

## Review :

At steady state,  $V_0 > V_m$

If  $V_0 < V_m$ ,  $i_L$  will  $\uparrow$ , even when 'S' is opened.

$$\frac{di_L}{dt} = \frac{(V_{01} - V_0)}{L}; \text{ peak of } V_{01} = V_m$$

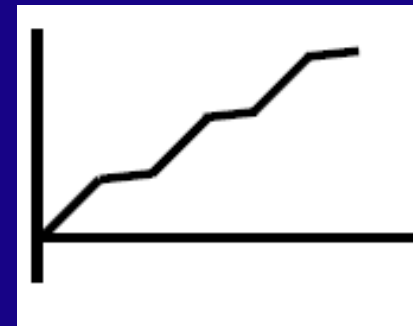
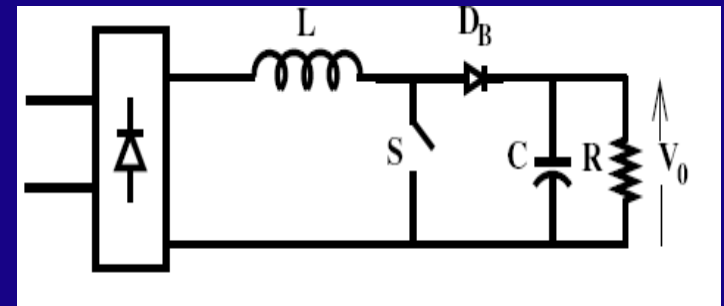
$\Rightarrow$  If 'S' is closed at  $t = 0^+$

$i_L$  and  $\therefore i_s$  goes on  $\uparrow$ .

When  $V_0 > V_{01}$ ,  $i_L$  starts  $\downarrow$ .

'V' rating of 'S' or  $D_B > V_0$

Switching time of  $D_B \approx$  that of 'S'



In fixed 'D' control,

$i_p \propto$  instantaneous value of  $v_{o1}$

$D \rightarrow i_L$  is just continuous at  $\omega t \approx \frac{\pi}{2}$

High frequency components of  $i_s$  can be filtered out using a small filter.

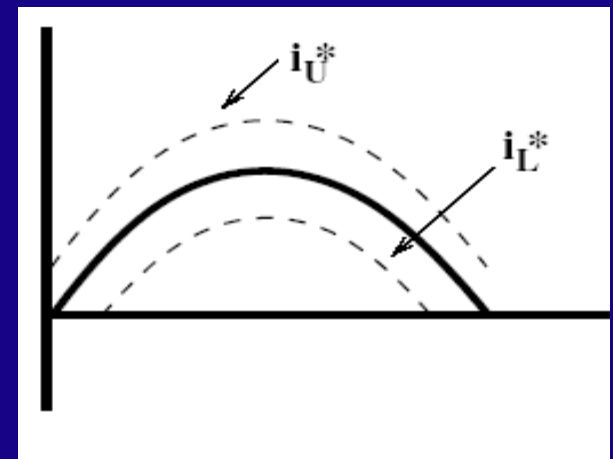
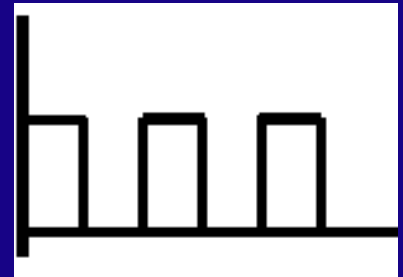
P.F.  $\approx 1$ .

$\Rightarrow$  Switching F is constant.

In current control,  $i_L^* \leq i_L \leq i_U^*$

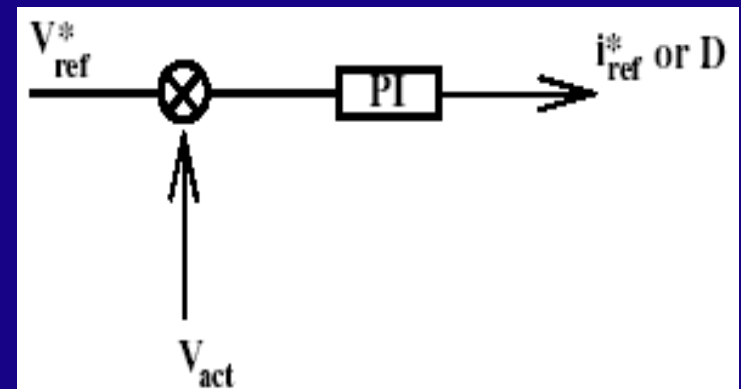
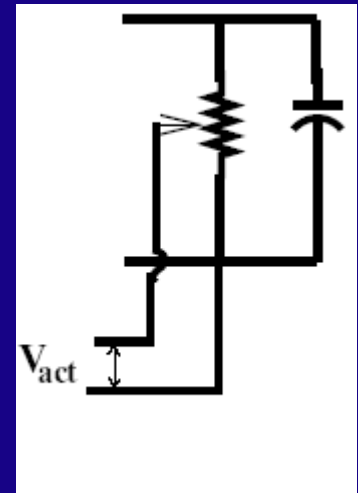
Smaller the band, Higher the switching frequency.

$\Rightarrow$  Waveform is superior.



How to choose the magnitude of  $i_{ref}^*$  or D:

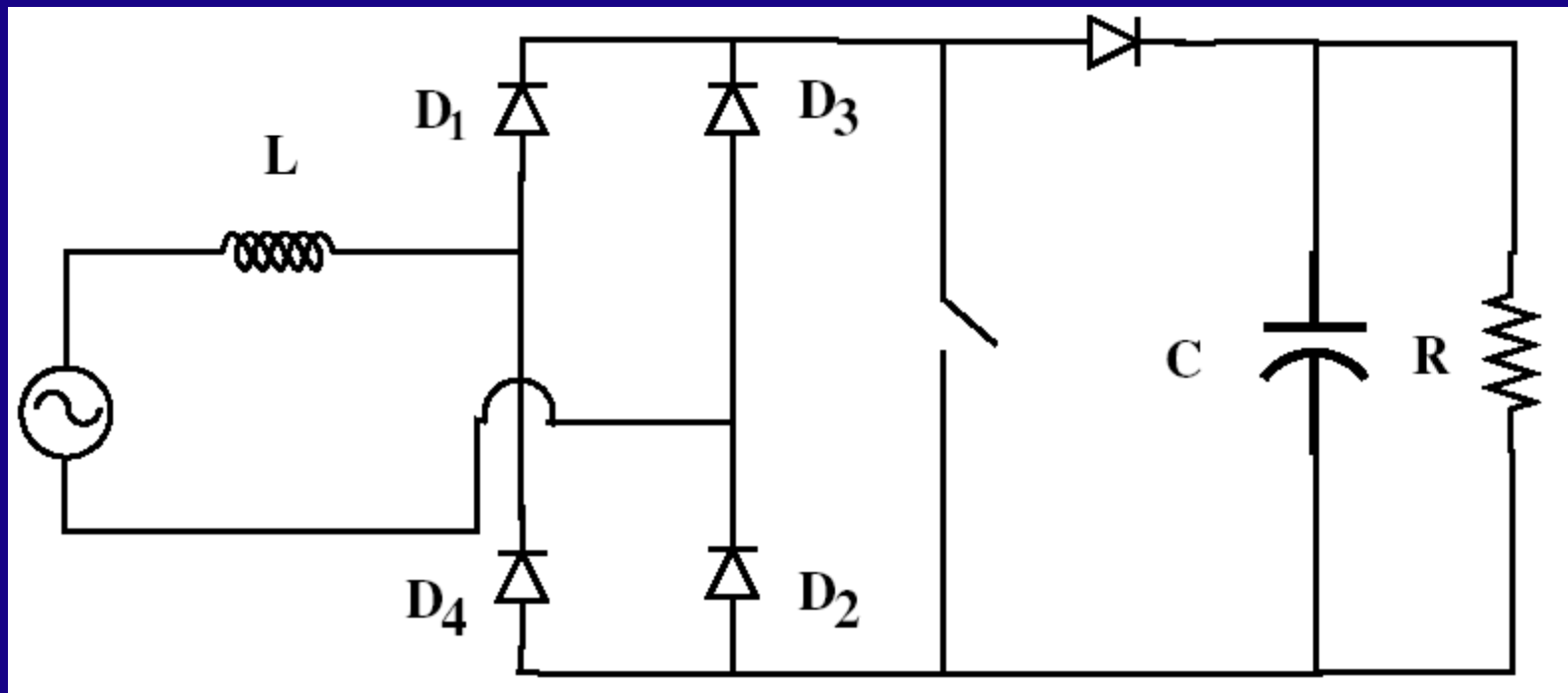
- ⇒ At the output side if  $V_o$  is constant.
- ⇒ Power supplied by the source = Power consumed by the load.
- ⇒ Input power =  $VI\cos\theta$ ,  $\cos\theta \approx 1$
- ⇒ If  $V_o \uparrow$  above the set value,  
decrease magnitude of  $i_{ref}^*$ .
- OR If  $V_o \downarrow$  below the set limit,  
increase magnitude of  $i_{ref}^*$ .



## Inductor on AC side:

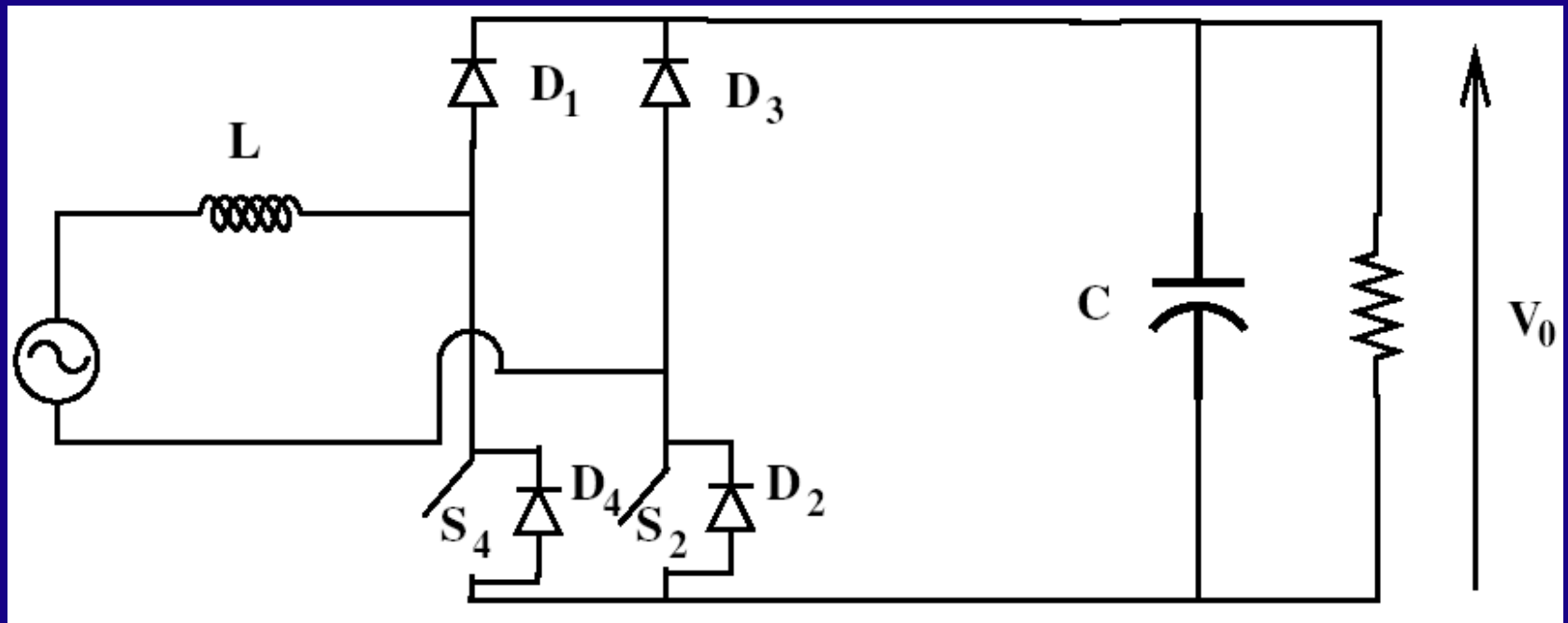
Principle of operation is the same.

⇒ Better utilization of iron (both halves of hysteresis loop).



## Case 3:

With two switching devices.



In the +ve half:

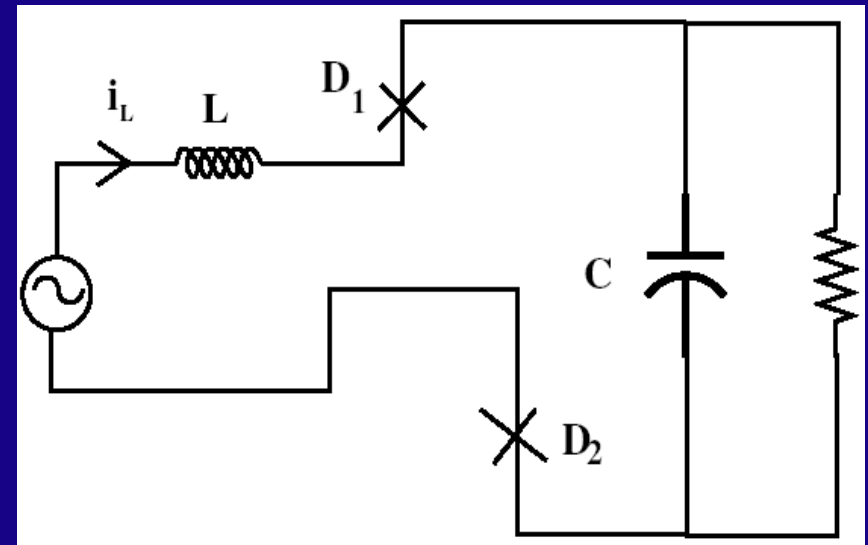
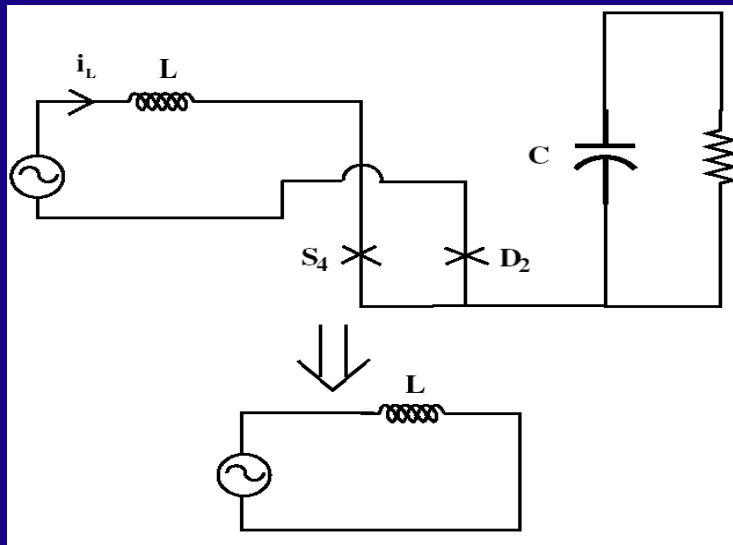
At a particular instant, close ' $S_4$ '.

$i_L \uparrow$  linearly.

'C' supplies power to the load.

Depending upon the switching strategy, open ' $S_4$ '.

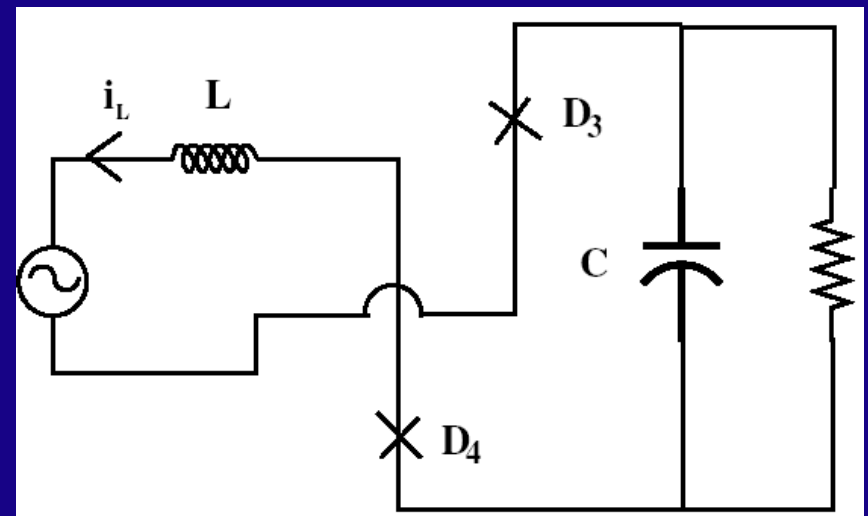
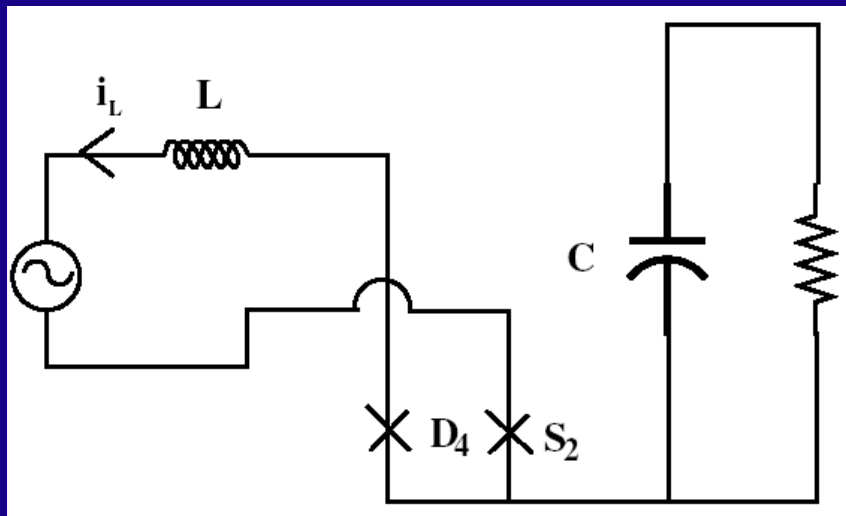
The stored energy is now transferred to the load.



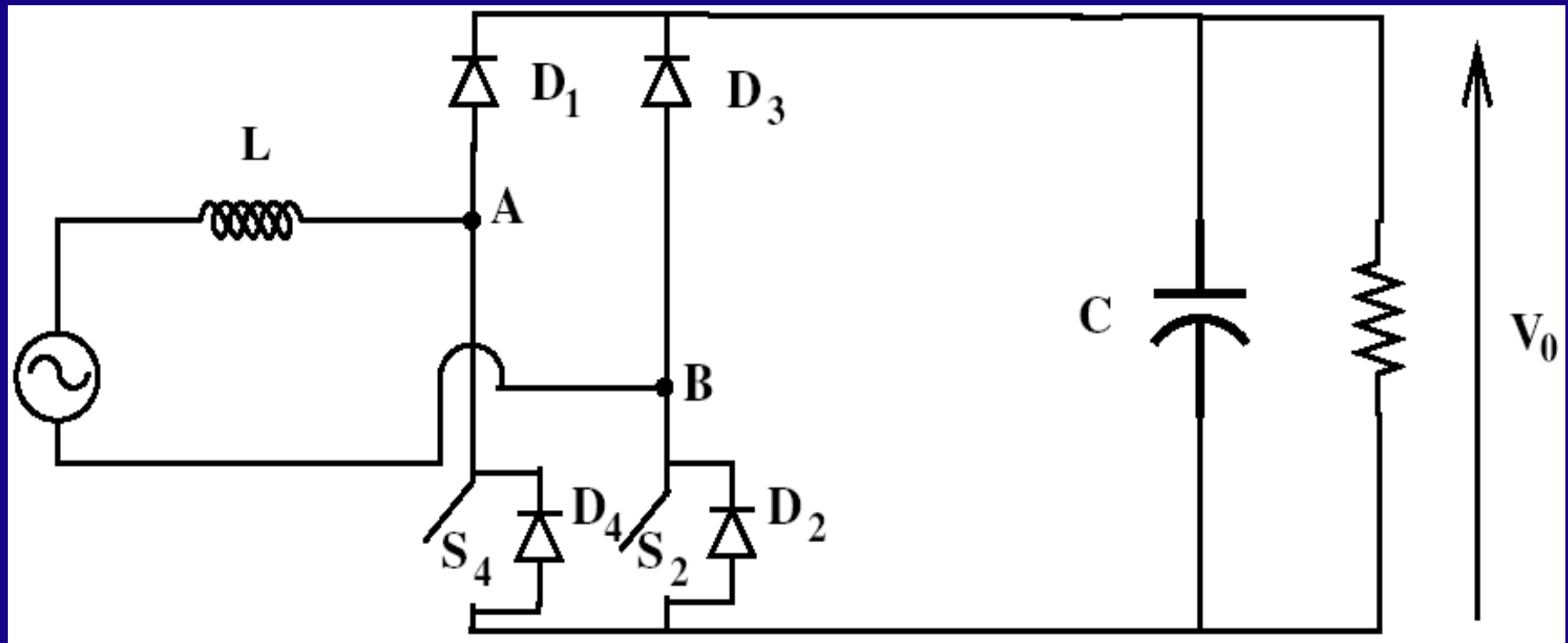


In the -ve half:

Close ' $S_2$ ' to  $\uparrow |i_L|$  and open ' $S_2$ ' to  $\downarrow |i_L|$



What sort of waveform across AB:

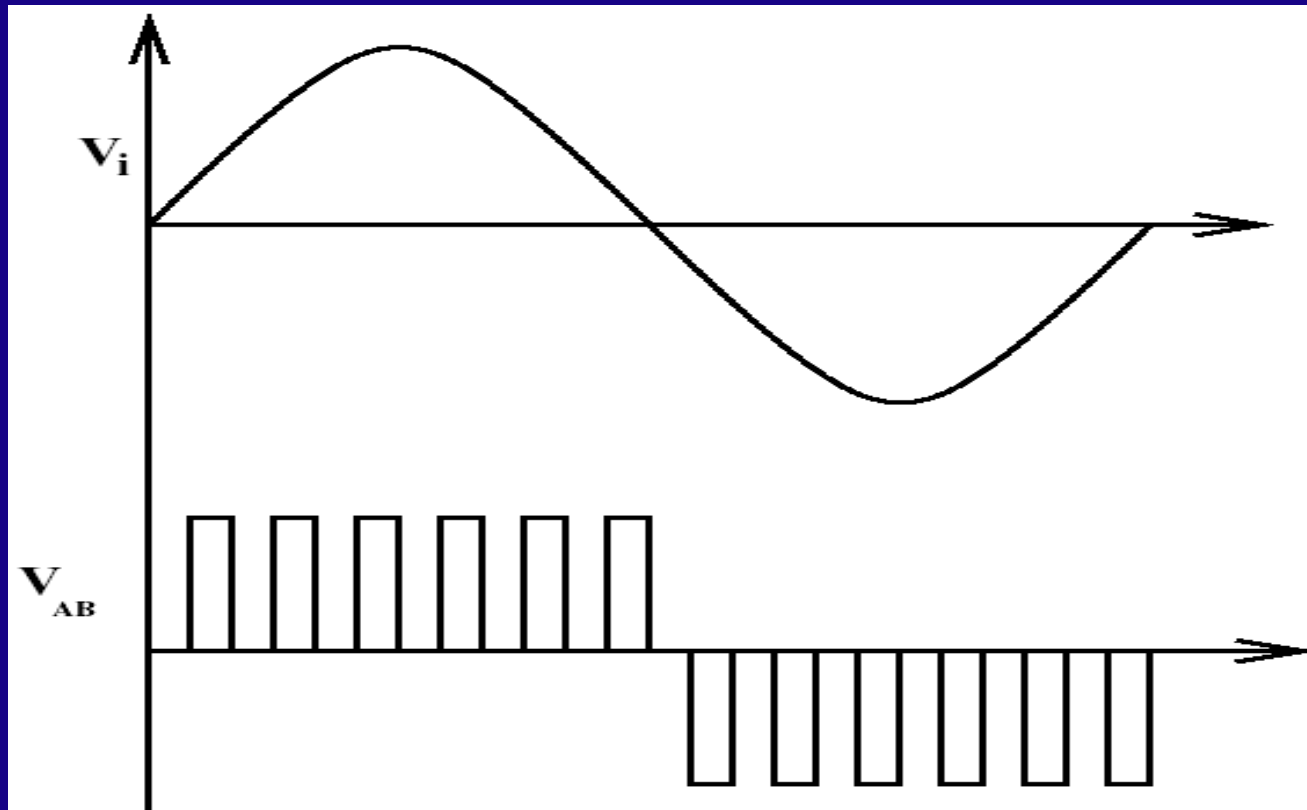




In the + ve half

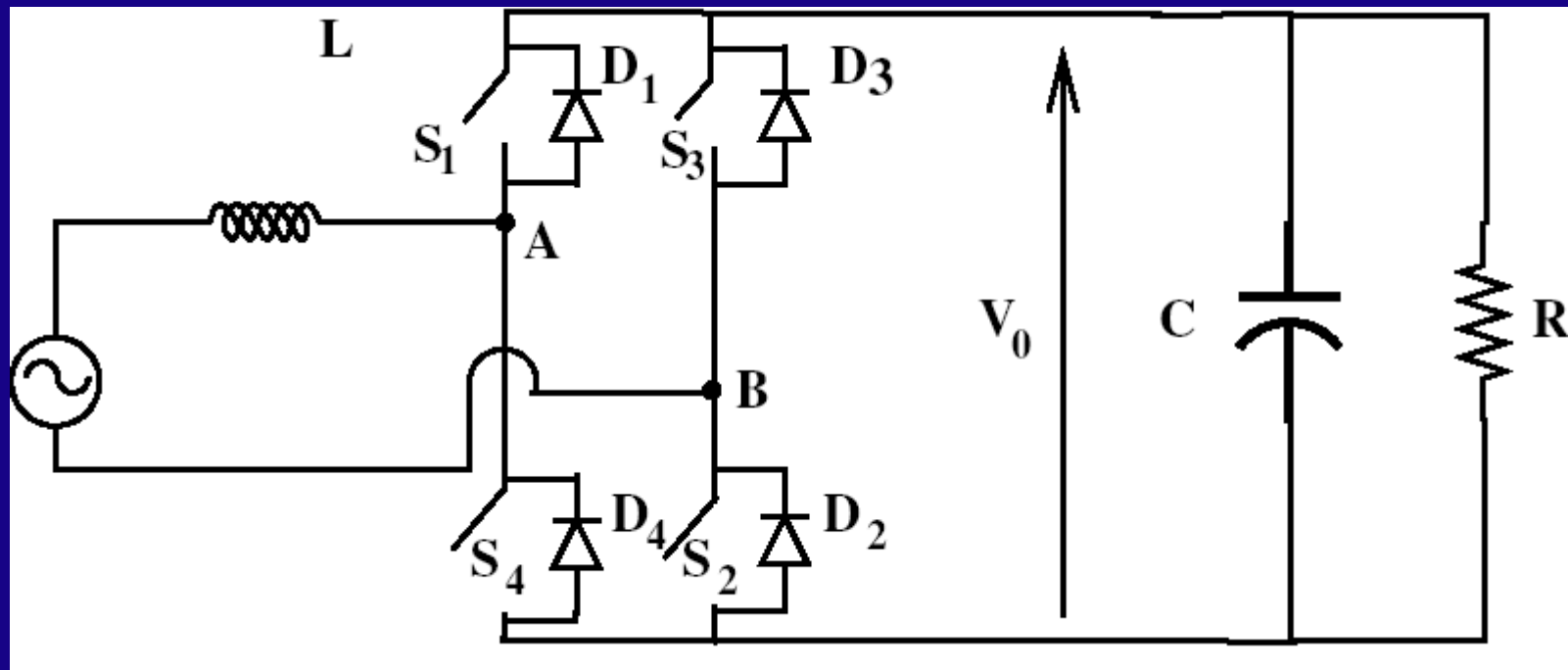
1) When  $S_4$  is closed:  $V_{AB} = 0$

2) When  $S_4$  is open:  $V_{AB} = V_0$



## Bi – Directional Power Transfer:

⇒ 2 quadrant converter  
( $V$  is +ve and  $I$  can be +ve or -ve)



In the +ve half:

At a particular instant,  
close ' $S_2$ ' as

$$\frac{di}{dt} = \frac{V_i}{L}$$

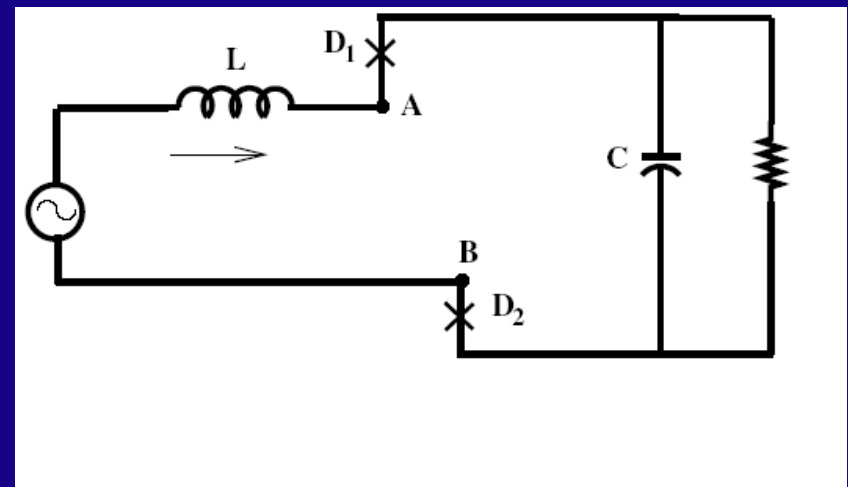
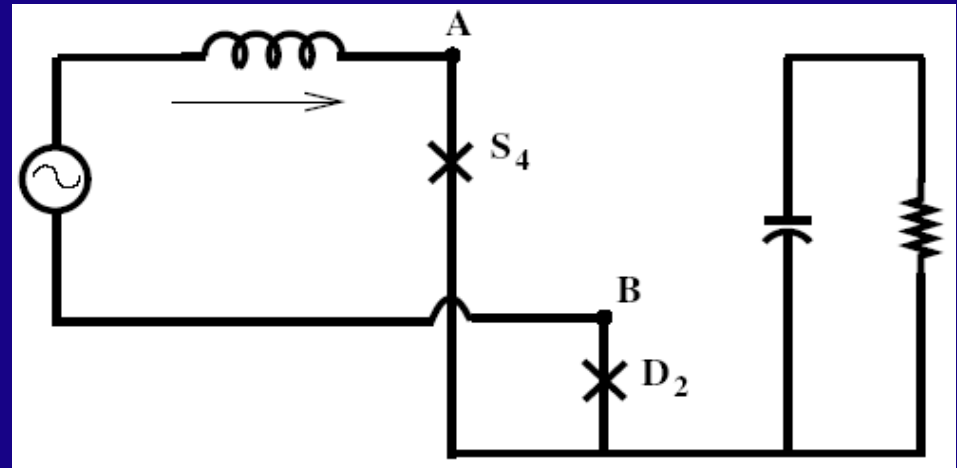
Capacitor supplies power to the load.

$$V_{AB} = 0$$

Open  $S_2$  :

Stored energy is transferred  
to the load through  $D_1D_2$

$$V_{AB} = V_0$$



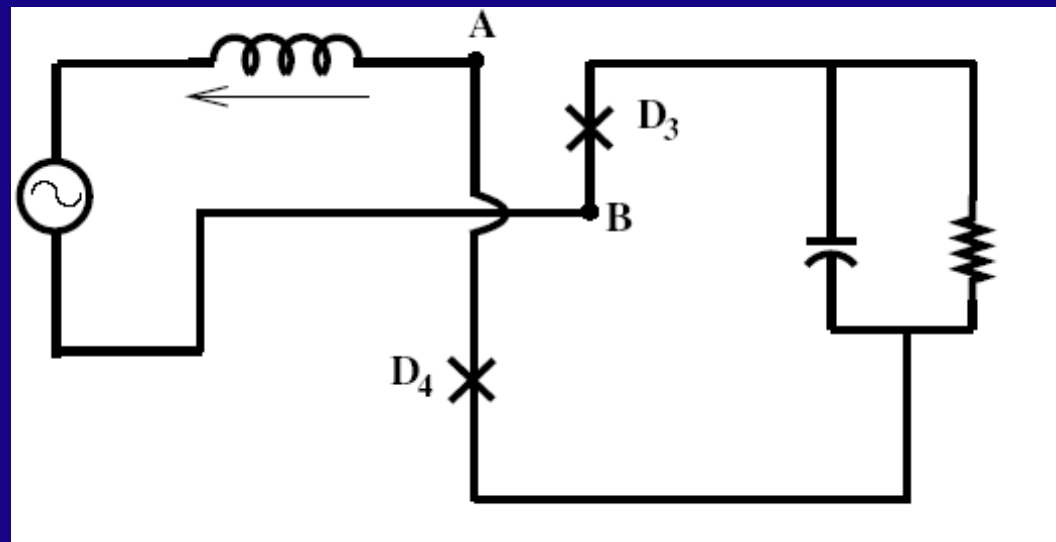
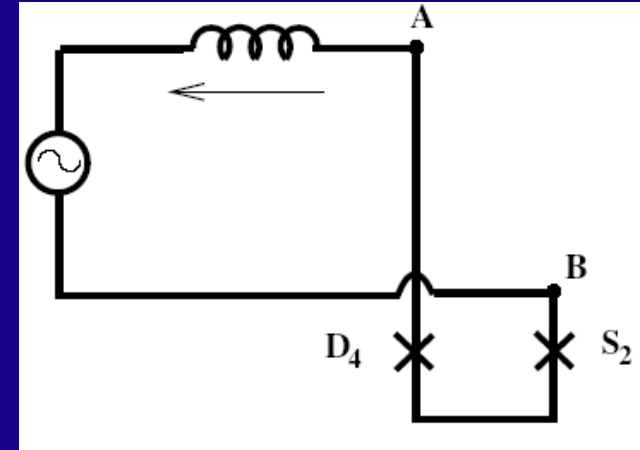
Similarly in the -ve half:

Close ' $S_2$ '.

$$V_{AB} = 0$$

After a while, open ' $S_2$ '

$$V_{AB} = -V_0$$



∴ Power transfer from source to

$$\text{the load} = \frac{V_i V_{AB1}}{\omega L} \sin \delta,$$

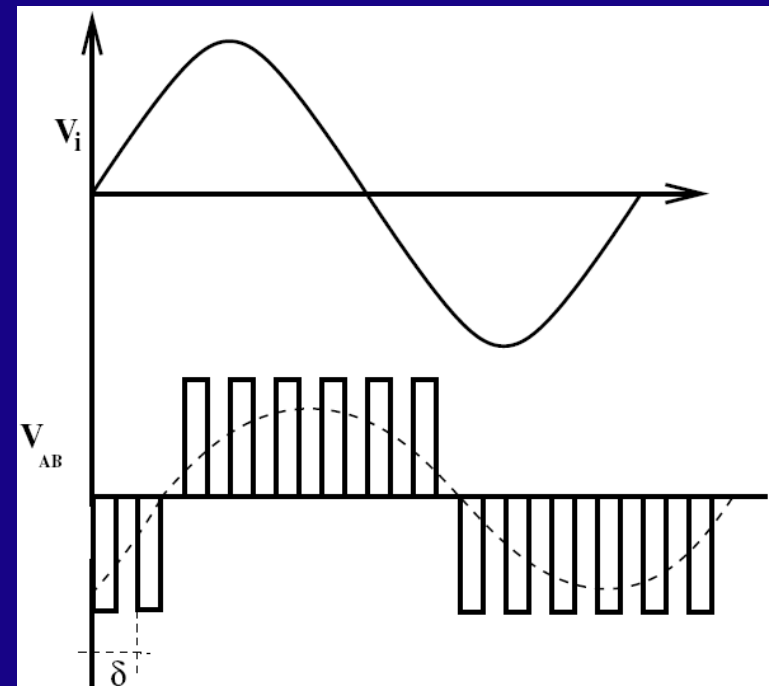
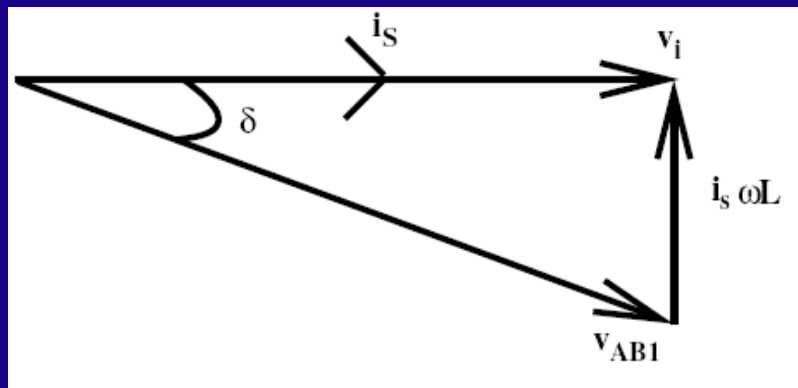
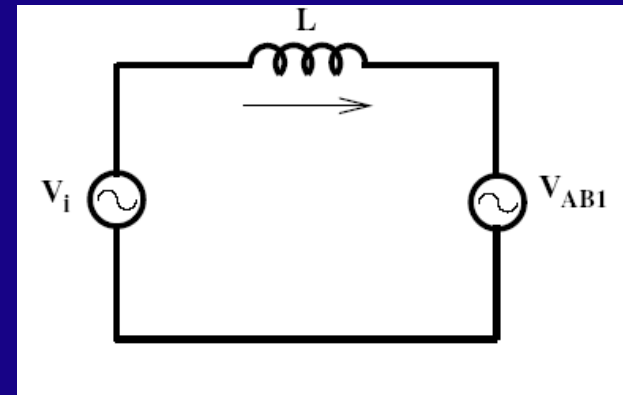
where  $\omega = 2\pi F$  and

$F \rightarrow$  frequency of  $v_i$

If  $\delta = 0$  and  $|V_s| \neq |V_{AB1}|$

Power transfer to the load is = 0.

∴  $|V_s| \neq |V_{AB1}|$ ,  $i_s$  will flow



If  $|V_S| < |V_{AB1}|$ ,  $\angle_{V_S}^{i_s} = 90^\circ$  leading

⇒ Capacitor

If  $|V_S| > |V_{AB1}|$ ,  $\angle_{V_S}^{i_s} = 90^\circ$  lagging

⇒ Inductor

⇒ Can be used to improve the  
P.F. both supplying  $\pm$  VARs

