

→ Receive Filtering

$$y(t) = s(t) + z(t)$$

Write $y(t) =$

Theorem 3.A.3, Madhwa

→ MLE decision rule $\hat{i} = \underset{1 \leq m \leq M}{\operatorname{argmax}} \operatorname{Re} \{ \langle r(t), s_m(t) \rangle \} - \frac{1}{2} \|s_m(t)\|^2$

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→ ML Rule:

Choose $\hat{i} = \underset{i}{\operatorname{argmin}} \|y - s_i\|^2$ --- Geometrically closest

$$= \underset{i}{\operatorname{argmin}} (\|y\|^2 + \|s_i\|^2 - 2 \operatorname{Re} \langle y, s_i \rangle)$$

$$= \underset{i}{\operatorname{argmax}} \left(\operatorname{Re} \langle y, s_i \rangle - \frac{\|s_i\|^2}{2} \right)$$

→ Minimum Error Probability rule

Choose $\hat{i} = \underset{i}{\operatorname{argmax}} \left(\operatorname{Re} \langle y, s_i \rangle - \frac{\|s_i\|^2}{2} + \sigma^2 \log(\pi \sigma^2) \right)$
↓
noise variance ($\frac{N_0}{2}$)

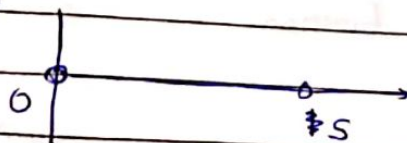
eg For QPSK, $\|s_i\|^2$ is same

∴ Answer for ML is Geometrically

eg On-Off Keying (OOK)

0 → 0

1 → $s \psi(t)$



Dimension of signal space = 1, basis = $\{ \psi(t) \}$

Obtain ' \hat{y} ' by projecting $y(t)$ onto $\underline{\psi}(t)$ (~~which is~~

~~We want to guess $s(t)$ from y .~~

$$P_{\text{error}} = P_{\text{error} | 0 \text{ sent}} P_{0 \text{ sent}} + P_{\text{error} | 1 \text{ sent}} P_{1 \text{ sent}}$$

$$\quad \quad \quad \downarrow \quad \quad \quad \downarrow$$

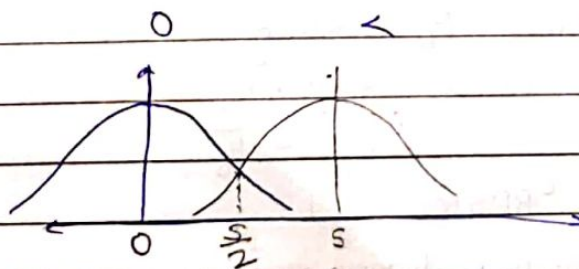
$$\quad \quad \quad \frac{1}{2} \quad \quad \quad \frac{1}{2}$$
$$1 \quad \therefore H_1 \equiv y(t) = s(t) + n(t)$$
$$y = y^{\psi_1}$$

$$S_T = 0 \text{ or } S^{\psi_1}$$

- If 0 was sent, $\text{Re} \langle y, s_r \rangle = \|s_{ill}\|^2/2 = 0 - 0 = 0$

$$- \quad | \quad \dots \quad s_y - \frac{s^2}{2}$$

- We guess 1 if $\frac{sy}{2} > \frac{s^2}{2} \Rightarrow y > \frac{s}{2}$



$$\bullet P_{\text{error} | 0 \text{ sent}} = P\left(y > \frac{S}{2} \mid 0 \text{ was sent}\right) = \frac{1}{\sqrt{2\pi}\sigma} \int_{S/2}^{\infty} e^{-x^2/2\sigma^2} dx$$

$$= Q\left(\frac{S}{2\sigma}\right)$$

bits in a symbol

~~* $E_s = \text{Energy per symbol} = n E_b$~~

E_b = Energy per bit.

$$0 \rightarrow 0, \quad S \rightarrow S^2 \Rightarrow F_b = \frac{S^2}{2}$$

* Binary Signaling

$$0 \rightarrow s_1 \quad H_1 \equiv y(t) = s_1 + n(t)$$

$$1 \rightarrow s_2 \quad H_2 \equiv y(t) = s_2 + n(t)$$

$$\therefore E_b = \frac{s_1^2 + s_2^2}{2}$$

- Decision:-

$$\langle y, s_1 \rangle - \frac{\|s_1\|^2}{2} \underset{H_2}{\overset{H_1}{\geq}} \langle y, s_2 \rangle - \frac{\|s_2\|^2}{2}$$

$$\text{ie} \rightarrow \langle y, s_1 - s_2 \rangle \underset{H_2}{\overset{H_1}{\geq}} \frac{\|s_1\|^2 - \|s_2\|^2}{2}$$

- Mathematical simplification

$$\text{Define } \tilde{y}(t) = y(t) - s_2(t)$$

$$\therefore H_1 \equiv \tilde{y}(t) = s_1(t) - s_2(t) + n(t)$$

$$H_2 \equiv \tilde{y}(t) = n(t)$$

This is just like OOK

$$\therefore P_{\text{error} | s_2 \text{ is sent}} = Q\left(\frac{|s_1 - s_2|}{2\sigma}\right) = P_{\text{error} | s_1 \text{ is sent}}$$

- To minimize this, maximize $|s_1 - s_2|$

\therefore Under E_b constraint,

$$\text{choose } s_1 = \sqrt{E_b}$$

$$s_2 = -\sqrt{E_b}$$

'BPSK'

This is the best binary signaling under energy constraint for equiprobable symbols.

eg QPSK

$$E_s = 2E_b = \frac{s_1^2 + s_2^2 + s_3^2 + s_4^2}{4}$$

For farthest spacing, $\|s\| = \sqrt{E_s}$



7/2 is QPSK
If symbol has 2-bits, $\begin{bmatrix} y_r \\ y_i \end{bmatrix} = \begin{bmatrix} \sqrt{E_s/2} \\ \sqrt{E_s/2} \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \end{bmatrix}$ independent $G(0, N_0/2)$
1 symbol
 $\sqrt{\frac{N_0}{2}} e^{j\pi/4}$

$\begin{bmatrix} y_r \\ y_i \end{bmatrix} \therefore$ Jointly Gaussian: Mean = $\begin{bmatrix} \sqrt{E_s/2} \\ \sqrt{E_s/2} \end{bmatrix}$, Covariance = $\begin{bmatrix} N_0/2 & 0 \\ 0 & N_0/2 \end{bmatrix}$

\therefore Distribution: $f_y(y_r, y_i) = \frac{1}{(\sqrt{2\pi\sigma^2})^2} e^{-\frac{(y_r - \mu_r)^2}{2} - \frac{(y_i - \mu_i)^2}{2}}$
 $= \frac{1}{2\pi(\frac{N_0}{2})} e^{-\frac{\|y - \mu\|^2}{2(\frac{N_0}{2})}} \quad \Sigma^{-1} \Rightarrow \frac{1}{N_0/2}$

Integrate
Gaussian
over
correct
area

$\therefore P_{\text{correct}} | 1 \text{ is sent} = \int_0^\infty \int_0^\infty f_{y_r, y_i}(y_r, y_i) dy_r dy_i$

$= \int_0^\infty \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(y_r - \sqrt{E_s/2})^2}{N_0}} dy_r \int_0^\infty \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(y_i - \sqrt{E_s/2})^2}{N_0}} dy_i$

$= \left(\int_0^\infty \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(y - \sqrt{E_s/2})^2}{N_0}} dy \right)^2$

$= Q^2 \left(-\sqrt{\frac{E_s}{2N_0}} \right)$

$= \left(1 - Q \left(\sqrt{\frac{E_s}{N_0}} \right) \right)^2$

$\therefore P_{\text{error}} | 1 \text{ is sent} = 1 - P_{\text{correct}} | 1 \text{ is sent}$

$= 2Q \left(\sqrt{\frac{E_s}{N_0}} \right) - \underbrace{Q^2 \left(\sqrt{\frac{E_s}{N_0}} \right)}_{\text{Quite small}}$

- For higher number of symbols (eg - 16-QAM), it is cumbersome to detect.

\therefore Use union bound.

→ Union Bound Approximation

eg QPSK

$$P_{\text{error}} | 1 \text{ is sent} = P(y_1 < 0 \text{ OR } y_2 < 0)$$

$$\leq P(y_1 < 0) + P(y_2 < 0) = 1 - Q\left(\frac{\sqrt{E_b}}{N_0}\right) + 1 - Q\left(\frac{\sqrt{E_b}}{N_0}\right)$$

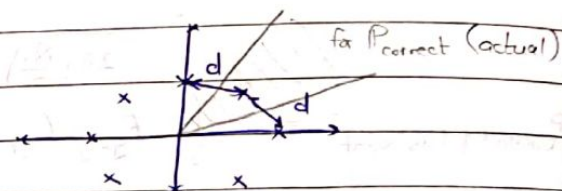
$P(y_1 \& y_2 < 0)$ is counted twice

$$= 2Q\left(\frac{\sqrt{E_b}}{N_0}\right) = 2Q\left(\frac{d}{2\sigma}\right) \quad d = \sqrt{2E_b}$$

eg 8-PSK

$$P_{\text{error}} | 1 \text{ is sent} \leq 2Q\left(\frac{d}{2\sigma}\right)$$

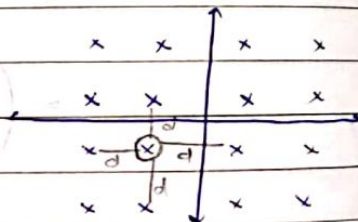
$$\text{Ans: } Q\left(\frac{d}{2\sigma}\right) \text{ for each nearest neighbour}$$



eg 16-QAM

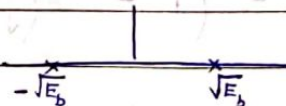
$$P_{\text{error}} | 1 \text{ is sent} \leq 4Q\left(\frac{d}{2\sigma}\right)$$

$$\sigma = \sqrt{\frac{N_0}{2}}$$



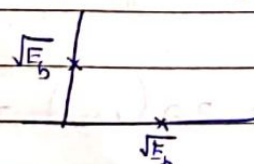
1/2

eg Binary Signalling



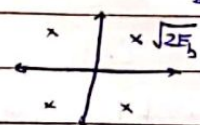
$$\text{BER} = Q\left(\frac{\sqrt{E_b}}{N_0}\right)$$

Orthogonal Signalling



$$\text{BER} = Q\left(\frac{\sqrt{E_b}}{N_0}\right)$$

QPSK



$$\text{SER} = 2Q\left(\frac{\sqrt{E_b}}{N_0}\right) = Q^2\left(\frac{\sqrt{2E_b}}{N_0}\right)$$

$$\leq 2Q\left(\frac{\sqrt{2E_b}}{N_0}\right)$$

$$\rightarrow \eta_r = \frac{d^2}{E_b}$$

→ Bit Mapping

- Arbit coding for QPSK

11 x	x 00
10 x	x 01

There will be 2 bit errors on horizontal direction misprediction.

Better - Gray Coding for QPSK: Neighbors differ by one bit.

10 x	x 00
11 x	x 01

MSB is determined by real part

LSB

imaginary part.

For one adjacent neighbour, $Q\left(\frac{d}{2\sigma}\right) = Q\left(\frac{2\sqrt{E_b}}{2\sqrt{\frac{N_0}{2}}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$

.... same expression as BPSK

(because the vertical/horizontal distance can be thought of as BPSK)

★ ∴ For ~~QPSK~~ same E_b and P_e , QPSK gives twice as much bit rate as BPSK

- Similarly, 16-QAM can be thought of as 2 separate PAM-4

1/2 • Bit mapping aims to reduce E_b . Does not affect E_s

- 16-QAM

00	x	x	3	x	x
01	x	x	1	x	x
11	x	x	-1	x	x
10	x	x	-3	x	x

PAM-4 x PAM-4

Normalize scale to obtain unit E_s

$$E_s = 4 \left(\frac{9+9}{16} \right) + 8 \left(\frac{1+9}{16} \right) + 4 \left(\frac{1+1}{16} \right) = 10$$

∴ Divide all lengths by $\sqrt{10}$

* Alternatively, find Energy of one PAM-4. Multiply by

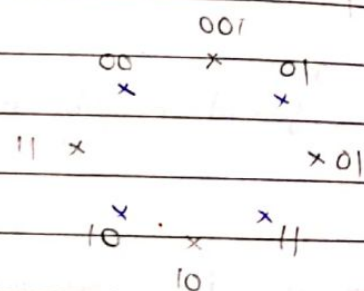
Union Bound : $P_e \leq \underbrace{\left(\text{No. of nearest neighbours} \right)}_{\text{average} = 3 \text{ (equiprobable case)}} Q\left(\frac{d}{2\sigma}\right)$

$$P_e \leq 3 Q\left(\frac{d}{2\sigma}\right)$$

$$d = \frac{2}{\sqrt{10}} \times \sqrt{E_s} \quad (\text{for BPSK it was } \sqrt{E_s})$$

\therefore QAM-16 is less immune to noise.

- Gray code for ~~QPSK~~ 8-PSK
Consider 8-PSK as 2 QPSKs



→ Rotation of Constellation

- No change in performance.

• Shifting changes performance - Changes energy (E_b) requirement.

→ Orthogonal Signalling

- Power BW efficiency = $\frac{\log_2 M}{M}$

$$s_1 = [1 \ 0 \ 0 \ \dots]^T \sqrt{E_s}$$

$$s_2 = [0 \ 1 \ 0 \ \dots]^T \sqrt{E_s}$$

Every s_i has $M-1$ nearest neighbours, each $\sqrt{2E_s}$ away.

Union bound: $P_e \leq (M-1) Q\left(\frac{\sqrt{2E_s}}{\sqrt{2N_0}}\right)$

- This bound is very loose for higher M . \Rightarrow not useful
- Use exact error instead

- Decision boundary (ML)

For any point on \mathbb{R}^M , project it onto each of the axes and detect the symbol for whose axis the projection is closest to $\sqrt{E_s}$.

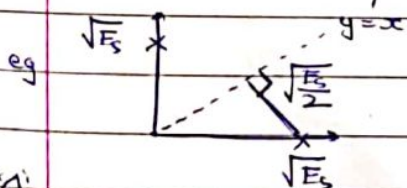
- Exact $P_e = (M-1) \int_{-\infty}^{\infty} (\Phi(x))^{M-2} \Phi(m-x) \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx$

where $m = \sqrt{\frac{2E_b \log_2 M}{N_0}}$

* For orthogonal signalling, bit error can be made arbitrarily small for $\frac{E_b}{N_0} > -1.6 \text{ dB}$

Resolving Gaussian Noise

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For that symbol, $Y \sim \text{Mean} \begin{bmatrix} \sqrt{E_s} \\ 0 \end{bmatrix}$

Covariance $\begin{bmatrix} N_0/2 & 0 \\ 0 & N_0/2 \end{bmatrix}$

(A)

For calculating error, we resolve the (circularly symmetric) noise along perpendicular to $y=x$.

This resolved component has variance $\frac{N_0}{2}$

$$P_{\text{error}} = \int_{-\infty}^{\infty} \frac{1}{\sqrt{\frac{E_s}{2}}} \frac{1}{\sqrt{2\pi}\sigma} e^{-x^2/2\sigma^2} dx$$

which is same as we would have obtained by double integral on x, y

eg 3D orthogonal signalling

$$s_1 = \begin{bmatrix} \sqrt{E_s} \\ 0 \\ 0 \end{bmatrix}$$

$$y_i \sim \text{Mean} \begin{bmatrix} \sqrt{E_s} \\ 0 \\ 0 \end{bmatrix}$$

Covariance: $\frac{N_0}{2} I_3$

$$\begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} \sqrt{E_s} \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

$$P_c = P(r_1 > r_2, r_1 > r_3)$$

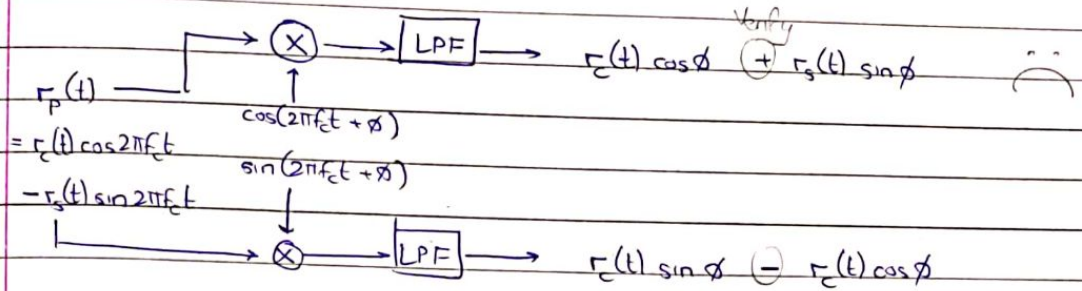
$$= P(r_2 < a, r_3 < a | r_1 = a) P(r_1 = a)$$

$$= P^2(r_2 < a | r_1 = a) P(r_1 = a)$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^a \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}} dx \right)^2 \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(a - \sqrt{E_s})^2}{2\sigma^2}} da$$

* Training sequence

- Transmitter periodically sends predecided sequence for training



- If f_c is also indefinite $\therefore r_c(t) \cos(2\pi \Delta f_c \tau) - r_s(t) \sin(2\pi \Delta f_c \tau)$