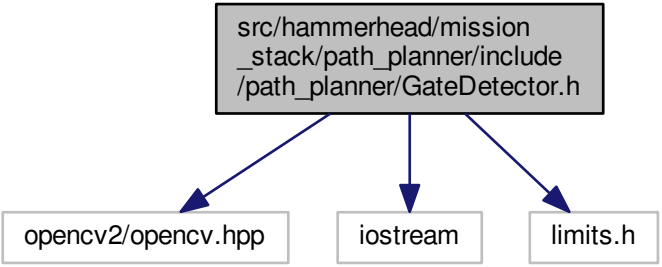


src/hammerhead/mission
_stack/path_planner/include
/path_planner/GateDetector.h



```
graph TD; A["src/hammerhead/mission_stack/path_planner/include/path_planner/GateDetector.h"] --> B["opencv2/opencv.hpp"]; A --> C["iostream"]; A --> D["limits.h"];
```

The diagram illustrates the dependencies of the file `src/hammerhead/mission_stack/path_planner/include/path_planner/GateDetector.h`. Three blue arrows point from the top box to three bottom boxes, indicating that the top file includes the three files listed below.

opencv2/opencv.hpp

iostream

limits.h