

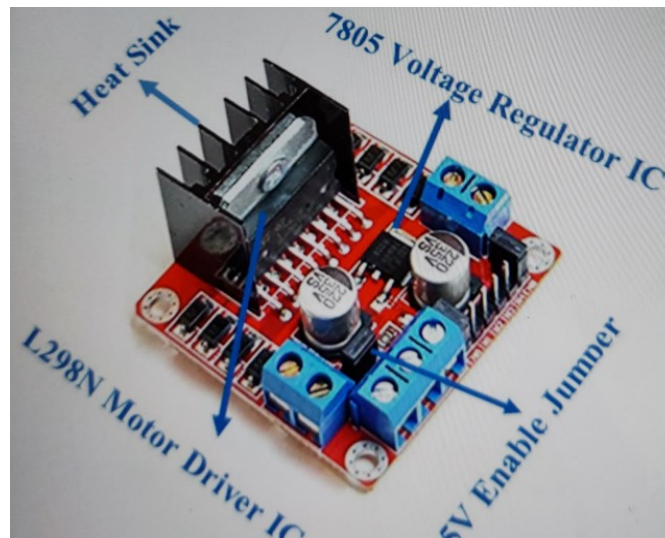
\*\*\*\*\*Draft Valve Control\*\*\*\*\*

Initial work by Joe Small  
using a pico\_w programmed with Arduino IDE  
L288 Motor Control

08/02/23

\*\*\*\*\*Draft Valve Control\*\*\*\*\*

## L288 Components

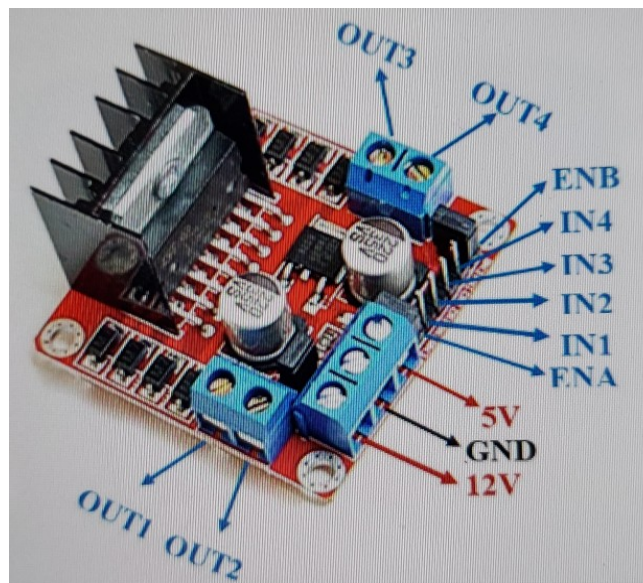


## L288 pins description

This L298N Motor Driver Module consists of an L298 motor driver IC and a 78M05 5V regulator. Motors. This module consists of an L298 motor driver IC and a 78M05 5V regulator. can control up to 4 DC motors, or 2 DC motors with directional and speed control.

L298N Module Pinout Configuration	
Pin Name	Description
IN1 & IN2	Motor A input pins. Used to control the spinning direction of Motor A
IN3 & IN4	Motor B input pins. Used to control the spinning direction of Motor B
ENA	Enables PWM signal for Motor A
ENB	Enables PWM signal for Motor B
OUT1 & OUT2	Output pins of Motor A
OUT3 & OUT4	Output pins of Motor B
12V	12V input from DC power Source
5V	Supplies power for the switching logic circuitry inside L298N
GND	Ground pin

L288 pins.



pico\_w program provided by Joe Small (setup).

```
void setup() {  
    // put your setup code here,  
    pinMode(in1Pin, OUTPUT);  
    pinMode(in2Pin, OUTPUT);  
    pinMode(in3Pin, OUTPUT);  
    pinMode(LED_BUILTIN, OUTPUT)  
}  
  
void loop() {  
    // put your main code here
```

xxpico\_w program provided by Joe Small (loop).

```
    digitalWrite(in1Pin, LOW);
    digitalWrite(in2Pin, HIGH); //setup to open
    solenoid
    delay(1000);
    // open solenoid
    digitalWrite(in3Pin, HIGH);
    delay(100);    digitalWrite(in3Pin, LOW);
    delay(5000);

    digitalWrite(in1Pin, HIGH);
    digitalWrite(in2Pin, LOW); //setup to close
    solenoid
    delay(1000);

    //close solenoid
    digitalWrite(in3Pin, HIGH);    delay(100);
    digitalWrite(in3Pin, LOW);
    delay(5000);

}
;
```

XX