

Review :

1.AC → Avg. value of o/p $V = 0$



→ There has to be AC to
DC conversion to provide input DC

Features

⇒ Input is 12V DC

O/P - 230V, 50Hz AC

Induction Machine

→ For $T_l = \text{constant}$

Input power is ; Constant
and independent of speed

For wide variation in speed N_s has to be changed

$$\bar{I}_M ; \frac{\bar{E}_1}{2 \pi F L_M} ; \frac{V_s}{2 \pi F L_M}$$

What is the relationship between the magnitude of o/p voltage and frequency?:

$$T \propto F_{SR} F_r \sin \left| \frac{F_r}{F_{SR}} \right|$$

$$\propto \Phi I_r'$$

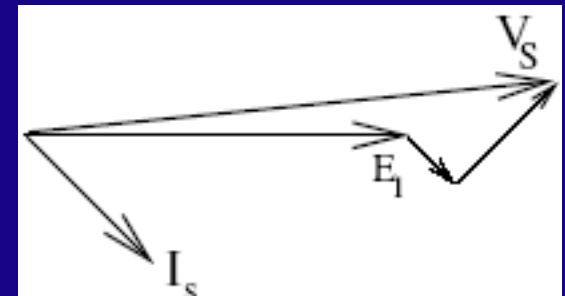
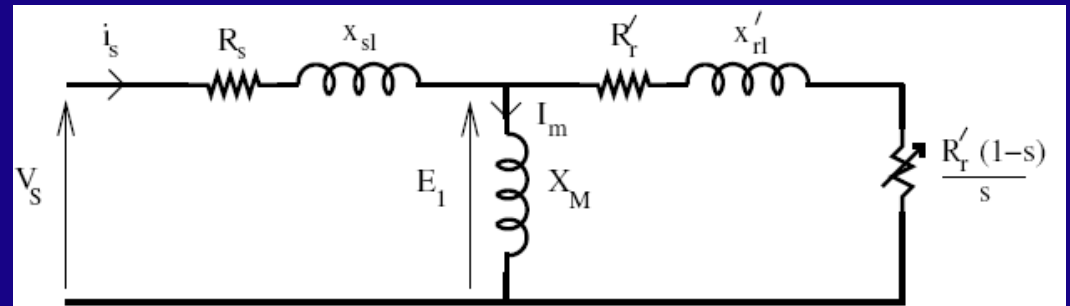
$$\propto I_M I_r'$$

$$\bar{I}_M = \frac{\bar{E}_1}{2 \pi F L_M}$$

Generally R_s and x_{sl} are small

Also at relatively high 'F' (25 - 50Hz)

$$|E_1| \propto |V_s| \quad \therefore \bar{I}_M = \frac{\bar{V}_s}{2 \pi F L_M}$$



Case 1: V_s constant & $\downarrow F$ to $\downarrow N_s$

$|I_M| \uparrow \Rightarrow \Phi$ tends to \uparrow

All magnetic circuits operated at the knee point

If magnetising $AT \uparrow$, core gets saturated.

\Rightarrow I/p 'I' becomes peaky and core loss \uparrow

Case 2: Keeping V_s constant and $\uparrow F$ to $\uparrow \underline{N_s}$

$$\Rightarrow I_M = \frac{V_s}{2 \pi F L_M} \downarrow \Rightarrow \Phi \downarrow$$

N_s increases N_r increases

to increase the speed of the induction machine we can increase the frequency or weaken the field

\Rightarrow If $V_s = V_{\text{rated}}$ & F is \uparrow above F_{rated}

N_s and $\therefore N_r$ also \uparrow above rated.

$$\Rightarrow |\Phi| \downarrow$$

\Rightarrow similar to field weakening mode of DC motor

$[V_a \text{ constant \& } I_f \downarrow]$

\Rightarrow Possible mode of operation

\Rightarrow DC / AC converter should have the feature

$$\text{that } |V_s| = V_{\text{rated}}$$

and ' F ' should be able to \uparrow .

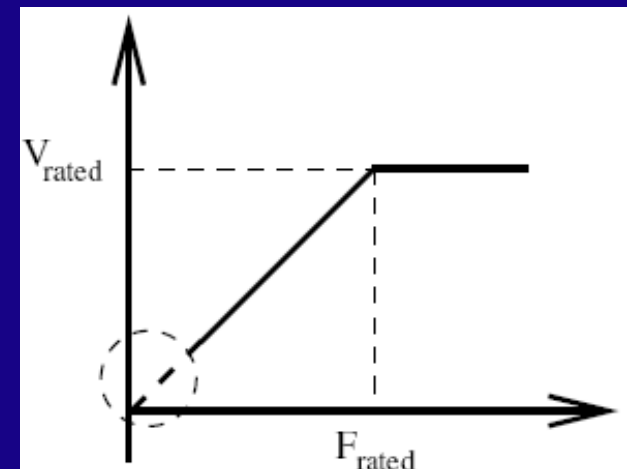
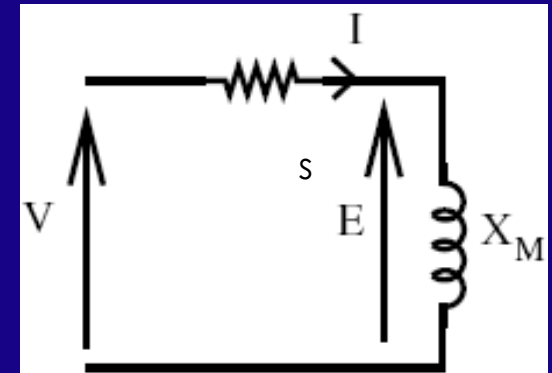
Case 3 : In S.E. DC motor, Φ (I_f)
was kept constant from 0 to N_{rated} .
 \Rightarrow Constant Φ operation

$$I_M \propto \Phi ; \frac{V}{2 \pi F L_M}$$

If $\frac{V}{F}$ is held constant, ' Φ ' remains constant.

At low ' F ', $x_{sl} \rightarrow 0$, circuit is DC

$$\underline{V = E + I_s R}$$



⇒ DC - AC converter should have
another feature

⇒ Variable voltage & variable 'F' (VVVF)

Majority of DC-AC converters used
in AC drives

High frequency induction heating,
surface hardening

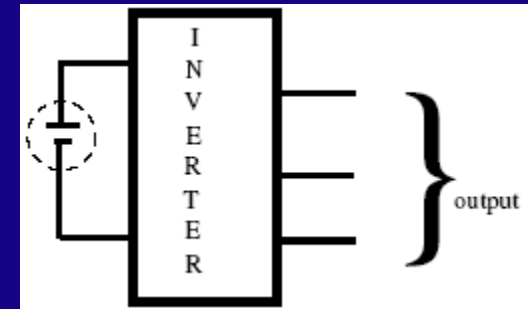
Types of Inverters :

If the input to the inverter is a voltage source

⇒ Battery or large 'C' [input 'Z' \rightarrow 0]

⇒ Voltage Source Inverter [V.S.I]

⇒ 'I' can reverse & not 'V'

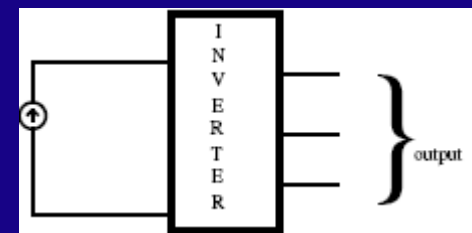
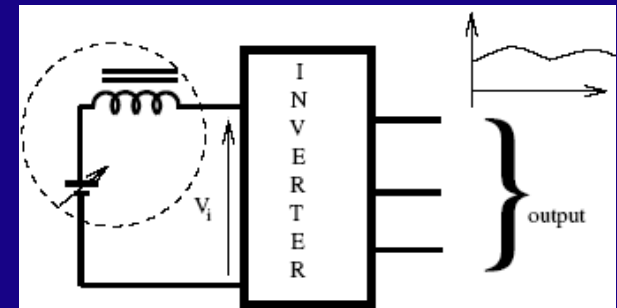


⇒ If it's a current source

⇒ Current Source Inverter [C.S.I]

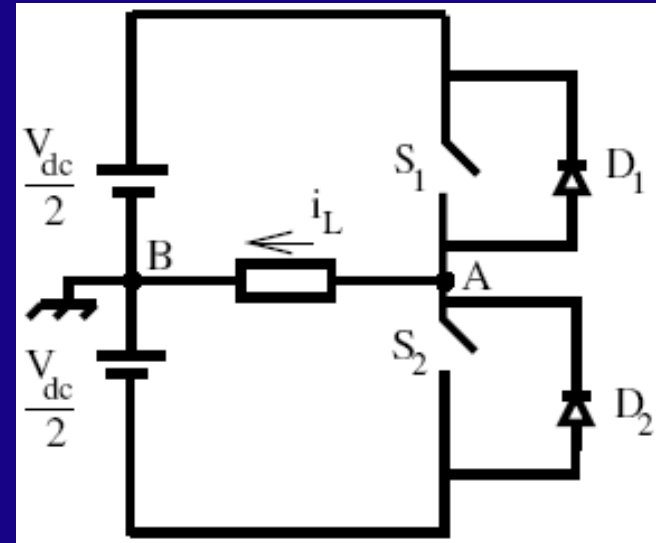
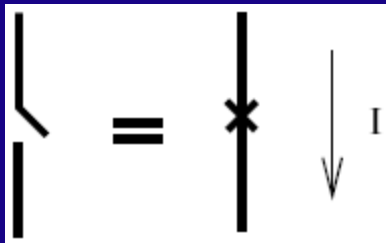
⇒ ' V_i ' can reverse and not 'I'

⇒ Input L is very high



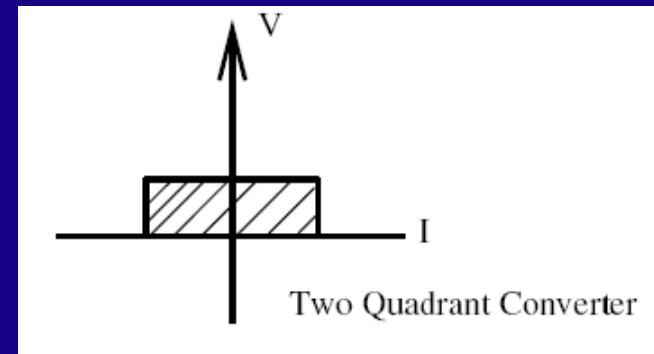
Circuit configuration of V.S.I :

Basic Block: $\frac{1}{2}$ Bridge



Since 'i' can reverse, switches should be able to carry bi-directional I

⇒ Connect a diode in anti parallel

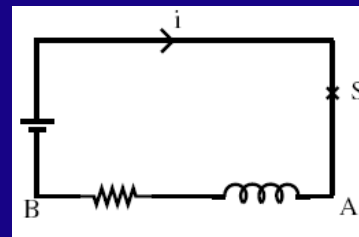


In VSI :

Switching signals for S_1 & S_2
(same leg) are always
complimentary. (ideal condition)

S_1 ON :

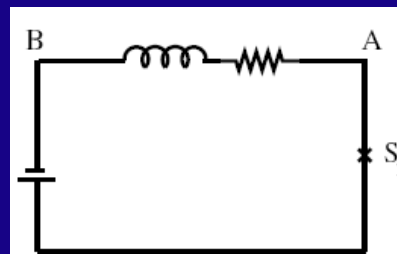
For $\frac{T}{2}$ duration, $V_{AB} = \frac{V_{DC}}{2}$



load = R-L

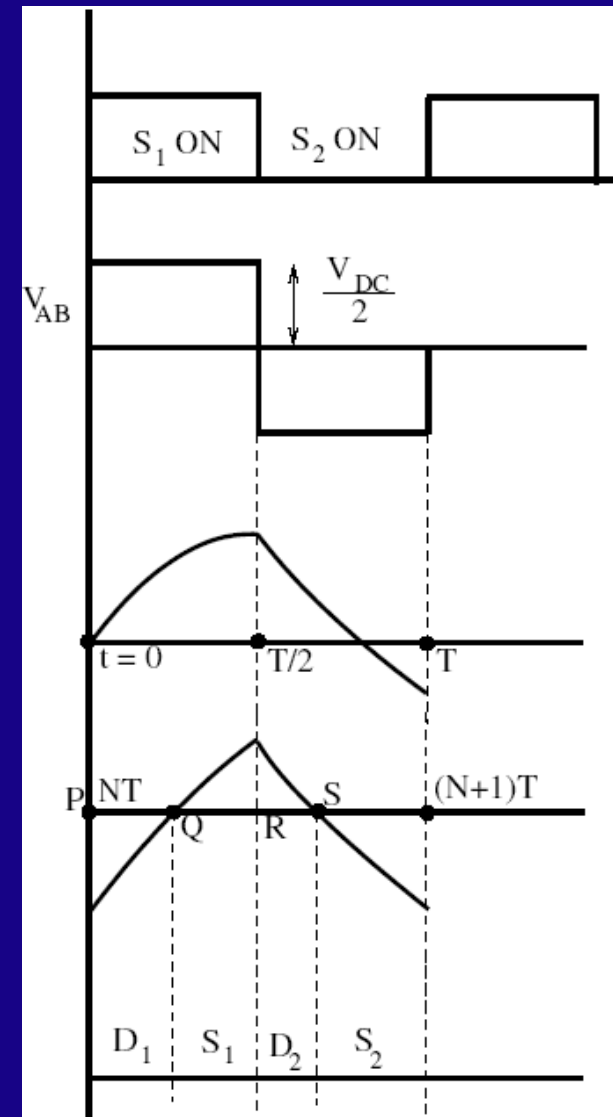
$$i = \frac{V}{R} [1 - e^{-\frac{t}{\tau}}]$$

S_1 OFF and S_2 ON :



$$V_{AB} = -\frac{V_{DC}}{2}$$

'i' will decay and become negative.



Observations :

Time for which S_1/S_2 is ON will determine the frequency of ' V_0 '.

$$\Rightarrow \text{if } \frac{T}{2} = 10 \text{ msec, } F = 50 \text{ Hz}$$
$$= 100 \text{ msec, } F = 5 \text{ Hz}$$

At Steady State :

P-Q : V applied to the load = +ve

i_L is -ve [i flowing from B to A]

\Rightarrow ' D_1 ' is carrying 'I'

Q-R : 'V' and 'I' are +ve

'S₁' is carrying 'I'

R-S : 'V' is -ve and 'i' is +ve

'D₂' is carrying 'I'

S-T : 'V' and 'I' are -ve

'S₂' is carrying 'I'

If load is not purely resistive, switch should have a diode across it.

Dead Time :

To avoid shoot through across
DC Bus

⇒ Input 'V' = V_{DC}

Output V = $\frac{V_{DC}}{2}$

⇒ Has 3rd, 5th, 7th ... all odd harmonics.

THD $\approx 48\%$

