Initial work by Joe Small using a pico_w programmed with Arduino IDE L288 Motor Control

08/05/23

Remote5 battery level shifter L288

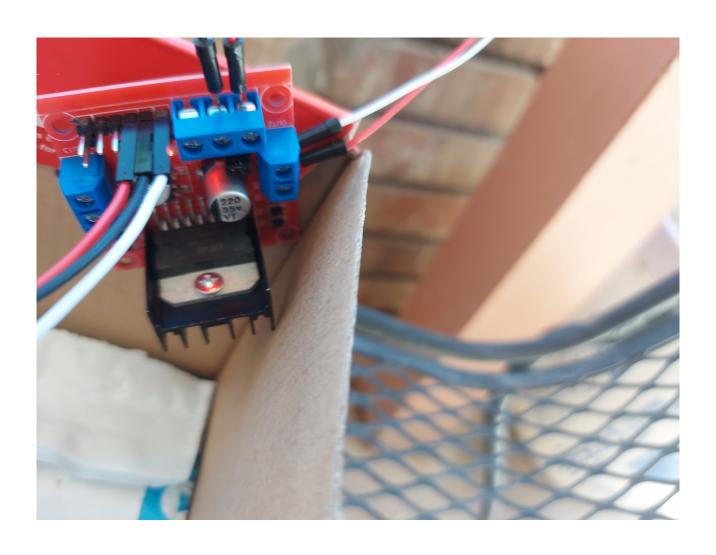


Open water flows



Closed no water flowing



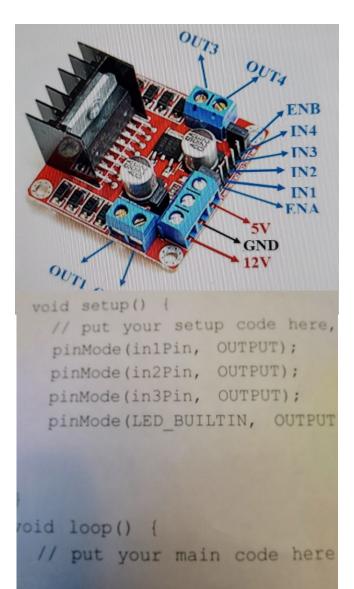


L288 Components

L298N Module Pinout Configuration	
Pin Name	Description
IN1 & IN2	Motor A input pins. Used to control the spinning direction of Mo
IN3 & IN4	Motor B input pins. Used to control the spinning direction of Mo
ENA	Enables PWM signal for Motor A
ENB	Enables PWM signal for Motor B
OUT1 & OUT2	Output pins of Motor A
OUT3 & OUT4	Output pins of Motor B
12V	12V input from DC power Source
5V	Supplies power for the switching logic circuitry inside L298N
GND	Ground pin

L288 pins description

L288 pins.



pico_w program provided by Joe Small (setup).

xxpico_w program provided by Joe Small (loop).

```
digitalWrite(inlPin, LOW);
 digitalWrite(in2Pin, HIGH);//setup to open
 solenoid
 delay(1000);
   // open solenoid
   digitalWrite(in3Pin, HIGH);
  delay(100); digitalWrite(in3Pin, LOW);
  delay(5000);
  digitalWrite(in1Pin, HIGH);
digitalWrite(in2Pin, LOW); //setup to close
solenoid
  delay(1000);
  //close solenod
  digitalWrite(in3Pin, HIGH); delay(100);
digitalWrite(in3Pin, LOW);
  delay(5000);
```