

# **Acoustic-Based Drone Detection**

## **Identifying UAVs Through Sound Signatures**

### **Mentor Evaluation - 1**

**Submitted by:**

**(102203449) Devansh Dhir**

**(102203061) Gautam Dhawan**

**(102203408) Ipsita Devgan**

**(102203012) Miet Pamecha**

**(102203413) Tamanna Bajaj**

**BE Third Year**

**CPG No. 179**

Under the Mentorship of

Dr. Sharad Saxena

Associate Professor



**Computer Science and Engineering Department**

**Thapar Institute of Engineering and Technology, Patiala**

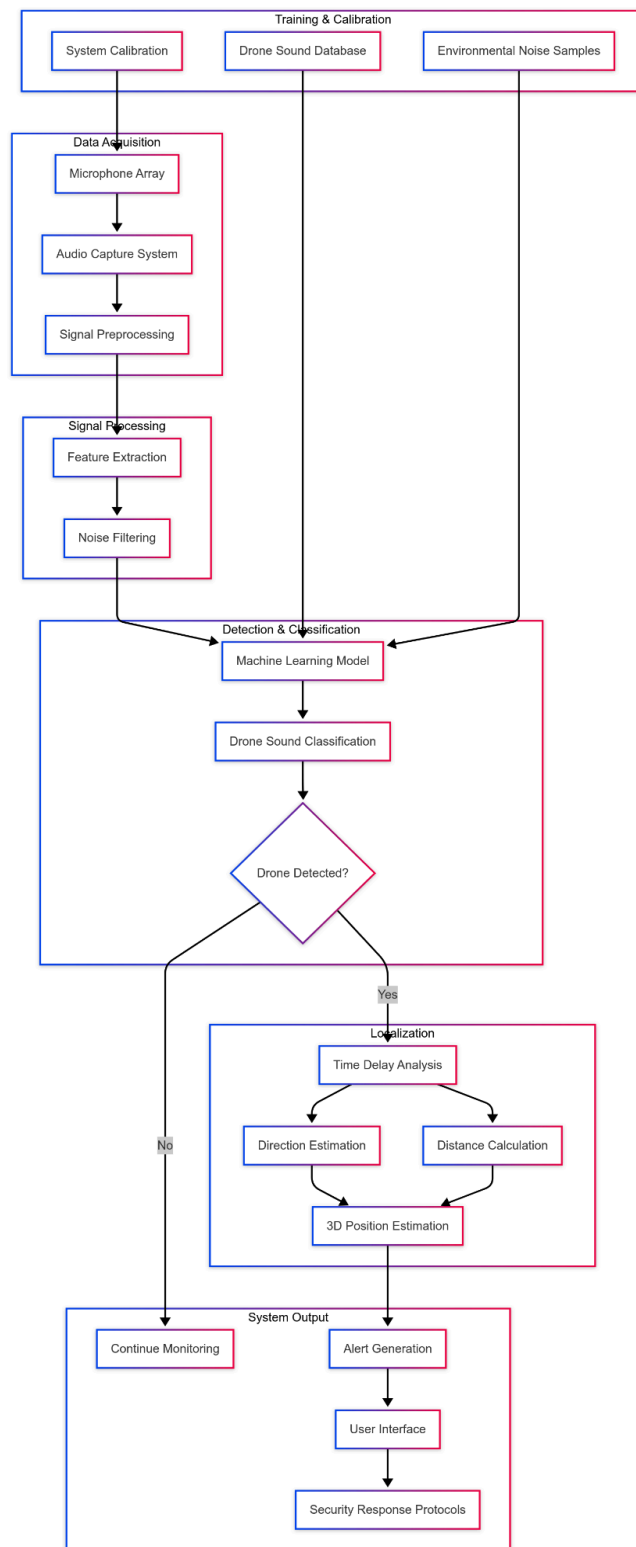
**APRIL 2025**

## TABLE OF CONTENTS

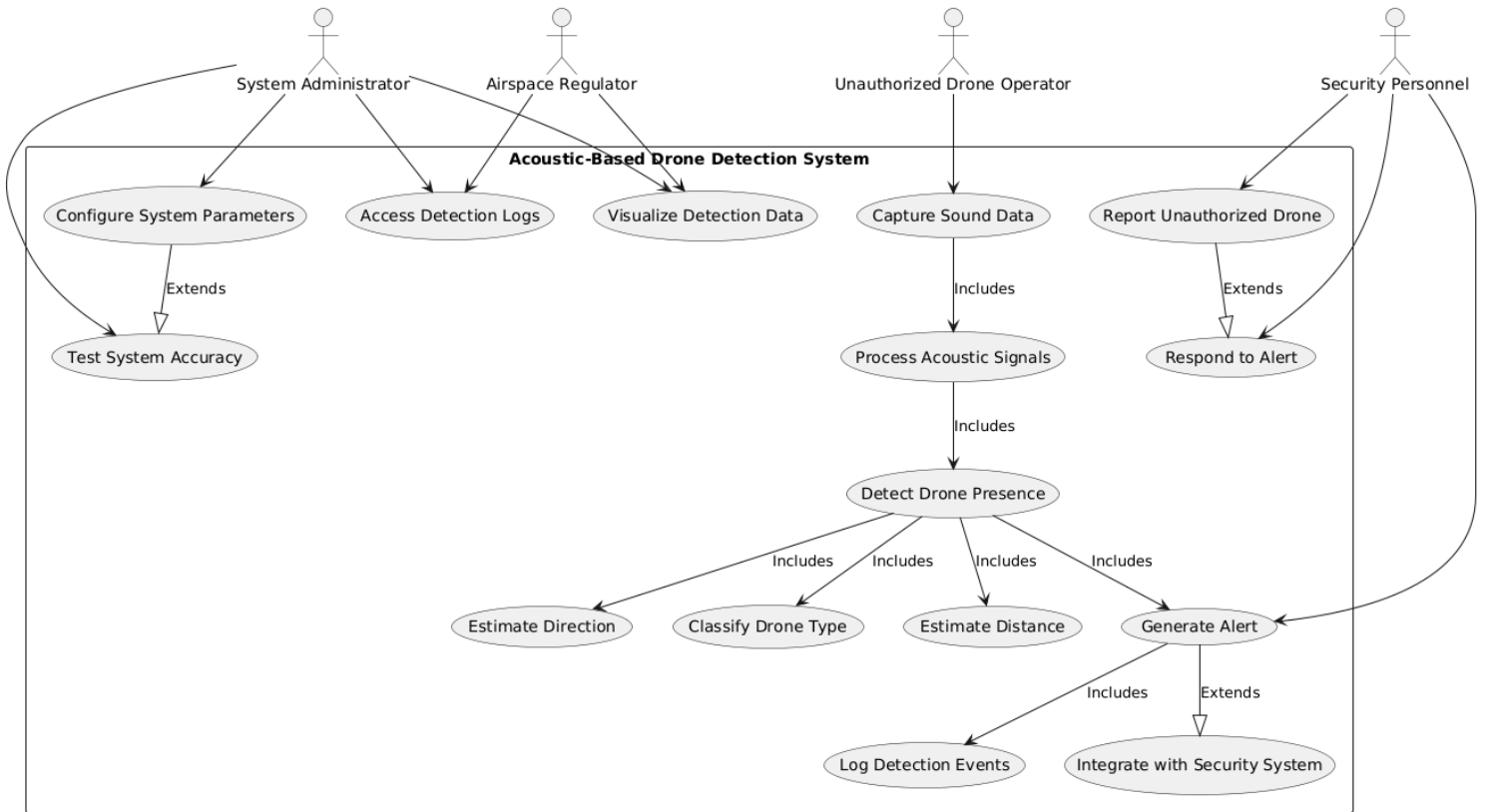
● Product Perspective	3
● Use Case Diagrams	4
● Tasks and Subtasks	10
● Swimlane Diagram	12
● Work Breakdown Structure	13
● Gantt Chart	14
● Functional & Non-Functional Requirements	15

## Product Perspective

The Acoustic Drone Detection System provides real-time identification and tracking of UAVs through advanced sound signature analysis. By leveraging microphone arrays and machine learning algorithms, the system enables non-intrusive monitoring of drones in diverse environments, offering a practical solution for enhancing airspace security and management in urban areas, event venues, and sensitive locations.



# Use Case Diagrams



# Use Case Templates

<b>1. Use Case Title</b>	Capture Sound Data
<b>2. Abbreviated Title</b>	CSD
<b>3. Use Case Id</b>	UC1
<b>4. Actors</b>	Drone Detection System , Unauthorized Drone Operator
<b>5. Description</b> The system captures ambient sound data using acoustic sensors to detect potential drone activity.	
<b>5.1. Pre Conditions:</b> System must be powered on and sensors must be functional.	
<b>5.2. Task Sequence</b>  1. System initializes acoustic sensors. 2. Continuous or periodic recording of environmental sounds. 3. Store captured sound data for further processing.	
<b>5.3. Post Conditions:</b>  1. Sound data is stored and ready for signal processing.	
<b>6. Modification History:</b> 01-04-2025	
<b>7. Author:</b> CPG 179	

<b>1. Use Case Title</b>	Process Acoustic Signals
<b>2. Abbreviated Title</b>	PAS
<b>3. Use Case Id</b>	UC2
<b>4. Actors</b>	Acoustic-Based Drone Detection System
<b>5. Description</b> The system processes recorded sound data to filter noise and extract relevant drone-related signals.	
<b>5.1. Pre Conditions:</b> Sound data must be available from the sensors.	
<b>5.2. Task Sequence</b>  1. Apply noise filtering techniques. 2. Extract features specific to drone sounds. 3. Prepare processed data for detection.	
<b>5.3. Post Conditions:</b>  <ul style="list-style-type: none"> <li>Processed acoustic signals are available for drone detection.</li> </ul>	
<b>6. Modification History:</b> 01-04-2025	
<b>7. Author:</b> CPG 179	

1. Use Case Title	Estimate Distance
2. Abbreviated Title	ED
3. Use Case Id	UC4
4. Actors	Acoustic-Based Drone Detection System
5. Description The system estimates the distance of a detected drone based on sound intensity analysis.	
5.1. Pre Conditions: Drone presence must be detected.	
5.2. Task Sequence  1. Measure sound intensity levels. 2. Use predefined models to approximate drone distance.	
5.3. Post Conditions:  • Estimated distance value is available.	
6. Modification History: 01-04-2025	
7. Author: CPG 179	

<b>1. Use Case Title</b>	Generate Alert
<b>2. Abbreviated Title</b>	GA
<b>3. Use Case Id</b>	UC5
<b>4. Actors</b>	Security Personnel, Acoustic-Based Drone Detection System
<b>5. Description</b> The system generates an alert if unauthorized drone activity is detected.	
<b>5.1. Pre Conditions:</b> Drone presence must be detected.	
<b>5.2. Task Sequence</b>  1. Send alert notification to security personnel. 2. Log detection event. 3. Optionally, trigger integration with security systems.	
<b>5.3. Post Conditions:</b>  <ul style="list-style-type: none"> <li>Security personnel is notified.</li> </ul>	
<b>6. Modification History:</b> 01-04-2025	
<b>7. Author:</b> CPG 179	



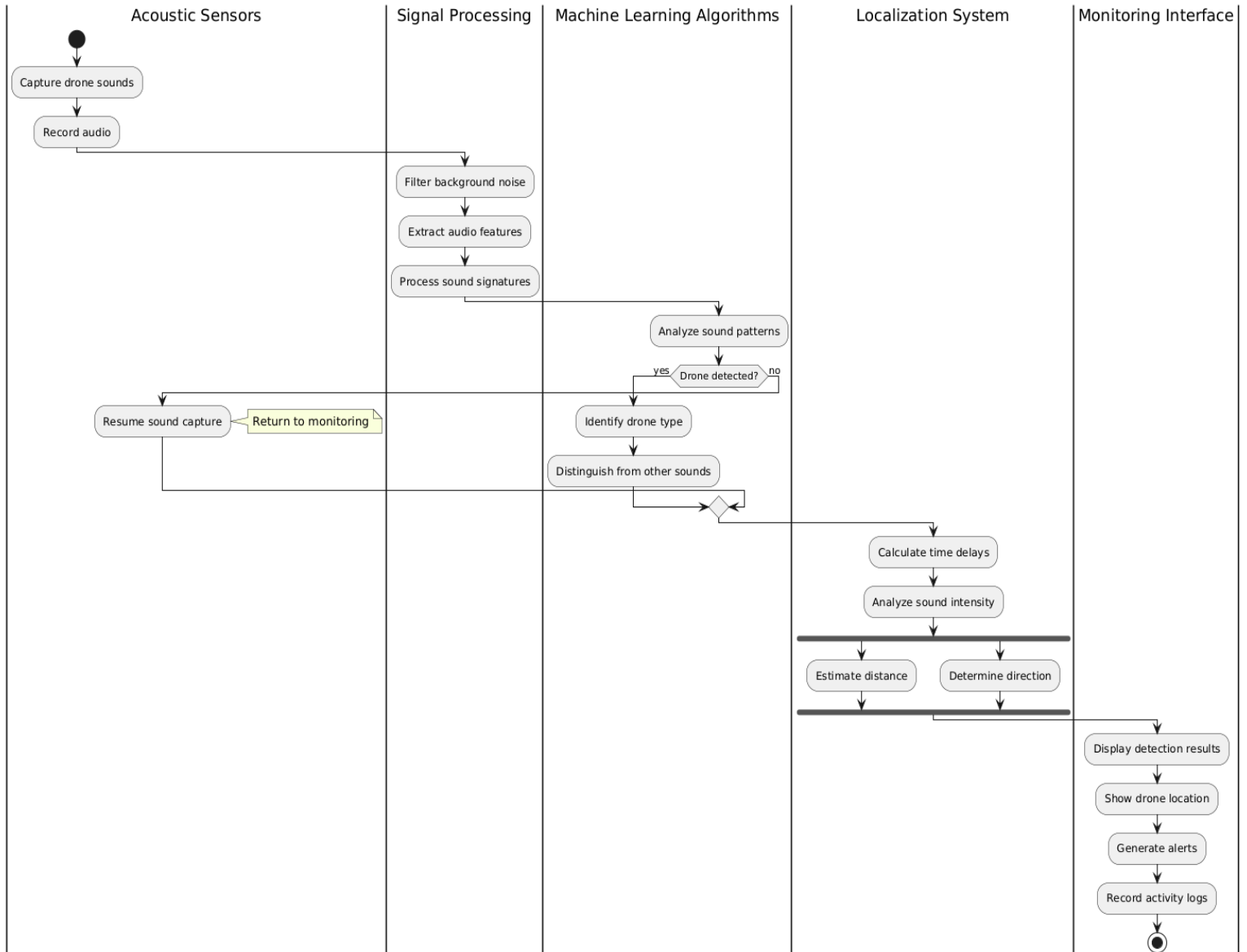
<b>1. Use Case Title</b>	Estimate Direction
<b>2. Abbreviated Title</b>	EDIR
<b>3. Use Case Id</b>	UC6
<b>4. Actors</b>	Acoustic-Based Drone Detection System
<b>5. Description</b> The system estimates the direction from which a detected drone is approaching.	
<b>5.1. Pre Conditions:</b> A drone must be detected.	
<b>5.2. Task Sequence</b>  1. Administrator logs into the system. 2. Admin views, adds, or modifies QR code placements.	
<b>5.3. Post Conditions:</b>  <ul style="list-style-type: none"> <li>Directional data is available.</li> </ul>	
<b>6. Modification History:</b> 01-04-2025	
<b>7. Author:</b> CPG 179	

## Tasks and Subtasks

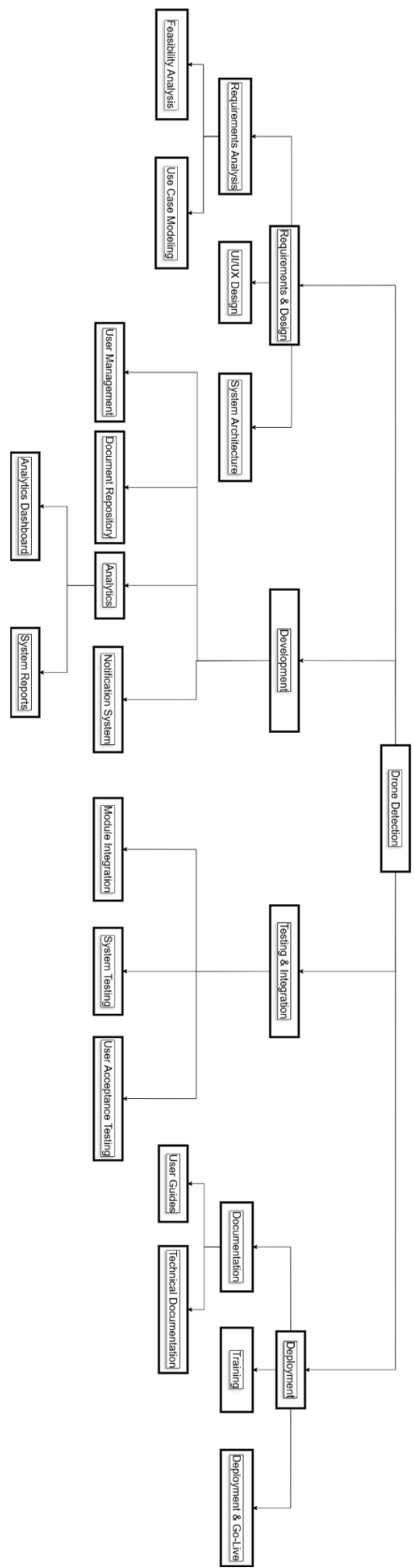
Task	Subtask
<ul style="list-style-type: none"> <li>Researching Hardware / Planning</li> </ul>	Identify required hardware components. Define project scope and goals.
<ul style="list-style-type: none"> <li>Testing Hardware / Data Collection</li> </ul>	Capture sounds from various drone models. Record at different distances and angles. Document flight modes. Record background noise in target environments.
<ul style="list-style-type: none"> <li>Data Preprocessing &amp; Feature Extraction</li> </ul>	Filter background noise. Normalize audio samples. Segment recordings into usable frames. Implement MFCC extraction. Process STFT. Extract time-domain features.
<ul style="list-style-type: none"> <li>Machine Learning Model Development</li> </ul>	Evaluate classifiers (CNN, SVM, etc.). Train models on dataset. Optimize hyperparameters. Test accuracy with validation data. Measure false positive/negative rates.
<ul style="list-style-type: none"> <li>Implementation of Distance &amp; Direction Estimation</li> </ul>	Implement time-delay localization algorithms. Develop beamforming techniques. Calibrate for accurate directional data. Create sound intensity analysis for distance estimation. Develop triangulation methods.
<ul style="list-style-type: none"> <li>Model Evaluation / Testing</li> </ul>	Evaluate in lab conditions. Measure detection accuracy & range. Test with multiple drones.
<ul style="list-style-type: none"> <li>System Integration / UI Development</li> </ul>	Create real-time processing pipeline. Implement detection algorithms. Design user dashboard. Create visualization components.

<ul style="list-style-type: none"> <li>● Performance Testing in Real-Time Environment</li> </ul>	<p>Deploy in real-world environments. Test in varying weather conditions. Document system limitations.</p>
<ul style="list-style-type: none"> <li>● Final Deliverables</li> </ul>	<p>Technical Documentation. Develop user manual and guides. Prepare demonstration materials.</p>

# Swimlane Diagram



# Work Breakdown Structure



## Gantt Chart

Sr. No.	Activity	Month	February				March				April				May				June				July				August				September				October				November			
		Week No.	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4						
1	Researching Hardware / Planning	Plan																																								
		Actual																																								
2	Testing Hardware / Data Collection	Plan																																								
		Actual																																								
3	Data Preprocessing & Feature Extraction	Plan																																								
		Actual																																								
4	Machine Learning Model Development	Plan																																								
		Actual																																								
5	Implementation of distance & direction estimation techniques	Plan																																								
		Actual																																								
6	Model Evaluation / Testing	Plan																																								
		Actual																																								
7	System Integration / UI Development	Plan																																								
		Actual																																								
8	Performance Testing in Real Time Environment	Plan																																								
		Actual																																								

# Functional and Non-Functional Requirements

## Functional Requirements

- **Sound Capture:** Capture drone sounds using microphones.
- **Audio Processing:** Continuously record and process audio.
- **Noise Reduction:** Apply noise reduction and filtering.
- **Sound Identification:** Identify and differentiate drone sounds.
- **Machine Learning Classification:** Use machine learning for classification.
- **Distance Estimation:** Estimate drone distance using sound intensity.
- **Direction Detection:** Determine drone direction using time-delay localization.
- **Monitoring Dashboard:** Offer a dashboard for real-time monitoring.

## Non-Functional Requirements

- **Real-Time Processing:** Process audio data in real-time.
- **Scalability:** Support multiple microphones for accuracy.
- **Large-Area Monitoring:** Scale for large-area coverage.
- **Detection Accuracy:** Achieve at least 90% detection accuracy.
- **Environmental Adaptability:** Perform reliably in different environments.
- **Error Reduction:** Minimize false positives and negatives.
- **Data Security:** Ensure secure data transmission and storage.
- **Regulatory Compliance:** Comply with data protection regulations.
- **Access Control:** Prevent unauthorized access.
- **User-Friendly Interface:** Provide an intuitive user interface.
- **Remote Access:** Support remote access via web or mobile.
- **Customizable Alerts:** Allow alert and notification customization.
- **Modular Design:** Ensure modular design for future upgrades.
- **System Updates:** Support updates without downtime.
- **Diagnostics & Troubleshooting:** Provide logs and diagnostics.
- **Operational Flexibility:** Operate in indoor and outdoor environments.
- **Weather Resistance:** Function under varying weather conditions.
- **Power Efficiency:** Be power-efficient with battery/solar support.