Unit 5 review – Iterative Methods



Gradient descent for solving general optimization problems: arg min L(X, y; w)

(Idea) Iterate in the direction of greatest descent

$$w^{(k+1)} = w^{(k)} - \tau \nabla_{w} L(X, y; w^{(k)})$$

Proximal gradient methods for solving regularized least-squares: $\underset{w}{\text{arg }} \min_{w} ||Xw - y||_{2}^{2} + \gamma R(w)$

$$\arg\min_{w} ||Xw - y||_2^2 + \gamma R(w)$$

(Idea) Iterate between 2 steps:
$$\begin{cases} z^{(k)} = w^{(k)} - \tau X^T (Xw^{(k)} - y) & \text{Gradient descent on } ||Xw - y||_2^2 \\ w^{(k+1)} = \arg\min_{w} \left\| w - z^{(k)} \right\|_2^2 + \gamma R(w) & \text{Regularize. Often closed-form solution exists.} \end{cases}$$

LASSO: $R(w) = \sum_{i} |w_{i}|$

- L1 regularization tends to encourage sparse solutions
- No closed form solution
- Proximal gradient method to solve LASSO iteratively

Support Vector Machines

$$\arg\min_{w} \sum_{i} (1 - y_i w^T x_i)_+ + \gamma ||w||_2^2$$

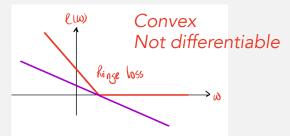
- Why hinge loss? Least squares penalizes easy samples.
- Minimizing $||w||_2^2$ subject to $y_i w^T x_i \ge 1$ maximizes the margin of the classifier.

(Today) Sub gradients and their role with nondifferentiable function optimization

Activity 20



Sub-gradients



Sub-gradient: any plane that lies below function.

any
$$\boldsymbol{v}$$
 such that $\ell(\boldsymbol{w}) \geq \ell(\boldsymbol{w}_0) + (\boldsymbol{w} - \boldsymbol{w}_0)^T \boldsymbol{v}$

Classifying new data:

$$oldsymbol{x} =$$

$$\widehat{y} = \operatorname{sign}(\boldsymbol{x}^T \boldsymbol{w})$$

if $\widehat{y} = 1$ then dog

if
$$\widehat{y} = -1$$
 then cat

Training a classifier:

$$\min_{oldsymbol{w}} \sum_{i=1}^{ ext{a million}} (oldsymbol{x}_i^T oldsymbol{w} - y_i)^2$$

 $(\boldsymbol{x}_i, y_i), i = 1, ..., a \text{ million}$



Stochastic Gradient Descent

$$\min_{\boldsymbol{w}} \sum_{i=1}^{\text{a million}} \ell_i(\boldsymbol{w}) \qquad \boldsymbol{w}^{(k+1)} = \boldsymbol{w}^{(k)} - \tau \nabla \ell(\boldsymbol{w}^k)$$
 (Gradient Descent)

Main idea

Do gradient descent, but on a random subset of training examples at each iteration.

$$\mathbf{w}^{(1)} = \mathbf{w}^{(0)} - \tau \sum_{i=1}^{100} \nabla \ell_i(\mathbf{w}^{(0)})$$

$$\mathbf{w}^{(2)} = \mathbf{w}^{(1)} - \tau \sum_{i=101}^{200} \nabla \ell_i(\mathbf{w}^{(1)})$$

- Image/video classification and recognition
- ML translation
- Large scale prediction and regression tasks

Problem: computing the loss is too slow.



- a) Is f(w) convex? Why? *Hint*: Graph the function.
- **b)** Is f(w) differentiable everywhere? If not, where not?
- c) The "differential set" $\partial f(\boldsymbol{w})$ is the set of subgradients $\boldsymbol{v} \in \partial f(\boldsymbol{w})$ for which $f(\boldsymbol{u}) \geq f(\boldsymbol{w}) + (\boldsymbol{u} \boldsymbol{w})^T \boldsymbol{v}$. Find the differential set for f(w) as a function of w.

minimize
$$\sum_{i=1}^{m} (1 - b_i \boldsymbol{x}_i^T \boldsymbol{w})_+$$
 where $(u)_+ = \max(0, u)$ is the hinge loss operator

- a) Derive a gradient descent method for solving this problem. Explicitly give the computations required at each step. *Note:* you may ignore points where the function is non-differentiable.
- b) Explain what happens to the algorithm if you land at a w^k that classifies all the points perfectly, and by a substantial margin.



CS/ECE/ME 532 Matrix Methods in Machine Learning **3.** You have four training samples $y_1 = 1, \boldsymbol{x}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, y_2 = 2, \boldsymbol{x}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, y_3 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$

$$-1, \boldsymbol{x}_3 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$
, and $y_4 = -2, \boldsymbol{x}_4 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$. Use cyclic stochastic gradient descent

to find the first two updates for the LASSO problem

$$\min_{\boldsymbol{w}} ||\boldsymbol{y} - \boldsymbol{X} \boldsymbol{w}||_2^2 + 2||\boldsymbol{w}||_1$$

assuming a step size of $\tau = 1$ and $\mathbf{w}^{(0)} = 0$. Also indicate the data used for the first six updates.