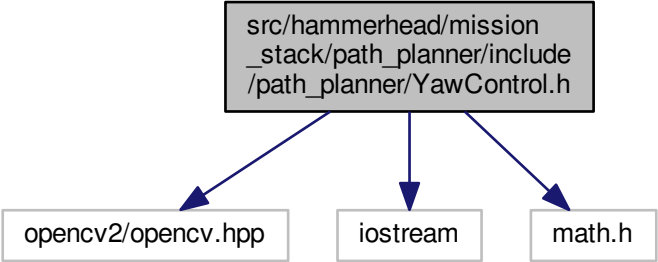


src/hammerhead/mission
_stack/path_planner/include
/path_planner/YawControl.h



```
graph TD; A["src/hammerhead/mission_stack/path_planner/include/path_planner/YawControl.h"] --> B["opencv2/opencv.hpp"]; A --> C["iostream"]; A --> D["math.h"];
```

The diagram illustrates the dependencies of the file `src/hammerhead/mission_stack/path_planner/include/path_planner/YawControl.h`. Three blue arrows point from the bottom of the top box to the three boxes below it, indicating that `YawControl.h` includes `opencv2/opencv.hpp`, `iostream`, and `math.h`.

opencv2/opencv.hpp

iostream

math.h