

Review :

1) If there are large no. of pulses/cycle, frequency of predominant harmonic can be \uparrow .

2) Sinusoidal PWM Technique:

→ Modulating Wave: Rectified AC of $2F$ & variable amplitude.

→ Δ wave of constant frequency & magnitude.

$\Rightarrow F_{\Delta} \gg F$

\Rightarrow 'N' pulses / $\frac{1}{2}$ cycle

Frequency of predominant harmonic = $(N+1)F_s$

$\Rightarrow F_{\Delta}$ is determined by the Power Rating and type of device.

How to vary the o/p voltage ?

$$\text{o/p voltage } V_o \propto m = \frac{A_m}{A_c}$$

⇒ A_c is held constant.

⇒ As $A_m \uparrow$, $V_o \uparrow$ till $m=1$

⇒ Conduction has started at +ve zero crossing .

⇒ D.F =1

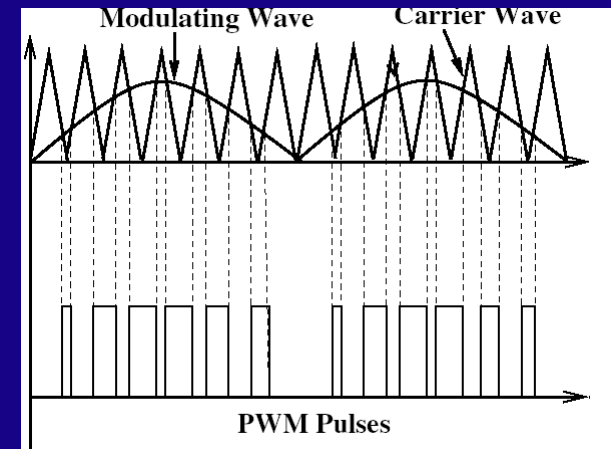
⇒ Using a filter (frequency is high), $I_{s1} \approx I_s$

∴ P.F. → 1

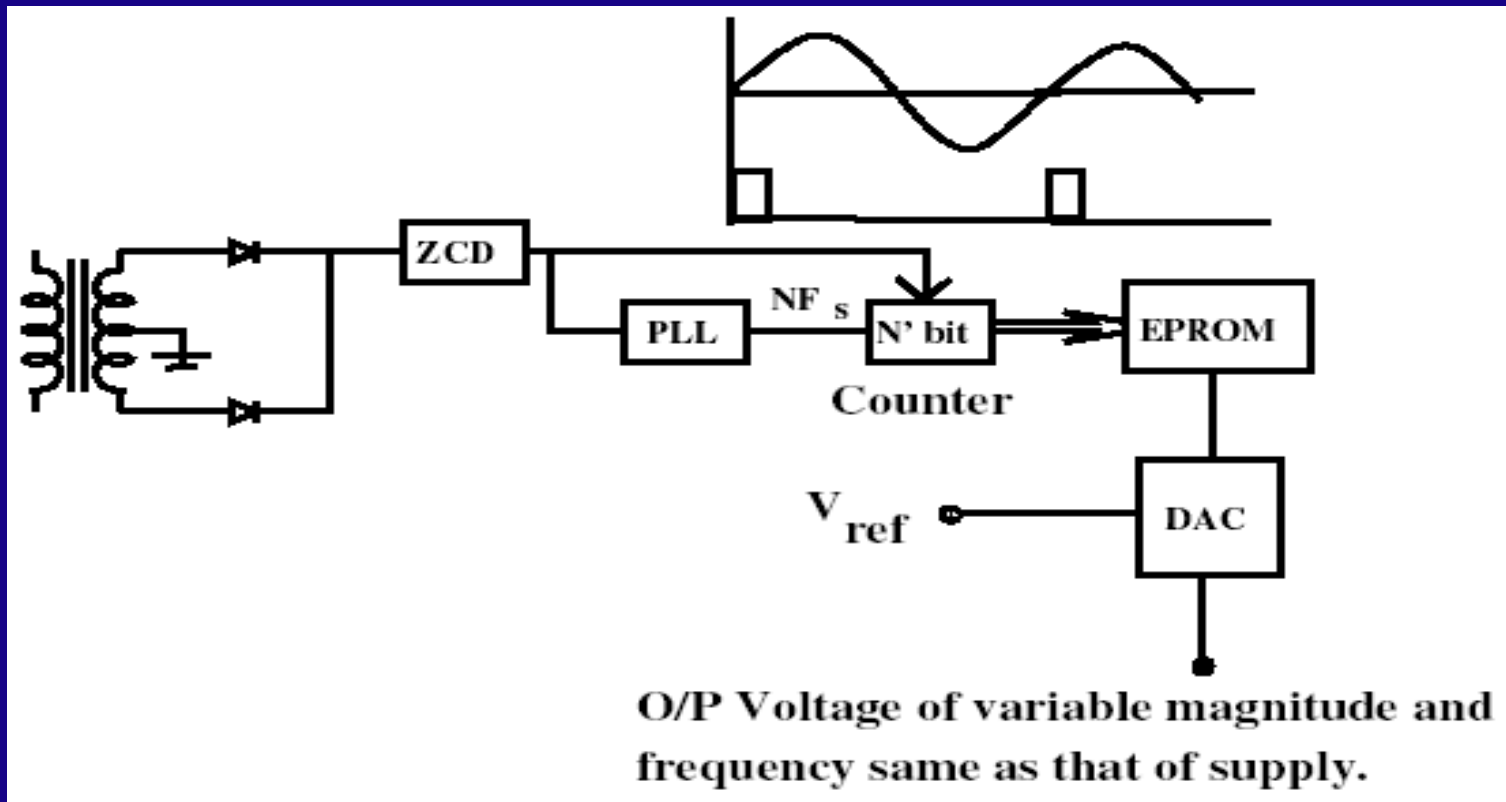
How to get a sine wave of variable magnitude & synchronized with the mains ?

⇒ Step down transformer & a potential divider.

⇒ Digital synthesizer.



Simple scheme:



→ Other sophisticated schemes using DSP are available.

Switched Mode Rectification:

To decrease THD of source I using low frequency passive elements:

⇒ Large size, weight.

⇒ size of passive elements ↓ IF converter devices are switched at high frequency.

⇒ size of L & C depend on switching frequency and NOT on source frequency.

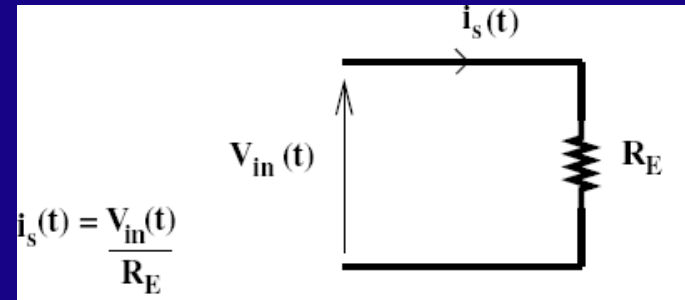
⇒ PWM rectifier → P.F. and THD improves.

$$|V_o| < V_m$$

⇒ Application requires constant DC power supply
(Low ripple in V_o)

- Harmonics in source I should be low.
- Reactive VA should be minimum.

- ⇒ Desired that source P.F. = 1
- ⇒ Source I and V are in phase.
- ⇒ Rectifier system presents a resistive load to AC system.
- ⇒ R_E is the 'emulated resistance' of the converter.
- ⇒ Power is not dissipated as heat.
- ⇒ Transferred to the o/p port.
- ⇒ Model representation.



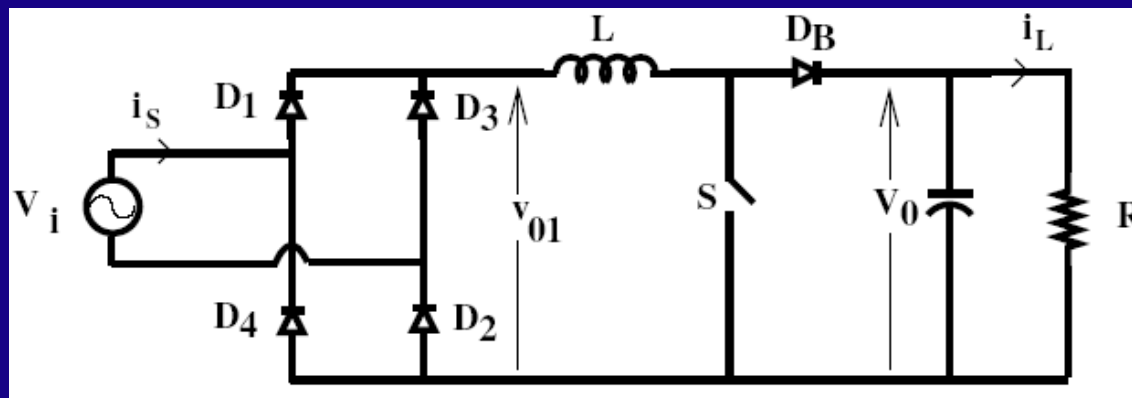
Single phase Switched Mode Rectifier:

Assume ' V_0 ' is constant and ripple free.

Keep 'S' open & the bridge is energized.

At steady state,

$$\text{Avg}(v_{o1}) = \text{Avg}(V_0)$$

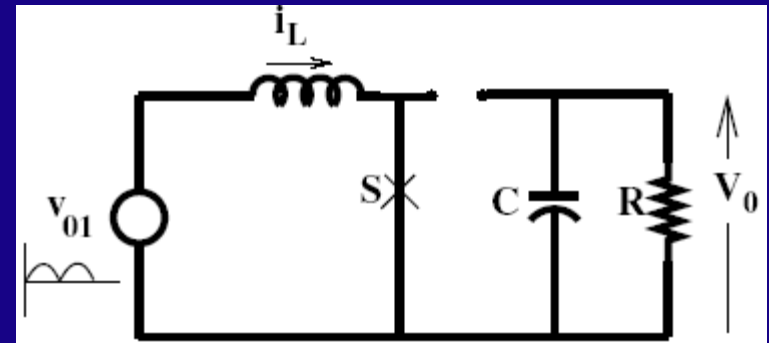


Switch 'S' is closed ON/OFF at a frequency $\gg F_s$

\Rightarrow Under this condition, ' v_{01} ' is assumed to remain constant at a value = instantaneous value.

e.g.: at $\omega t = \frac{\pi}{2}$, $v_{01} = V_m$

at $\omega t = \frac{\pi}{3}$, $v_{01} = \frac{\sqrt{3}}{2} V_m$



\Rightarrow When 'S' is closed, $V_L = v_{01} \rightarrow$ constant and +ve.

$i_L \uparrow$ linearly.

Cathode pot. of $D_B = V_0$ w.r.t -ve DC Bus.

$\therefore V_{DB} = -V_0$ (Blocking State)

Capacitor supplies power to the load.

Open 'S':

Stored energy in 'L' is transferred to the output.

⇒ i_L increases when 'S' is closed.

⇒ i_L should decrease when 'S' is opened.

⇒ $i(t) = i(t+T)$

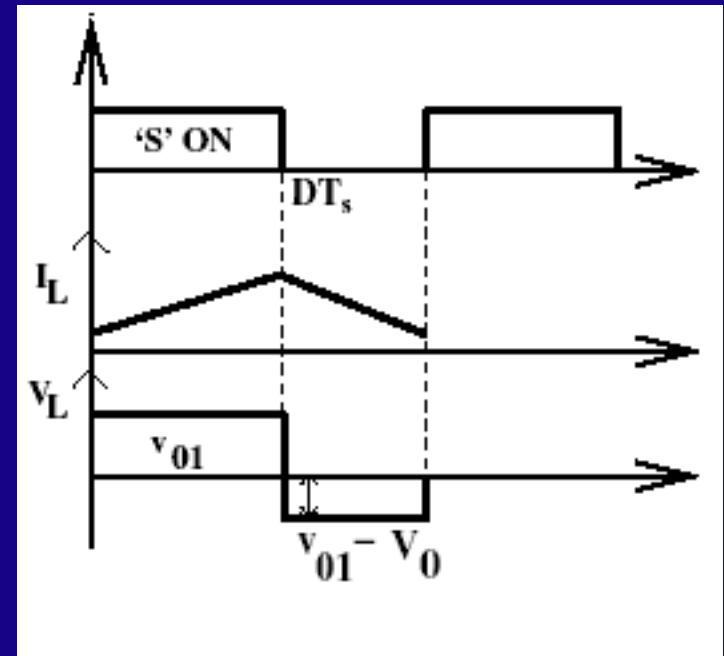
⇒ V_L should be negative.

Let 'D' be the duty cycle.

$$D = \frac{T_{ON}}{T_{ON} + T_{OFF}} = \frac{T_{ON}}{T_s}$$

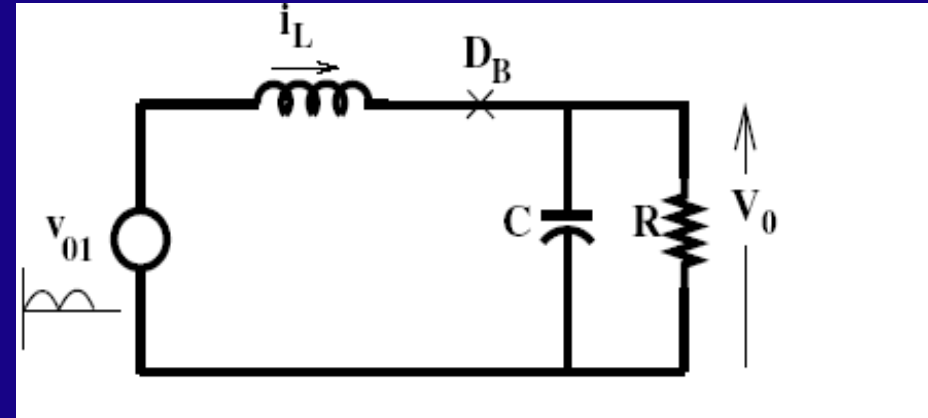
Switch is ON for DT_s and OFF for $(1-D)T_s$

Assume that i_L is continuous.



Switch is OFF for $(1-D)T_s$.

$$V_L = (V_{01} - V_0)$$

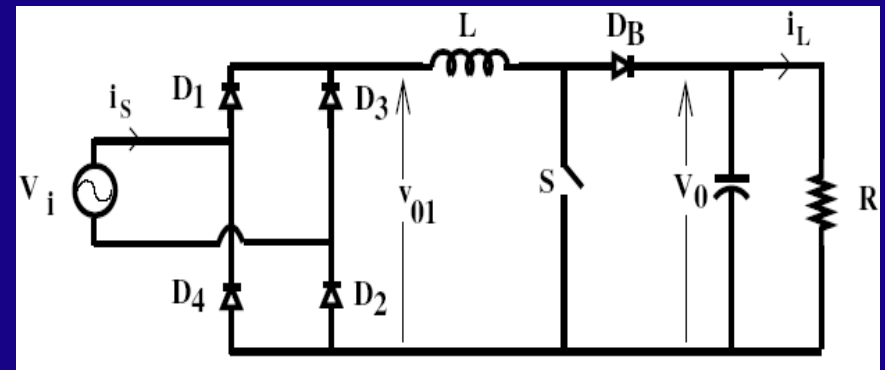


\Rightarrow At steady state, V_L should be -ve during $(1-D)T_s$.

$$\therefore V_0 > V_{01}$$

\Rightarrow Peak value of $V_{01} = V_m$

$$\therefore V_0 > V_m$$



⇒ **BOOST CONVERTER:**

$$V_{01} DT_s = (V_0 - V_{01})(1-D)T_s$$

$$\therefore V_0 = \frac{V_{01}}{(1-D)}$$

⇒ Energy is stored in the inductor when 'S' is ON.

⇒ Stored energy is transferred to the load when 'S' is opened.

How to choose D:

Case 1:

Switching frequency is held constant.

Also, keep D constant.

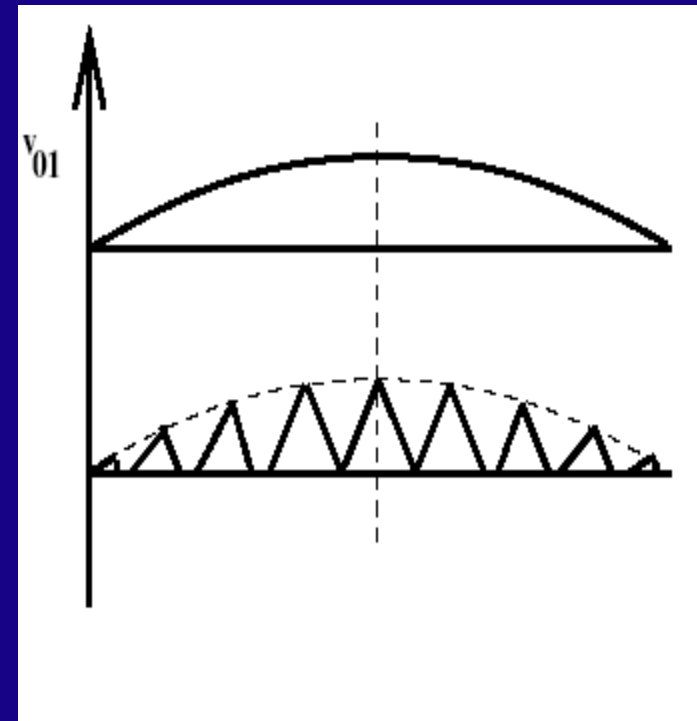
Choose D in such a way that i_L is

JUST CONTINUOUS at $\omega t = \frac{\pi}{2}$.

$\Rightarrow i_L$ will be discontinuous at $\omega t \neq \frac{\pi}{2}$.

$\Rightarrow \frac{di_L}{dt}$ is maximum at $\omega t = \frac{\pi}{2}$ ($v_{o1} = V_m$)

$\Rightarrow \frac{di_L}{dt}$ is minimum at $\omega t = \frac{\pi}{2}$ ($V_0 - v_{o1}$)



$$i_{\text{peak}} = \frac{V_{01}}{L} DT$$

$$i_{\text{peak}} \propto V_{01}$$

$$\therefore \max(i_{\text{peak}}) \text{ is at } \omega t = \frac{\pi}{2}.$$

$$\Rightarrow -\frac{di_L}{dt} \text{ is max. when } |V_0 - V_{01}| \text{ is max.}$$

$$\Rightarrow V_0 \text{ is held constant.}$$

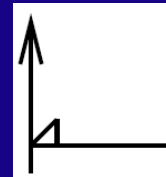
$$\Rightarrow -\frac{di_L}{dt} \text{ is max. when } V_{01} = 0 \text{ at } \omega t = 0, \pi$$

$+\frac{di_L}{dt}$ is min. near the zero crossing

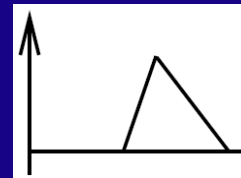
(for low values of ωt)

$-\frac{di_L}{dt}$ is max. near the zero crossing

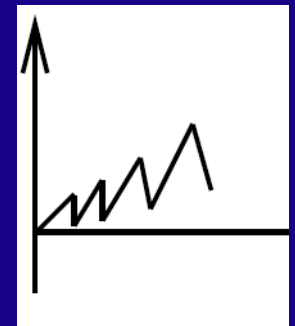
$\Rightarrow +\frac{di_L}{dt}$ is max. near $\omega t = \frac{\pi}{2}$



$\Rightarrow -\frac{di_L}{dt}$ is min. near $\omega t = \frac{\pi}{2}$



\Rightarrow If i_L is JUST CONTINUOUS near the zero crossing as $\omega t \uparrow$ towards 90° , 'i' will be continuous and may saturate the inductor.



- ⇒ Peak value of ' i_s ' is \propto instantaneous value of V_i
- ⇒ displacement factor = 1
- ⇒ Using a small filter, high frequency components can be filtered out.
- ⇒ P.F. \approx 1.

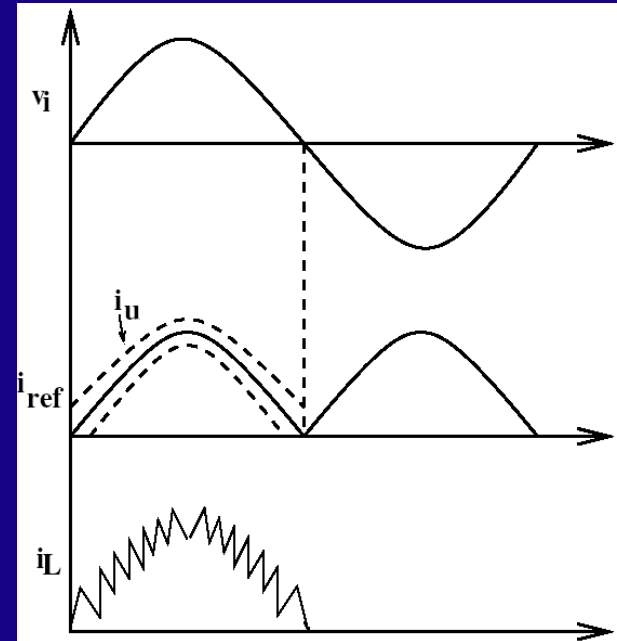
Case 2:

Take a Full wave rectified sine wave of required magnitude and in phase with v_{o1} .

⇒ Call this as i_{ref}^* .

⇒ Choose an upper band → i_u^*
& a lower band → i_L^* .

⇒ Measure inductor current and control it in such a way that it lies within i_u^* & i_L^* .



- ⇒ Closing 'S' increases i_L & opening 'S' decrease i_L .
- ⇒ When $i_L = i_L^*$, close 'S' $\Rightarrow i_L \uparrow$ and $i_L = i_u^*$, open 'S' $\Rightarrow i_L \downarrow$.
- ⇒ i_L current \square rectified sinusoid
- ⇒ $i_s \square$ sine wave.
- ⇒ Smaller the band, Higher the switching frequency.
- ⇒ Switching Frequency is function of Load.