# DEVESH DATWANI

Portfolio: http://www.deveshdatwani.com Github: https://github.com/deveshdatwani

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EDUCATION

## Worcester Polytechnic Institute

Worcester, MA, USA

Master of Science, Robotics Engineering

August 2021 - May 2023

Email: dbdatwani@wpi.edu

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Courses: Computer Vision, Artificial Intelligence, Machine Learning, Human Robot Interaction, Robot Control

### University of Mumbai

Mumbai, India

Bachelor of Engineering, Mechanical Engineering

January 2014 - March 2018

Notable Achievement: Young Innovator Award at ICASTe Conference for exemplary work on Plasma Actuators

SKILL SET

Programming Languages: Python, C, C++, MATLAB

Libraries / Frameworks: ROS, PyTorch, OpenCV, TensorFlow, Keras, Scikit-Learn, Numpy, STL, Django, Flask

Tools: Git, AWS, Linux, SQLite3, Gropher Bot, Arduino, Raspberry Pi, Aerial Vehicles

Career Focus: Computer Vision, Deep Learning, Robot Perception

Lab Experience

#### Human Inspired Robots Lab - Github

Worcester Polytechnic Institute, Worcester

Graduate Student Researcher

January 2023 - Present

- Working with Dr Li on human robot interaction in assisted autonomy of dexterous manipulation by nursing robots
- o Identifying autonomy failures & building robot interface that enhances operator spatial awareness through cameras
- Conducting user studies to compare interfaces for effective navigation of a Gopher nursing bot in Unity simulator

#### Surface Meteorology Lab

Worcester Polytechnic Institute, Worcester

Graduate Student Researcher

January 2022 - March 2022

- o Contributed in building multi-scale analysis pipeline to predict material surface friction with Prof Christopher Brown
- Implemented polynomial regression on cloud point metadata obtained with 3D microscopes for predictive analysis

#### Popovic Labs

Worcester Polytechnic Institute, Worcester

Graduate Student Researcher

January 2023 - Present

- o Represented Worcester Polytechnic Institute in a team of 15 students at the NASA Big Idea Challenge 2022
- Brainstormed terrain challenges on Martian surface & fabricated an 'OTM' mechanism to build a light-weight rover
- Wrote complementary & extended Kalman filters with Runge-Kutta method in C++ for robust attitude estimation

## Propulsion Lab - Doc

Indian Institute of Technology & University of Mumbai August 2017 - May 2018

Undergraduate Thesis - Patent Application: 201921038313

o Designed a research project on plasma actuators for airflow induction without conventional devices under Prof Bodi

- o Constructed a novel actuator design for airflow induction in hollow pipes powered by high voltage AC transformers
- Compared voltage magnitudes & frequencies with flow velocities & observed maximum airflow of 9000 litres / hr

#### Professional Experience

### WPI - Worcester Fire Department - Github

Worcester, MA, USA

Capstone Experience Project Member

August 2022 - December 2022

- Engaged with the Worcester Fire Department to identify firefighting challenges & their solutions in robotics domain
- Developed a scalable solution based on differential drive robots with a novel approach to evaluate real time fire safety
- Devised a fire safety metric for homes by evaluating harmonic means of path lengths & obstacle proximity to fire exits
- o Integrated a navigation stack for autonomous motion planning & validated accurate localization with particle filter • Implemented change detection algorithm with PCA & K-Means clustering to detect & localize obstacles with LiDARs
- Implemented the informed RRT\* algorithm for finding average path lengths to nearest fire exits on buildings floors

• Built a finite state machine to automate task scheduling & tested the system to evaluate fire safety of apartments

Admatazz Data Analyst

Mumbai, India December 2019 - December 2020

• Worked in the data specialist team to improve marketing strategies through data acquisition & interpretation

- Built web applications for business lead generation with the Django web framework hosted on AWS EC2 servers
- Built a Twitter trends visualizer for seamless real time news & trends access through an interactive web application
- Implemented unsupervised clustering algorithms for customer segmentation for informed & data-driven advertising
- o Built crawling tools for real time lead acquisition from social media platforms like Reddit, JustDial & Product Hunt

#### Air India Engineering Services

Mumbai, India

Intern Trainee

June 2017 - July 2017

o Interned at the engine department & partook in the major overhaul of CFM-56B high bypass turbofan engines

#### ACADEMIC PROJECTS

# Deep Image Segmentation With Attention- Github Computer Vision

Worcester Polytechnic Institute  $March\ 2023\ -\ April\ 2023$ 

- o Developed a U-Net model with attention mechanism for semantic segmentation of medical images on Kvasir dataset
- Implemented the training pipeline & conducted hyper-parameter tuning to achieve a Dice coefficient of 0.87 on test set
- o Demonstrated 2.3% improvement in the Dice mean coefficient with attention mechanisms for clinical applications

#### Vision Based Teleoperation Study - Github

Human Robot Interaction

Worcester Polytechnic Institute September 2022 - December 2022

- o Conducted user study to compare hand gestures and joysticks for mobile robot teleoperation in Gazebo environment
- Integrated Media Pipe's pipeline with ROS & Gazebo framework to estimate hand pose with multiview bootstrapping
- o Observed 53% higher user control efficiency with joystick teleoperation in a custom scratch-built obstacle course

# Classical and Deep Image Stitching - Github

Computer Vision

Worcester Polytechnic Institute August 2022 - October 2022

- Wrote Python scripts to build panoramas with Harris corner detection, Adaptive Non Max Suppression & RANSAC
- Synthesized data samples by transforming COCO dataset images & finding their closed form solutions in OpenCV
- Built HomographyNet from scratch in PyTorch & validated Spatial Transformer Network for homography estimation

# Structure From Motion / SLAM - Github

Computer Vision

Worcester Polytechnic Institute August 2022 - October 2022

- o Optimized non-linear geometric projection with Zhang's camera calibration method
- $\circ$  Constructed a 3D structure from images of different views of WPI's Unity Hall through epipolar geometry principles
- Wrote non-linear triangulation, PnP & bundle adjustment scripts in Python to build 3D structures from 2D images

# Deep Pose Estimation - Github

' Artificial Intelligence

Worcester Polytechnic Institute March 2022 - May 2022

- o Implemented the Deep Pose paper from scratch to estimate human body pose in 2 dimensional space with TensorFlow
- Built a deep learning regressor with AlexNet as the base network and trained it on FLIC dataset on Google Colab
- o Observed 12% decrease in MSE by cascading the network through interest region cropping & key-point normalization

# Optimizing Mask R-CNN For Traffic Sign Detection - Github Machine Learning

Worcester Polytechnic Institute  $September\ 2021$  -  $December\ 2021$ 

- o Experimented with the Mask R-CNN model to optimize it for traffic sign detection in harsh weather conditions
- Trained the model on an augmented traffic sign dataset sampled by synthesizing motion blur, rain & dew effects
- o Observed a 15% increase in mAP scores by optimizing the model with sample redistribution & annotation correction

# Personal Projects

## Aerial Vehicle Design and Autonomy - Doc

Mumbai, India

Personal Project

May 2011 - February 2019

- o Designed fabricated & flight tested scaled fixed wing aircraft & quad-copters to satiate passion for aviation
- o Constructed fixed wing aircraft powered by one of the smallest internal combustion engines in production
- Implemented PD controller in C++ on Arduino microcontroller to enable cruising autonomy for fixed wing aircraft
- o Built aerial vehicles with carbon fiber, composites, balsa wood & 3D printed parts for light-weight durable airframes
- $\circ$  Gained hands-on experience in building aerial vehicles after 15+ successful aircraft designs & tests