

## Review :

1) Avg. value of  $V_o = \frac{2V_m}{\pi} \cos \alpha$  provided

' $i_l$ ' is continuous.

2) For ' $i_l$ ' to be continuous for  $90 < \alpha < 180$ , load should be R-L-E.

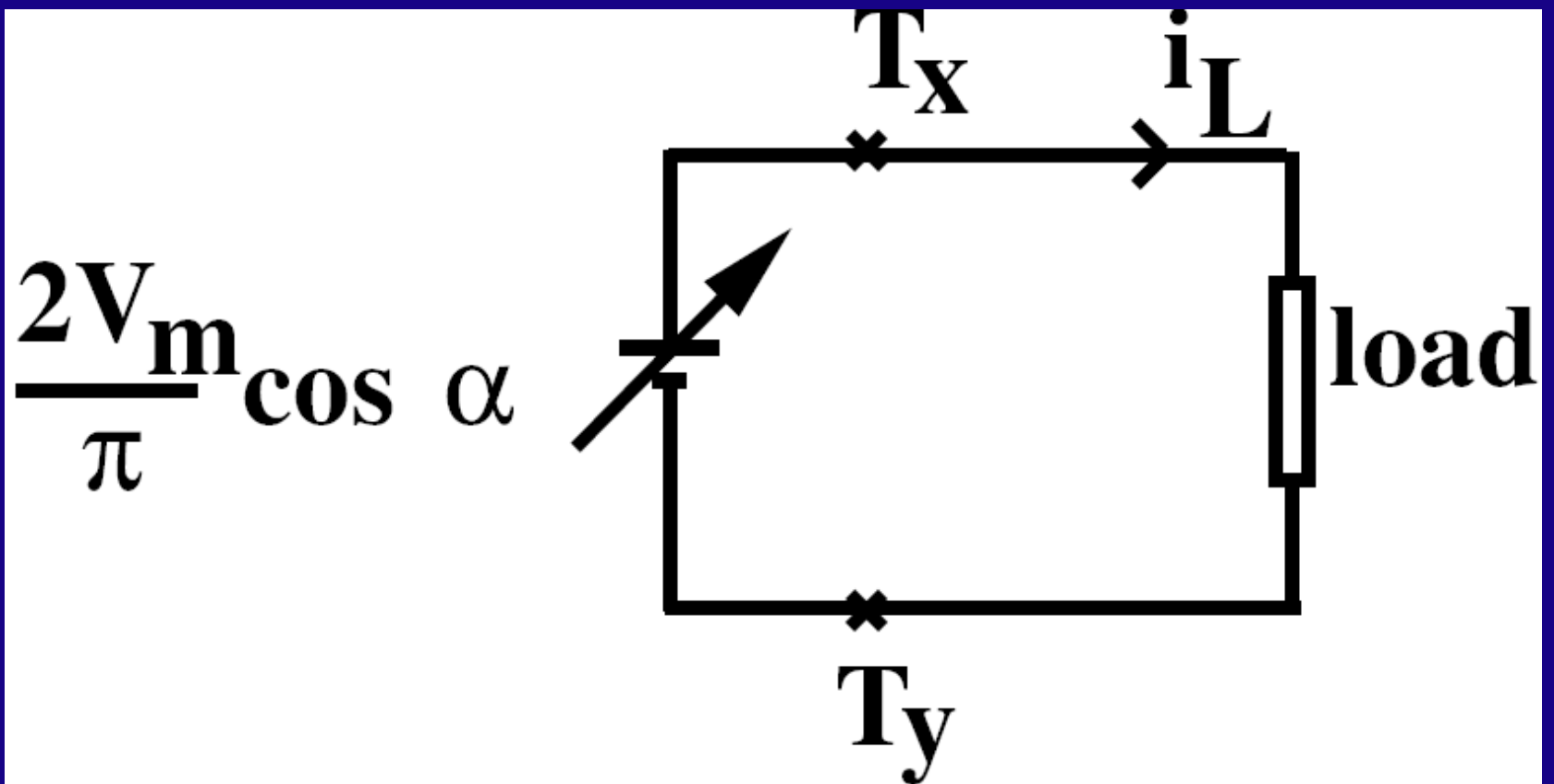
3) For regenerative braking, armature terminals should be reversed for ' $i_a$ ' reversal.

$\Rightarrow i_a \gg I_F$

$\Rightarrow$  Inductive circuit

$\Rightarrow$  momentarily this circuit is broken

$\Rightarrow$  arcing will occur.



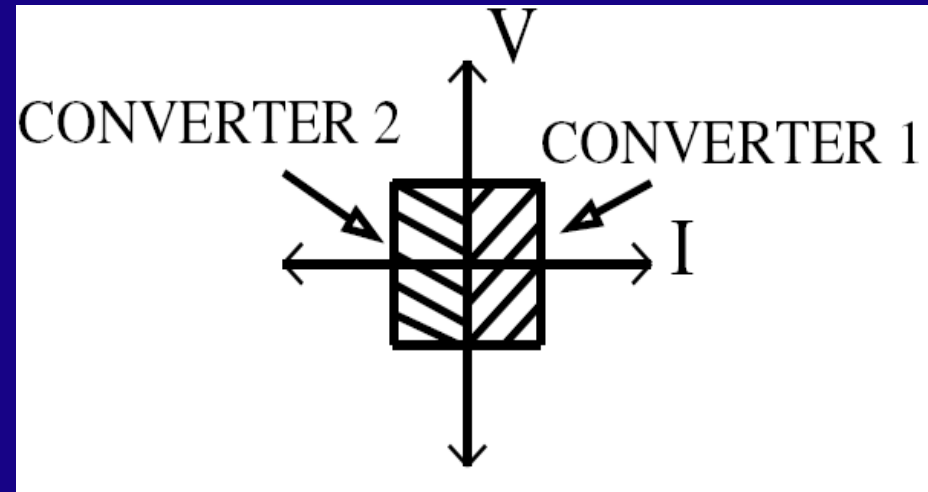
⇒ In a 2-quadrant converter,  
'V' can be reversed, but not 'i'.

⇒ use one more bridge.

⇒ Dual converter  
connect them back  
to back.

⇒ 'i' can be reversed and  
flows back to the source  
through the 2<sup>nd</sup> bridge.

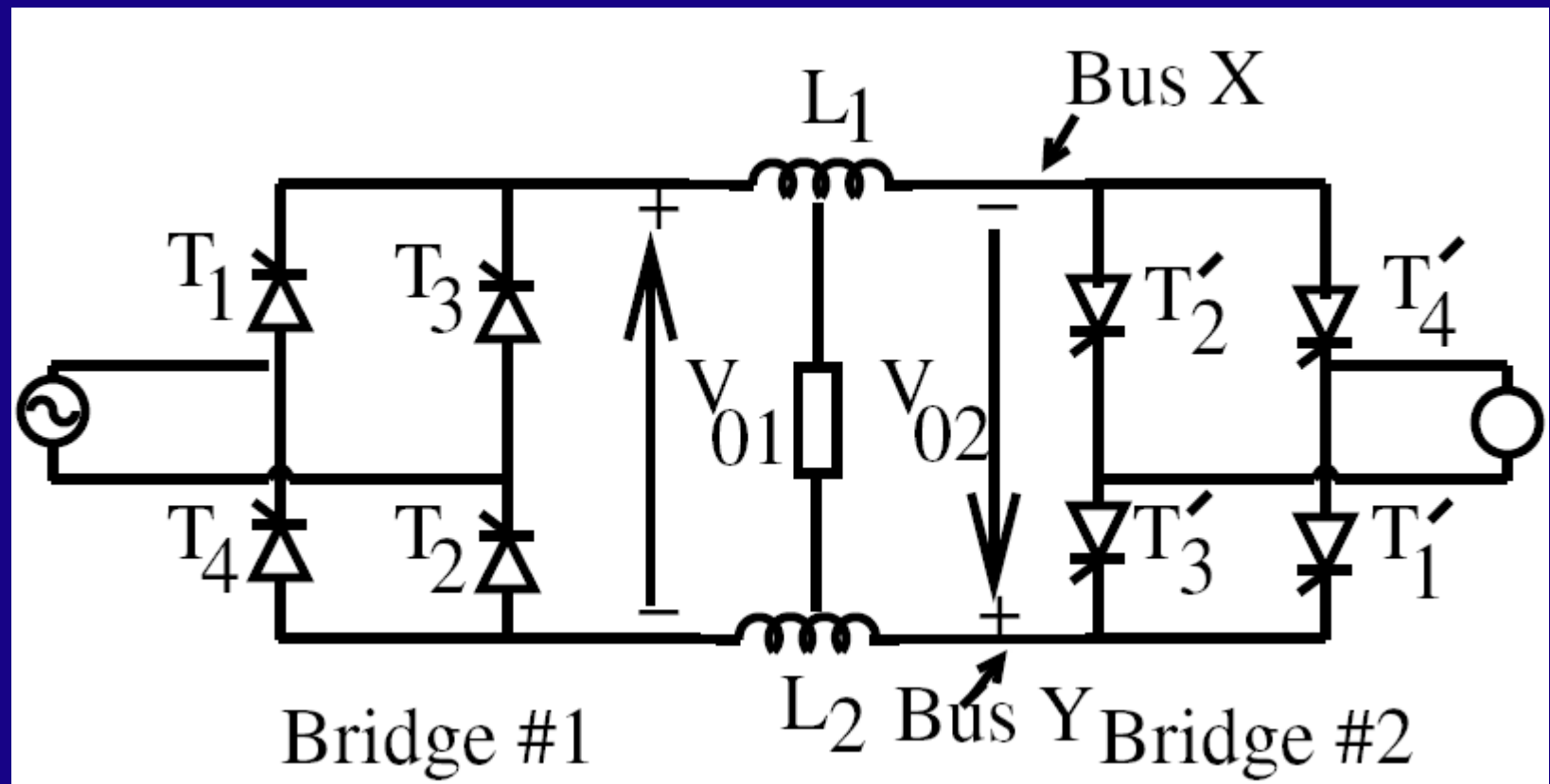
⇒ All 4 quadrant operation.



⇒ o/p 'V' of the converter is pulsating. In order to reduce the current pulsation, generally the inductor is connected in series with the load and the converter.  
(current cannot change instantaneously)

$$T = k\phi I_a$$

⇒ Torque pulsation depends on ripple in 'I<sub>a</sub>' and not on the o/p 'V' of the bridge.



Assume that both bridges are ON

Let  $\alpha_1$  be the triggering angle for bridge-1

Let  $\alpha_2$  be the triggering angle for bridge-2

$$\therefore V_{01} = \frac{2V_m}{\pi} \cos \alpha_1$$

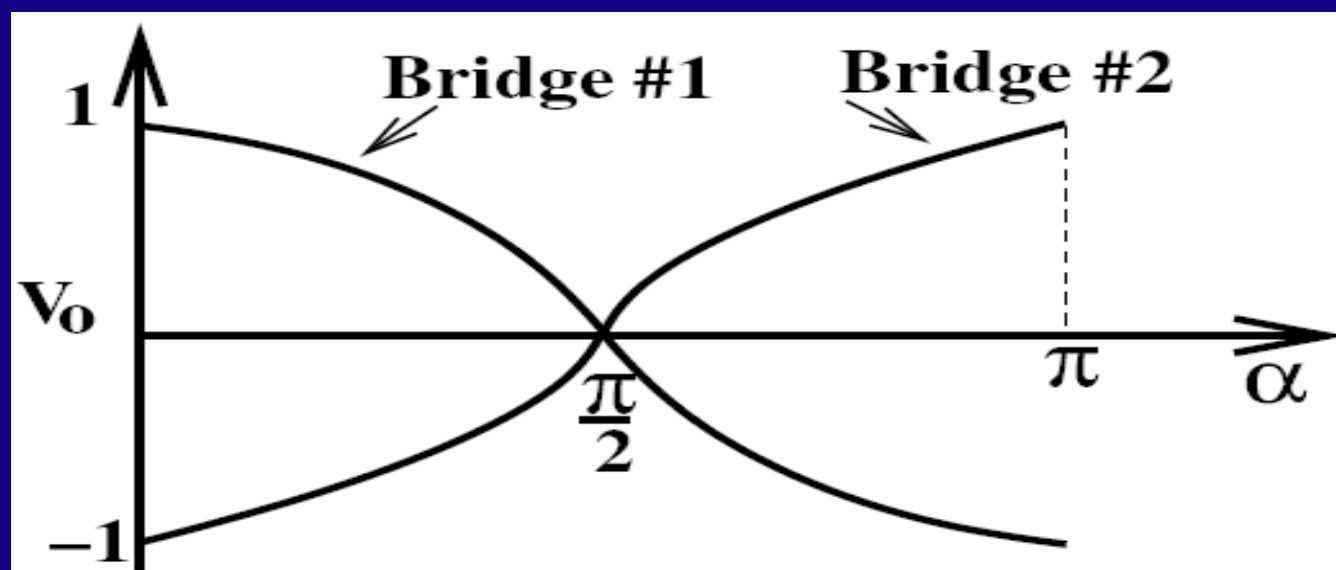
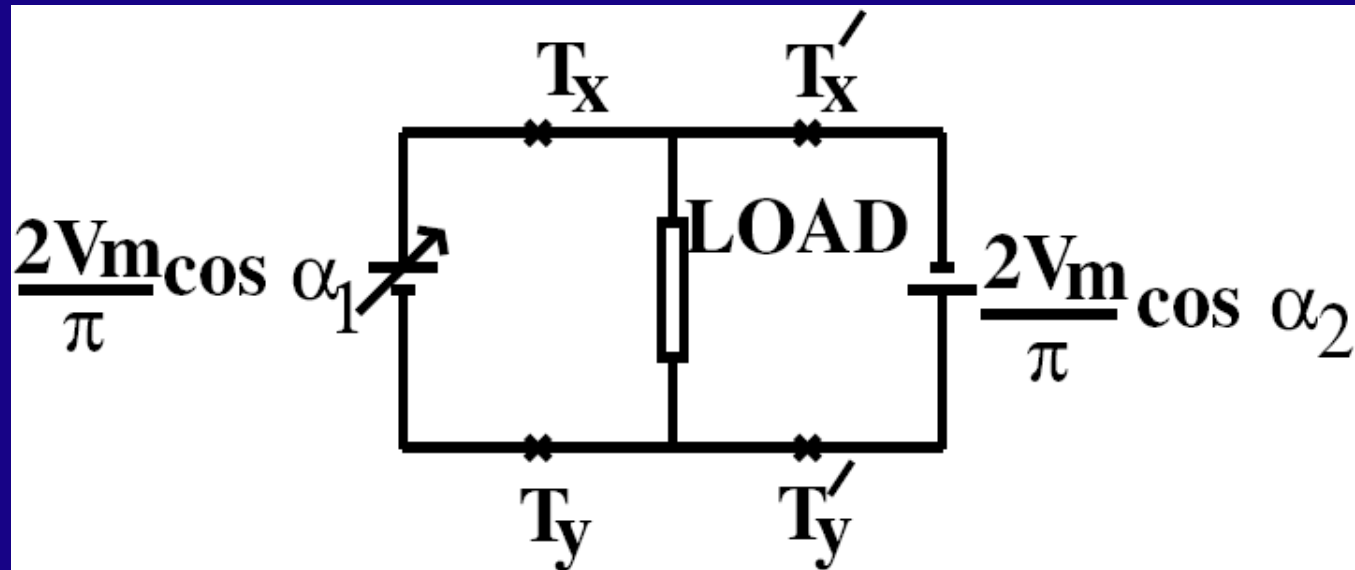
$$V_{02} = \frac{2V_m}{\pi} \cos \alpha_2$$

KVL gives  $V_{01} + V_{02} = 0$

$$[ \because (L \frac{di}{dt})_{\text{avg}} = 0 ]$$

$$\therefore \alpha_2 = \pi - \alpha_1$$





$V_{01}$  is the voltage w.r.t Bus Y and

$V_{02}$  is the voltage w.r.t Bus X.

Assume that ' $L_2$ ' is combined with ' $L_1$ '.

$$V_L = V_{01} + V_{02}$$

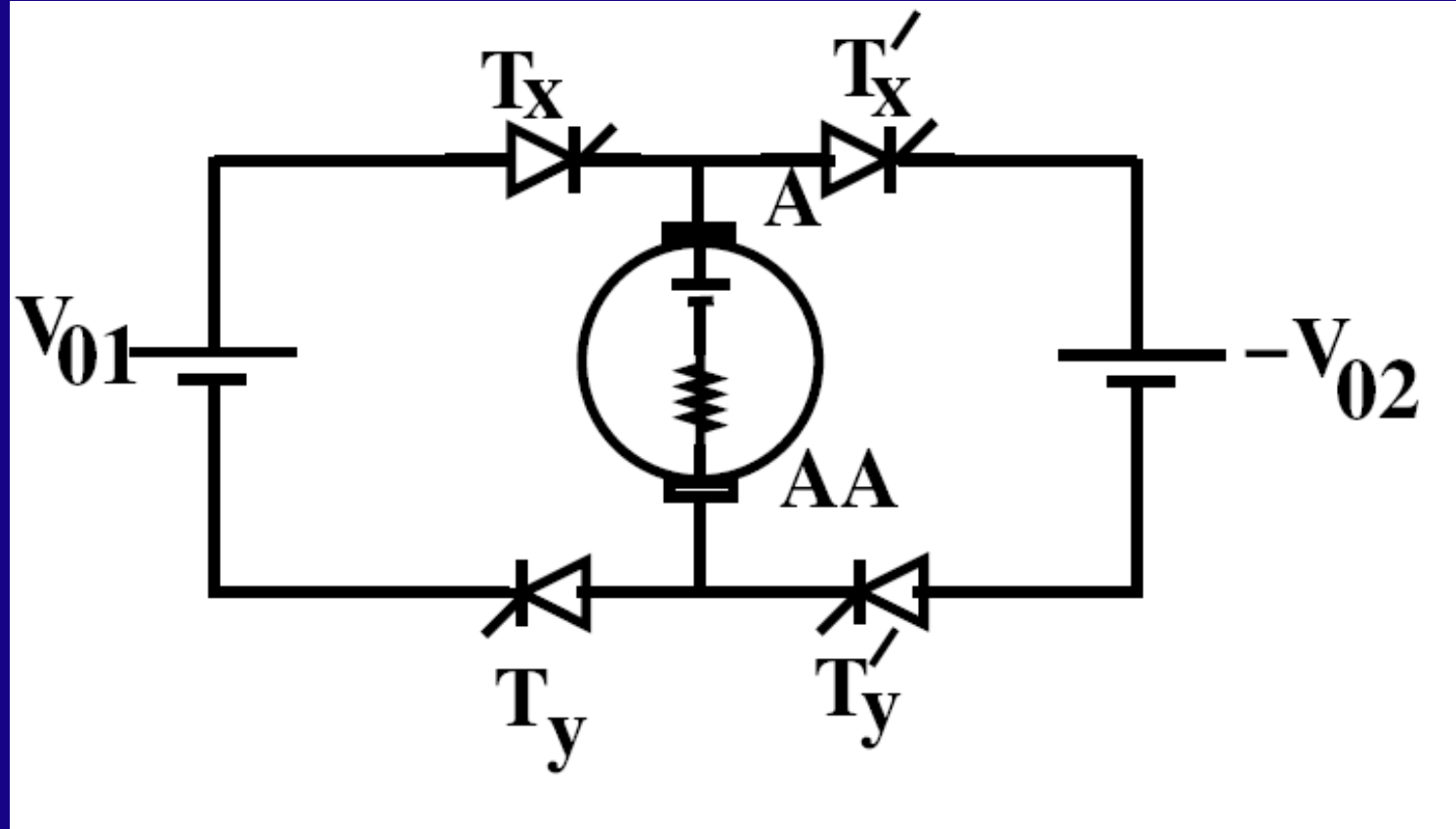
If both are w.r.t Bus Y, then

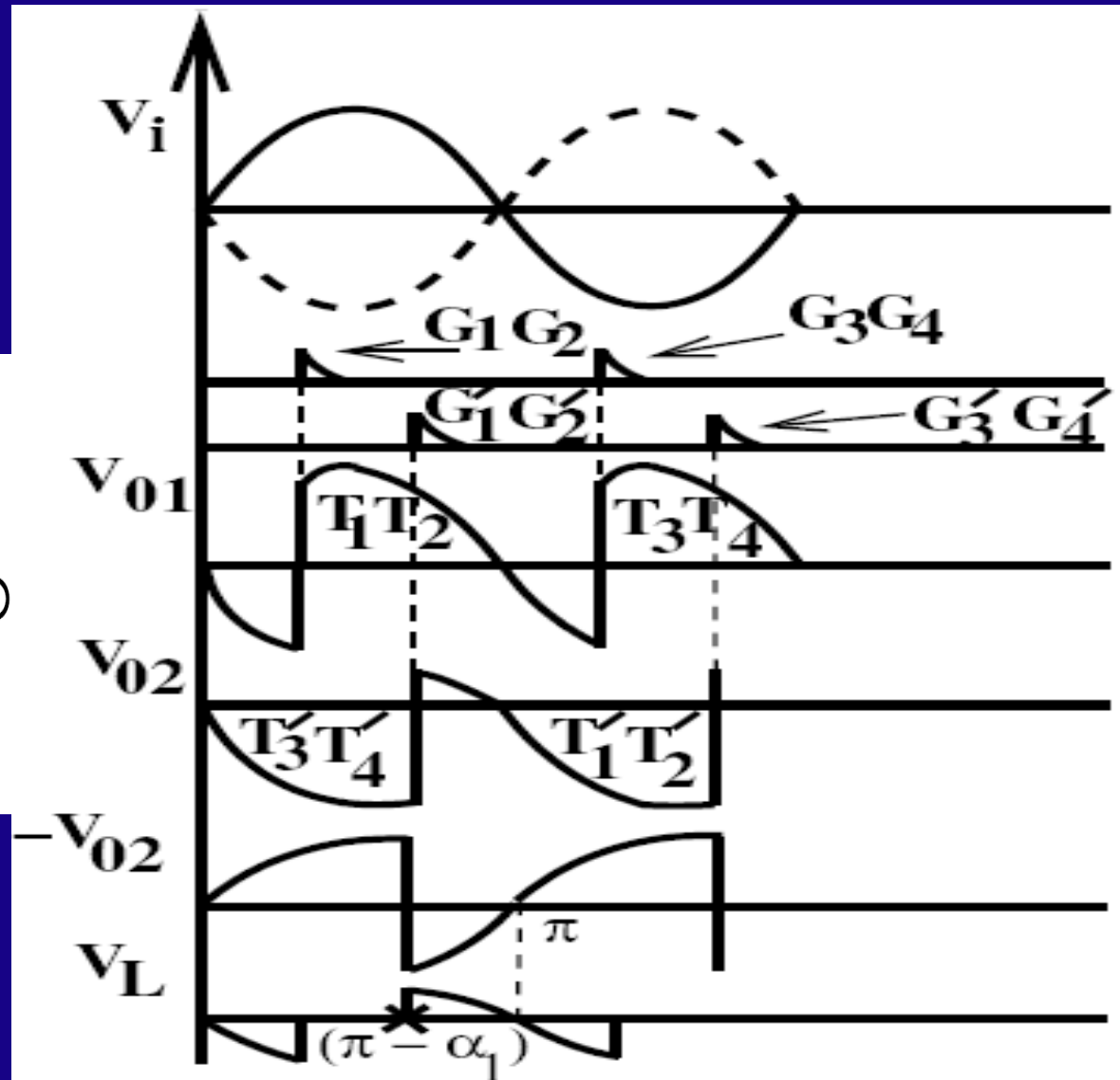
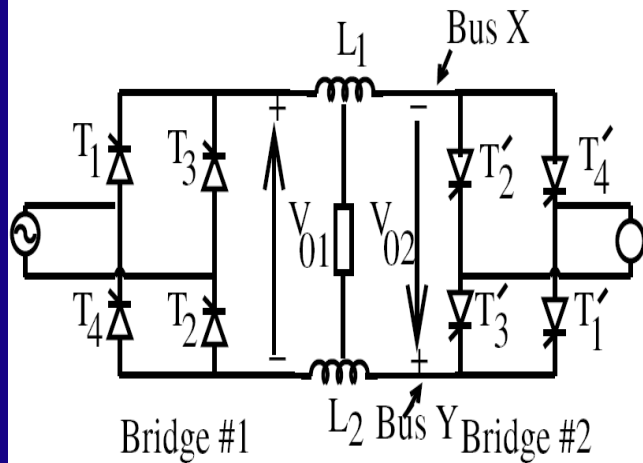
$$V_L = V_{01} - V_{02}$$

⇒ Average voltage across L = 0,  
but not instantaneous voltage.

⇒ If both bridges are ON, there  
will be a circulating current.







Assume that the motor is rotating at ' $\omega$ ' in the clockwise direction and corresponding

$$E_b = 90\text{ V} \text{ \& } V_{01} = -V_{02} = 95\text{ V}.$$

$$\text{Let } \alpha_1 \approx 45^\circ (\alpha_2 \approx 135^\circ)$$

$V_{01}$  is supplying power to the m/c.

$I_a$  is positive which means

'T' is also +ve.

Now,  $\uparrow \alpha_1$  to  $60^\circ$  or ( $\downarrow \alpha_2$  to  $120^\circ$ )  $\Rightarrow V_{01} \downarrow$

$E_b$  cannot change instantaneously

$\therefore$  ' $\omega$ ' cannot change instantaneously.

$E_b > V_{o1}$  generative action

$i_a$  reverses and flows through bridge 2.

$\Rightarrow E_b$  is still +ve,  $i_a$  is -ve.  $\therefore T$  is -ve.

$\Rightarrow$  Regenerative braking

$\Rightarrow M/c$  is still running in clockwise.

$\Rightarrow$  II quadrant operation.

$\Rightarrow \omega \downarrow$ .

$\Rightarrow$  continue  $\uparrow \alpha_1$  towards  $90^\circ$  Text

( $\alpha_2 \downarrow$  towards  $90^\circ$ ).

At  $\alpha_1 = 90^\circ$ ,  $V_{o1} = 0$  ( $\omega$  approaches 0)

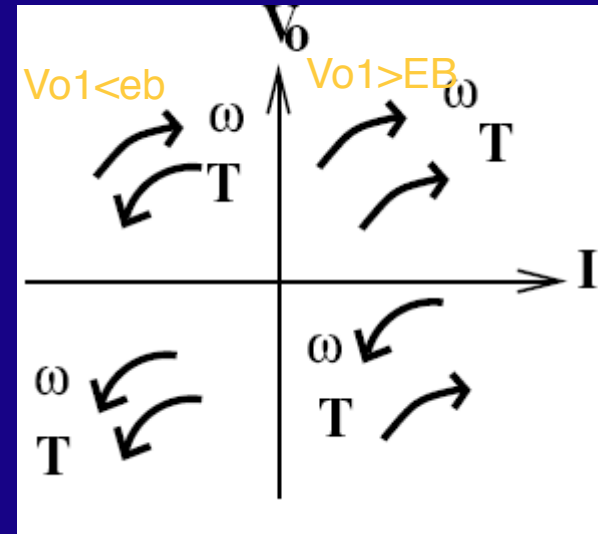
$\uparrow \alpha_1$  beyond  $90^\circ$  ( $\alpha_2 \downarrow$  below  $90^\circ$ ).

Bridge 1  $\rightarrow$  Inverter and

Bridge 2  $\rightarrow$  Converter.

Bridge 2 supplies power, m/c starts rotating in -ve direction.

' $E_b$ ' reverses,  $\therefore$  III quadrant (reverse motoring)



## Problem 1.1

Armature current  $I_a = 30 \text{ A}$

EMF constant =  $0.17 \text{ V / rpm}$

Assume large  $L$

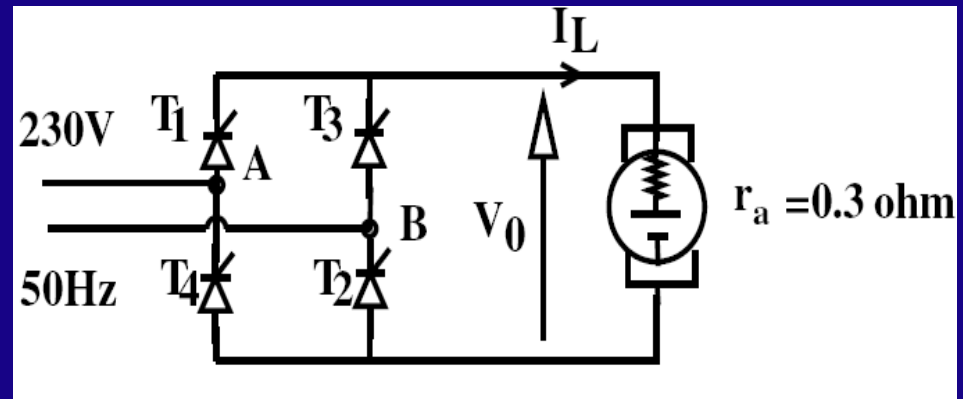
$I$  is constant in arm. ckt.

In rectifier operation

Determine speed & supply P.F.

$$\begin{aligned} \text{Sol: } \text{Av } V_0 &= \frac{2V_m}{\pi} \cos \alpha \\ &= \frac{2 * 230 * \sqrt{2}}{\pi} \cos 30 \\ &= 179 \text{ V} \end{aligned}$$

$$\therefore E_b = 179 - 30 * 0.3 = 170 \text{ V}$$





$$E_b = K\phi\omega$$

$\therefore$  EMF constant is in V / rpm

$$\therefore E_b = (K\phi)N$$

$$\therefore N = \frac{170}{0.17} = 1000 \text{ rpm}$$

**motor current is constant**

**and ripple free  $I_{\text{rms}} = 30\text{A}$**

$$\text{i/p VA} = 230 * 30 = 6900 \text{ VA}$$

$$\text{o/p Power} = V_o I_{\text{av}} = 179 * 30 \text{ W}$$

**(Neglecting inverter losses)**

$$\text{P.F} = \frac{179 * 30}{230 * 30} = 0.77 \text{ lag}$$



Or

**RMS value of fundamental component**

$$\text{of source current} = \frac{2\sqrt{2}}{\pi} 30 = 27 \text{ A}$$

$$\text{Cos } \phi_1 = \text{Cos } \alpha$$

$$\therefore \text{P.F} = \frac{V_{11} \text{Cos } \phi_1}{V_{\text{rms}} I_{\text{rms}}} = \frac{27 * \text{Cos } 30}{30} = 0.779$$

## 1.2. Regeneration: Polarity of back emf

is reversed by reversing the ' $\phi$ '

Calculate ' $\alpha$ ' and power fed back.

Armature current is maintained at previous value.

Sol: At the instant of polarity reversal

$$E_b = 170 \text{ V}$$

$$\therefore V_0 = -170 + I_a r_a$$

$$= -161 \text{ V} = \frac{2V_m}{\pi} \cos \alpha$$

$$\Rightarrow \alpha = 141^\circ$$

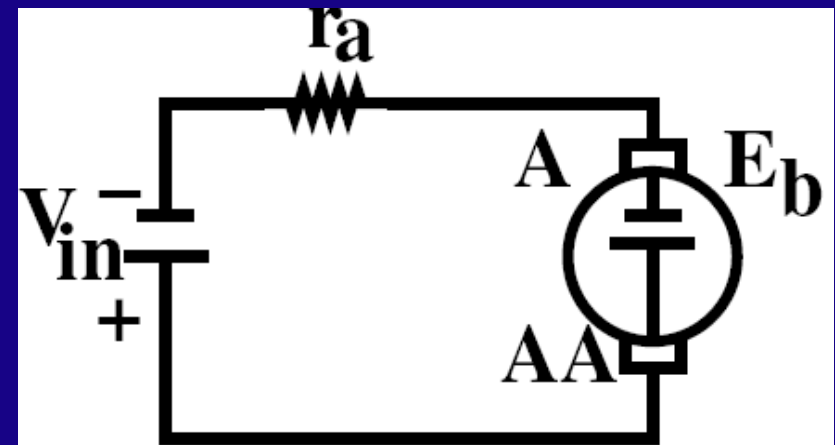
$$\text{Power o/p from generator} = 170 \times 30$$

$$= 5100 \text{ W}$$

$$\text{Armature copper loss} = 0.3 \times 30^2 = 270 \text{ W}$$

$$\therefore \text{Power fed back} = 5100 - 270 = 4800 \text{ W}$$

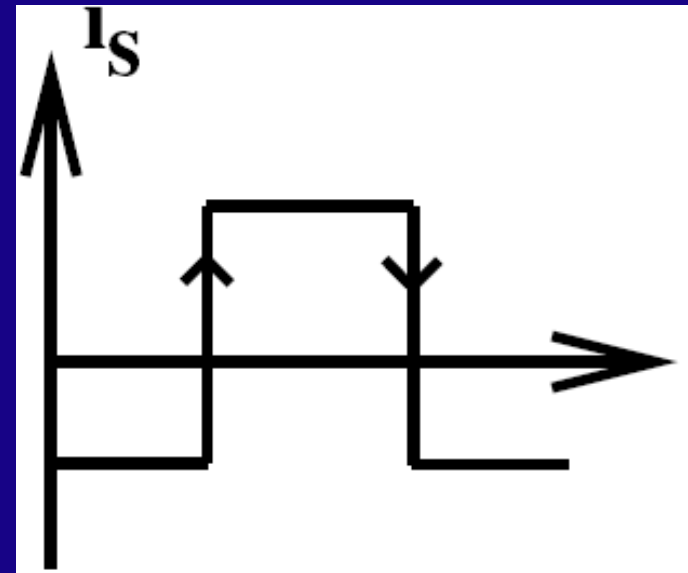
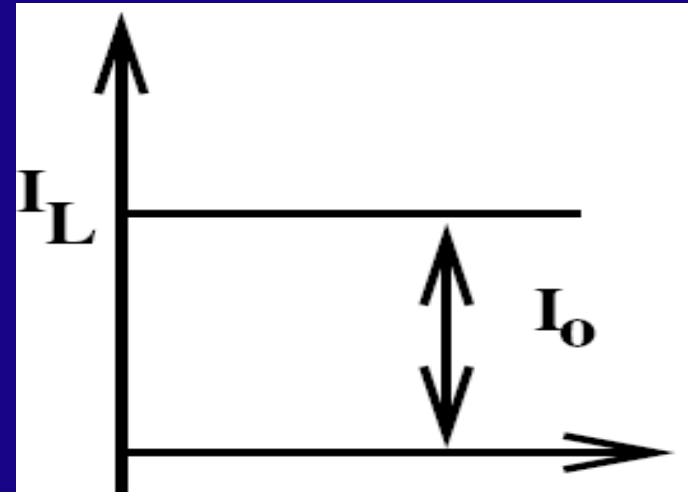
$$= 161 \times 30 = 4800 \text{ W}$$



## Effect of source inductance

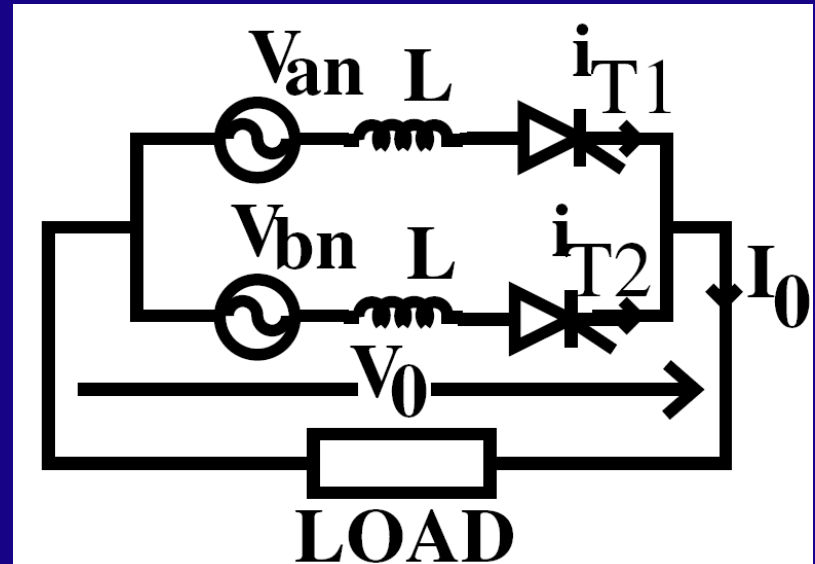
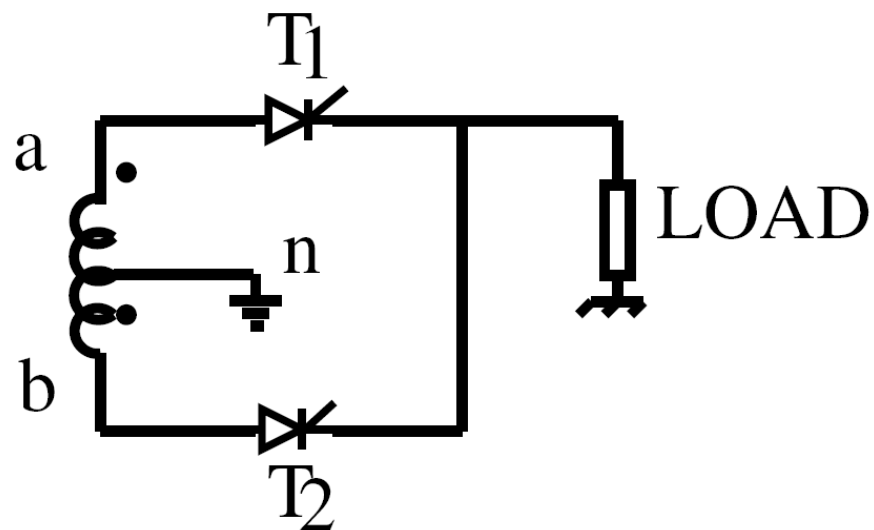
In 1- $\phi$  bridge, when  $T_3$  is triggered,  $T_1$  turns off instantaneously.

- $\Rightarrow$  source  $L = 0$
- $\Rightarrow$  there is always some 'L'
- $\Rightarrow$  'i' cannot change instantaneously.



at  $\omega t = \alpha$ ,  $T_1$  is triggered.

at  $\omega t = \pi + \alpha$ ,  $T_2$  is triggered.



$$i_{T1} + i_{T2} = I_o$$

$$\frac{di_{T1}}{dt} = -\frac{di_{T2}}{dt}$$

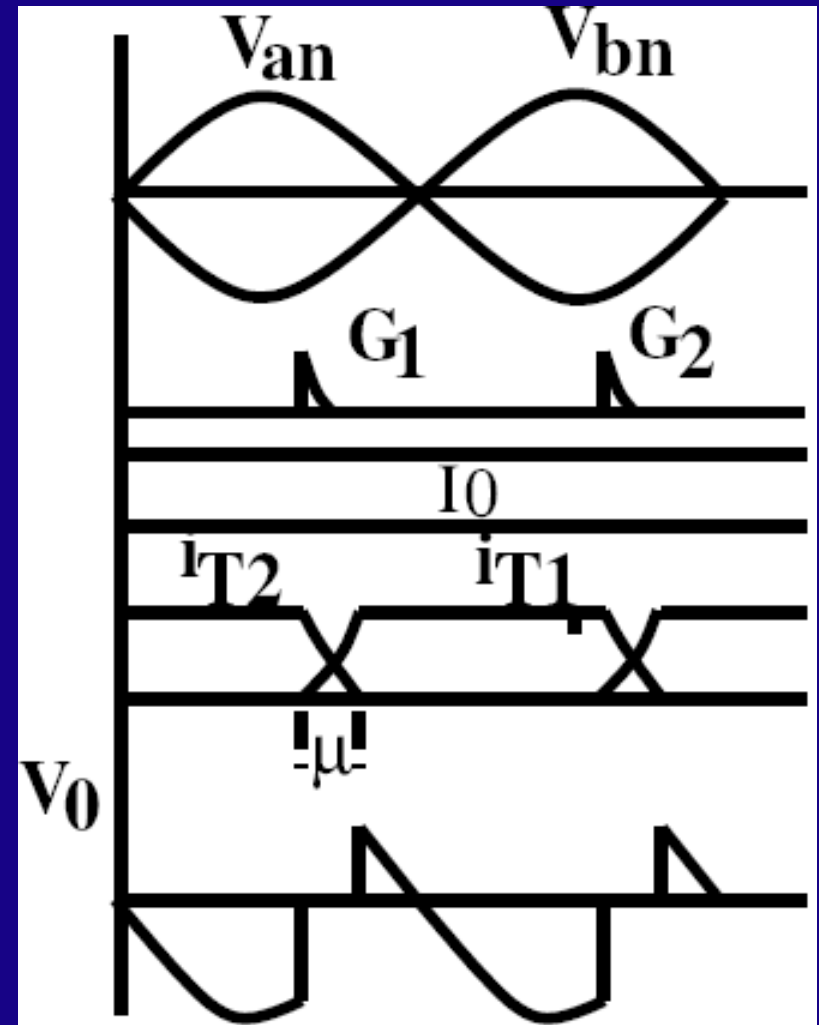
$$V_{an} = -V_{bn} = V_m \sin \omega t$$

Using KVL :

$$V_{an} - V_{bn} = L \frac{di_{T1}}{dt} - L \frac{di_{T2}}{dt}$$

$$\therefore 2V_m \sin \omega t = 2L \frac{di_{T1}}{dt}$$

$$V_0 = V_{an} - L \frac{di_{T1}}{dt} = 0; \text{ during } \mu$$



## Observation:

Instantaneous  $V_0$  is +ve if  $L = 0$

Instantaneous  $V_0$  is 0 if 'L' is finite.

$\therefore$  Avg.  $V_0 \downarrow$

$$V_m \sin \omega t = L \frac{di_{T1}}{dt}$$

$$\frac{V_m \sin \omega t}{\omega} d(\omega t) = L di_{T1}$$

$$\therefore i_{T1} = \int_{\alpha}^{\alpha+\mu} \frac{V_m \sin \omega t d(\omega t)}{\omega L}$$

$$\Rightarrow i_{T1} = \frac{V_m}{\omega L} [\cos \alpha - \cos(\alpha + \mu)] = I_0 \text{ at } \mu \dots \dots \dots (1)$$

$\therefore$  Overlap is complete at  $\mu$ ,

$\Rightarrow \mu$  is known as the overlap angle



$$\begin{aligned}\therefore \text{Avg. } V_0 &= \frac{2}{2\pi} \int_{\alpha+\mu}^{\pi+\alpha} V_m \sin \omega t \, d(\omega t) \\ &= \frac{V_m}{\pi} [\cos \alpha + \cos(\alpha + \mu)]\end{aligned}$$

Using Eq.1

$$\frac{V_m}{\pi} \cos(\alpha + \mu) = \frac{V_m}{\pi} \cos \alpha - \frac{I_0 \omega L}{\pi}$$

Substituting in the above equation

$$V_0 + \frac{I_0 \omega L}{\pi} = \frac{2V_m}{\pi} \cos \alpha$$

$\therefore$  Equivalent circuit

$$V_0 = 0 \text{ for } \mu = \pi \text{ or } \pi - 2\alpha$$

$\mu = \pi \Rightarrow$  one overlap mode

$\Rightarrow$  no powering mode !

$\Rightarrow$  Load is a current source

$\Rightarrow$  Magnitude 'I' is independent of terminal 'V'

$$\mu = \pi - 2\alpha$$

$\Rightarrow$  Load is pure 'L'

$\Rightarrow$  Possible

