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**Roll No: 9766**

**TE Comps A**

### **AI Experiment No. 7**

**Aim: Block World Problem solving by hill climbing approach**

#### **Program:**

```
# Devesh Vengurlekar
```

```
#Roll No: 9766
```

```
# TE Comps A
```

```
import random
```

```
# Define the initial state of the block world
```

```
initial_state = ['A', 'B', 'C', 'D']
```

```
# Define the goal state of the block world
```

```
goal_state = ['D', 'A', 'B', 'C']
```

```
# Define a function to calculate the heuristic (number of misplaced blocks)
```

```
def heuristic(state):
```

```
    return sum([1 for i, j in zip(state, goal_state) if i != j])
```

```
# Define a function to generate neighboring states (move a block to the top)
```

```
def generate_neighbors(state):
```

```
    neighbors = []
```

```
    for i in range(len(state)):
```

```
        for j in range(i+1, len(state)):
```

```
            neighbor = state[:i] + [state[j]] + state[i:j] + state[j+1:]
```

```
            neighbors.append(neighbor)
```

```
    return neighbors
```

```
# Define the Hill Climbing algorithm
```

```
def hill_climbing(initial_state, goal_state):
```

```
    current_state = initial_state
```

```
    while True:
```

```
        current_heuristic = heuristic(current_state)
```

```
        neighbors = generate_neighbors(current_state)
```

```
best_neighbor = min(neighbors, key=lambda neighbor: heuristic(neighbor))
if heuristic(best_neighbor) >= current_heuristic:
    return current_state
current_state = best_neighbor

# Run the Hill Climbing algorithm
final_state = hill_climbing(initial_state, goal_state)

# Print the result
print("Initial State:", initial_state)
print("Final State:", final_state)
```

## Output:

```
# Print the result
print("Initial State:", initial_state)
print("Final State:", final_state)
```

```
Initial State: ['A', 'B', 'C', 'D']
Final State: ['D', 'A', 'B', 'C']
```