modem: Computer Interface



Terminal Settings can be found at:

http://www.developer.nokia.com/Community/Wiki/AT_Commands

AT Commands Basics

- AT+X? //Queries value of X
- AT+X= //Sets value of X
- ATD 9559753551; //Calls number
OK
- Entire AT command set can be accessed from:

http://www.developer.nokia.com/Community/Wiki/AT_Commands

SMS: Using AT Commands

- Two message modes: PDU and Text
- AT+CMGF=1 //Text Mode

OK

AT+CMGS="9559753551"

> Hello World?<Ctrl>+<Z>

+CMGS: 44

OK

GSM Modem: MCU Interface



Device 1

Rx	?	Tx
Tx	?	Rx
GND	?	GND

(XCK/T0) PB0	1	40	PA0 (ADC0)
(T1) PB1	2	39	PA1 (ADC1)
(INT2/AIN0) PB2	3	38	PA2 (ADC2)
(OC0/AIN1) PB3	4	37	PA3 (ADC3)
(SS) PB4	5	36	PA4 (ADC4)
(MOSI) PB5	6	35	PA5 (ADC5)
(MISO) PB6	7	34	PA6 (ADC6)
(SCK) PB7	8	33	PA7 (ADC7)
RESET	9	32	AREF
VCC	10	31	GND
GND	11	30	AVCC
XTAL2	12	29	PC7 (TOSC2)
XTAL1	13	28	PC6 (TOSC1)
(RXD) PD0	14	27	PC5 (TDI)
(TXD) PD1	15	26	PC4 (TDO)
(INT0) PD2	16	25	PC3 (TMS)
(INT1) PD3	17	24	PC2 (TCK)
(OC1B) PD4	18	23	PC1 (SDA)
(OC1A) PD5	19	22	PC0 (SCL)
(ICP1) PD6	20	21	PD7 (OC2)

Device 2

AT Commands: MCU Coding

- `char` ack1,ack2;
- `void` sendsms() {
 puts("AT");
 ack1 = getchar();
 ack2 = getchar();
 if(ack1 == 'O' && ack2 == 'K') //check "OK"
 puts("ATD 9559753551;");
 return }

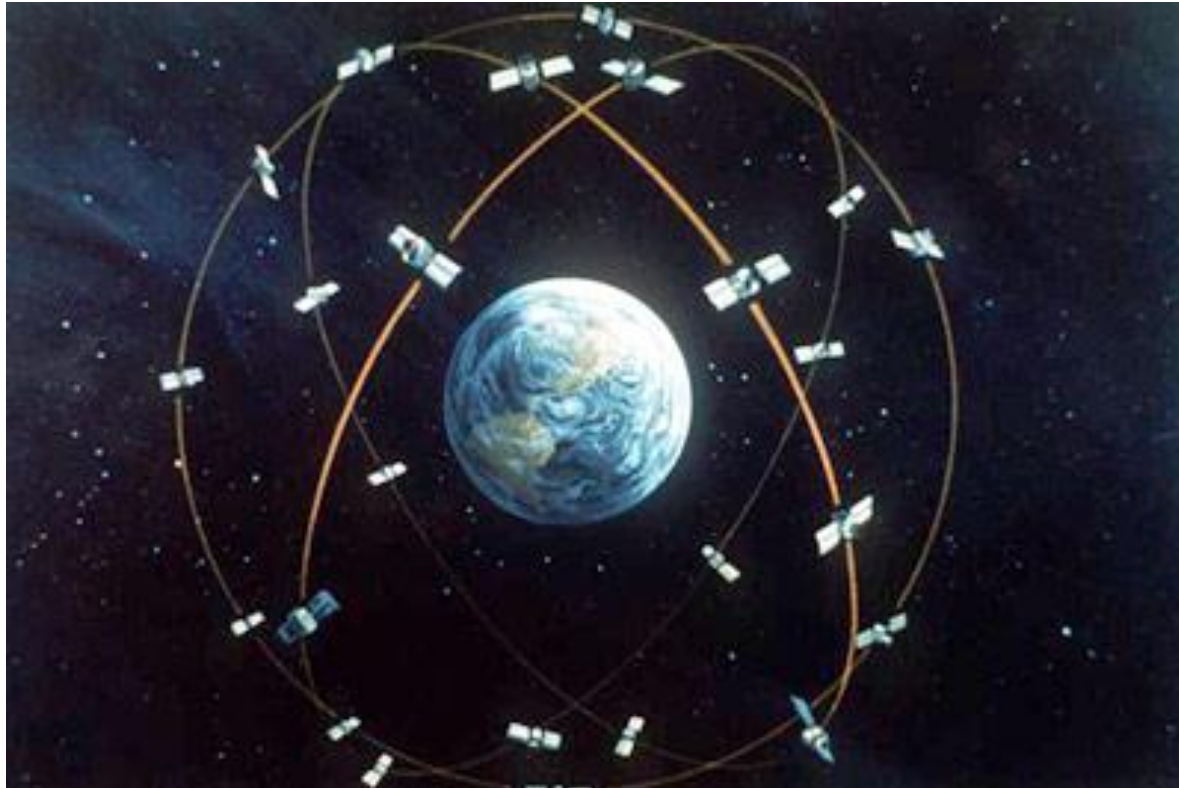
Agent Ethan Hunt

Impossible Missions Force

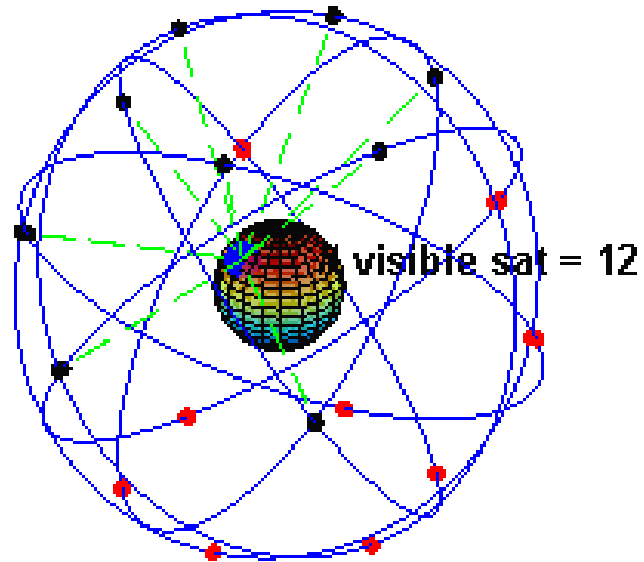


Mission: Hunting the bad guys !!

GPS: Global Positioning System



Visible Satellites



Distance Calculation

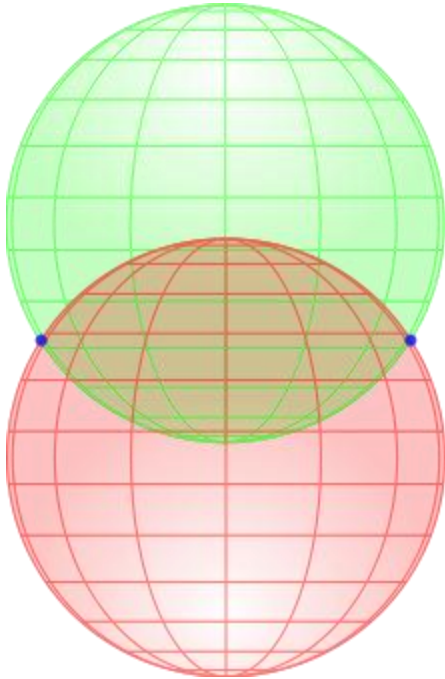


Value Sent: t_1
Time Sent : t_1

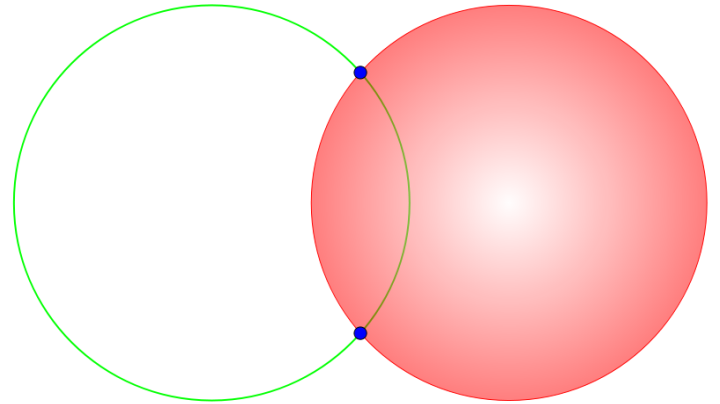
Value Received: t_2
Time Received : t_2

- Distance = speed x time taken
 $= c \times (t_2 - t_1)$

Triangulation Basics

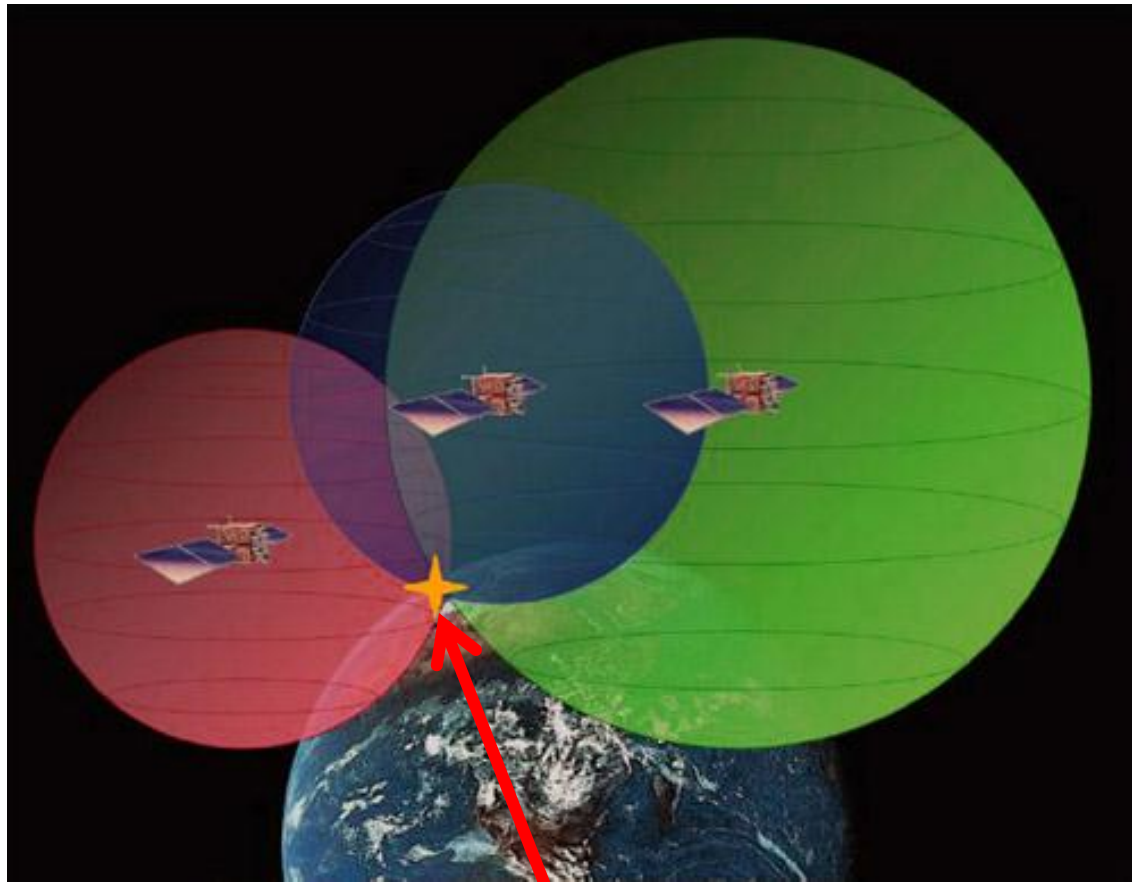


1. Two spheres intersecting in a circle.



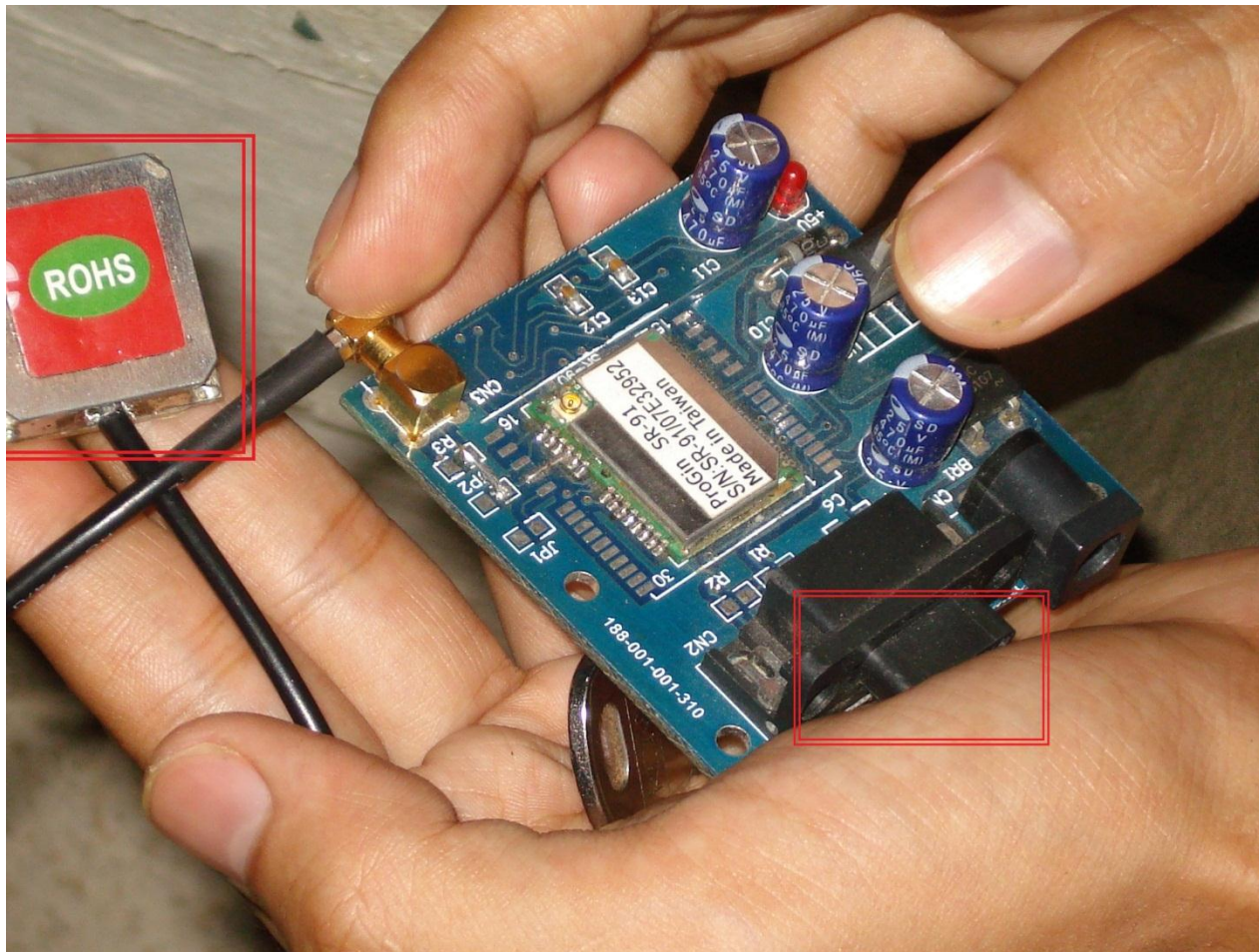
2. Surface of a sphere intersecting a circle.

Triangulation

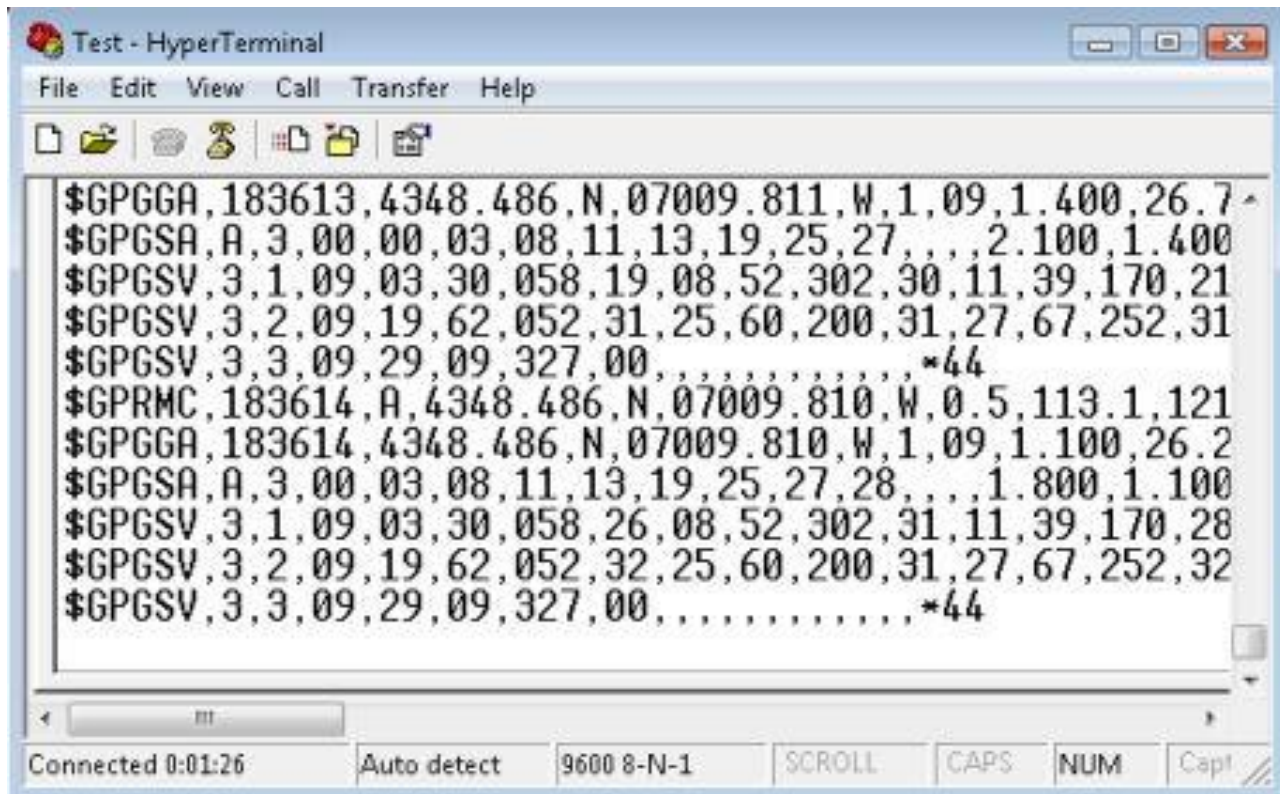


Target Locked: He is here !!

GPS Module



Terminal Data Collected



```
$GPGGA,183613,4348.486,N,07009.811,W,1,09,1.400,26.7-  
$GPGSA,A,3,00,00,03,08,11,13,19,25,27,...,2.100,1.400  
$GPGSV,3,1,09,03,30,058,19,08,52,302,30,11,39,170,21  
$GPGSV,3,2,09,19,62,052,31,25,60,200,31,27,67,252,31  
$GPGSV,3,3,09,29,09,327,00,...*44  
$GPRMC,183614,A,4348.486,N,07009.810,W,0.5,113.1,121  
$GPGGA,183614,4348.486,N,07009.810,W,1,09,1.100,26.2  
$GPGSA,A,3,00,03,08,11,13,19,25,27,28,...,1.800,1.100  
$GPGSV,3,1,09,03,30,058,26,08,52,302,31,11,39,170,28  
$GPGSV,3,2,09,19,62,052,32,25,60,200,31,27,67,252,32  
$GPGSV,3,3,09,29,09,327,00,...*44
```

Connected 0:01:26 Auto detect 9600 8-N-1 SCROLL CAPS NUM Ctrl

Terminal Settings can be found at:

<http://forum.delorme.com/viewtopic.php?t=12267>

NMEA Format

- \$GPGGA,123519,4807.038,N,01131.000,E,1,08,0.9,545.4,M,46.9,M,,*47
 - 2 is Latitude
 - 4 is Longitude
 - 6 is Quality //0: invalid, 1: GPS fix
 - 7 is No. of satellites in view

Detailed list of sentences can be found at:

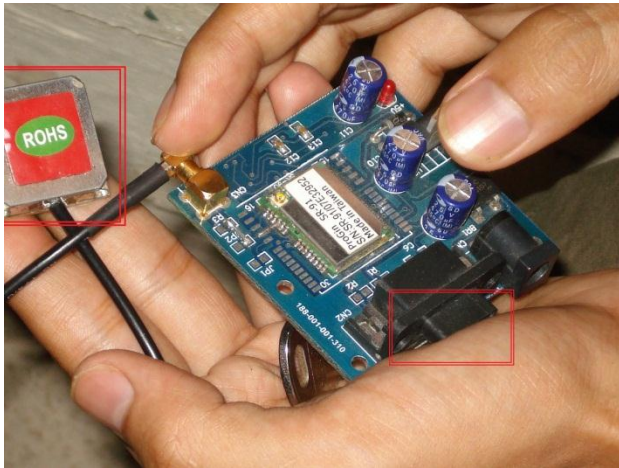
<http://aprs.gids.nl/nmea/>

GPS Visualizer

- Go to: <http://www.gpsvisualizer.com/>
- Upload your GPS file
- Get your map !!

[GPS-Visualizer.html](http://www.gpsvisualizer.com/GPS-Visualizer.html)

GPS: MCU Interface



Device 1

Rx	?	Tx
Tx	?	Rx
GND	?	GND

(XCK/T0) PB0	1	40	PA0 (ADC0)
(T1) PB1	2	39	PA1 (ADC1)
(INT2/AIN0) PB2	3	38	PA2 (ADC2)
(OC0/AIN1) PB3	4	37	PA3 (ADC3)
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(OC1B) PD4	18	23	PC1 (SDA)
(OC1A) PD5	19	22	PC0 (SCL)
(ICP1) PD6	20	21	PD7 (OC2)

Device 2

GPS: MCU Coding

- Enable UART buffer before you code.
- `char GPS_data[100];`

Pööple who are crazy enough to think they can change the world are the ones who usually do.

```
for( i = 0, i <= ; i++) {  
    GPS_data[i] = getchar();  
    lcd_puts(GPS_data); }  

```

UART buffer settings in CVAVR will soon be uploaded.

“People who are crazy enough to think they can change the world are the ones who usually do.”

