

# Physics 89 - Introduction to Mathematical Physics

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# 1 Difference between Mathematics and Physics

## Example 1 - Electrostatics

### Math Question

$$x + \frac{x^2}{2} + \frac{x^3}{3} + \frac{x^4}{4} + \dots = ?$$

### Math Solution

$$x + \frac{x^2}{2} + \frac{x^3}{3} + \dots = -\log(1-x), \quad \text{for } -1 \leq x \leq 1$$

So,

$$-1 + \frac{1}{2} - \frac{1}{3} + \frac{1}{4} - \frac{1}{5} + \dots = -\log(2)$$

## Example 2 - Diffusion

$f(x, y, z, t)$  = density of diffusing material at time  $t$

Let there exist a cube containing moles

$$\frac{\partial f}{\partial t} = D \left( \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \right)$$

where  $D$  is the *diffusion coefficient*, and the diffusion equation describes how  $f$  evolves with time

### Math Question

Solve

$$\frac{\partial f}{\partial t} = D \left( \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \right)$$

given initial condition

$f(x, y, z, 0)$  = concentrated lump at the origin

### Math Solution

$$f(x, y, z, t) = \frac{N}{(4\pi Dt)^{3/2}} e^{-\frac{x^2+y^2+z^2}{4Dt}}$$

where  $N$  is the number of moles released

## 2 Taylor Series

- Techniques for obtaining series
- Estimate error, converge?

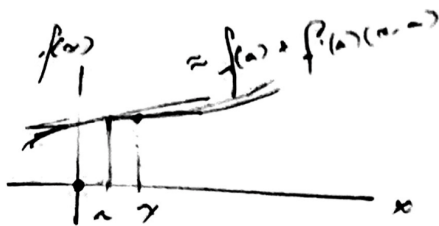


Figure 1: Taylor Series Visualization

$$f(x) \approx f(0) + f'(0)x + \cdots + \frac{1}{n!}f^n(0)x^n$$

$$f(x) \approx f(a) + f'(a)(x-a) + \frac{1}{2}f''(a)(x-a)^2 + \dots = \sum_{k=0}^{\infty} \frac{1}{k!}f^k(a)(x-a)^k$$

### Question

How good is this approximation?

*Big O notation*

$$\sum_{k=0}^n \frac{1}{k!}f^k(0)x^k + O(x^{n+1})$$

**Formally,**

$$F(x) = o(x^{n+1}) \quad \text{as } x \rightarrow 0$$

$$|F| \leq C|x|^{n+1} \quad \text{for some unexpected constant } c$$

$$\lim_{x \rightarrow 0} \frac{F}{|x|^{n+1}} = 0$$

### Example

$$e \approx 1.9 \text{ GeV} \approx 3700 mc^2$$

Special Relativity

$$\begin{aligned} E_k &= m_0 c^2 - mc^2 = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}} - mc^2 \\ &\approx 0 + \frac{1}{2}mv^2 + \frac{3}{8}m\frac{v^4}{c^2} + \frac{5}{16}m\frac{v^6}{c^4} \\ f(v) &= \frac{1}{2}mv^2 + \frac{3}{8}m\frac{v^4}{c^2} + \dots \end{aligned}$$

$$\frac{1}{\sqrt{1-x}} \rightarrow \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$(1+x)^P, \quad \text{then set } p = \frac{1}{2}$$

$$\begin{aligned} f(x) &= (1+x)^n \\ f'(x) &= p(1+x)^{p-1} \\ f^k(x) &= p(p-1)\dots(p-k+1)(1+x)^{p-k} \rightarrow f^k(0) \\ &= p\dots(p-k+1) \end{aligned}$$

$$(1+x)^n \approx 1 + px + \frac{p(p-1)}{2!}x^2 + \dots + \frac{p!}{k!(p-k)!}x^k = \binom{p}{k}x^k$$

$$\sum_{k=0}^n \binom{p}{k} x^k \quad \text{generalized binomial coefficient}$$

$$(1+x)^P = \sum_{k=0}^n \binom{p}{k} x^k + O(x^{n+1})$$

### Question

Given  $\frac{1}{\sqrt{1+x}}$  Taylor series, how good is this approximation if  $x = 0.1$ ?

### Solution

$$\text{Actual Answer} \rightarrow \frac{1}{\sqrt{1.1}} = 0.9534626$$

$$\text{Taylor Polynomials } x, x^2 \rightarrow 1 - \frac{0.1}{2} = 0.95 \quad / \quad 1 - \frac{0.5}{2} + \frac{3(0.5)^2}{8} = 0.95375 \quad \text{good approx}$$

### *More Taylor Series*

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

$$\cosh x = \frac{e^x + e^{-x}}{2} = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \frac{x^6}{6!} + \dots$$

$$\sinh x = \frac{e^x - e^{-x}}{2} = x - \frac{x^3}{3!} + \frac{x^5}{5!} + \dots$$

## 2.1 Testing for Convergence

If  $\sum_0^\infty a_n x^n \leq \infty$  converges,

$$\sum_0^\infty a_n (\lambda X)^n \leq \infty \quad |\lambda| \leq 1$$

Taylor Series have interval of convergence of the form

$$[-L, L] \quad (-L, L) \quad [-L, L) \quad (-L, L]$$

### Truncated Taylor Series Approximation

$$R_0(x) = f(x) - f(0) = f'(c)x$$

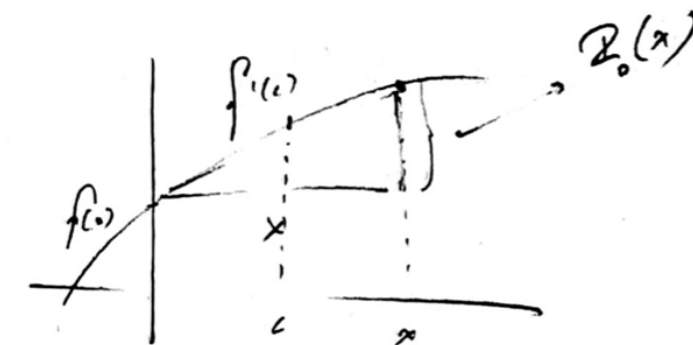


Figure 2: Remainder Visualized

### Remainder Theorem

$$R_n(x) = f^{(n+1)}(c) \frac{x^{n+1}}{(n+1)!} \quad \text{for some } 0 \leq c \leq x$$

$$\begin{aligned} x &= \frac{\pi}{2} \\ R &= \sin \frac{\pi}{2} - \left( x - \frac{x^3}{6} + \frac{x^5}{120} - \frac{x^7}{5040} + \frac{x^9}{362880} + 0 \right) \\ &= f^{(10)}(c) \frac{x^{10}}{10!} \quad 0 \leq c \leq \frac{\pi}{2} \end{aligned}$$

$$|f^{(11)}(c)| = |-\cos c| < 1$$

$$|R_{10}| \leq \frac{1}{11!} \left( \frac{\pi}{2} \right)^{11} \approx 3.6 \times 10^{-6}$$

*Technique for Solving Taylor Series by dividing two polynomials*

$$f(x) = a_0 + a_1x + \dots$$

$$g(x) = b_0 + b_1x + \dots$$

$$\frac{f(x)}{g(x)} = (c_0 + c_1x + c_2x^2 + \dots)$$

$$a_0 + a_1x + \dots = (b_0 + b_1x + \dots)(c_0 + c_1x + \dots)$$

$$a_0 = b_0c_0$$

### 3 Complex Numbers

- Definition
- Functions:  $\log z$ ,  $\sqrt{z}$ ,  $\sin z$ , etc.
- Applications: AC Circuits, Hydrodynamics
- Math Applications:  $\int_{-\infty}^{\infty}$

#### 3.1 Taylor Series

$$f(x) = \frac{1}{1+x^2} = \frac{1}{1-(-x^2)} = 1 - x^2 + x^4 - x^6 + \dots = \sum_{n=0}^{\infty} (-1)^n x^{2n}$$

The interval of convergence for the Taylor series of  $\frac{1}{1+x^2}$  is from  $(-1, 1)$ , which is not readily apparent since

$$\text{@ } x \pm 1, f(x) = \frac{1}{2}$$

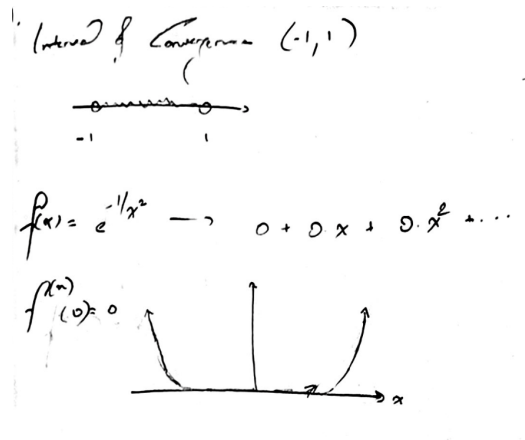


Figure 3: Taylor series of  $e^{1/x^2}$

#### 3.2 Complex Numbers

Introduced by *Cardano* in the 1500s with the intent of solving cubic equations.

##### Quadratic Equations

$$0 = x^2 + bx + c \quad x = -b \pm \frac{\sqrt{b^2 - 4ac}}{2a}$$



### Cubic Equations

$$0 = x^3 + ax + b \quad \left( \frac{-b}{2} + \sqrt{\frac{b^2}{4} - \frac{a^3}{27}} \right)^{\frac{1}{3}}$$

$$x^3 - x = 0 \rightarrow x = \frac{1}{\sqrt{3}} \left[ \sqrt{-1}^{1/3} + (-\sqrt{-1})^{1/3} \right]$$

- consistency
- final answer is **real**
- simplifies computations

#### 3.2.0.1 Rules of Complex Numbers

$$z = a + bi$$

$$i^2 = -1$$

$$(a + bi)(c + di) = (ac - bd) + (ad + bc)i$$

#### Example

$$(1 + i)^2 = 2i$$

$$i^4 = 1$$

$$\begin{aligned} \frac{1}{a + bi} &= \frac{(a + bi)}{(a - bi)(a + bi)} = \frac{(a - bi)}{a^2 + b^2} \\ &= \left( \frac{a}{a^2 + b^2} \right) - \left( \frac{b}{a^2 + b^2} \right) i \end{aligned}$$

### 3.3 Applications

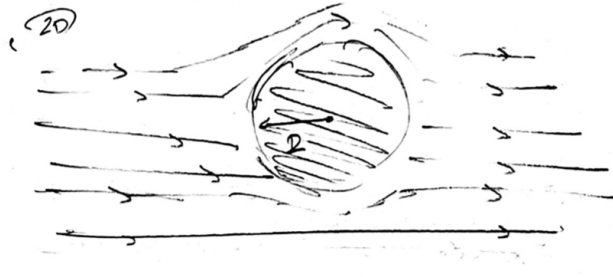


Figure 4: 2D diagram of Sphere from above

#### 3.3.0.1 Hydrodynamics

$$\vec{v}(x, y) = v_x \hat{i} + v_y \hat{j}$$

Problem

$$V_x, V_y = ?$$

Model

1. Incompressible

$$(a). \quad 0 = \nabla \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}$$

2. Irrotational

$$(b.) \quad 0 = (\nabla \times \vec{v})_z = \frac{\partial v_x}{\partial x} - \frac{\partial v_x}{\partial y}$$

### Solving (a) and (b)

Set of **coupled** partial differential equations (PDEs)

- What are the Boundary Conditions?
  - an additional set of equations at the edges

$$(1.) \quad r = \sqrt{x^2 + y^2} \rightarrow \infty \quad \vec{v} \rightarrow v_0 \hat{i}$$

$$(2.) \quad \vec{v} \cdot \hat{r} = 0$$

**Fact:** Complex Numbers

Define  $z = x + iy$ ,  $z$  is **not** the third coordinate

Define  $U = v_x \hat{i} - iv_y$  and  $U = f(z) \rightarrow$  Equations (a.) and (b.) are automatically satisfied.

### Solution

$$U = v_0 \left( 1 - \frac{R^2}{z^2} \right)$$

$$\frac{1}{z} = \frac{1}{x + iy} = \frac{x - iy}{x^2 + y^2}$$

$$\frac{1}{z^2} = \frac{x^2 - y^2 - 2ixy}{(x^2 + y^2)^2}$$

$$v_x = v_0 - \frac{v_0 R^2 (x^2 - y^2)}{(x^2 + y^2)^2}$$

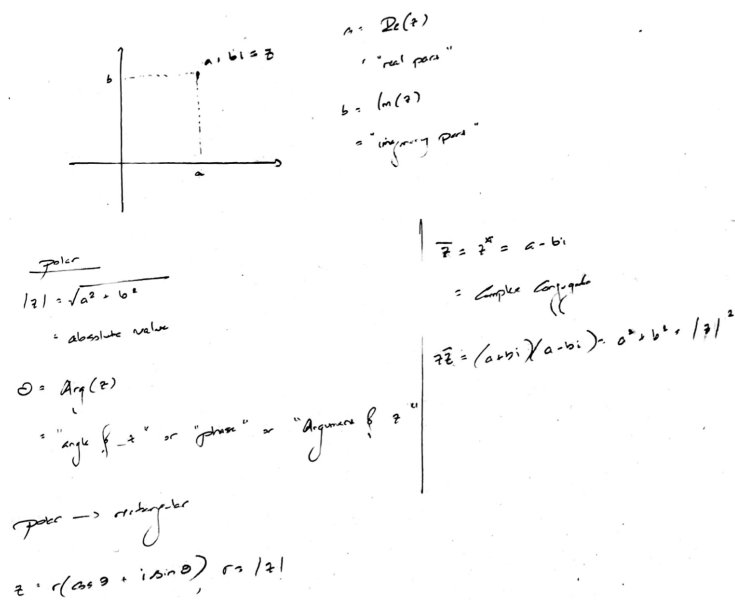


Figure 5: complex plane

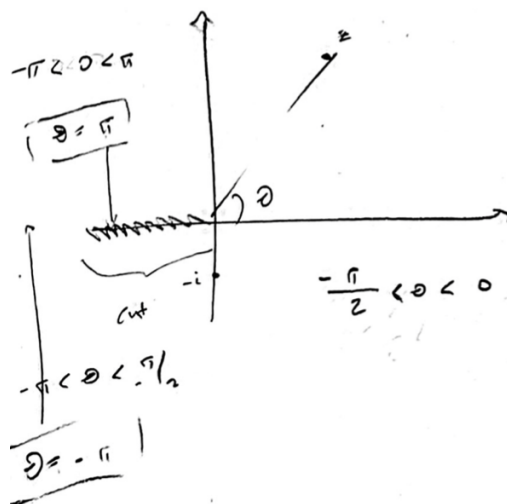


Figure 6: quadrant's of complex plane in polar coordinates

### 3.3.0.2 The Complex Plane

### 3.3.0.3 Euler's Identity

$$\cos \theta + i \sin \theta = e^{i\theta}$$

$$e^x = 1 + \frac{x}{1} + \frac{x^2}{2} + \frac{x^3}{3!} + \dots \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

$$\begin{aligned} e^{iy} &= 1 + \frac{iy}{1} - \frac{y^2}{2!} - \frac{iy^3}{3!} + \frac{y^4}{4!} + \dots \\ &= \left(1 - \frac{y^2}{2!} + \frac{y^4}{4!} + \dots\right) + \left(\frac{y}{1} - \frac{y^3}{3!} + \dots\right)i = \cos y + i \sin y \end{aligned}$$

#### Euler's Identities

$$\begin{aligned} e^{i\pi} &= -1 \\ 1 = e^{2\pi i} &= e^{2\pi ni} \quad n = 0, \pm 1, \pm 2, \dots \end{aligned}$$

$$\log z = ?$$

$$z = re^{i\theta}$$

$$\log z = \log r + i(\theta + 2\pi n)$$

$$\sqrt{z}$$

$$\begin{aligned} \sqrt{re^{iz}} &= \sqrt{r}e^{i\theta/2} \\ &= \sqrt{r}e^{\frac{i(\theta+2\pi)}{2}} \\ &= -\sqrt{r}e^{i\theta/2} \end{aligned}$$

### 3.3.0.4 Trigonometric Functions

$$\cos z = \frac{e^{iz} + e^{-iz}}{2}$$

$$\sin z = \frac{e^{iz} - e^{-iz}}{2i}$$

$$\cos(iy) = \frac{e^{-y} + e^y}{2} = \cosh y$$

$$\sin(iy) = i \frac{e^y - e^{-y}}{2} = i \sinh y$$

### 3.4 Hyperbolic Functions

$$\tanh = \frac{\sinh y}{\cosh y}$$

Everything is **Real** from now on.

#### 3.4.0.1 Identities

$$\sinh(\alpha + \beta) = \sinh \alpha \cosh \beta + \cosh \alpha \sinh \beta$$

$$\cosh(\alpha + \beta) = \cosh \alpha \cosh \beta + \sinh \alpha \sinh \beta$$

$$\tanh(\alpha + \beta) = \frac{\tanh \alpha + \tanh \beta}{1 + \tanh \alpha \tanh \beta}$$

#### 3.4.0.2 Applications to Special Relativity Relativistic Addition to Velocities

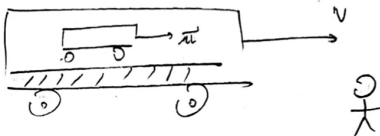


Figure 7: a train moving with a car moving inside of it, what would an observer calculate for the speed of the interior car?

$$iW = \frac{u + v}{1 + \frac{uv}{c^2}} = c \frac{\tanh \alpha + \tanh \beta}{1 + \tanh \alpha \tanh \beta} = c \tanh(\alpha + \beta)$$

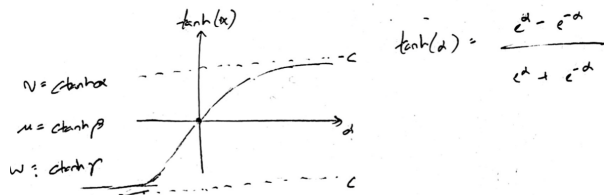


Figure 8: rapidity - using hyperbolic tangent establishes the bounds of velocity as  $c$  and  $-c$

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Functions of Complex Variables

- Cauchy - Riemann Eqns
- Taylor Series
- $\int_{-\infty}^{\infty}$

- Singularities, Poles, Residue

The Complex Conjugate

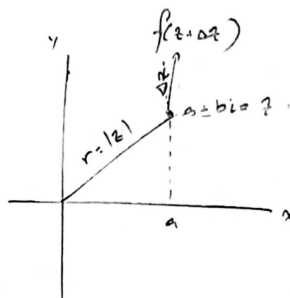


Figure 9: graphing complex numbers

$$\bar{z} = a - bi \quad z\bar{z} = a^2 + b^2 = |z|^2$$

Functions of  $z = x + iy$

$$\begin{aligned} \operatorname{Re} Z &= x \\ \operatorname{Im} Z &= y \\ |z| &= \sqrt{x^2 + y^2} \\ \bar{z} &= x - iy \end{aligned}$$

## Analytic Functions

$$\begin{aligned} & \frac{1}{z} \\ & z^2 \\ & e^z \\ & \sin z \\ & \cos z \end{aligned}$$

$$f(z) = u + iv$$

$$u = u(x, y)$$

$$v = v(x, y)$$

Analytic Functions are the functions where you can write

$$f(z + \Delta z) - f(z) = f'(z)\Delta z + O(\Delta z^2) \quad \Delta z \rightarrow 0$$

**Note**

$$f(x + \Delta x, y + \Delta y) - f(x, y) = \left( \frac{\partial f}{\partial x} \right) \Delta x + \left( \frac{\partial f}{\partial y} \right) \Delta y + \dots$$

**Check**

$$\begin{aligned} e^{z+\Delta z} &= e^z e^{\Delta z} = e^z (1 + \Delta z + \dots) \\ e^{z+\Delta z} - e^z &= e^z \delta z + \dots = f''(z) \delta z + \dots \end{aligned}$$

Therefore,  $e^{z+\Delta z}$  is *analytic*. However,

$$\bar{z} + \Delta \bar{z} - \bar{z} = \bar{\Delta} z$$

$$\Delta z = \Delta x \rightarrow \bar{\Delta} z = (1)\Delta z \quad \text{Horizontal}$$

$$\Delta z = i\Delta y \rightarrow \bar{\Delta} z = -i\Delta y = (-1)\Delta z \quad \text{Vertical}$$



$$f(z) = u + iv$$

$$\frac{f(x + \Delta x, y) - f(x)}{\Delta x} = f'(z)$$

$$\frac{f(x, y + \Delta y) - f(x, y)}{i\Delta y} = f'(z) = \frac{\partial f}{\partial y} \frac{1}{i}$$

$$\begin{aligned} \frac{\partial f}{\partial x} &= \frac{1}{i} \frac{\partial f}{\partial y} \\ \left( \frac{\partial u}{\partial x} \right) + i \left( \frac{\partial v}{\partial x} \right) &= \frac{1}{i} \left[ \left( \frac{\partial u}{\partial y} \right) + i \left( \frac{\partial v}{\partial y} \right) \right] \\ &= \frac{\partial v}{\partial y} - i \frac{\partial u}{\partial y} \end{aligned}$$

#### Cauchy Riemann Equations

$$\begin{aligned} \frac{\partial u}{\partial x} &= \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} &= -\frac{\partial v}{\partial x} \end{aligned}$$

#### *Example*

$$f(z) = x^2 - y^2 + 2ixy$$

$$\begin{aligned} u &= x^2 - y^2 \\ v &= 2xy \end{aligned}$$

$$\frac{\partial u}{\partial x} = 2x = \frac{\partial v}{\partial y}$$

$$\frac{\partial u}{\partial y} = -2y = -\frac{\partial v}{\partial x}$$

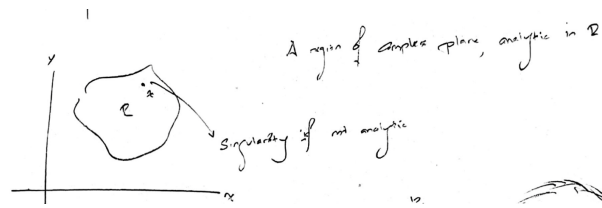


Figure 10: a region in the complex plane

### 3.4.0.3 Taylor Series

$$f(z) = \sum_{n=0}^{\infty} a_n z^n \quad \text{converges if analytic}$$

Given a constant  $\lambda$

$$0 < \lambda < 1$$

$$f(\lambda z) = \sum_{n=0}^{\infty} a_n (\lambda z)^n \quad \text{definitely converges}$$

$$|a_n z^n \lambda^n| = |a_n z^n| |\lambda|^n$$

Let  $\lambda = r e^{i\theta}$ ,  $0 < r < 1$ ,  $|\lambda| < 1$

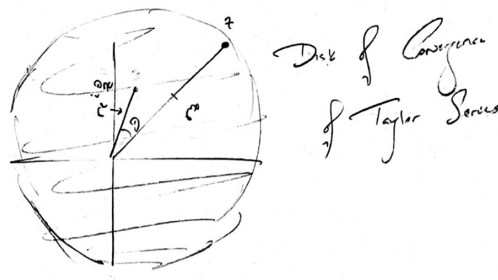


Figure 11: disk of convergence of power series



Figure 12: disk of convergence is disk with maximum radius inside  $R$



### 3.4.0.4 Path Integrals

$$\int_{-\infty}^{\infty} \left( \frac{\sin x}{x} \right) dx = \pi$$

$$\int_{-\infty}^{\infty} \frac{dx}{x^2 + 1} = \arctan x \Big|_{-\infty}^{\infty} = \pi$$

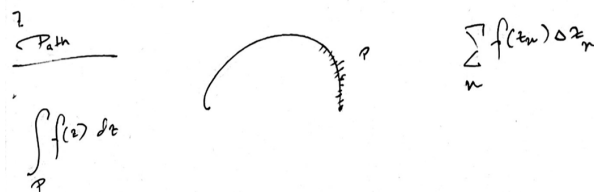


Figure 15: path  $P$

#### Technique

Parametrize  $P$  from  $0 < t < \pi$  as  $z(t)$

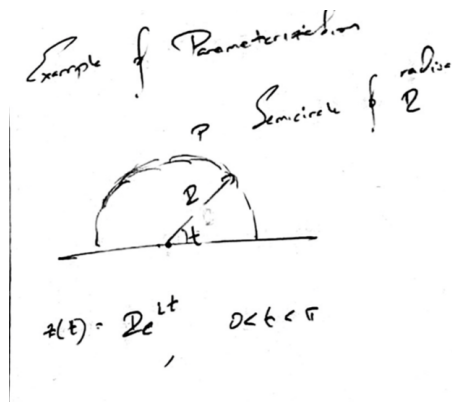


Figure 16: example of parameterizing  $z(t)$

$$\int_P f(z) dz = \int_a^b f(z(t)) \left( \frac{dz}{dt} \right) dt$$

$$f(z) = z^3$$

$$\frac{dz}{dt} = iRe^{it}$$

$$f(z(t)) = (Re^{it})^3 = R^3 e^{3it}$$

**Collect**

$$\begin{aligned}\int_0^\pi f(z(t)) \left( \frac{dz}{dt} \right) dt &= \int_0^\pi R^3 e^{3it} (iR e^{it}) dt \\ &= iR^4 \int_0^\pi e^{4it} dt = \frac{iR^4}{4i} e^{4it} \Big|_0^\pi = 0 \\ e^{4\pi i} &= 1\end{aligned}$$

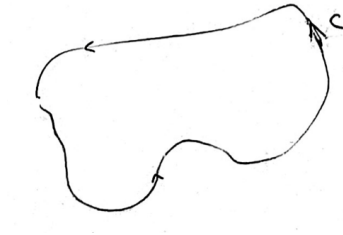


Figure 17: contour integral path

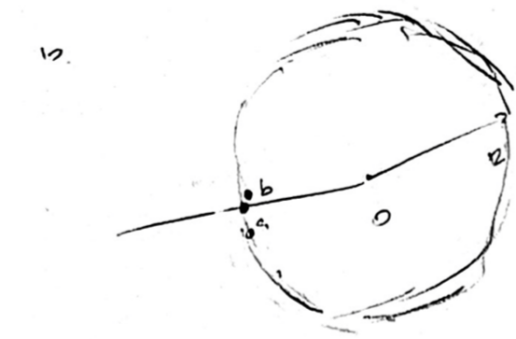
**3.4.0.5 Contour Integrals** Contour Integrals = 0 for any analytic function that is analytic for the entire region C

$$\begin{aligned}\oint_C f(z) dz &= 0 \\ &= \int_0^{2\pi} R^n e^{nit} \frac{dz}{dt} dt \\ &= \int_0^{2\pi} R^n e^{nit} iR e^{it} dt \\ &= iR^{n+1} \int_0^{2\pi} e^{i(n+1)t} dt \\ &= \frac{iR^{n+1}}{i(n+1)} e^{i(n+1)t} \Big|_0^{2\pi} = 0\end{aligned}$$

**Effect of Singularities**

Let  $n = -1$

$$\begin{aligned}f(z) &= \frac{1}{z} \\ \oint_C \frac{dz}{z} &= iR^{n+1} \int_0^{2\pi} e^{i(n+1)t} dt \\ &= i \int_0^{2\pi} dt = 2\pi i \neq 0\end{aligned}$$



$$\begin{aligned}
 & \overline{f(z)} = \log(z) \\
 & f(b) \rightarrow \log(r) + i\pi \\
 & f(a) \rightarrow \log(r) - i\pi \\
 & \underline{f(b) - f(a) = 2i\pi}
 \end{aligned}$$

Figure 18: Fundamental Theorem of Contour Integrals

$$\int_a^b f(z) dz = F(b) - F(a)$$

**Example**

$$\begin{aligned}
 f(z) &= \frac{1}{z^2 + 1} & \alpha &= i \\
 &= \frac{1}{(z - i)(z + i)} = \frac{1}{z - i} \left( \frac{1}{z + i} \right)
 \end{aligned}$$

$$f(z) = \frac{g(z)}{z - \alpha}$$

$$\begin{aligned} f(z) &= \frac{1}{z - \alpha} [g(\alpha) + (z - \alpha)g'(\alpha) + \dots] \\ &= \frac{g(\alpha)}{z - \alpha} + g'(\alpha) + \dots \end{aligned}$$

$$\oint_C f(z) dz = \oint_C' f(z) dz = \oint_D f(z) dz = \oint \frac{g(\alpha)}{z - \alpha} dz$$

**Jan 31**

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Main Topic

- Tensors (Vectors First)

### 3.4.0.6 Analytic Functions

$$f(z) = x + iy = \sum_{n=0}^{\infty} a_n (z - \alpha)^n$$

Taylor series around  $\alpha$  – Disk of Convergence

### 3.4.0.7 Cauchy Riemann Equations

$$f(z) = u + iv$$

$$u = \operatorname{Re} f$$

$$v = \operatorname{Im} f$$

Cauchy Riemann Equations

$$\begin{aligned}\frac{\partial u}{\partial x} &= \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} &= -\frac{\partial v}{\partial x}\end{aligned}$$





$$\vec{v} = v_x \hat{i} + v_y \hat{j}$$

$$\vec{v}(z) = v_x - i v_y \longrightarrow \text{if } v(z) \text{ is analytic}$$

- ① fluid is incompressible ( $\text{div } \vec{v} = 0$ )
- ② fluid is irrotational ( $\text{curl } \vec{v} = \vec{0}$ )

$\uparrow$   
 Cauchy  
 Riemann  
 eqs

Figure 19: velocity field of a fluid obeying Cauchy-Riemann Equations

#### 3.4.0.8 Hydrodynamics If $v(z)$ is analytic

- Incompressible:  $\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} = 0$
- Irrotational:  $\frac{\partial v_x}{\partial y} - \frac{\partial v_y}{\partial x} = 0$

#### 3.4.0.9 Contour Integrals

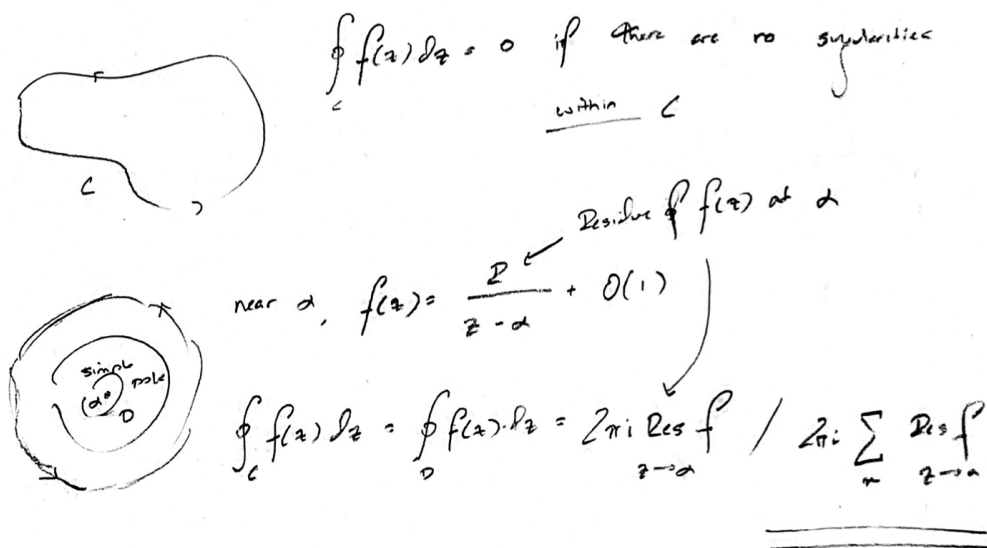


Figure 20: Equation for contour integrals with a singularity:  $2\pi i \sum_n \operatorname{Res}_{z \rightarrow \alpha} f$

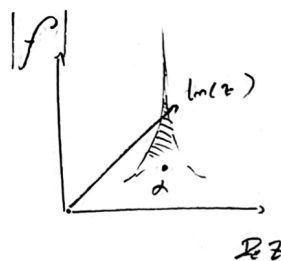


Figure 21: it's called a singularity / simple pole because the magnitude of the function approaches infinity at  $\alpha$

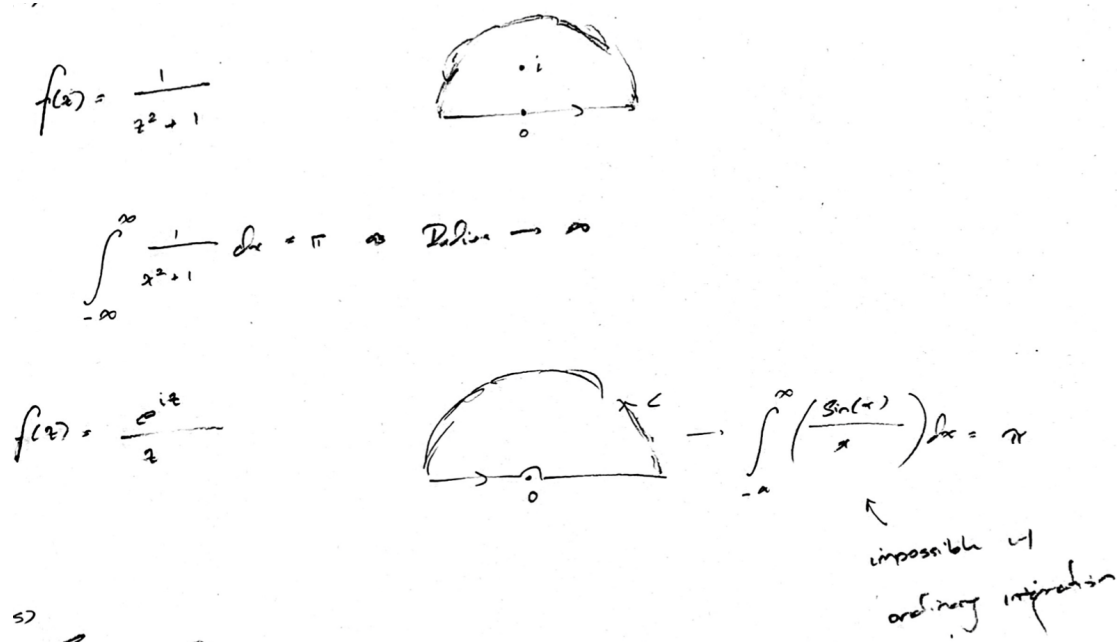


Figure 22: Examples of integrals that are easier with Contour Integration

### Theorem

$\sum_{n=0}^{\infty} a_n(z - \alpha)^n$  converges with nonzero radius of convergence for every  $\alpha \in R$

$f(z)$  is a analytic function in region  $R$ .

#### 3.4.0.10 Computing Res $f$ at $\alpha$

$$f(z) = \frac{g(z)}{h(z)} \approx \frac{g(\alpha)}{(z - \alpha)h'(\alpha)} = \frac{g(\alpha)/h'(\alpha)}{z - \alpha} = \frac{R}{z - \alpha}$$

## 4 Tensors

### 4.1 Vectors first

#### Goal

Geometric notion of a vector — Algebraic notion of a vector

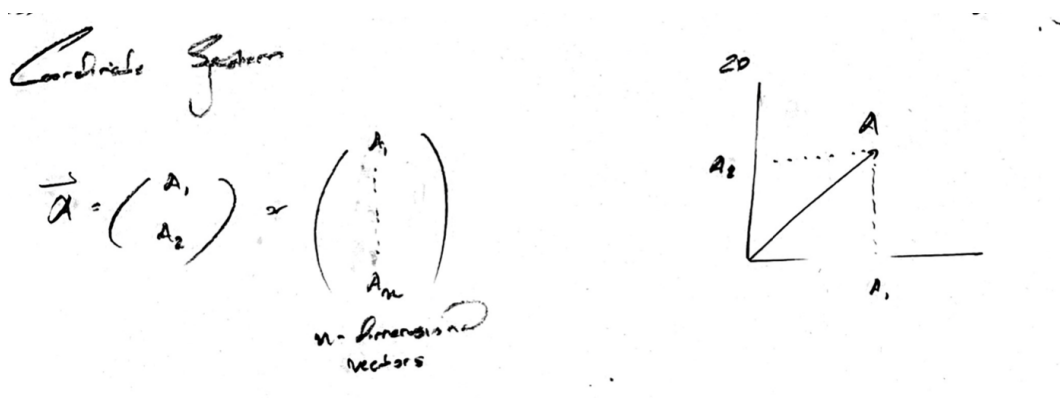


Figure 23: matrix vector visualization

$$\begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

The Rotation Matrix

$$A'_j = \sum_{i=1}^2 R_{ji} A_i$$

Example

$$\begin{aligned} A'_2 &= \sum_{i=1}^2 R_{2i} A_i = R_{21} A_1 + R_{22} A_2 \\ &= -\sin \theta A_1 + \cos \theta A_2 \end{aligned}$$

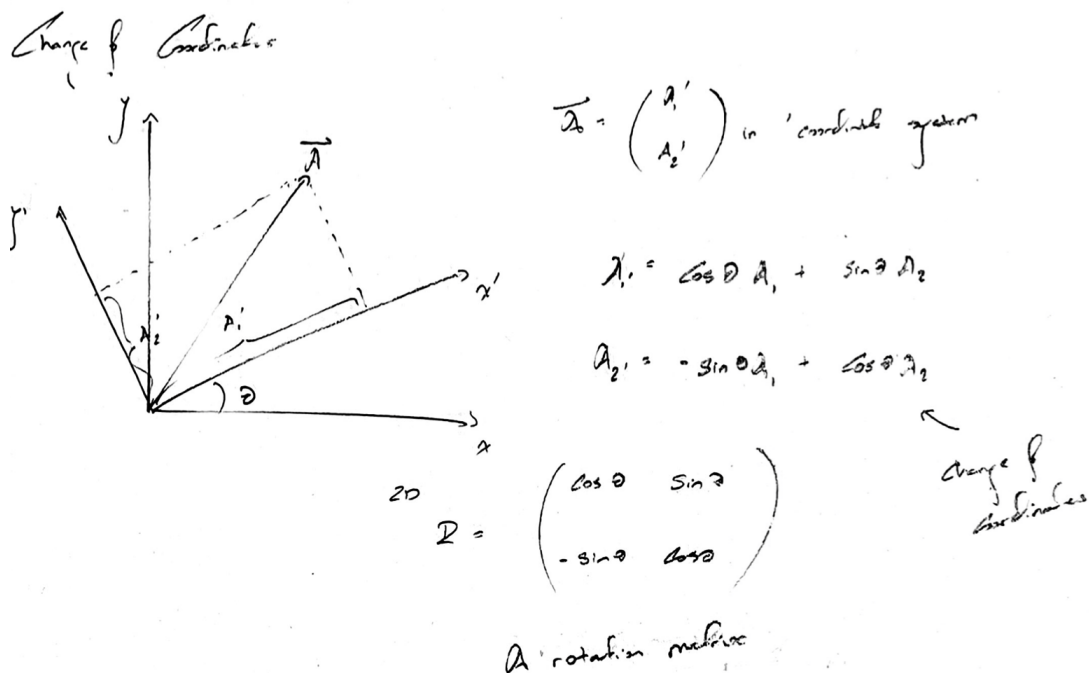


Figure 24: Changing Coordinates - Rotation Matrices

### Tensors

Made up of components  $\frac{\partial v_i}{\partial x_j}$ .

Each derivative component of the tensor has different values from different coordinate systems.

### Simple Tensors

Two Vectors

$$\vec{A}, \vec{B}$$

Then

$$T_{ij} = A_i B_j$$

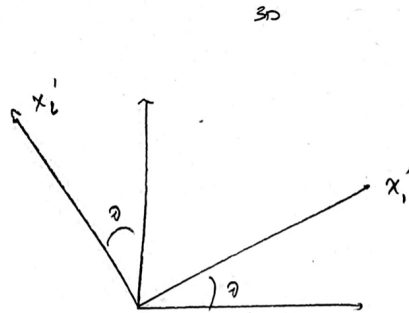


Figure 25: Prime vs. Unprimed coordinate axes

$$T'_{ij} = A'_i B'_j = \left( \sum_{k=1}^2 R_{jk} A_k \right) \left( \sum_{l=1}^2 R_{jl} B_l \right)$$

$$= \sum_{k=1}^2 \sum_{l=1}^2 R_{ik} R_{jl} A_k B_l$$

Tensor Transformation Law

$$T'_{ij} = \sum_{k=1}^2 \sum_{l=1}^2 R_{ik} R_{jl} T_{kl}$$

**Example:** Theory of Elasticity

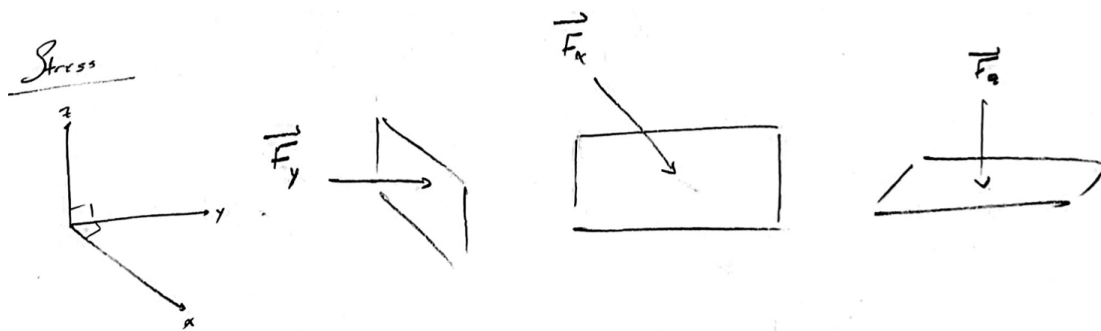


Figure 26: Parallel forces on surfaces perpendicular to their axis

$$\vec{S}_1 = \lim_{\Delta y \Delta z \rightarrow 0} \frac{\vec{F}_x}{\Delta y \Delta z}$$

$$\vec{S}_2 = \lim_{\Delta x \Delta z \rightarrow 0} \frac{\vec{F}_y}{\Delta x \Delta z}$$

$$\vec{S}_3 = \lim_{\Delta x \Delta y \rightarrow 0} \frac{\vec{F}_z}{\Delta x \Delta y}$$

$$S_{ij} = (\vec{S}_i)_j \quad i, j = 1, 2, 3, \dots \quad \text{Stress Tensor}$$

Using the stress tensor:

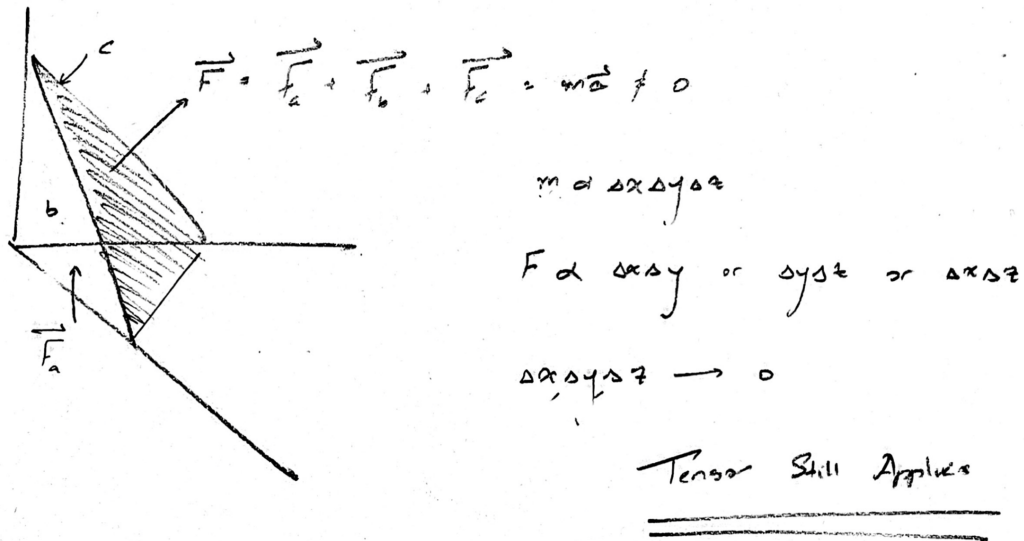


Figure 27: to calculate the force on the triangle, you can sum the forces on the edges  $a, b, c$  of the triangle

The forces  $S_{11}, S_{22}, S_{33}$  are "pushing forces"

The forces  $S_{12}, S_{23}, S_{13}, \dots$  are "shear forces"

#### 4.1.0.1 Dot Product

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \phi$$

In components,

$$\vec{A} \cdot \vec{B} = \sum_{i=1}^3 A_i B_i = \sum_{i=1}^3 \sum_{j=1}^3 C_{ij} A_i B_j$$

$$\delta_{ij} = C_{ij} = 1 \quad i = j$$

$$\delta_{ij} = C_{ij} = 0 \quad i \neq j$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Kronecker Delta Symbol Tensor

Checking Tensor Transformation Law:

$$\delta'_{ij} = \sum_{k=1}^2 \sum_{l=1}^2 R_{ik} R_{jl} \delta_{kl}$$

is correct for any rotation in any dimension

#### 4.1.0.2 Cross Product

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \end{vmatrix}$$

$$(\vec{A} \times \vec{B})_i = \sum_{j=1}^3 \sum_{k=1}^3 C_{ijk} A_j B_k$$

$$C_{ijk} = 1 \quad ijk = (123), (231), (312)$$

$$C_{ijk} = -1 \quad ijk = (132), (321), (213)$$

$$C_{ijk} = 0 \quad i = j, i = k, j = k$$

The Levi - Civita Tensor