DEVESH DATWANI

ROBOTICS **ENGINEER**
WORCESTER, MA

OBJECTIVE

Seeking for full time co-op positions in the space of computer vision and/or robot perception

SKILLS

LANGUAGES
Python 3+ ● MATLAB ● C/C++

SOFTWARE STACK
ROS 1 & 2 ● Git ● OpenCV ● TensorFlow
Numpy & Keras ● AWS ● Django & Flask
Linux ● SolidWorks ● AutoCad ● PyTorch

HARDWARE STACK
Arduino Uno ● Raspberry Pi 3 B

EXPERTISE
Deep Learning ● Computer Vision
Machine Learning ● Robot Perception

EDUCATION

MS IN ROBOTICS ENGINEERING
WORCESTER POLYTECHNIC INSTITUTE
WORCESTER, MA | AUG 2021 - MAY 2023

KEY COURSES: Machine Learning ● Robot Control ● Computer Vision ● Artificial Intelligence ● AI For Autonomous Vehicles Robot Dynamics

BE IN MECHANICAL ENGINEERING
APSIT MUMBAI UNIVERSITY
MUMBAI, INDIA | AUG 2014 - MAY 2018

NOTABLE ACHIEVEMENT: Received the "Young Innovator" award for research on Plasma Actuators at the ICASTe conference

CERTIFICATION

Python Programming ● Robotics: Aerial Vehicles ● Applied Machine Learning
Introduction To Self Driving Cars
Deep Learning Specialization

LINKS

https://github.com/deveshdatwani
http://www.linkedin.com/in/deveshdatwani
http://www.deveshdatwani.com/

CONTACT

dbdatwani@wpi.edu
(978) 809-5026

LATEST EXPERIENCE

SPACE GOAT | DESIGN & PERCEPTION ENGINEER
SEP 2021 - JAN 2022 | WPI, WORCESTER, MA
- Competed at the NASA Extreme Terrain Challenge 2022 to build a Mars rover while representing WPI
- Actively contributed in the design of a Martian rover encompassing a novel OTM capstone clutch mechanism
- Integrated sensors with the rover and contributed to the firmware code for rover-environment-perception by implementing statistical filtering algorithms on sensor data

CAPSTONE PROJECT

QUADCOPTER NAVIGATION | RESEARCH ASSISTANT
AUG 2022 - PRESENT | WPI, WORCESTER, MA
- Developing a swarm of mini-quadcopters to navigate through dense spaces like forests & buildings to aid rescue missions under Professor Nitin Sanket
- Building GPS-free quadcopters the size of sunflowers that solely rely on visual perception to navigate challenging environments
- Attempting to build a neural network-based perception stack

RESEARCH PROJECT

AIRFLOW INDUCTION WITH PLASMA ACTUATORS [DOC]
2017 - 2018 | ASPIT, MUMBAI UNIVERSITY
- Designed and led a research project on plasma actuators to induce air flow without the use of any moving elements
- Designed and fabricated a plasma actuator inside hollow pipes powered by a high voltage-high frequency transformer
- Observed & recorded wall-bounded jet air flow of ~ 9000 liters/hr during experiments at the aerospace department of IIT, Bombay

ENGINEERING PROJECTS

HUMAN POSE ESTIMATION WITH CNN [GITHUB]
MAR 2022 - MAY 2022 | WORCESTER POLYTECHNIC INSTITUTE
- Implemented the DeepPose paper to build a convolution neural network for estimating human-body pose in 2 dimensions
- Created a TensorFlow pipeline to fetch and load the FLIC dataset and train an AlexNet on a Google Colab notebook
- Recorded mean squared error values of ~ 400

TRAFFIC SIGN DETECTION WITH MASK R-CNN [GITHUB]
SEP 2021 - DEC 2021 | WORCESTER POLYTECHNIC INSTITUTE
- Implemented adaptations to the Mask R-CNN network to enhance its performance in detecting traffic signs
- Augmented a dataset of 10,000+ traffic sign images (motion blur and condensation) to improve model robustness in adverse weather conditions
- Helped enhance mAP value of the model from 0.05 to 0.25

AERIAL VEHICLE DESIGN [DOC]
2011 - 2020 | MUMBAI, INDIA
- Designed, fabricated and flight-tested remote operated and semi-autonomous fixed-wing planes and quad copters
- Combined various power-plant, wing, composites and electronic, microcontroller and sensor configurations in the 100+ test flights
- Gained hands on experience working with open source firmware for reaching semi and sometimes full autonomy during flights