CS 228 : Logic in Computer Science

Krishna. S

Recap

- Transition Systems as models of systems (read circuits, code, and so on)
- Traces of transition systems
- Properties as set of allowed traces
- These properties are certain languages over the alphabet 2^{AP}, and are called LT properties
- Writing properties in a language fashion
- ► Logic LTL to capture LT properties

Syntax of Linear Temporal Logic

Given AP, a set of propositions,

Syntax of Linear Temporal Logic

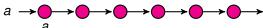
Given AP, a set of propositions,

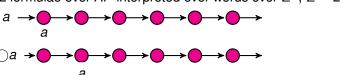
- Propositional logic formulae over AP
 - $ightharpoonup a \in AP$ (atomic propositions)
 - $\triangleright \neg \varphi, \varphi \land \psi, \varphi \lor \psi$

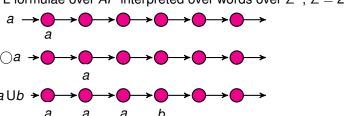
Syntax of Linear Temporal Logic

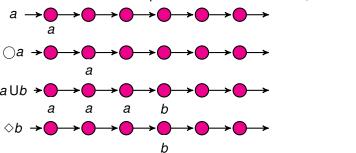
Given AP, a set of propositions,

- Propositional logic formulae over AP
 - $ightharpoonup a \in AP$ (atomic propositions)
 - $\triangleright \neg \varphi, \varphi \land \psi, \varphi \lor \psi$
- Temporal Operators
 - $\triangleright \bigcirc \varphi \text{ (Next } \varphi \text{)}$
 - $\varphi \cup \psi \ (\varphi \text{ holds until a } \psi \text{-state is reached})$
- LTL : Logic for describing LT properties

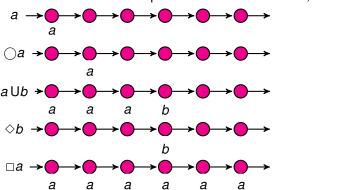








LTL formulae over \textit{AP} interpreted over words over Σ^{ω} , $\Sigma=2^{\textit{AP}}$



4/21

Derived Operators

- $true = \varphi \lor \neg \varphi$
- ▶ false = ¬true
- $\Diamond \varphi = true \, \mathsf{U} \varphi \, (\mathsf{Eventually} \, \varphi)$

Precedence

- Unary Operators bind stronger than Binary
- ▶ and ¬ equally strong
- ▶ U takes precedence over \land, \lor, \rightarrow
 - \bullet $a \lor b \cup c \equiv a \lor (b \cup c)$

► Whenever the traffic light is red, it cannot become green immediately:

6/2

► Whenever the traffic light is red, it cannot become green immediately:

 \Box (red $\rightarrow \neg \bigcirc$ green)

► Whenever the traffic light is red, it cannot become green immediately:

```
\Box (red \rightarrow \neg \bigcirc green)
```

Eventually the traffic light will become yellow

6/2

► Whenever the traffic light is red, it cannot become green immediately:

```
\Box(red \rightarrow \neg \bigcirc green)
```

Eventually the traffic light will become yellow \(\frac{\psi ellow}{\text{yellow}}\)

Whenever the traffic light is red, it cannot become green immediately:

```
\Box (red \rightarrow \neg \bigcirc green)
```

- Eventually the traffic light will become yellow \(\forall yellow \)
- Once the traffic light becomes yellow, it will eventually become green

Whenever the traffic light is red, it cannot become green immediately:

```
\Box (red \rightarrow \neg \bigcirc green)
```

- Eventually the traffic light will become yellow \(\forall yellow \)
- Once the traffic light becomes yellow, it will eventually become green

```
\Box(yellow \rightarrow \Diamond green)
```

Whenever the traffic light is red, it cannot become green immediately:

```
\Box(red \rightarrow \neg \bigcirc green)
```

- Eventually the traffic light will become yellow \$\forall yellow\$
- Once the traffic light becomes yellow, it will eventually become green

```
\Box(yellow \rightarrow \Diamondgreen)
```

Whenever the traffic light is red, it will eventually become green, but it must be yellow for sometime in between the red and the green

6/21

Whenever the traffic light is red, it cannot become green immediately:

```
\Box (red \rightarrow \neg \bigcirc green)
```

- Eventually the traffic light will become yellow vellow
- Once the traffic light becomes yellow, it will eventually become green

```
\Box(yellow \rightarrow \Diamondgreen)
```

Whenever the traffic light is red, it will eventually become green, but it must be yellow for sometime in between the red and the green

```
\Box(red \rightarrow \bigcirc(red \Box[yellow
```

Whenever the traffic light is red, it cannot become green immediately:

```
\Box (red \rightarrow \neg \bigcirc green)
```

- Eventually the traffic light will become yellow vellow
- Once the traffic light becomes yellow, it will eventually become green

```
\Box(yellow \rightarrow \Diamond green)
```

Whenever the traffic light is red, it will eventually become green, but it must be yellow for sometime in between the red and the green

```
\Box(red \rightarrow \bigcirc(red \Box[yellow \land \bigcirc (yellow \Boxgreen)]))
```

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

Let $\sigma = A_0 A_1 A_2 \dots$

▶ $\sigma \models a \text{ iff } a \in A_0$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- $ightharpoonup \sigma \models a \text{ iff } a \in A_0$
- \bullet $\sigma \models \varphi_1 \land \varphi_2 \text{ iff } \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (\mathbf{2}^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- $ightharpoonup \sigma \models a \text{ iff } a \in A_0$
- \bullet $\sigma \models \varphi_1 \land \varphi_2 \text{ iff } \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (\mathbf{2}^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- $ightharpoonup \sigma \models a \text{ iff } a \in A_0$
- \bullet $\sigma \models \varphi_1 \land \varphi_2 \text{ iff } \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$
- $\triangleright \ \sigma \models \bigcirc \varphi \text{ iff } A_1 A_2 \ldots \models \varphi$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- $ightharpoonup \sigma \models a \text{ iff } a \in A_0$
- $\sigma \models \varphi_1 \land \varphi_2 \text{ iff } \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$
- $\triangleright \ \sigma \models \bigcirc \varphi \text{ iff } A_1 A_2 \ldots \models \varphi$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- $ightharpoonup \sigma \models \Box \varphi \text{ iff } \forall j \geqslant 0, A_i A_{i+1} \ldots \models \varphi$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

- \bullet $\sigma \models \Diamond \varphi \text{ iff } \exists j \geqslant 0, A_i A_{i+1} \ldots \models \varphi$

Given LTL formula φ over AP,

$$L(\varphi) = \{ \sigma \in (2^{AP})^{\omega} \mid \sigma \models \varphi \}$$

If $\sigma = A_0 A_1 A_2 \ldots$, $\sigma \models \varphi$ is also written as $\sigma, 0 \models \varphi$. This simply means $A_0 A_1 A_2 \ldots \models \varphi$. One can also define $\sigma, i \models \varphi$ to mean $A_i A_{i+1} A_{i+2} \ldots \models \varphi$ to talk about a suffix of the word σ satisfying a property.

Let $TS = (S, S_0, \rightarrow, AP, L)$ be a transition system, and φ an LTL formula over AP

▶ For an infinite path fragment π of TS,

$$\pi \models \varphi \text{ iff } trace(\pi) \models \varphi$$

Let $TS = (S, S_0, \rightarrow, AP, L)$ be a transition system, and φ an LTL formula over AP

▶ For an infinite path fragment π of TS,

$$\pi \models \varphi \text{ iff } trace(\pi) \models \varphi$$

▶ For $s \in S$,

$$s \models \varphi \text{ iff } \forall \pi \in \textit{Paths}(s), \pi \models \varphi$$

Let $TS = (S, S_0, \rightarrow, AP, L)$ be a transition system, and φ an LTL formula over AP

▶ For an infinite path fragment π of TS,

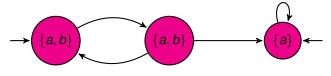
$$\pi \models \varphi \text{ iff } trace(\pi) \models \varphi$$

▶ For $s \in S$, $s \models \varphi$ iff $\forall \pi \in Paths(s), \pi \models \varphi$

▶ $TS \models \varphi \text{ iff } Traces(TS) \subseteq L(\varphi)$

Assume all states in TS are reachable from S_0 .

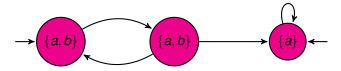
- ▶ $TS \models \varphi \text{ iff } TS \models L(\varphi) \text{ iff } Traces(TS) \subseteq L(\varphi)$
- ▶ $TS \models L(\varphi)$ iff $\pi \models \varphi \ \forall \pi \in Paths(TS)$
- $\blacktriangleright \pi \models \varphi \ \forall \pi \in Paths(TS) \ \text{iff} \ s_0 \models \varphi \ \forall s_0 \in S_0$



TS |= □a,

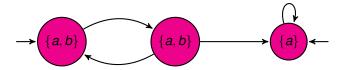
11/2

Example



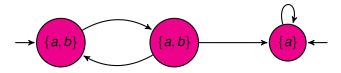
- *► TS* |= □*a*,
- ▶ $TS \nvDash \bigcirc (a \land b)$

Example



- TS |= □a,
- ▶ $TS \nvDash \bigcirc (a \land b)$
- ▶ $TS \nvDash (b \cup (a \land \neg b))$

Example



- TS |= □a,
- ▶ $TS \nvDash \bigcirc (a \land b)$
- ▶ $TS \nvDash (b \cup (a \land \neg b))$
- $TS \models \Box (\neg b \rightarrow \Box (a \land \neg b))$

More Semantics

▶ For paths π , $\pi \models \varphi$ iff $\pi \nvDash \neg \varphi$

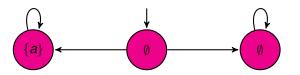
More Semantics

- ► For paths π , $\pi \models \varphi$ iff $\pi \nvDash \neg \varphi$ trace(π) $\in L(\varphi)$ iff trace(π) $\notin L(\neg \varphi) = \overline{L(\varphi)}$
- ▶ $TS \nvDash \varphi$ iff $TS \models \neg \varphi$?
 - ▶ $TS \models \neg \varphi \rightarrow \forall$ paths π of TS, $\pi \models \neg \varphi$
 - ▶ Thus, $\forall \pi, \pi \nvDash \varphi$. Hence, $TS \nvDash \varphi$

More Semantics

- ► For paths π , $\pi \models \varphi$ iff $\pi \nvDash \neg \varphi$ trace(π) $\in L(\varphi)$ iff trace(π) $\notin L(\neg \varphi) = \overline{L(\varphi)}$
- ▶ $TS \nvDash \varphi$ iff $TS \models \neg \varphi$?
 - ▶ $TS \models \neg \varphi \rightarrow \forall$ paths π of TS, $\pi \models \neg \varphi$
 - ▶ Thus, $\forall \pi, \pi \nvDash \varphi$. Hence, $TS \nvDash \varphi$
 - ▶ Now assume $TS \nvDash \varphi$
 - ▶ Then \exists some path π in *TS* such that $\pi \models \neg \varphi$
 - ▶ However, there could be another path π' such that $\pi' \models \varphi$
 - ▶ Then $TS \nvDash \neg \varphi$ as well
- ▶ Thus, $TS \nvDash \varphi \not\equiv TS \models \neg \varphi$.

An Example





Equivalence

 φ and ψ are equivalent $(\varphi \equiv \psi)$ iff $L(\varphi) = L(\psi)$.

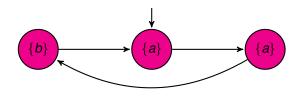
Expansion Laws

 φ and ψ are equivalent iff $L(\varphi) = L(\psi)$.

 φ and ψ are equivalent iff $L(\varphi) = L(\psi)$.

Distribution

$$\bigcirc(\varphi \lor \psi) \equiv \bigcirc\varphi \lor \bigcirc\psi,
\bigcirc(\varphi \land \psi) \equiv \bigcirc\varphi \land \bigcirc\psi,
\bigcirc(\varphi U\psi) \equiv (\bigcirc\varphi) U(\bigcirc\psi),
\diamondsuit(\varphi \lor \psi) \equiv \diamondsuit\varphi \lor \diamondsuit\psi,
\Box(\varphi \land \psi) \equiv \Box\varphi \land \Box\psi$$



$$TS \models \Diamond a \land \Diamond b, TS \nvDash \Diamond (a \land b)$$

$$TS \models \Box (a \lor b), TS \nvDash \Box a \lor \Box b$$

Satisfiability, Model Checking of LTL

Two Questions

Given transition system TS, and an LTL formula φ . Does $TS \models \varphi$? Given an LTL formula φ , is $L(\varphi) = \emptyset$?

How we go about this:

- ▶ Translate φ into an automaton A_{φ} that accepts infinite words such that $L(A_{\varphi}) = L(\varphi)$.
- ▶ Check for emptiness of A_{φ} to check satisfiability of φ .
- ▶ Check if $TS \cap \overline{A_{\varphi}}$ is empty, to answer the model-checking problem.

Notations for Infinite Words

- Σ is a finite alphabet
- Σ* set of finite words over Σ
- ▶ An infinite word is written as $\alpha = \alpha(0)\alpha(1)\alpha(2)\dots$, where $\alpha(i) \in \Sigma$
- Such words are called ω-words
- ▶ $Inf(\alpha) = \{a \in \Sigma \mid \alpha(i) = a \text{ for infinitely many } i\}$. $Inf(\alpha)$ gives the set of symbols occurring infinitely often in α .

ω -automata

An ω -automaton is a tuple $\mathcal{A} = (Q, \Sigma, \delta, q_0, Acc)$ where

- Q is a finite set of states
- Σ is a finite alphabet
- ▶ $\delta: Q \times \Sigma \to 2^Q$ is a state transition function (if non-deterministic, otherwise, $\delta: Q \times \Sigma \to Q$)
- ▶ $q_0 \in Q$ is an initial state and Acc is an acceptance condition

ω -automata

An ω -automaton is a tuple $\mathcal{A} = (Q, \Sigma, \delta, q_0, Acc)$ where

- Q is a finite set of states
- Σ is a finite alphabet
- ▶ $\delta: Q \times \Sigma \to 2^Q$ is a state transition function (if non-deterministic, otherwise, $\delta: Q \times \Sigma \to Q$)
- ▶ $q_0 \in Q$ is an initial state and Acc is an acceptance condition

Run

A run ρ of \mathcal{A} on an ω -word $\alpha = a_1 a_2 \cdots \in \Sigma^{\omega}$ is an infinite state sequence $\rho(0)\rho(1)\rho(2)\ldots$ such that

- $\rho(i) = \delta(\rho(i-1), a_i)$ if A is deterministic,
- ▶ $\rho(i) \in \delta(\rho(i-1), a_i)$ if A is non-deterministic,

ω -automata

An ω -automaton is a tuple $\mathcal{A} = (Q, \Sigma, \delta, q_0, Acc)$ where

- Q is a finite set of states
- Σ is a finite alphabet
- ▶ $\delta: Q \times \Sigma \to 2^Q$ is a state transition function (if non-deterministic, otherwise, $\delta: Q \times \Sigma \to Q$)
- ▶ $q_0 \in Q$ is an initial state and Acc is an acceptance condition

Run

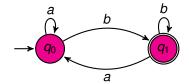
A run ρ of \mathcal{A} on an ω -word $\alpha = a_1 a_2 \cdots \in \Sigma^{\omega}$ is an infinite state sequence $\rho(0)\rho(1)\rho(2)\ldots$ such that

- ▶ $\rho(0) = q_0$,
- $\rho(i) = \delta(\rho(i-1), a_i)$ if A is deterministic,
- ▶ $\rho(i) \in \delta(\rho(i-1), a_i)$ if A is non-deterministic,

Büchi Acceptance

For Büchi Acceptance, *Acc* is specified as a set of states, $G \subseteq Q$. The ω -word α is accepted if there is a run ρ of α such that $Inf(\rho) \cap G \neq \emptyset$.

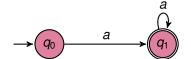
ω -Automata with Büchi Acceptance

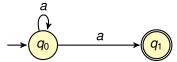


$$L(A) = \{ \alpha \in \Sigma^{\omega} \mid \alpha \text{ has a run } \rho \text{ such that } Inf(\rho) \cap G \neq \emptyset \}$$

Language accepted=Infinitely many b's.

Comparing NFA and NBA





Comparing NFA and NBA

