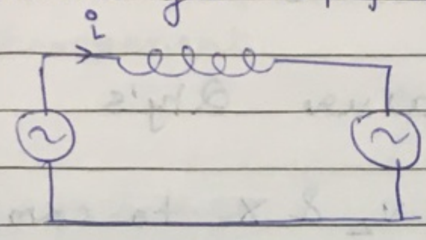
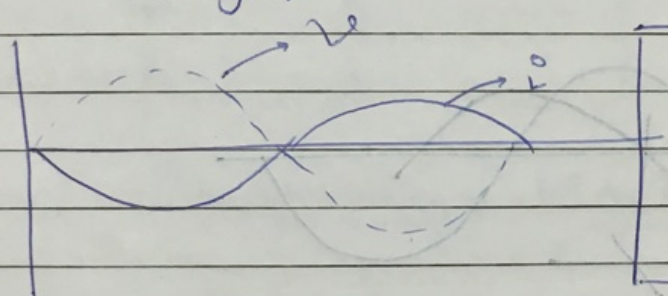
→ Can we get upf current using sine PWM?



- Sine PWM: Indirect
  We are generating the voltage waveform which forces the ~~sine~~ current.
- HB PWM: Direct

→ To supply power to DC source



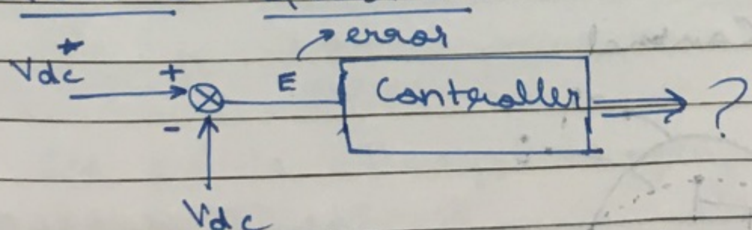
→ Achieve upf

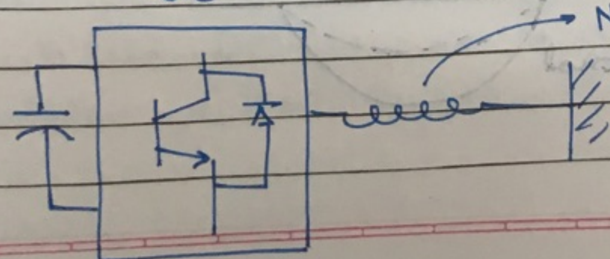
AC → DC conversion

→ Choose δ such that in the Inphase comp. of current, there is power balance.

23.3.17

Quiz-2 Question





→ Not required when feeding IM, Leakage limits current.

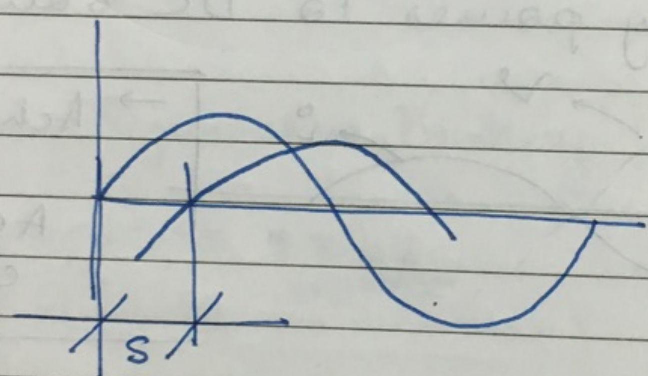
$$? = \frac{V_1 V_2}{X} \sin \delta$$

→ Not possible to measure Qty's

• Can't measure V_1, V_2 & X to compute δ. Recorded Information not used.

V_{dc}^* → Desired (say 600V) (Reference)
V_{dc} → Actual : say 590V (Cap. Voltage)

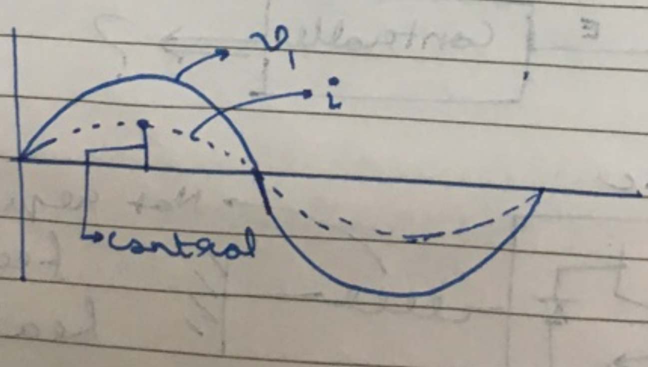
→ Cap. Voltage is falling



→ Supplying power to cap. must ↓

Voltage control → δ

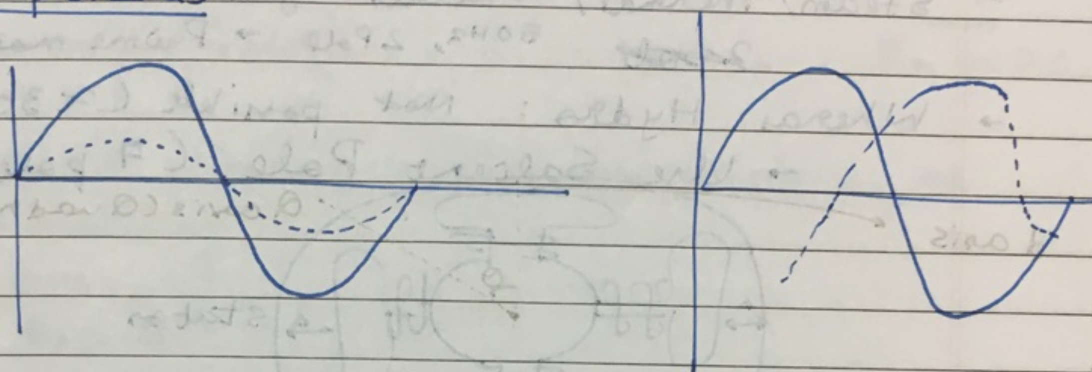
→ Current Control



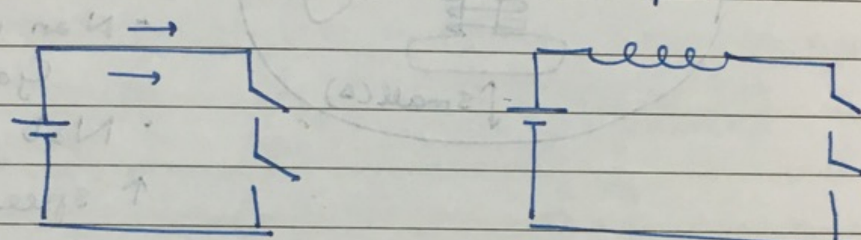
→ Non upf ($\delta = 90°$ say,) $\Rightarrow P = 0$
Must find in phase component and quadrature component.

$$\Rightarrow \cancel{\frac{N_1 V_2 \sin\delta}{X}}$$

2 components



Q-4)



Synchronous Machine

- Used in ALL generators.
- Speed is independant of load. $\frac{120F}{P}$
- Usually MW range

Stator	Rotor	
AC	DC	→ Mostly
DC	AC	→ Rare (Why?)

Find out why?

- In IM pf is always lagging. since I_M must be supplied
- Brushless DC Motor is a synchronous machine (PM Synch. Machine)

Syn. Generator

- Stator → 3 φ Sine. distributed winding
- Rotor → DC I
  - → 2P Cylindrical

→ Steam/ Thermal/ Nuclear Gen. are 2 pole

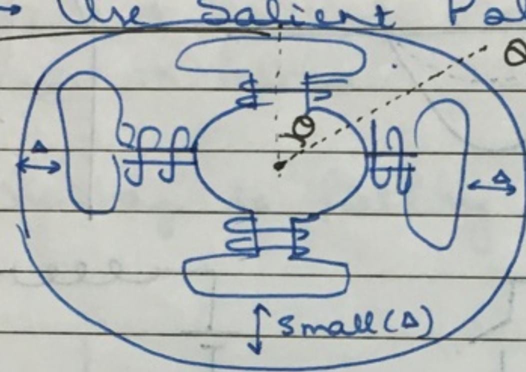
~~2 pole~~ 50Hz, 2 Pole → Prime mover 3000 rpm

→ Wheras Hydro : Not possible (≈ 300 rpm)

→ Use Salient Pole (4 pole const.)

d axis

Q axis (Quadrature Axis)



stator

- Non unifor Air Gap.
- Not suitable for ↑ speed (Air resis?)

Field Axes

→ d axis (Small Air Gap)

→ Q axis (Larger Air Gap)

→ $\mathcal{R}_d << \mathcal{R}_Q \Rightarrow X_d >> X_Q$

Equivalent Ckt

→ I_F in Rotor winding, producing flux,

Assume N_s = 3000 rpm (2pole)

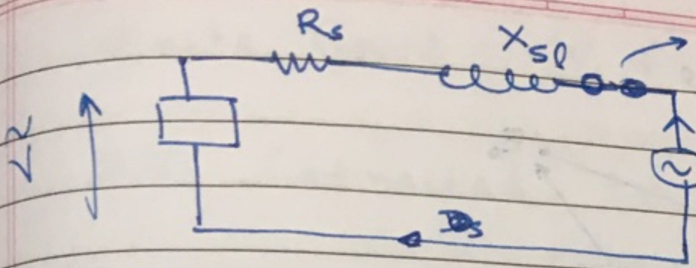
→ ϕ_{DC} 3000 rpm

→ Stator (AC winding) voltage Induced

~~RMS value ∝ 4.44 × F × ϕ_{DC}~~

RMS value ∝ ωI_F

(Also number of turns in stator, can't change)

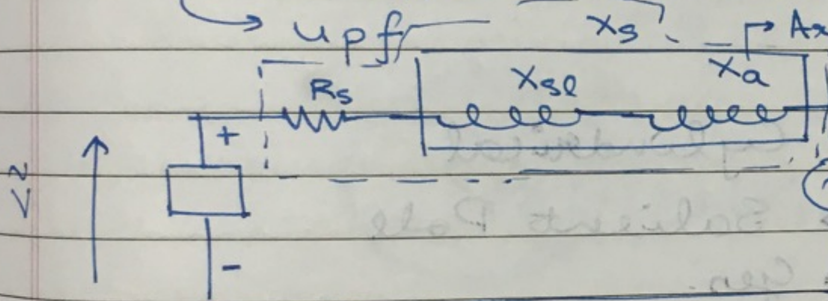


What else

$E_0 \propto \omega I_F$ (Due to field flux alone) → was E_b in DC

- In DC Machine, there was Arm. Rxn. (Current flows in S, has its own field)

- Current flowing could aid / oppose or do nothing
  - → Aid
  - → Oppose
  - → Net effect = 0 (Cross Magnetization) → upf

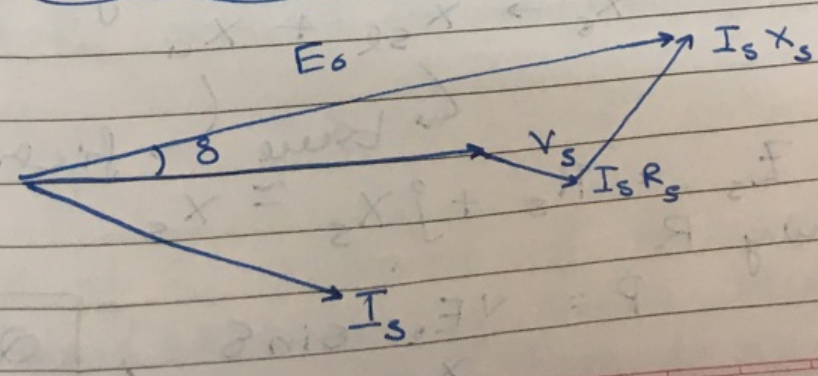


Armature rxn reactance

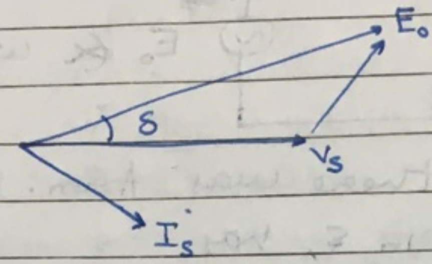
X_a → Not a real reactance

X_s → Synchronous reactance

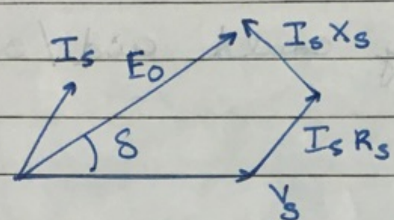
Z_s → $R_s + jX_s$ (Syn. Impedance)



→ Ignore resistance



→ Leading Current

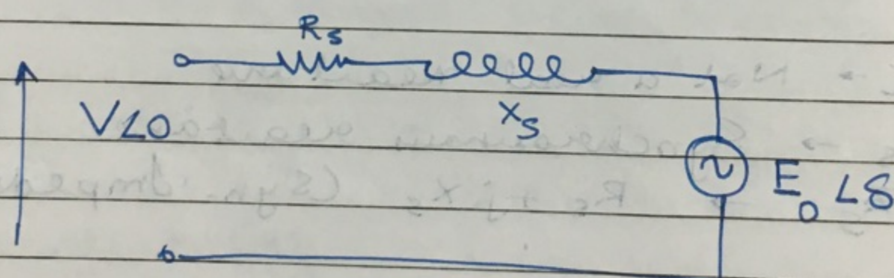


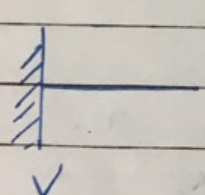
28.3.18

Syn Machine

Recap: → Cylindrical
→ Salient Pole

Eqvt Ckt for Gen.





$R_s \rightarrow$ Must be very low

$X_s \rightarrow X_{sl} + X_a$

X_{sl} ↳ true, X_a ↳ fiction

$$Z_s = R_s + jX_s \simeq X_s$$

→ Ignoring R

$$P = \frac{VE_o}{X_s}\sin\delta \quad , \quad \boxed{Q = ?}$$

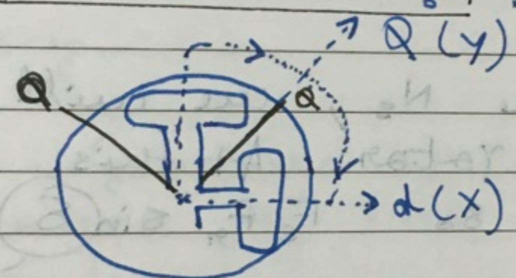
→ Infinite Grid : V, f are fixed

1) M/C Connected to the grid $\rightarrow$ V, F = K

→ Power output cannot change unless there is change input.

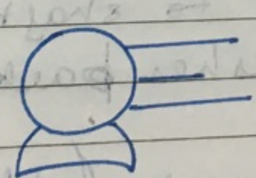
→ Hence on change in excitation : Active component cannot change ⇒ Reactive comp. changes ⇒ P.F $\uparrow$

H.W : $\boxed{\text{Derive : } P = ?}$ for salient pole.



$\boxed{X_d >> X_q}$ → less Magnetizing current required

→ Synchronous Motor



Self Start?

→ $T \propto F_s F_r \sin\delta$

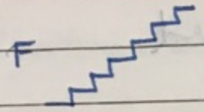
F_s & F_r should be stationary (steady state)

$F_s \rightarrow \frac{120F}{P}$

$F_r \rightarrow$ 0 at start

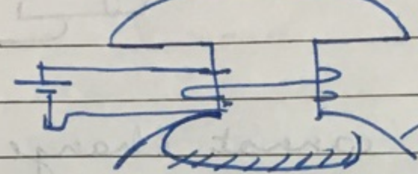
→ Speed of F_r = Speed of Rotor

→ If freq. (at start) is small then rotor may catch up (Depends on Inertia)



→ Rotor may catch up ⇒ $N_r \uparrow$

Winding Solution



→ Rotor has both $\underbrace{\text{cage Rotor}}_{\text{starts}}$ & $\underbrace{\text{DC type.}}_{\text{at Syn. speed.}}$

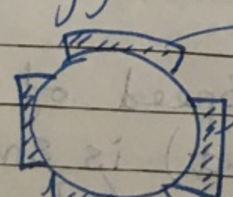
→ Before synch. speed, cage Rotor gives torque like IM

→ Just before N_s, we will close DC source to rotor. At this $N_r < N_r$ (slightly) so $F_s F_r \sin \delta$ → not constant

→ Pulsations will push Rotor to N_s

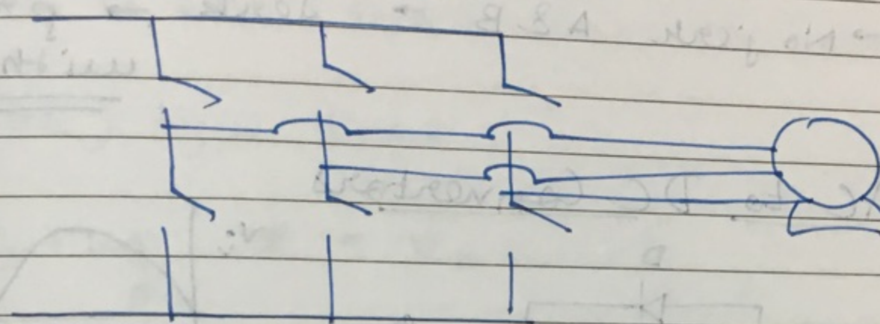
• If we add load to shaft, again $N_r < N_s$ & Cage pushes back to δ (N_s)

• Permanent Magnet (Unstable since for certain loads: Sudden Impact loads) OK for fan & pump since T_L cannot change instantly (∵ we cannot change instantaneously)



- Address ~~con~~ unstability using control systems. (What happens on sudden loading)

PMSM (Per. Mag. SM)

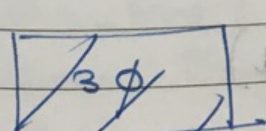


- Stator unaffected by any such external event.
- Rotor speed determined by stator frequency

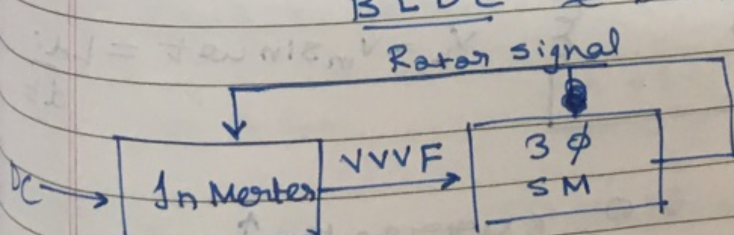
Instead: Generate stator frequency as a function of rotor speed. (Make it dependant)

- No longer a constant speed/synchronous machine. (Similar to DC machine)

But no brushes ⇒ Brushless DC motor



BLDC ~~(Brush~~



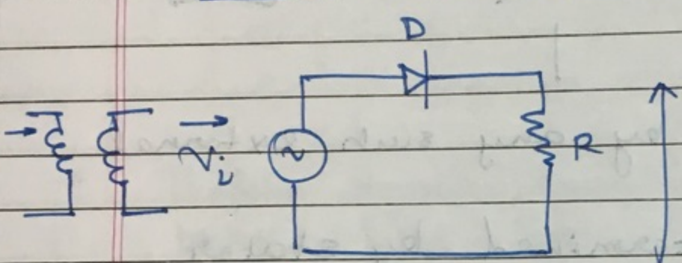
3φ SM has per. magnets & its synch. speed depends on rotor speed.

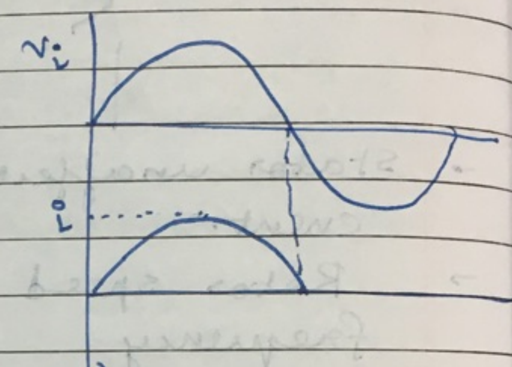
Have → Read!

Starting BLDC

→ Stator phase ABC (like F control)
Excite A ~~with~~, Jerk? → proceed
→ No jerk A & B → Jerk → proceed
with F ↑ AB, BC →

AC to DC Converters





$\alpha \to 0$ (conduction starts)
$\beta = \pi$ (conduction stops)

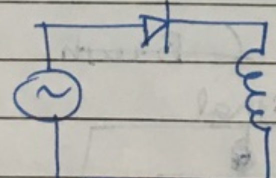
$\gamma = \beta - \alpha =$ Conduction period, on time

$$\boxed{V_o = \frac{V_i}{\pi}}$$

→ DC/Average value.

→ R → L (Purely Inductive load)

$\alpha = 0$
$\beta = 2\pi$



$V_L = V_m \sin \omega t = L\frac{di}{dt}$

$\alpha > 0 \to L\frac{di}{dt} > 0$, current ↑

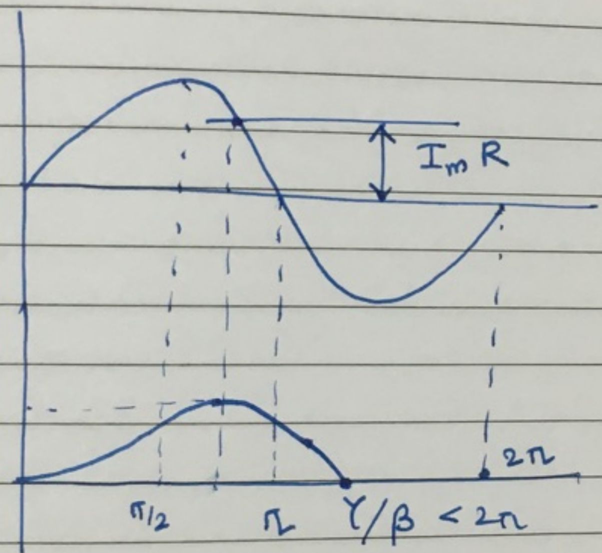
$\alpha = \pi \to L\frac{di}{dt} = 0 \Rightarrow$ Current $= i_m$

$2\pi > \alpha > \pi \rightarrow L\frac{di}{dt} < 0 \Rightarrow$ current decreases from i_m

$\Rightarrow$ v_o is sine, but i_o is not (unidirectional)

→ (R+L) type load.

$$Ri + L\frac{di}{dt} = v_m \sin \omega t$$



→ As $\gamma \uparrow$, average value of $v_o \downarrow$ (Counter Intuitive)

Reason: Beyond π, v_i is < 0

Quiz-4 soln.

A-1) 2m + 2m
1m → Any
1m → Just.

A-2) Must show subtraction of two sines.

A-3) fourier transform ✓

A-4) Table: 1m (All 4 Any) (0.25×4)
1m (All Just) (0.25×4)