

$$\frac{dy}{dx} = \Omega_p \cosh \left[\frac{1}{N} \sinh^{-1} \left(\frac{1}{e} \right) \right]$$

$$\frac{dx}{dy} = \Omega_p \sinh \left[\frac{1}{N} \sinh^{-1} \left(\frac{1}{e} \right) \right]$$

$$\therefore C_k = \frac{(2k+1)\pi}{2N}$$

$$D_k = \frac{1}{N} \sinh^{-1} \left(\frac{1}{e} \right)$$

For all poles, we take any contiguous $2N$ values of k

- Obtain all poles

$H_{\text{analog}}(s)$ contains only poles in LHP.

Find constant by $H_{\text{analog}}(d)$.

CP Sketch poles of $H_{\text{analog}}(s)$ for $N = 3, 4, 5, 6$

Theorem Poles lie on an ellipse.

II/3

Passband

Monotonic

Equiripple

M

E

Stop-band

Monotonic

M

E

E

Filter Type

Butterworth

Chebyshev

Inverse Chebyshev

Jacobi / Elliptic.

IV

ANALOG FREQUENCY TRANSFORMATIONS

e.g

Transform :- $H_{\text{analog, BPF}}(s) \xrightarrow{s_L \leftarrow F(s)} H_{\text{analog, LPF}}(s_L)$

- We transform bandpass specifications to auxiliary specifications, design the LPF, transform back to

you've

- The frequency transform [$s = j\omega$ maps to $s_L = j\Omega_L$] must retain:
 - Stability with causality
 - Rationality

: $F(s)$ is an LC admittance function.

↳ admittance or impedance

$$s = j\omega \Rightarrow s_L = -j \frac{\omega_p}{\Omega} = j\omega_L$$

$$\underline{\Omega}_L = - \frac{\underline{\Omega}_P}{\underline{\Omega}}$$

$$\text{Also, } \underline{F(-j\omega)} = -F(j\omega)$$

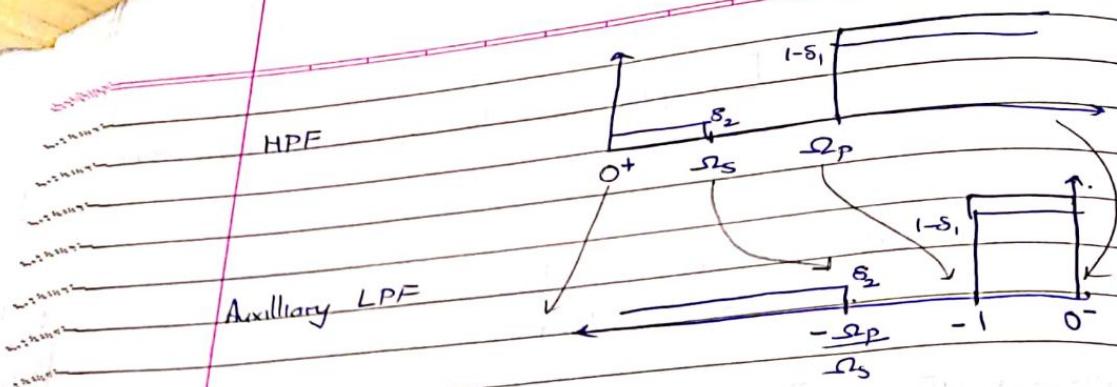
$$\text{and } \frac{d\Omega_1}{d\Omega} = \frac{\Omega_p}{\Omega^2} \rightarrow 0$$

We observe only on positive frequencies. The result for negative images would just be a mirror image.

→ Critical Points :-

Ω	Ω_L
0^+	$-\infty$
Ω_P	-1
Ω_S	$-\Omega_P/\Omega_S$
$+\infty$	0^-

P.T.O.



* We ~~could~~ could not have taken $\omega_L = \frac{\omega_p}{\omega_s} \Rightarrow s_L = -\frac{\omega_p}{\omega_s}$

because stability would have been compromised.

- In $F(s)$, LHP of s must be mapped to RHP.

$$\rightarrow \text{BPF} \xrightarrow{F(s)} \text{LPF}$$

- $F(s)$ cannot be a first order transformation.

Use $\text{---} / \text{---}$

$$s_L = \frac{sL + 1}{sC} = \frac{s^2 LC + 1}{sC} = \frac{s^2 + \omega_L^2}{sC}$$

$$\omega_L = 1/\sqrt{LC}$$

$$B = \sqrt{L}$$

$$\omega_L = \frac{\omega^2 - \omega_0^2}{B\omega} = \frac{\omega}{B} - \frac{\omega_0^2}{B\omega}$$

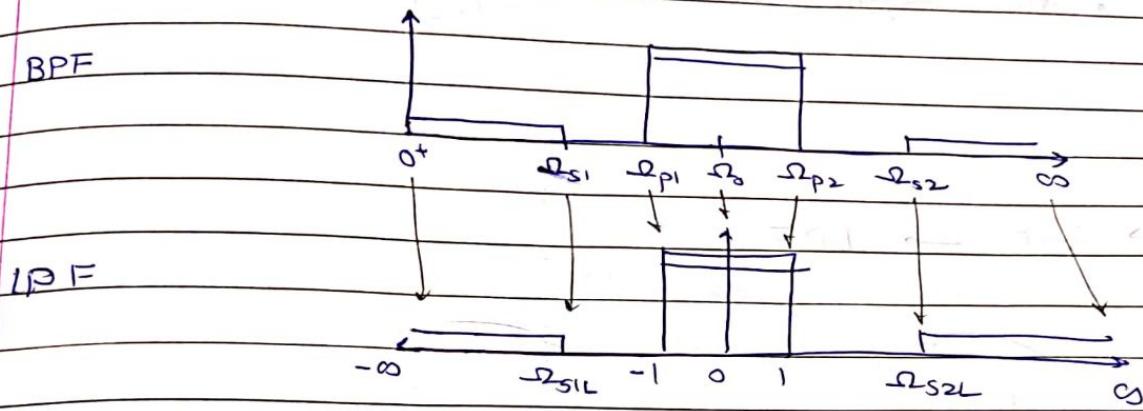
$$d\omega_L = \frac{1}{B} + \frac{\omega_0^2}{B\omega^2}$$

..... this mapping is also monotonic increasing.

$|\omega_L|$ is even function of ω

Critical Points :-

$$\begin{matrix} \Omega & \Omega \\ 0^+ & -\infty \\ \omega_{S1} & \\ \frac{\omega_{P1}}{\omega_{P2}} & 0 \\ \omega_{S2} & \\ +\infty & +\infty \end{matrix}$$



- We constrain mapping of ω_{P1} & ω_{P2} (passband edges) to be $-1, +1$

$$\frac{\omega_{P1}^2 - \omega_0^2}{\omega_{P2}^2 - \omega_0^2} = -1$$

B.O._{P1}

$$\frac{\omega_{P2}^2 - \omega_0^2}{\omega_{P1}^2 - \omega_0^2} = 1$$

B.O._{P2}

Solve to get

$$\begin{cases} \omega_0^2 = \omega_{P1} \omega_{P2} \\ B = \omega_{P2} - \omega_{P1} \end{cases}$$

* Even in RLC BPF, the resonant frequency is the GM of the two half-power frequencies.

12/3

- If the two stopband tolerances are not equal, use the more stringent tolerance for the auxiliary LPF.
- If transition widths $([\omega_{S1L}, -1] \text{ and } [1, \omega_{S2L}])$ are not equal, use the smaller of the two.

- Auxiliary LPF specifications :-
- Passband edge = 1
- Stopband edge = $\min \{\Omega_{S2L}, -\Omega_{SIL}\}$
- Tolerances are same as BPF *

- After designing BPF, $s \rightarrow \frac{1-z^{-1}}{1+z^{-1}}$ to get digital filter

\rightarrow BSF \rightarrow LPF

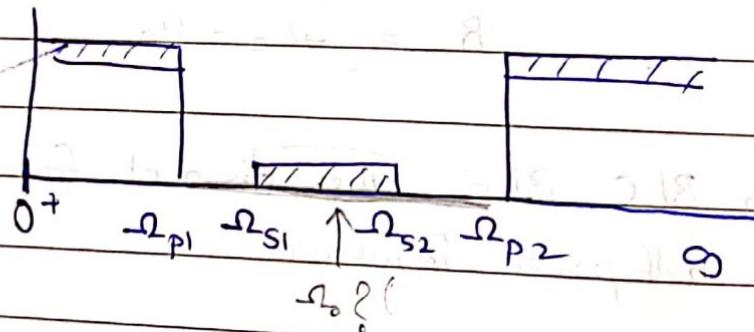
$$\frac{1}{sC + 1} = \frac{s/C}{s^2 + 1/LC}$$

$$F_{BS}(s) = B_s \Rightarrow F_{BS}(j\omega) = \frac{j B_s \omega}{\omega_s^2 - \omega^2}$$

As always (since LC imittance is always an odd function)

$$\Omega_L(-\omega) = -\Omega_L(\omega)$$

• BSF



• Critical Points:-

$$\Omega_1 = B_s \omega$$

$$\omega_s^2 - \omega^2$$

Ω	Ω_L
0^+	0^+
Ω_{p1}	$+1$
Ω_{si}	Ω_{sil}
Ω_s	$+\infty$
Ω_{s2}	$-\Omega_{s2L}$
Ω_{p2}	-1
∞	0^-

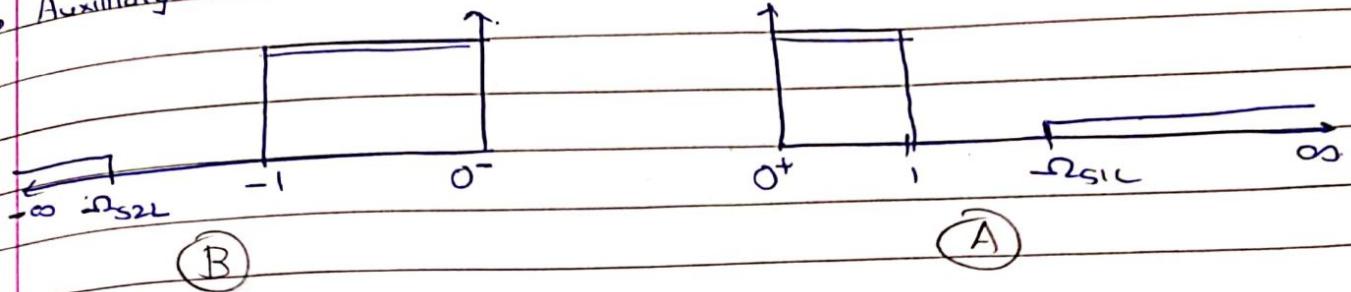
(A)

(B)

- Make passband \rightarrow
- Same equations as BPF.

$$\begin{aligned}\Omega_0^2 &= \Omega_{p1} \Omega_{p2} \\ B &= \Omega_{p2} - \Omega_{p1}\end{aligned}$$

- Auxiliary LPF :-



• Note:- $\frac{d\Omega_1}{d\omega} = \frac{B(\Omega_0^2 - \Omega^2) + 2B\Omega^2}{(\Omega_0^2 - \Omega^2)^2} \rightarrow 0$

$\therefore \Omega_L$ is monotonically increasing
(despite it and its derivative being discontinuous at Ω_0)

- Auxillary LPF specifications.

- Passband edge = 1
- Stopband edge = $\min\{|\Omega_{s1}|, |\Omega_{s2L}|\}$.
- Tolerances are same as BPF *

- What if $\Omega_0 = \sqrt{\Omega_{p1}\Omega_{p2}}$ does not lie between $(\Omega_{s1}, \Omega_{s2L})$

FINITE IMPULSE RESPONSE FILTER

Page No.:
Date: YOUVKA

- Impulse response is $h[n]$ of finite duration \Rightarrow Is absolutely summable
 \Rightarrow Coefficient perturbation cannot cause instability.
- Can give linear phase response :-

$$H_{FIR}(e^{j\omega}) = |H_{FIR}(e^{j\omega})| e^{-j\omega D}$$

D is an integer or half-integers
 (Any other D would make filter unrealizable)

We also generally accept

$$H_{FIR}(e^{j\omega}) = e^{-j\omega D} H_R(e^{j\omega})$$

where $H_R(e^{j\omega})$ is any real function.

- Different from above expression because H_R can be negative and hence produce a phase shift of π .

* Pseudo linear H_{FIR} can be acceptable.

- Group delay is constant

Phase not.

- $H_R(e^{j\omega}) = e^{j\omega D} H_{FIR}(e^{j\omega})$ \sim Shifting h_{FIR} b in time by D .

What if D is a half integer?

If D is an integer, we are shifting h_{FIR} by D samples.

• Since $h_{FIR}[n]$ is real, $H_{FIR}(e^{-j\omega}) = H_{FIR}^*(e^{j\omega})$
 $= H_R(e^{j\omega})$

$\therefore H_R$ is even-symmetric.

* Real and even sequences have real and even DTFTs.

- Consider $H_{\text{FIR}}(e^{j\omega}) = j e^{-j\omega D} H_R(e^{j\omega})$

$\star \therefore e^{j\omega D} H_{\text{FIR}}(e^{j\omega}) = j \underbrace{H_R(e^{j\omega})}_{\text{real}}$

$\star \therefore j h_R[n]$ is real

$$\therefore j H_R(e^{j\omega}) = (j H_R(e^{j\omega}))^*$$

\star

$$= -j H_R(e^{j\omega})$$

$$\therefore H_R(e^{-j\omega}) = -H_R(e^{j\omega})$$

H_R is antisymmetric

* Real and antisymmetric sequences have pure and imaginary and odd DTFTs

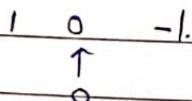
eg



0

1

$$\text{DTFT} = 2 \cos \omega$$



1

0

-1

$$\text{DTFT} = 2j \sin \omega$$

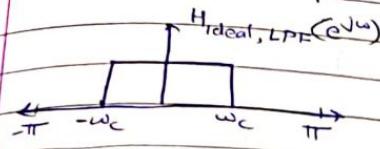
Both are accepted as pseudo linear phase responses.

Theorem

Pseudo linear phase requires symmetry or anti-symmetry in impulse responses

- IIR filters can never have symmetric/antisymmetric response

I LOWPASS FILTER



$$h_{ideal}[n] = \begin{cases} \frac{\omega_c}{\pi} & \text{for } n=0 \\ \frac{\sin \omega_c n}{\pi n} & \text{for } n \neq 0 \end{cases}$$

$$h[-n] = h[n]$$

- Infinitely, non-causal, unstable, irrational

- Analog filters can never give us a finite length impulse response
- Cannot have linear phase
- No transformations possible to design FIR filters.
- We approximate ideal LPF by truncating $h_{ideal}[n]$ to obtain finite length impulse response.
- For linear phase response, we maintain symmetry in $h_{FIR}[n]$

eg - Choose $n \in \{-10, -9, \dots, 10\}$ to make $h_{FIR}[n]$ of ∞ length

21.

- 1/3 - Truncation \sim Multiplication of $h[n]$ by a window sequence

$$\underline{w[n]} = \begin{cases} 1 & \text{for } -N \leq n \leq N \\ 0 & \text{otherwise} \end{cases}$$

'Rectangular window sequence'.

$$h_{FIR}[n] = h_{ideal}[n] w_R[n]$$

\hookrightarrow 'R for real'

$$\therefore H_{FIR}(e^{j\omega}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_{ideal}(e^{j\lambda}) V_R(e^{j(\omega-\lambda)}) d\lambda$$

where $V_R(e^{j\omega}) = \text{DTFT of } w_R[n]$

$$= \sum_{n=-N}^N w_R[n] e^{-j\omega n}$$

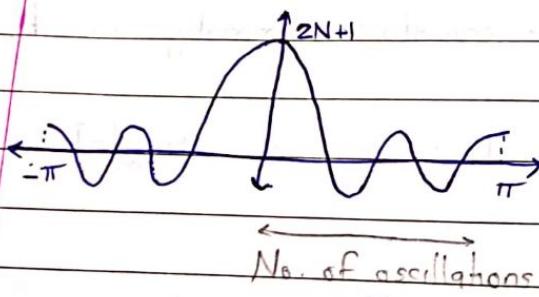
P.T.O..

$$\begin{aligned}
 &= \sum_{n=-N}^N e^{-j\omega n} \\
 &= e^{j\omega N} \frac{((e^{-j\omega})^{2N+1} - 1)}{e^{-j\omega} - 1} \\
 &= \frac{e^{j\omega N} - j\omega \frac{(2N+1)}{2}}{e^{-j\omega/2} 2j \sin \frac{\omega}{2}} \frac{2j \sin \omega \frac{(2N+1)}{2}}{2j \sin \frac{\omega}{2}} \\
 &= e^{j\omega(N - N + \frac{1}{2}) - \frac{1}{2}} \frac{\sin \omega \frac{(2N+1)}{2}}{\sin \omega \frac{(\omega)}{2}}
 \end{aligned}$$

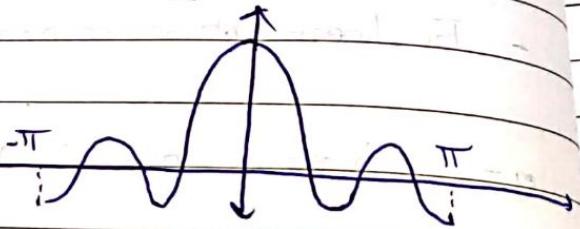
$$V_R = \frac{\sin \omega \frac{(N + \frac{1}{2})}{2}}{\sin \frac{(\omega)}{2}}$$

... even, because $V_R[\omega]$ was real and even

For $N = \text{even}$

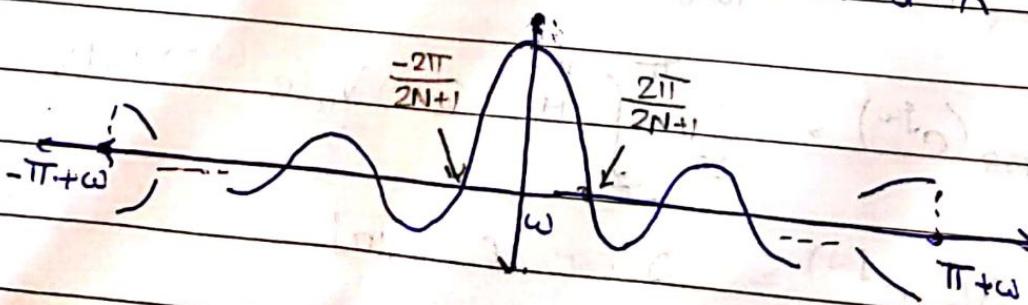


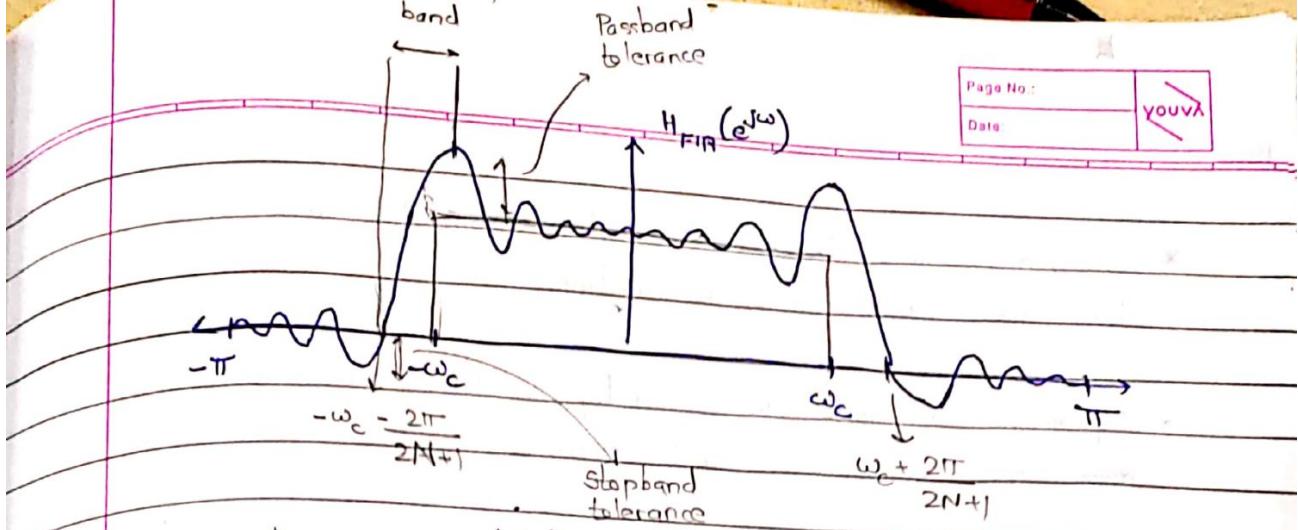
For $N = \text{odd}$



$$H_{FIR}(e^{j\omega}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_{ideal}(e^{j\lambda}) V_R(e^{j(\omega-\lambda)}) d\lambda$$

$V_R(e^{j(\omega-\lambda)})$ as a function of λ





- At $\omega = \pm \omega_c$, $H_{FIR}(e^{j\omega}) \approx \frac{1}{2}$ of maximum value

- $H_{FIR}(e^{j\omega})$ is maximum at $\pm \left(\omega_c - \frac{2\pi}{2N+1} \right)$

- Passband and stopband tolerances transition bands are caused by side-lobes of $V_R(e^{j\omega})$
- The transition width = $\frac{4\pi}{2N+1}$

- Asymptotic ($N \rightarrow \infty$) area under the primary side-lobe of $V_R(e^{j\omega})$

$$= \frac{4\pi}{2N+1} \int_{-\frac{2\pi}{2N+1}}^{\frac{2\pi}{2N+1}} \sin \frac{\omega(2N+1)}{2} d\omega$$

$\sin \frac{\omega}{2}$

$$\approx \frac{2}{2N+1} \int_{-\pi}^{\pi} \frac{\sin \theta}{\frac{\theta}{2N+1}} d\theta$$

$$\approx 2 \int_{\pi}^{2\pi} \frac{\sin \theta}{\theta} d\theta$$

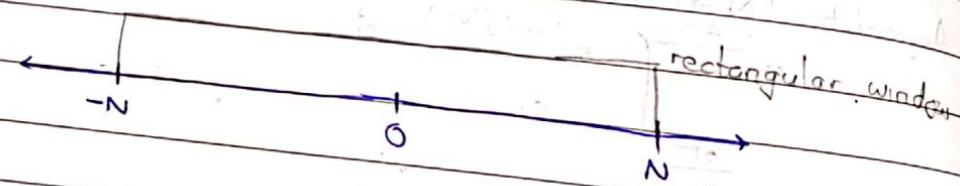
... independent of N

Gibb's phenomenon :- Irrespective of value of N, there is always an asymptotic deviation near the point of discontinuity even though the transition band width decrease for higher N.

- ∴ We have no control over passband and stopband tolerance.

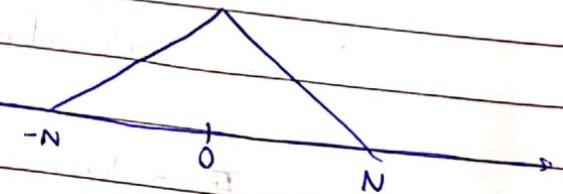
- * It can similarly be shown that asymptotic area of other lobes also approaches a constant.
- The height of ripple is given by relative area between side lobe and ideal 'rect' response.
- Average height reached is caused by main lobe relative area.
- The stopband and passband tolerances are equal. (because both are caused by side lobe area)
 - They also do not depend on N for large enough N.
 - If we want to control passband and stopband tolerances we will have to change the window sequence used.

→ Other window sequences

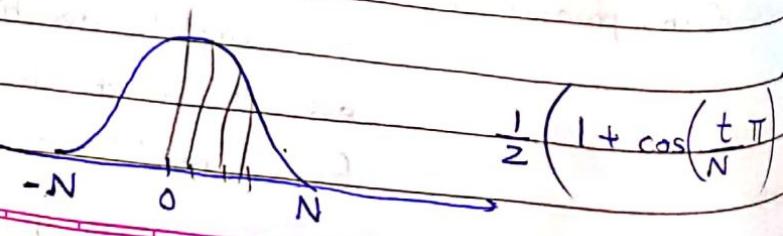


- The passband and stopband tolerances in rectangular window case were caused because of discontinuity in the rectangular window.
- To reduce tolerances, we try to make the window smooth.

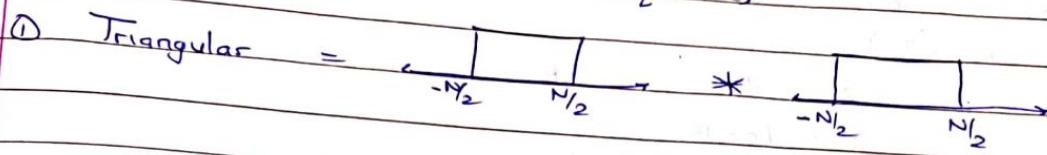
eg Triangular



Better eg Raised Cosine
(Hann window)



Q Find DTFT of above window sequences



② Raised cosine :- Write cos as exponentials.

$$\text{Generalized raised cosine} = \alpha + (1-\alpha) \cos\left(\frac{t\pi}{N}\right)$$

for $0.5 < \alpha < 1$.

'Generalized Hamming Window'

- Smoothness of window is characterized by continuity of derivative(s). — Smoother is better

* Blackman window

$$\alpha + \beta \cos\left(\frac{t\pi}{N}\right) + \gamma \cos\left(\frac{2t\pi}{N}\right)$$

$$\alpha, \beta, \gamma > 0 \quad \text{and} \quad \alpha + \beta + \gamma = 1.$$

- For the same window size 'N', there is a conflict between transition width and passband/stopband tolerance.
- characterized by relative mainlobe width
- characterized by relative sidelobe area.

18

→ Kaiser proposed a window based on modified Bessel functions (I_0)

β = Shape parameter

N = Length

$$\text{Window} = I_0(\beta N)$$

- Kaiser window, through β and N , allows for changes in main lobe width and relative side lobe area.

$\beta = 0 \therefore$ Rectangular Window

(High side lobe area \therefore
Low main lobe area \therefore)

- Choose shape parameter based on tolerances required
Then choose length to satisfy transition width