

Assignment :- I

H Problem Stmt:

- Install and explore the OpenGL.

H Objective:

- To Understand basic concepts of OpenGL & its installation.

H Outcome:

- To implement basic concept of OpenGL.

Theory:

Q. What is OpenGL?

→ OpenGL is a library of function calls for doing computer graphics. The document applications that render high-quality color images composed of 3D geometric objects & images. The current version of OpenGL is 4.5 released on August 11, 2014, and is eighteenth revision since original version 1.0.

H Software Organisation in OpenGL.

- The OpenGL API is window & operating system independent. That means that part of application that draws can be platform independent. Generally, that is controlled by windowing system on whatever platform you are working on.

Software Organisation:

application program

OpenGL Motif

widget or similar

GLUT

GLX, AGL

or

X → Win32 Mac OS

OpLU

Gt

software and/or hardware.

The OpenGL Interface consists of functions in three libraries:

- i). OpenGL core lib: OpenGL 32 on Windows and GL on most unix / Linux systems (libGL.a)
- ii). OpenGL Utility lib. (GLU): Provides func. in OpenGL core but avoids having to rewrite code.
- iii). Links and Window System: GLX for X window systems, WGL for Windows, AGL for Macintosh.

Open GL Utility Toolkit (GLUT)

GLUT provides functionality common to all window system such as opening a window, getting input from mouse & keyboard, menus. GLUT is even - driven & its code is portable.

- GLUT is designed for constructing small to medium sized OpenGL programs.

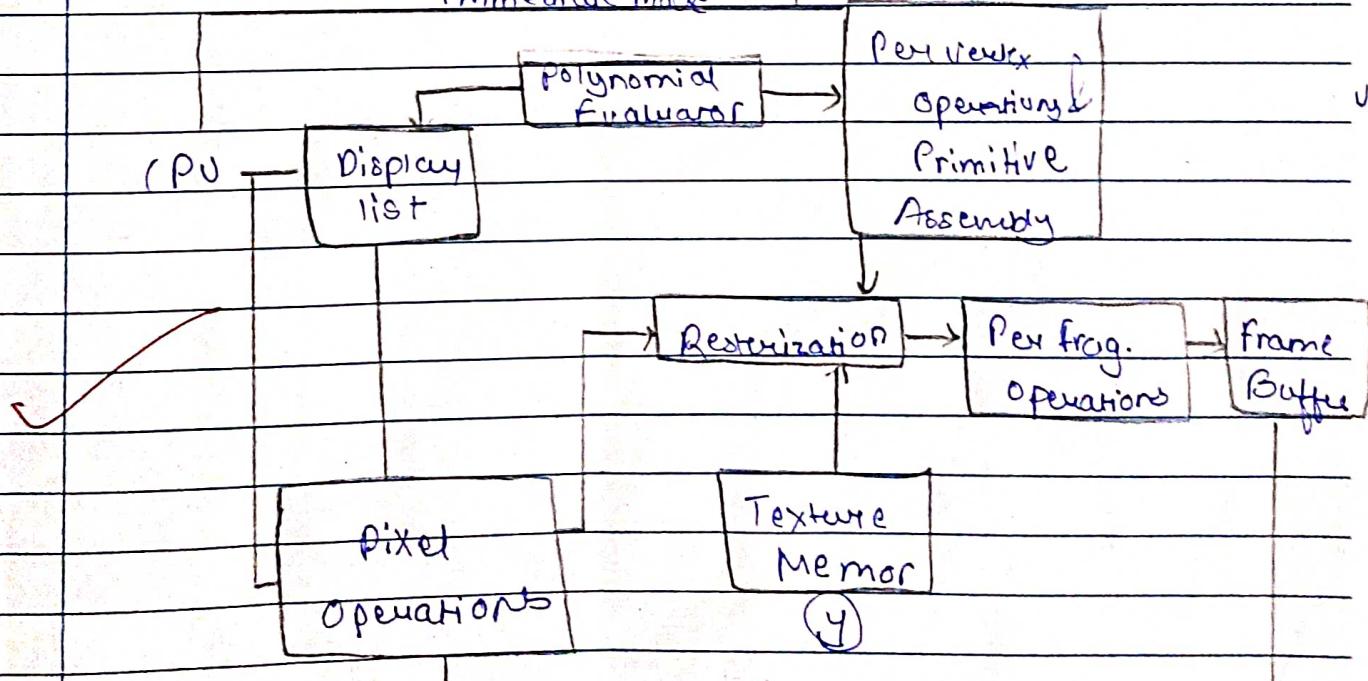
- So large applications requiring sophisticated user interfaces are better off using native window system toolkit. The current version is 3.7. The toolkit supports multiple windows for OpenGL rendering, callbacks driven even processing

Sophisticated input devices on 'idle' awaiting f timers
 A simple, cascading pop-up menu facility, utility
 routines to generate various solid & wireframe
 objects support for bitmap & stroke fonts.

- + OpenGL pipeline Architecture:
- Generally data flows from an application through GPU to generate an image in frame buffer
- The application will provide vertices, which are collections of data that are composed to form geometric objects to the OpenGL pipeline.
- The other shading stages like tessellation & geometry shading are also used for vertex processing.

OpenGL Pipeline

Immediate mode



Primitive & Attributes:

OpenGL
Primitive

Descriptive

Total vertices
for primitive

- | 1) GL - POINTS | Render a single pt.
per vertex (pt. may
be larger than a
single pixel) | n |
|---------------------|--|-----|
| 2). GL-LINES | Connect each pair of
vertices with a
single line segment | 2n |
| 3). GL-LINE STRIP | Connect each successive
vertex to previous one
with line seg. | n+1 |
| 4). GL-LINE LOOP | Connect all vertices in
a loop of line seg. | n |
| 5). GL-TRIANGLES | Render a triangle for
each triple of vertices | 3n |
| 6). GL-TRIANGLE FAN | Create 1'st by using
first vertex in list,
pairs of successive ver-
tices | n+2 |

Commonly Required OpenGL functions:

✓ void glVertex [2/3/4][sifd] (TYPE * coordinate,
Type coordinate,...)

✓ void glVertex [2/3/4]v (TYPE * coordinate)

- Specifies position of vertex in 2,3 or 4 dimensions
The coordinates can be specified as short
s, int ; , float f , or double d . The current

normal, texture coordinates, fog coordinate are associated with vertex x when glVertex is called.

- Delimits the vertices or a primitive or a group of like primitives.
- Mode: Specifies primitive or primitives that'll be created from vertices presented betw. glBegin and subsequent glEnd. Ten symbolic constants are accepted.
- GL_POINTS, GL_LINES, GL_LINE_STRIP, GL_LINE_LOOP, GL_TRIANGLES, GL_TRIANGLE_STRIP, GL_TRIANGLE_FAN, GL_QUADS, and GL_POLYGON void glEnd() terminates a list of vertices.

void glRect [sifd] (TYPE x1, TYPE y1, TYPE x2, TYPE y2)
 void glRect [sifd] v (TYPE * v1, TYPE * v2)

- Specify a 2D axis aligned rectangle by $\begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix}$ coordinates of diagonally opposite vertices (or pointers to the vertices) using standard data types.

b). Specify color :

- void glColor [3u] [b if double] (TYPE red, TYPE green, TYPE blue, TYPE alpha)
- void glColor [3u] [b if double] v (TYPE *color)

- void glClear(GLbitmask r, GLbitmask g, GLbitmask b)
- Specified red, green, blue & alpha values.
- void glIndexi [s if o u] (TYPE index)
 - Set the current colour index.
- + void glutSetColor (int cell, GLfloat red, GLfloat green, GLfloat blue)
 - cell: (glutCreateWindow "window")
 - (Starting at zero)
 - Sets the color index colormap entry of current window's logical colormap for the layer i in use with the colour Specified by red, green and blue.
- + void glPointSize (GLfloat size);

Size: Specifies the diameter of rasterized points. The initial value is 1. glPointSize specifies rasterized diameter of both aliased & antialiased points.

- To enable and disable point antialiasing, call glEnable and glDisable with argument GL_POINT_SMOOTH. Point antialiasing is initially disabled.

Working WITH Window System:

- Different GL implementations buffer commands in several diff. locations, including network buffers and the graphics accelerator itself.

Interaction :

- 1). void glutMouseFunc (void (*func)(int button, int state, int x, int y));
- 2). void glutReshapeFunc (void (*func)(int width, int height));
- 3). void glutKeyboardFunc (void (*func)(unsigned char key, int x, int y));
- 4). void glutIdleFunc(void (*func)(void));
- 5). void glutTimerFunc(unsigned int msecs, void (*func)(int value), value);

Transformations :

- 1). void glMatrixMode(GLenum mode);
- 2). void glPushMatrix(void);
void glPopMatrix(void);
- 3). void glRotatef(float angle, GLdouble x, GLdouble y, GLdouble z);
- 4). void glTranslate(GLdouble x, GLdouble y, GLdouble z);

void glLoadMatrixF (const GLfloat m);

Viewing :

1). void glOrtho (GLdouble left, GLdouble right,
 GLdouble bottom, GLdouble top,
 GLdouble nearVal, GLdouble farVal);

2). void gluOrtho2D (GLdouble left, GLdouble right,
 GLdouble bottom, GLdouble top);
 - define a 2D orthographic projection matrix.

3). void gluLookAt (GLdouble eyeX, eyeY, eyeZ,
 centerX, centerY, centerZ,
 upX, upY, upZ);

4). void gluPerspective (GLdouble Fovy, GLdouble
 aspect, GLdouble zNear, GLdouble zFar);

- The aspect ratio is the ratio of x (width)
 to y (height).
 distance from the viewer to the

near clipping plane (away positive).

✓ zFar specifies the distance from the
 viewer to the far clipping plane
 (always positive).

• OpenGL Installation ;

- > Open Terminal by using following command
 $\text{Ctrl} + \text{Alt} + \text{T}$
- > Go to root directory by using following command
 $\text{su} -$
- > Then press enter
Enter password
- > Run the following commands to install OpenGL.
 $\$ \text{sudo apt-get update}$
 $\$ \text{sudo apt-get install libglu1-mesa-dev freeglut3-dev mesa-common-dev}$
- > Now to test;
if OpenGL libraries are working fine on our linux → we will create a C++ program and test it.
 - For creating Program type \$ gedit on terminal Then save the program in root directory :cpp extension.
- > Now give command (to compile);
→ $\$ \text{g++ programme.cpp -o batchfilename -lglut -lGLU -lGL}$.

- How run your OpenGL program with command
- \$./basenamefilename.

[Output] :

(Execute program & attach the printout)

ii) Conclusion) ;

In this way we have studied that how to install & explore OpenGL.

mainapp (1) - Code::Blocks 20.01

File Edit View Search Project Build Debug Run Configuration Tools Tasks Plugins Help

Project File Symbols Resources

mainapp

Source main.cpp

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Assignment :- 2

Problem Statement;

Implement DDA and Bresenham's line drawing algorithm to draw ;

- Simple Line
- Dotted Line
- Dashed Line
- Solid line

using mouse interface Divide the screen in 4 quadrants with center as $(0,0)$. The line should work for all the slopes +ve as well as -ve.

Objectives;

- To learn DDA line drawing algorithm.
- To learn Bresenham line drawing algorithm.

CO Relevance;

CO₂

PO PSOs Relevance;

PO1, PO2, PO5, PO6

Raster Scan Display;

- When the beam reaches the bottom of the screen, it is made off and rapidly retraced back to top left and start again.

Components:

- a) Graphic Commands
- b) Frame Buffer.
- c) Visual Display Unit.

H Characteristics ;

Host CPU Graphics Commands	Display file Translator	Display file program	Display file Processor
----------------------------------	-------------------------------	----------------------------	------------------------------

++ Line;

- It is the path between two end points. Any point (x, y) on the line must follow the line equation.

$$y = m * x + b, \text{ where}$$

- m is the slope of the line

- b is a constant represent the intercept on y -axis.

The slope of the line (m) between these points can be calculated as:

$$m = \Delta y / \Delta x = (y_1 - y_0) / (x_1 - x_0)$$

To draw a line, we can use two algorithms:

I). DDA Line Drawing Algorithm;

- 1). Start
- 2) Declare variables & gDriver = DETECT & gMode.
- 3). Initialize graphics mode using initgraph()
- 4). Read line end points (x_1, y_1) & (x_2, y_2)
- 5). Calculate difference betw. 2 end points.

$$\Delta x = x_1 - x_2$$

$$\Delta y = y_1 - y_2$$

- 6). If $\Delta x = \Delta y$ & $x_1 \leq x_2$ then
 - Increment x by 1
 - " y by m
- else if $\Delta x > \Delta y$ & $x_1 > x_2$ then
 - Increment x by -1
 - " y by -m

Close if $\Delta x < \Delta y$ & $y_1 \leq y_2$ then

Increment x by $1/m$

Increment y by 1

Else if $\Delta x < \Delta y$ & $y_1 > y_2$ then

Increment x by $-1/m$

" y by -1

7). Plot x increment & y increment.

8). repeat step 6

9). Close graph

10). Stop

+ Bresenham's Line Drawing Algorithm }

1). Start

2). Declare the variables and gdriver = DETECT & gMode.

3). Initialize the graphics mode using initgraph().

4). Read the line end points (x_1, y_1) & (x_2, y_2) .

5). Calculate $d_x = x_2 - x_1$ & $d_y = y_2 - y_1$.

6). $x = x_1$ & $y = y_1$

7). $e = 2 * d_y - d_x$

8). $i = 1$

9). Plot (x, y)

10). while ($e \geq 0$)

 2

$y = y + 1$

$e = e - 2 * d_x$

 3

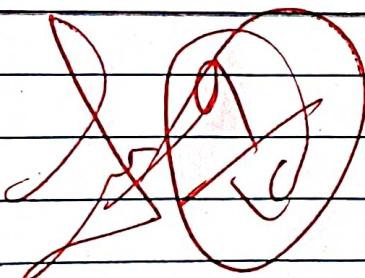
$x = x + 1$

$e = e + 2 * d_y$

11). $i = i + 1$

12). if ($i \leq d_x$) then go to step 9.

- 13) Close graph
 - 14) Stop.
- + Output ;
- (Execute program and attach printout here)
- + Conclusion ;
- In This way we have studied that how to draw a line using PDA and Bresenham's.



mainapp [D] - CodeBlocks 20.05

File Edit View Send Project Build Debug Tutorials wsSmith Tools Help Plugins EasyBlocks Settings Help

mainapp.x
352 185 cout << "End point: (" << x1 << ", " << y1 << ")\n";

Start point: (-222, 203)
End point: (201, 202)

Line DDA and Bresenham Scheme 5512009

```
C:\Program Files (x86)\CodeBlocks\MinGW\include\crt\w32api.h:76: Warning: ignoring #pragma warning [-Wunknown-pragmas]
# pragma warning (disable:4244) /* Disable bogus VC++ 4.2 conversion warnings. */
C:\Program Files (x86)\CodeBlocks\MinGW\include\crt\w32api.h:77: Warning: ignoring #pragma warning [-Wunknown-pragmas]
# pragma warning (disable:4211) /* VC++ 8.0 version of above warning. */

Output file is mainapp.exe with size 111 KB
Program terminated with status 0 (0 minutes, 1 seconds)
0 errors, 0 warnings (0 minutes, 1 seconds)

----- Run: Debug in D:\compiler\bin\MinGW -----
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.exe
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.pdb
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.map
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.hprof
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.dSYM
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.pdb
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.map
Checking file existence: C:\Users\Hari\Downloads\mainapp\mainapp.hprof
Executing "C:\Program Files (x86)\CodeBlocks\MinGW\bin\Debug\mainapp.exe" via C:\Program Files (x86)\CodeBlocks\MinGW\bin
```

C:\Users\Hari\Desktop\CG\5\mainapp

C/C++ Windows (CR-LF) WINDOWS-1252 Line 368 Col 53 Pos 3110 Insert Read/Write default

Assignment :- 3

H Problem Statement:

- Implement Bresenham's circle drawing algorithm to draw any object. The object should be displayed in all the quadrants with respect to center & radius.

-II Objective:

- To Understand the basic concepts of circle drawing.

H Outcome:

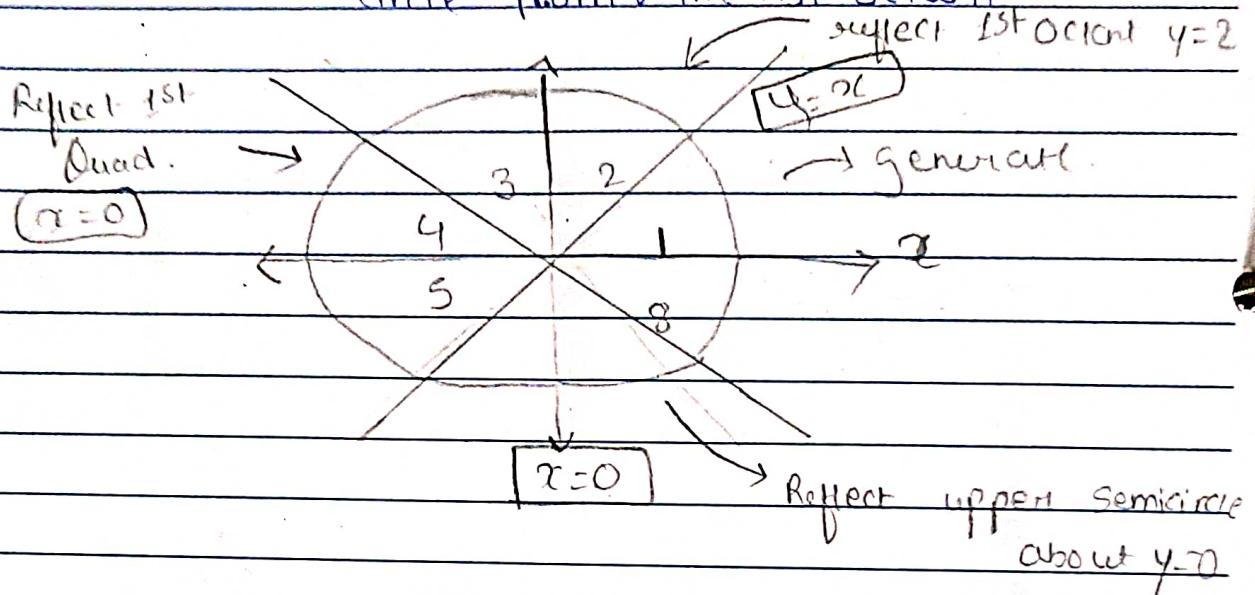
- To implement basic concept of circle drawing using Bresenham's algorithm.

H Theory Concepts:

- One of the most efficient and easier to draw circle is by using Bresenham's circle drawing algorithm.
- The other parts can be obtained by successive reflections. The line $y = x$ to yield the 1st quadrant.
- The result in the 1st quadrant are reflected through the line $x = 0$ to obtain those in 2nd quadrant.

Diagram:

Generation of complete circle from the first octant



- This can be decided by parameter p
 - If $p \leq 0$, then $N(x+1, y)$
 - If $p > 0$, then $S(x+1, y-1)$

+ Algorithm :

- 1) Input radius r and circle center (x_c, y_c) obtained the first point $(x_0, y_0) = (0, r)$
- 2) Calculate the initial value of decision parameter as $[P_0 = 3 - 2r]$
- 3) At each x_k position, starting at $[k=0]$, perform \rightarrow the following test:

IF $P_k \leq 0$, the next pt. is (x_{k+1}, y_k)
 $P_{k+1} = P_k + 4y_k + G$

Otherwise next point is (x_{k+1}, y_{k-1})
 $P_{k+1} = P_k + 4(x_k - y_k) + 10$

4). Determine Symmetry points in other seven octant.

5). Move each pixel position (x, y) into circular path $x = x + xc$ & $y = y + yc$

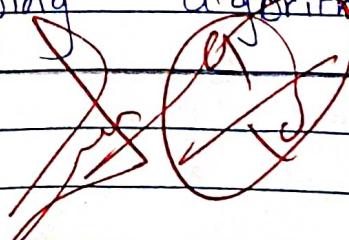
6). Repeat Step 3 & 5.

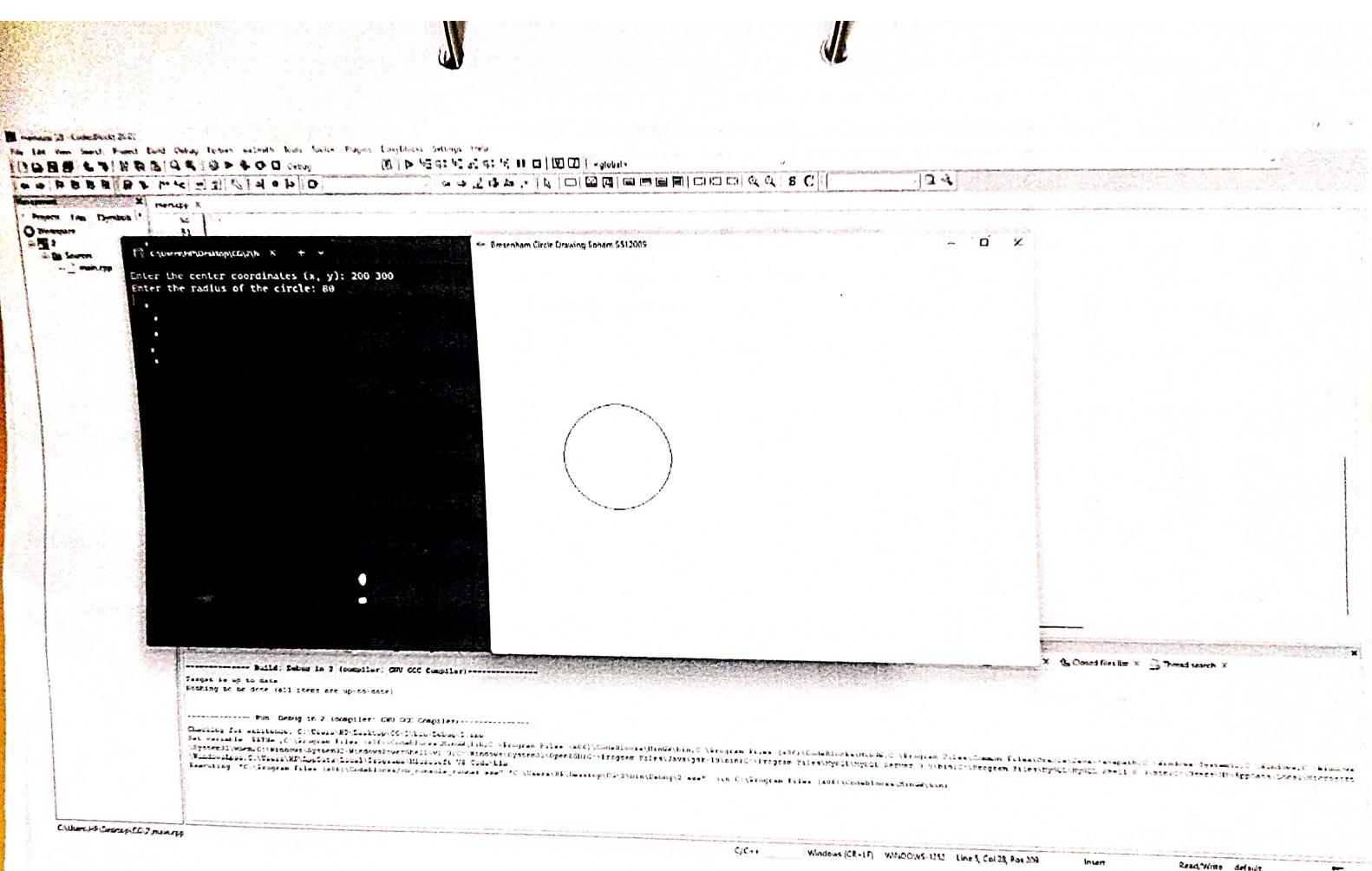
+ Output :

- Execute program & attach.

+ Conclusion :

- In this way we have studied that how to draw a circle using Bresenham's circle drawing algorithm.





Assignment :- 4

Problem Statement:

Implement following polygon filling methods;
 i). Flood fill / Seed fill ; ii) Boundary fill
 ; using mouse click,
 keyboard interface & menu driven
 programming.

Objective :

To Understand the basic concepts of polygon filling.

Outcome:

To implement a polygon filling methods using Flood fill / Seed fill & Boundary fill.

Theory Concepts:

1). Polygon Filling Approaches:

Types:

- a) Boundary Fill Algorithm.
- b) Flood fill Algorithm.

2). Boundary fill Algorithm:

Algorithm:

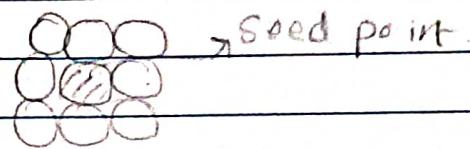
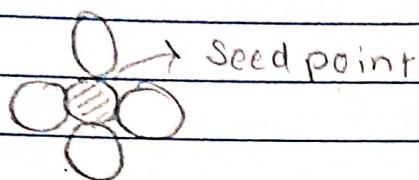
- 1). The Boundary fill procedure accepts input as coordinates of an interior point (x, y) , fill color and boundary color.
 - 2). Starting from (x, y) which is seed pixel, the procedure tests the neighbouring positions to determine whether they are boundary color.
 - 3). If not, they are painted with fill color, and neighbours are tested.
 - 4). This process continues until all pixels up to the boundary color for the are have been tested.
- These are two methods for filling the pixel and find the neighbour pixel;
- i). 4-connected
 - ii) 8-connected

ii]. Flood Fill:

- The purpose of flood fill is to color an entire

We start with seed pixel, seed pixel is examined for specified interior color instead of boundary color.

Diagram:



i) 4-connected

ii) 8-connected

Pseudo Code for boundary fill - Algorithms;

```
void boundary fill4 (int x, int y, int fill_color, int
boundary_color)
```

{

```
    putpixel (x, y, fill_color);
```

```
    boundaryfill4 (x + 1, y, fill_color, boundary
color);
```

:

\

```
    boundaryfill4 (x, y - 1, fill_color, boundary
color);
```

}

g

Pseudo Code for Flood Fill Algorithm;

IF (getpixel (x, y) = old_color)

3

Setpixel (x, y , fill_color);

fill ($x+1, y$, fill_color, old_color)

fill ($x-1, y$, fill_color, old_color);

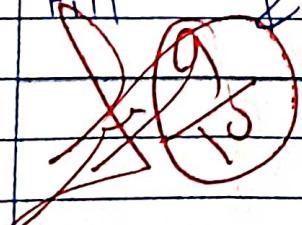
($x, y-1$, fill_color, old_color);

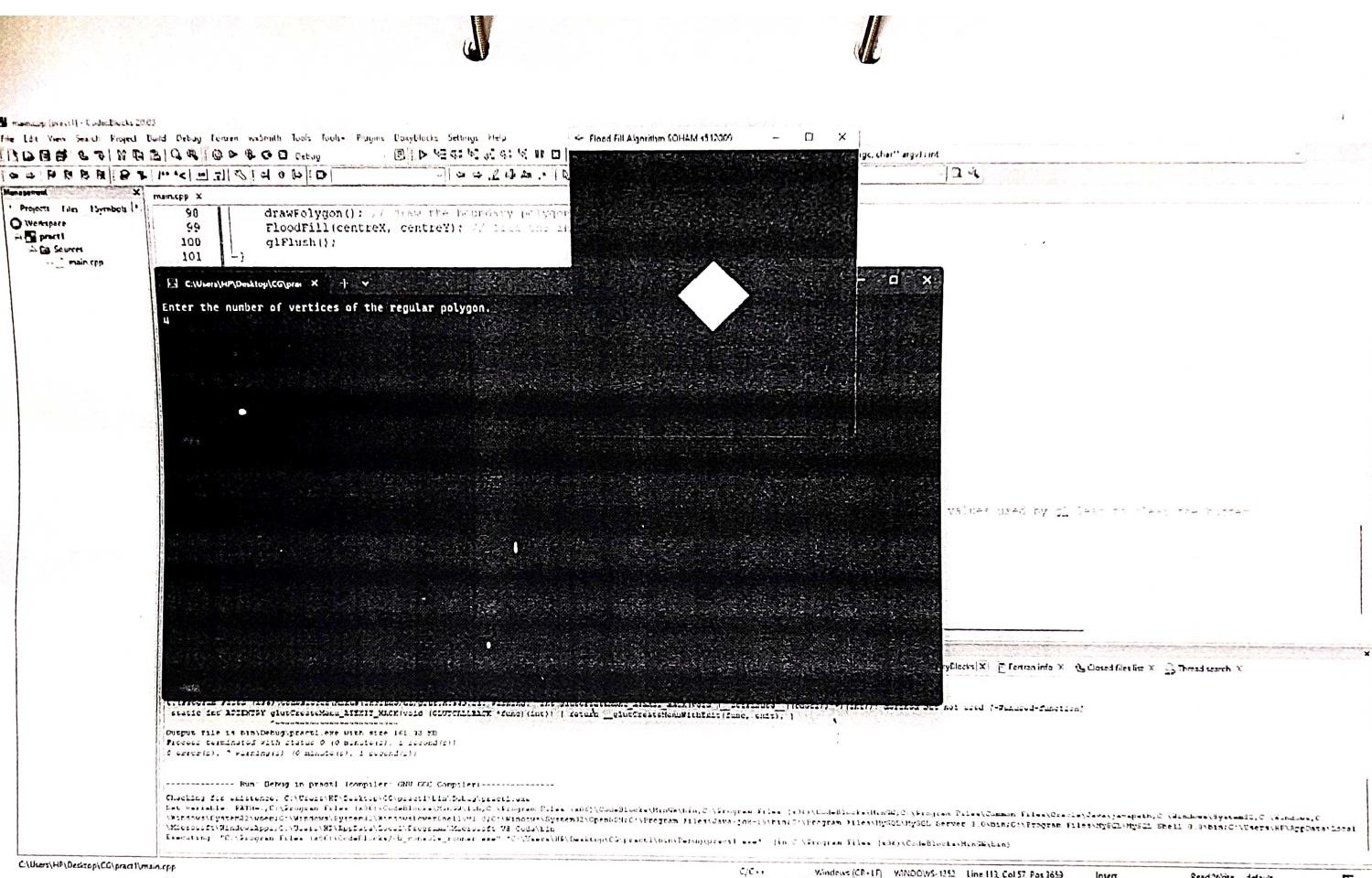
3

Output;

Conclusion;

In This way we have studied that how to fill polygon using flood fill / Seed fill & boundary fill method.





Assignment No:- 5

H Problem Statement:

- Implement Cohen Sutherland polygon clipping method to clip the polygon with respect to the view-port and window.
- Use mouse click, keyboard interface.

H Objective;

- To Understand the basic concept of polygon clipping.

H Outcome;

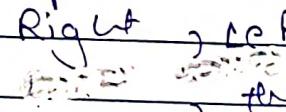
- To implement basic concept of polygon clipping using Cohen Sutherland clipping algorithm.

H Theory;

1). Line Clipping - Cohen Sutherland;

- In computer graphics, 'line clipping' is the process of removing lines or portions of lines outside of an area of interest.
- The algorithm was developed in 1967 during flight simulator work by Dan Cohen and Ivan Sutherland. The design state includes excludes or partially

includes line based on where;

- Both endpoints are in viewport region (bitwise OR of endpoints $= 0$);
- Both endpoints share at least one non-vrsc region (bitwise AND of endpoints $\neq 0$).
- + The numbers in the figure below are called outcodes.
- The outcode is computed for each of the two pts. i.e. The outcode will have four bits for two-dimensional clipping, or six bits on three dimensions.
- The first bit is set if the point is above the viewport. The bits in the 2D outcode represent:
 - Top, Bottom, Right, Left.
 - for example  the outcode 1010 represents a point i.e. top-right of the viewport.

- Note that the outcodes for endpoints must be recalculated on each iteration after the clipping occurs

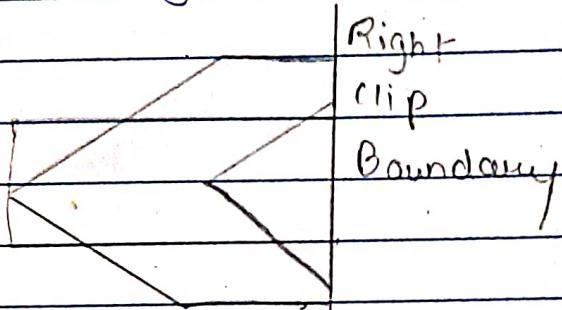
1001	1000	1010
0001	0000	0010
0101	0100	0110

+ Sutherland Hodgman Polygon Clipping :

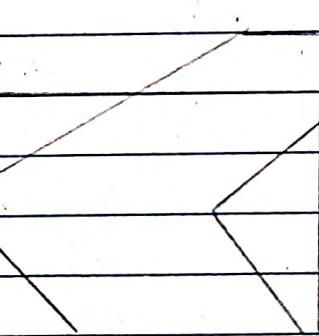
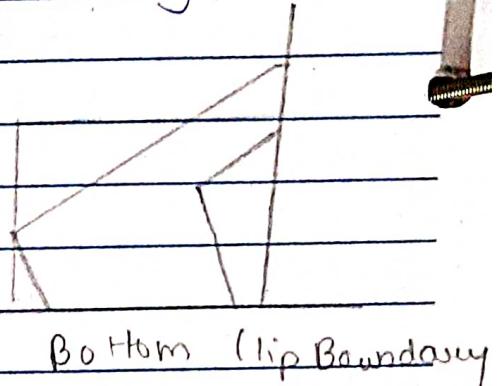
- Used for clipping polygons. It works by extending each line of the convex clip polygon in turn and selecting only vertices from the subject polygon those are on the ~~subject~~ ^{visible} state.
- This process is repeated for iteratively for each clip polygon side, using the output list from one stage as the input list for the next.
Once all sides of the clip polygon have been processed, the final generated list of vertices defines a new single polygon i.e. entirely visible.
- Note i.e. the subject polygon was concave at vertices outside the clipping polygon, the new polygon may have

coincident (i.e. overlapping) edges - this is acceptable for rendering, but not for other applications such as computing shadows.

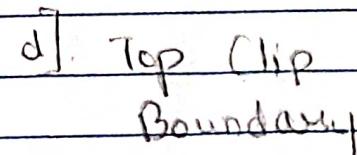
a].



b].

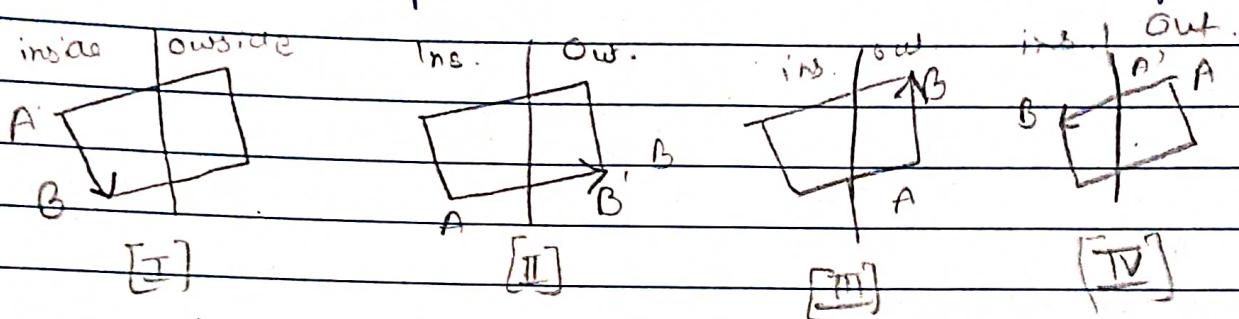


c]. Left clip Boundary



d]. Top clip Boundary

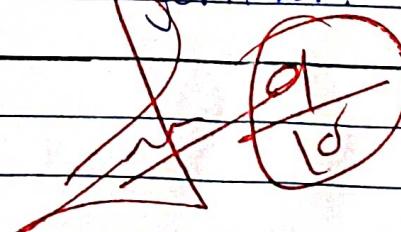
- The Sutherland - Hodgeman algorithm clips a polygon to be quite complex.
- The algorithm steps from vertex to vertex adding 0, 1 or 2 vertices to the output list at each step

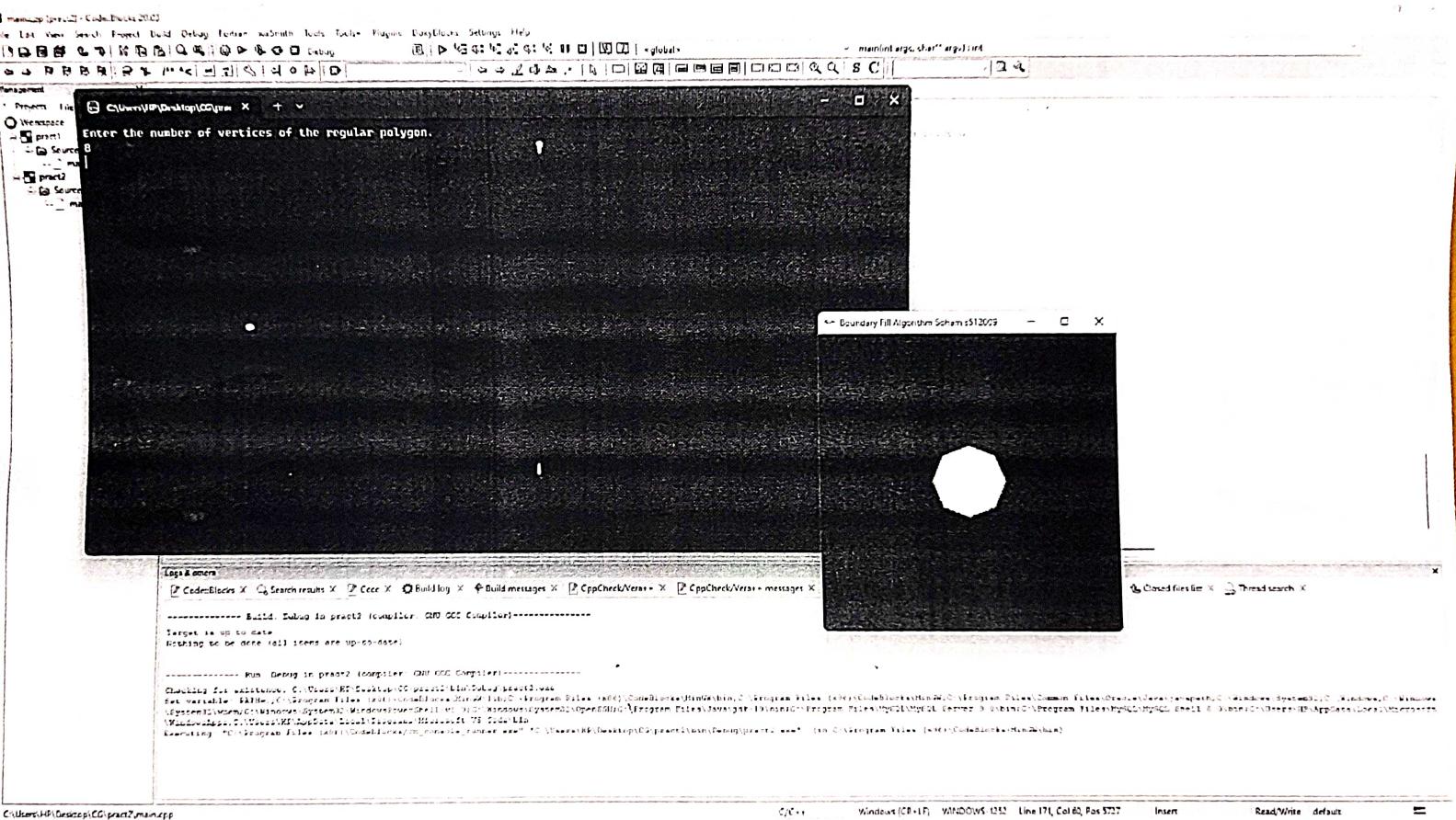


- The Sutherland - Hodgeman Polygon-Clipping Algorithms clips a given polygon successively against the edges of the given clip-rectangle.

Conclusion ;

- In this way we have studied that how to clip polygon using Cohen Sutherland Clipping algorithm.





Assignment :- 6

+ Problem Statement;

- Implement following 2D transformations on the object with respect to axis;
- i). Scaling ; ii). Rotation about arbitrary point.
- iii). Reflection.

+ Objective;

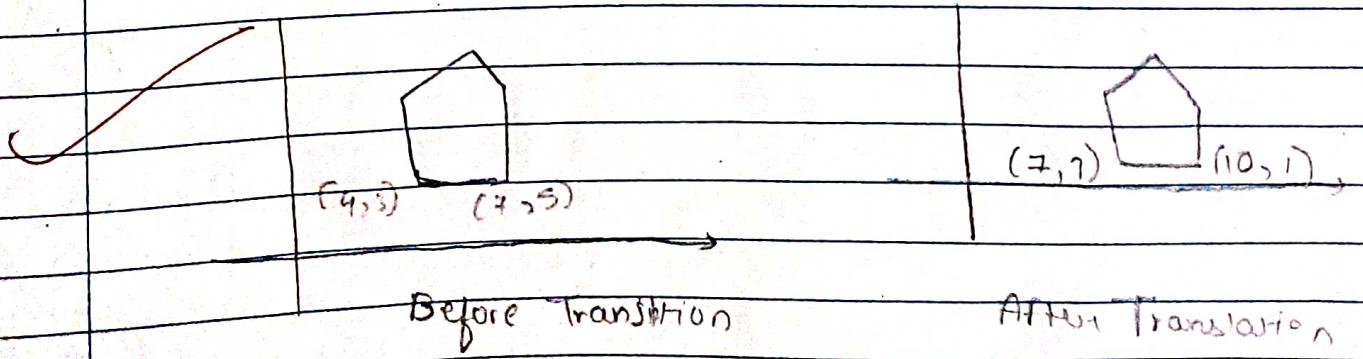
- 1). To understand 2D Homogeneous coordi. System
- 2). Understand and implement 2D transformations in laboratory.

+ Outcome;

- To implement transformation operations.

+ Theory;

1). Translation;



- We can move the objects based on translation distances along x & y axis
- Consider (x, y) are old coordinates of a point. Then the new coordinates of that same point (x', y') can be obtained as follows;

$$x' = x + tx$$

$$y' = y + ty$$

27. [Scaling] ;

- Scaling refers to changing size of the object either by increasing or decreasing
- If (x, y) are old coordinates of object, then new coordinates of object after applying scaling transformation are obtained as,

$$x' = x * s_x$$

$$y' = y * s_y$$

$$\therefore \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix}$$

4

Rotation :

- A rotation imposes all points in an object along a circular path in the plane centered at the pivot point. We rotate an object by an angle theta.

$$x' = x \cos \theta - y \sin \theta$$

$$y' = x \sin \theta + y \cos \theta$$

$$P' = R * P$$

R - Rotation Matrix.

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

formula : $x = x \cos \theta - y \sin \theta$
 $y = x \sin \theta + y \cos \theta$

The above formula will rotate the point around the origin.

To rotate around a diff. point, the formula;

$$x = (x + (cx - cx) * \cos \theta - (y - cy) * \sin \theta)$$

$$y = (x + (x - cx) * \sin \theta + (y - cy) * \cos \theta)$$

(x, y) is center coordinates,
 θ is the angle of rotation,

+ Reflection ;

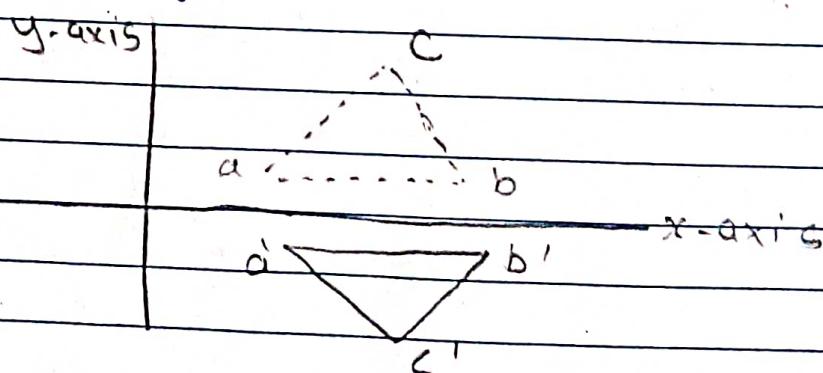
- It is transformation which produces a mirror image of an object. The mirror image can be either about x -axis, or y -axis
 Object rotated by 180° .

+ Types of Reflection;

I). Reflection about x -axis;

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- In this transformation value of x will remain same whereas value of y will become $-ve$.
 Following figure shows the reflection of the object axis. The obj. will lies on another side of the x -axis.



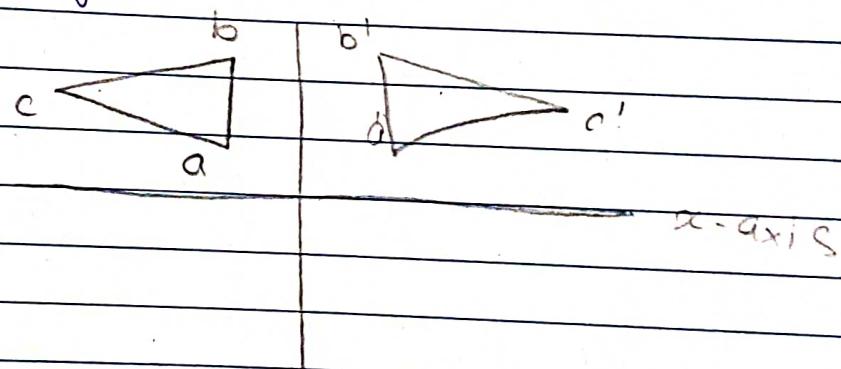
(35)

(33)

II]. Reflection about y-axis;

$$\rightarrow \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Here the values of x 'll be reversed, whereas the value of y will remain the same. The object will lie another side of the y -axis.

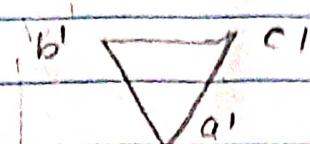
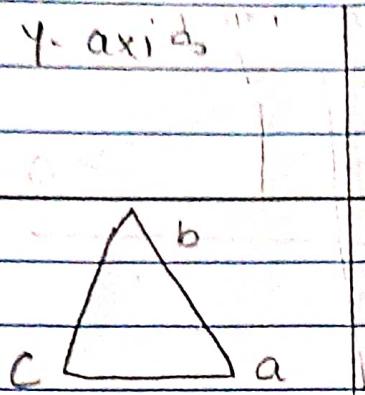


III]. Reflection about an axis perpendicular to xy plane & passing through origin;

In the matrix of this transformation is given below

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

y-axis



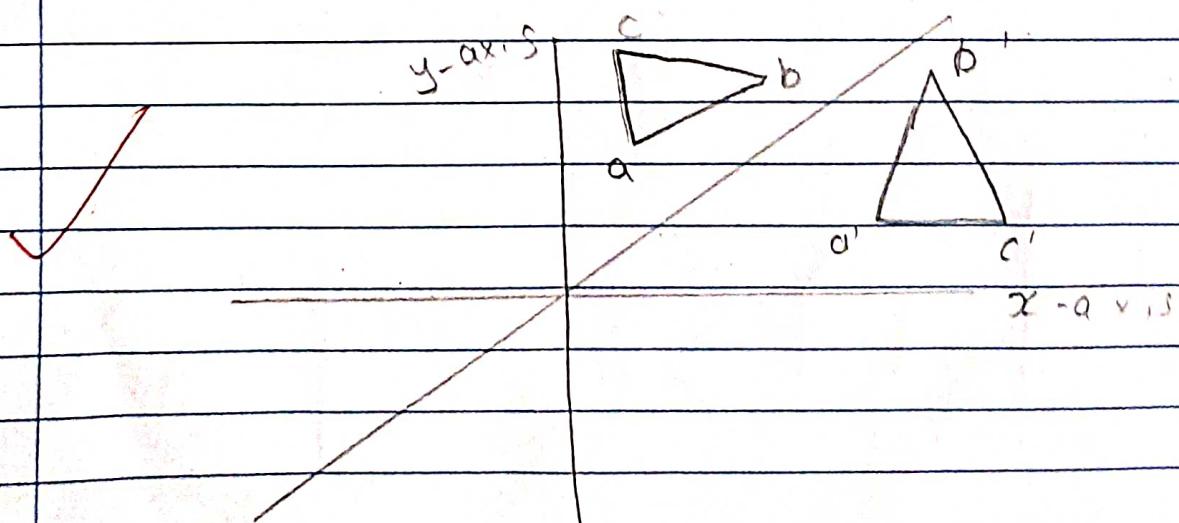
x-axis

In this value of x and y both will be reversed. This is also called as $1/2$ revolution about the origin.

IV] Reflection about line $y=x$:

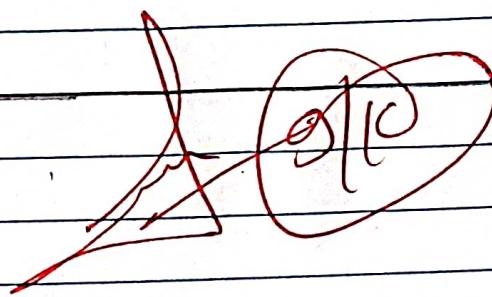
- The object may be reflected about line $y=x$ with the help of following transformation matrix.

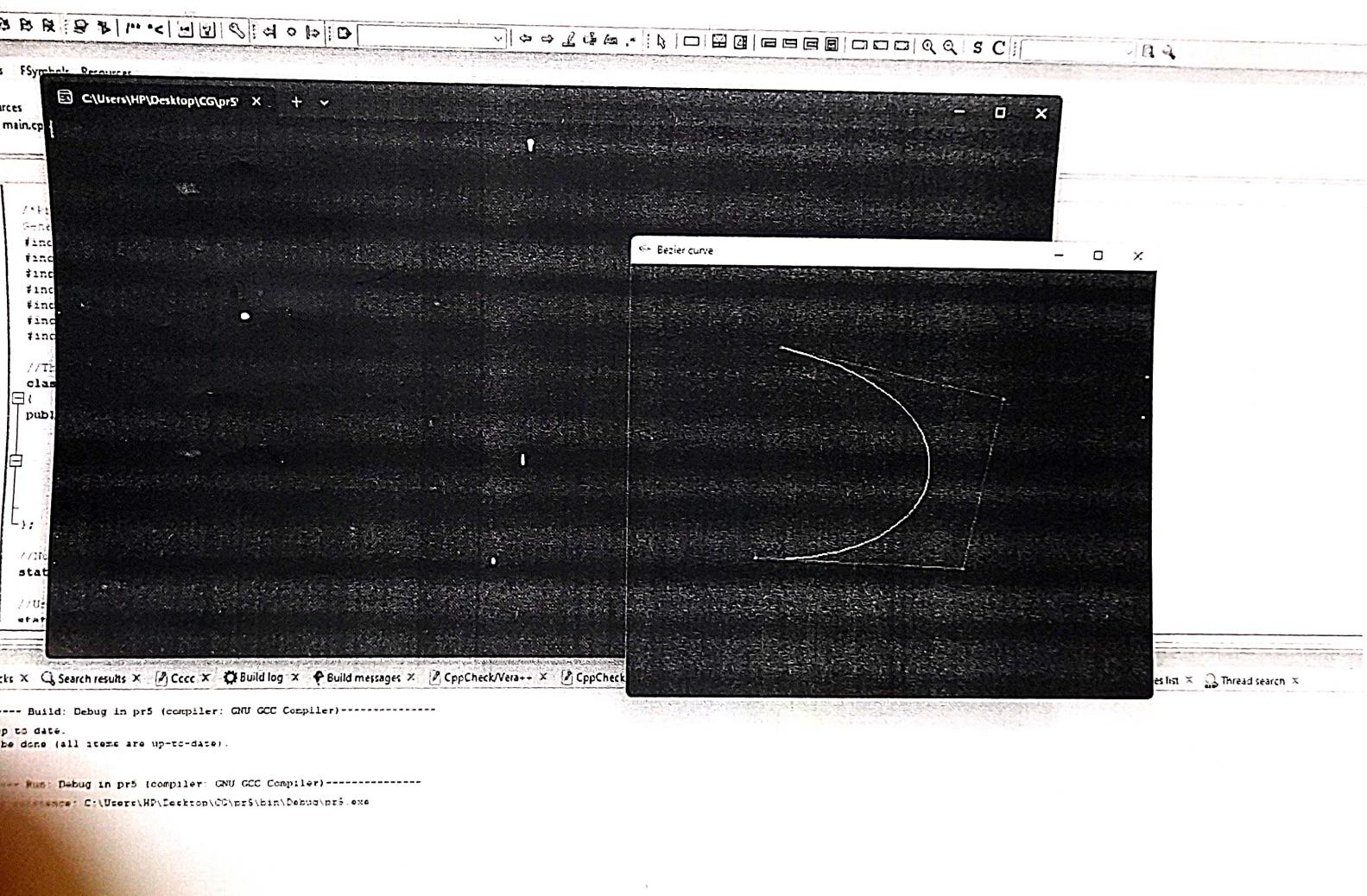
$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



+ Conclusion:

✓ In this way we have studied that how to perform 2 dimension operations on object.





Assignment:- 7

H Problem Statement;

- Generate fractal patterns using i). Bezier
- ii). Koch Curve.

H Objective;

- Understand different types of curve.
- Implement diff. Objects using Koch curve & bezier curve fractal patterns.

H Outcome;

- To implement fractals patterns using bezier & Koch curve.

H Theory Concept;

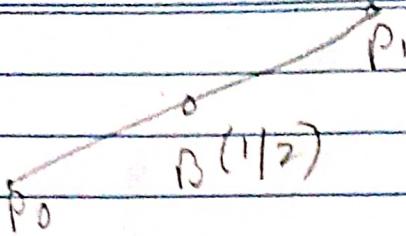
i) Bezier Curves:

Bezier curve is discovered by french engineer Pierre Bézier. These curves can be generated under control of other points. Approximate tangents by using control points are used to generate curve. The Bezier can be represented as;

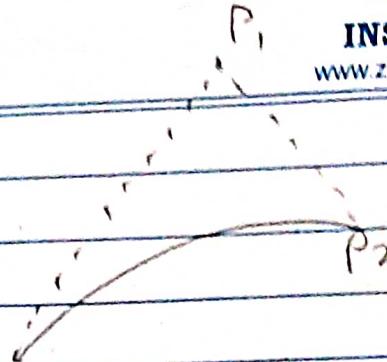
$$\sum k = \text{On } P_i B_{ni}(t)$$

(where P is set of points & $B_{ni}(t)$ represents Bernstein polynomials given by;

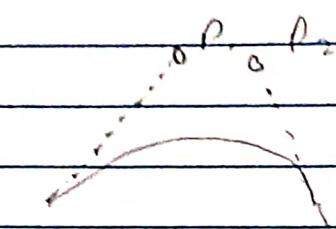
$$B_{ni}(t) = (n_i) (1-t)^{n-i} t^i$$



Simple Bezier Curve



Quadratic Bezier Curve



Cubic Bezier Curve

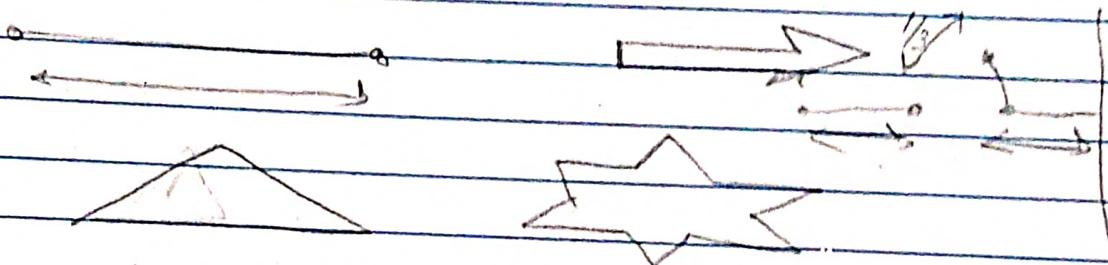
Properties of Bezier Curves:

- They generally follow shape of control polygon.
- They always pass through first & last.
- They are contained in convex hull of their defining control pts.
- The degree of polynomial defining curve segment is one less than no. of defining polygon points.
- A Bezier curve generally follows shape of defining polygon.
- ✓ The convex hull property for Bezier curve ensures that polynomial smoothly follows control pts.
- No straight line intersects Bezier curve more times than it intersects its control polygon.
- They are invariant under an affine transformation.

Surface textures & just to make pretty patterns.

In other disciplines, fractal patterns have been found in distrib. of stars, rivers, islands and moon craters; in rain field; in stock market variations; in music; in traffic flow.

Koch Fractals (Snow-flakes)



Add some Randomness:

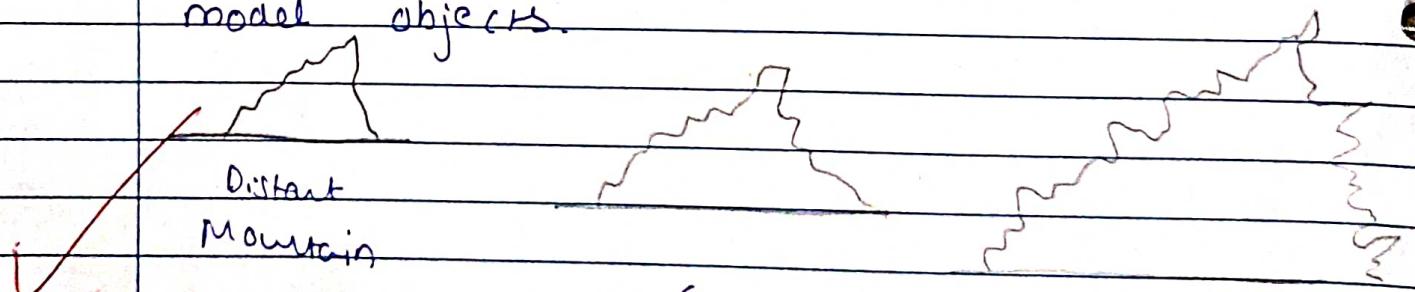
- > Fractals we've produced so far seem to be very regular & "artificial".
- > To create some realism & variability simply change angles slightly sometimes based on random no. generator.

? For eg:- you can curve some of fracs to one side

- Bezier curves exhibit global control means moving a control point alters shape of whole curve.

+ Koch Curve;

- fractals are geometric objects. Many real-world objects like ferns are shaped like fractals. Fractals are self-similar. In CG, we use fractal functions to create complex object. The obj. representations uses Euclidean - geo. methods; obj. shapes were described by the eqns. Those that're smooth, surfaces & regular shapes.
- Natural objects can be metabolically described fractal - geo. methods, where procedures rather than eqn's are used to model objects.



Ex: In graphics representation, application, yet fractal are used to model terrain, clouds, water, trees & other plants, feathers, fur & various

H Terrain (Random Mid-Point Displacement):

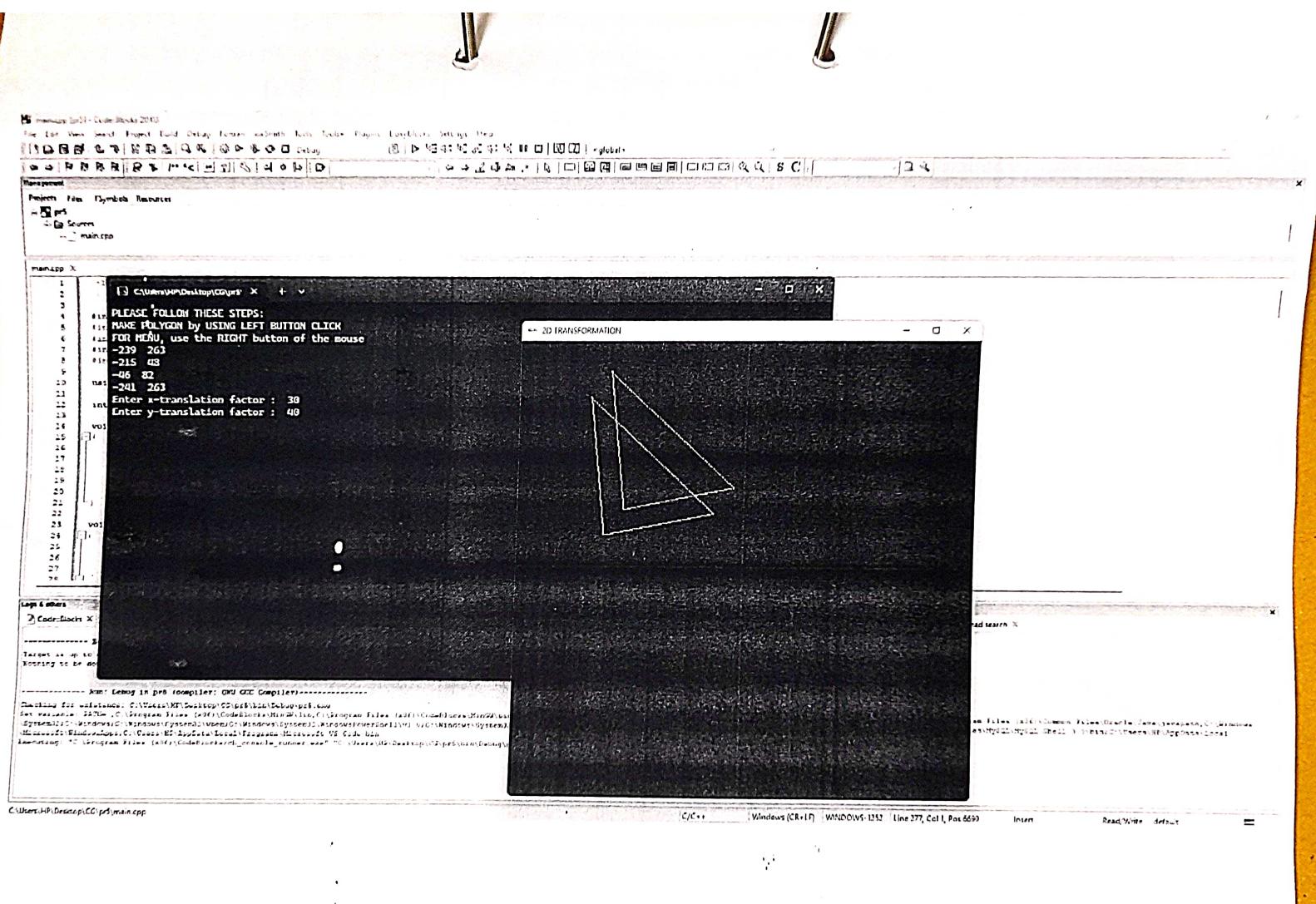
- > Given hts. of two end-pnts. \rightarrow generate a ht. at mid-pt.
- > Then \rightarrow the height at mid-pt. will be:

$$y_{mid} = (y(a) + y(b))/2 + r,$$
 r is random offset.
- > This is how to generate random offset r
 $r = s \cdot rg(b-a),$
 rg is Gaussian random variable with
mean 0 & variance 1.

H Conclusion:

In this way we've studied that how to generate fractal patterns using curve generation methods.

9/10



Assignment :- 8

Problem Statement:

Implement animation principles for any object

Objective:

- 1). To learn different types of animation
- 2). To learn OpenGL function which support for animation.

Sutcome:

- To implement animation for an object.

Theory Concepts:

- Animation is defined as series of images rapidly changing to create an illusion of movement. We replace previous image with new image is little bit shifted.
- Animation Industry is having a huge market nowadays. To make an efficacious animation there are some principle to be followed.

Principle's

- There are 12 major principles for an effective and easy to communicate animation.

I]. Squash & Stretch;

- This principle works over the physical properties that are expected to change

in any process. Ensuring proper square and stretch makes our animation more convincing.

II] Anticipation;

- Anticipation works on action. Animation has broadly divided into 3 phases :
 - 1) Preparation phase
 - 2) Movement phase
 - 3) Finish.
- In Anticipation ; we make audience prepare for action.

III] Arcs;

- In Reality, humans & animals move in arcs - Introducing concept of arcs will increase Realism. This principle of Animation helps us to implement the Realism through projectile motion also.

IV] Slow in - Slow out;

- ~~- While performing animation , one should always keep in mind that in reality object takes time to accelerate and slow down.~~
- To make our animation look realistic, we should always focus on its slow in slow out

V]. Appeal;

- Animation Should be appealing to the audience and must be easy to understand. The Syntax or font style user should be easily understood and appealing to the audience.

VI]. Timing;

- Velocity with which object is moving effects animation a lot. The Speed is handled with care in case of animation.

VII]. 3D- Effect;

- By giving 3D-effects we can make our animation more convincing and effective.
- In 3D Effect , we convert our object in 3D plane i.e. X-Y-Z plane which improves realism of the object .

VIII]. Exaggeration;

- Exaggeration deals with the physical features and emotions. In Animation, we represent emotions and feelings in exaggerated form to make it more

realistic . If there is more than one element in a scene then it is necessary to make balance between various exaggerated element to avoid conflicts.

IX) Staging ;

- Staging is defined as presentation of primary idea , mood or action.
- It should always be in presentable and easy to manner.
- The purpose of defining principle is to avoid unnecessary details and focus on important features only.
The primary idea should always be clear & unambiguous.

X) Follow Through ;

- It refers to the action which continues to move even after the completion of action . This type of action helps in generation of more idealistic animations.

XI). Overlap;

- It deals with the nature in which before ending first action, the second action starts.

for eg:- Consider situation when we are drinking Tea from right hand and holding sandwich in the left hand.

- While drinking a tea our left hand starts showing movement towards mouth which shows interference of second action before end of 1st action.

II) Output;
(Execute)

II) Conclusion;

- In this way we have studied that how to use animation techniques



~~9/10~~

