Ultibo virtual MQTT Broker connection with nano-rp2040-connect with a goal to use a pico_w instead 11/27/22

Required: QEMU 6.2.0 compiled from source. qemu-6.2.0-rpios-32bit.img or qemu-6.2.0-rpios-64bit.img. Openocd is also compiled from source installed-openocd050322-610f137.img installed-openocd082722-228ede-64bit.img. Lazarus IDE (Ultibo-Edition) is installed using https://github.com/develone/Tools/blob/master/Installer/Core/Linux/ultiboinstaller.sh
The MQTT will run on a Raspberry Pi OS 32 or 64 bit system.
Arduino IDE was installed on a 32 bit Raspberry Pi OS.

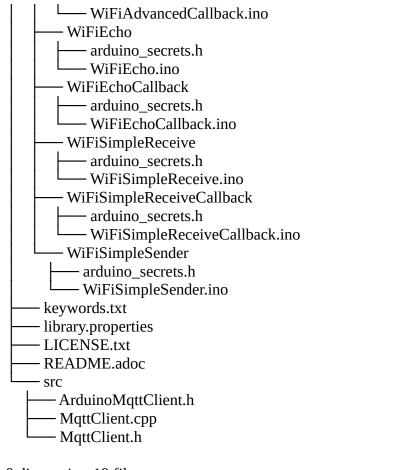
nano-rp2040-connect configuration.

Since the MQTT Broker is running in a virtual system the mqtt-port is 9883 instead of 1883

Goal: To use a pico_w instead of nano-rp2040-connect to connect to MQTT Broker running virtually on Raspberry Pi 4B. The code for mqtt broker was written by Ultibo user https://github.com/pjde/ultibo-mqtt which was added to https://github.com/develone/Ultibo Projects/tree/master/Pauls-ultibo-mqtt

Status: Two files are used on the nano-rp2040-connect arduino_secrets.h & mqtt.ino plus

```
libraries/ArduinoMqttClient/
— examples
— WiFiAdvancedCallback
— arduino_secrets.h
```



8 directories, 19 files

The current pico_w code is found at https://github.com/develone/pico_w-mqtt_example This code compile links and executes but does not connect like nano-rp2040-connect.

```
pico_w configuration.
```

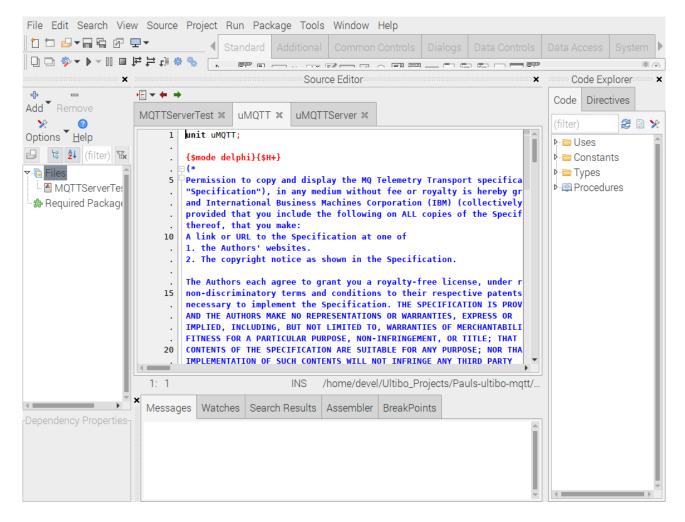
u16_t mqtt_port = 9883;

#define LWIP_MQTT_EXAMPLE_IPADDR_INIT = IPADDR4_INIT(PP_HTONL(0xc0a801e5))

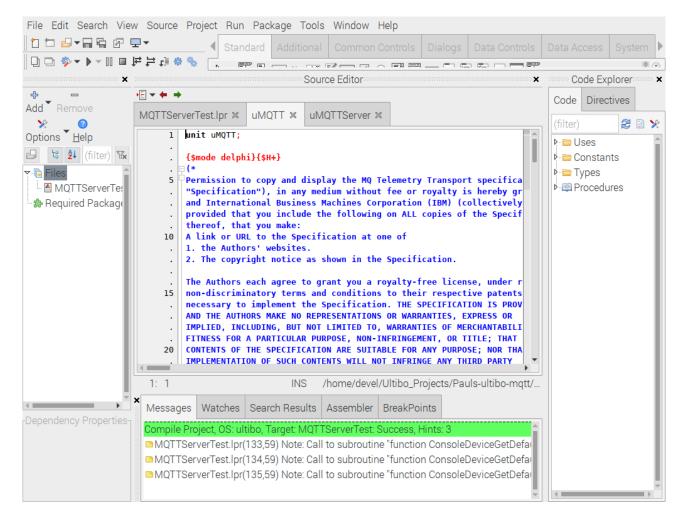
The following command is used to set the path for openocd & qemu.

. Ultibo_Projects/picoultibo.sh

export ULTIBO1=/home/devel/ultibo/core export ULTIBO2=/home/devel/qemu-6.2.0-rpios/bin export PICO=/home/devel/local/openocd/bin export PICOTOOL=/home/devel/picotool/build/ export PATH=\$ULTIBO1:\$ULTIBO2:\$PICO:\$PICOTOOL:\$PATH echo \$PATH



From the main menu Run/Compile will generate a "kernel.bin" when the green bar appears.



The script startqemu.sh will bring up the MQTT broker.

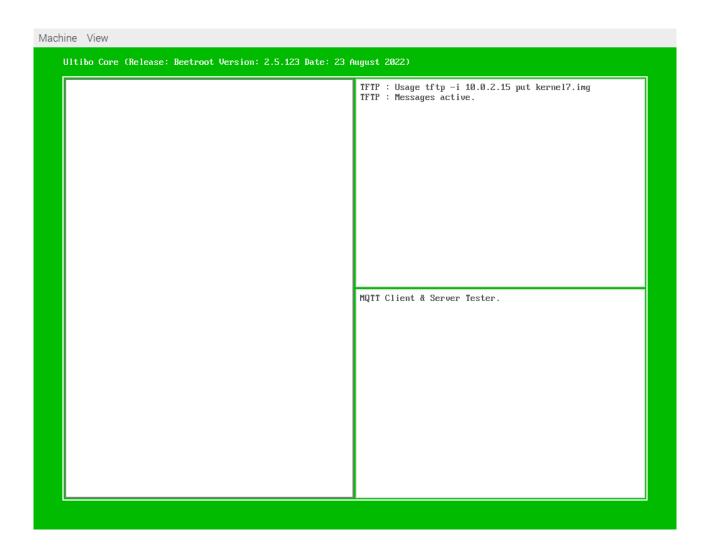
#!/bin/bash

qemu-system-arm -machine versatilepb -cpu cortex-a8 -kernel kernel.bin \

-net

user,hostfwd=tcp::5080-:80,hostfwd=tcp::5023-:23,hostfwd=tcp::9883-:1883,hostfwd=udp::5069-:6

9,hostfwd=tcp::6050-:5050 -net nic \
-drive file=disk.img,if=sd,format=raw



When a 5 is depressed in the left panel currently the nano-rp2040-connect and begin sending messages. The nano-rp2040 will connect to the mqtt broker as client "nano-rp2040-connect" user "testuser" password "password123" and start sending messages on topic "update/memo".

cat /dev/ttyACM0 Sent MQTT message.

Received a message with topic 'update/memo', length 10 bytes:

BUTTON 399

Sent MQTT message.

Received a message with topic 'update/memo', length 10 bytes:

BUTTON 400

Sent MQTT message.

Received a message with topic 'update/memo', length 10 bytes:

BUTTON 401

Sent MQTT message.

Received a message with topic 'update/memo', length 10 bytes:

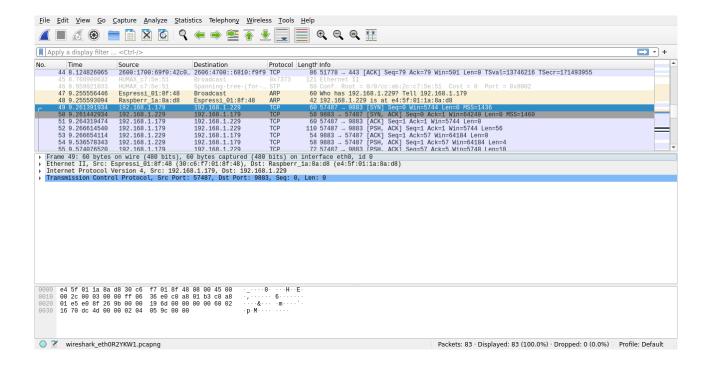
BUTTON 402

Sent MQTT message.

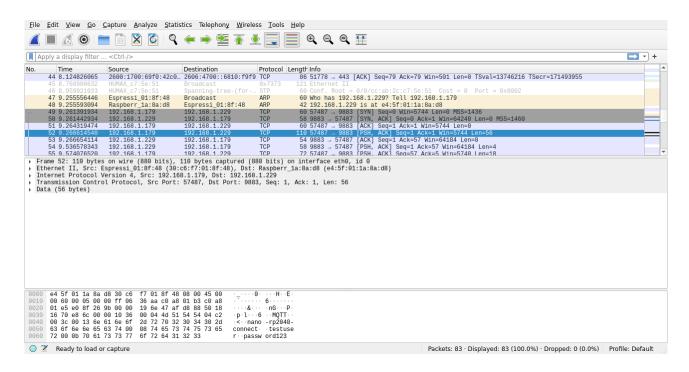
Received a message with topic 'update/memo', length 10 bytes:

BUTTON 403

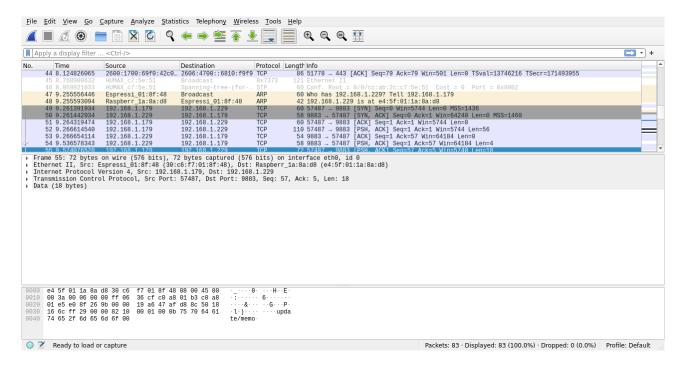
The nano-rp2040-connect



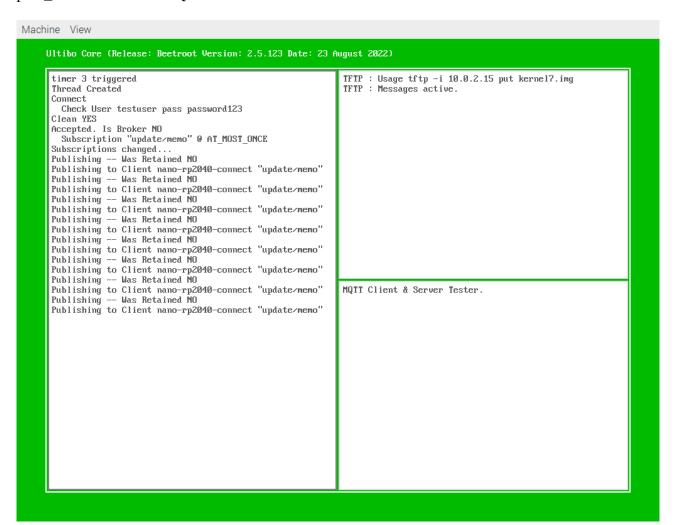
This when the connection information is sent from the nano-rp2040-connect to the mqtt broker.



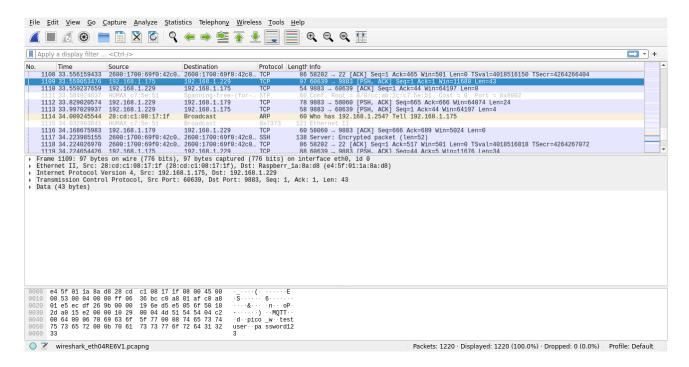
The nano-rp2040-connect begins sending updates to topic "update/memo" to mqtt broker.



pico_w connects with MQTT Broker



This is when the pico_w connects with the mqtt broker.



Starting FreeRTOS on core 0:

Connecting to WiFi...

Connected.

Connecting to WiFi...

Connected.

mqtt_port = 9883 &mqtt_port 0x20000598 mqtt_ip = 0xe501a8c0 &mqtt_ip = 0x20000594 IPADDR_LOOPBACK = 0x7f000001 mqtt_client 0x20001bac &mqtt_client 0x20000f40 mqtt_set_inpub_callback 0x10001249 mqtt_client_connect 0x10001261

Ready, running iperf server at 192.168.1.175 MQTT client "pico_w" connection cb: status 0 MQTT client "pico_w" request cb: err 0 MQTT client "pico_w" request cb: err 0