Binary Search Tree (BST) Operations: Time & Space Complexity

Operation	Balanced BST	Skewed BST	Iterative vs Recursive	Best Approach & Why?	Time Complexity	Space Complexity
Insert	Recursive (Good)	Iterative (Best)tera	tive (safe), Recursive Recada	ble)is cleaner, but Iterative avoids deep red	curstition (hog N) / O(N)	O(log N) / O(1)
Search	Recursive (Good)	Iterative (Best)	terative (best for largetentations)	is safer since recursion may cause stack of	ve đi(do gN)/O(N)	O(log N) / O(1)
Delete	Recursive (Best) I	terative (Not Feasib Re	cursive (better logic Ræddins	g)e preferred for handling two-child deletion	n ca 9(lo g N) / O(N)	O(log N) / O(1)
Inorder Traversal	Recursive (Good)	Iterative (Good)Re	cursive (best for depthRetage	(N)e is natural, but Iterative needed for large	e trees O(N)	O(N) / O(log N)
Preorder Traversal	Recursive (Good)	Iterative (GRoed)ursi	ve (simple), Iterative (for lagg	ætitre∉s)quires explicit stack, recursive is ea	sier O(N)	O(N)
Postorder Traversal	Recursive (Best)	Iterative (Feasible)	Recursive (better structured)	Iterative is tricky as it requires two stacks	O(N)	O(N)
Level Order (BFS)	Iterative (Best)	Iterative (Best) Ite	rative (only feasible approac	h)Uses a queue, recursion is not practical	O(N)	O(N)
Height Calculation	Recursive (Best) R	ecursive (Not Feasible	eRecursive (nubeterastionopuleiòn)	max(left, right)`, but deep recursion issue	in skew @(M ees	O(log N) / O(N)
Check if BST is Balanced	Recursive (Best) R	ecursive (Not Feasible	eRecursive (best approach)N	eeds recursion to check height and balanc	e O(N) / O(N²)	O(log N) / O(N)

When to Use What?

Scenario	Best Approach	Why?	
Tree is small or balanced	Use Recursive	Cleaner & more natural	
Tree is large or unbalanced	Use Iterative	Prevents deep recursion & stack overflow	
Level Order Traversal (BFS)	Use Iterative (Queue-based)	No recursion alternative	
Deletion in BST	Use Recursive	Handles all cases efficiently	
Performance is a concern	Use Iterative	Uses O(1) space, avoids recursion overhead	