

ME 333

02/19/19

Homework 11

Chapter 7:

1. False. The input pin can also read 'high' when disconnected if the pin is configured with an internal pull-up resistor.

2. b). $AD1PCFG = 0x0000001E;$
 $TRISB = 0x0000FFFF;$
 $ODCB = 0x00000004;$
 $CNPUE = 0x00000010;$
 $CNCON = 0x00008000;$
 $CNEN = 0x00000001;$

a). Here pin 2 can have an external pull-up resistor.
 We should not try to source or sink more than 10 mA.

$$\therefore \text{minimum resistance} = \frac{5V}{0.01A} = 500\Omega$$

The voltage across this resistance should not be more than 9V otherwise, this may damage the PIC32,

$$\therefore \text{maximum resistance} = \frac{9V}{0.01A} = 900\Omega$$

Chapter 8:

1. No. of ticks = $(PR+1) \times 64$

$$\Rightarrow (PR+1) \times 64 = \frac{16 \times 10^6 \text{ ns}}{12.5 \text{ ns}}$$

$$\Rightarrow PR = 19999$$

$$T3CON = 0 \times 8060;$$

$$PR3 = 0 \times 4E1F;$$

Chapter 9:

1. $f_{\text{PWM}} \geq 100 f_c \Rightarrow f_c \leq \frac{f_{\text{PWM}}}{100}$, $f_c \geq 10 f_a \Rightarrow f_a \leq \frac{f_c}{10}$

$$\Rightarrow f_a \leq \frac{f_{\text{PWM}}}{1000}$$

$$\text{Maximum value of } f_{\text{PWM}} = \frac{80 \text{ MHz}}{2^n}$$

$$\therefore \text{maximum } f_a = \frac{80}{1000 \times 2^n} \text{ MHz}$$
$$= 2^{3-n} \times 10 \text{ KHz}$$

$$\text{Also, } f_c = \frac{1}{2\pi RC}$$

$$\Rightarrow \text{minimum } RC = \frac{1}{2\pi \times 10^4} = \frac{2^{n-3}}{200\pi}$$

Chapter 10 :-

1. The least possible value of TAD is 75 ns

∴ we don't need to configure the ADC to sample automatically, we can choose the sampling time = 132 ns.

∴ minimum read time = $132 \text{ ns} + 12 \times 75 \text{ ns} = 1032 \text{ ns}$

```
AD1CON1bits.ON = 1;  
AD1CON1bits.SSRC = 0b111;  
AD1CON1bits.ASAM = 0;  
AD1CON3bits.ADCS = 2;
```

```
2. unsigned int adc_sample_convert(int pin) {  
    unsigned int elapsed = 0, finish_time = 0;  
    AD1CHbits.CH0SA = pin;  
    AD1CON1bits.SAMP = 1;  
    elapsed = CPO_GET_COUNT();  
    finish_time = elapsed + 10; // 10 core ticks = 250 ns  
    while (CPO_GET_COUNT() < finish_time) {  
    }  
    AD1CON1bits.SAMP = 0;  
    AD1CON1bits.SSRC = 0b111; // Auto conversion  
    while (!AD1CON1bits.DONE) {  
    }  
    return ADC1BUF0;  
}
```