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On complex plain complex Random variables has 2 Real random variables

$$Z = Z_R + j Z_I \quad \begin{matrix} \text{complex normal} \\ \text{random variable} \end{matrix}$$

$$\begin{matrix} N(0, 1) \\ N(0, 1) \end{matrix} \quad \begin{matrix} N(0, \frac{1}{2}) \\ N(0, \frac{1}{2}) \end{matrix}$$

$$\mathbb{E}[Z] = 0 \quad (0 + j 0)$$

$$\mathbb{E}[|Z|^2] = 1/2 + 1/2 = 1$$

$$\hookrightarrow \mathbb{E}[Z\bar{Z}] = \mathbb{E}(Z_R^2 + Z_I^2) = \frac{1}{2} + \frac{1}{2} = 1$$

$$n(t) = n_R(t) + j n_I(t)$$

$$\frac{\downarrow}{N_0} \quad \frac{\downarrow}{N_0}$$

Complex Ang N process

~~23-1-19~~

Recap

→ Complex Dimensions

- All PSK have 1 complex and 2 real dimensions, there is no "orthogonality"

$$\psi_1 e^{j\pi/4} = \psi_1 \begin{bmatrix} 1 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

→ Complex N. R. L. S. W. D. P. T. A. V.

for $Z = Z_R + j Z_I$

$$\begin{matrix} N(0, \frac{1}{2}) \\ N(0, \frac{1}{2}) \end{matrix}$$

$$C_Z = \frac{1}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{IF}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$$

And X, Y are jointly Gaussian \Rightarrow

x, y are Independent

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→ for Complex Noise

CMLX WGN

$$N_0 = kT$$

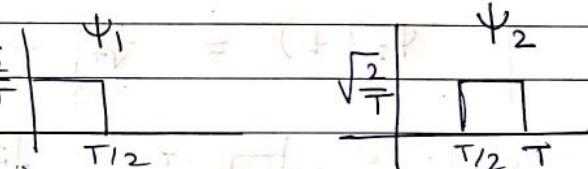
↳ Boltzmann const $\propto T/k$

Signal Space Concept

(ex 1)

Given the basis

$$S_i = \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix}$$



$$S_1 = \sqrt{\frac{2}{T}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$S_2 = \sqrt{\frac{2}{T}} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$S_3 = \sqrt{\frac{2}{T}} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Algorithm to obtain an ~~base~~ orthonormalization

Gramm - Schmidt

$$\psi_1(t) = \frac{s_1(t)}{\|s_1(t)\|} \quad \int_{-\infty}^{\infty} \|s_1(t)\|^2 dt$$

$$\phi_2(t) = s_2(t) - \langle \psi_1, s_2 \rangle \psi_1$$

$$\psi_2(t) = \frac{\phi_2(t)}{\|\phi_2(t)\|}$$

Normalize ...

→ Applied to ex 1

$$\psi_1(t) = \sqrt{\frac{1}{T}} \begin{cases} 1 & 0 \leq t < T \\ 0 & \text{otherwise} \end{cases}$$

$$\psi_2(t) = \frac{1}{\sqrt{T}} \begin{cases} 1 & 0 \leq t < T \\ -1 & T \leq t < 2T \\ 0 & \text{otherwise} \end{cases} = \frac{\sqrt{2}}{\sqrt{T}} \frac{1}{\sqrt{2}} \times \begin{cases} 1 & 0 \leq t < T \\ -1 & T \leq t < 2T \\ 0 & \text{otherwise} \end{cases}$$

$$\psi_2(t) = \frac{1}{\sqrt{T}} \begin{cases} 1 & 0 \leq t < T \\ -1 & T \leq t < 2T \\ 0 & \text{otherwise} \end{cases} = \frac{\sqrt{2}}{\sqrt{T}} \frac{1}{\sqrt{2}} \begin{cases} 1 & 0 \leq t < T \\ -1 & T \leq t < 2T \\ 0 & \text{otherwise} \end{cases}$$

→ The final basis is not unique ...

Effect of Noise

$$\rightarrow s(t) \xrightarrow[\psi_1]{\text{cor}} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$s(t) \xrightarrow[\psi_2]{\text{cor}} \frac{1}{\sqrt{2}} \begin{bmatrix} 0.74 \\ 0.62 \end{bmatrix}$$

$$s_i = s_i^o + n$$

$$\underline{I}_{\langle n, u \rangle} = \int_{-\infty}^{\infty} n(\tau) u^*(\tau) d\tau = A \text{ Random variable}$$

where $u(t)$ is any finite energy square integrable signal

$$\int_{-\infty}^{\infty} |u(t)|^2 dt < \infty$$

$\rightarrow \psi_i$'s form an orthonormal basis

$$\langle \psi_i, \psi_i \rangle \text{ is finite } (= 1)$$

$$\langle \psi_i, \psi_j \rangle = \delta_{ij}$$

$$\rightarrow \langle n, \psi_i \rangle = \int_{-\infty}^{\infty} n(t) \psi_i(t) dt :$$

= Gaussian r.v (Property of G.R.P)
(Zero mean)

$$IE [\langle n, \psi_i \rangle \langle n^*, \psi_i \rangle]$$

ψ_i is real

$$= IE \left[\int_{-\infty}^{\infty} n(t) \psi_i(t) dt \int_{-\infty}^{\infty} n^*(\tau) \psi_i(\tau) d\tau \right]$$

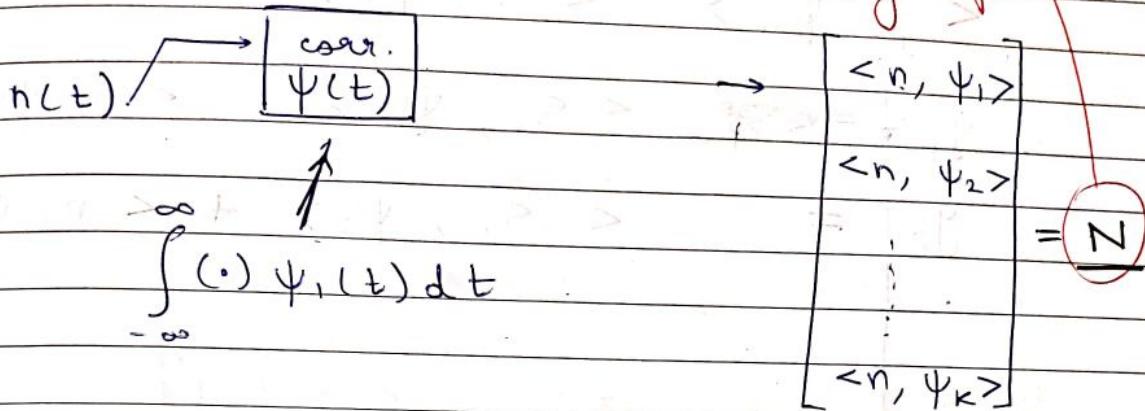
$$= E \left[\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} n(t) n^*(\tau) \psi_i(t) \psi_i(\tau) dt d\tau \right]$$

$$= E \left[\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} N_0 S(t - \tau) \psi_i(t) \psi_i(\tau) dt d\tau \right]$$

Since $\langle \psi_i, \psi_i \rangle = 1$

$$E[n] = N_0 \times 1 \quad \text{N is Noise vector in}$$

\Rightarrow Variance σ^2 or N_0 . Sig. Spat.



$= \text{cov} = \sigma^2$ or N_0 k-dimensional jointly Gaussian r.v., mean 0, Cov?

In fact, they are all IID

Proof

$$\begin{aligned} & E[\langle n, \psi_1 \rangle \langle n, \psi_2 \rangle] \\ &= E\left[\int_{-\infty}^{\infty} n(t) \psi_1(t) dt \int_{-\infty}^{\infty} n^*(\tau) \psi_2(\tau) d\tau \right] \\ &= E\left[\int_{-\infty}^{\infty} \underbrace{\int_{-\infty}^{\infty} n(t) n^*(\tau)}_{\delta(t-\tau)} \psi_1(t) \psi_2(\tau) d\tau \right] \\ & \qquad \qquad \qquad = \langle \psi_1, \psi_2 \rangle = 0 \end{aligned}$$

$N_0 \rightarrow$ Noise per Complex Dimension

$\frac{N_0}{2} \rightarrow$ Noise per Real Dimension

→ So what is going on?

- We are projecting Noise onto an orthonormal vector space

$$y(t) = s_i(t) + n(t)$$

 s_i N

$$\underline{y} \cdot \underline{\psi_i} = [\langle s_i, \psi_i \rangle^i + \langle n, \psi_i \rangle]$$

$$y_1 = \cancel{\langle s_i, \psi_i \rangle} + \langle n, \psi_1 \rangle$$

$$y_2 = \langle s_i, \psi_2 \rangle + \langle n, \psi_2 \rangle$$

$$\vdots \quad \vdots$$

$$y_k = \langle s_i, \psi_k \rangle + \langle n, \psi_k \rangle$$

→ We went from : Which Waveform was sent?

To → Which vector was sent

→ What Information have we lost? Was the Info useful?

$$\underline{y} = \underline{s_i} + \underline{N}$$

$$n(t) \rightarrow N = \begin{bmatrix} N(1) \\ \vdots \\ N(k) \end{bmatrix}$$

→ So we have lost the Component of Noise orthogonal to $n(t)$ in the higher / Infinite dimensional vector space

Does this Info lost being
lost create problems?

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$$n^+(t) = n(t) - \sum_{i=1}^k N[i] \psi_i(t)$$

$$\begin{aligned} y^+(t) &= y(t) - \sum_{j=1}^k \langle y, \psi_j \rangle \psi_j(t) \\ &= s_i(t) + n(t) - \sum_{j=1}^k (\cancel{\langle s_i, \psi_j \rangle} + \cancel{\langle n, \psi_j \rangle}) \psi_j(t) \\ y^+(t) &= n^+(t) \end{aligned}$$

$$\mathbb{E}[n^+(t) N[k]] = \mathbb{E}[n^+ \langle n, \psi_k \rangle] \rightarrow 0$$

Hence, The Information lost has no part to play in $y = \underline{s_i} + \underline{N}$

BPSK



Vector Space Rep. (Detection problem)

$$\begin{aligned} s_1(t) &\\ s_2(t) &\\ \vdots &\\ s_M(t) & \end{aligned} \quad \left. \begin{aligned} s_i(t) \\ \oplus \\ n(t) \end{aligned} \right\} \rightarrow s(t) = \underline{s_i(t)} + \underline{n(t)}$$

$$s_i \rightarrow g_i = \underline{s_i} + \underline{N}$$

$$s_i(t) = s_{i1} \psi_1(t) + s_{i2} \psi_2(t)$$

$$+ \dots + s_{ik} \psi_k(t)$$

$$\underline{N} = \begin{bmatrix} < n, \psi_1 > \\ & \vdots \\ & & < n, \psi_k > \end{bmatrix} \xrightarrow{\text{CN}(0, \sigma^2 I)}$$

$$< r(t) - \sum r_j \psi_j(t)$$

$$= n^\perp(t) = n(t) - \sum_{j=1}^k N[j] \psi_j(t)$$

$\rightarrow r(t)$ projected onto $\vec{\psi}$

$$= E \left[\int_{-\infty}^t n^\perp(\tau) N^*[k] d\tau \right] = E \left[n^\perp(t) \int_{-\infty}^t n^*(\tau) N^*[k] d\tau \right]$$

$$= E \left[n(t) \int_{-\infty}^t n^*(\tau) \psi_k(\tau) d\tau \right] - E \left[\sum_{j=1}^k N[j] N^*[k] \right]$$

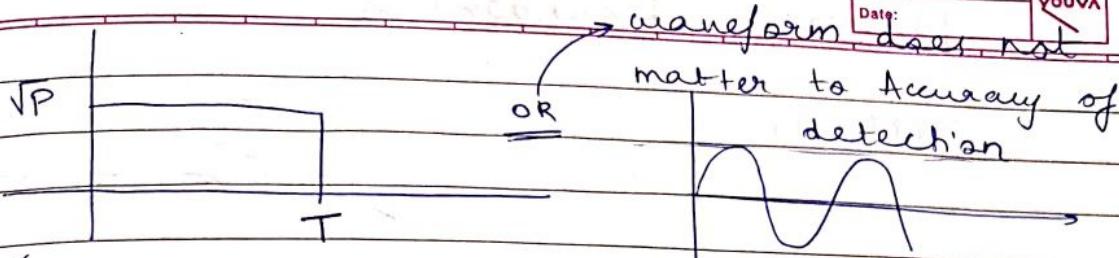
$$= E \left[\left(n(t) - \sum_{j=1}^k N[j] \psi_j(t) \right) \int_{-\infty}^t n^*(\tau) \psi_k(\tau) d\tau \right]$$

$$= E \left[n(t) N^*[k] \right] - \sum_{j=1}^k E \left[N[j] N^*[k] \right] \underbrace{\psi_j(t)}_{N^*[k]}$$

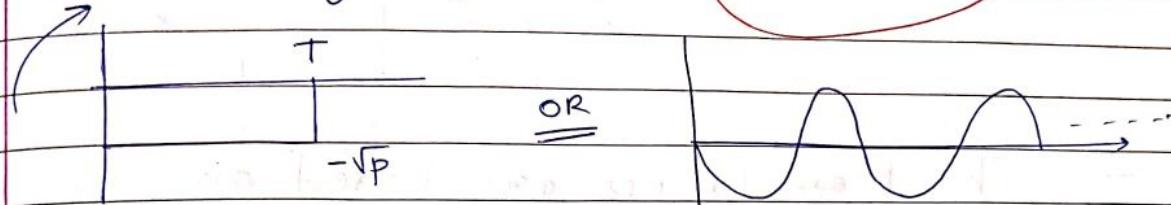
$$= E \left[n(t) N^*[k] \right] - \sigma^2 \psi_k(t)$$

ex BPSK

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The only difference is Bandwidth Chap 2



$$\vec{r} = \vec{s}_i + \vec{N}$$

$\rightarrow CN(0, \sigma^2 I)$
 $\sigma^2 = N_0$

Why?

Since ψ is taken
to be dimensionless

Hypothesis Testing

→ The maximum likelihood rule

$$f_{\vec{N}}(\vec{N}) = C \exp \left(-\frac{(\vec{r} - \vec{s}_i)^H (\vec{r} - \vec{s}_i)}{N_0} \right)$$

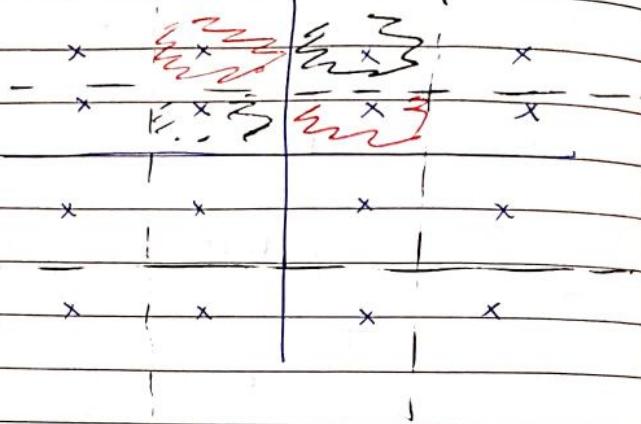
Independent of s and r

$$\text{argmax}_{i=1, \dots, M} e^{-\frac{\|\vec{r} - \vec{s}_i\|^2}{N_0}} = \arg \min_{i=1, 2, \dots, M} \|\vec{r} - \vec{s}_i\|^2$$

Decision Boundaries

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→ The boundaries are based on euclidean distance because of Gaussian Density

- Is the MLE Optimal? No!

ex Consider non-equiprobable s_i 's

Minimize probability of error,

$s_1 \rightarrow \pi(1)$ MPE rule

$$\arg \min_{1 \leq i \leq M} \|r - s_i\|^2 - 2\sigma^2 \log \pi(i)$$

$s_M \rightarrow \pi(M)$

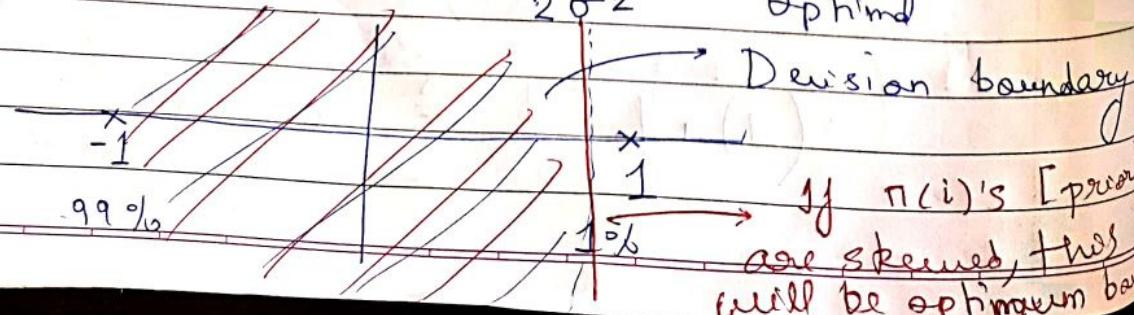
4.2.1

→ Corrected MLE problem

$$\text{Max } \pi(i) e^{-\|r - s_i\|^2 / 2\sigma^2}$$

Case 1

$$\log \pi(i) - \frac{\|r - s_i\|^2}{2\sigma^2} \text{ Optimized}$$



If $\pi(i)$'s are skewed, they will be optimum boundary.

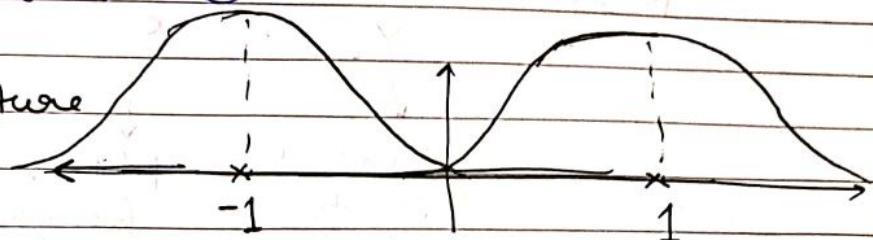
Case 2

Case 3

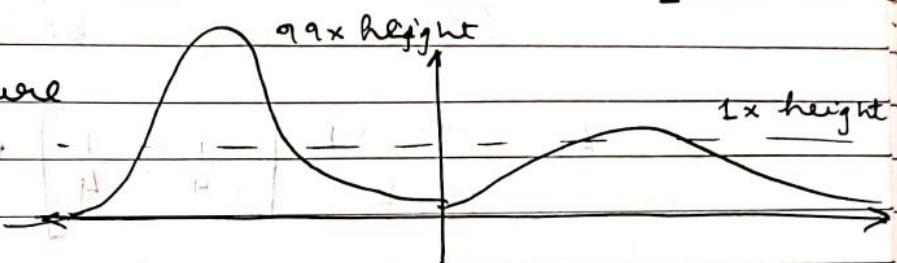
$$P(1 \text{ sent} | \vec{s}) = P(\vec{s} | 1 \text{ sent}).$$

$$= \pi(1) e^{-\frac{\|\vec{s} - \vec{s}_0\|^2}{N_0}}$$

→ The wrong picture



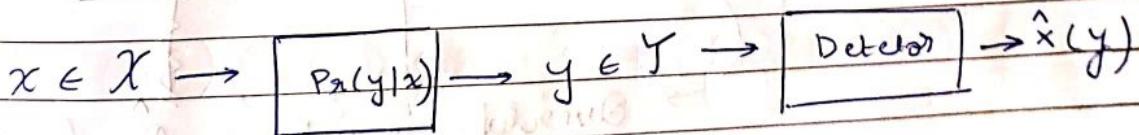
→ The Right picture



- For ~~non~~ equiprobable s_i 's (Symbols)
then Maximum likelihood (Geometric)
= Min. Prob. of error

Since $\pi(i) = \frac{1}{M}$ (Independent) MLE = MAP
when $\pi(i) = \frac{1}{M}$

Recap: Receivers and Estimators



Case 1
Detection - X countable $\hat{x}(y) \in \{1, \dots, M\}$
→ like an MCQ

Case 2
Estimation - X real valued $\in \mathbb{R}^m$
→ like a fill in the blank problem
Probability measure

Case 3
Soft Detection - $\hat{x}(y) = (\hat{x}, p_{\hat{x}}(\hat{x}))$
 $\forall \hat{x} \in X$

Q → Estimating Student height (An estimation problem)

Model

$$Y_i = \theta + Z_i$$

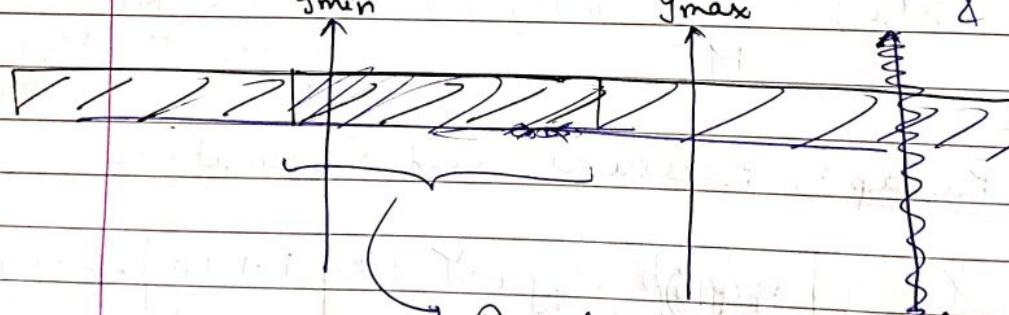
↓ ↓

Student heights Mean height to
 (Oleseunale) be estimated

$$Z_i \sim U \left[-\frac{1}{4}, \frac{1}{4} \right] \text{ meters}$$

Problem : Estimate θ

Say we take Readings, and the min & max are



Overlap is where θ lies

→ Objective

Map Decoder

→ Probability of Correctness

$$\Pr(C) \triangleq 1 - \Pr(E)$$

$$x \rightarrow \boxed{\quad} \quad y \in \mathcal{Y}$$

$\hat{x}(y) = x$

$$\Pr(C) = \sum_{i=1}^M \Pr(C, x_i)$$

$$= \sum_{i=1}^M \Pr(i) \Pr(C | x_i)$$

$\downarrow \pi(i)$

$$\Pr(C) = \sum_{i=1}^M (\pi(i)) \Pr(C | x_i)$$

$$= \sum_{i=1}^M \pi(i) \int_{\mathcal{Y}} \Pr(y | i) dy$$

$y \in \mathcal{D}_i$

$$= \sum_{i=1}^M \int_{\mathcal{Y}} \pi(i) \Pr(y | i) \mathbf{1}_{\{y \in \mathcal{D}_i\}} dy$$

$$= \int_{\mathcal{Y}} \sum_{i=1}^M \pi(i) \Pr(y | i) \mathbf{1}_{\{y \in \mathcal{D}_i\}} dy$$

$$\leq \int_{\mathcal{Y}} \left(\sum_{i=1}^M \max_{1 \leq j \leq M} \pi(j) \Pr(y | j) \right) \mathbf{1}_{\{y \in \mathcal{D}_i\}} dy$$

$$\int_{y \in Y} \left(\max_{1 \leq j \leq m} \pi(j) \Pr(y|j) \right) \sum_{i=1}^M 1$$

↓
1

$$\Pr(C) \leq \int_{y \in Y} \max_i (\pi(i) \Pr(y|i)) dy$$

$$= \sum_{i=1}^m \pi(i) \int_{y \in Y \setminus A_i} \Pr(y|i) dy$$

→

where,

$$A_i = \{y \in Y_i \mid \pi(i) \Pr(y|i) > \pi(j) \Pr(y|j) \quad \forall i \neq j\}$$

→ MAP : Maximum A posteriori Prob. Decoder

Signal Space

$$s(t) = \sum_{i \in I} d_i \phi_i(t)$$

$$\langle \phi_i(t), \phi_j(t) \rangle = \delta(i-j) \quad \text{"Orthogonal"}$$

Example

→ (i) Bandlimited Signals

$$\phi_m(t) = \operatorname{sinc} \frac{\beta}{\pi} \left(t - \frac{m}{\beta} \right) \quad t \in \mathbb{R}$$

→ (ii) Time limited waveforms

8.5.2.19

ML Decision Rule

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Protocol

$$\text{arg min}_i \| \mathbf{y} - \mathbf{s}_i \mathbf{s}_i^H \|^2 = \text{arg min}_i (\| \mathbf{y} \|^2 + \| \mathbf{s}_i \|^2 - 2 \operatorname{Re} \langle \mathbf{y}, \mathbf{s}_i \rangle)$$

$$= \text{arg max}_i \left(\operatorname{Re} \langle \mathbf{y}, \mathbf{s}_i \rangle - \frac{\| \mathbf{s}_i \|^2}{2} \right) \rightarrow \begin{array}{l} \text{ML Decision} \\ \text{rule for Gaussian} \\ \text{Distribution} \end{array}$$

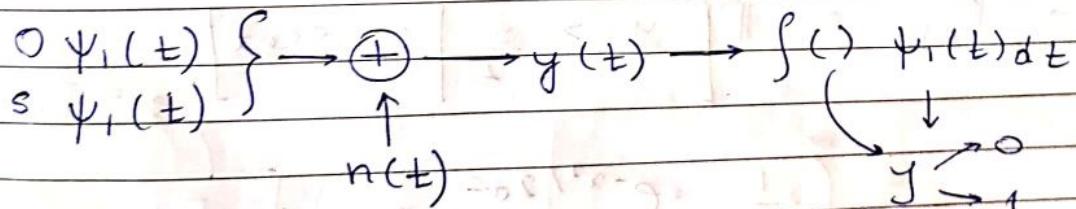
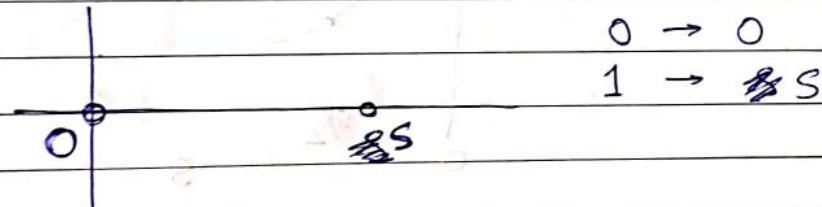
MEP (Minimum Error prob./MAP)

$$\operatorname{Re} \langle \mathbf{y}, \mathbf{s}_i \rangle - \frac{\| \mathbf{s}_i \|^2}{2} + \sigma^2 \log(\pi_i)$$

↓ Noise Variance

On-Off Keying

OOK + AWGN Channel



For now, consider this 1-D problem

Probability of Error, $P(\text{Error})$

$$P_e = P_{\text{0 sent}} \times \frac{1}{2} + P_{\text{1 sent}} \times \frac{1}{2}$$

$\downarrow \pi(0) \qquad \downarrow \pi(1)$

$$H_1: y(t) = s + n(t)$$

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$$H_0: y(t) = n(t)$$

$$\text{Cymax}_i : \langle y, s_i \rangle - \frac{\|s_i\|^2}{2}$$

$$0 \rightarrow 0 - 0 = 0$$

$$1 \rightarrow sy - \frac{s^2}{2}$$

$= 0, \Rightarrow \text{bound. } @ s$

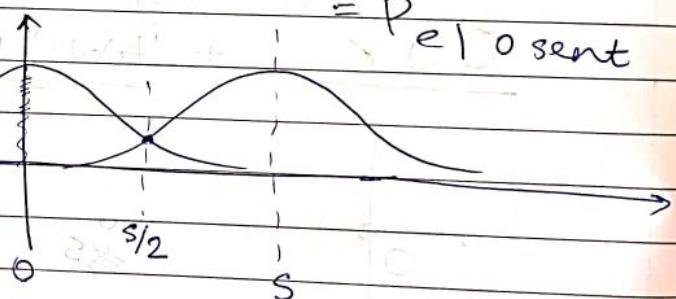
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$$\# P_{e|1 \text{ sent}} = P \left[z < \frac{\|s\|^2}{2} \mid H_1 \right]$$

$$\rightarrow P \left[sy < \frac{s^2}{2} \mid H_1 \right] = P \left[y < \frac{s}{2} \mid 1 \text{ sent} \right]$$

$= P_{e|0 \text{ sent}}$

Bin



$$0 \rightarrow P_{e|0} = P \left[y > \frac{s}{2} \mid 0 \text{ sent} \right]$$

$= P_e \text{ abs}$

$$= \int_{s/2}^{\infty} \frac{1}{\sigma \sqrt{2\pi}} e^{-x^2/2\sigma^2} dx = Q \left(\frac{s}{2\sigma} \right)$$

$$\text{Where, } Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^{\infty} e^{-z^2/2} dz$$

$$\text{BER for OOK} = Q \left(\frac{s}{2\sigma} \right)$$

Since 1 bit/s
BER = P_e

Bit Error Rate

$$\frac{1}{2} P_{e11} = \frac{1}{2} P_{e10}$$

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$$\Rightarrow P_e = P_{e11}$$

Define

E_s : Energy per symbol

E_b : Energy per bit

$$\rightarrow \text{for QPSK Average } E_b = \frac{s^2}{2} \left(\frac{1}{2} \times s^2 + \frac{1}{2} \times 0 \right)$$

$$E_b = \frac{s^2}{2}, \quad s = \sqrt{2E_b} \quad \text{with } E_b = \frac{s^2}{2}$$

$$Q\left(\frac{s}{2\sigma}\right) = s \left(\sqrt{\frac{E_b}{2\sigma^2}} \right) = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

Binary Signalling

$$s_1(t) \rightarrow s_1, H_1: y(t) = s_1(t) + n(t)$$

$$s_2(t) \rightarrow s_2, H_2: y(t) = s_2(t) + n(t)$$

$$E_b = \frac{s_1^2 + s_2^2}{2}$$

$$\left[\frac{\langle y, s_1 \rangle - \|s_1\|^2}{2} \right] \stackrel{H_1}{>} \left[\frac{\langle y, s_2 \rangle - \|s_2\|^2}{2} \right]$$

$$\left[\frac{\langle y, s_1 - s_2 \rangle}{2} \right] \stackrel{H_1}{>} \left[\frac{\|s_1\|^2 - \|s_2\|^2}{2} \right]$$

$$\tilde{y}(t) = y(t) - s_2(t)$$

$$\tilde{y} = y - s_2$$

$$H_1: \tilde{y}(t) = s_1(t) - s_2(t) + n(t)$$

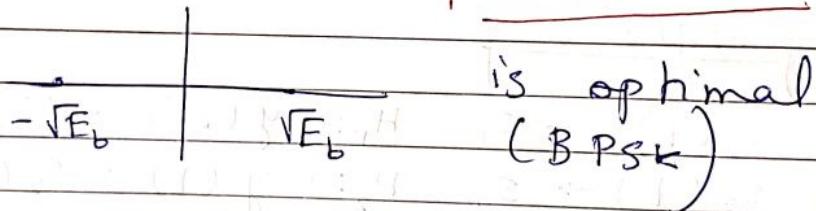
$$H_0: \tilde{y}(t) = n(t)$$

$$\rightarrow \text{Constraint: } E_b = \frac{s_1^2 + s_2^2}{2} \leq E_b$$

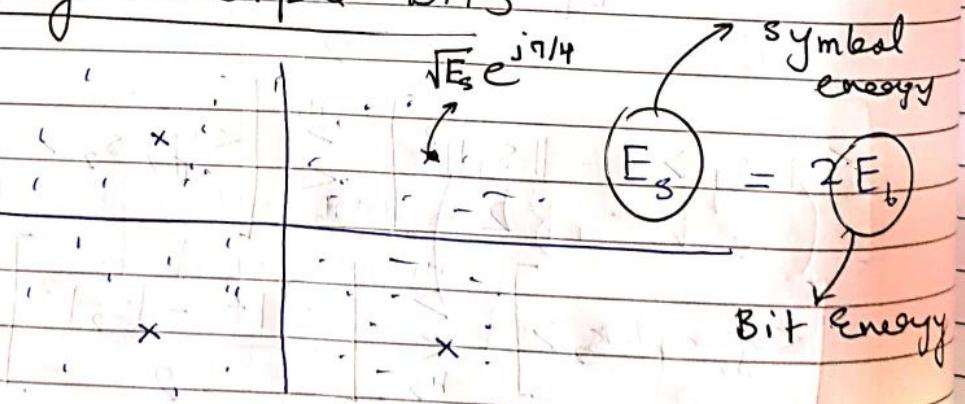
$$Q\left(\frac{|s_1 - s_2|}{2\sigma}\right) \rightarrow \text{BER} \quad \begin{matrix} \text{minimize} \\ \text{maximize } |s_1 - s_2| \end{matrix}$$

$$\text{Subject to } \frac{s_1^2 + s_2^2}{2} \leq E_b \quad \text{subject to}$$

$$\therefore \text{BER}_{\min} \text{ soln} = \left[-\sqrt{\frac{E_b}{2}}, \sqrt{\frac{E_b}{2}} \right]$$



\rightarrow Sending Multiple Bits



\rightarrow Symbol Error Rate same for all 4

For QPSK $E_s = 2E_b$

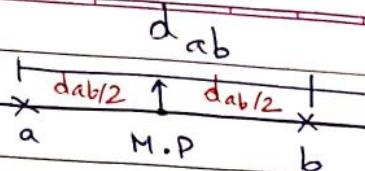
use this in Calculations

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$\pi(i)$'s are eq

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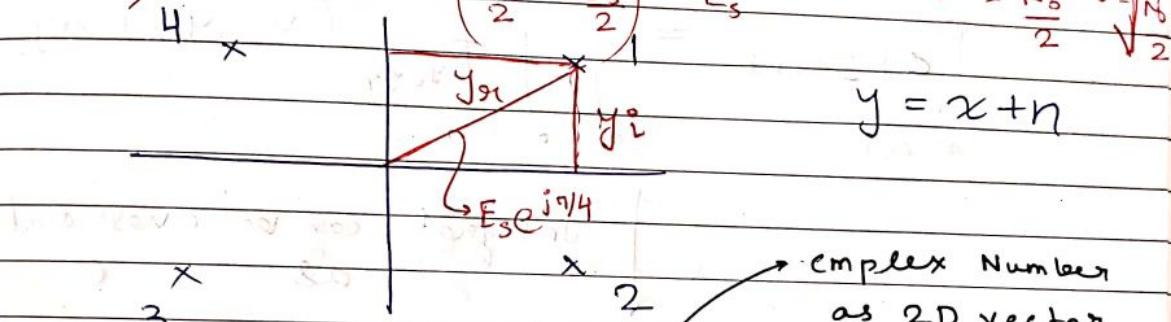


$$P_e = Q\left(\frac{d_{ab}}{2\sigma}\right)$$

$$a, b = + \sqrt{E_b}, - \sqrt{E_b}, \sigma^2 = N_0$$

$$Q\left(\frac{\sqrt{2E_b}}{N_0}\right) \quad P_e = Q\left(\frac{\sqrt{2E_b}}{N_0}\right) \quad Q\left(\frac{\sqrt{E_b}}{\sigma}\right)$$

$$\left(\frac{E_s^2}{2} + \frac{E_s^2}{2}\right) = E_s^2 \quad \sigma^2 = \frac{N_0}{2} \quad \sigma = \sqrt{\frac{N_0}{2}}$$



$$y = x + n$$

$$\begin{bmatrix} y_R \\ y_i \end{bmatrix} = \begin{bmatrix} \sqrt{\frac{E_s}{2}} \\ \sqrt{\frac{E_s}{2}} \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \end{bmatrix}$$

mean

$$\text{cov}_\text{var} \quad \left(\sigma^2 = \frac{N_0}{2} \right)$$

$$\begin{bmatrix} y_R \\ y_i \end{bmatrix} \sim \mathcal{N}(0, I) \rightarrow \text{jointly Gaussian}$$

jointly Gaussian

Mean changes, Cov same. (on shift)

$$\text{mean} = \begin{bmatrix} \sqrt{\frac{E_s}{2}} \\ \sqrt{\frac{E_s}{2}} \end{bmatrix}$$

$$\text{cov} = \begin{bmatrix} N_0/2 & 0 \\ 0 & N_0/2 \end{bmatrix}$$

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$$f_{y_i y_n} (y_i, y_n)$$

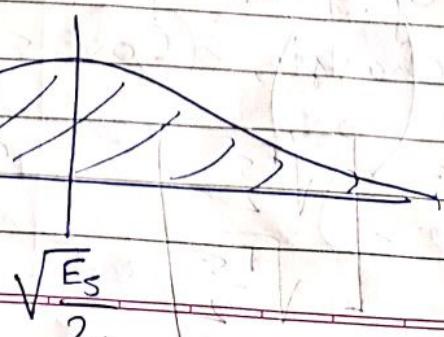
$$= \frac{1}{\frac{N_0}{2} \cdot 2\pi} \exp \left(-\|\vec{y} - \left(\begin{pmatrix} \sqrt{\frac{E_S}{2}} \\ \sqrt{\frac{E_S}{2}} \end{pmatrix} \right)\|^2 \right)$$

$$P_{\text{sent}} = \int_0^{\infty} \int_0^{\infty} f_{y_i y_r}(y_i, y_r) dy_i dy_r$$

Integral can be evaluated as

$$\left(\frac{1}{(2\pi \cdot N_0)^{\frac{1}{2}}} \right) \int_0^{\infty} \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{N_0}} \exp \left(- \frac{(y_i - \sqrt{\frac{E_S}{2}})^2}{N_0} \right) dy_i \cdot \int_0^{\infty} \exp \left(- \frac{(y_r - \sqrt{\frac{E_S}{2}})^2}{N_0} \right) dy_r$$

$$I = \int_0^{\infty} \frac{1}{\sqrt{\pi N_0}} \exp \left(- \left(y_r - \sqrt{\frac{E_s}{2}} \right)^2 \right) dt$$



$$\text{Using } Q(-x) = 1 - Q(x)$$

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$$= \left(1 - Q \left(\sqrt{\frac{E_s}{N_0}} \right) \right)^2$$

$$P_{e|1\text{ sent}} = 1 - P_{c|1\text{ sent}}$$

$$= 1 - ()^2$$

~~$$= 2Q \left(\sqrt{\frac{E_s}{N_0}} \right)^2 - Q^2$$~~

$$= 2Q \left(\sqrt{\frac{E_s}{N_0}} \right) - Q^2 \left(\sqrt{\frac{E_s}{N_0}} \right)$$

$$P_{\text{total errors}} = P_e = P_{e|1\text{ sent}}$$

$$P_e = 2Q \left(\sqrt{\frac{2E_b}{N_0}} \right) - Q \left(\left(\sqrt{\frac{2E_b}{N_0}} \right)^2 \right)$$

Using $E_b = \frac{E_s}{2}$ Exact expression.

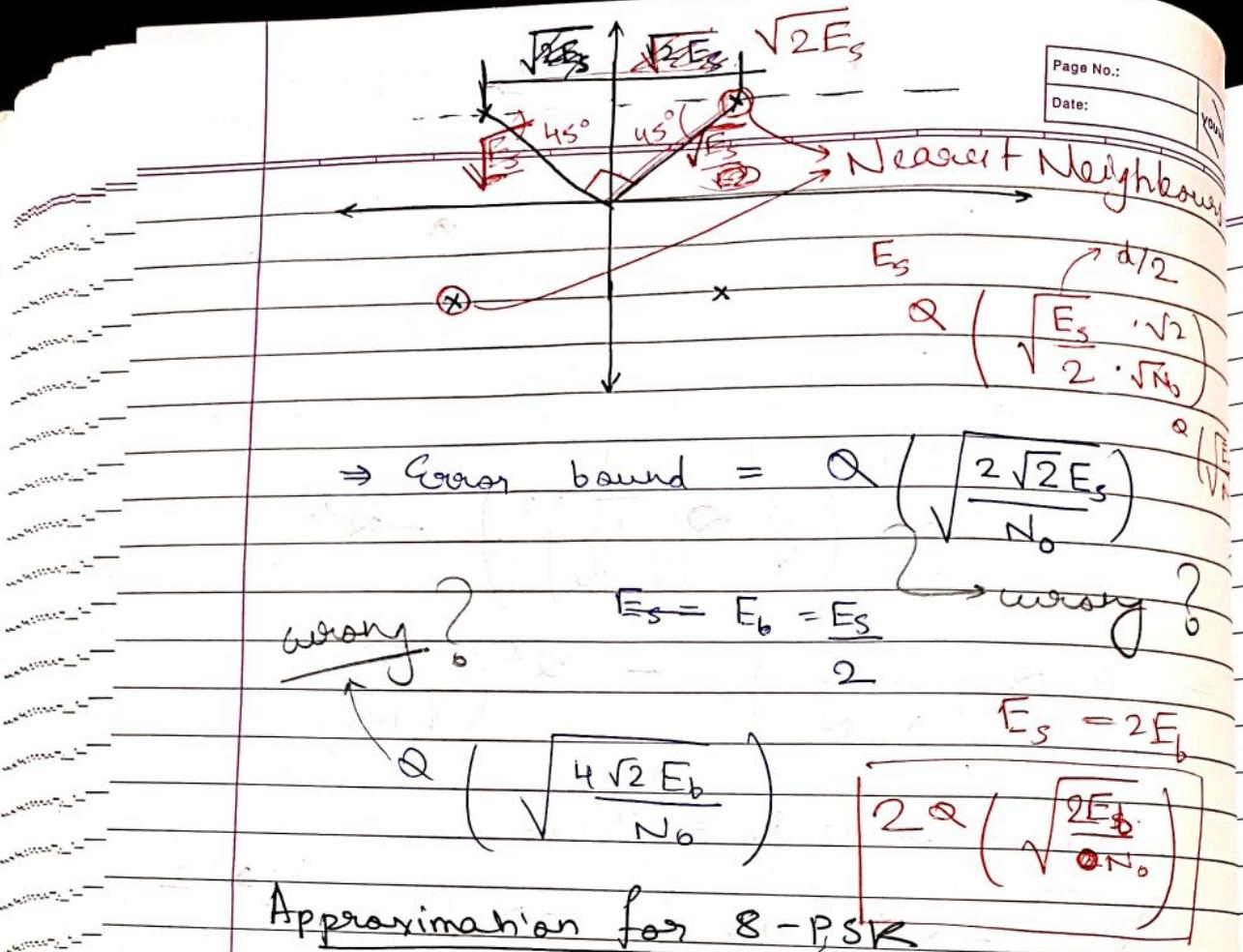
Probability of Error using Union bound



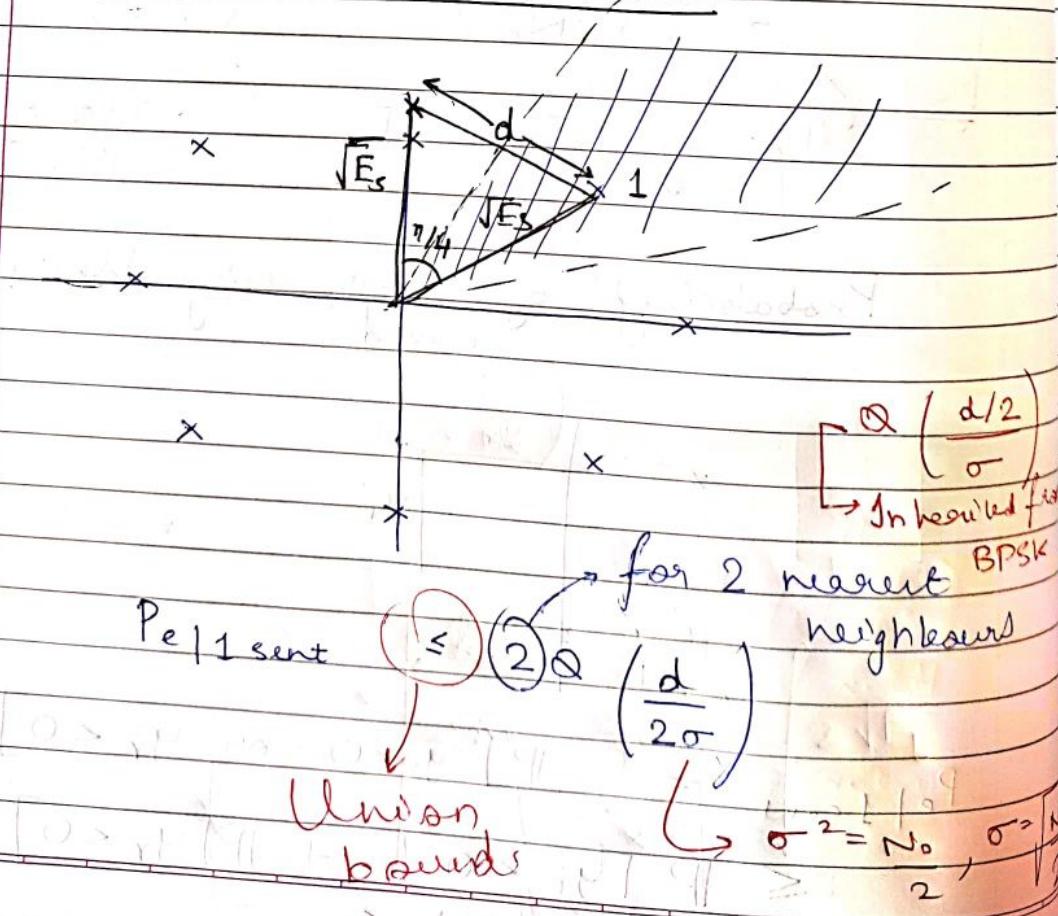
$$P_{e|1\text{ sent}} = \Pr [y_i < 0 \text{ or } y_r < 0]$$

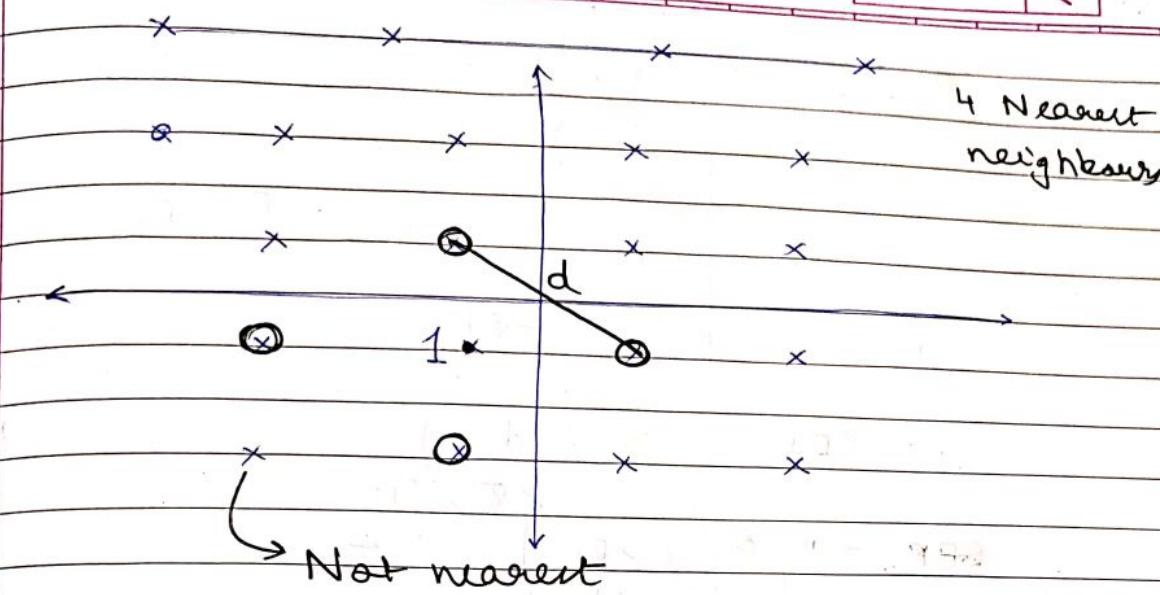
$$\leq \Pr [y_i < 0] + \Pr [y_r < 0]$$

Given 1 sent



Approximation for 8-PSK





$$P_{e \mid 1 \text{ sent}} = 4 \times Q \left(\frac{\sqrt{2d}}{\sqrt{N}} \right)$$

↓
4 NN

$$\textcircled{R} P_{e \mid 1 \text{ sent}} = P_e \text{ (symmetry)}$$

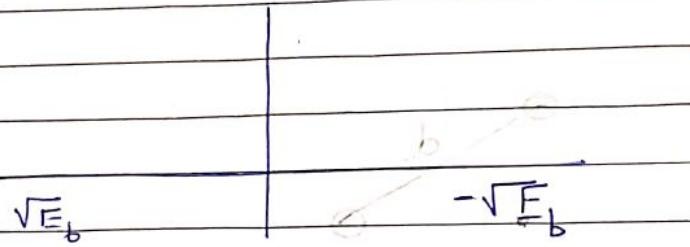
$$\Rightarrow P_e \leq M Q \left(\frac{d/2}{\sigma} \right)$$

→ No. of nearest
neighbours.

11.2.1a

BER / SER

→ Binary Signalling



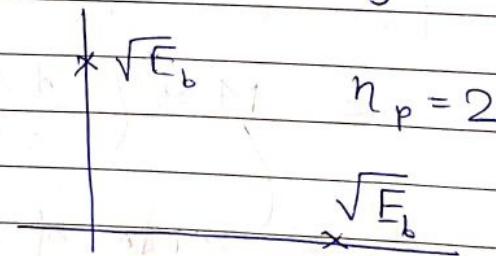
$$E_s = E_b$$

$$BER = Q\left(\frac{d}{2\sigma}\right)$$

$$BER = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

$$Q\left(\sqrt{\frac{n_p E_b}{2 N_0}}\right)$$

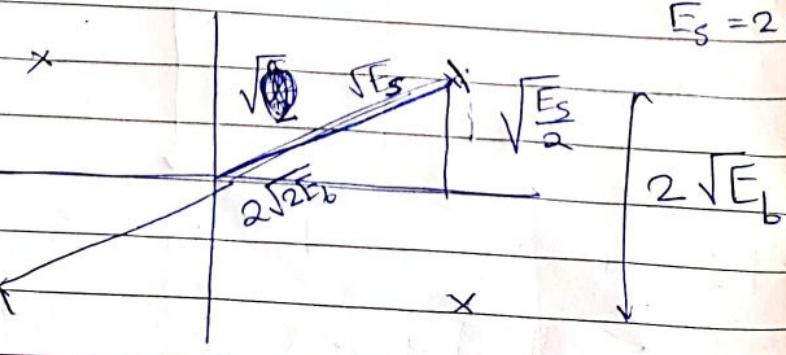
→ Orthogonal Signalling



$$BER = Q\left(\sqrt{\frac{E_t}{N_0}}\right)$$

→ QPSK

$$E_s = 2E_b$$



$$SER = 2Q\left(\sqrt{\frac{2E_b}{N_0}}\right) - Q\left(\sqrt{\frac{2E_b}{N_0}}\right)^2$$

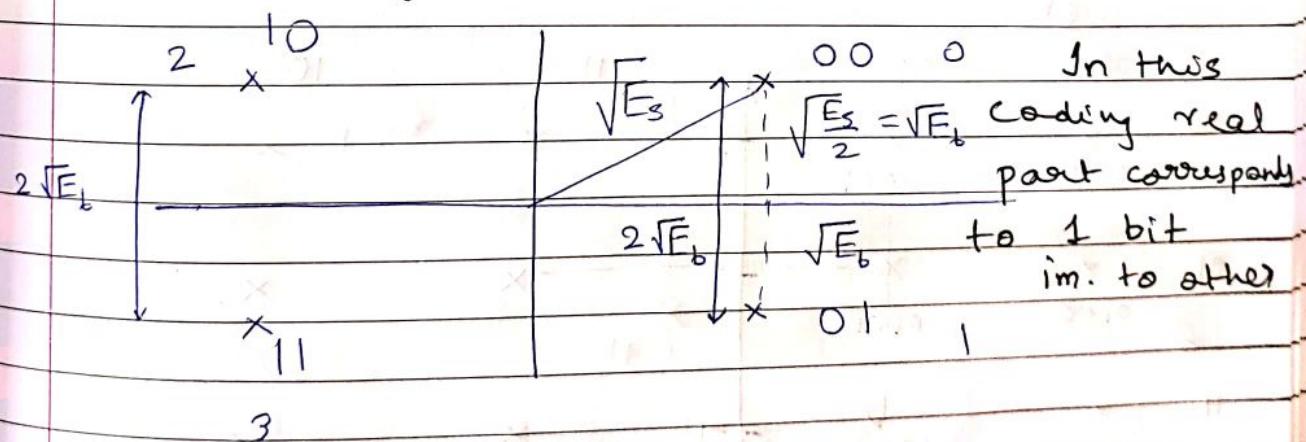
$$\leq 2Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

Define

$$\text{Efficiency / Metric} = \eta_p = \frac{d^2}{E_b}$$

Gray Coding

- A single symbol error should ideally cause only 1 bit error



- Can be viewed as 2-BPSK Systems

$$N_o \rightarrow n_i + jn_q$$

project on any line, get $\frac{N_o}{2}$

$\frac{N_o}{2}$ $\frac{N_o}{2}$

2-D Gaussian Noise

→ Error rate using Real / imaginary projection

$$Q\left(\frac{d}{2\sigma}\right) = Q\left(\frac{2\sqrt{E_b}}{2\sqrt{\frac{N_0}{2}}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

Same as BPSK

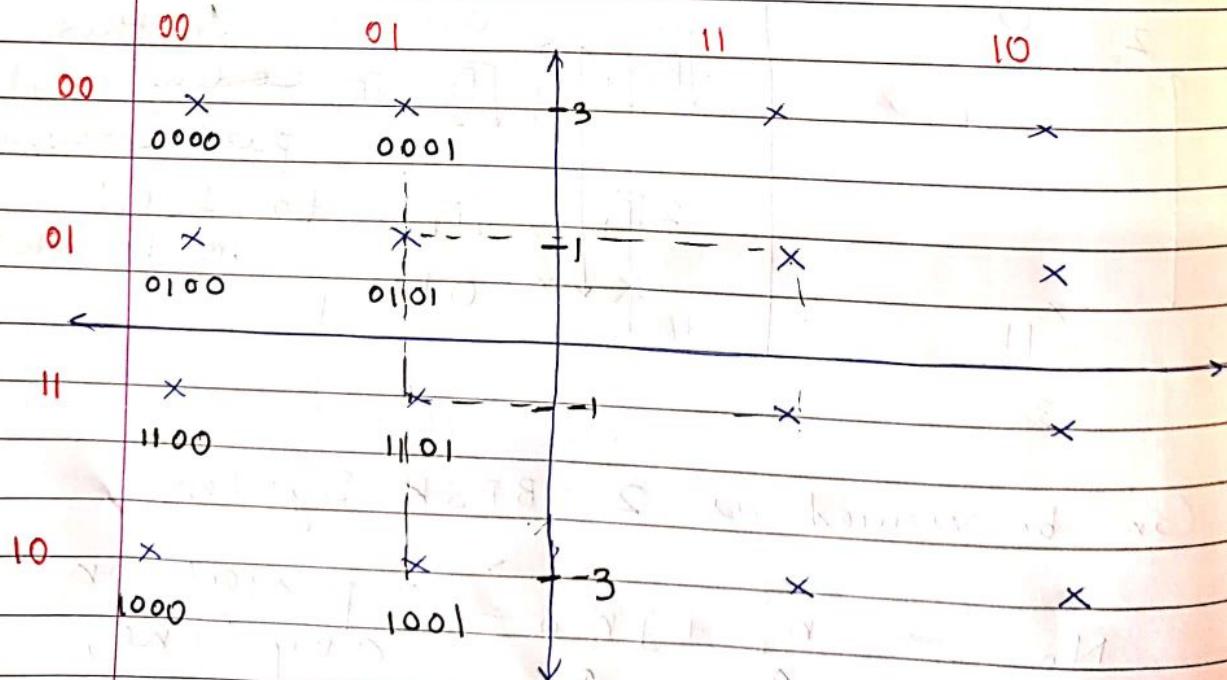
→ Why the Same?

- Think in terms of power $E_s = 2E_b$ and distance only from $2\sqrt{E_b} \rightarrow \sqrt{2E_s}$

~~12.2.19~~

ex

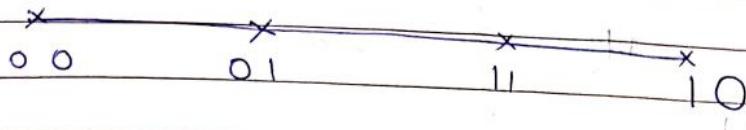
QAM - 16 Gray Coding



Gray \rightarrow Min BER for fixed SER

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Consider QAM - 4



Average Energy (E_s)

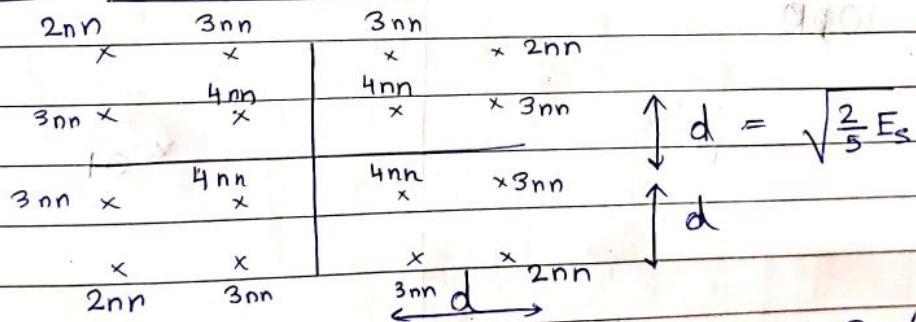
$$E_s = \frac{1}{16} (12 \times 3^2 + 4 \times 1^2)$$

$$= \frac{12 \times 9 + 4 \times 1}{16} = \frac{28}{4} = 7$$

QAM

→ Gray

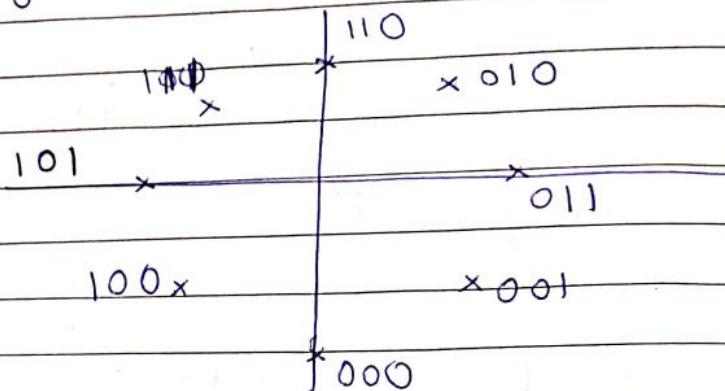
QAM - 16 Union Bound



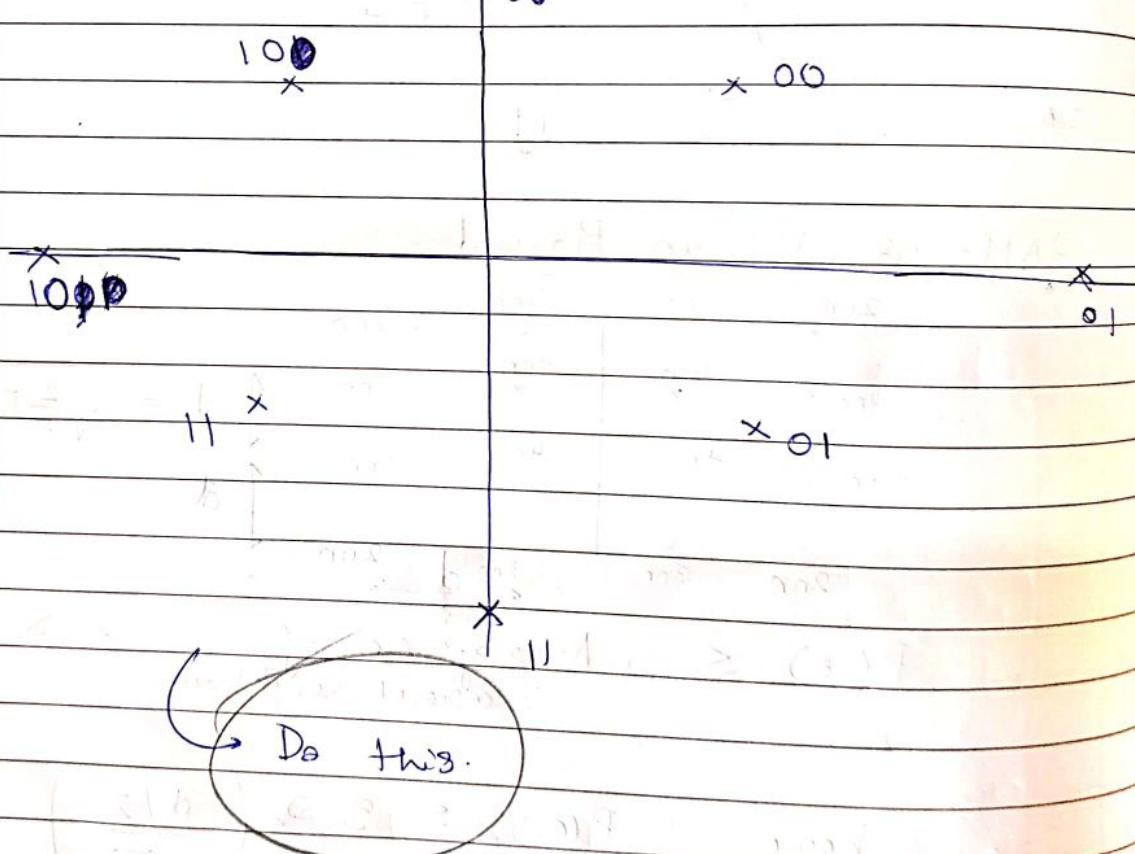
$$\rightarrow P(e) \leq \text{Average no. of nearest neighbour} \times Q\left(\frac{d/2}{\sigma}\right)$$

$$\text{here } P(e) \leq 3 Q\left(\frac{d/2}{\sigma}\right)$$

→ Gray code for 8 - PSK



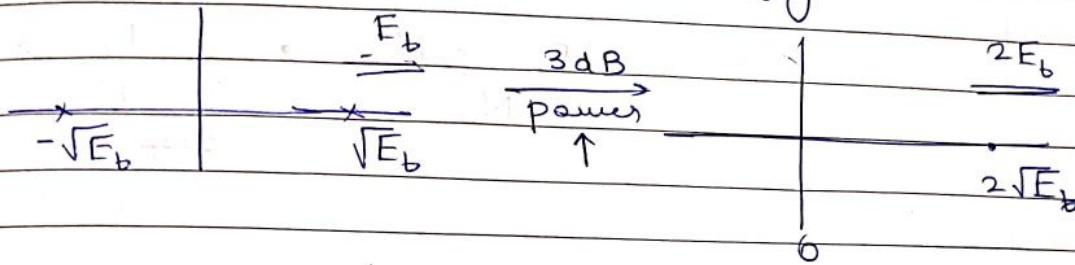
→ Algorithm → Think of this as 2 - QPSK



$$10 \log_2 \frac{2}{10} = 3 \text{ dB}$$

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- Rotation of Constellation has no effect on performance.
- Shifting of Constellation gives same performance at higher energy cost



$$E_s = E_b \log_2 M$$

Orthogonal Signalling

$$\vec{s}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \sqrt{E_s} \quad \vec{s}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \sqrt{E_s} \quad \vec{s}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \sqrt{E_s}$$

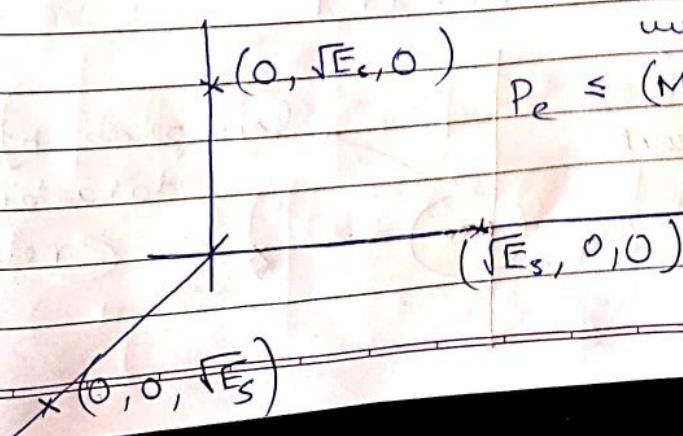
$$\dots \vec{s}_M = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix} \sqrt{E_s}$$

$$\text{no. of bits} = \log_2 M \quad \frac{\log_2 M}{M} \xrightarrow[M \rightarrow \infty]{} 0$$

- Union bound for Orthogonal Signalling

Union bound will give

$$P_e \leq (M-1) \alpha \left(\frac{\sqrt{2E_s}}{\sqrt{2N_0}} \right)$$



→ Here union bound is very loose, we exact expression

$$P_e = (M-1) \int_{-\infty}^{\infty} (\Phi(x))^m \Phi(m-x) \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx$$

$$m = \sqrt{\frac{2E_b \log_2 M}{N_0}}, \text{ if } \frac{E_b}{N_0} > -1.6 \text{ dB}$$

SNR BER ↓
as M ↑

BER for orthogonal Signalling

- There is no Gray coding, all are equidistant
- To get BER consider all cases and no. of bits flipped
- or $\frac{M}{2}, \frac{M}{2}-1$ reasoning per bit

Soft Decisions

→ ex, gives redundancy such that, 6 times same bit sent

0 → 0000 00

1 → 1111 11

High prob. of this data being correct

00*

000

low prob. of this data being reliable

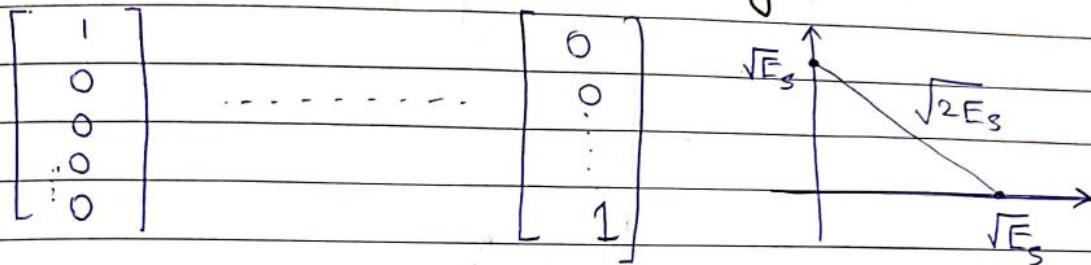
*

Hard Decision $\frac{4}{6} \rightarrow +1 \rightarrow +1$

Soft " $\rightarrow -1$

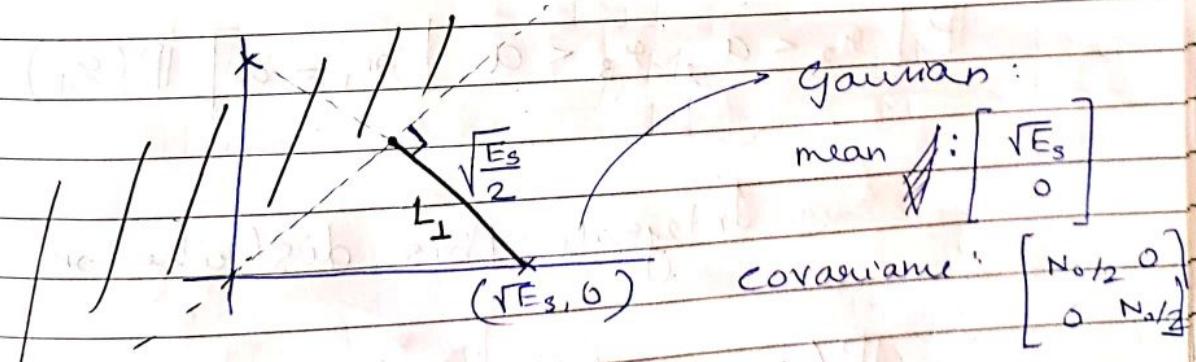
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Orthogonal Signalling



$$\text{2-D Case: } \text{BER SER} = Q\left(\frac{\sqrt{2E_s}}{2\sigma}\right) \sqrt{\frac{N_0}{2}}$$

→ Sent $(\sqrt{E_s}, 0)$, What is received
disttribution:



→ Instead of 2D Integral,
integrate along L_1 from $\sqrt{\frac{E_s}{2}} \rightarrow \infty$

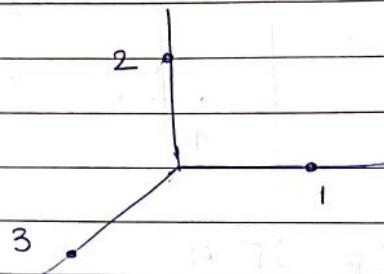
$$\int_{\sqrt{\frac{E_s}{2}}}^{\infty} e^{-x^2/2\sigma^2} dx$$

→ Another approach,

Correct if $x > y$

3-D

Correct if $x > y \wedge x > z$



$$\begin{bmatrix} g_1 \\ g_2 \\ g_3 \end{bmatrix} = \begin{bmatrix} \sqrt{E_s} \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

VS

$$P[g_1 = \max_{1,2,3} g_i] =$$

$$P[g_2 < a, g_3 < a | g_1 = a] P(g_1)$$

Integrate this distribution

$$= P(g_2 < a | g_1 = a)^2 P(g_1)$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^y \frac{1}{\sigma \sqrt{2\pi}} e^{-x^2/2\sigma^2} dx \right] \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(y-\sqrt{E_s})^2}{2\sigma^2}} dy$$

Link - Budget Analysis

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① Data rate requirement

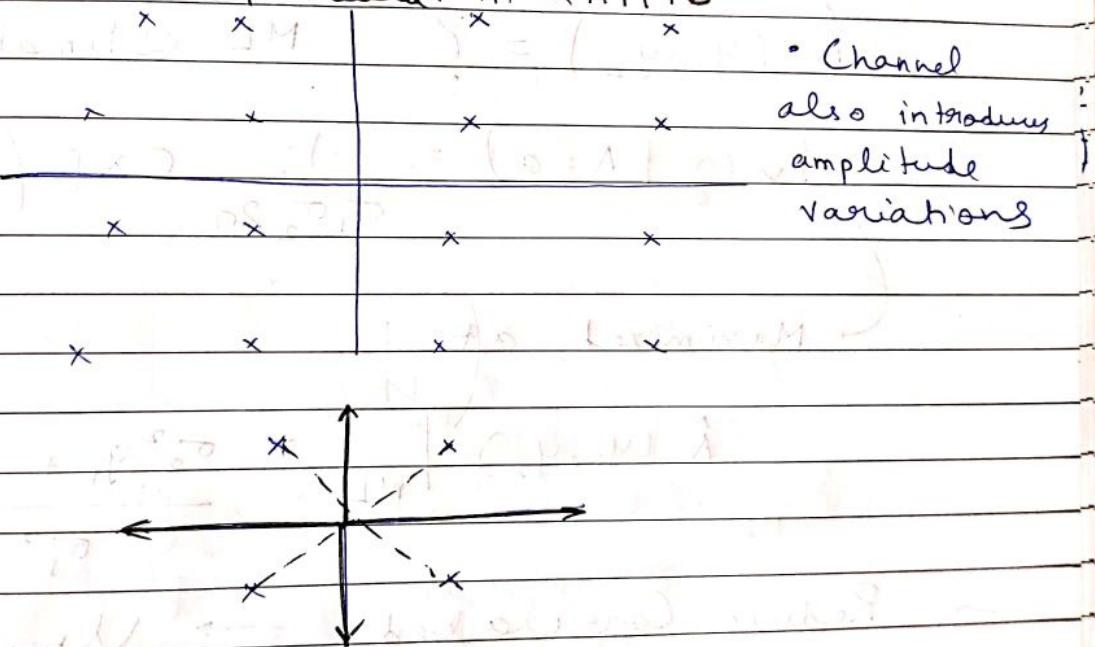
② Bandwidth

③ Power

④ ($N_r N_t$)

→ Difference b/w QPSK & QAM 16

complicated decision bound. in QAM 16



Chap 4 - Synchronisation

→ Issues of equalization, synchronisation . . .

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$$y_1 = A + \omega_1$$

$$y_2 = A + \omega_2$$

ω_1, ω_2 are jointly Gaussian mean $\mathbf{0}$
covariance C_w (Invertible)

$$\begin{aligned} y_1 &= A_p + n_1, & \sigma_1^2 \\ y_2 &= A + n_2 & \sigma_2^2 \end{aligned} \quad \text{Independent}$$

$$\hat{A}(y_1, y_2) = ? \quad \text{ML estimate}$$

$$f_y(y | A=a) = \frac{1}{\sigma_1 \sigma_2 \sqrt{2\pi}} \exp \left(-\frac{(y - [a])^T}{2} \begin{pmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{pmatrix}^{-1} (y - [a]) \right)$$

Maximized at

$$\hat{A}(y_1, y_2) \Big|_{ML} = \frac{\sigma_2^2 y_1 + \sigma_1^2 y_2}{\sigma_1^2 + \sigma_2^2}$$

Consider

→ Reduce Correlated → Uncorr

$\omega_1, \omega_2 \rightarrow$ correlated

$$C_w = U \Lambda U^H$$

$$\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_2 \end{bmatrix} \xrightarrow{?} \mathbf{0}$$

$$= (U \Lambda^{1/2}) (\Lambda^{1/2} U^H)$$

$$= (U \Lambda^{1/2}) (U \Lambda^{1/2})^H$$

Called
square
root of
a Matrix

ML

$$y = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$(U\lambda)^{1/2} y \rightarrow (0, \lambda)$$

Pre multiply to get uncorrelated
r.v.s

$$\left(\frac{\sigma_1^2}{\sigma_2^2} \right) \left(y - \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \right)$$

Channel Modifies Signal

→ Consider a Real AWGN channel

$$y = Ax + w$$

real number

Get an optimal estimate of A given all
the samples of y

→ We want to estimate para. Θ

y depends on Θ

$$\hat{\Theta}_{ML}^{(A|y)} = \arg \max_{\Theta} P(y | \Theta)$$

Consider a new problem

$$y_1 = A + w_1$$

$$y_2 = A + w_2$$

⋮

$$\hat{A}_{ML}(\bar{y}) = \underset{A}{\operatorname{argmax}} p(\bar{y}|A)$$

If w_1, w_2, \dots are iid

$$\hat{A}_{NL}(\bar{y}) = \underset{A}{\operatorname{argmax}} \prod_{i=1}^n p(y_i|A)$$

$$\frac{\sum y_i}{n} = \underset{A}{\operatorname{argmax}} \frac{1}{\sqrt{2\pi}} \prod_{i=1}^n \exp \left(-\frac{(y_i - a)^2}{2\sigma^2} \right)$$

$$y = Ab + w \quad (\text{BPSK})$$

1) ~~b is known~~, ~~to be ±1~~

$$\hat{A}_{ML} = \hat{A}_{ML} \mid \text{previous}$$

$$\hat{A}_{ML}(\text{b known}) = \frac{y}{b}$$

↳ exactly

$$2) y = Ab + w \quad \begin{matrix} \nearrow \pm 1 \text{ (unknown but lies in } \pm 1) \\ N(0, \sigma^2) \end{matrix}$$

↳ unknown

$$\hat{A}_{ML} = ?$$

$$P(y|A=a) = \frac{1}{2} \left(P(y|A=a, b=+1) \right.$$

$$\left. + P(y|A=a, b=-1) \right)$$

$$P(y|A=a, b=+1) \propto \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-a)^2}{2}} + \frac{1}{\sqrt{2\pi}} e^{-\frac{(y+a)^2}{2}}$$

$$\frac{1}{2} \left(\exp\left(-\frac{(y-a)^2}{2}\right) + \exp\left(-\frac{(y+a)^2}{2}\right) \right)$$

Shifted ω by $\langle A \rangle$

Maximized for which a ?

$$\frac{\partial}{\partial a} \left(\frac{-2(y-a)}{2\sigma^2} \exp\left(-\frac{(y-a)^2}{2\sigma^2}\right) + \frac{2(y+a)}{2\sigma^2} \exp\left(-\frac{(y+a)^2}{2\sigma^2}\right) \right) = 0$$

\rightarrow Solve for a in terms of y

Q3) $y_1 = Ab_1 + \omega_1 \quad N(0, \sigma^2) : \{ \text{BPSK}$

$y_2 = Ab_2 + \omega_2 \quad N(0, \sigma^2)$

$y_N = Ab_N + \omega_N$

$$\hat{A}_{ML} = \frac{1}{N} \sum_{i=1}^N \frac{y_i}{b_i}$$

Q4)

$$y_1 = A b_1 + w_1$$

$$y_2 = A b_2 + w_2$$

$$\vdots$$

$$y_N = A b_N + w_N$$

$$\hat{\theta}_{ML}(\bar{y}) = \arg \max_{\theta} p(\bar{y} | \theta)$$

$$\underset{A_{ML}}{\arg \max} \prod_{i=1}^N \exp \left(-\frac{(y_i - b_i A)^2}{2 \sigma^2} \right) = \hat{A}_{ML}$$

\downarrow Take log (Strictly Increasing)

$$\text{Minimized this} \rightarrow \sum_{i=1}^N \frac{(y_i - A b_i)^2}{2 \sigma^2}$$

\rightarrow Substitute known y_i, b_i (after condition on b_i)

$$\text{Get, } \hat{A}_{ML} = \sum y_i \tanh \left(\frac{ay_i}{\sigma^2} \right)$$

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$$b[n] \in \{-1\}$$

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$$y[0] = Ab[0] + w[0]$$

$$y[k-1] = Ab[k-1] + w[k-1]$$

$$\hat{A}_{ML} = \frac{1}{k} \sum_{k=0}^{k-1} y[k] b[k] \quad (\text{or divide})$$

(Squaring
works because
 ± 1)

→ $b[k]$'s are unknown

$$y[0] = b[0] A + w[0]$$

~~$y[k-1] = b[k-1] A + w[k-1]$~~

$$y[k-1] = b[k-1] A + w[k-1]$$

$$IP[\vec{y} | A=a] = \sum_b IP(\vec{y} | \vec{b}, A=a) \frac{1}{2^k}$$

The tanh formula

$$a = \frac{1}{k} \sum_{k=0}^{k-1} y[k] \tanh\left(\frac{ay[k]}{\sigma^2}\right)$$

$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} \approx \underline{b} \quad (\text{since } \pm \text{ both sides is same})$$

$$a = \tanh\left(\frac{ya}{\sigma^2}\right) \approx a^2 b \quad (\text{as } x \text{ both sides } (b=\pm 1))$$

⇒ sign of a is linked to sign of b

0 ||| / ↑ 1

→ Earlier : write the pdf, estimate the unknown parameter.

$$y \sim N(\theta, \sigma^2)$$

↳ want this

Set A,

$$P[y \in A] = \int_{y \in A} f_y(y) dy$$

Maximize
this

since q ind. of θ

$$\Rightarrow \underset{\theta}{\operatorname{argmax}} \frac{f_y(y)}{q(y)}$$

$$= \underset{\theta}{\operatorname{argmax}} f_y(y)$$

$$\int_A \left(\frac{f_y(y)}{q(y)} \right) q(y) dy$$

Not depd.
on θ
↳ like expressing pdf
of y in terms of
another pdf

→ Requirement : $q(y) > 0$ whenever $f_y(y)$

$$\int_A L(y|\theta) q(y) dy \rightarrow \text{A Ratio of PDFs}$$

↳ Likelihood function (When q is also a pdf)

ex

$$\underset{\theta}{\operatorname{argmax}} \frac{1}{\sigma \sqrt{2\pi}} \exp \left(-\frac{(y-\theta)^2}{2\sigma^2} \right)$$

$$= \underset{\theta}{\operatorname{argmax}} \frac{1}{\sigma \sqrt{2\pi}} \exp \left(-\frac{(y-\theta)^2}{2\sigma^2} \right) / \exp$$

Like likelihood & Log of LR

Ratio

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$$\text{Sign} \left(\log \left(\frac{p(y_{l+1})}{p(y_{l-1})} \right) \right)$$

→ LLR

$$y[0] = A + w[0]$$

$$y[k-1] = A + w[k-1]$$

$$\vec{H} = a \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \quad \text{Cov} = \sigma^2 I_{K \times K}$$

pendent

df

$\lambda > 0$