**Project List**

* Keyboard control drone using mavlink and raspberry pi
* Keyboard control drone using NRF Arduino and raspberry pi
* Keyboard control drone using Arduino and raspberry pi with ZeroTier network
* SiTL and Gazebo Keyboard control using mavlink
* Blynk control drone using ESP32
* Override Fs-iA6B using Arduino & send PPM output to pin 2 🡪 signal pin Pixhawk
* Override Fs-iA6B using ESP32 & send PPM output to pin 14 🡪 signal pin Pixhawk
* Override Fs-iA6B using Arduino & send PPM output to pin 5,6,7,8 (servo.attach) 🡪 PPM Encoder 🡪 signal pin Pixhawk
* Gesture control drone using Jetson Nano and Mavlink
* Human Pose estimation control drone using Jetson Nano and Mavlink
* Drone delivery project – Refer to YT channel
* Obstacle avoidance robot using override Fs-iA6B PPM output using Arduino – HCSR04 / Lidar
* Obstacle avoidance robot using Telemetry port and Mavlink – HCSR04 / Lidar
* Aruco Drone Project for precision landing and manuever
* Range Finder and Follow me mode
* Install Gimbal into drone.

**Status**