Today I Learned

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April 2019

(11/4/19) Today I learned a way of defining integration of differential form over a continuous path and how the definition will match with piece-wise differentiable path. I also learned about properties of Index of a path with respect to a point and why it is a locally constant function.

(12/4/19) Today I learned about Laurent expansion in complex analysis and the proof of the theorem that Laurent expansion of holomorphic function in an annulus exists and is unique. The proof involved a way of sneaking Cauchy integral formula in the annulus by applying it to a null-homotopic but information giving path and things as you expect them to be nicely.

(13/4/19) Today I learned about continuous dependence of initial points/data of a differential equation which is C^1 and Lipschitz in phase variable, the proof relied on inequality called fundamental estimate and Picard-Lindelöf theorem, it also introduced something informally called butterfly region in phase space and why because of conditions of Picard-Lindelöf the solution stayed in that region, I think the condition of Lipschitz is pretty important here because nature of butterfly region coming together with Picard-Lindelöf conditions.

(14/4/19) Today I learned how under sufficiently nice conditions the solutions of differential equations are C^1 function of initial point. I also learned about local phase flows in autonomous and non-autonomous differential equations.

(15/4/19) Today I learned how constant level sets of n-1 integral curves in an n dimensional vector field gives solution of vector field up-to parametrization. I hope to study transversality in more detail to understand this.

(16/4/19) Today I learned why solution of IVP with locally Lispchitz in phase vector field must exit any compact set K in extended phase space/domain of vector field (non-autonomous case here). The solution was sweetly based on property that for IVP's with initial phase point in a given compact set the maximal interval of existence say (ω_-, ω_+) will have minimum length, say 2b only decided by that compact set K and the vector field v, so if you go near the endpoints of maximal interval of existence (within distance of b) the corresponding extended phase point must be outside the compact set otherwise you will end up extending maximal interval of existence.

(17/4/19) Today I did some topology, nothing new.

(18/4/19) Today I got exposed to group theory in physics, quantum mechanics to be specific, I got some vague ideas how representation theory will be used in angular momentum in quantum mechanics

(19/4/19) Today I relearned how infinitesimal space translation are generated by momentum and how angular momentum generates infinitesimal rotation. The theory of angular momentum in quantum mechanics started in the setup of rotationally invariant systems so that angular momentum is conserved which implies it commutes with Hamiltonian. We constructed an operator $L^2 = L_x^2 + L_y^2 + L_z^2$, together with commutation relations $[L_i, L_j] = i\hbar\epsilon_{ijk}L_k$ to obtain $[L^2, L_i] = 0$. So now we go on to find a common eigenbasis of L^2 and L_z , turns out this approach is similar to that of creation and annihilation operators of Harmonic Oscillator, the operators $L_{+} = L_{x} + iL_{y}$ and $L_{-} = L_{x} - iL_{y}$ do the job here, they increase/decrease eigenvalues of L_z without affecting eigenvalues of L^2 . Solving for that it happened that if we just assume the commutation relation of L (i.e. $L \times L = i\hbar L$) we will get a more general eigenvalues which includes half integer angular momentum as well (in units of \hbar). Well it is not possible for the physical angular momentum we started with $(L_z = XP_y - YP_x)$ but there comes an explanation that we solved the general problem of finding generators of infinitesimal rotations of vector fields not just scalar fields so in general total angular momentum is given by J = L + S where S denotes spin operator which operates on component of vector fields and our original orbital angular momentum L operates on coordinates, so spin rotates the vector at each point and orbital angular momentum rotates the coordinates system without affecting vectors at each point and they commute.

(20/4/19) Today I finally learned what Clebsch-Gordan coefficients mean, pure moment of joy. Wikipedia article on it helped a lot

(21/4/19-27/4/19) Exam week.

June 2019

(7/6/19) Today I learned that connection forms are skew-symmetric with respect to an orthonormal frame and Riemannian connection and how structural equation proves that curvature forms are also skew symmetric with same conditions. The second structural equation in metric form is

$$\Omega = d\omega + \omega \wedge \omega.$$

August 2019

(10/8/19) Today I (re)learned how to think of Hilbert Nullstellensatz as theorem of the kind 'The only obstructions are the obvious obstructions', this kind of theorems may be more prevalent in mathematics than I used to think and will look for them in future since it is powerful and ingenious way to think. I also learned about L^2 and L^{∞} estimates of linear first-order PDE and definition of Weak solutions of linear first-order PDE.

(16/8/19) Today I learned of an idea of tangent space with minimal structure on the given space, the setting is in a locally ringed space. Given $x \in X$ let m_x be the maximal ideal of the local ring R_x at x, then R_x/m_x is a field and the tangent space is defined to be dual of the vector space m_x/m_x^2 over field R_x/m_x . The motivation to do so is explained in the Wikipedia article on locally ringed space. In a way it also displays how Algebraic Geometry will need much more powerful tools to study than differential geometry since you almost need to throw away analysis.

(17/8/19) Today I (re)learned the definition of gradient of a function in Riemannian manifold. The definition I got to know is

$$\operatorname{grad} f = \tilde{df}$$

where $\tilde{}$ is for correspondence between T_pM and T_p^*M via the given inner product on T_pM and other way to see it is a vector such that

$$\langle \operatorname{grad} f, X_p \rangle = X_p f = (df)(X_p)$$

(18/8/19) Today I learned about sheaf and presheaf (old definition) from the books Frank Warner - Foundations of Differentiable Manifold and Lie Groups, his definition of complete presheaf is the current definition of sheaf and his definition of sheaf is the current definition of étalé space(?). I learned how from a sheaf you can get a presheaf and from a presheaf you can construct a sheaf with stalks and introducing a topology on disjoint union of stalks. Sheaves still look like vector bundles to me or having seen vector bundles before sheaf it confuses me to some bit.

(19/8/19) Today I learned about tensor product of sheaves and about fine sheaves. I got some idea how paracompactness will be needed for partitions of unity to work.

(26/8/19) Today I learned about method of characteristics in quasi-linear PDE's. One has complete local description of existence/non-existence of solutions in terms of transversality conditions.

September 2019

(2/9/19) Today I learned about Riesz Representation theorem and how space of compactly supported continuous functions on **R** is not a Banach space. A generic example comes from sequence approximating a function tending to zero for large values say $f = e^{-|x|}$ via compactly supported functions such that the compact supports are unbounded.

(20/9/19) Today I learned about maximum principle of Laplace equation solution and their Mean Value Property. There are two maximum principle one strong and other weak. The weak one requires bounded domain in hypothesis while the strong one requires connected domain. The book remarked that Weak maximum principle can be extended to general elliptic operators.

October 2019

(10/10/19) Today I learned something about non-vanishing holomorphic function on simply connected set. The theorem is as follows:

Let U be simply connected and open and $f:U\to \mathbf{C}$ is holomorphic and nowhere vanishing. Then there exists a holomorphic function $h:U\to \mathbf{C}$ such that

$$f(z) = \exp h(z)$$

for all $z \in U$.

This theorem allows us to define logarithm of a function on simply connected domains. I also learned a proof of Riemann mapping theorem, idea of getting a desired function was solving an extremal problem with derivative of function. I got to know that this idea will be used in other problems as well.

(14/10/19) Today I learned one important result in commutative algebra: (Zariski lemma) Let k be a field, R a finitely generated k-algebra. Suppose R is a field. Then R is algebraic over k.

(20/10/19) Today I learned about elementary Hilbert space theory. The approach of Rudin to prove Parseval identity and completeness of trigonometric system is seamless and intuitive.

November 2019

(5/11/19) Recently I saw two very beautiful applications of Zorn's lemma both very similar in approach, almost the same; one in Analysis and one in Field Theory. First one was a proof of Hahn-Banach Theorem and second one was result that field homomorphisms to algebraically closed fields can be extended to algebraic extensions of domain.

(12/11/19) Today I learned about inverse limits and for the first time saw a use of snake lemma. It was from book Atiyah-Macdonald book chapter 11 - Completions.

(13/11/19) Today I learned more about completions. I have intuition that inverse limits are algebraic analogue of successive approximations like a Taylor series expansion. Take for example the filtration

$$\mathbf{Z}\supset p\mathbf{Z}\supset p^2\mathbf{Z}\supset \dots$$

Now a coherent sequence in this is like a number with elements of the sequence representing approximations of it modulo $p^n \mathbf{Z}$.

December 2019

(8/12/19) Today I learned something about lifting of covering maps. If $p: Y \to X$ is covering map and Z is a simply connected space with a continuous map $f: Z \to X$ then for ANY y_0 in the fibre $p^{-1}(f(z_0))$ there exits a unique lift $\tilde{f}: Z \to Y$ such that $\tilde{f}(z_0) = y_0$.

The construction of the map is by lifts of f on paths and simply connectedness ensures that that is independent of path.

(11/12/19) Today I learned about sheaves and topological space associated to a presheaf (sheafication). An interesting example of sheaves came up - Suppose X is a Riemann surface. For $U \subset X$ open, let

$$\mathcal{F}(U) = \mathcal{O}^*(\mathcal{U}) / \exp \mathcal{O}(\mathcal{U})$$

Then \mathcal{F} is a presheaf but does not a sheaf because it does not satisfy uniqueness axiom. The idea is not split a non simply connected set into simply connected components.

I also learned about analytic continuation of function germs along a curve, it is equivalent to a continuous lift in the $|\mathcal{O}|$ space between the two function germs.

(16/12/19) Today I learned about Differential forms in a Riemann surface. The definition of cotangent space at a point is in terms of stalks. For $a \in X$ let \mathcal{E}_a denote the stalk of \mathbb{C} -valued C^{∞} functions and m_a denote the vector space of functions vanishing at a, m_a^2 denote the vector space of functions vanishing in first order at a. Define $T_a^{(1)} = m_a/m_a^2$ and differential operator $d: \mathcal{E}_a \to T_a^{(1)}$ be the map $f \mapsto (f - f(a)) \mod m_a^2$. Then $T_a^{(1)}$ is a two dimensional \mathbb{C} vector space with $d_a x, d_a y$ as a basis where z = x + iy is a coordinate chart around a.

(17/12/19) Today I learned how étalé spaces of sheaves are used as covering space. First it was for analytic continuation and today for primitive, I reckon it will be used many more times like this. Apart from that there is a neat theory of integration of closed differential forms along continuous paths (one that matches with definition along a piecewise C^1 path); For any closed differential form $\omega \in \mathcal{E}^{(1)}(X)$ there exists a covering map $p: \tilde{X} \to X$ with \tilde{X} connected and a primitive $F \in \mathcal{E}(\tilde{X})$ of the differential form $p^*\omega$. Now

$$\int_{c} \omega = \int_{\hat{c}} p^* \omega = F(\hat{c}(1)) - F(\hat{c}(0))$$

where \hat{c} is a lift of path c. Further one can prove that integration is invariant upto homotopy of paths, this give a group homomorphism $\pi(x) \to \mathbb{C}$ given by $u \mapsto \int_u \omega$ which is called *period homomorphism* associated to the closed differential form ω .

(18/12/19) Today I learned about Čech Cohomology. The construction is fairly abstract and unintuitive. I am still struggling with basic proofs.

(20/12/19) Today I learned more about Čech cohomology. It is defined as a direct limit over the set(not actually a set as I learned from another note) of open covers of the topological space. It is beautifully proven that for any Riemann surface X, $H^1(X, \mathcal{E}) = 0$ where \mathcal{E} denote sheaf of \mathbb{C} -valued C^{∞} functions and with the help of this one can prove $H^1(X,\mathbb{C}) = H^1(X,\mathbb{Z}) = 0$ for simply connected Riemann surface X. This fact along with Leray's theorem is used to calculate cohomologies of some simple Riemann surfaces which can be decomposed into union of simply connected subsets. Moreover for compact Riemann surface X, $H^1(X,\mathbb{C})$ is finite-dimensional.

(21/12/19) Today I learned about Dolbeault's lemma. It states that for $X = \{z \in \mathbb{C} : |z| < R\}, 0 < R \le \infty$, and $g \in \mathcal{E}(X)$, there exists $f \in \mathcal{E}(X)$ such that

$$\frac{\partial f}{\partial \bar{z}} = g$$

The trick is to solve it with compactly supported g first and then extend it in general case using exhaustion and partitions of unity. The compactly supported part is done ingeniously using the integration

$$f(\zeta) = \frac{1}{2\pi i} \iint_{\mathbb{C}} \frac{g(z)}{z - \zeta} \, dz \wedge d\bar{z}$$

and converting it back and forth between polar coordinates. One corollary that follows is there also exists $h \in \mathcal{E}(X)$ such that $\Delta h = g$.

With the help of this we can prove that $H^1(X, \mathcal{O}) = 0$ and consequently $H^1(\mathbb{P}^1, \mathcal{O}) = 0$.

(26/12/19) Today I learned about finite dimensionality of $H^1(X, \mathcal{O})$ for compact Riemann surface X. The dimension $g = \dim H^1(X, \mathcal{O})$ is called genus of the Riemann surface.

(27/12/19) Today I learned about sheaf homomorphisms. A sheaf homomorphism $\alpha: \mathcal{F} \to \mathcal{G}$ is a family of group homomorphisms

$$\alpha_U: \mathcal{F}(U) \to \mathcal{G}(U), \ U \text{ open in } X$$

which are compatible with restriction maps. The exactness of sheaf maps is decided by exactness at every stalk. An easy consequence of sheaf axioms is that if $0 \to \mathcal{F} \xrightarrow{\alpha} \mathcal{G} \xrightarrow{\beta} \mathcal{H} \to 0$ is exact then for every open set U, the sequence

$$0 \to \mathcal{F}(U) \xrightarrow{\alpha_U} \mathcal{G}(U) \xrightarrow{\beta_U} \mathcal{H}(U)$$

is exact. Also sheaf cohomology measures how much exact is this sequence on the right side for U = X. To be precise, we have an exact sequence of cohomology

$$0 \to H^0(X, \mathcal{F}) \xrightarrow{\alpha_0} H^0(X, \mathcal{G}) \xrightarrow{\beta_0} H^0(X, \mathcal{H}) \xrightarrow{\delta} H^1(X, \mathcal{F}) \xrightarrow{\alpha_1} H^1(X, \mathcal{G}) \xrightarrow{\beta_1} H^1(X, \mathcal{H})$$

and we know $H^0(X,\mathcal{G}) = \mathcal{G}(X)$. One interesting consequence of this is that one can view DeRham cohomology as sheaf cohomology $H^1(X,\mathbb{R})$ from the exact sequence $0 \to \mathbb{R} \to \mathcal{E} \xrightarrow{d} \mathcal{L} \to 0$ where \mathcal{L} denotes sheaf of closed 1-forms.

(28/12/10) Today I learned about Riemann-Roch theorem for compact Riemann surfaces. The result quickly follows from a clever exact sequence

$$0 \to \mathcal{O}_D \to \mathcal{O}_{D+P} \xrightarrow{\beta} \mathbb{C}_P \to 0$$

where \mathbb{C}_P is the skyscraper sheaf at P, P also denotes a singular divisor having value 1 at point $P \in X$ and β is the map picking coefficient of pole at P. So we get

$$0 \to H^0(X, \mathcal{O}_D) \to H^0(X, \mathcal{O}_{D+P}) \to \mathbb{C} \to H^1(X, \mathcal{O}_D) \to H^1(X, \mathcal{O}_{D+P}) \to 0$$

So two cases are possible depending on the surjectivity of third map -

- 1. $\dim H^0(X, \mathcal{O}_D) = \dim H^0(X, \mathcal{O}_{D+P})$ and $\dim H^1(X, \mathcal{O}_D) = 1 + \dim H^1(X, \mathcal{O}_{D+P})$ or
- 2. dim $H^0(X, \mathcal{O}_D) = \dim H^0(X, \mathcal{O}_{D+P}) 1$ and dim $H^1(X, \mathcal{O}_D) = \dim H^1(X, \mathcal{O}_{D+P})$ either way we have

$$\dim H^0(X, \mathcal{O}_D) - \dim H^1(X, \mathcal{O}_D) = \dim H^0(X, \mathcal{O}_{D+P}) - \dim H^1(X, \mathcal{O}_{D+P}) - 1$$

implying

$$\dim H^0(X, \mathcal{O}_D) - \dim H^1(X, \mathcal{O}_D) - \deg D = \dim H^0(X, \mathcal{O}_{D+P}) - \dim H^1(X, \mathcal{O}_{D+P}) - \deg(D+P)$$

So this quantity is invariant of divisor and for $D=0$ it is $1-q$.

January 2020

(2/1/20) Today I learned about Serre's duality theorem and Hodge star operator. Serre's duality result is hinged (for now) on a bilinear map

$$H^0(X,\Omega_{-D}) \times H^1(X,\mathcal{O}_D) \to H^0(X,\Omega) \xrightarrow{Res} \mathbb{C}$$

which induces a map

$$i_D: H^0(X, \Omega_{-D}) \to H^1(X, \mathcal{O}_D)^*$$

Serre's duality asserts that this map is an isomorphism. So we get dim $H^0(X, \Omega_{-D}) = \dim H^1(X, \mathcal{O}_D)$ and for D = 0, $g = \dim H^0(X, \Omega) = \dim H^1(X, \mathcal{O})$ thus genus of a compact Riemann surface X is also the number of linearly independednt meromorphic 1-forms on it. Let $K = (\omega)$ be a canonical divisor, then we have an isomorphism of sheaves $\mathcal{O}_{D+K} \cong \Omega_D$ $(f \mapsto f \cdot \omega)$, this fact along with Serre's duality has many many applications.

Hodge star operator introduces an inner product on $\mathcal{E}^{(1)}(X)$ in which the subspaces $d'\mathcal{E}(X), d''\mathcal{E}(X), \Omega(X)$ and $\overline{\Omega}(X)$ are pairwise orthogonal which has some interesting applications.

(21/1/20) Today I learned about prime spectrum and the how elements in it are functions on it. The traditional intuition comes from polynomial ring $A=k[x_1,...,x_n]$ as elements of A (polynomials) are function on \mathbb{A}^n_k , for an arbitrary ring, in prime spectrum, the difference comes from the fact that points of \mathbb{A}^n_k correspond to maximal ideals of A but in Spec A we also have prime ideals of A. So a function on Spec A is an element $f \in A$ and its value in a point [(p)] (a prime ideal of A) is given by $\frac{f \mod (p)}{1}$ in $\operatorname{Frac}(A/p)$.

(22/1/20) Today I learned about Smith Normal form of matrix with entries in a PID. The proof was existence was beautiful and consisted of small yet very powerful ideas. In a PID, we have some sort of length function on its elements, $l(a) = l(p_1^{n_1}...p_k^{n_k}) = \sum n_i$. With respect to this length function we create an algorithm so that we get a least length element in the top left corner of the matrix by changing basis both sides (equivalently multiplying left and right by elementary matrices for row and column operations). Using this can classify finitely generated modules over a PID completely, let M be a finitely generated module over

PID R, then there exist unique $d_1, ..., d_k$ with $d_i|d_{i+1}$ and an integer l called rank of M such that

$$M \cong \frac{R}{d_1 R} \oplus \cdots \oplus \frac{R}{d_k R} \oplus R^l.$$

(23/1/20) Today I learned more about schemes. To extend the analogy between variety and schemes one even defines scheme-theoretically $\mathbb{A}^n_k = \operatorname{Spec} k[x_1, ..., x_n]$. Moreover similar to ideal of polynomials vanishing on a set, we have functions (elements of ring) vanishing on a subet of Spec - For a set $S \subset \operatorname{Spec} A$, define the ideal $I(S) = \bigcap_{p \in S} p$, then just like in varieties $\overline{S} = V(I(S))$ and $I(V(J)) = \sqrt{J}$ (this result was non-trivial in varieties and is true there because intersection of maximal and prime ideals is same, which is Hilbert Nullstellensatz). So, natrually we have a bijection between closed sets of Spec A and radical ideals of A and a bijection between irreducible closed subsets Spec A and prime ideals of A, hence a bijection between points of Spec A and irreducible closed sets of Spec A.

(26/1/20) Today I learned about structure sheaf on spectrum of a ring from Ravi Vakil's The Rising Sea. When elements of ring A are considered as functions on Spec A, the sheaf $\mathcal{O}_{\operatorname{Spec} A}$ on D(f) is defined as localization with the multiplicative set not vanishing on D(f) so the set $\{g \in A : D(f) \subset D(g)\}$ which is $\{1, f, ...\}$, hence $\mathcal{O}_{\operatorname{Spec} A}(D(f)) = A_f$. He proves this satisfies identity and gluing axioms on distinguished open sets and so with sheafification we can extend this sheaf to collection of all open sets of Spec A.

(28/1/20) Today I learned about gluing of sheaves, given an open covering $\{U_i\}_{i\in I}$ of topological space X with corresponding collection of sheaves $\{\mathcal{F}_i\}_{i\in I}$ along with gluing data of isomorphisms $\{\varphi_{ij}:\mathcal{F}_i|_{U_i\cap U_j}\to\mathcal{F}_j|_{U_i\cap U_j}\}$ with $\varphi_{jk}\circ\varphi_{ij}=\varphi_{ik}$ on $\mathcal{F}_i|_{U_i\cap U_j\cap U_k}$ then there exists a sheaf \mathcal{F} on X with isomorphisms $\{\varphi_i:\mathcal{F}|_{U_i}\to\mathcal{F}_i\}$ such that $\varphi_j=\varphi_{ij}\circ\varphi_i$ on $\mathcal{F}|_{U_i\cap U_j}$. One solution to construct such sheaf is to think that we are gluing sheaves from definition. For any open set Y our definition of elements of $\mathcal{F}(Y)$ will be a collection of sheaf elements $\{s_i\in\mathcal{F}_i(U_i\cap Y)\}$ such that $\varphi_{ij}(s_i|_{U_i\cap U_j\cap Y})=(s_j|_{U_i\cap U_j\cap Y})$. Using this one defines gluing of schemes.

(29/1/20) Today I learned some applications of structure theorem in Linear Algebra. For a field F, given a finite dimensional vector space over F and a linear operator $T:V\to V$, V can be considered as a finitely generated R=F[X] module with $X\cdot v=T(v)$. Applying structure theorem we get

$$V \cong \frac{F[X]}{(d_1(X))} \oplus \cdots \oplus \frac{F[X]}{(d_k(X))}$$

From here using suitable bases from right hand side we can get matrix of T in Rational canonical form and Jordan canonical form.

February 2020

(4/2/20) More about gluing of sheaves - The construction of a global sheaf does not require cocycle condition, rather we require it for restriction isomorphism $\{\varphi_i : \mathcal{F}|_{U_i} \to \mathcal{F}_i\}$.

(15/2/20) Today I learned about equivalence of categories. The word naturally isomorphic is attached to the notion of natural transformation of functor and should be seen in the light of categories.

(17/2/20) Today I learned about algebraic closure of a field. Artin's proof of construction of algebraic closure was delightful to read. The construction was step wise and the genius was getting a field extension in which every polynomial has a root. To do this he labeled all the polynomial and created a polynomial ring with those variables. Then he created a maximal ideal out of polynomials in those variables and by quotient it we get a field in which every polynomial has a root, namely the variable labeled by it.

(23/2/20) Today I learned definition of homolorphic function in several complex variables (SCV).

(26/2/20) Today I learned about triangulations of topological surface. A topological surface X is called a polyhedron if there exists a simplicial complex K and a homeomorphism $h: |K| \to X$, where |K| is the geometric realization of the simplicial complex. Let Δ^n denotes standard n-simplex, then its skeleton, say K, is homotopic to S^{n-1} , so S^{n-1} is a polyhedron. With the help of this fact and simiplicial approximation we can prove that for m < n, any continuous map $f: S^m \to S^n$ is null homotopic, proving that the homotopy groups $\pi_m(S^n) = 0$ for m < n.

March 2020

(1/3/20) Today I learned a proof of homotopy axiom of singular homology. The proof in Rotman's An Introduction to Algebraic Topology involved prism maps construction by induction to get chain homotopy beteen chain complexes $\{S_{\bullet}(X)\}$ and $\{S_{\bullet}(X \times I)\}$

(22/3/20) Today I learned about CW complexes from Hatcher's *Algebraic Topology*. The construction is inductively based on attaching cells.

(23/3/20) Today I learned about excision axiom of homology(singular). Many definitions and proofs in homology are broken into two parts, first doing it on a simplex or convex space and then extending it to general spaces via simplicial maps. A good example of this technique is proof of homotopy axiom of homology.

A major tool used in proof of excision is barycentric division of simplicial complexes. Barycentric division induces identity in the homology map and is useful in separating a simplex into parts which belong to open sets of the two set open cover.

Excision has many wonderful consequences and it makes some homology groups computable. One result is Mayer-Vietoris sequence in homology which can be used to compute homology groups of space which have good covers. S^n is an example and for $n \geq 2$ because of its non-trivial homology group, we get an example of a simply connected space which is not contractible.

(24/3/20) Today I learned about degree of a map $f: S^n \to S^n$. As $H_n(S^n) = \mathbb{Z}$, the

group morphism $H_n(f): H_n(S^n) \to H_n(S^n)$ is determined by an integer (as any group homomorphism $g: \mathbb{Z} \to \mathbb{Z}$ is multiplication by g(1)) which is defined to the degree of f. One can prove that the antipodal map $a: S^n \to S^n$ has degree $(-1)^{n+1}$. A consequence of this theorem is the Hairy ball theorem about S^{2n} .

April 2020

(1/4/20) Today I learned about relation between simplicial and singular homology. If K is a finite simplicial complex, |K| it's geometric realization then we have an inclusion map $j^K: C_{\bullet}(K):\to S_{\bullet}(|K|)$ which induces isomorphism in the reduced/augmented homology. Since singular homology is independent of the simplicial structure of the complex, it tells a great deal about the invariants of polyhedrons. Like Euler-Poincare characteristic of a polyhedron is independent of the triangulation.

(4/4/20) Today I learned about a description of fundamental group of polyhedra in terms of generators and relations. We can prove the existence of a maximal tree for any simplicial complex which occupies every vertex and given this the group generated by all edges with quotient by normal group generated by edges of the maximal tree and obvious the homotopy equivalences gives us fundamental group of the simplicial complex. This description can be very efficient for computation.

An unexpected corollary is the result that fundamental group of a connected 1-complex is always a free group. If a 1-complex K contains m edges and n vertices then its fundamental group is free group of rank m - (n - 1).

- (5/4/20) Today I learned about Seifert-van Kampen Theorem and the concept of pushout.
- (6/4/20) Today I learned about attaching cells and attaching maps.
- (11/4/20) Today I learned about critical points, their index and nullity and the lemma of Morse characterizing any smooth function near a non-singular critical point
 - (12/4/20) Today I learned about some properties of chain complexes.
- (16/4/20) Today I learned a different proof of the fundamental theorem of algebra from Milnor's *Topology*. It uses the fact that for a smooth map $f: M \to N$ between same dimensional manifolds with M compact, $\#f^{-1}(y)$ is a locally constant function for regular values y.
- (19/4/20) Today I learned M. Hirsch's proof of Brouwer fixed point theorem. Hirsch's proof brilliantly used classification of 1 dimensional compact manifolds and Weierstrass approximation theorem to extend it from smooth to continuous case. The idea was simple yet so powerful. I also learned a proof of Sard's theorem. The theorem looks like the beginning of a fruitful research on Differential Topology.

Sard's theorem used Fubini's theorem and very surprisingly induction. It involved three steps dividing the image space into pieces on which induction is done. The third step is also individually important, it proves that if $C_k = \{x : \text{all partial derivatives of } f \leq x \}$

k vanishes at x} then $f(C_k)$ has measure zero for sufficiently large k ($k > \frac{n}{p} - 1$ where $f: U \to \mathbb{R}^p$ and U is an open subset of \mathbb{R}^n). The key intuition is that using taylor expansion on a compact cube I, we can control the difference |f(x+h) - f(x)| if $x \in C_k \cap I$, $x+h \in I$ leading us to the result.

(25/4/20) Today I learned about mod 2 degree of a map. Given a smooth map $f:M\to N$ where M is compact manifold without boundary and of same dimension as N and a regular value $y\in N$ it will turn out that $f^{-1}(y)$ is a finite set and and cardinality mod 2 of the set is invariant of the regular value. The proof involved an ingenious homogeneity lemma which states that given two arbitrary interior points in a manifold, there exists a diffeomorphism sending one point to other which is smoothly isotopic to identity. The diffeomorphism can be constructed locally from the existence of 1-parameter group of transformations of a suitable vector field. This lemma is more important than the theorem.

(27/4/20) Today I learned about Brouwer degree of a map. Let $f: M \to N$ be a smooth map between oriented manifolds of dimension n without boundary where M is compact. Then for a regular value $y \in N$, the degree is defined to be

$$\deg(f;y) = \sum_{x \in f^{-1}(y)} \operatorname{sign} df_x$$

where sign df_x is ± 1 depending on whether df_x preserve or reverse the orientation. Again deg is a locally constant function of regular value y and is independent of the regular value. The proof is similar to that of mod 2 degree.

(28/4/20) Today I learned about index of a vector field at an isolated zero. Brouwer degree can be used to define degree of a vector field near an isolated zero normalizing it and restricting it to a small sphere near the zero. To prove it is well defined, we need to prove it is invariant under diffeomorphism and the proof involved a useful lemma which states that any orientation preserving diffeomorphism $f: \mathbb{R}^n \to \mathbb{R}^n$ is smoothly isotopic to identity.

May 2020

(4/5/20) Today I wrote a proof of fact that B_n is manifold with boundary as it was asked on stackexchange. Since the post was deleted, I am dumping my proof here because my precious Latexed effort should not be wasted.

Using stereographic projection from the north pole N = (0, ..., 1), we have a function $\psi: S^n \setminus N \to \{x \in \mathbb{R}^{n+1} : x_{n+1} = 0\}$ defined by

$$\psi(x_1, ..., x_{n+1}) = \left(\frac{x_1}{1 - x_{n+1}}, ..., \frac{x_n}{1 - x_{n+1}}, 0\right)$$

Now for an arbitrary $y = (y_1, ..., y_{n+1}) \in B_n \setminus N$, join a straight line between and N and y and suppose it intersect with S^n at $x = (x_1, ..., x_{n+1})$. Then $y = (1 - \lambda)N + \lambda x$ for some $\lambda \in (0, 1]$ which implies relations

$$y_1 = \lambda x_1, \quad \dots \quad , y_n = \lambda x_n, \quad y_{n+1} = 1 - \lambda (1 - x_{n+1})$$

Define $\phi: B_{n+1} \setminus N \to \mathbb{R}^{n+1}$ by

$$\phi(y) = (1 - \lambda)N + \lambda\psi(x)$$

solving those relations and using ||x|| = 1, we get

$$\phi(y) = \left(\frac{\lambda y_1}{1 - y_{n+1}}, ..., \frac{\lambda y_n}{1 - y_{n+1}}, 1 - \lambda\right)$$

with
$$\lambda = \frac{||y||^2 + 1 - 2y_{n+1}}{2(1 - y_{n+1})}$$

So ψ is a homeomorphism with range in $\mathbb{H}^n = \{x \in \mathbb{R}^{n+1} : x_{n+1} \geq 0\}$

Unsuprisingly there is an outline for cleaner proof in Lee's book *Introduction to smooth manifolds* Chapter 1, Problem 1-11, page number 31.

(7/5/20) Today I learned about cyclotomic polynomials over \mathbb{Q} . A primitive nth root of 1 in F is an element of order n in F^{\times} . The polynomial with primitive nth roots is the nth cyclotomic polynomial. Cyclotomic polynomials are irreducible and the proof by Dedekind involves a brilliant technique. Proving irreducibility is equivalent to proving the map $\operatorname{Gal}([\zeta]/F) \to (\mathbb{Z}/n\mathbb{Z})^{\times}$ is onto which is equivalent to proving that ζ^i is also a primitive nth root whenever $\gcd(i,n)=1$. As every such i can be written as product of primes relatively prime to n, we can reduce it to proving that ζ^p is primitive. Assume not and reduce the equation to mod p, using frobenius automorphism we can derive a contradiction.

(9/5/20) Today I learned a property of the homology of the product $X \times S^n$. Using Mayer-Vietoris sequence and induction there is a proof that $H_q(X \times S^n, X \times p_0) = H_{q-n}(X)$. It uses the same techinque which is used to calculate homology groups of S^n ; breaking $S^n = U \cup V$ and identifying $S^{n-1} \subset U \cap V$ as strong deformation retract. A consequence of this fact is $H_q(X \times S^n) = H_q(X) \oplus H_{q-n}(X)$.

A question I thought of today is how to give a simplicial structure to cartesian product of two simplicial complexes. Given two simplicial complexes K, L, is there a way to form a simplicial complex $K \times L$ such that $|K \times L|$ is homeomorphic to $|K| \times |L|$?

(10/5/20) Today I learned a proof of the fact that the closed *n*-cell with boundary points identified is homeomorphic to *n*-sphere from Lee's *Introduction to Topological Manifolds*. The map $q: \mathbb{B}^n \to S^n$ is

$$q(x) = (2\sqrt{1 - |x|^2}x, 2|x|^2 - 1)$$

which after quotient gives homeomorphism $\bar{q}: \mathbb{B}^n/S^{n-1} \to S^n$.

(13/5/20) Today I learned about Lüroth's theorem. Let F be field and X transcendental over F, let E be a subfield of F(X). Lüroth's theorem states that $\exists u \in E$ such that E = F(u). Define degree of a rational function to be the maximum of the degree of numerator and denominator. Then using Gauss's lemma it can be proved that $[F(X):F(u)] = \deg(u)$ for any non-constant rational function u.

So to prove Lüroth's theorem we need to find an element $u \in E$ such that $[F(X) : E] = [F(X) : F(u)] = \deg(u)$ equivalently to find $u \in E$ which has minimum degree such that the bound $[F(X) : E] \leq [F(X) : F(u)]$ is achieved. The proof is a creative juggle of polynomials in two variables and Gauss's lemma.

(14/5/20) Today I learned about Jacobi's formula on derivative of determinant of a matrix. Suppose $A(t) \in M_n(\mathbb{R})$ with entries $a_{ij}(t)$ which are differentiable function of t. Then

$$\frac{d}{dt}\det(A(t)) = \operatorname{tr}\left(\operatorname{adj}(A(t))\frac{d}{dt}(A(t))\right)$$

The proof is based on expanding det(A(t)) in a row with adjoint factors and using formula of trace for product of matrices.

This was used for deriving a formula for Laplacian of a C^2 function f on a smooth Riemannian manifold (M,g). The formula is

$$\Delta f = \frac{1}{\sqrt{g}} \sum_{j,k} \partial_j (g^{jk} \sqrt{g} \, \partial_k f)$$

I am learning spectra of Laplacian from the text *Eigenvalues in Riemannian Geometry* by Issac Chavel.

(17/5/20) Today I somewhat understood how the proof of homotopy axiom works for singular homology. From Akhil Mathew's blogpost I got a vague idea of the method of acyclic models. In the singular homology case the simplexes Δ^n serves as model objects in the category of topological spaces because of the way singular homology is defined. The proof the homotopy axiom is broken into two parts - first proving it for simplexes (models) and then extending it by using some natural transformations. This approached is generalized in acyclic model theorem.

(26/5/20) Today I learned something very interesting in Riemannian geometry. Let M be a smooth manifold, then the scalar curvature functional from the set of all riemannian metrics (normalised to unital volume) to reals given by $g \mapsto \int_M R(g) dV_g$ recovers Einstein equations through Euler-Lagrange equations. This was discovered by Hilbert. I do not have much knowledge in the subject but I will look into more.

June 2020

(4/6/20) Today I learned about various forms of Hahn-Banach Theorem. One is the general extension of linear functional on a subspace to the whole space and the others are geometric separation of convex sets by hyperplanes.

(7/6/20) As suspected I have had wrong definition of inner product of tensors on Riemannian manifold in my mind all along. The correct definition is there is John Lee's book. Let $h = h_{ij}dx^i \otimes dx^j$ and $k = k_{ij}dx^i \otimes dx^j$ in local coordinates, then the inner product is defined be

$$(h|k) = g(h,s) = h_{mn}k_{st} g(dx^m \otimes dx^n, dx^s \otimes dx^t) = g(dx^m, dx^s)g(dx^n, dx^t)h_{mn}k_{st} = g^{ms}g^{nt}h_{mn}k_{st}$$

(16/6/20) Today I learned equivalence of three properties in a connected, locally Euclidean, Hausdorff topological space X. The properties are

- 1. X is second countable.
- 2. X is paracompact.
- 3. X admits a compact exhaustion.

I found the proof here. The proof from (3) to (2) is quite nice. The idea is to think of X as union of rings and in between the rings find the refinement of a given open cover. This is possible because the rings are compact.

(18/6/20) I learned a really neat technique today which is used quite often in differential topology. When you want to prove a set is not-empty, a great way to do this is to prove that it's complement has measure zero. With the help of Sard's theorem this method was used in various parts of the weak Whitney embedding theorem.

In the weak embedding theorem there is a lemma about reducing the dimension of the euclidean space the manifold embeds in. The inequality N > 2n was required to obtain an injective immersion, n part was needed for injectiveness, n part was needed for immersion and one extra dimension for the map to be critical so we could use Sard's theorem.

(20/6/20) Today I learned the proof of weak Whitney Embedding theorem and Whitney approximation theorem for functions. The proof of weak Whitney embedding theorem was divided into 2 parts -

- 1. Construct an embedding into sufficiently large dimension euclidean space. This is easy in the case of compact manifold but non-compact manifold requires some work. To extend into non-compact case the idea is to use the result for compact case and to use the property that injective immersion + proper map = embedding.
- 2. If the manifold admits a smooth embedding into \mathbb{R}^N , for some N, then it admits a proper smooth embedding into \mathbb{R}^{2n+1} , where n is the dimension of the manifold.

July 2020

(3/7/20) Today I learned about weak topology on Banach spaces. One really strange fact about weak topology is that the closure of unit sphere in weak topology is the whole closed unit ball! Like the weak topology does not repect norms at all. But still there are few limiting properties on the behavior of weak convergence with respect to norm. For example if $x_n \to x$ weakly in $\sigma(E, E^*)$, then $(||x_n||)$ is bounded and $||x|| \le \liminf ||x_n||$.

(4/7/20) Today I learned about Banach-Alaoglu-Bourbaki theorem on the compactness of closed unit ball in weak* topology. Surprisingly the proof was easy to understand but hard to come up with. Not to mention how unexpected the result was.

One trick to prove compactness was to embed the dual space E^* into \mathbb{R}^E (the set of all function from E to \mathbb{R}) and prove the theorem there. It is intriguing how easy the proof

became after this. Definitely this trick is going to come up again and again when dealing with topological properties of large topological vector spaces.

The proof also relied on Tychonoff theorem.

(5/7/20) Today I learned about Kakutani theorem on criteria for Banach spaces to be reflexive. It says that a Banach spaces E is reflexive if and only if the unit ball $B_E = \{x \in E; ||x|| \le 1\}$ is compact in the weak topology $\sigma(E, E^*)$. One part of the proof is easy by Banach-Alaoglu-Bourbaki theorem when E is reflexive. The other part is prove by a lemma by Goldstine stating that $J(B_E)$ is dense in $B_{E^{**}}$ in $\sigma(E^{**}, E^*)$ topology.

(9/7/20) Gradually I am understanding the importance of weak topology after doing some exercises. The main theorem has to be Banach-Alaoglu-Bourbaki theorem for duals and Kakutani theorem for reflexive Banach spaces. Having bounded balls compact is a great thing but the trade off is that you lose metric and can't use sequential compactness criteria (Important: compactness does not apply sequential compactness for arbitrary topological spaces).

(12/07/20) Today I learned about convolution in L^p spaces. Convolution of $f \in L^1$ and $g \in L^p$ yields $f \star g \in L^p$ which satisfies the inequality

$$||f \star g||_p \le ||f||_1 ||g||_p$$

For separable spaces, support of a function can be defined in L^p sense which doesn't depend on the representative (seperability seemed important here).

Morever in case of \mathbb{R}^n we have an important result about smoothing by convolutions. If $f \in C_c^k(\mathbb{R}^n)$ ($k \ge 1$) and $g \in L^1_{loc}(\mathbb{R}^n)$. Then $f \star g \in C^k(\mathbb{R}^n)$ and

$$D^{\alpha}(f \star q) = (D^{\alpha}f) \star q \quad \forall \alpha \text{ with } |\alpha| < k$$

(14/07/20) Today I recalled an important property that compact metric spaces are separable. It almost skipped my mind when I was revisiting the proof of Arzelà-Ascoli theorem.

(23/07/20) Today I learned about compact operators on Banach spaces. A linear bounded operator $T: E \to F$ is said to be compact if $T(B_E)$ has compact closure or equivalently if for any sequence $v_n \in B_E$ the sequence $T(v_n)$ has a convergent subsequence. The set of compact operators $\mathcal{K}(E, F)$ is a closed subspace of $\mathcal{L}(E, F)$.

A theorem of Schauder states that $T \in \mathcal{K}(E, F)$ if and only if $T^* \in \mathcal{K}(F^*, E^*)$. The proof deployed the Arzelà-Ascoli theorem neatly.

(24/07/20) Today I learned about one of the Riesz's result which states that a normed vector space E the unit ball B_E is compact if and only if E is finite dimensional. This result is then used to prove Fredholm alternative which deals with compact operators $\mathcal{K}(E)$ which describes some properties of compact operators similar to linear operators between finite dimensional spaces.

(28/07/20) Today I learned about Sobolev spaces $W^{1,p}(I)$ for an interval I = (a, b). It is based on the idea of functions having weak derivatives so when integrated against a compactly supported smooth function you can switch the derivative with a minus sign. Surprisingly these spaces are complete allowing all Banach spaces techniques. Also $H^1 = W^{1,2}$ is a Hilbert space which I guess will be important function space to look for solutions.

(30/07/20) Today I learned that smooth functions are dense in Sobolev spaces $W^{1,p}$, quite an interesting fact. This might be the motivation for developing Sobolev spaces because derivative take a part in the norm.

August 2020

(1/08/20) Today I learned some absolutely brilliant applications of Lax-Milgram theorem. The theorem is so powerful when equipped with appropriate Sobolev spaces. For good enough differential equations after proving existence of a unique solution the derivative itself lends its continuity implying sufficient differentiability of the solution and converting it to a strong solution. It was magnificent to learn about it, you can just crush differential equations with it.

(9/08/20) Today I learned about Hodge decomposition theorem. Assuming regularity of the laplacian, the theorem yields such important results. First and foremost, for compact oriented smooth manifold, the deRham cohomology spaces are finite dimensional and secondly every cohomology class can be represented by an unique harmonic form.

At the end it seems like "All roads leads to complex geometry".

September 2020

(23/09/20) Today I learned about compactly generated topological spaces. A compactly generated topological space is a topological space whose topology is coherent with compact sets, so a set A is closed iff $A \cap K$ is closed for all compact sets K. A very important fact is that any Hausdorff locally compact space is compactly generated. This fact is very useful when dealing with proper maps.

October 2020

(13/10/20) Today I learned about line bundles on riemann surfaces and how they are connected with divisor. If we assume the fact that every holomorphic line bundle on a Riemann surface has a non-zero meromorphic section then, the group of line bundles on a Riemann surface (say X) is isomorphic to group of divisors on X modulo principal divisors on X.

November 2020

(6/11/20) Today I started reading a paper of Bennett Chow and Richard Hamilton about cross curvature flow.

(16/11/20) Today I learned a cool trick to take covariant derivative of tensors from Bennett Chow's book *Hamilton's Ricci flow* The trick was used to obtain covariant derivative of Christoffel symbols and expressing them in terms of covariant derivatives of the metric. The idea is to take normal coordinates so that derivatives of metric with respect to coordinates vanishes. Now the covariant derivative matches with the usual coordinate derivative, so we substitute that and get a tensorial equation. Hence this calculation is valid in all coordinates and we get the formula.

(18/11/20) Today I learned how vector bundles are related to locally free sheaves. The isomorphism is simple to get.

(20/11/20) Today I thought of an innocent looking problem which was not innocent at all. The problem came up while thinking about the definition of meromorphic functions. Meromorphic function on a complex manifold is defined locally as a ratio of two holomorphic functions on a codemension 1 space of the total manifold but what is stoping this local definition to be global? In the simpler case of a Riemann surface, the question is whether every holomorphic map to \mathbb{P}^1 is ratio of two holomorphic maps, like maybe after some adjustments to the two projections from \mathbb{P}^1 . The question is stupid for compact Riemann surfaces as every holomorphic map is a constant so we only care about non compact spaces.

(22/11/20) Today I learned a bit about the eight model geometry and the Geometrization conjecture of Thurston. One very ambitious goal is to understand it along with the study of Ricci flow.

(27/11/20) Today I learned about van Kampen theorem from the category theory perspective. The theorem is formulated in terms of fundamental groupoid and colimits of the diagram from an good open cover. It felt way more clean than the group theory presentation although it is the same thing. Essentially in category theory there is just one proof with one idea and that's it, van Kampen in 4 lines. I had the first taste of abstract nonsense and it looks promising. Before this I finally learned about limits and colimits of category theory.

December 2020

(4/12/20) Today I learned about the algebraic topology proof of theorem that subgroup of a free group is free. I always knew there existed a proof but never bothered to look into it, neither it was required but today when I saw it for the first time, I was spell-bounded by the simplicity of the proof. Just a little bit of covering space theory and a lemma about fundamental group of graphs, and you are done.

(10/12/20) Today I learned about cellular homology. The first definition is based on singular homology and then goes on to prove that it matches with singular homology. I

don't completely understand the motivation behind the definition but it is pretty that you have one more homology theory isomorphic to singular homology.

(12/12/20) Today I learned about good pairs of topological spaces. A pair of topological space (X, A) is called a good pair if $H_n(X, A) \cong \tilde{H}(X/A)$. If A is closed and strong deformation retract to an open set, then (X, A) is a good pair. The proof goes by some diagram gymnastics and use of excision axiom. This is a very useful theorem because for CW complexes, (X, A) is always a good pair when A is a subcomplex and X/A can also be given a CW structure. In a way it seems like CW structure was defined in a way so that subcomplexes are strong deformation retracts to open sets (just puncture the remaining cells of the CW complex to get an open set).

(13/12/20) Today I learned about Yoneda lemma. In a locally small category \mathcal{C} , for each object we can associate a $h^A = Hom(A, \cdot)$ functor. Let F be a functor from \mathcal{C} to the category of sets, Yoneda lemma states that the set all natural transformations from $Hom(A, \cdot)$ is in bijection with F(A). In the proof it can be seen that h^A is a special type of functor. For each element in $f \in h^A(B) = Hom(A, B)$ one also gets a map $h^A(f) : Hom(A, A) \to Hom(A, B)$ and $h^A(f)(id_A) = f$.

(24/12/20) Today I learned about integrable almost complex structure and Kähler manifolds. I also got to know about Newlander-Nirenberg theorem which says that any integrable almost complex structure actually comes from a complex structure. What makes complex geometry difficult to understand is that there are so many things happening at the same time.

(25/12/20) Today I learned about the linear algebra related to Lefschetz operator and Lefschetz decomposition of exterior product. The Lefschetz operator is defined by wedge of fundamental form on exterior product. The Lefschetz also interacts with hodge star operator and there is a very very strange formula of the relation defined on primitive forms. This is all linear algebra but still so messy and unintuitive.

Also the Lefschetz decomposition is related to $\mathfrak{sl}_2(\mathbb{C})$ representations which I know nothing about.

(26/12/20) Today I learned about Kähler identities relating $L, \Lambda, d, d^*, \partial, \bar{\partial}, \partial^*, \bar{\partial}^*$. The count doesn't stop...! How they came up with these many operators and their relations is beyond my imagination.

I also learned about Hodge decomposition on Kähler manifolds and how it prove $\partial, \bar{\partial}, \partial\bar{\partial}$ lemma on d-closed forms. The symmetries of the hodge diamond are pretty cool. We have three symmetries, Serre duality, isomorphism by hodge star and complex conjugation so the cohomology of Kähler manifold looks pretty restricted.

(27/12/20) Today I relearned the fact that the following fact about flasque sheaves. Let \mathcal{F}^1 be a flasque sheaf. Then given an exact sequence of sheaves

$$0 \to \mathcal{F}^1 \xrightarrow{\alpha} \mathcal{F}^2 \xrightarrow{\beta} \mathcal{F}^3(U) \to 0$$

is an exact sequence of sheaves then for any open set $U \in M$, the sequence

$$0 \longrightarrow \mathcal{F}^1(U) \longrightarrow \mathcal{F}^2(U) \longrightarrow \mathcal{F}^3(U) \longrightarrow 0$$

is also exact.

The proof is so tricky that I always forget it. The idea is (surprisingly) to use Zorn's lemma. Let s be a section of $\mathcal{F}^3(U)$, by stalk surjectivity we can construct an inverse of s locally on \mathcal{F}^2 . We apply Zorn's lemma to get a maximal element of this set, and prove by contradiction that if the maximal element is not U (say V) then we can extend V to a bigger set $V \cup W$ by adjusting in on W exactly because we have the to power to globally extend on the kernel of β .

(29/12/20) Today I learned about fundamental class of a compact, oriented manifold. The existence proof is such an amazing application of induction and reducing to case to more and more simple setting until it becomes trivial. One proves a more general theorem of existence and uniqueness for compact subsets of a manifold and then apply it to compact manifolds. It uses a technique called local global principle which states that if a proposition is true for compact sets A, B and $A \cap B$ then it is true for $A \cup B$. The proof goes via some standard Mayer-Vietoris arguement.

(30/12/20) Today I continued learning about fundamental class. One thing which bothered me very much was the isomorphism $H_n(M, M-\{x\}; R) \cong H_{n-1}(S^{n-1}; R) \cong \mathbb{Z} \otimes_{\mathbb{Z}} R \cong R$ for a commutative ring R. The second last isomorphism comes universal coefficient theorem which only gives it as a group isomorphism, then one has to see that the map is indeed also a ring homomorphism which then implies that it is also a ring isomorphism. Only now some arguments in the proof of fundamental class are valid.

January 2021

(1/1/21) Today I finally completed the proof of Poincaré duality for manifolds with or without boundary. The end result is so good but it doesn't come free. So many new ideas and things needed to be established before the proof, especially local orientation and fundamental class.

(3/1/21) Today I learned about intersection paring on cohomology on compact manifold with boundary. It is defined from Poincaré pairing.

(21/1/21) Today I learned about decay of scalar curvature under normalized ricci flow on a 2 manifold with r = 0. The case with r < 0 required most of the work and this was more of an extension of previous techniques. However the techniques of r < 0 case will just get us some bounds, not a decay. The trick for r = 0 was to look at heat equations with a time factor multiplied. This technique is called Bernstein - Bando - Shi (BBS) technique.

(23/1/21) Today I learned about Moser theorem which relates symplectic forms upto isotpoy. The proof was an instructive illustration of using utilizing Cartan's magic formula and integrating vector fields to get isoptoy. Basically the theorem answered some questions

on how much can we relate two symplectic forms on a compact manifold by symplectomorphism/isotopy. One condition is to have all convex combination symplectic and the other is to have constant de Rham cohomology.

(24/1/21) Today I learned about Darboux theorem of symplectic manifolds. The theorem was an easy corollary of relative Moser theorem. Because of this result, there is no local geometry of symplectic manifolds because everything is same as canonical form on \mathbb{R}^{2n} locally.

(25/1/21) Today I learned about Weinstein Lagrangian Neighborhood theorem and Weinstein tubular neighborhood theorem. It turns out in a compact lagrangian X submanifold of a symplectic manifold (M, ω) , you can relate the symplectic form ω to canonical symplectic form ω_0 of T^*X by a diffeomorphism of neighbourhoods of X in both manifolds. This theorem practically classifies lagrangian embeddings.

(26/1/21) Today I learned about the compatibility between a symplectic, an almost complex and a riemannian structure. Given two of these we can construct the third one compatible with them. This should give a way to explore one geometry through other lenses, like we can ask questions like how much curvature affects/restricts symplectic structure. The sweet intersection of all of this is of course Kähler geometry.

February 2021

(2/2/21) Today I learned about Fibre bundles in algebraic topology. It looked like a important generalization of covering space which can help in finding homotopy groups. More surprising were fibrations which like fibre bundles satisfied long exact sequence of homotopy groups.

I also learned about Whitehead theorem on weak homotopy equivalence. The proof was so illustrative use of various properties, first mapping cylinder, then using compression lemma, probably also using the fact that every CW pair is a cofibration.

(5/2/21) Today I learned about Gagliardo - Nirenberg inequality on euclidean space or compact Riemannian manifold. At first sight it is a strange inequality with covariant derivatives on both side and different norms and a strange condition of norms but it can be really helpful. Today it was used to complete the argument that riemannian metric under normalized ricci flow on torus converges to a metric with constant scalar curvature. Most of the work for this convergence was already done by proving decay of derivatives through BBS methods and this inequality closed the proof but none of it works for sphere case.

(9/2/21) Today I learned about Serre spectral sequence of fibrations. I haven't looked at the proof but it looks far far from anything easy. The emphasis of my algebraic topology course is to learn calculations so we are doing that more without bothering about difficult proves. The method was so difficult to grasp at first but after some examples it is more clear and computational. It is surprising that we can relate homology/cohomology of fibrations. This method enables to compute homology/cohomology of more complicated spaces like

Eilenberg-Maclane space which looks more accessible from fibrations than other techniques like CW homology or Mayer-Vietoris sequence.

(11/2/21) Today I learned about surface entropy on riemannian surface when scalar curvature is strictly positive. Since normalized ricci flow preserves the positive sign of scalar curvature, the entropy is defined as long as solution exists. It turns out that surface entropy is a monotonous (strictly monotonous unless scalar curvature becomes constant) quantity and it helps in estimating diameter of the manifold.

April 2021

(3/4/21) Today I learned about complex deformations and Beltrami coefficient. It is related to marked Riemann surfaces, space of complex structures on a Riemann surface along a marking on it in the form of generators of fundamental group. This space upto a nice equivalence is called Teichmuller space and is related to study of Moduli spaces of Riemann surfaces.

(4/4/21) Today I learned about Fuchsian groups. They are discrete subgroups of Aut(H) and because H is second-countable space, there are atmost countable number of elements in a Fuchsian group.

(18/4/21) Today I learned about the characterization of growth of groups. For now I am only concerned about finietly generated groups, let $\gamma(n)$ be the number of elements in the group of length less than n where length is defined with the help of the generators. Some equivalence is defined to get rid of dependence of generators. Now we want to study the asymptotic bounds of $\gamma(n)$. For example, free group generated by k elements, $\gamma(n) = 2k(2k-1)^{n-1}$ which is exponential and for finite group $\gamma(n)$ is bounded.

Milnor studied the relation between curvature of a Riemannian manifold and growth of its fundamental group. Under some curvature conditions, he found that growth of volume of the universal cover is same as that of fundamental group. It is beyond amazing that such a relation exists. One relates a very crude data of fundamental group to growth of volume given a metric.

(19/4/21) Today I learned about Volume entropy and topological entropy of a metric space. It was a surprising fact for me that hyperbolic balls have exponential volumes. Volume entropy is defined to capture this coefficient by taking logarithm, dividing it by radius and taking the limit.

Precisely, for a compact riemannian manifold (M, g), take its universal cover with the induced metric (\tilde{M}, \tilde{g}) . For $y \in \tilde{M}$ define

$$h(g) = \lim_{R \to \infty} \frac{\log \operatorname{vol}(B(y, r))}{R}$$

Then this limit exists (not infinity) and is independent of y. This is called the volume entropy. It is related to a different kind of entropy called topological entropy which is more

dynamical system wise definition. This is from paper Topological entropy for geodesic flows by Anthony Manning.

(26/4/21) Today I learned about partial differential operators on smooth vector bundles.

June 2021

(12/6/21) Today I learned about characters of a finite group and Dirichlet L function.

(24/6/21) Today I learned about Harmonic maps between Riemannian manifolds from Eells and Sampson paper. The concept is not too difficult, it is based on energy of a function between two Riemannian manifolds and with the most obvious definition one can imagine. Let $f:(M,g)\mapsto (M',g')$ be a map between two Riemannian manifolds. For any point $x\in M$, $Df_x:T_xM\mapsto T_{f(x)}M'$ is a map between two vector spaces with inner product so $Df_x\in \operatorname{Hom}(T_xM,t_{f(x)}M')\cong T_x^*M\otimes T_{f(x)}M'$. From inner product g one can equip T_x^*M with an obvious inner product and tensor product of two inner product is also an inner product so we have a concept of norm for Df_x . Let $g=g_{ij}dx^i\otimes dx^j$ and $g'=g_{\alpha\beta}dy^{\alpha}dy^{\beta}$ be expression in local coordinates near x and f(x), then

$$||Df_x||^2 = g'_{\alpha\beta}(f(x)) \frac{\partial f^{\alpha}}{\partial x^i} \frac{\partial f^{\beta}}{\partial x^j} g^{ij}(x)$$

Define energy of f by

$$E(f) = \frac{1}{2} \int_{M} ||Df_x||^2 d\mu$$

Harmonic functions are externals of this functional.

August 2021

(26/8/21) Today I learned about Morse theory. From a lemma of Morse, non-degenerate critical points of a function are quite rigid and upto a coordinate change behave like

$$f(x_1, x_2, \dots, x_n) = x_1^2 + \dots + x_{\lambda}^2 - x_{\lambda+1}^2 \dots - x_n^2$$

where λ is called the index of the critical point.

September 2021

(8/9/21) Today I learned about existence of functions with no degenerate points on an embedded manifold. One of the function which does this wonder is distance from a point function. Its only degenerate points are the points where intuitively normals of the manifold converge. With the help of Sard's theorem and evaluation function of normal bundles, such points have measure 0.

It proves something even better. With other part of the morse theory, we can conclude that any differentiable manifold has the homotopy type of a CW-complex and there exists a function with no degenerate points such that each M^a is compact.

November 2021

(15/11/21) Today I learned about Caretheodory extension theorem of premeasures. It states that starting from a premeasure μ_0 on an algebra \mathcal{A} , you can get a measure μ on a σ -algebra \mathcal{M} containing \mathcal{A} which when restricted to \mathcal{A} is equal to μ_0 . Another nice property of this extension is that it is greater than every other extension of μ_0 , further if the space is σ finite, then every extension of μ_0 is same on the σ algebra generated by \mathcal{A} .

This theorem enables us to define Lebesgue measure on the euclidean space, based on the algebra of intervals.

(22/11/21) Today I learned about Malgrange-Ehrenpreis theorem in the theory of distributions. Given a polynomial differential operator $P = \sum_{\alpha} a_{\alpha} \partial^{\alpha}$ on an open set $\Omega \subset \mathbb{R}^n$, we want to find whether there exists a solution of the distributional equation

$$P(E) = \delta \tag{1}$$

Malgrange-Ehrenpreis theorem gurantees the existence of such distribution. Notice that $S \star \delta = S$ in convolution of distributions so $P(S \star E) = S \star P(E) = S \star \delta = S$, hence if we can solve the fundamental equation (1), then we can solve any equation of the form L(T) = S by substitution $T = S \star E$.

(28/11/21) Today I learned more about Sobolev spaces and density theorems on it. It turns out that like L^p spaces we can approximate Sobolev functions in some sense by compactly supported smooth functions but not completely but nice things happen if it is the complete Euclidean space. Let $W^{m,p}(\Omega)$ denote your standard Sobolev space and $W_0^{m,p}(\Omega) = \overline{D(\Omega)}$ be closure of compactly supported smooth functions with respect to sobolev norm. Then for \mathbb{R}^n we have

$$W_0^{m,p}(\mathbb{R}^n) = W^{m,p}(\mathbb{R}^n)$$

The other density result for arbitrary open sets is the Friedrichs theorem which says that we can approximate by compactly supported smooth functions but we have to restrict this limit to relatively compact subsets.

(29/11/21) Today I learned a small part of the trace theorem in Sobolev spaces. One part of the trace theory was to show that if $u \in W^{1,p}(\Omega) \cap \overline{C(\Omega)}$ and $u|_{\partial\Omega} = 0$ then $u \in W^{1,p}_0(\Omega)$, which is a really intuitive statement. If a function vanishes on the boundary we wish we could approximate it by compactly supported functions in Ω . I guess u being continuous is needed to make sense of vanishing at the boundary which might be a measure zero set. The hard part would be proving the converse of this which will be part of trace theory.

I also learned about extension operator $P:W_0^{1,p}(\Omega)\to W^{1,p}(\mathbb{R}^n)$ which is a continuous linear map such that $P(u)|_{\Omega}=u$. There always exists such operator and its existence makes some things about the space $W_0^{1,0}(\Omega)$ so much simpler to deal with.

(30/11/21) Today I learned (again) about Poincaré inequality on bounded open sets of Euclidean space but finally with the proof. The proof had plenty of room for generalization and the author Kesavan suggests so too in the remarks. We can get away with unbounded domain which is bounded in one direction and the function only needs to vanish in that boundary.

December 2021

(1/12/21) Today I learned about Sobolev inequality on \mathbb{R}^n . One part of the theorem is that if $1 \le p < n$ then there exists a continuous map

$$W^{1,p}(\mathbb{R}^n) \to L^{p^*}(\mathbb{R}^n)$$

where $p^* > p$ and satisfies $\frac{1}{p^*} = \frac{1}{p} - \frac{1}{n}$.

Basically it says that by the existence of L^p derivatives we should be able to say something more about the function. The proof not surprisingly had 2 steps where we first proved this for compactly supported smooth function and then took the limit.

(8/12/21) Today I learned about Trace operator for Sobolev spaces. The concept is very interesting and it generalizes Green's formula for Sobolev spaces which in my mind seems to be a big result. This opens up more space to do calculus on Sobolev spaces and C^1 domains. A peculiar finding was the range of Trace map. Let $\gamma: H^1(\mathbb{R}^n_+) \to L^2(\mathbb{R}^{n-1})$ be the trace map, then the range of map is $H^{\frac{1}{2}}(\mathbb{R}^{n-1})$, where the fractional Sobolev space is defined with the help of Fourier transforms. What this suggests is that going into the boundary eats up half of the derivative, a really good explanation of this fact with an example was done in the math.stackexchange post. More strangely, it tells that functions with more than $\frac{1}{2}$ derivative in some sense can be extended to to \mathbb{R}^n_+ . The inverse is not very difficult to obtain, a formula with the help of exponential decay and Fourier transformations does the job as demonstrated in Kesavan.

Overall the fractional derivative thing is mostly dealt with the help of Fourier transformations and seems to be serving as a generalization rather than a big concept in itself. I don't know how to interpret fractional derivative without Fourier transforms.

(9/12/21) Today I learned about Lax-Milgram theorem again from Evans PDE book. Sobolev spaces were developed to solved PDEs and the space provides a solution in the weak sense. In the particular case of elliptic PDEs we have a regularity theorem which ensures that the solution has classical derivatives too given the test function is smooth.

(10/12/21) Today I learned about the existence of the weak solution of the elliptic operator. The solution also depends continuously on the input function which was not too

surprising. Poincaré theorem was crucial in one step of the proof, so we need to assume some sort of boundedness of the domain. This assumption felt pretty strong so it will be interesting to see how much of this is true in unbounded domains which seems like a natural question.

February 2022

(18/2/22) Today I learned about semisimple modules. The definition is intuitive in the sense we want simple modules to be the building blocks to do algebra and semisimple modules are the object born out of it. One prominent feature here seems to be abundant use of Zorn's lemma to prove things which is understandable since we are dealing with quite general rings and modules.

March 2022

(5/3/22)Today I learned about congruent numbers. This seemingly innocent problem led to a solution of Fermat's last Theorem for n=4. The original proof by Fermat is amazing ingenuity, both 1 being congruent and Fermat's last theorem for n=4 reduces to equation

$$x^4 - y^4 = u^2$$

with u being odd. Fermat solve this using the method of descent, that is given a solution he produced another solution with one of the parameters less than the previous one. Using this repeatedly would give us the required contradiction.

(31/3/22) Today I learned about characters of representation.

April 2022

(5/4/22) Today I learned about Mazur's theorem on Elliptic curves. The bounds on the theorem looks suprising strong. Why will anyone expect a bound on the number of torsion rational points in an elliptic curve to be a subgroup of order 12, such a small number. Not only that, Nagell-Lutz theorem sorts of gives an algorithm to find all rational points (which are actually integer points) because the y coordinate needs to be a factor of the discriminant D.

(6/4/22) Today I learned about p adic numbers. The p adic norm is not very geometric but does some job. It was very weird to see expansion of rational numbers with respect to this norm as you have infinite numbers on the left, not on the right! This is because norm of p^n is actually $\frac{1}{p^n}$ which looks counter intuitive for the first time. So for example

$$-1 = \sum_{i=0}^{\infty} (p-1)p^n$$

which in traditional decimal notation might look like $-1 = \dots 666.0$ say for p = 7.

(7/4/22) Today I learned about points of order 3 on an elliptic curve. Surprisingly they always exist and form the group $\mathbb{Z}/3\mathbb{Z} \times \mathbb{Z}/3\mathbb{Z}$. The result comes from solving the cubic polynomial x(2P) = x(P) which always have 3 distinct roots because f has distinct roots. Suppose β_i are the solutions and $\delta_i = \sqrt{\beta_i}$ is the positive square root, the the group is explicitly

$$G = \{\infty, (\beta_1, \pm \delta_1), (\beta_2, \pm \delta_2), (\beta_3, \pm \delta_3), \}$$

(11/4/22) Today I learned about Nagell Lutz theorem in Elliptic curves from Silverman and Tate's book, Rational Points on Elliptic curves. The proof was an interesting application of p adic techniques and how primes numbers are fundamental blocks in the case of integers when it comes to divisibility. The proof combined the idea of group theory, elliptic curves and calculations related to it, integer divisibility in a intriguing fashion. A very important step was projective transformation to work in better coordinates and get a group homomorphism into rationals which illustrates how geometric number theory can be!

(12/4/22) Today I learned about Descent method to prove that the set of rational points on an elliptic curve is finitely generated. It seemed to be such a peculiar yet strong technique. The first step is to get a height function on the points and prove it has the required properties. As remarked in Tate and Silverman the subtlest part of the proof is proving that $[C(\mathbb{Q}):2C(\mathbb{Q})]<\infty$.

(21/4/22) Today I learned about Ramanujan's τ function and the conjectures related to it. First question was why, second question was how, third question was what does it mean. So Ramanujan's tau function are coefficients of Δ expansions and somehow they satisfy arithmetic properties. This is also the unique cusp form of weight 12 with q coefficient 1.

(24/4/22) Today I learned about Hecke operators on modular forms. Hecke operators are kind of an averaging operator on the modular forms, where the averaging is done over $SL_2(\mathbb{Z})$ cosets of matrices of determinant m.

(27/4/22) Today I realized something very very basic about function composition. The notation $(f \circ g)(x) = f(g(x))$ can be thought as left group action of function so by design, $f \cdot g = (fg)$ when thinking like group action.

May 2022

(1/5/22) Today I learned about representations of finite group. From Maschke's theorem, the ring kG is semisimple so the regular representation can be decomposed into irreducible representations (and every irreducible decomposition comes from this). One can look at the center of kG in two ways - conjugacy classes of the group and the Artin-Wedderburn decomposition. This leads to an interesting fact that the number of conjugacy classes is equal to the number of irreducible decomposition of a finite group.

(11/5/22) Today I learned about unitary operators on Hilbert space. It was surprising that there are restricted class of isometries which are more suitable to study for Hilbert spaces.

The two notion isometry and unitary coincides for finite dimensional spaces but differs for infinite dimensional which leads to interesting Hilbert theory. The difference seems subtle at first.

(25/5/22) Today I learned about Ricci flow equation. The Ricci curvature has a formula computed with respect to metric derivatives and Christoffel symbols where one particular term is of the form $-\frac{1}{2}$ times the Laplacian of the metric. So when Hamilton wrote

$$\frac{\partial}{\partial t}g_{ij} = -2\mathrm{Ric}_{ij}$$

for the Ricci flow, it almost is like a heat equation but with extra terms.

(28/5/22) Today I learned about Weyl tensor and Kulkarni-Nomizu product of symmetric (2,0) tensors. The idea of Kulkarni-Nomizu product is very simple, given the symmetry of Riemannian curvature tensor we want to construct a product which has the same properties. Now Weyl tensor is traceless Riemannian 4 tensor constructed using Kulkarni-Nomizu product. In the book *The Ricci flow in Riemannian Geometry* there is a result by Huisken which suggests controlling Weyl tensor under Ricci flow is key to differentiable sphere theorem. It would be interesting to study the algebra of theses tensors, including dimension and representations of Riemannian type tensor.

(29/5/22) Today I learned about Ulhenbeck's trick for Ricci flow. The idea is to generate a one-parameter family of isomorphisms on the tangent bundle which take the Ricci flow to the initial metric g(0). A similar idea was used in the concept of self-similar solitons of the Ricci flow, the difference is that here the manifold is fixed and the isomorphisms is on the tangent bundle.

(30/5/22) Today I learned Ulhenbeck's trick with orthonormal frame approach and the fact that tangent space of Frame bundle is trivial. It is important to note that Frame bundle is not a vector bundle but a principal GL(n) bundle.

June 2022

(2/6/22) Today I learned another approach for Ulhenbeck's trick. This time a very natural idea was to consider the manifold $M \times \mathbb{R}$ and consider a family g(t) on its TM part of its vector bundle. We construct a (non symmetric) connection on the spatial vector bundle where the covariant derivative with respect to time is equal to time derivative of Riemannian curvature.

(5/6/22) Today I learned about maximum principle for symmetric 2-tensor. An interesting application of this is for Ricci tensor under Ricci flow in 3 dimension. Hamilton observed that Weyl tensor vanishes in dimension 3 and this allows a flow equation of Ricci tensor purely in terms on Ricci tensor and its contractions(so no R_{ijkl} terms). This remark and the remarkable maximum principle implies that for 3 manifolds if the initial Ricci tensor is positive then it remains so for all time the solution exists under Ricci flow.

(6/6/22) Today I learned about for maximum principle of vector bundle. The formalization was so abstract but it needed to be this way. Few concepts were introduced such as fibrewise convexity of a set, invariance under parallel transport along with normal and tangent cone of a closed convex set. The idea is that in the analogue of heat equation for section of vector bundle, its values continue to lie in fibrewise convex set if some good conditions are satisfied.

(7/6/22) Today I learned how the maximum principles for vector bundles implies the maximum principle for symmetric 2 tensors.

(12/6/22) Today I learned about the Bernstein-Bando-Shi estimates for all derivatives for an n dimensional manifold. Again the crucial trick was to create a function like

$$G = t^m |\nabla^m \text{Rm}|^2 + \text{lower derivatives of Rm with appropriate ratio}$$

to compensate for the bad terms. The maximum principle on G then allows to produce a bound on the derivative in terms of the tensor Rm.

(19/6/22) Today I learned the fact that every closed 3-manifold is parrallelizable. The proof which I didn't pursue goes through obstruction theory and Stiefel-Whitney classes.

I also learned about the curvature operator. Its just Riemannian tensor adopted to look like an operator on 2-forms (because of good anti-symmetry properties) with the help of metric isomorphisms of T^*M and TM. Ricci flow preserves the sign of this operator which has great consequences. Also, this operator when diagonalized in 3 dimensions remain so under Ricci flow.

July 2022

(5/7/22) Today I learned about locally convex hyperplanes. In a paper of embedding of negatively curved manifolds into Minkowski space, there is a result stating that the Gauss curvature flow is equivalent to cross curvature flow in a certain specific setting(locally convex, co-compact, spacelike hypersurface). Ben Andrews and others proved that the Gauss curvature flow in that case converges to hyperboloid of constant negative sectional curvature. Another evidence for the XCF conjecture.

(8/7/22) Today I learned about local isometric embedding of Riemannian manifolds. Let (M^n, g) be a n-dimensional manifold which we want to locally embed in a Euclidean space (\mathbb{R}^q, δ) . This reduces to solving for a function (locally) $u: B \subset \mathbb{R}^n \to \mathbb{R}^q$ such that $u^*\delta = g$ which is a system of $\frac{n(n+1)}{2}$ equation so ideally it should be possible with $q = \frac{n(n+1)}{2}$ and it turns out it is! There are different treatments for analytic and smooth cases.

(9/7/22) Today I learned about curve-shortening flow.

September 2022

(1/9/22) Today I learned about the transcendence of e. The proof is slightly involved and the properties of e comes unexpectedly. The idea is to use simultaneous approximation.

This is a recurring theme in Transcendental number theory. Algebraic numbers can't be approximated too well because of Liouville's theorem.

(4/9/22) Today I learned about non-collapsing result in the mean curvature flow. Sheng and Wang proved that any compact mean-convex solution of MCF is δ -non-collapsed for some $\delta > 0$. Ben devised a simpler solution by using maximum principle on a two point function whose supremum measures the inscribed curvature. The evolution equation of this function satisfies maximum principle, so if we start with a δ -non-collapsed hypersurface, it remains so under MCF.

(17/9/22) Today I learned about avoidance principle of MCF. Given two disjoint hypersurface evolving under MCF out of which at least one is compact, the distance between the hypersurface is a non-decreasing function of time. The solution is geometric flavour of maximum principle for parabolic equations. At the time of minima, the tangent planes become parallel which agrees with the intuition geometrically. The proof also implies that if we start the flow on an embedding, then it remains an embedding because of injectivity.

(20/9/22) Today I learn about Monotonicity formula of Huisken. Under MCF, the Gaussian area of the manifold is a non-increasing function. This will be useful later to find about the manifolds arising as type-I singularities of the MCF.

(21/9/22) Today I learn about Liouville's theorem on irrational algebraic numbers. The theorem says that any algebraic number can be approximated by rational numbers only upto a certain degree. Liouville numbers are numbers can be approximated by rational numbers with any degree. Liouville numbers are transcendental, an example is

$$\alpha = \sum_{i=0}^{\infty} \frac{1}{10^{n!}}$$

which contain arbitrarily large gaps of zeros growing on a factorial pace.

(22/9/22) Today I learned about Lindemann-Weierstrass theorem. The theorem states that if $\alpha_1, \ldots, \alpha_s$ are distinct algebraic numbers, then $e_1^{\alpha}, \ldots, e_s^{\alpha}$ are linearly independent over $\overline{\mathbb{Q}}$. The idea comes from Lindemann's proof of transcendence of π but applied to a larger setting of number fields. The proof is somewhat involved, but the plan of attack is very similar, construction of an auxillary function and getting an integer out of it divisible by (p-1)! but not p! establishing it is non-zero and a bound on such that the integer is squeezed between 0 and 1 which gives the contradiction.

October 2022

(12/10/22) Today I learned an example of Riemannian manifold where geodesic balls might not have compact closure. Most of the time the picture I have in mind is of closed manifolds embedded in \mathbb{R}^n but we can consider open submanifolds of \mathbb{R}^n . In fact for manifolds which can be isometrically embedded as closed submanifolds of \mathbb{R}^n the geodesic balls will always have compact closure because of Heine-Borel theorem. In case of open manifold, this need

not happen. For example consider an open cylinder in \mathbb{R}^n so the manifold has bounded diameter but is non-compact.

November 2022

(2/11/22) Today I learned about Gelfond-Schneider theorem. The theorem gives an affirmative answer to Hilbert's seventh problem. Lang generalized the theorem which says more about transcendence of some values of elliptic functions. The proof is a difficult excursion through inequalities, maximum modulus principle, Siegel's lemma, estimates on derivatives and rate of growth of entire functions.

(3/11/22) Today I learned about Baker's theorem which is a generalization of Gelfond-Schneider theorem. The proof is a complicated multivariable version on Gelfond-Schneider theorem with vast applications. The theorem also proves transcendence results of some values of Dirichlet L-series for non-trivial characters.

(6/11/22) Today I learned about width-pinching of convex hypersurfaces. This idea devised by Ben simplifies the proof of Huisken's proof. Essentially, I think it is a local-global principle which says that local pinching of principle curvatures leads to global pinching of widths of the hypersurface. Now, Hamilton's tensor maximum principle implies that the pinching of principle curvature is preserved. Also, widths are related to circumradius and inradius which will imply pinching of circumscribed radius and inscribed radius.

(7/11/22) Today I learned few properties of elementary symmetric polynomials, particularly the Newton's inequality.

(9/11/22) Today I learned about convexity of positive cones of symmetric polynomials. In Huisken and Sinestrari's paper Convexity estimates for mean curvature flow and singularities of mean curvature flow they want to prove some general convexity estimates. The paper starts with proving convexity of the set

$$\Gamma_k = \{ \mu \in \mathbb{R}^n | s_1(\mu) > 0, \dots, s_k(\mu) > 0 \}$$

and concavity of function $q_{k+1} = \frac{s_{k+1}}{s_k}$ on cone Γ_k . The calculations are really lengthy and loaded with tricks.

December 2022

(1/12/22) Today I learned about Stampacchia iteration technique used by Huisken in the 1984 MCF paper. I have to verify a few details, but I think the crux of the argument is to get an L^p bound for sufficiently large p and then establish an L^{∞} bound.

January 2023

(3/1/23) Today I learned about Brendle's sharp bound on the inscribed radius under MCF. Brendle proved a sharper viscosity PDE for the reciprocal of inscribed radius with

negative gradient term. The aim of the paper is to use this in order to finder a sharper bound for inscribed radius. The viscosity PDE proof is also presented in Ben's book in a cleaner fashion where they also cover the boundary case of supremum. I still have to understand the blow-up of the diagonal construction which is very neat.

(7/1/23) Today I learned more about Stampacchia iteration which is often used in singularity analysis of MCF. The proof is divided into two steps; step one is obtaining L^p bound for sufficiently large p and then using Stampacchia lemma to make it L^{∞} bound using Michael-Simon inequality. It is the L^p bound which consists of very elaborate calculations because of few bad terms.

(11/1/23) Today I learned about variational inequalities.

(23/1/23) Today I learned about nets in topological spaces. They generalize the notion of a convergent sequence; instead of dealing with a totally ordered set (\mathbb{N} in the case of sequences) we define it using any directed set. This generality allows us to work in general topological spaces where limits may not be unique. In fact, the uniqueness of limit of nets is equivalent to the space being Hausdorff.

(27/1/23) Today I learned about distributions on manifolds. The main motivation seems to be answering the question which distribution comes from a submanifold. Frobenius theorem states that a distribution being involutive is same as it being induced by a submanifold at each point. Notice that here we do not care about manifold being embedded. The Lie bracket of an immersion (one-one and injective differential but the topology may not match) is still involutive because the integral flow of vector fields will lie in the submanifold.

Now given any distribution \mathscr{D} we can consider the set of one-forms which annihilates it. Let \mathscr{I} be the ideal generated by it in the graded algebra of differential forms. It turns out that this ideal being differential $(d(\mathscr{I}) \subset \mathscr{I})$ is same as \mathscr{D} being involutive which same as \mathscr{D} being induced by a submanifold.

February 2023

(15/2/23) Today I learned about the automorphism group of simply connected Lie groups. So given a Lie group G, every automorphism of G leads to an automorphism of Lie algebra \mathfrak{g} . This gives a group homomorphism $\operatorname{Aut}(G) \to \operatorname{Aut}(\mathfrak{g})$ and in the case of simply connected Lie groups it is an isomorphism. Now we know that $\mathfrak{g} \cong \mathbb{R}^n$ so the automorphism group $\operatorname{Aut}(\mathfrak{g})$ can be identified as a subgroup of $\operatorname{GL}(n,\mathbb{R})$ which satisfy $A[e_i,e_j]=[A(e_i),A(e_j)]$. This can be proven to be a closed group so Cartan's theorem implies that $\operatorname{Aut}(G)$ is infact a Lie group itself.

(22/2/23) Today I learned about simplicial sets. A simplicial set is a contravariant functor $X: \Delta \to \mathbf{Set}$. Here Δ is the category with objects $[n] = \{0 < 1 < \cdots < n\}$ for $n \geq 0$ and morphisms are $\delta: [n] \to [m]$ are weakly monotone functions.

(25/2/23) Today I finished the proof of Stampacchia iteration after nearly 8 months. The entire proof is very complicated and one has to get L^p estimates before the iteration even starts. That in itself is a task requiring so many estimates. This is the major part of proving that the limit of a mean-convex compact hypersurface is convex. The not-so difficult part is to get done with the convergence of manifolds theory and prove that mean-convex hypersurface satisfy those convergence conditions.

(28/2/23) Today I learned about locally compact spaces. One definition is that X is locally compact if for any $x \in X$ and any open neighborhood U_x of x, there exists a compact Neighborhood K_x such that $K_x \subset U_x$. The other definition is that every point $x \in X$ has a relatively compact neighborhood. This is more restrictive (and natural to me) however the two definitions match on Hausdorff spaces.

March 2023

(1/3/23) Today I learned about induced representation on $L^1(G)$ from a unitary representation of G. So given a unitary continuous representation $\pi: G \to \mathcal{U}(H)$, we can define a representation on $L^1(G)$ using the formula

$$\langle \pi(f)v, w \rangle = \int_G f(x) \langle \pi(x)v, w \rangle dx$$

which be thought of as averaging with weight f given by $\pi(f) = \int_G f(x)\pi(x)dx$. Surprisingly there is a way to formalize this without using the previous explicit formula. It is called Bochner integration which can be defined whenever we want to integrate a function with values in a Banach space (not just \mathbb{C}).

(2/3/23) Today I learned about type II singularity in MCF. For mean-convex hypersurface it can be proved using maximum principle that $|A|^2 \leq c_0 H^2$ for some constant c_0 depending only on initial hypersurface. Also, algebraically $H^2 \leq n|A|^2$ so $|A|^2$ and H^2 have same rate of blow-up. Using maximum principle again on the evolution equation of $|A|^2$ one can derive that

$$\max_{\mathcal{M}_t} |A|^2 \ge \frac{1}{2(T-t)}.$$

Using this we say that the MCF develops a singularity of $type\ I$ if there exists a constant C>0 such that

$$\max_{\mathcal{M}_t} |A|^2 \le \frac{C}{T - t}$$

so the blow-up rate is inverse linear. Otherwise, it is called a singularity of type II. I think most singularities are type II but strictly convex hypersurface are type I.

(3/3/23) Today I learned about Cheeger-Gromov convergence of pointed Riemannian manifolds. Question - Is the Cheeger-Gromov limit unique up to pointed isometries?

(14/3/23) Today I learned why representation theory is important for the study of Lie groups. Given a Lie group G, we can study the representation on the obvious vector space - the Lie algebra \mathfrak{g} . Now it might be interesting to look at irreducible representations of the adjoint action.

(17/3/23) Today I learned a small result on inscribed curvature of a hypersurface. As expected the reciprocal of the inscribed radius at any point of the hypersurface is related to the principal curvatures. The relation is

$$k > \kappa_n$$

if $\kappa_1 \leq \ldots \leq \kappa_n$ is the order of principal curvatures.

(18/3/23) Today I learned more about the viscosity differential inequality for noncollapsing. The inscribed curvature $k(x) = 2\sup_{y \neq x} \frac{\langle x-y,N(x) \rangle}{|x-y|^2}$ as described is the inverse of the largest sphere inscribed in the hypersurface M touching the point $x \in M$. For any point $x \in M$, two cases might happen. Either the supremum is achieved from a different point say $y \in M \setminus \{x\}$ or the supremum is achieved by y approaching x in some curve. The first is called the interior case and the second is the boundary case. It can be proven that $k > \kappa_n$ in the interior case and $k = \kappa_n$ in the boundary case. This can be seen from the fact that κ_n is the maximum of the second fundamental form (thinking of this as a bilinear form) when restricted to normal vectors and the expression of k is the same as the second fundamental form in the limiting boundary case.

Now k satisfies a differential inequality in the viscosity sense. The proof is done by finding an appropriate elliptic differential term of k. The boundary case happens in a set of measure zero which for me is a little more difficult to prove than the interior case. The setup in the book is that you attach the sphere bundle on the diagonal which characterizes the inscribed curvature in the boundary cases of supremum (it is determined by the tangent vector of the curve y approaching x which achieves the supremum).

In the interior case, the elliptic equation is simpler where the coefficients are constant and its matrix is block diagonal (block of 4 identity matrices if we pick normal coordinates in the product manifold $M \times M$). Also, one can notice that the differential inequality has a single variable however the proof goes through the maximum principle on a two-point function. Besides, one can notice that the differential inequality has a single variable however the proof goes through the maximum principle on a two-point function.

April 2023

(16/4/23) Today I learned some results on representations of Lie groups. One of the basic questions in representation theory is to find out when a given representation is irreducible. One way to probe a representation is by character functions. Let $\rho: G \to GL(V)$ be a complex representation, define $\chi_{\rho}: G \to \mathbb{C}$ by

$$\chi_{\rho}(g) = \operatorname{tr}(\rho(g)).$$

This function is constant on conjugacy classes of G. One big theorem I got to know today is the following classification theorem of Frobenius-Schur which states that if G is a topological compact group, then two representations ϕ and ψ are equivalent if and only if the characters χ_{ϕ} and χ_{ψ} are equivalent. The proof heavily relies on Schur's lemma and existence of Haar measure.

(25/4/23) Today I learned a very basic fact about Lie algebra. The Jacobi identity is equivalent to the fact that adjoint representation is a Lie algebra representation.

May 2023

(27/5/23) Today I learned about Principal bundles. An interesting property of principal bundles is that every principle bundle over a contractible space is trivial. This required a homotopy lifting property in fiber bundles which was new to me. For covering spaces, the fiber is a discrete space and with the help of local homeomorphism one can prove the homotopy lifting property easily. However, for general fiber bundles it seems to require a little more thought. Some of the assumptions I think are needed is that the fiber should be locally connected and locally path connected.

June 2023

(1/6/23) Today I learned about construction of principal bundle from family of transition maps satisfying cocycle condition. The idea isn't new, you construct a big disjoint union of product space and quotient out the relations coming from the transition maps.

(2/6/23) Today I learned about principal bundles over S^n . The principal bundles over S^n are in one-to-one correspondence with the homotopy group $\pi_{n-1}(S^n)$. We can do this by covering S^n by two disks covering North and South Pole and having equator S^{n-1} in the intersection. Then we just need to specify the transition function which will be like a map $S^{n-1} \to G$.

(8/6/23) Today I learned about connections on fiber bundles. So connections can be constructed on any fiber bundle with the vector bundle set up I am used to. The fundamental idea is to get a notion of parallel transport between two fibres. In fact in fiber bundles case one can even avoid smooth structures.

(13/6/23) Today I went back and learned something about the postulates of Quantum Mechanics. The idea that you need separable Hilbert spaces to specify you physical states and observables are now operators and not functions is so weird.

August 2023

(17/8/23) Today I learned about transversality of smooth maps into a submanifold. It can be thought of as an extension of regular value. Let $f: X \to Y$ be a smooth map and let $Z \subset Y$ be a submanifold of Y. We say f is transversal to Z if for each $x \in f^{-1}(Z)$ the following condition holds

$$\operatorname{im}(df_x) + T_y(Z) = T_y(Z).$$

This is denoted by $f \cap Z$. This condition leads to the property that if f is transversal to Z then the preimage $f^{-1}(Z)$ is also a submanifold of X with same codimension as Z (this is easier to check).

When f is an inclusion map of a submanifold $i: X \to Y$, the condition becomes for every $x \in X \cap Z$,

$$T_x(X) + T_x(Z) = T_x(Y)$$

which is a symmetric condition and we write this as $X \cap Z$. In Guilleman and Pollack, it is explained that this basically happens when the cutout functions of X and Z are independent.

(18/8/23) Today I relearned about steady Ricci solitons and gradient Ricci solitons.

(27/8/23) Today I relearned about Riemannian curvature tensor as an operator on twoforms. In the context of Ricci flow, this is particularly helpful. It turns out that upto an isometry(a very specific pullback involving Uhlenbeck's trick), the Ricci flow can be simply written as

 $\frac{\partial}{\partial t}(\iota^*Rm) = \Delta_D Rm + Rm^2 + Rm^\#$

where ι is the pullback, Rm^2 is square of Rm when thinking of as an operator, and $Rm^\#$ is its Lie algebra square. Two corollaries -

- 1. If the curvature operator is positive, then it remains so during the flow.
- 2. In dimension three, this implies that the flow is diagonal under an orthonormal frame.

(28/8/23) Today I learned about Perelman's \mathcal{F} functional. It is defined on product space of Riemannian metrics and functions by the formula

$$\mathcal{F}(g,f) = \int_{M} (R + |\nabla f|^{2})e^{-f}dV$$

where R is the scalar curvature.

(31/8/23) Today I learned more about Perelman \mathcal{F} functional. The \mathcal{F} functional is diffeomorphism invariant and we can construct a functional purely based on metrics out of it. Let $d\omega$ be a fixed measure, then for a given metric g by Radon-Nikodym we can consider the function $f = \log(\frac{d\mu(g)}{d\omega})$ and composing it with \mathcal{F} , we get a functional $\mathcal{F}^m : \mathfrak{Met} \to \mathbb{R}$,

$$\mathcal{F}^m(g) = \mathcal{F}\left(g, \log\left(\frac{d\mu(g)}{d\omega}\right)\right) = \int_M (R + |\nabla f|^2) d\omega.$$

Perelman proves that the gradient flow of this functional is upto a diffeomorphism same as the Ricci flow coupled with an evolution equation of f. Further since this is a gradient flow, this quantity is monotonic and by diffeomorphism invariance of the functional we further get that it is monotonic under Ricci flow too! So if (g(t), f(t)) is a solution of the coupled Ricci flow, then

$$\frac{d}{dt}\mathcal{F}(g(t), f(t)) = 2\int_{M} |R_{ij} + \nabla_{i}\nabla_{j}f|^{2}e^{-f}d\mu \ge 0.$$

September 2023

(4/9/23) Today I learned about Perelman's theorem on breathers. A metric $g_{ij}(t)$ evolving by the Ricci flow is called a **breather** if there exists $t_1 < t_2$ and $\alpha > 0$ such that the metrics $\alpha g_{ij}(t_1)$ and $g_{ij}(t_2)$ differ only by diffeomorphism. The cases $\alpha = 1, \alpha < 1, \alpha > 1$ correspond to **steady**, **shrinking**, and **expanding breathers** respectively.

Using the monotonicity of functional \mathcal{F} , Perelman proved two results regarding the first two breathers -

- 1. A steady breather is necessarily a steady gradient soliton.
- 2. An expanding breather is necessarily an expanding gradient soliton.

(6/9/23) Today I learned about Perelman's \mathcal{W} functional. It is more involved functional defined on $\mathcal{W}: \mathfrak{Met} \times C^{\infty}(M) \times \mathbb{R}^+ \to \mathbb{R}$ as

$$\mathcal{W}(g, f, \tau) = \int_{M} (\tau(R + |\nabla f|^{2}) + f - n)ud\mu$$
$$= \frac{1}{(4\pi\tau)^{\frac{n}{2}}} \left(\tau \mathcal{F}(g, f) + \int_{M} (f - n)e^{-f}d\mu\right)$$

where $u = (4\pi\tau)^{\frac{-n}{2}}e^{-f}$. Like \mathcal{F} functional this is also diffeomorphism invariant so its gradient flow which is diffeomorphically similar to Ricci flow yields a monotonicity formula for Ricci flow.

(9/9/23) Today I learned about the μ functional minimizing the W functional, which is like λ functional minimizing \mathcal{F} functional. It is defined as

$$\mu(g,\tau) = \inf \{ \mathcal{W}(g,f,\tau) | f \in C^{\infty}(M) \text{ is compatible with } g \text{ and } \tau \}$$

where we say that f is compatible with (g, τ) if

$$\int_{M} (4\pi\tau)^{-\frac{n}{2}} e^{-f} d\mu = \int_{M} u d\mu = 1.$$

From some really involved elliptic PDE theory, Andrews-Hopper's book proves that μ has a smooth minimizer. Then from the monotonicity of \mathcal{W} one can prove that μ is monotonous as well (the compatibility of a minimizer function is preserved under Ricci flow). The monotonicity of μ can be used to prove that shrinking breather are necessarily a gradient shrinking soliton. Thus we have proved that every breather is actually a gradient soliton.

(13/9/23) Today I learned about Curve shortening flow (CSF), the one-dimensional version of MCF. The flow is simpler than MCF and it being in one-dimension makes some computations easier or intuitive. Like MCF it obeys avoidance principle and preserve embeddedness. For the proof of embeddedness in the book *Extrinsic Geometric Flows* Andrews et al. prove a maximum principle for a two-variable distance function.

(16/9/23) Today I learned about convex ancient solutions of the CSF. I am trying to read a paper by Theodora et al. which classifies convex ancient solutions of CSF. In the beginning we are dealing with asymptotics of a given solution. Let $\Gamma: (-\frac{\pi}{2}, \frac{\pi}{2}) \times (-\infty, 0) \to \mathbb{R}^2$ be a convex, non-compact ancient solution in the angle turning parametrization bounded in the strip $|x| < \frac{\pi}{2}$ and contained in no smaller strip. Then for any s < 0, the spacetime translated curve

$$\Gamma^s(\theta, t) := \Gamma(\theta, t + s) - \Gamma(0, s)$$

is also a solution of the CSF with $\Gamma^s(0,0) = 0$. Using Harnack inequality and classification of translating solutions to CSF, they prove that

$$\lim_{s \to -\infty} \Gamma^s(\theta, t) = rG(\theta, r^{-2}t)$$

converges locally uniformly in the smooth topology where $G(\theta, t) = (\theta, t + \log \sec(\theta))$ is the Grim reaper solution and $r = \lim_{s \to -\infty} \kappa^{-1}(0, s)$.

One interesting point in the proof is that in the limit, the curvature doesn't depend on time, so it is a translating solution after which they use the classification result.

(17/9/23) Today I learned more about convex ancient solutions of CSF. Continuing the paper, a convex ancient solutions sweeps out the strip $|x| < \frac{\pi}{2}$. The proof relies on the fact that in the limit $t \to -\infty$, we have $\kappa \to \kappa_{-\infty} > 0$.

(22/9/23) Today I learned about estimates of derivatives of harmonic function on an open set in \mathbb{R}^n . If α is a mutlindex of norm k, then

$$|D^{\alpha}u(x_0)| \le \frac{C_k}{r^{n+k}}||u||_{L^1(B(x_0,r))}$$

for each $B(x_0, r)$ in the domain. Here

$$C_0 = \frac{1}{\alpha(n)}, \qquad C_k = \frac{(2^{n+1}nk)^k}{\alpha(n)} \qquad (k = 1, \dots)$$

are dimensional constants. The proof is by induction $(D^{\alpha}u)$ is also harmonic if u is) and using the mean value property on $B(x_0, \frac{r}{k})$ to get

$$|D^{\alpha}(x_0)| \le \frac{nk}{r} ||D^{\beta}u||_{L^{\infty}(\partial B(x, \frac{r}{k}))}$$

where $\alpha = \beta + e_i$ for some i. Now if $x \in B(x_0, \frac{r}{k})$ then $B(x, \frac{(k-1)}{k}r) \subset B(x_0, r)$ and by using the induction hypothesis we get a bound.

The arbitrary radius in the small ball argument indicates the constants might not be sharp.

(26/9/23) Today I learned about Green's function. It is useful for solving Poisson's equation for a bounded domain. Using the method solving Poisson's equation reduces to constructing a Green's function for the given domain (which can be difficult).

(29/9/23) Today I learned about stochastic process. A general idea is that a stochastic process is a family of random variables X(t) indexed by time (can be discrete or continuous). The question is how to make sense of the continuity of $t \mapsto X(t)$ when t takes values from an interval in \mathbb{R} . There are various ways to define this continuity, some stronger than others. We say that X(t) is **continuous with probability one** at t if

$$\mathbf{P}\left(\left\{\omega \in \Omega \middle| \lim_{s \to t} |X(s) - X(t)| = 0\right\}\right) = 1$$

where Ω is the sample space. The family X(t) is said to be **continuous in probability** at t if, for all $\epsilon > 0$,

$$\lim_{s \to t} \mathbf{P}\left(\left\{\omega \in \Omega \middle| |X(s) - X(t)| \ge \epsilon\right\}\right) = 0.$$

Conintuity with probability one implies continuity in probability but I haven't read the proof. Also, it can be useful to think of an element $\omega \in \Omega$ as a particle and the function $t \mapsto X(t)$ as its path.

October 2023

(16/10/23) Today I learned about CMC (constant mean curvature) surfaces. Let $U \subset \mathbb{R}^n$ be a bounded open set with C^2 boundary and $f \in C^2(\partial U)$, $u \in C^2(U) \cap C(\overline{U})$. Suppose the graph of the function $u: U \to \mathbb{R}$ in \mathbb{R}^{n+1} when subjected to a volume constraint and required to be f on the boundary is an area minimizer, then it is a CMC surface.

I also learned about Hopf boundary point lemma for elliptic PDEs.

(31/10/23) Today I learned how Brendle's paper on sharp bound on the inscribed curvature is related to the convexity estimates of mean-convex MCF. The smallest principal curvature κ_1 can be considered like a local exscribed radius bound and similarly the largest principal curvature can be considered like a local inscribed radius bound. Let k(x) be the inscribed curvature (inverse of the radius of the largest sphere inside the hypersurface touching it at x), and $\rho(x)$ be the exscribed curvature. These function contain global data and not surprisingly are shaper than the local data, particularly

$$-\rho(x) \le \kappa_1(x) \le \dots \le \kappa_n \le k(x).$$

Convexity estimates imply that for every $\epsilon > 0$ there exists a constant C_{ϵ} such that

$$\frac{\kappa_1}{H} \ge -\epsilon$$

whenever $H \geq C_{\epsilon}$. Brendle's result improves this to sharper result that for every $\epsilon > 0$ there exists a constant C_{ϵ} such that

$$\frac{\rho}{H} \le \epsilon$$
 or $-\frac{\rho}{H} \ge -\epsilon$

whenever $H \geq C_{\epsilon}$. Asymptotically this means that under MCF the hypersurface is becoming convex and its limit will be weakly convex, as proved by convexity estimates. However we can't conclude convexity estimates from Brendle's results since he needs convexity estimates to prove this.

Also, the theme of Stampacchia iteration is similar in the spirit of convexity estimates. The function this time is

$$f_{\sigma} = (k - (1 + \delta)H) H^{\sigma - 1}$$

and with steps similar to the proof of convexity estimates, there exists a constant c_0 , such that

$$\frac{d}{dt} \left(\int_{M_t} f_{\sigma,+}^p d\mu \right) \le 0$$

whenever $p \ge c_0$ and $\sigma \le (c_0 p)^{-\frac{1}{2}}$.

November 2023

(5/11/23) Today I learned more about the Brendle's sharp inscribed curvature bound proof.

January 2024

(10/1/24) Today I learned about minimal surfaces from Colding and Minicozzi's book. It started with proving that graphical solution of minimal surfaces is area-minimizing, not just critical of area functional. There are plenty of examples of minimal surfaces mentioned in the book and it seems to be a goal to classify all minimal surfaces under good assumptions.

Another good result covered is that proposition that any compact minimal submanifold in Euclidean space is contained in the convex hull of it's boundary. So for example in reverse if we cut any part of helicoid/catenoid then the minimal surface it is easy to visualize that the minial surface interior is contained in the convex hull of boundary present.

(14/1/24) Today I learned about minimal surfaces. We can define a mean curvature vector for a any general submanifold (not just a hypersurface). It lives on the normal space and the definition matches with classical one when specialized to hypersurface. After calculating the first variation of volume of a submanifold it is easy to see that a submanifold immersed in Euclidean space is minimal if and only if the coordinate functions are harmonic in the induced metric.

(31/1/24) Today I realized how subbundles are submanifolds. Let E be a vector bundle over M and $D \subset E$ be a subbundle. So $D_x \subset E_x$ is a subspace at each $x \in M$. Consider a trivialization

$$\psi_U: \pi^{-1}(U) \to U \times \mathbb{R}^n.$$

Then $\psi(D_x)$ is a subspace of \mathbb{R}^n at each point. We can consider invertible linear maps $T_x: \mathbb{R}^n \to \mathbb{R}^n$ such that $T_x(\psi(D_x)) = \mathbb{R}^d \subset \mathbb{R}^n$, with last n-d coordinates zero. Then $(id \times T_x) \circ \psi$ can be considered a chart for D.

February 2024

(1/2/24) Today I learned about the Yang-Mills functional. Given a vector bundle E equipped with metric over real manifold M, the Yang-Mills functional operates on the space of all metric connections on E and is given by

$$YM(D) = \int_{M} \langle F_D, F_D \rangle d\mu,$$

where F_D denotes the curvature of connection D. Let D^* denote the adjoint of D, then the Euler-Lagrange equation of this functional is

$$D^*F_D=0$$

which is called the Yang-Mills equation.

(4/2/24) Today I learned the geometric way of combining the Maxwell's equations. Let **E** and **B** denote electric and magnetic field in space respectively. Let ρ denote the charge density and **j** denote the current density. Then the Maxwell equations read

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = 0$$

$$\nabla \cdot \mathbf{E} = \rho$$

$$\nabla \times \mathbf{B} - \frac{\partial \mathbf{E}}{\partial t} = \mathbf{j}.$$

The first two can be cast in the language of differential forms by an easy observation. If $\mathbf{B} = (B_x, B_y, B_z)$ and likewise for \mathbf{E} , then

$$B = B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy$$

is a two-form which satisfies dB = 0 and

$$E = E_x dx + E_y dy + E_z dz$$

is a one-form which satisfies dE=0. Bringing the time coordinate, we can define an electromagnetic two-form

$$F = B + E \wedge dt.$$

Then the two equations can be combined to give dF = 0. Take the diagonal Minkowski metric with $g(\partial_0, \partial_0) = -1$ and $g(\partial_i, \partial_i) = 1$ for i = 1, 2, 3. This defines a Hodge star operator and the last two Maxwell equations are equivalent to

$$\star d \star F = J$$

where $J = j_x dx + j_y dy + j_z dz - \rho dt$.

(7/2/24) Today I learned about electromagnetism as a Yang-Mills theory, connecting the last two posts. The main thing here is that F as a curvature is \mathbb{R} valued two-form. I don't completely understand what U(1) symmetry for electromagnetic field is supposed to be but its Lie algebra is abelian. Hence the second term in the expression

$$F_{\alpha\beta} = \partial_{\alpha} A_{\beta} - \partial_{\beta} A_{\alpha} + [A_{\alpha}, A_{\beta}] = \partial_{\alpha} A_{\beta} - \partial_{\beta} A_{\alpha}$$

vanishes and F = dA.

(16/2/24) Today I learned about Spin representation. The unit quaternions form a group which is isomorphic to SU(2) and topologically is S^3 . It acts on \mathbb{C}^2 as the standard representation which is called the spin representation. The name possibly comes from physics I guess. It turns out SO(3) isn't quite the symmetry group of an electron. The physics explanation comes from Stern-Gerlach experiment which demonstrates need for an additional variable, physicists call spin. An electron beam rotated 360° isn't the same but a 720° beam has same properties as the unrotated beam. For some fortunate reason, this can be resolved by considering the group SU(2) as the symmetry group since its a double cover of SO(3). Purely mathematically it makes sense to go to SU(2) but psychologically it gets very difficult to digest. Topology describes that there are two non-homotopic paths to reach any non-identity element $A \in SO(3)$.

(17/2/24) Today I learned about the classification of irreducible SU(2) representations. They can be completely classified and for every dimension n, there exists only one irreducible representation on \mathbb{C}^n . The idea is to consider $U(1) \hookrightarrow SU(2)$ and break down any SU(2) rep into the irreducible components of U(1) rep. Then from the Lie algebra $\mathfrak{sl}(2,\mathbb{C})$ which is complexified Lie algebra $\mathfrak{su}(2)$, we can construct operators which moves the vectors in the eigenstates of U(1) rep to a higher or lower eigenstate (at Lie algebra level U(1) rep produces eigenstates of integer values only). The idea of breaking down the components using U(1) inside Lie groups seems to be important. Infact, as $T^n = U(1) \times \cdots \times U(1)$ is abelian, Schur's lemma tells us that the only irreducible rep are one dimensional so we can look for tori inside Lie groups and use to study representations. The eigenvalues of representation also have some symmetry since there are various ways tori sits inside the Lie group however the eigenvalues are invariant.

(22/2/24) Today I learned about quantization in quantum mechanics. Roughly speaking it is thought as a technique to seek quantum mechanics observables from a classical mechanics satisfying certain rules. Dirac observed that the Poisson bracket of classical mechanics is similar to Heisenberg commutation relations. This led to general philosophy(?) that one should seek a map from set of functions space of phase space to observables on the quantum Hilbert space. After all, the position, momentum and energy (Hamiltonian) operators have such construction.

(23/2/24) Today I learned about Heisenberg lie algebra and Schrödinger representation. Heisenberg commutation relation is given by

$$[X,P]=i\hbar\operatorname{id}$$

(24/2/24) Today I tried to learn about the path integral formulation of quantum mechanics. Woit mentions in his book that the idea is to create a Lagrangian formalism of quantum mechanics. But the whole idea of getting a Lagrangian from the propagator is a little confusing. Assuming a lot of hand-waving he arrives at an action integral which I couldn't understand.

March 2024

(3/3/24) Today I learned about symplectic formulation of classical mechanics. Let N be the configuration space thought of as the position space for say, k-system of particles. It could be \mathbb{R}^{3k} or some submanifold of it under constrained motion. Then the cotangent bundle, T^*N is thought of as total phase space where the covectors coordinates is momentum of the system. T^*N naturally comes with a one-form, ω defined by

$$\omega(v_{\phi}) = \phi(\pi_* v)$$

where $\phi \in T^*N$ is the point where the vector v is considered. The two-form $d\omega$ is closed and non-degenerate, thus $(T^*N, d\omega)$ is a symplectic manifold. Consider a Hamiltonian function on T^*N as

$$H = \frac{1}{2} \langle \phi, \phi \rangle + V(\pi_* \phi)$$

where $\langle \cdot, \cdot \rangle$ is some Riemannian metric, used for mass units. The Hamiltonian H generates a Hamiltonian vector field X_H which generates the time-flow of symplectomorphisms. That is, $\Phi: T^*N \times (-\epsilon, \epsilon) \to T^*N$ is the time translation function of the phase space so $\Phi(t, (p, v))$ is the position-momentum vector of the state after time t.

(4/3/24) Today I learned about the Lagrangian of a particle in an electromagnetic field. The action integral should be Lorentz-invariant, and Folland takes the simplest one as

$$S = \int_{(t_0, \mathbf{x}_0)}^{(t_1, \mathbf{x}_1)} (-mds - qA_{\mu}dx^{\mu})$$

where $ds^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2$ is the Lorentz metric and $A_{\mu} = (\phi, \mathbf{A})$ is the electromagnetic 4-potential. The ratio of the different integrand (ds and A_{μ}) is kept to ultimately derive the Lorentz force law. Using $\mathbf{v} = \frac{d\mathbf{x}}{dt}$, we can obtain the Lagrangian as

$$L = -m\sqrt{1 - |\mathbf{v}|^2} + \mathbf{q} \cdot \mathbf{v} - q\phi.$$

Folland then goes on to describing the corresponding Lagrangian for a field.

April 2024

(8/4/24) Today I learned about self-similar solution of the α -Gauss flow. Consider a very general anisotropic flow given by

$$\frac{dx}{dt} = -\rho(\nu_x) K_x^{\alpha} \nu_x.$$

Then the self similar solutions are obtained by the formula

$$\langle x, \nu_x \rangle = c\rho K^{\alpha}$$

for some c > 0.

(15/4/24) Today I tried to cast the self similar solutions of α -Gauss flow in the Monge-Ampere type using support function. The equation $\langle X(x), \nu(x) \rangle = cK^{\alpha}$ can be written as

$$h = c \left(\frac{\det(\overline{\nabla}^2 h + \overline{g}h)}{\det(\overline{g})} \right)^{-\alpha}$$

where $\overline{\nabla}^2 h$ is the 2-tensor defined using the standard connection on S^n . It is easy to calculate

$$\overline{\nabla}_i \overline{\nabla}_j h = \partial_i \partial_j h - (\overline{\nabla}_i \partial_j) h$$

(16/4/24) Today I tried spherical coordinates on the α -Gauss flow. In the parametrization $x = \cos \theta \cos \phi$, $y = \cos \theta \sin \phi$, $z = \cos \theta$, we have

$$\overline{g} = \begin{bmatrix} 1 & 0 \\ 0 & \cos \theta \end{bmatrix}$$

and

$$K^{-1} = \frac{\det\left(\begin{bmatrix} h_{\theta\theta} & h_{\theta\phi} - \frac{\tan\theta}{2}h_{\phi} \\ h_{\theta\phi} - \frac{\tan\theta}{2}h_{\phi} & h_{\phi\phi} - \frac{\cos\theta}{2}h_{\theta} \end{bmatrix} + h\begin{bmatrix} 1 & 0 \\ 0 & \cos\theta \end{bmatrix}\right)}{\cos\theta}$$

which is quite ugly.

(17/4/24) Today I learned about the homogeneous degree 1 extension of the support function. Let $h: S^n \to \mathbb{R}$ be the support function of a strictly convex hypersurface. We extend this to $H: \mathbb{R}^{n+1} \to \mathbb{R}$ by defining,

$$H(x) = |x|h\left(\frac{x}{|x|}\right).$$

Note that H is just continuous but not necessarily differentiable at 0. It is easy to see that $DH(\lambda x) = DH(x)$. Let $x \in \mathbb{R}^{n+1}$ and v be a unit vector,

$$D_v H(x) = h\left(\frac{x}{|x|}\right) D_v |x| + |x| D_v h\left(\frac{x}{|x|}\right)$$
$$= \frac{v \cdot x}{|x|} h\left(\frac{x}{|x|}\right) + |x| \overline{\nabla}_{v^T} h\left(\frac{x}{|x|}\right)$$

where $\overline{\nabla}_{v^T}$ is the covariant derivative on S^n in the direction $v^T \in T_x S^n$. Let $x \in S^n$ and substitute $v \in \{e_1, \ldots, e_{n+1}\}$ to get

$$DH(x) = xh(x) + \overline{\nabla}h(x)$$

which is the inverse of Gauss map! Thus, $G^{-1}(x) = DH(x)$, and also weirdly $D_xH(x) = DH(x)$ so the steepest accent is in the normal direction.

(18/4/24) Today I learned about a possible reducible symmetric group to try to construct self-similar solutions of the α -Gauss curvature flow. As considered previously the setup is with support functions. The sphere $h \equiv 1$ is an equilibrium point of the normalized α -Gauss flow. The construction of Γ symmetric solutions in Ben's paper is using spherical harmonics (eigenfunctions of the Laplacian) and some general version of the stable/unstable manifold theorem. The linearized version of normalized α -Gauss flow at $h \equiv 1$ is given by

$$\frac{\partial u}{\partial t} = \alpha(\Delta + n)u + u$$

so if $\Delta \psi = -\lambda \psi$, then $h \equiv 1$ is strictly unstable in the direction ψ (what does this really mean?). Another important fact is that entropy is a min for unstable direction, the Hessian of entropy at $h \equiv 1$ satisfies

$$D^2 Z_h(\psi, \psi) > 0.$$

A new idea is to use an affine boost along with the spherical harmonics to possible control the isoperimetric ratio. The considered example of a reducible group was generated by $x \mapsto -x$ and a 3-fold rotation symmetric group in yz plane along with reflection of the triangle (so the dihedral group D_3 in the yz plane). Consider a one-parameter family of affine transformations which stretches the x-direction,

$$T_{\lambda} = \begin{bmatrix} e^{2\lambda} & 0 & 0 \\ 0 & e^{-\lambda} & 0 \\ 0 & 0 & e^{-\lambda} \end{bmatrix}.$$

Now we can consider a one parameter family of flows produced by the unstable direction $\epsilon \psi + T_{\lambda}$ and the expectation is that since the entropy of the solutions with $\lambda = 0, \infty$ is ∞ (to check) one can possibly use a mountain pass theorem (in homotopies of λ variable) to create a critical point which will be a self-similar solution of the flow.

(19/4/24) Today I learned about the α -Gaussin entropy of a bounded convex hypersurface. In the book it is defined as

$$E_{\alpha}(\mathcal{M}) \doteq \begin{cases} \left(\frac{\operatorname{Vol}(\mathcal{M}^{n})}{|B^{n+1}|}\right)^{\frac{n}{n+1}} \exp\left(\frac{1}{|S^{n}|} \int_{\mathcal{M}^{n}} K \log K d\mu\right) & \text{if } \alpha = 1\\ \left(\frac{\operatorname{Vol}(\mathcal{M}^{n})}{|B^{n+1}|}\right)^{\frac{n}{n+1}} \left(\frac{1}{|S^{n}|} \int_{\mathcal{M}^{n}} K^{\alpha} d\mu\right)^{\frac{1}{\alpha-1}} & \text{if } \alpha \neq 1 \end{cases}$$

It turns out that the α -Gaussian entropy is non-increasing under α -Gauss flow. The next task is to understand its property on normalized α -Gauss flow.

(22/4/24) Today I learned about the Brunn-Minkowski inequality. It states that for convex bodies $A, B \subset \mathbb{R}^n$ and $\lambda \in [0, 1]$, we have

$$\operatorname{Vol}(\lambda A + (1 - \lambda)B)^{\frac{1}{n}} \ge \lambda \operatorname{Vol}(A)^{\frac{1}{n}} + (1 - \lambda)\operatorname{Vol}(B)^{\frac{1}{n}}$$

which is same as saying that $\operatorname{Vol}(\cdot)^{\frac{1}{n}}$ is a concave function on the set of convex bodies.

(23/4/24) Today I learned about the proof of monotonicity of α -Gaussian entropy under α -Gaussian flow using Brunn-Minkowski inequality.

(24/4/24) Today I tried to finish the monotonicity of entropy proof.

(29/4/24) Today I learned about Jacobi fields in the general context of calculus of variations. Let $I(u) = \int F(t, u(t), \dot{u}(t))$ which we want to minimize.

May 2024

(3/5/24) Today I learned about Mountain Pass Theorem(MPT).

(18/5/24) Today I learned about Perron's method of subharmonic function. The Green's function for balls can be obtained with involutions. This allows to solve the Dirichlet problem on balls. Perron's idea is to define a definition of subharmonic function using this result which so that subharmonic functions strong maximum principle (infact the mean value property).

Let Ω be a domain, a function $u \in C^0(\Omega)$ is said to be **subharmonic** if for every ball $B \subset\subset \Omega$ and every harmonic function h on B with $u \leq h$ on ∂B , we have

$$u \leq h$$
 on B .

It is easy to see that u satisfy the mean value property, hence also the strong maximum principle.

(7/5/24) Today I am writing equations for nomalized α -Gauss curvature flow for once and all. Let X(t) be a solution of the α -GCF, so that

$$\partial_t X = -K^{\alpha} \nu.$$

The evolution of volume under α -GCF is given by

$$\frac{d}{dt}V(X(t)) = -\int_{S^n} K^{\alpha - 1} d\overline{\mu}.$$

We normalize the the equation for the scaled hypersurface to have constant volume $|B^{n+1}|$, by defining

$$\tilde{X}(\tau(t)) = \left(\frac{|B^{n+1}|}{V(X(t))}\right)^{\frac{1}{n+1}} X(t)$$

where τ is some parametrization of time to be defined later to make equations cleaner. Note that by scaling, the new Gauss curvature is $\tilde{K} = \left(\frac{|B^{n+1}|}{V(X(t))}\right)^{-\frac{n}{n+1}} K$. Differentiating with

respect to τ ,

$$\begin{split} \frac{\partial \tilde{X}}{\partial \tau} &= \frac{\partial \tilde{X}}{\partial t} \frac{dt}{d\tau} \\ &= \left[-\left(\frac{|B^{n+1}|}{V(X(t))}\right)^{\frac{1}{n+1}} K^{\alpha} \nu + \frac{\tilde{X}}{(n+1)V} \int_{S^n} K^{\alpha-1} d\overline{\mu} \right] \frac{dt}{d\tau} \\ &= \left[-\left(\frac{|B^{n+1}|}{V(X(t))}\right)^{\frac{1+\alpha n}{1+n}} \tilde{K}^{\alpha} \nu + \frac{\tilde{X}}{(n+1)V} \left(\frac{|B^{n+1}|}{V(X(t))}\right)^{\frac{(\alpha-1)n}{n+1}} \int_{S^n} \tilde{K}^{\alpha-1} \right] \frac{dt}{d\tau} \\ &= \left[-\tilde{K}^{\alpha} \nu + \frac{\tilde{X}}{(n+1)|B^{n+1}|} \int_{S^n} \tilde{K}^{\alpha-1} d\overline{\mu} \right] \left(\frac{|B^{n+1}|}{V(X(t))}\right)^{-\frac{(1+\alpha n)}{1+n}} \frac{dt}{d\tau}. \end{split}$$

Choose $\tau(t)$ such that the term outside square bracket is 1 so that the new evolution equation is

$$\begin{split} \frac{\partial \tilde{X}}{\partial \tau} &= -\tilde{K}^{\alpha} \nu + \frac{\tilde{X}}{(n+1)|B^{n+1}|} \int_{S^n} \tilde{K}^{\alpha-1} d\overline{\mu} \\ &= -\tilde{K}^{\alpha} \nu + \frac{\tilde{X}}{|S^n|} \int_{S^n} \tilde{K}^{\alpha-1} d\overline{\mu} = -\tilde{K}^{\alpha} \nu + \tilde{X} \int_{S^n} \tilde{K}^{\alpha-1} d\overline{\mu} \end{split}$$

Let $\tilde{h}(z) = \sup\{p \cdot z : p \in \tilde{X}\} = \left(\frac{|B^{n+1}|}{V(X(t))}\right)^{\frac{1}{n+1}} h(z)$ be the support function of the rescaled hypersurface. Its evolution equation is

$$\frac{\partial \tilde{h}}{\partial \tau} = -\tilde{K}^{\alpha} + \frac{\tilde{h}}{|S^{n}|} \int_{S^{n}} \tilde{K}^{\alpha - 1} d\overline{\mu}$$

$$= -\det_{\overline{g}} (\overline{\nabla}^{2} \tilde{h} + \overline{g} \tilde{h})^{-\alpha} + \tilde{h} \int_{S^{n}} \det_{\overline{g}} (\overline{\nabla}^{2} \tilde{h} + \overline{g} \tilde{h})^{1 - \alpha} d\overline{\mu}$$

where we have used the fact that Gauss curvature can be determined from the support function by the formula

$$K = \det_{\overline{g}} (\overline{\nabla}^2 \tilde{h} + \overline{g} \tilde{h})^{-1}.$$

(9/5/24) Today I learned about some rigidity results of ancient solutions of α -GCF. If $X_t = \phi(t)X_0$ is a family of hypersurfaces moving homothetically, then under α -GCF it satisfies

$$K^{\alpha}[X_0] = -\lambda \langle X_0, \nu_0 \rangle$$
 with $\phi'(t)\phi^{n\alpha}(t) = \lambda$.

If $\lambda > 0$ it is called **expanding solution** and if $\lambda < 0$ it is called **contracting/shrinking solution**.

In paper Complete noncompact self-similar solutions of Gauss curvature flows I. Positive powers, Urbas proves that all complete non-compact convex hypersurfaces which move homothetically under α -GCF for some $\alpha \in (0, \infty)$ satisfy the previous equation and further for contracting solutions $(\lambda < 0)$, X_0 is a hyperplane through the origin.

(10/5/24) Today I learned about Hersch's theorem on first eigenvalue of the Laplacian on a sphere (S^2, g) . It states that given a Riemmanian metric g on sphere, the first non-zero eigenvalue of negative Laplacian $-\Delta_g (= -g^{ij}\nabla_i\nabla_j)$ satisfies

$$\lambda_1 \le \frac{8\pi}{\operatorname{Area}(S^2, g)}.$$

The full proof is present in Schoen, Yau's Lectures on Differential Geometry. It centrally use the fact that there is only one conformal class of metrics in S^2 (uniformization theorem I guess) and then finds a nice conformal metric of g where the center of mass is at the origin.

(14/5/24) Today I learned about stable manifold theorem. The proof is based on Banach contraction theorem like in the case of Picard-Lindelof theorem. In Picard-Lindelof the idea was to define an integral operator which is a contraction and the fixed point of the operator solves the ODE. The idea here is very similar but it takes more effort to the set up the appropriate Banach space and define the operator and then prove that it is a contraction.

(26/5/24) Today I learned about harmonic maps between Riemannian manifolds. A harmonic map $f:(M,g)\to (N,h)$ (assume C^1) is a critical point of the energy functional

$$E(f) = \int_{M} |Df|^2 d\mu_g.$$

The differential Df can be thought of as a section of the bundle $T^*M \otimes f^*TN$ with the obvious metric. The Euler-Lagrange equation of this functional (assume f is C^2) is given by

$$\frac{1}{\sqrt{g}} \frac{\partial}{\partial x^{\alpha}} \left(\sqrt{g} g^{\alpha\beta} \frac{\partial f^{i}}{\partial x^{\beta}} \right) + g^{\alpha\beta} \Gamma^{i}_{jk}(f(x)) \frac{\partial f^{j}}{\partial x^{\alpha}} \frac{\partial f^{k}}{\partial x^{\beta}} = 0 \quad \text{for each } i = 1, \dots, \dim N$$

where greek indices denote local coordinates in M and $g = \det(g_{\alpha\beta})$.

An interesting case happens when $M = \Sigma$ is a Riemann surface. A holomorphic structure on Σ induces a conformal class of metrics given by $dz \otimes d\overline{z}$. The E-L equation for the metric $\lambda^2(z)dz \otimes d\overline{z}$ takes the form

$$\frac{1}{4\lambda^2(z)}\frac{\partial^2 f^i}{\partial z \partial \overline{z}} + \frac{1}{4\lambda^2(z)}\Gamma^i_{jk}(f(z))\frac{\partial f^j}{\partial z}\frac{\partial f^k}{\partial \overline{z}} = 0$$

or

$$\frac{\partial^2 f^i}{\partial z \partial \overline{z}} + \Gamma^i_{jk}(f(z)) \frac{\partial f^j}{\partial z} \frac{\partial f^k}{\partial \overline{z}} = 0$$

which only depends on the conformal structure, not the metic of Σ (independent of λ). Also the energy functional is given by

$$E(f) = \frac{1}{2} \int_{\Sigma} \frac{4}{\lambda^{2}(z)} g_{ij} \frac{\partial f^{i}}{\partial z} \frac{\partial f^{j}}{\partial \bar{z}} \frac{\sqrt{-1}}{2} \lambda^{2}(z) dz \wedge d\bar{z}$$
$$= \int_{\Sigma} g_{ij} \frac{\partial f^{i}}{\partial z} \frac{\partial f^{j}}{\partial \bar{z}} \sqrt{-1} dz \wedge d\bar{z}.$$

June 2024

(10/6/24) Today I learned about Sobolev embedding theorem and Morrey's inequality. Essentially Sobolev spaces $W^{1,p}(\mathbb{R}^n)$ for large enough p embed in Holder spaces which is to say that weak derivatives are sufficient to deduce continuous regularity of functions (after possibly redefining on a set of measure 0). Morrey's inequality states that if n , then there exists a constant depending only on <math>p and n such that

$$||u||_{C^{0,1-\frac{n}{p}}(\mathbb{R}^n)} \le C||u||_{W^{1,p}(\mathbb{R}^n)}$$

for all $u \in C^1(\mathbb{R}^n) \cap L^p(\mathbb{R}^n)$. It follows that if $u \in W^{1,p}(\mathbb{R}^n)$, then u is in fact Hölder continuous with exponent $\gamma = 1 - \frac{n}{p}$.

August 2024

(12/8/24) Today I learned about connection on frame bundle or more generally principal bundle. While reading Hamilton's paper on Harnack estimates on MCF, he stated the following property of covariant derivative. For a local frame $\{F_a\}$ given by $F_a = F_a^i \partial_i$, and a one-form V, we have

$$D_a V_b \doteq (D_a V)_b = (F_a^i F_b^j D_i V)_j \doteq F_a^i F_b^j D_i V_j.$$

The identity has to be interpreted appropriatly using frame bundle and connection on frame bundle as a principal bundle.

(23/8/24) Today I learned about the equation of self-similar solution of α -GCF in terms of support function for $\alpha \neq 1$. The self-similar shrinker is given by

$$\langle X, \nu \rangle = cK^{\alpha}$$

for some c > 0 which can be determined by the volume enclosed by the hypersurface. Recall that the α -Gaussian entropy is given by

$$E_{\alpha}(\mathcal{M}) = \left(\frac{\operatorname{Vol}(\mathcal{M}^{n})}{|B^{n+1}|}\right)^{\frac{n}{n+1}} \left(\frac{1}{|S^{n}|} \int_{\mathcal{M}^{n}} K^{\alpha} d\mu\right)^{\frac{1}{\alpha-1}}$$

which can be written purely in terms of support function,

$$E_{\alpha}(\sigma) = \left(\int_{S^n} \sigma \det_{\overline{g}} A[\sigma] d\overline{\mu} \right)^{\frac{n}{n+1}} \left(\int_{S^n} (\det_{\overline{g}} A[\sigma])^{1-\alpha} d\overline{\mu} \right)^{\frac{1}{\alpha-1}}$$
$$= \frac{\left(\int_{S^n} \sigma \det_{\overline{g}} A[\sigma] d\overline{\mu} \right)^{\frac{n}{n+1}}}{\left(\int_{S^n} (\det_{\overline{g}} A[\sigma])^{1-\alpha} d\overline{\mu} \right)^{\frac{1}{1-\alpha}}}$$

where $A[\sigma]_{ij} = \overline{\nabla}_i \overline{\nabla}_j \sigma + \overline{g}_{ij} \sigma$ is a differential operator on S^n . The eigenvalue of A with respect to metric \overline{g} are $\kappa_1^{-1}, \ldots, \kappa_n^{-1}$ so $K = \det_{\overline{g}} A[\sigma] = \frac{\det A[\sigma]}{\det \overline{g}}$.

From the reverse Hölder inequality, we get

$$\oint \sigma \det_{\overline{g}} A[\sigma] \ge \left(\oint \det_{\overline{g}} A[\sigma]^{1-\alpha} \right)^{\frac{1}{1-\alpha}} \left(\oint \sigma^{-\frac{(1-\alpha)}{\alpha}} \right)^{-\frac{\alpha}{1-\alpha}}$$

where the equality holds for self-similar solution $\sigma = c \det_{\overline{g}} A[\sigma]^{-\alpha}$.

(24/8/24) Today I calculated the first variation of the α -Gaussian entropy. Let σ_s be a family of support functions with constant volume and $\sigma_0 = c \det_{\overline{g}} A[\sigma]^{-\alpha}$ a shrinker. Let the variation be $\partial_s|_{s=0}\sigma_s = \eta$. From the constant volume condition we get,

$$0 = (n+1)\partial_s \operatorname{Vol}(\sigma_s) = \partial_s \int_{S^n} \sigma_s \det A[\sigma_s]$$

$$= \int_{S^n} \eta \det A[\sigma_0] + \sigma_0 \det A[\sigma] A^{-1}[\sigma_0]^{jk} A[\eta]_{jk}$$

$$= \int_{S^n} \eta \det A[\sigma_0] + c \det A[\sigma_0]^{1-\alpha} A^{-1}[\sigma_0]^{jk} A[\eta]_{jk}.$$

Now the variation of log of entropy is

$$\begin{split} \partial_s \big|_{s=0} \log E_\alpha(\sigma_s) &= -\frac{1}{1-\alpha} \partial_s \log \left(\oint_{S^n} \det A[\sigma_s]^{1-\alpha} \right) \\ &= -\left(\oint_{S^n} \det A[\sigma_0]^{1-\alpha} \right)^{-1} \left(\oint_{S^n} \det A[\sigma_0]^{1-\alpha} A^{-1}[\sigma_0]^{jk} A[\eta]_{jk} \right) \\ &= \frac{1}{c} \left(\oint_{S^n} \det A[\sigma_0]^{1-\alpha} \right)^{-1} \left(\oint_{S^n} \eta \det A[\sigma_0] \right) \\ &= \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\sigma_0)} \right) \left(\oint_{S^n} \eta \det A[\sigma_0] \right) \end{split}$$

In the inner product $L^2_{\sigma_0} \doteq L^2\left(\frac{\det A[\sigma_0]}{\sigma_0}d\bar{\mu}\right)$, this can be written as

$$\partial_s(E_{\alpha}(\sigma_s)) = E_{\alpha}(\sigma_0) \frac{\langle \eta, \sigma_0 \rangle_{\sigma_0}}{c \langle \sigma_0, \det A[\sigma_0]^{-\alpha} \rangle_{\sigma_0}} = E_{\alpha}(\sigma_0) \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\sigma_0)} \right) \langle \eta, \sigma_0 \rangle_{\sigma_0}.$$

While we are at it, lets calculate the variation of Firey entropy as well. The Firey entropy for $\alpha \neq 1$ is defined by

$$\mathcal{E}_{\alpha}(\mathcal{M}^{n}) = \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\mathcal{M}^{n})}\right)^{\frac{1}{n+1}} \left(\int_{S^{n}} \sigma^{\frac{\alpha-1}{\alpha}} d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}}$$

$$= \left(\int_{S^{n}} \sigma \det_{\overline{g}} A[\sigma] d\bar{\mu}\right)^{\frac{-1}{n+1}} \left(\int_{S^{n}} \sigma^{\frac{\alpha-1}{\alpha}} d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}}$$

$$= \frac{\left(\int_{S^{n}} \sigma \det_{\overline{g}} A[\sigma] d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}}}{\left(\int_{S^{n}} \sigma \det_{\overline{g}} A[\sigma] d\bar{\mu}\right)^{\frac{1}{n+1}}}.$$

Let σ_s be a variation with same conditions as before. Then,

$$\partial_{s}|_{s=0} \log \mathcal{E}_{\alpha}(\sigma_{s}) = \left(\int \sigma_{0}^{\frac{\alpha-1}{\alpha}} \right)^{-1} \left(\int \sigma_{0}^{\frac{-1}{\alpha}} \eta \right)$$

$$= \left(\int c^{\frac{\alpha-1}{\alpha}} \det A[\sigma_{0}]^{1-\alpha} \right)^{-1} \left(\int c^{\frac{-1}{\alpha}} \eta \det A[\sigma] \right)$$

$$= \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\sigma_{0})} \right) \left(\int_{S^{n}} \eta \det A[\sigma_{0}] \right)$$

This imlpies,

$$\partial_s \big|_{s=0} \mathcal{E}_{\alpha}(\sigma_0) = \mathcal{E}(\sigma_0) \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\sigma_0)} \right) \langle \eta, \sigma_0 \rangle_{\sigma_0}.$$

Also another observation yields that for a shrinker $\sigma_0 = c \det A[\sigma_0]^{-\alpha}$,

$$E_{\alpha}(\sigma_0) = \mathcal{E}_{\alpha}(\sigma_0).$$

(29/8/24) The Brunn-Minkowski inequality states that for two non-empty compact sets $A,B\subset\mathbb{R}^{n+1}$

$$Vol(A+B)^{\frac{1}{n+1}} \le Vol(A)^{\frac{1}{n+1}} + Vol(B)^{\frac{1}{n+1}}$$

which is to say that $\operatorname{Vol}^{\frac{1}{n+1}}$ is a concave function under Minkowski addition of subsets. This also implies

$$\frac{d^2}{dt^2} \operatorname{Vol}^{\frac{1}{n+1}}(A+tB) \le 0.$$

Let σ, η be the support functions of A and B respectively, then the concavity can be expressed as

$$\left(\int_{S^n} \eta \det A[\sigma_A] A^{-1}[\sigma_A]^{jk} A[\eta]_{jk} d\bar{\mu} \right) \le n \frac{\left(\int_{S^n} \eta \det A[\sigma_A] d\bar{\mu} \right)^2}{\left(\int_{S^n} \sigma_A \det A[\sigma_A] d\bar{\mu} \right)}.$$

When $A = S^n$ we get

$$\left(\oint_{S^n} \eta(\Delta \eta + n\eta) \right) \le n \left(\oint_{S^n} \eta \right)^2$$

or

$$n\left(\oint_{S^n} \eta^2\right) \le n\left(\oint_{S^n} \eta\right)^2 + \left(\oint_{S^n} |\nabla \eta|^2\right).$$

The support function η satisfies the property that its homogenous degree one extension $\tilde{\eta}(x) = |x| \eta(\frac{x}{|x|})$ is convex.

(30/8/24) The normalized α -Gauss curvature flow $(\alpha$ -NGCF) can be written as

$$\frac{\partial \tilde{X}}{\partial \tau} = -\tilde{K}^{\alpha} \nu + \frac{\tilde{X}}{|S^n|} \int_{S^n} \tilde{K}^{\alpha - 1} d\bar{\mu} = -\tilde{K}^{\alpha} \nu + \tilde{X} \oint_{S^n} \tilde{K}^{\alpha - 1} d\bar{\mu}$$

or

$$\partial_{\tau}\sigma = -\det A[\sigma]^{-\alpha} + \sigma \int_{S^n} \det A[\sigma]^{1-\alpha} d\bar{\mu}$$

in terms of the support function. Let $\sigma_s = \sigma_0 + s\eta$ be a fixed volume variation for a shrinker σ_0 with $1 = \frac{\operatorname{Vol}(\sigma_0)}{|B^{n+1}|} = \int_{S^n} \sigma_0 \det A[\sigma_0]$ (i.e. $\sigma_0 c = \det A[\sigma_0]^{-\alpha}$ for $c = \int_{S^n} \det A[\sigma_0]^{1-\alpha} = E_{\alpha}(\sigma)^{\alpha-1} = \mathcal{E}_{\alpha}(\sigma)^{\alpha-1}$), then

$$\partial_{\tau}(\sigma_0 + s\eta) = -\det A[\sigma_0 + s\eta]^{-\alpha} + (\sigma_0 + s\eta) \oint_{S^n} \det A[\sigma_0 + s\eta]^{1-\alpha} d\bar{\mu}$$
$$= -\det A[\sigma_0 + s\eta]^{-\alpha} + c(\sigma_0 + s\eta)$$

Differentiating with respect to s at s = 0 gives

$$\partial_{\tau} \eta = \alpha \det A[\sigma_0]^{-\alpha} A^{-1} [\sigma_0]^{jk} A[\eta]_{jk} + \eta c$$

= $\alpha c \sigma_0 A^{-1} [\sigma_0]^{jk} A[\eta]_{jk} + \eta c$
= $c \left(\alpha \sigma_0 A^{-1} [\sigma_0] A[\eta]_{jk} + \eta \right)$.

This proves that $\mathcal{L}\eta = \alpha\sigma_0 A^{-1}[\sigma_0]^{jk}A[\eta]_{jk} + \eta$ is the linearized operator for α -NGCF subject to condition $\int_{S^n} \eta \det A[\sigma_0]d\bar{\mu} = 0$.

For $\sigma_0 = 1$, this simplifies to $\mathcal{L}\eta = \alpha(\Delta \eta + n\eta) + \eta = \alpha \Delta \eta + (1 + \alpha n)\eta$ subject to condition $\int_{S^n} \eta d\bar{\mu} = 0$.

September 2024

(1/9/24) The equation of a shrinker for α -CSF is given by

$$h_{\theta\theta} + h = h^{-\frac{1}{\alpha}}.$$

Linearizing the normalized α -curve shortening flow around h, we get the equation,

$$\partial_{\tau} \eta = \alpha h^{1 + \frac{1}{\alpha}} (\eta_{\theta\theta} + \eta) + \eta = \mathcal{L}_h \eta.$$

Choi and Sun prove the following theorem about the elliptic operator \mathcal{L} . Let $\bar{\Gamma}_{\alpha}^{k}$ be the shrinker for α -CSF with k-fold symmetry obtained by Andrews. For $k \geq 3$, $\alpha \in (0, \frac{1}{k^{2}-1})$ the negative eigenspace of $-\mathcal{L}_{\bar{\Gamma}_{\alpha}^{k}}$ has dimension 2k-1.

(5/9/24) The Firey entropy $\mathcal{E}_{\alpha}(\sigma) = \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\sigma)}\right)^{\frac{1}{n+1}} \left(\int_{S^n} \sigma^{\frac{\alpha-1}{\alpha}} d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}}$ for $\alpha \neq 1$ is non-increasing under normalised α -Gauss curvature flow as well. The proof is the same as done in α -Gauss curvature flow since the time derivative of \mathcal{E}_{α} comes out to be the same.

(7/9/24) Consider the normalized α -CSF flow in \mathbb{R}^2 for convex curves, where the time derivative of the support funtion is given by

$$\partial_t \sigma = -\mathfrak{r}[\sigma]^{-\alpha} + \sigma \int_{S^1} \mathfrak{r}[\sigma]^{1-\alpha} d\theta.$$

The linearized equation around a shrinker σ with variation η is given by

$$\partial_t \eta = E_{\alpha}(\sigma)^{\alpha-1} \left(\alpha \frac{\sigma}{\mathfrak{r}[\sigma]} \mathfrak{r}[\eta] + \eta \right)$$

where $\mathfrak{r}[f] = f_{\theta\theta} + f$. Consider the L^2 measure space $L^2_{\sigma} = L^2(\frac{\mathfrak{r}[\sigma]}{\sigma}d\theta)$ and $\mathcal{L}_{\sigma}f = \frac{\sigma}{\mathfrak{r}[\sigma]}\mathfrak{r}[f]$ on S^1 . Then \mathcal{L}_{σ} is a self-adjoint operator on L^2_{σ} hence has real eigenvalues and there is an orthonormal eigenbasis. The first three eigenvalues are -1, 0, 0 for functions $\sigma, \sin \theta, \cos \theta$ respectively (λ is an eigenvalue if $\mathcal{L}f + \lambda f = 0$). Using Brunn-Minkowski inequality, Andrews proved that there are no other non-positive eigenvalues. Using Rayleigh quotient, the next eigenvalue is given by

$$\lambda_{4} = \inf \left\{ -\frac{\langle f, \mathcal{L}_{\sigma} f \rangle_{\sigma}}{\langle f, f \rangle_{\sigma}} : f \in C^{\infty}(S^{1}), \langle \sigma, f \rangle_{\sigma} = \langle \sin \theta, f \rangle_{\sigma} = \langle \cos \theta, f \rangle_{\sigma} = 0 \right\}$$

$$= \inf \left\{ \frac{\int_{S^{1}} f_{\theta}^{2} - f^{2}}{\int_{S^{1}} \frac{\mathfrak{r}[\sigma]}{\sigma} f^{2}} : \int_{S^{1}} \mathfrak{r}[\sigma] f = \int_{S^{1}} \frac{\mathfrak{r}[\sigma]}{\sigma} f \sin \theta = \int_{S^{1}} \frac{\mathfrak{r}[\sigma]}{\sigma} f \cos \theta = 0 \right\}.$$

Andrews also proved that the spectrum of \mathcal{L}_{σ} is invariant under $SL(2,\mathbb{R})$ transformations using Rayleigh quotient. I will reconstruct the proof here. The lie algebra $\mathfrak{sl}(2)$ of traceless matrices can be decomposed as

$$\mathfrak{sl}(2) = \left\{ \begin{bmatrix} a & b \\ b & -a \end{bmatrix} : a, b \in \mathbb{R} \right\} \oplus \left\{ \begin{bmatrix} 0 & t \\ -t & 0 \end{bmatrix} : t \in \mathbb{R} \right\}$$

where the second summand generates rotations. To prove the invariance of spectrum, it will be enough to prove that the lie algebra action leaves the inner product and orthogonality to σ , cos, sin preserved. More formally, let $X \in \mathfrak{sl}(2)$, consider the convex curve $\gamma_t = e^{sX} \circ \gamma$ and denote by σ_s the support function of γ_s . Then,

$$\gamma_s(\theta) = e^{sX} \gamma(\theta) = e^{sX} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} s \\ s_{\theta} \end{bmatrix}$$

where for $s \neq 0$, this is not necessarily the inverse Gauss map parametrization. Since rotations don't change the geometry, we will assume that X comes from the first summand, i.e. $X = \begin{bmatrix} a & b \\ b & -a \end{bmatrix}$. The derivative of support function at s = 0 will be given by the derivative of the action since the inverse Gauss map is continuous at s = 0, so

$$\frac{\partial}{\partial s} \Big|_{s=0} \sigma_s(\theta) = \frac{\partial}{\partial s} \Big|_{s=0} \left\langle \gamma_s(\theta), e^{i\theta} \right\rangle
= \frac{\partial}{\partial s} \Big|_{s=0} \left\langle e^{sX} \gamma(\theta), e^{i\theta} \right\rangle
= \frac{\partial}{\partial s} \Big|_{s=0} \left[\cos \theta \quad \sin \theta \right] e^{sX} \left[\frac{\cos \theta}{\sin \theta} \quad -\sin \theta}{\cos \theta} \right] \left[\frac{\sigma}{\sigma_{\theta}} \right]
= \left[\cos \theta \quad \sin \theta \right] \left[\frac{a}{b} \quad b \right] \left[\frac{\cos \theta}{\sin \theta} \quad \cos \theta \right] \left[\frac{\sigma}{\sigma_{\theta}} \right]
= R \left(\cos(2\theta - \theta_0)\sigma - \sin(2\theta - \theta_0)\sigma_{\theta} \right)$$

where $R = \sqrt{a^2 + b^2}$, $\cos \theta_0 = \frac{a}{R}$ and $\sin \theta_0 = \frac{b}{R}$. Also the induced change in the radius of curvature is given by

$$\begin{aligned} \frac{\partial}{\partial s} \Big|_{s=0} \mathfrak{r}[\sigma_s] &= \mathfrak{r} \left[\frac{\partial}{\partial s} \Big|_{s=0} \sigma_s \right] \\ &= R\mathfrak{r}[\cos(2\theta - \theta_0)\sigma - \sin(2\theta - \theta_0)\sigma_\theta] \\ &= -R(3\mathfrak{r}[\sigma]\cos(2\theta - \theta_0) + \mathfrak{r}[\sigma]_{\theta}\sin(2\theta - \theta_0)). \end{aligned}$$

We will also formally consider this the action on all smooth functions $C^{\infty}(S^1)$, not just support functions.

To prove the invariance of spectrum, we will prove the following

$$\frac{d}{ds}\Big|_{s=0} \langle \mathcal{L}_{\sigma_s} f_s, g_s \rangle_{\sigma_s} = 0, \quad \frac{d}{ds}\Big|_{s=0} \langle f_s, g_s \rangle_{\sigma_s} = 0$$

where the action $f_s = e^{sX}f$ is formally extended to $C^{\infty}(S^1)$ using the same formula as for

the support functions. For the first equality,

$$\begin{aligned} \frac{d}{ds} \Big|_{s=0} \left\langle \mathcal{L}_{\sigma_s} f_s, g_s \right\rangle_{\sigma_s} &= \frac{d}{ds} \Big|_{s=0} \int_{S^1} g_s \mathbf{r}[f_s] \\ &= \int_{S^1} \mathbf{r}[f] \frac{\partial}{\partial s} \Big|_{s=0} g_s + g \frac{\partial}{\partial s} \Big|_{s=0} \mathbf{r}[f_s] \\ &= R \int_{S^1} \mathbf{r}[f] (\cos(2\theta - \theta_0)g - \sin(2\theta - \theta_0)g_\theta) \\ &- R \int_{S^1} g(3\mathbf{r}[f] \cos(2\theta - \theta_0) + \mathbf{r}[f]_{\theta} \sin(2\theta - \theta_0)) \\ &= -R \int_{S^1} 2 \cos(2\theta - \theta_0)g\mathbf{r}[f] + \sin(2\theta - \theta_0)(g\mathbf{r}[f])_{\theta} \\ &= -R \int_{S^1} (\sin(2\theta - \theta_0)g\mathbf{r}[f])_{\theta} \\ &= 0 \end{aligned}$$

For the second equality it is enough to do it for f = g because of polarization identity,

$$\frac{d}{ds}\Big|_{s=0} \langle f_s, f_s \rangle_{\sigma_s} = \frac{d}{ds}\Big|_{s=0} \int_{S^1} \frac{\mathbf{r}[\sigma_s]}{\sigma_s} f_s^2$$

$$= \int_{S^1} f^2 \frac{\partial}{\partial s}\Big|_{s=0} \frac{\mathbf{r}[\sigma_s]}{\sigma_s} + 2 \frac{f\mathbf{r}[\sigma]}{\sigma} \frac{\partial}{\partial s}\Big|_{s=0} f_s$$

$$= \int_{S^1} \frac{f^2}{\sigma} \frac{\partial}{\partial s}\Big|_{s=0} \mathbf{r}[\sigma_s] - \frac{f^2\mathbf{r}[\sigma]}{\sigma^2} \frac{\partial}{\partial s}\Big|_{s=0} \sigma_s + 2 \frac{f\mathbf{r}[\sigma]}{\sigma} \frac{\partial}{\partial s}\Big|_{s=0} f_s$$

$$= \int_{S^1} \frac{f^2}{\sigma} (-R) (3\cos(2\theta - \theta_0)\mathbf{r}[\sigma] + \sin(2\theta - \theta_0)\mathbf{r}[\sigma]_{\theta})$$

$$- \int_{S^1} \frac{f^2\mathbf{r}[\sigma]}{\sigma^2} R(\cos(2\theta - \theta_0)\sigma - \sin(2\theta - \theta_0)\sigma_{\theta})$$

$$+ 2 \int_{S^1} \frac{f\mathbf{r}[\sigma]}{\sigma} R(\cos(2\theta - \theta_0)f - \sin(2\theta - \theta_0)f_{\theta})$$

$$= -R \int_{S^1} 2\cos(2\theta - \theta_0) \left(\frac{f^2\mathbf{r}[\sigma]}{\sigma}\right) + \sin(2\theta - \theta_0) \left(\frac{f^2\mathbf{r}[\sigma]}{\sigma}\right)_{\theta}$$

$$= -R \int_{S^1} \left(\sin(2\theta - \theta_0) \frac{f^2\mathbf{r}[\sigma]}{\sigma}\right)_{\theta}$$

$$= 0.$$

This completes the proof of invariance of spectrum of L_{σ_s} since the differential change in inner product is zero implying Rayleigh quotient gives same eigenvalues.

(9/9/24) Let σ be a shrinker for α -GCF and $L_{\sigma}f = \sigma A^{-1}[\sigma]^{jk}A[f]_{jk}$ be the associated elliptic self-adjoint operator for $L_{\sigma}^2 = L^2(\frac{\det A[\sigma]}{\sigma}d\bar{\mu})$ on S^n . Using similar methods like in

the case of curves, we hope to prove that the spectrum of L_{σ} is $SL(n+1,\mathbb{R})$ invariant. The inverse Gauss map is given by

$$X(z) = \sigma(z)z + \overline{\nabla}\sigma(z).$$

Let $L \in \mathfrak{sl}(n+1,\mathbb{R})$ be a symmetric zero trace matrix. Let $X_s = e^{sL} \circ X$ denote the affine boosted hypersurfaces. The variation of the support function is given by

$$\frac{\partial}{\partial s} \Big|_{s=0} \sigma_s(z) = \frac{\partial}{\partial s} \Big|_{s=0} \left\langle e^{sL} X(z), z \right\rangle$$
$$= \left\langle \sigma(z) L(z) + L(\overline{\nabla} \sigma(z)), z \right\rangle$$
$$= \sigma(z) z^T L z + \left\langle \overline{\nabla} \sigma(z), L z \right\rangle$$

where in the last line we use that L is symmetric hence self-adjoint. In the basis $\{\partial_i, z\}$ we can write L as

$$L(\partial_i) = P_i^j \partial_i + Q_i z;$$
 and $L(z) = R^i \partial_i + Sz$

for some P_i^j, Q_i, R^i and S. Observe that $z^T L z = S$ and $z^T L \overline{\nabla} \sigma(z) = Q_i \partial^i \sigma$.

Now we calculate the variation in the operator A_{ij} for the affine boost for an orthonormal basis $\{\partial_i\}$ of S^n at z,

$$\begin{split} \frac{\partial}{\partial s} \Big|_{s=0} A[\sigma_s]_{ij}(z) &= A \left[\frac{\partial}{\partial s} \Big|_{s=0} \sigma_s \right]_{ij}(z) \\ &= \overline{\nabla}_i \overline{\nabla}_j \left(\sigma(z) z^T L z + z^T L \overline{\nabla} \sigma(z) \right) + \delta_{ij} (\sigma(z) z^T L z + z^T L \overline{\nabla} \sigma(z)) \\ &= \left\{ z^T L z \overline{\nabla}_i \overline{\nabla}_j \sigma(z) + 2 \overline{\nabla}_i \sigma(z) \overline{\nabla}_j (z^T L z) + \sigma(z) \overline{\nabla}_i \overline{\nabla}_j (z^T L z) \right\} \\ &+ \overline{\nabla}_i \overline{\nabla}_j z^T L \overline{\nabla} \sigma(z) + \delta_{ij} \left(\sigma(z) z^T L z + z^T L \overline{\nabla} \sigma(z) \right) \\ &= \left\{ S \overline{\nabla}_i \overline{\nabla}_j \sigma(z) + 2 \partial_i \sigma \partial_j S \sigma(z) + \sigma(z) \overline{\nabla}_i \overline{\nabla}_j S \right\} + \overline{\nabla}_i \overline{\nabla}_j Q_k \partial^k \sigma \\ &+ \delta_{ij} \left(S \sigma(z) + Q_k \partial^k \sigma \right) \end{split}$$

(10/9/24) Let σ_s be a variation with $\sigma_0 = \sigma$ a shrinker (so $\mathcal{E}_{\alpha}(\sigma)^{\alpha-1}\sigma = \det A[\sigma]^{-\alpha}$) and $\operatorname{Vol}(\sigma_s) = |B^{n+1}|$. Assume that the variation is given by $\partial_s \sigma = \eta_s$. The constant volume condition implies

$$0 = \partial_s \operatorname{Vol}(\sigma_s) = \int_{S^n} \eta_s \det A[\sigma_s].$$

Differentiating this further gives,

$$0 = \int_{S^n} (\partial_s \eta_s) \det A[\sigma_s] + \eta_s \det A[\sigma_s] A^{-1} [\sigma_s]^{jk} A[\eta_s]_{jk}.$$

The Firey entropy is given by $\mathcal{E}_{\alpha}(\sigma_s) = \left(\frac{|B^{n+1}|}{\operatorname{Vol}(\mathcal{M}^n)}\right)^{\frac{1}{n+1}} \left(\int_{S^n} \sigma_s^{\frac{\alpha-1}{\alpha}} d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}} = \left(\int_{S^n} \sigma_s^{\frac{\alpha-1}{\alpha}} d\bar{\mu}\right)^{\frac{\alpha}{\alpha-1}}$.

The first variation of the Firey entropy is given by

$$\frac{\partial}{\partial s} \mathcal{E}_{\alpha}(\sigma_{s}) = \frac{\partial}{\partial s} \left(\oint_{S^{n}} \sigma_{s}^{1 - \frac{1}{\alpha}} \right)^{\frac{\alpha}{\alpha - 1}}$$

$$= \left(\oint_{S^{n}} \sigma_{s}^{1 - \frac{1}{\alpha}} \right)^{\frac{1}{\alpha - 1}} \left(\oint_{S^{n}} \sigma_{s}^{-\frac{1}{\alpha}} \eta_{s} \right) (= 0 \text{ at } s = 0).$$

The second variation is given by

$$\begin{split} \frac{\partial^{2}}{\partial s^{2}}\Big|_{s=0} \mathcal{E}_{\alpha}(\sigma_{s}) &= \frac{1}{\alpha} \left(\oint_{S^{n}} \sigma^{1-\frac{1}{\alpha}} \right)^{\frac{1}{\alpha-1}-1} \left(\oint_{S^{n}} \sigma^{-\frac{1}{\alpha}} \eta \right)^{2} \\ &+ \left(\oint_{S^{n}} \sigma^{1-\frac{1}{\alpha}} \right)^{\frac{1}{\alpha-1}} \left(\oint_{S^{n}} -\frac{1}{\alpha} \sigma^{-\frac{1}{\alpha}-1} \eta^{2} + \sigma^{-\frac{1}{\alpha}} (\partial_{s} \eta) \right) \\ &= \left(\oint_{S^{n}} \sigma^{1-\frac{1}{\alpha}} \right)^{\frac{1}{\alpha-1}-1} \left\{ \frac{1}{\alpha} \left(\oint_{S^{n}} \sigma^{-\frac{1}{\alpha}} \eta \right)^{2} \\ &+ \mathcal{E}_{\alpha}(\sigma)^{\frac{\alpha-1}{\alpha}} \left(\oint_{S^{n}} \sigma^{1-\frac{1}{\alpha}} \right) \left(\oint_{S^{n}} (\partial_{s} \eta) \det A[\sigma] - \frac{1}{\alpha} \sigma^{-1} \eta^{2} \det A[\sigma] \right) \right\} \\ &= \mathcal{E}_{\alpha}(\sigma) \left(\oint_{S^{n}} (\partial_{s} \eta) \det A[\sigma] - \frac{1}{\alpha} \sigma^{-1} \eta^{2} \det A[\sigma] \right) \\ &= -\mathcal{E}_{\alpha}(\sigma) \left(\oint_{S^{n}} \eta \det A[\sigma] A^{-1} [\sigma]^{jk} A[\eta]_{jk} + \frac{1}{\alpha} \sigma^{-1} \eta^{2} \det A[\sigma] \right) \\ &= -\mathcal{E}_{\alpha}(\sigma) \left(\langle \eta, \mathcal{L}_{\sigma} \eta \rangle_{\sigma} + \left\langle \eta, \frac{\eta}{\alpha} \right\rangle_{\sigma} \right) \\ &= -\frac{\mathcal{E}_{\alpha}(\sigma)}{\alpha} \left\langle \eta, (\alpha \mathcal{L}_{\sigma} + 1) \eta \right\rangle_{\sigma}. \end{split}$$

Thus the stability of a shrinker is decided by the index of $\alpha L_{\sigma} + 1$. Furthermore by Brunn-Minkowski inequality one can prove that

$$\langle \eta, \mathcal{L}_{\sigma} \eta \rangle_{\sigma} = \int_{S^n} \eta \det A[\sigma] A^{-1}[\sigma]^{ij} A[\eta]_{ij} \le n \frac{\left(\int_{S^n} \eta \det A[\sigma] \right)^2}{\int_{S^n} \sigma \det A[\sigma]} = n \frac{\langle \eta, \sigma \rangle_{\sigma}}{\langle \sigma, \sigma \rangle_{\sigma}} = 0.$$

Thus we also have a lower bound,

$$\left. \frac{\partial^2}{\partial s^2} \right|_{s=0} \mathcal{E}_{\alpha}(\sigma) \ge -\frac{\mathcal{E}_{\alpha}(\sigma)}{\alpha} \left\langle \eta, \eta \right\rangle_{\sigma}.$$

For $\sigma = 1$,

$$\frac{\partial^2}{\partial s^2} \Big|_{s=0} \mathcal{E}_{\alpha}(\sigma_s) = -\left(\int_{S^n} \eta(\Delta_{S^n} \eta + n\eta) + \frac{1}{\alpha} \eta^2 \right)$$
$$= -\frac{1}{\alpha} \left(\int_{S^n} (1 + n\alpha) \eta^2 - \alpha |\overline{\nabla} \eta|^2 \right)$$
$$\geq -\frac{1}{\alpha} \int_{S^n} \eta^2.$$

For a spherical harmonic η with $\Delta_{S^n}\eta = -\lambda \eta$, this also gives

$$\left. \frac{\partial^2}{\partial s^2} \right|_{s=0} \mathcal{E}_{\alpha}(\sigma_s) = \left(\lambda - n - \frac{1}{\alpha}\right) \int_{S^n} \eta^2.$$

In particular for $\alpha \in (0, \frac{1}{\lambda - n})$ the sphere is a maxima of the Firey entropy \mathcal{E}_{α} in the space of constant volume convex bodies with respect to spherical harmonic variation η .

We can calculate the same for curvature entropy as well under constant volume variation around a shrinker. The curvature entropy is $E_{\alpha}(\sigma_s) = \left(\int_{S^n} \det A[\sigma]^{1-\alpha} \right)^{\frac{1}{\alpha-1}}$. The first variation is given by

$$\frac{\partial}{\partial s} E_{\alpha}(\sigma_s) = -\left(\oint_{S^n} \det A[\sigma]^{1-\alpha} \right)^{\frac{1}{\alpha-1}-1} \oint_{S^n} \det A[\sigma]^{1-\alpha} A^{-1}[\sigma]^{jk} A[\eta]_{jk}$$
$$= -E_{\alpha}^{2-\alpha} \oint_{S^n} \eta \det A[\sigma] A^{-1}[\sigma]^{jk} A[\det A[\sigma]^{-\alpha}]_{jk}.$$

It follows that

$$\begin{split} \frac{\partial^2}{\partial s^2} \bigg|_{s=0} E_{\alpha}(\sigma_s) &= -E_{\alpha}^{2-\alpha} \oint_{S^n} (1-\alpha) \det A[\sigma]^{1-\alpha} (A^{-1}[\sigma]^{jk} A[\eta]_{jk})^2 \\ &+ E_{\alpha}^{2-\alpha} \oint_{S^n} \det A[\sigma]^{1-\alpha} A^{-1}[\sigma]^{jp} A[\eta]_{pq} A^{-1}[\sigma]^{qk} A[\eta]_{jk} \\ &- E_{\alpha}^{2-\alpha} \oint_{S^n} (\partial_s \eta) \det A[\sigma] A^{-1}[\sigma]^{jk} A[\det A[\sigma]^{-\alpha}]_{jk} \\ &= -E_{\alpha} \oint_{S^n} (1-\alpha) \sigma \det A[\sigma] (A^{-1}[\sigma]^{jk} A[\eta]_{jk})^2 \\ &+ E_{\alpha} \oint_{S^n} \sigma \det A[\sigma] |A[\eta]|_{A[\sigma]}^2 + n E_{\alpha} \oint_{S^n} \eta \det A[\sigma] A^{-1}[\sigma]^{jk} A[\eta]_{jk} \\ &= E_{\alpha} \left((\alpha-1) \left\langle \sigma^2, \operatorname{tr}(A[\eta])_{A[\sigma]}^2 \right\rangle_{\sigma} + \left\langle \sigma^2, |A[\eta]|_{A[\sigma]}^2 \right\rangle_{\sigma} + n \left\langle \eta, \mathcal{L}_{\sigma} \eta \right\rangle_{\sigma} \right). \end{split}$$

(11/9/24)