SPI_Slave XulA2-LX9 + StickIt!-MB with Raspberry Pi 2B (RPi2B) Master four wire MOSI, MISO, SCLK, and SS 04/18/16

Raspberry Pi 2B RPi2B provides connections to the StickIt!-MB which provides the signals needed to communicate with the XulA2-LX9 or XulA2-LX25.

An external led is connected to T4 PM2 Xula2 CH 15 led<0>. Following the loading of the FPGA the external led will blink at 1 per sec. This is currently functioning correctly.

Four signals provide the SPI interface between the RPi2B and XulA2.

```
Xula2 CH 25 pin 19 GPIO10(SPI_MOSI)
Xula2 CH 24 pin 21 GPIO09 (SPI_MISO)
Xula2 CH 24 pin 23 GPIO11 (SPI_CLK)
Xula2 CH 08 pin 24 GPIO08_CE0
```

In the build module of the xula2_blinky_spi_slave is where the pins are mapped to RPi2B connector P1.

```
brd.add_port_name('led', 'pm2', slice(0, 8))

#xula2 chan25 BCM10_MOSI ----> RPI_GPIO_P1_19 /* MOSI */
brd.add_port('mosi', 'F2')

#xula2 chan24 BCM09_MISO ----> RPI_GPIO_P1_21 /* MISO */
brd.add_port('miso', 'F1')

#xula2 chan23 BCM11_SCLK ----> RPI_ GPIO_P1_23 /* CLK */
brd.add_port('sck', 'H2')

#xula2 chan08 BCM08_CE0 ----> RPI_GPIO_P1_24 /* CE0 */
brd.add_port('ss', 'J14')
```

The above information is what rhea uses to create the xula2.ucf

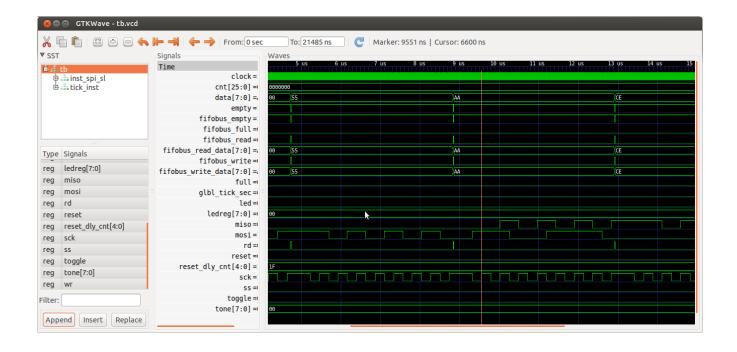
The rhea package creates several files xula2.v xula2.ucf below.

```
#
NET "miso" LOC = "F1";
NET "led<0>" LOC = "T4";
NET "led<1>" LOC = "R1";
NET "led<2>" LOC = "M1";
NET "led<3>" LOC = "J4";
NET "led<4>" LOC = "R2";
NET "led<5>" LOC = "M2";
NET "led<6>" LOC = "K3";
NET "led<7>" LOC = "H1";
```

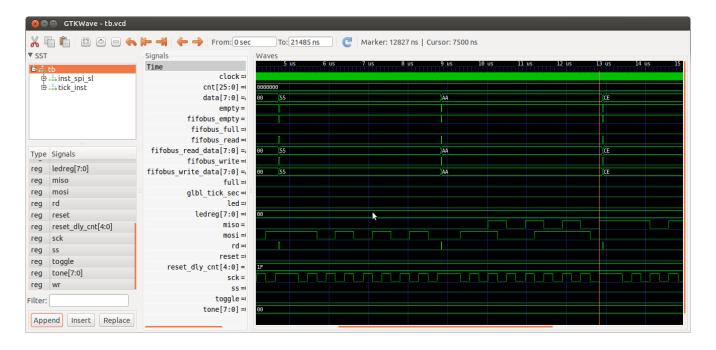
```
NET "ss" LOC = "J14";
NET "clock" LOC = "A9";
NET "mosi" LOC = "F2";
NET "sck" LOC = "H2";
NET "clock" TNM_NET = "clock";
TIMESPEC "TS clock" = PERIOD "clock" 83.3333333 ns HIGH 50%;
In RPi2B bcm2835 library. This is where the pins for the spi are assigned
void bcm2835_spi_begin(void)
  volatile uint32_t* paddr;
  /* Set the SPI0 pins to the Alt 0 function to enable SPI0 access on them */
  bcm2835_gpio_fsel(RPI_GPIO_P1_26, BCM2835_GPIO_FSEL_ALT0); /* CE1 */
  bcm2835_gpio_fsel(RPI_GPIO_P1_24, BCM2835_GPIO_FSEL_ALT0); /* CE0 */
  bcm2835_gpio_fsel(RPI_GPIO_P1_21, BCM2835_GPIO_FSEL_ALT0); /* MISO */
  bcm2835_gpio_fsel(RPI_GPIO_P1_19, BCM2835_GPIO_FSEL_ALT0); /* MOSI */
  bcm2835 gpio fsel(RPI GPIO P1 23, BCM2835 GPIO FSEL ALTO); /* CLK */
  /* Set the SPI CS register to the some sensible defaults */
  paddr = bcm2835_spi0 + BCM2835_SPI0_CS/4;
  bcm2835_peri_write(paddr, 0); /* All 0s */
  /* Clear TX and RX fifos */
  bcm2835_peri_write_nb(paddr, BCM2835_SPI0_CS_CLEAR);
}
In file spi.c after calling the bcm2835_spi_begin(); above the bit order is set to MSBFIRST
  bcm2835_spi_setBitOrder(BCM2835_SPI_BIT_ORDER_MSBFIRST);
                                                                    // The default
  bcm2835 spi setDataMode(BCM2835 SPI MODE0);
                                                             // The default
  bcm2835_spi_setClockDivider(BCM2835_SPI_CLOCK_DIVIDER_65536); // The default
  bcm2835 spi chipSelect(BCM2835 SPI CS0);
                                                        // The default
  bcm2835_spi_setChipSelectPolarity(BCM2835_SPI_CS0, LOW);
                                                               // the default
```

To run the simulation "python xula2_blinky_spi_slave.py -trace" which traces the signals of def tb(led, clock, mosi, miso, sck, ss, reset=None): and creates the "tb.vcd" file that can be viewed with "gtkwave tb.vcd"

The RPi2B is set to send MSBFIRST. In the simulation below the signal mosi MSB of the value 0xCE 11001110 is at 9551 ns on the raising edge of the signal sck.



In the simulation below the signal mosi LSB of 0xCE 11001110 is at 12827 ns the raising edge of the signal sck.



This appears to match the RPi2B sending MSBFIRST.

In addition rhea creates the xula2.tcl file.

```
#
# ISE implementation script
# create: Sun, 10 Apr 2016 12:13:22 +0000
# by: xula2_blinky_spi_slave.py
#
# set compile directory:
set compile_directory.
set top_name xula2
set top xula2
# set Project:
set proj xula2
# change to the directory:
cd xilinx/
# set ucf file:
set constraints file xula2.ucf
# set variables:
project new xula2.xise
project set family spartan6
project set device XC6SLX9
project set package FTG256
project set speed -2
# add hdl files:
xfile add xula2.ucf
xfile add xula2.v
# test if set_source_directory is set:
if { ! [catch {set source_directory $source_directory}]} {
 project set "Macro Search Path"
$source_directory -process Translate
project set "Create Binary Configuration File" "true" -process "Generate Programming File"
project set "FPGA Start-Up Clock" "JTAG Clock" -process "Generate Programming File"
# run the implementation:
process run "Synthesize"
```

process run "Translate"
process run "Map"
process run "Place & Route"
process run "Generate Programming File"
close the project:
project close

	STICKIT-MB RPI2B						
XuLA2	CHAN	Rpi I/O	Rpi I/O Rpi I/O				XuLA2
		+3.3V	1	2	+5V		
A2	CH31	BCM2_SDA	3	4	+5V		
B2	CH30	BCM2_SCL	5	6	GND		
B1	CH29	BCM4_GPCLK0	7	8	BCM14_TXD	CH14	B15
GND		GND	9	10	BCM15_RXD	CH13	B16
C1	CH28	BCM17	11	12	BCM18_PCM_C	CH12	C15
E2	CH27	BCM27_PCM_D	13	14	GND		GND
E1	CH26	BCM22	15	16	RCM23	CH11	C16
		+3.3V	17	18	6℃ M24	CH10	F16
F2	CH25	BCM10_MOSI	19	20	GND		
F1	CH24	BCM9_MISO	21	22	BCM25	CH9	F15
H2	CH23	BCM11_SCLK	23	24	BCM8_CE0	CH8	J14
GND		GND	25	26	BCM7_CE1	CH7	J16
		BCM0_ID_SD	27	28	BCM1_ID_SC		
H1	CH22	BCM5	29	30	GND		GND
K15	CH5	BCM6	31	32	BCM12	CH6	K16
M16	CH4	BCM13	33	34	GND		GND
R16	CH2	BCM19_MISO	35	36	BCM16	CH3	M15
R7	CH0	BCM26	37	38	BCM20_MOSI	CH1	R15
GND		GND	39	40	BCM21 SCLK	CHANCLK	T7

Here are the FPGA pins connected to each channel for both the XuLA and XuLA2 Boards:

XuLA	XuLA2	J1	Pi	n#	J1	XuLA2	XuLA
AN1	AN1		1	21	RESET	RESET	RESET
AN0	AN0		2	22		+1.2V	+1.2V
+5V	+5V	+5V	3	23	GND	GND	GND
P88	A2	CH31	4	24		+3.3V	+3.3V
P89	B2	CH30	5	25	CH14	B15	P84
P93	B1	CH29	6	26	CH13	B16	P83
P94	C1	CH28	7	27	CH12	C15	P82
P97	E2	CH27	8	28	CH11	C16	P73
P3	E1	CH26	9	29	CH10	F16	P72
P4	F2	CH25	10	30	CH9	F15	P68
P7	F1	CH24	11	31	CH8	J14	P62
P12	H2	CH23	12	32	CH7	J16	P61
P13	H1	CH22	13	33	CH6	K16	P57
P19	J4	CH21	14	34	CH5	K15	P56
P20	K3	CH20	15	35	CH4	M16	P52
P21	M1	CH19	16	36	CH3	M15	P50
P32	M2	CH18	1743	37	CH2	R16	P39
P33	R1	CH17	18	38	CH1	R15	P37
P34	R2	CH16	19	39	CH0	R7	P36
P35	T4	CH15	20	40	CHCLK	T7	P44

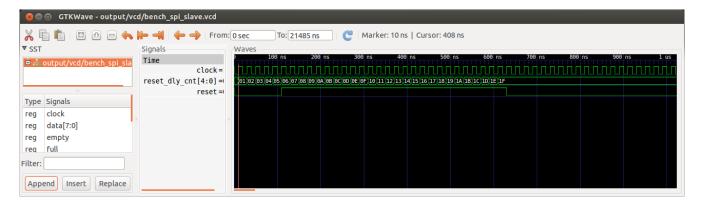
GPIO

GPI01 RPi_GPI0

	131	_0110	
.3V-RPi 1 0 3 0 CHAN31 5 0 CHAN29 7 0 CHAN29 13 0 CHAN26 15 0 CHAN25 15 0 CHAN25 15 0 CHAN25 23 0 CHAN22 23 0 CHAN22 29 0 CHAN22 25 0 CHAN22 29 0 CHAN22 25 0 CHAN2 35 0 CHAN2	3.3V BCM2_SDA BCM3_SCL BCM4_GPCLK0 GND BCM17 BCM27_PCM_D BCM22 3.3V BCM10_MOSI BCM9_MISO BCM11_SCLK GND BCM0_ID_SD BCM5 BCM6 BCM13	5V 5V GND BCM14_TXD BCM15_RXD BCM18_PCM_C GND BCM23 BCM24 GND BCM25 BCM8_CE0 BCM7_CE1 BCM1_ID_SC GND BCM12 GND BCM12 GND BCM12 GND BCM12	02 +5V-RI 06 GND 08 CHAN14 010 CHAN13 012 CHAN12 014 GND 016 CHAN11 018 CHAN11 020 GND 024 CHAN8 026 CHAN8 026 CHAN8 026 CHAN7 031 GND 032 CHAN6 032 CHAN6 034 GND
CHANA 33	BCM13		O34 GND

Pin#	NAME		NAME	Pin#
01	3.3v DC Power	00	DC Power 5v	02
03	GPIO02 (SDA1, I2C)	00	DC Power 5v	04
05	GPIO03 (SCL1, I2C)	00	Ground	06
07	GPIO04 (GPIO_GCLK)	00	(TXD0) GPIO14	08
09	Ground	00	(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)	00	(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)	00	Ground	14
15	GPIO22 (GPIO_GEN3)	00	(GPIO_GEN4) GPIO23	16
17	3.3v DC Power	00	(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)	00	Ground	20
21	GPIO09 (SPI_MISO)	00	(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)	00	(SPI_CE0_N) GPIO08	24
25	Ground	00	(SPI_CE1_N) GPIO07	26
27	ID_SD (I2C ID EEPROM)	00	(I2C ID EEPROM) ID_SC	28
29	GPIO05	00	Ground	30
31	GPIO06	00	GPIO12	32
33	GPIO13	00	Ground	34
35	GPIO19	00	GPIO16	36
37	GPIO26	00	GPIO20	38
39	Ground	00	GPIO21	40

Creating a software reset for the XulA2-LX with StickIt!-MB.

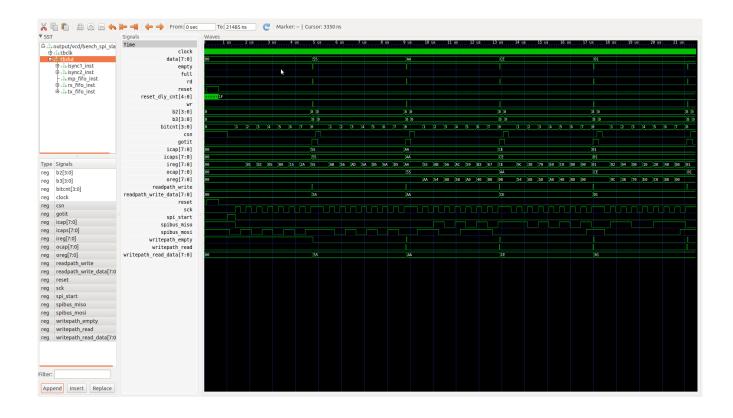


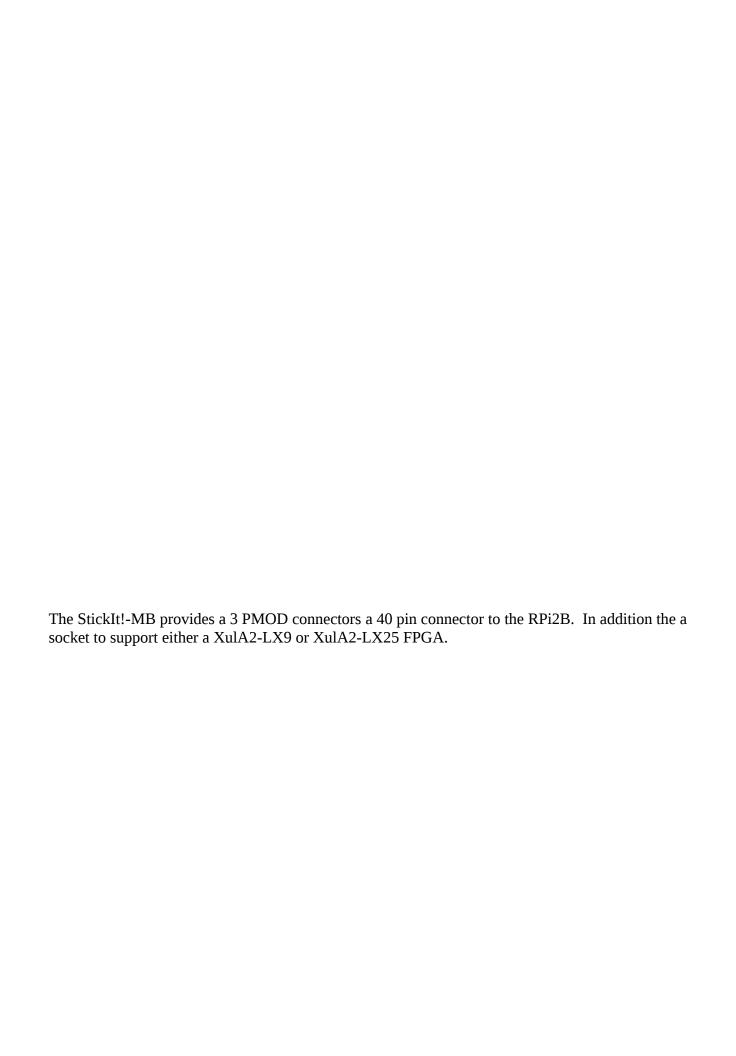
SPI_Slave software is provided with rhea package.

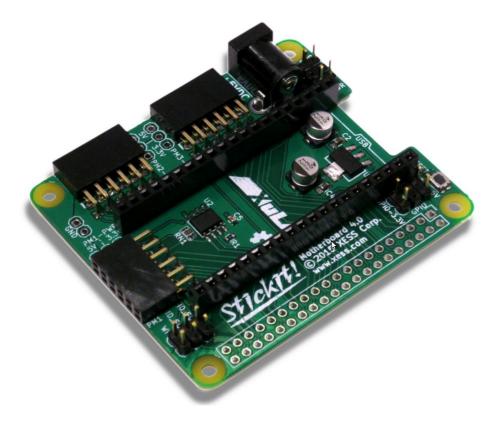
from rhea.system import Global, Clock, Reset, FIFOBus, Signals
/home/vidal/wkg/rhea/rhea/system/glbl.py
Global
/home/vidal/wkg/rhea/rhea/system/clock.py
Clock
/home/vidal/wkg/rhea/rhea/system/reset.py
Reset
/home/vidal/wkg/rhea/rhea/system/stream/fifobus.py
FIFOBus
/home/vidal/wkg/rhea/rhea/system/hwtypes.py
Signals
from rhea.cores.spi import SPIBus, spi_slave_fifo
/home/vidal/wkg/rhea/rhea/cores/spi/spi.py
SPIBus
/home/vidal/wkg/rhea/rhea/cores/spi/spi_fifo_slave.py

spi_slave_fifo

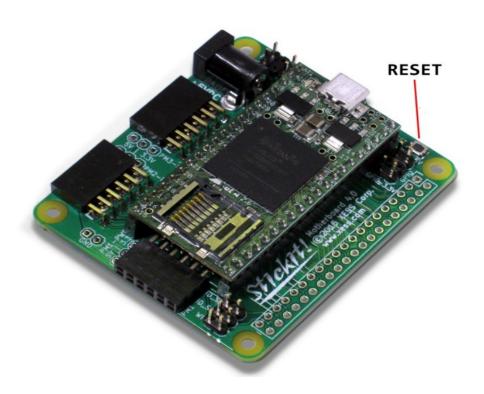
from rhea.cores.misc import glbl_timer_ticks /home/vidal/wkg/rhea/rhea/cores/misc/glbl_timer_ticks.py glbl_timer_ticks







XulA2 mounted on StickIt!-MB.



Create a bit file to make the xula2 FPGA provide a jumper on

pins 19 GPIO10(SPI_MOSI) & pin 21 GPIO09 (SPI_MISO).

Set the PATH to ISE WEB PACK

./opt/Xilinx/14.6/ISE_DS/settings64.sh

vidal@ws009:~/wkg/jpeg-2000-test/xula2_fpga/jumper_tests/spi\$ python jumper_xula2_spi.py -build

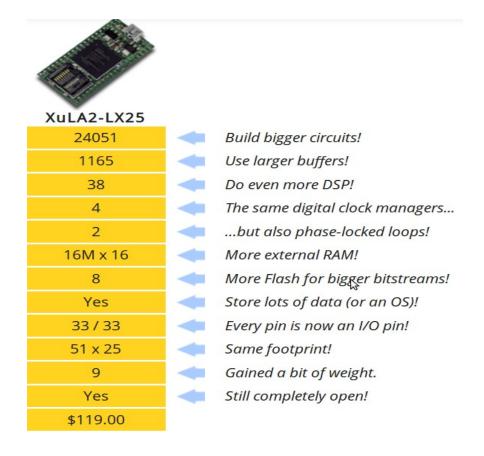
vidal@ws009:~/wkg/jpeg-2000-test/xula2_fpga/jumper_tests/spi\$ cp xilinx/xula2.bit xilinx/jumper_spi.bit

vidal@ws009:~/wkg/jpeg-2000-test/xula2_fpga/jumper_tests/spi\$ python jumper_xula2_spi.py -build

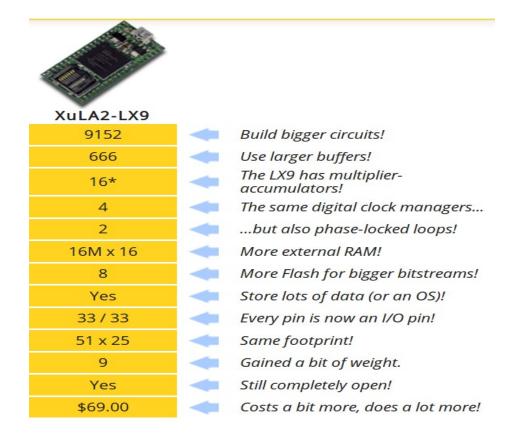
pi@raspberrypi2-146 ~/bcm2835-1.45/examples/spi \$ xsload --usb 0 --fpga ~/jpeg-2000/xula2_fpga/jumper_tests/spi/xilinx/jumper_spi.bit

pi@raspberrypi2-146 ~/bcm2835-1.45/examples/spi \$ gcc -o spi spi.c -l bcm2835

pi@raspberrypi2-146 ~/bcm2835-1.45/examples/spi \$ sudo ./spi Sent to SPI: 0x23. Read back from SPI: 0x23. pi@raspberrypi2-146 ~/bcm2835-1.45/examples/spi



LX9



LX25

- Open-source design
- XC6SLX25 FPGA
- 32 MByte SDRAM
- 8 Mbit Flash
- microSD card socket
- 3.3 & 1.2V regulators
- 40-pin interface
- 12 MHz oscillator
- PIC 18F14K50 micro
- USB 2.0 port
- Auxiliary JTAG port
- Works with the XSTOOLs software
- · Works with XILINX ISE and WebPACK
- Works with XILINX iMPACT and ChipScope (requires Xilinx JTAG cable)

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