

Lab-VII

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1 Aim

Write and execute an octave program to simulate/solve motion of a particle in an EM field.

2 Theory

3 Program

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% MotionInEM
%
% Program to solve/simulate the motion of a particle in electromagnetic field
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graphics_toolkit gnuplot
pkg load symbolic

% function to compute accelerations
function retval = F(V, E, B, q, m)
    ax = (E(1) + V(2)*B(3) - V(3)*B(2)) * q/m;
    ay = (E(2) + V(3)*B(1) - V(1)*B(3)) * q/m;
    az = (E(3) + V(1)*B(2) - V(2)*B(1)) * q/m;
    retval = [ax, ay, az];
endfunction

% function to compute positions via RK45 method
function retval = Compute(t0, tf, steps, X, V, E, B, q, m)
    increment = (tf - t0) / steps;
    retval = [X];
    for i=t0:increment:tf
        k1 = F(V, E, B, q, m);

        k2 = F(V + increment*k1/2, E, B, q, m);
        k3 = F(V + increment*k2/2, E, B, q, m);
        k4 = F(V + increment*k3, E, B, q, m);

        X = X + increment*V + (increment**2)*(k1 + k2 + k3)/6;
        V = V + (k1 + 2*k2 + 2*k3 + k4)*increment / 6;
        retval = [retval; X];
    endfor
endfunction

printf("Solving equation of motions using RK45 method")

% Initial conditions
B = [0 0 1]
E = [0 0 1]
pos = [1 0 0]
V = [0 1 0.1]
q = 1
m = 1
t0 = 0
tf = 40
steps = 1000;

% calling the compute function to compute positions
X = Compute(t0, tf, steps, pos, V, E, B, q, m);

% plotting the trajectory
figure()
set(gca, 'XMinorTick', 'on', 'YMinorTick', 'on');
plot3(X(:, 1), X(:, 2), X(:, 3), "linewidth", 2);
xlabel("X");
ylabel("Y");
zlabel("Z");
title("Trajectory");
set(gcf, 'renderer', 'painters');
print("-dpng", "motion_in_em_traj.png");

% Computing current density
% set the symbolic vars
syms x y z pi;
% set the symbolic funcs
syms B_x(x, y, z) B_y(x, y, z) B_z(x, y, z);

% magnetic field
B = [B_x; B_y; B_z]
% Magnetic current density
J = curl(B) * 1e7 / 4*pi
```

4 Results

4.1 Terminal output

```
(escape) devansh@ds:~/GitHub/Vault/OctaveLab/Programs/outputs$ octave ../RungaKuttaMotionInEM.m
Solving equation of motions using RK45 methodB =

    0    0    1

E =

    0.10000    0.10000    0.00000

pos =

    1    0    0

V =

    0.00000    1.00000    0.10000

q = 1
m = 1
t0 = 0
tf = 40
Symbolic pkg v2.9.0: Python communication link active, SymPy v1.5.1.
B = (sym 3x1 matrix)


$$\begin{bmatrix} B_x(x, y, z) \\ B_y(x, y, z) \\ B_z(x, y, z) \end{bmatrix}$$


J = (sym 3x1 matrix)


$$\begin{bmatrix} \pi \cdot \left( -2500000 \cdot \frac{\partial}{\partial z} (B_y(x, y, z)) + 2500000 \cdot \frac{\partial}{\partial y} (B_z(x, y, z)) \right) \\ \pi \cdot \left( 2500000 \cdot \frac{\partial}{\partial z} (B_x(x, y, z)) - 2500000 \cdot \frac{\partial}{\partial x} (B_z(x, y, z)) \right) \\ \pi \cdot \left( -2500000 \cdot \frac{\partial}{\partial y} (B_x(x, y, z)) + 2500000 \cdot \frac{\partial}{\partial x} (B_y(x, y, z)) \right) \end{bmatrix}$$

```

4.2 Plots

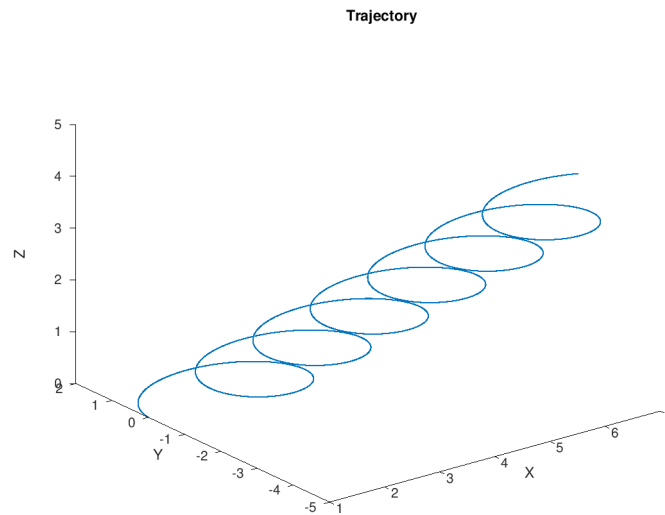


Figure 1: $B = \hat{k}$; $E = 0.1\hat{i} + 0.1\hat{j}$; $v = \hat{j} + 0.1\hat{k}$; $r = \hat{i}$; $q = 1C$; $m = 1kg$

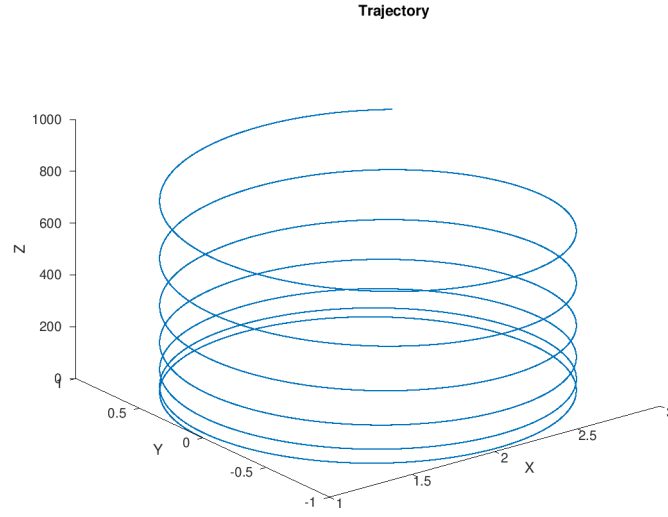


Figure 2: $B = \hat{k}$; $E = 1\hat{k}$; $v = \hat{j} + 0.1\hat{k}$; $r = \hat{i}$; $q = 1C$; $m = 1kg$

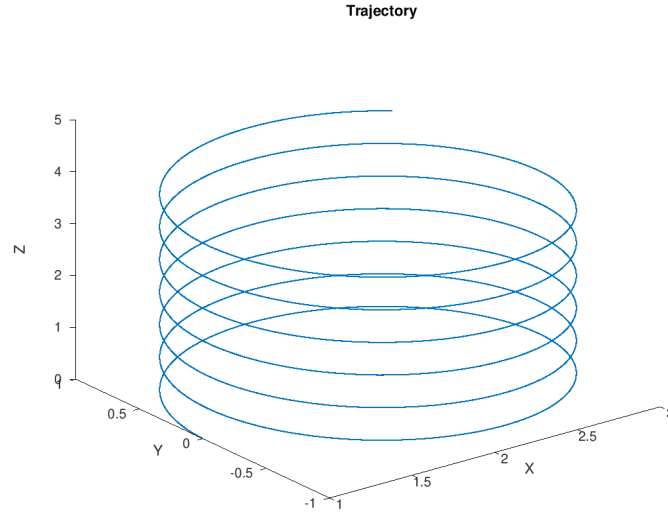


Figure 3: $B = \hat{k}$; $E = 0$; $v = \hat{j} + 0.1\hat{k}$; $r = \hat{i}$; $q = 1C$; $m = 1kg$

5 Remarks

The programs can be used to trace and simulate the motion of any particle in an electromagnetic field by defining the required parameters.