

Physics 8A

Vectors & Tensors

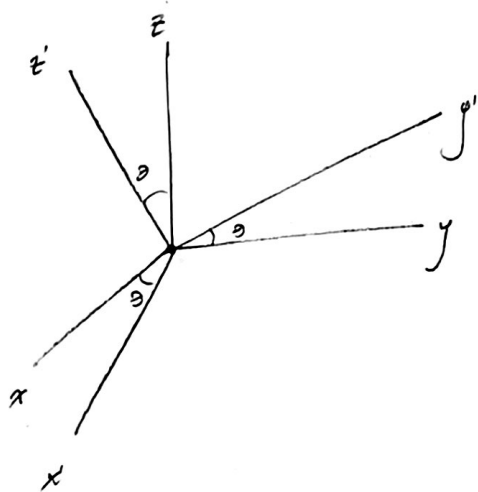
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1 TENSORS

$$A'_i = \sum_{k=1}^2 P_{ik} A_k$$

$$T'_{ij} = \sum_{k=1}^2 \sum_{l=1}^2 P_{ik} P_{jl} T_{kl}$$

$$P = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$



$$a) T'_{11} = \sum_{k=1}^2 \sum_{l=1}^2 P_{1k} P_{1l} T_{kl}$$

$$= T_{11} P_{11} P_{11} + T_{21} P_{12} P_{11} + T_{12} P_{11} P_{12} + T_{22} P_{12} P_{12}$$

$$= T_{11} \cos^2 \theta + T_{21} \sin \theta \cos \theta + T_{12} \cos \theta \sin \theta + T_{22} \sin^2 \theta$$

$$T'_{12} = \sum_{k=1}^2 \sum_{l=1}^2 P_{1k} P_{2l} T_{kl}$$

$$= T_{11} P_{11} P_{21} + T_{21} P_{12} P_{21} + T_{12} P_{11} P_{22} + T_{22} P_{12} P_{22}$$

$$= -T_{11} \cos \theta \sin \theta - T_{21} \sin^2 \theta + T_{12} \cos^2 \theta + T_{22} \sin \theta \cos \theta$$

$$T'_{21} = \sum_{k=1}^2 \sum_{l=1}^2 P_{2k} P_{1l} T_{kl} = T_{11} P_{21} P_{11} + T_{21} P_{22} P_{11} + T_{12} P_{21} P_{12} + T_{22} P_{22} P_{12}$$

$$= -T_{11} \sin \theta \cos \theta + T_{21} \cos^2 \theta \sin \theta - T_{12} \sin^2 \theta + T_{22} \cos \theta \sin \theta$$

$$T'_{22} = \sum_{k=1}^2 \sum_{l=1}^2 P_{2k} P_{2l} T_{kl}$$

$$= T_{11} P_{21} P_{21} + T_{21} P_{22} P_{21} + T_{12} P_{21} P_{22} + T_{22} P_{22} P_{22}$$

$$= T_{11} \sin^2 \theta - T_{21} \cos \theta \sin \theta - T_{12} \cos \theta \sin \theta + T_{22} \cos^2 \theta$$

b) Symmetric Tensor $\rightarrow T_{12} = T_{21}$

$$T'_{12} = \sum_{k=1}^2 \sum_{l=1}^2 P_{1k} P_{2l} T_{kl} = -T_{11} \cos \theta \sin \theta - T_{21} \sin^2 \theta + T_{12} \cos^2 \theta + T_{22} \sin \theta \cos \theta$$

$$T'_{21} = \sum_{k=1}^2 \sum_{l=1}^2 P_{2k} P_{1l} T_{kl} = -T_{11} \sin \theta \cos \theta + T_{21} \cos^2 \theta - T_{12} \sin^2 \theta + T_{22} \cos \theta \sin \theta$$

$$\text{if } T_{21} = T_{12}$$

$$T'_{21} = T'_{12}$$

c) $T_{12} = T_{21} = 0$

$$T'_{12} = -T_{11} \cos \theta \sin \theta + T_{22} \cos \theta \sin \theta = -\cos \theta \sin \theta (T_{11} - T_{22}) \Rightarrow \alpha = -\cos \theta \sin \theta$$

d) $T_{ij} = \delta_{ij} (T_{11} = T_{22} = 1, T_{12} = T_{21} = 0) \quad T'_{ij} = \delta_{ij}$

$$T'_{11} = \cos^2 \theta + \sin^2 \theta = \underline{\underline{1}}$$

$$T'_{21} = \sin \theta \cos \theta - \cos \theta \sin \theta = \underline{\underline{0}}$$

$$T'_{12} = T'_{21} = \underline{\underline{0}}$$

$$T'_{22} = \sin^2 \theta + \cos^2 \theta = \underline{\underline{1}}$$

$$T'_{11} = T'_{22} = 1$$

$$T'_{12} = T'_{21} = 0$$

$$\rightarrow T'_{ij} = \underline{\underline{\delta_{ij}}}$$

2. BASES OF VECTOR SPACES

$$\vec{v} = a\hat{x} + b\hat{y} + c\hat{z}$$

$$\vec{x} = \hat{x} + \hat{y} \quad \vec{y} = \hat{x} + \hat{z} \quad \vec{z} = \hat{y} + \hat{z}$$

$$\vec{v} = \alpha\vec{x} + \beta\vec{y} + \gamma\vec{z}$$

$$\alpha\vec{x} = \alpha \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad \beta\vec{y} = \beta \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \quad \gamma\vec{z} = \gamma \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \alpha \\ \alpha \\ 0 \end{pmatrix} + \begin{pmatrix} \beta \\ 0 \\ \beta \end{pmatrix} + \begin{pmatrix} 0 \\ \gamma \\ \gamma \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 0 & a \\ 1 & 0 & 1 & b \\ 0 & 1 & 1 & c \end{array} \right) \Rightarrow \left(\begin{array}{ccc|c} 1 & 0 & 0 & \frac{a+b-c}{2} \\ 0 & 1 & 0 & \frac{a-b+c}{2} \\ 0 & 0 & 1 & \frac{-a+b+c}{2} \end{array} \right)$$

$$\alpha = \frac{1}{2}(a+b-c)$$

$$\beta = \frac{1}{2}(a-b+c)$$

$$\gamma = \frac{1}{2}(-a+b+c)$$

3. VECTOR SPACES OF FUNCTIONS

a) Expand functions e^x, e^{-x} in the basis $[\sinh(x), \cosh(x)]$

$$\sinh(x) = \frac{e^x - e^{-x}}{2} \quad \cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$e^x = \cosh(x) + \sinh(x)$$

$$e^{-x} = \cosh(x) - \sinh(x)$$

b) $[\sinh(x), \sinh(x+a)]$ at 0

$$\sinh(x) = \frac{e^x - e^{-x}}{2} \quad \sinh(x+a) = \frac{e^{x+a} - e^{-x-a}}{2}$$

$$e^x = \alpha \sinh(x) + \beta \sinh(x+a)$$

$$e^{-x} = -\alpha \sinh(x) - \beta \sinh(x+a)$$

$$= \alpha \left(\frac{e^x - e^{-x}}{2} \right) + \beta \left(\frac{e^{x+a} - e^{-x-a}}{2} \right)$$

$$= \frac{1}{2} \alpha e^x - \frac{1}{2} \alpha e^{-x} + \frac{1}{2} \beta e^{x+a} - \frac{1}{2} \beta e^{-x-a} = e^x$$

$$e^{-x} = \alpha \sinh(-x) + \beta \sinh(-x-a)$$

$$= \frac{1}{2} \alpha e^{-x} - \frac{1}{2} \alpha e^x + \frac{1}{2} \beta e^{-x-a} - \frac{1}{2} \beta e^{x+a} = e^{-x}$$

$$\begin{pmatrix} \sinh(x) & \sinh(x+a) & e^x \\ -\sinh(x) & -\sinh(x+a) & e^{-x} \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & \frac{\sinh(x+a)}{\sinh(x)} & \frac{e^x}{\sinh(x)} \\ \frac{\sinh(x)}{\sinh(x+a)} & 1 & \frac{e^{-x}}{-\sinh(x+a)} \end{pmatrix}$$

$$\begin{pmatrix} 1 & \frac{\sinh(x+a)}{\sinh(a)} & \frac{e^x}{\sinh(a)} \\ -\sinh(x) & -\sinh(x+a) & e^{-x} \end{pmatrix} \xrightarrow{R_1 + \sinh(x) R_2} \begin{pmatrix} 1 & \frac{\sinh(x+a)}{\sinh(a)} & \frac{e^x}{\sinh(a)} \\ 0 & 0 & 2\cosh(x) \end{pmatrix}$$

$$\xrightarrow{R_2 \cdot \frac{1}{2\cosh(x)}} \begin{pmatrix} 1 & \frac{\sinh(x+a)}{\sinh(a)} & \frac{e^x}{\sinh(a)} \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 - \frac{e^x}{\sinh(a)} R_2} \begin{pmatrix} 1 & \frac{\sinh(x+a)}{\sinh(a)} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$d + \beta \frac{\sinh(x+a)}{\sinh(a)} = 0$$

$$d \sinh(a) + \beta \sinh(x+a) = e^x$$

$$\vec{e} = d \begin{pmatrix} e^x \\ -\frac{e^x}{2} \end{pmatrix} + \beta \begin{pmatrix} \frac{e^{x+a} - e^{-x-a}}{2} \end{pmatrix}$$

$$= \frac{1}{2} d e^x - \frac{1}{2} d e^{-x} + \frac{1}{2} \beta e^{x+a} - \frac{1}{2} \beta e^{-x-a}$$

Not
Possible w/o
Parameterization

4. ORTHOGONAL VECTORS

$$\vec{N}_1 = \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix} \quad \vec{N}_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \quad \vec{N}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \quad f = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$a) |\vec{N}_1| = 2$$

$$|\vec{N}_2| = 2$$

$$|\vec{N}_3| = \sqrt{10}$$

$$\hat{e}_1 = \frac{\vec{N}_1}{|\vec{N}_1|} = \begin{pmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{pmatrix}$$

$$\hat{e}_2 = \frac{\vec{N}_2}{|\vec{N}_2|} = \begin{pmatrix} 1/2 \\ -1/2 \\ 1/2 \\ -1/2 \end{pmatrix}$$

$$\hat{e}_3 = \frac{\vec{N}_3}{|\vec{N}_3|} = \begin{pmatrix} 1/\sqrt{10} \\ 1/\sqrt{10} \\ 1/\sqrt{10} \\ 1/\sqrt{10} \end{pmatrix}$$

$$\vec{u}_1 = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} \quad \vec{u}_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \quad \vec{u}_3 = \begin{pmatrix} 1 \\ 7 \\ 1 \end{pmatrix}$$

$$\vec{u} = f - \text{proj}_{\vec{u}_1} f - \text{proj}_{\vec{u}_2} f - \text{proj}_{\vec{u}_3} f$$

$$= f - \frac{\langle f, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1 - \frac{\langle f, \vec{u}_2 \rangle}{\langle \vec{u}_2, \vec{u}_2 \rangle} \vec{u}_2 - \frac{\langle f, \vec{u}_3 \rangle}{\langle \vec{u}_3, \vec{u}_3 \rangle} \vec{u}_3$$

$$= f - \frac{u_1}{|\vec{u}_1|^2} - \frac{u_2}{|\vec{u}_2|^2} - \frac{u_3}{|\vec{u}_3|^2}$$

$$= f - \frac{u_1}{4} - \frac{u_2}{4} - \frac{u_3}{100} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 1/4 \\ 1/4 \\ -1/4 \\ -1/4 \end{pmatrix} - \begin{pmatrix} 1/4 \\ -1/4 \\ 1/4 \\ -1/4 \end{pmatrix} = \begin{pmatrix} 1/100 \\ 7/100 \\ 7/100 \\ 1/100 \end{pmatrix}$$

$$\vec{u}_4 = \begin{pmatrix} 49/100 \\ -7/100 \\ -7/100 \\ 49/100 \end{pmatrix}$$

$$|\vec{u}_4| = \sqrt{\frac{49^2 + 49 + 49 + 49^2}{100^2}} = 7/10$$

$$\vec{e}_4 = \frac{\vec{u}_4}{|\vec{u}_4|} = \begin{pmatrix} 7/10 \\ -1/10 \\ -1/10 \\ 7/10 \end{pmatrix}$$
