

8. a). and
and
la
jr
nop

a0, a0, 0
a1, a1, 0
t0, - main - entry

• end startup

b). SFRs with the highest address (ascending),

| | | |
|--------------|----|----------|
| C2FIFOI31INV | at | BF88CB4C |
| DEVCFG3 | at | BFC02FF0 |
| DEVCFG2 | at | BFC02FF4 |
| DEVCFG1 | at | BFC02FF8 |
| DEVCFG0 | at | BFC02FFC |

c). For the data type — SPI2STATbits_t ,
11 bit fields are defined namely,

| | |
|----------|-------------|
| SPIRBF | { 1 bit } |
| SPITBF | { 1 bit } |
| SPITBE | { 1 bit } |
| SPIRBE | { 1 bit } |
| SPIROV | { 1 bit } |
| SRMT | { 1 bit } |
| SPITUR | { 1 bit } |
| SPIBUSY | { 1 bit } |
| TXBUFELM | { 5 bits } |
| RXBUFELM | { 5 bits } |
| and, w | { 32 bits } |

From the Data sheet (SPI2 Register Map)
we see that the bit fields in p32mx795f512h.h
file are in accordance -

9. 1). TRISDSET = 0xB ; // TRISDSET = 0b1100
 - 2). TRISDCLR = 0b100010 ;
 - 3). TRISDINV = 0b10001 ;
7. The processor.o file contains the addresses of all the SFRs that the PIC32 can possibly use. This is why the file size is big. After linking with other object codes to produce the elf file, the hex file is finally produced which is usually less than 10 KB.

Chapter 4 :-

1. The following are meant to be used in other c files,

NU32_Startup(),
NU32_ReadUART3 and NU32_WriteUART3

NU32_DESIRED_BAUD is private to NU32.c

2. a). investPIC.c attached

b). The main.c consists of the main function which calls the functions to be used.

The function definitions are given in helper.h along with other constants used. The descriptions of these functions are given in helper.c which also include helper.h.

c). The io.h file contains function definitions of getuserInput and sendOutput, which is described in io.c. io.h also contains the structure Investment and MAX_YEARS

The calculate.h file contains only the function definition of calculateGrowth, described in calculate.c.

Note :- calculate.c will have an #include "io.h" because calculateGrowth uses Investment which is defined in io.h.

```
4. void LCD_ClearLine (int ln)
{
    char str[16] = "          " // 16 space characters
    if (ln == 0)
    {
        LCD_Move(0, 0); // moves cursor to line 0
        LCD_WriteString(str); // clears line 0
    }
    else if (ln == 1)
    {
        LCD_Move(1, 0); // moves cursor to line 1
        LCD_WriteString(str); // clears line 1
    }
    else
    {
        printf("Invalid Input value ln");
    }
}
```

Chapter 5 :-

3. a). The following commands has the jump 'jal'

$$\begin{aligned} j_3 &= j_1/j_2 ; \\ f_3 &= f_1 + f_2 ; \\ f_3 &= f_1 - f_2 ; \\ f_3 &= f_1 * f_2 ; \\ f_3 &= f_1/f_2 ; \end{aligned}$$

→ assembly code for this line is,

| | | |
|---------------------|-----|-------------------|
| 9d003134 : 8fc40930 | lw | a0,48(\$8) |
| 9d003138 : 8fc50034 | lw | a1,52(\$8) |
| 9d00313c : 0f400dc4 | jal | 9d003710 <divsf3> |
| 9d003140 : 00999999 | nop | |
| 9d003144 : afc20058 | sw | v0,88(\$8) |

$$\begin{aligned} d_3 &= d_1 + d_2 ; \\ d_3 &= d_1 - d_2 ; \\ d_3 &= d_1 * d_2 ; \\ d_3 &= d_1/d_2 ; \end{aligned}$$

b). The following commands have the least assembly code (4 lines) (without a jump)

$$i_3 = i_1 + i_2 ;$$

| | | |
|------------------|---------------------|---------------|
| i3 = i1 - i2 ; → | 9d002fe4 : 8fc30014 | lw v1,20(\$8) |
| | 9d002fe8 : 8fc20018 | lw v0,24(\$8) |
| | 9d002fec : 00621023 | subu v0,v1,v0 |
| | 9d002ff0 : afc2004c | sw v0,76(\$8) |

With some character arithmetic, the assembly code has an extra andi line which turns all the bits in V0 into 1.

c).

| | char | int | long long | float | long double |
|---|---------|---------|-----------|-----------|-------------|
| + | 1.25(5) | 1.0(4) | 2.75(11) | 1.25(5) J | 2.0(8) J |
| - | 1.25(5) | 1.0(4) | 2.75(11) | 1.25(5) J | 2.0(8) J |
| * | 1.5(6) | 1.25(5) | 4.75(19) | 1.25(5) J | 2.0(8) J |
| / | 1.75(7) | 1.75(7) | 3.0(12) J | 1.25(5) J | 2.0(8) J |

d). Math subroutines :-

| Subroutines | VA | memory (bytes) |
|------------------|------------|----------------|
| .text.dp32mul | 0x9d001e00 | 1208 |
| .text.dp32subadd | 0x9d002268 | 1072 |
| .text.dp32mul | 0x9d00269c | 812 |
| .text.fpsubadd | 0x9d003498 | 632 |
| .text.fp32div | 0x9d003710 | 560 |
| .text.fp32mul | 0x9d003940 | 444 |

4. & and | operators expands to 4 assembly lines while << and >> operator commands expand to 3 assembly lines.

<< and >> are a faster option than multiplying or dividing a 2^n number.

6. a). Using the core timer, elapsedticks = _CPO_GET_COUNT
elapsedns = elapsedticks * 25;
we can get the time for the program to compile in nanoseconds.

Divide this value by 12.5 ns gives SYSCLK cycles for each of the commands.

b). $f_2 = \cos f(f_1);$

9d00278c : 8fc40010 lw a0,16(\$8)

9d002790 : 0f400898 jal 9d002260 <cosf>

9d002794 : 00990909 nop

9d002798 : afc20020 sw v0,32(\$8)

$d_2 = \cos(d_1);$

9d0027ac : 8fc40018 lw a0,24(\$8)

9d0027b0 : 8fc5001c lw a1,28(\$8)

9d0027b4 : 0f400921 jal 9d002484 <_truncf> 23

9d0027b8 : 00090909 nop

9d0027bc : 00402021 move a0,v0

| | | |
|----------|------------|----------------------|
| 9d0027c0 | : 0f400898 | jal 9d002260 < cosf> |
| 9d0027c4 | : 00990940 | nop |
| 9d0027c8 | : 00402021 | meve a0, v0 |
| 9d0027cc | : 0f400a0a | jal 9d002828 <.LFE0> |
| 9d0027d0 | : 09000090 | nop |
| 9d0027d4 | : afc20028 | sw v0, 40(\$8) |
| 9d0027d8 | : afc3002c | sw v1, 44(\$8) |

Advantages :- long double calculates the value at a higher precision

Disadvantages :- using long double for cosine calculations are 3 times slower than using float.

It also contains 3 jumps within the assembly code.

c). Directory of libm.a :- (Full Path)

C:/program files(x86)/microchip/xc32/v2.15
/pic32mc/lib/libm.a

10. Total memory reserved for stack is 131032 bytes.

$$\therefore 131032 - 5000 \times 4 = 111032 \text{ bytes}$$

This is how much memory is available for the int array.

\therefore Max integer array :- int a[27758]