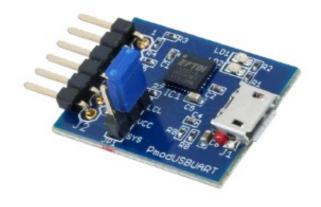
*************Default*********

Testing Pico MultiCore 01/15/22

************Default********

PmodUSBUART



The PmodUSBUART.

Features include:

- USB to serial UART interface
- Option to power the system board through the FTDI chip

Pico	PmodUSBUART

Orange pin 1 TX pin 2 RX
White pin 2 RX pin 3 TX
Black pin 3 GRD pin 5 GRD

export PATH=~/local/openocd/bin:\$PATH

devel@mypi3-20:/opt/pico-examples/build \$

openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program multicore_runner/multicore_runner.elf verify reset exit"

Hello, multicore_runner! Factorial 10 is 3628800 Fibonacci 10 is 0

pico_multicore
pico_stdlib)

create map/bin/hex file etc. pico_add_extra_outputs(multicore_runner_queue)

```
# add url via pico_set_program_url example_auto_set_url(multicore_runner_queue)
```

openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program multicore/hello_multicore/hello_multicore.elf verify reset exit"

Hello, multicore! It's all gone well on core 0!

openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program multicore/multicore_fifo_irqs/multicore_fifo_irqs.elf verify reset exit"

Minicom Baud Rate

```
File Edit Tabs Help
     A - Serial Device : /dev/ttyUSB0
B - Lockfile Location : /var/lock
     C - Callin Program
     D - Callout Program
                            : 115200 8N1
            Bps/Par/Bits
     F - Hardware Flow Control : No
     G - Software Flow Control: No
             RS485 Enable
     Н -
                                : No
           RS485 Rts On Send : No
     J - RS485 Rts After Send : No
     K - RS485 Rx During Tx
     L - RS485 Terminate Bus
     M - RS485 Delay Rts Before: 0
     N - RS485 Delay Rts After: 0
        Change which setting?
```