### 2G1915 Concurrent Programming Lecture 14

## Case Study: Introduction to MPI

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### Outline (see also Section 7.8)

- Introduction
  - MPI programming concepts: processes, communicators, etc.
- The MPI library: functions, types
- Basic MPI functions
- Send/receive:
  - Blocking
  - Non-blocking
- Collective operations: barriers, broadcast, gather/scatter, reduce, etc.
- Modularity: working with communicators

### MPI: Message Passing Interface

- MPI is a message-passing library specification for multiprocessor, clusters, and heterogeneous networks
  - Not a compiler specification, not a specific product.
  - Message-passing model and API
  - Designed
    - To permit the development of parallel software libraries
    - To provide access to advanced parallel hardware for end users, library writers, and tool developers.
  - MPI is a de facto standard for message passing systems
  - Language bindings: Fortran and C
- MPICH and LAM the two most popular implementations of MPI today
  - MPICH is more generally usable on various platforms
  - LAM for TCP/IP networks
- Other common systems: PVM, p4, Parmacs

## The MPI Library (API)

- The MPI library is large: about 130 functions
  - extensive functionality and flexibility
    - message passing (point-to-point, collective)
    - process groups and topologies
- The MPI library is small: 6 functions allow writing many programs
  - MPI\_Init, MPI\_Finalize,
     MPI\_Comm\_size, MPI\_Comm\_rank,
     MPI\_Send, MPI\_Recv
  - or another 6-function set:
    - MPI\_Init, MPI\_Finalize,
       MPI\_Comm\_size, MPI\_Comm\_rank,
       MPI\_ Bcast, MPI\_ Reduce
- All MPI functions, constants and data types have prefix MPI\_

## C Data Types Mapping in MPI

• (see mpi.h)

MPI datatype	C datatype
MPI_CHAR	signed char
MPI_SHORT	signed short int
MPI_IMT	signed int
MPI_LOWG	signed long int
MPI_UMSIGMED_CHAR	unsigned char
MPI_UMSIGNED_SHORT	unsigned short int
MPI_UMSIGNED	unsigned int
MPI_UMSIGNED_LONG	unsigned long int
MPI_FLOAT	float
MPI_DOUBLE	double
MPI_LONG_DOUBLE	long double
MPI_BYTE	_
MPI_PACKED	

## MPI Programming Concepts: Processes

#### • A MPI process

- A smallest unit of computation, e.g. a Unix process.
- Uniquely identified by its rank in a process group.
- Processes communicate with tagged messages within process groups identified by communicators (communication contexts)
- A proc can send messages either synchronously or asynchronously.
- The proc is responsible for receiving messages directed to it.
- The proc uses either blocking or non-blocking receive/send.
- The proc can participate in a collective operation such as broadcast, gather, barrier, that involves all processes in a group.

#### • A MPI application

- a static set of processes that interact to solve a problem.
- mpirun -np 2 hello starts two hello processes on two processors.

## Communicators. Process groups. Ranks

#### • Communicator

- An opaque object that defines a process group and a communication context for the group. Delimits scope of communication.
  - Separate groups of processes working on subproblems each with specific communication context identified by a communicator.

#### • Process group

- A virtual set of processes identified by a communicator.
  - Grouped for collective and point-to-point communications.
  - All communication (not just collective operations) takes place in groups.
  - Each process has a unique index (rank) in a given group.

#### Rank

A unique identifier (index) of a process within a communication (in a proc group).

## Programming, Building and Running a MPI Application

- Install one of the MPI implementations, e.g. MPICH
- Develop your application one program for all processes
  - The number of processes is specified at run time (could be 1)
  - Use the number of proc and proc ranks to determine process tasks
  - In C: #include <mpi.h>
- Compile:

```
mpicc -o myprog myprog.c
```

- For large projects, develop a Makefile (see for example, mpich/examples/Makefile.in
- Run:

```
mpirun -np 2 myprog
```

- The option -help shows all options to mpirun.

### **Basic MPI Functions**

- int MPI\_Init(int \*argc, char \*\*argv[])
  - Start MPI, enroll the process in the MPI application
- int MPI\_Finalize()
  - Stop (exit) MPI
- int MPI\_Comm\_size(MPI\_Comm comm, int \*size)
  - Determine the number of processes in the group comm.
    - comm communicator, e.g. MPI\_COMM\_WORLD
    - **size** number of processes in group (returned)
- int MPI\_Comm\_rank(MPI\_Comm comm, int \*rank)
  - Determine the rank of the calling process in the group comm.
    - comm communicator, e.g. MPI\_COMM\_WORLD
    - rank the rank (returned) is a number between zero and size-1

### Example: "Hello World"

```
#include "mpi.h"
#include <stdio.h>
int main( argc, argv )
int argc;
char **argv;
   int rank, size;
   MPI_Init( &argc, &argv );
   MPI Comm rank( MPI COMM WORLD, &rank );
   MPI Comm size( MPI COMM WORLD, &size );
   printf( "Hello world! I'm %d of %d\n", rank, size );
   MPI Finalize();
   return 0;
```

## Basic (Blocking) Send

- int MPI\_Send(void \*buf, int count, MPI\_datatype dt, int dest, int tag, MPI\_Comm comm)
  - Send a message with the given tag to the given destination process in the given communicator

• **buf** send buffer

• count number of items in buffer

• dt data type of items

• dest destination process rank

• tag message tag

• communicator

- Returns integer result code as for all MPI functions, normally MPI\_SUCCESS
- **datatype** can be elementary, continues array of data types, stridden blocks of data types, indexed array of blocks of data types, general structure.

### Basic (Blocking) Receive

int MPI\_Recv(void \*buf, int count, MPI\_datatype dt,
 int source, int tag, MPI\_Comm comm, MPI\_Status \*status))

Receive a message with the given tag from the given source in the given communicator

• **buf** receive buffer (loaded)

• count max number of entries in buffer

• dt data type of entries

• source source process rank

• tag message tag

• communicator

• status status (returned).

 "Wildcard" values are provided for tag (MPI\_ANY\_TAG) and source (MPI\_ANY\_SOURCE).

### Inspecting Received Message

• If wildcard values are used for tag and/or sources, the received message can be inspected via a MPI\_Status structure that has three components MPI\_SOURCE, MPI\_TAG, MPI\_ERROR

```
MPI_Status status;
MPI_Recv( ..., &status );
int tag_received = status.MPI_TAG;
int rank_of_source = status.MPI_SOURCE;
MPI_Get_count( &status, datatype, &count );
```

 MPI\_Get\_count is used to determine how much data of a particular type has been received.

### Communication Modes of Blocking Send

- Standard blocking send (non-local) MPI\_Send
  - Implementation defined buffering: If the message is buffered, the send may complete before a matching receive is invoked.
- Buffered blocking send (local) MPI\_Bsend
  - Can be started whether or not a matching receive has been posted,
  - may complete before a matching receive is posted.
- Synchronous blocking send (non-local) MPI\_Ssend
  - Can be started whether or not a matching receive has been posted,
  - complete when a matching receive is posted and has started to receive.
- *Ready* blocking send (non-local) MPI\_Rsend
  - may be started only if the matching receive is already posted,
  - Otherwise outcome is undefined.

# Example 1: Exchange of Messages (Always Succeeds)

```
MPI_Comm_rank(comm, &rank);
if (rank = 0) {
    MPI_Send(sendbuf, count, MPI_REAL, 1, tag, comm);
    MPI_Recv(recvbuf, count, MPI_REAL, 1, tag, comm, &status);
}
if (rank = 1) {
    MPI_Recv(recvbuf, count, MPI_REAL, 0, tag, comm, &status);
    MPI_Send(sendbuf, count, MPI_REAL, 0, tag, comm);
}
```

- This program will succeed even if no buffer space for data is available.
- The standard send operation can be replaced, in this example, with asynchronous send.

# Example 2: Exchange of Messages (Always Deadlocks)

```
MPI_Comm_rank(comm, &rank);
if (rank = 0) {
    MPI_Recv(recvbuf, count, MPI_REAL, 1, tag, comm, &status);
    MPI_Send(sendbuf, count, MPI_REAL, 1, tag, comm);
}
if (rank = 1) {
    MPI_Recv(recvbuf, count, MPI_REAL, 0, tag, comm, &status);
    MPI_Send(sendbuf, count, MPI_REAL, 0, tag, comm);
}
```

- This program will always deadlock!
- The same holds for any other send mode.

## Example 3: Exchange of Messages (Relies on Buffering)

```
MPI_Comm_rank(comm, &rank);
if (rank = 0)
    {
        MPI_Send(sendbuf, count, MPI_REAL, 1, tag, comm);
        MPI_Recv(recvbuf, count, MPI_REAL, 1, tag, comm, &status);
    }
if (rank = 1)
    {
        MPI_Send(sendbuf, count, MPI_REAL, 0, tag, comm);
        MPI_Recv(recvbuf, count, MPI_REAL, 0, tag, comm, &status);
    }
}
```

- For the program to complete, it is necessary that at least one of the two messages sent has been buffered.
- The program can succeed only if the communication system can buffer at least **count** words of data.

### Non-Blocking Communication Operations

• *Non-blocking send* initiates sending:

```
int MPI_Isend(void* buf, int count, MPI_Datatype type,
  int dest, int tag, MPI_Comm comm, MPI_Request *request)
```

• *Non-blocking receive* initiates receiving:

```
int MPI_Irecv(void* buf, int count, MPI_Datatype type,
  int source, int tag, MPI Comm comm, MPI Request *request)
```

- A request object is returned in **request** to identify the operation.
- To query the status of communication or to wait for its completion:

Returns immediately with flag = true if the operation identified by request has completed, otherwise returns immediately with flag = false.

```
int MPI_Wait(MPI_Request *request, MPI_Status *status)
```

Returns when the operation identified by request completes.

### Example: Non-Blocking Send/Receive

```
MPI Comm rank(comm, &rank);
if (rank = 0)
    MPI Isend(a, 10, MPI REAL, 1, tag, comm, request);
    /**** do some computation to mask latency ****/
    MPI Wait(request, &status);
if (rank = 1)
    MPI Irecv(a, 10, MPI REAL, 0, tag, comm, request);
    /**** do some computation to mask latency ****/
    MPI Wait(request, &status);
```

## Probing for Pending Messages

```
MPI_Iprobe(source, tag, comm, flag, status)
```

polls for pending messages

```
MPI_Probe(source, tag, comm, status)
```

- returns when a message is pending
- Non-blocking/blocking check for an incoming message without receiving it

## **Collection Operations**

- A *collective operation* is executed by having all processes in the communicator call the same communication routine with matching arguments.
  - Several collective routines have a single originating or receiving process the *root*.
  - Some arguments in the collective functions are specified as "significant only at root", and are ignored for all participants except the root.

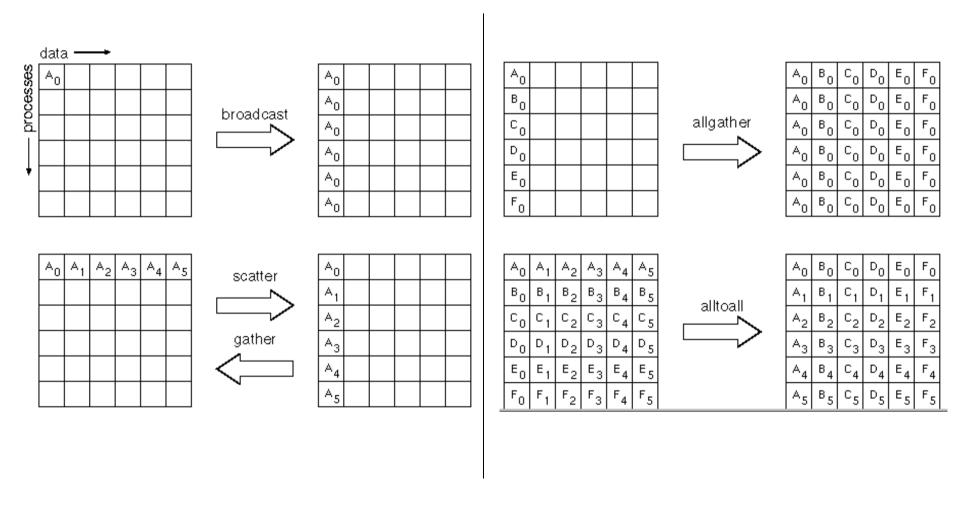
### **Collective Communication**

• Collective synchronization (barrier): int MPI Barrier(MPI Comm comm)

Broadcast from buf of root to all processes:
 int MPI\_Bcast(void \*buf, int count, MPI\_datatype dt,
 int root, MPI Comm comm)

• Collective data transfer:

## Collective Move Operations



### Example 1: Broadcast

• Broadcast 100 integers from process 0 to every process in the group.

```
MPI_Comm comm;
   int array[100];
   int root=0;
   ...
   MPI_Bcast( array, 100, MPI_INT, root, comm);
}
```

## Example 2: Gather

• Gather 100 integers from every process in group to root.

```
MPI_Comm comm;
int gsize, sendarray[100];
int root, myrank, *rbuf;
...
MPI_Comm_rank( comm, myrank);
MPI_Comm_size( comm, &gsize);
...
if ( myrank == root)
    rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Gather( sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

### Example 3: Scatter

• The reverse of Example 2 (previous slide): Scatter sets of 100 integers from the root to each process in the group.

```
100
                                         100
                                                 100
MPI Comm comm;
                                                                  all processes
int gsize, *sendbuf;
int root, rbuf[100];
                                     100
                                         100
                                              100
                                                                  at root
MPI Comm rank( comm, myrank);
MPI Comm size( comm, &gsize);
                                    sendbuf
if ( myrank == root) {
    sendbuf = (int *)malloc(gsize*100*sizeof(int));
    ... // fill the send buffer with data to be scattered
MPI_Scatter( sendbuf, 100, MPI_INT, rbuf, 100, MPI_INT, root,
   comm);
```

## Global Reduction Operations

• Reduce from send buffers of all participating processes into a receive buffer of the root proc using operation op

• Reduce from send buffers of all participating processes into receive buffers of all the processes using operation op

Available operations include:

```
MPI_MAX, MPI_MIN, MPI_SUM, MPI_LAND, MPI_BOR, ...
```

### **Timing Functions**

- double MPI\_Wtime(void)
  - Returns a floating-point number of seconds, representing elapsed wall-clock time since some time in the past. The time is "local" on the host.
- double MPI\_Wtick(void)
  - Returns the resolution of MPI\_WTIME in seconds, the number of seconds between successive clock ticks.
- Example of usage:

### Modularity: Communicators

- A *communicator* identifies a process group and provides a context for all communication within the group
  - Communicator acts as an extra tag on messages
- The communicator MPI\_COMM\_WORLD identifies all running processes of the MPI application

### **Create/Destroy Communicators**

• Create new communicator: same group, new context:

```
int MPI_Comm_dup(MPI_Comm comm, MPI_Comm *newcomm)
```

• Create new communicators based on colors, ordered by keys:

- color identifies a group, **key** rank in the group
- Create an inter-communicator from two intra-communicators

• Destroy a communicator

```
int MPI_Comm_free(MPI_Comm *comm)
```

### Communicators (cont'd)

• One use of communicators is for calling parallel library routines in different context:

```
MPI_Comm *newcomm;
...
MPI_Comm_dup(comm, newcomm);
transpose(newcomm, matrix); /* call library function */
MPI_Comm_free(newcomm);
```

# Example: Compute PI

```
#include "mpi.h"
#include <math.h>
int main(int argc,char *argv[]) {
    int done = 0, n, myid, numprocs, i, rc;
    double PI25DT = 3.141592653589793238462643;
    double mypi, pi, h, sum, x, a;
   MPI_Init(&argc,&argv);
    MPI Comm size(MPI COMM WORLD,&numprocs);
    MPI Comm rank(MPI COMM WORLD,&myid);
   while (!done) {
       if (myid == 0) {
          printf("Enter the number of intervals: (0 quits) ");
          scanf("%d",&n);
       MPI Bcast(&n, 1, MPI INT, 0, MPI COMM WORLD);
       if (n == 0) break;
      h = 1.0 / (double) n;
       sum = 0.0;
      for (i = myid + 1; i <= n; i += numprocs) {
          x = h * ((double)i - 0.5);
          sum += 4.0 / (1.0 + x*x);
       mypi = h * sum;
      MPI_Reduce(&mypi, &pi, 1, MPI_DOUBLE, MPI_SUM, 0,
                  MPI_COMM_WORLD);
      if (myid == 0) printf("pi is approximately %.16f,
                              Error is %.16f\n", pi,
                              fabs(pi - PI25DT));
 MPI Finalize();
```