

# 1 Tensors

Recall that 2D vectors (with components  $A_i$ ) and 2D tensors of rank 2 (with components  $T_{ij}$ ) transform under a change of coordinate system as

$$A'_i = \sum_{k=1}^2 R_{ik} A_k, \quad T'_{ij} = \sum_{k=1}^2 \sum_{l=1}^2 R_{ik} R_{jl} T_{kl}.$$

Here  $A'_i$  and  $T'_{ij}$  are the components in the “new” coordinate system which is rotated by an angle  $\theta$  to the original one.  $R_{ij}$  are the elements of the rotation matrix given by

$$R = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

or, in other words,

$$R_{11} = R_{22} = \cos \theta, \quad R_{12} = \sin \theta, \quad R_{21} = -\sin \theta.$$

- Write out explicitly the expressions for  $T'_{11}$ ,  $T'_{12}$ ,  $T'_{21}$ , and  $T'_{22}$  in terms of  $T_{11}$ ,  $T_{12}$ ,  $T_{21}$ ,  $T_{22}$ .
- A tensor is called **symmetric** if  $T_{ij} = T_{ji}$  for every  $i, j$ . In our 2D case there is only one requirement, which is  $T_{12} = T_{21}$ . Check that this implies  $T'_{12} = T'_{21}$ .
- Suppose that  $T_{12} = T_{21} = 0$ . Express  $T'_{12}$  in the form  $\alpha(T_{11} - T_{22})$  and find the factor  $\alpha$ . This shows that a diagonal tensor (i.e., one with  $T_{ij} = 0$  whenever  $i \neq j$ ) doesn't remain in diagonal in other coordinate systems.
- Check that if  $T_{ij} = \delta_{ij}$  (i.e.,  $T_{11} = T_{22} = 1$  and  $T_{12} = T_{21} = 0$ ) then  $T'_{ij} = \delta_{ij}$  as well.

# 2 Bases of vector spaces

Expand the vector

$$\vec{V} = a\hat{x} + b\hat{y} + c\hat{z}$$

in the basis

$$\vec{A} = \hat{x} + \hat{y}, \quad \vec{B} = \hat{x} + \hat{z}, \quad \vec{C} = \hat{y} + \hat{z}.$$

That is, find  $\alpha, \beta, \gamma$  such that  $\vec{V} = \alpha\vec{A} + \beta\vec{B} + \gamma\vec{C}$ .

# 3 Vector spaces of functions

- Expand the functions  $e^x$  and  $e^{-x}$  in the basis  $\sinh x$ ,  $\cosh x$ .
- Expand the function  $e^x$  in the basis  $\sinh x$ ,  $\sinh(x + a)$ , for a given number  $a \neq 0$ .

## 4 Orthogonal vectors

The three vectors

$$v_1 = \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix}, \quad v_3 = \begin{pmatrix} 1 \\ 7 \\ 7 \\ 1 \end{pmatrix},$$

are orthogonal to each other.

- (a) Calculate the orthonormal vectors  $e_1 = v_1/\|v_1\|$ ,  $e_2 = v_2/\|v_2\|$ , and  $e_3 = v_3/\|v_3\|$ .
- (b) Find a fourth vector  $e_4$  that is orthogonal to  $e_1$ ,  $e_2$  and  $e_3$  by applying the Gram-Schmidt process to

$$f = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

- (c) Normalize the vector  $e_4$ .

## References

- [1] Mary L. Boas, “Mathematical Methods in the Physical Sciences,” 3<sup>rd</sup> Edition, John Wiley & Sons, 2006.