\*\*\*\*\*\*\*DRAFT\*\*\*\*\*

# Adapting the OLED designed for the ICOBOARD to the CATBOARD 05/29/18

\*\*\*\*\*\*\*\*DRAFT\*\*\*\*\*\*

The youtube video <a href="https://www.youtube.com/watch?v=UMDcnwZA2YE">https://www.youtube.com/watch?v=UMDcnwZA2YE</a> describes the interface between an OLED display and the ICOBOARD.

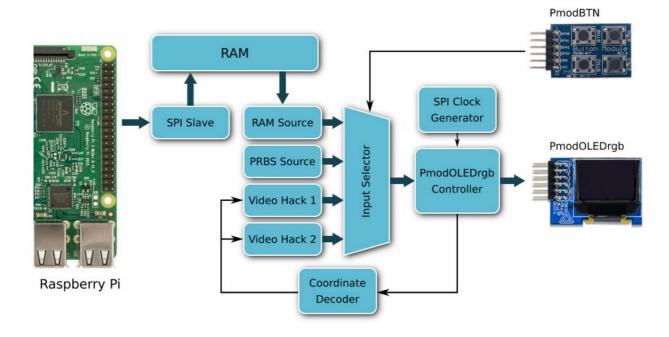
*Goal of this effor:* Is to perform the same functions using the CATBOARD instead of the ICOBOARD.

# otl-icoboard-pmodoldergb-demo



Design Block Diagram

## **Design Structure**



First forked the repository <a href="mailto:ttps://github.hcom/jhol/otl-icoboard-pmodoledrgb-demo">ttps://github.hcom/jhol/otl-icoboard-pmodoledrgb-demo</a>

git clone <a href="https://github.com/develone/otl-icoboard-pmodoledrgb-demo.git">https://github.com/develone/otl-icoboard-pmodoledrgb-demo.git</a>

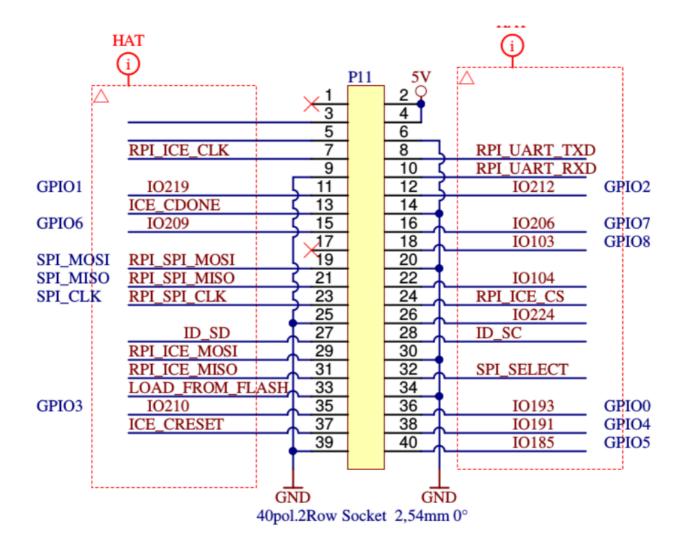
"cd otl-icoboard-pmodoledrgb-demo/"

Need to create a new branch to track the changes required for the CATBOARD. *"git branch catboard"* 

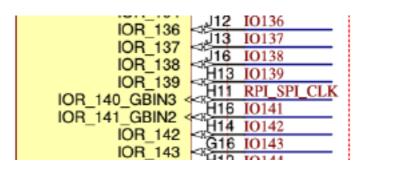
Even though the FPGAs ice40 HX8K are same for the CATBOARD and the ICOBOARD.

1.) The first issue is the interface between the Raspberry Pi and FPGA hat.

ICOBOARD RPi



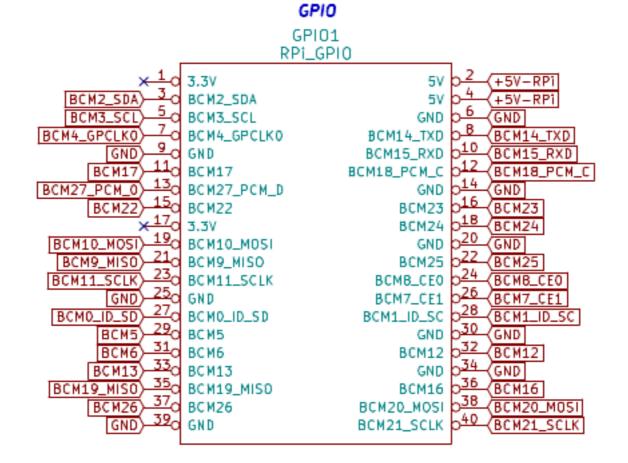
RPI\_SPI\_CLK H11 Pin 23 Pi icoboard



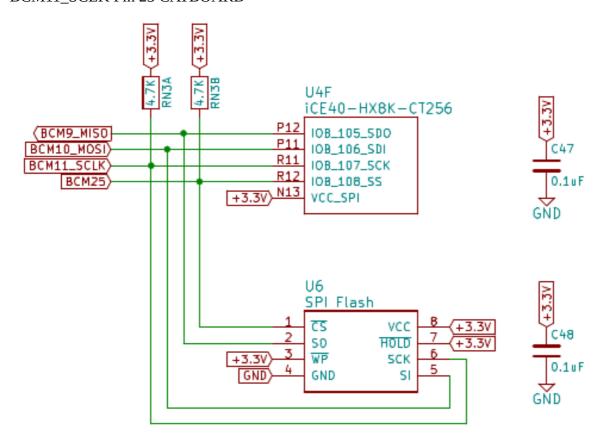
rpi\_cs D4 IOT\_224 Pin 26 Pi icoboard

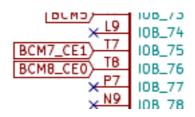
IOT_221	C4	IO222
IOT_222	B3	IO223
IOT_223	D4	IO224
IOT 225	∠E5	IO225

CATBOARD RPi



#### BCM11\_SCLK Pin 23 CATBOARD





- 2.) The 2<sup>nd</sup> issue is the PMOD connections to FPGA are different.
- 3.) Third, I do not have a Diglient PMOD 4 push button switch module.
- 4.) The 4<sup>th</sup> issue is the PHASE LOCK LOOP difference.

Post on #yosys

Pin C8 is my USER\_CLK comes from a 100MHz osc. It is connected to IOT\_197\_GBIN1 on HX8K. When I try using it for as an input to PLL I get the fatal error: bad constraint on `i\_clk': no PLL at pin C8.

Can only certain pins be used as inputs to PLL? daveshah

develonepi3: use the SB\_PLL40\_CORE instead of SB\_PLL40\_PAD variant (and REFERENCECLK in instead of PACKAGEPIN)

```
set_io clk_100mhz C8 #R9
```

```
set_io pmod1_1 A11
                   #D8
set_io pmod1_2 B12
                   #B9
set_io pmod1_3 B14
                   #B10
set_io pmod1_4 B15
                    #B11
# 654321
           catboard # 654321 icoboard
#
    xxxxxx PMOD3 A
                        #
                             xxxxxx PMOD1 A
#
                             xxxxxx PMOD1 B
    xxxxxx PMOD3 B
# 654321
                       # 654321
#
set_io pmod1_7 B10
                   #B8
set_io pmod1_8 B11
                   #A9
set_io pmod1_9 B13
                                      PM3
#A10
set_io pmod1_10 A15
                                      #A11
                         PM3-A4
```

PM3-PWR

CATBOARD connection to FPGA pins PMOD 2 & PMOD 3 push button switches, dip switch, and leds.

```
| CR3-IO1 C14 | IO1.168 | PM3-A4 B15 | IO1.179 | IO1.171 | IO1.172 | IO1.173 | IO1.173 | IO1.173 | IO1.174 | IO1.173 | IO1.174 | IO1.175 | IO1.175 | IO1.175 | IO1.176 | IO1.183 | IO1.183 | IO1.183 | IO1.184 | IO1.185 | IO1.185
```

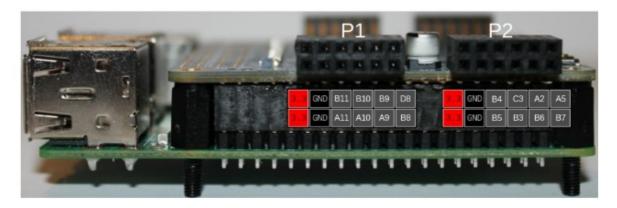
# In top.v

```
module top(clk_100mhz, pmod1_1, pmod1_2, pmod1_3, pmod1_4, pmod1_7, pmod1_8, pmod1_9, pmod1_10, pmod2_7, pmod2_8, pmod2_9, pmod2_10, rpi_sck, rpi_cs, rpi_mosi);

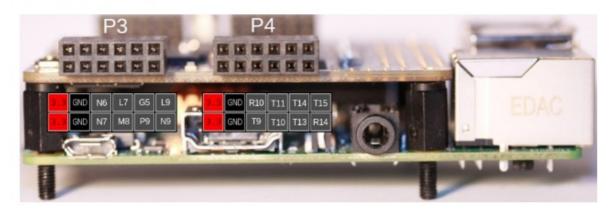
input rpi_sck, rpi_cs, rpi_mosi;
rpi_sck
rpi_cs
rpi_mosi

spi_ram_slave spi_ram_slave(clk, rpi_sck, rpi_cs, rpi_mosi, ram_addr, ram_data, ram_wr);
module spi_ram_slave(clk, sck, cs, mosi, ram_addr, ram_data, ram_wr);
PMOD pin out on icoboard
```

#### Pinout Pmod P1 and P2



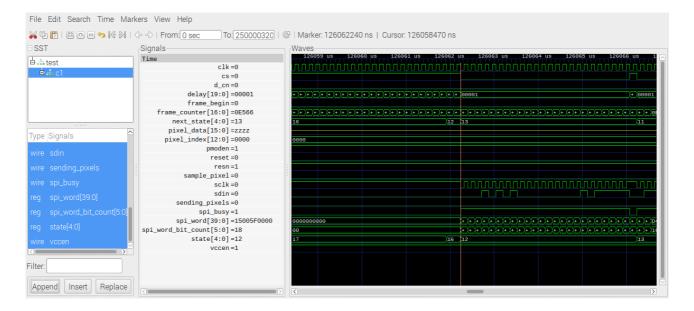
## Pinout PMOD P3 and P4



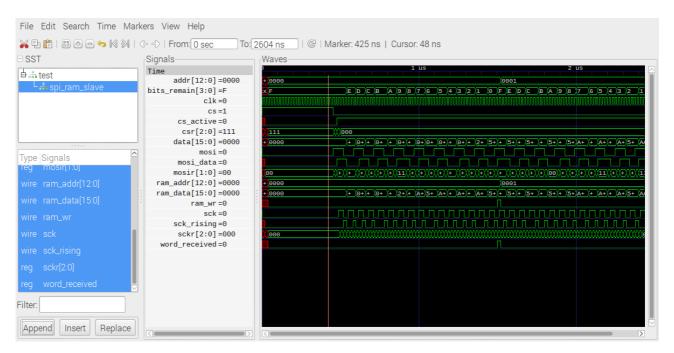
"cd otl-icoboard-pmodoledrgb-demo/fw"

"make"

 $\hbox{``make simulate-pmodoled rgb\_controller'' Creates the VCD file pmodoled rgb\_controller.vcd.}$ 



"make simulate-spi\_ram\_slave" Creates the VCD file spi\_ram\_slave.vcd.



"cd otl-icoboard-pmodoledrgb-demo/fw/"

"sudo config\_cat demo.bin"

"lrwxrwxrwx 1 root staff 34 May 18 20:10 /usr/local/bin/config\_cat -> /home/pi/catboard\_yosys/config\_cat"

#!/bin/bash

#

- # A script to configure Lattice iCE40 FPGA by SPI from Raspberry Pi #
- # Copyright (C) 2015 Jan Marjanovic < jan@marjanovic.pro>
- # This program is free software: you can redistribute it and/or modify
- # it under the terms of the GNU General Public License as published by

```
the Free Software Foundation, either version 3 of the License, or
#
  (at your option) any later version.
#
# This program is distributed in the hope that it will be useful,
#
  but WITHOUT ANY WARRANTY; without even the implied warranty of
  MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the
# GNU General Public License for more details.
#
# You should have received a copy of the GNU General Public License
# along with this program. If not, see <a href="http://www.gnu.org/licenses/">http://www.gnu.org/licenses/</a>>.
echo ""
if [ $# -ne 1 ]; then
  echo "Usage: $0 FPGA-bin-file "
  exit 1
fi
if [ $EUID -ne 0 ]; then
  echo "This script must be run as root" 1>&2
  exit 1
fi
if [!-d/sys/class/gpio/gpio25]; then
  echo "GPIO 25 not exported, trying to export..."
  echo 25 > /sys/class/qpio/export
  if [!-d/sys/class/qpio/qpio25]; then
       echo "ERROR: directory /sys/class/gpio/gpio25 does not exist"
       exit 1
  fi
else
  echo "OK: GPIO 25 exported"
fi
if [!-d/sys/class/qpio/qpio17]; then
  echo "GPIO 17 not exported, trying to export..."
  echo 17 > /sys/class/gpio/export
  if [!-d/sys/class/qpio/qpio17]; then
       echo "ERROR: directory /sys/class/qpio/qpio17 does not exist"
       exit 1
  fi
else
  echo "OK: GPIO 17 exported"
fi
if [!-d/sys/class/qpio/qpio22]; then
  echo "GPIO 22 not exported, trying to export..."
  echo 22 > /sys/class/gpio/export
  if [!-d/sys/class/qpio/qpio22]; then
       echo "ERROR: directory /sys/class/gpio/gpio22 does not exist"
       exit 1
```

```
fi
else
  echo "OK: GPIO 22 exported"
echo ""
if [ -e /dev/spidev0.0 ]; then
  echo "OK: SPI driver loaded"
else
  echo "spidev does not exist"
  lsmod | grep spi_bcm2708 >& /dev/null
  if [ $? -ne 0 ]; then
       echo "SPI driver not loaded, try to load it..."
       modprobe spi_bcm2708
       if [ $? -eq 0 ]; then
         echo "OK: SPI driver loaded"
       else
         echo "Could not load SPI driver"
         exit 1
       fi
  fi
fi
echo ""
echo "Setting GPIO directions"
echo out > /sys/class/gpio/gpio25/direction
cat /sys/class/gpio/gpio25/direction
echo out > /sys/class/gpio/gpio22/direction
cat /sys/class/gpio/gpio22/direction
echo in > /sys/class/gpio/gpio17/direction
cat /sys/class/gpio/gpio17/direction
echo "Setting output to low"
echo 0 > /sys/class/gpio/gpio25/value
cat /sys/class/gpio/gpio25/value
#echo ""
#echo "Please reset the iCE40 FPGA board"
#echo "Press any key..."
#read
echo "Reseting FPGA"
echo 0 > /sys/class/gpio/gpio22/value
cat /sys/class/gpio/gpio22/value
echo 1 > /sys/class/gpio/gpio22/value
cat /sys/class/gpio/gpio22/value
echo "Checking DONE pin"
cat /sys/class/gpio/gpio17/value
```

echo "Continuing with configuration procedure" dd if=\$1 of=/dev/spidev0.0

echo - e " |x0|x0|x0|x0|x0|x0|x0" > /dev/spidev0.0

echo "Setting output to high" echo 1 > /sys/class/gpio/gpio25/value cat /sys/class/gpio/gpio25/value

echo "Checking DONE pin" cat /sys/class/gpio/gpio17/value

"cd otl-icoboard-pmodoledrgb-demo/stream-tool/"

"ffmpeg -f v4l2 -i /dev/video0 -s 96x64 -f rawvideo -pix\_fmt rgb565 - | ./stream-tool"