

src/hammerhead/mission
_stack/path_planner/src
/FindGate.cpp

```
graph TD; A["src/hammerhead/mission_stack/path_planner/src/FindGate.cpp"] --> B["path_planner/FindGate.h"]; B --> C["iostream"]; B --> D["chrono"];
```

The diagram illustrates a dependency structure. At the top, a grey box contains the file path 'src/hammerhead/mission_stack/path_planner/src/FindGate.cpp'. A blue arrow points from this box to a white box below it containing 'path_planner/FindGate.h'. From this second box, two blue arrows branch out to two separate white boxes at the bottom: 'iostream' on the left and 'chrono' on the right.

path_planner/FindGate.h

iostream

chrono