

# Java with Raspberry Pi

Stephen Chin (@steveonjava)

Java Technology Evangelist

JavaOne Conference Chair

James Weaver (@javafxpert)

Java Technology Evangelist



# Java Scale

## Raspberry Pi Coffee









DEVNEXUS

# Driving Test





Pilatus

PILOTENFLUGSCHOOL  
PILOTENFLUGSCHOOL CIVIL AIRLINE PILOTS

1

01' 26" 06



GOOMBA  
GOOMBA  
GOOMBA  
GOOMBA  
GOOMBA

SCORE - 003700 STAGE - 1 - 1  
TIMER - 101 [  ] NINJA - |||  
P - 02 Z - 30 ENEMY - |||

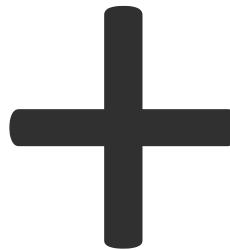






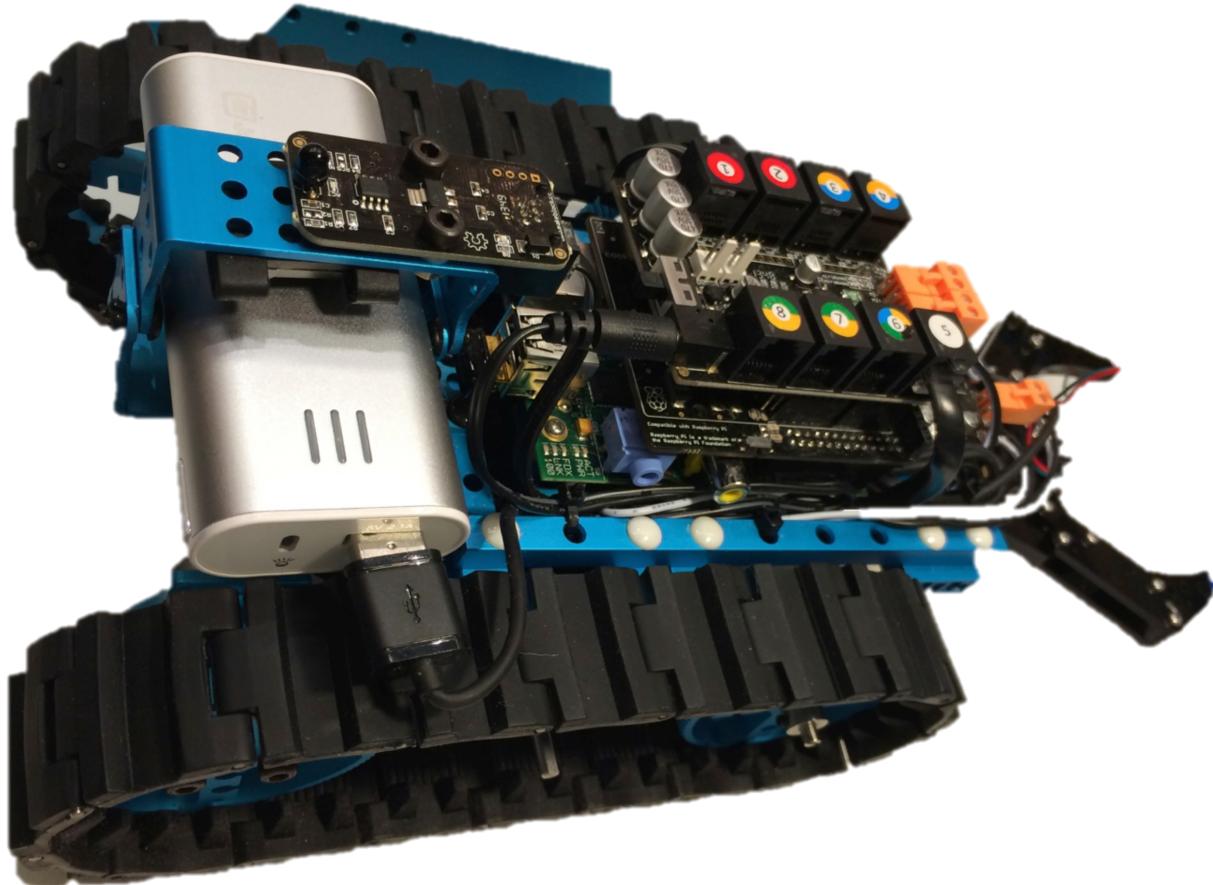
Up-Up-Down-Down-Left-Right-  
Left-Right B, A, Start

# Meet Mr. Grabby

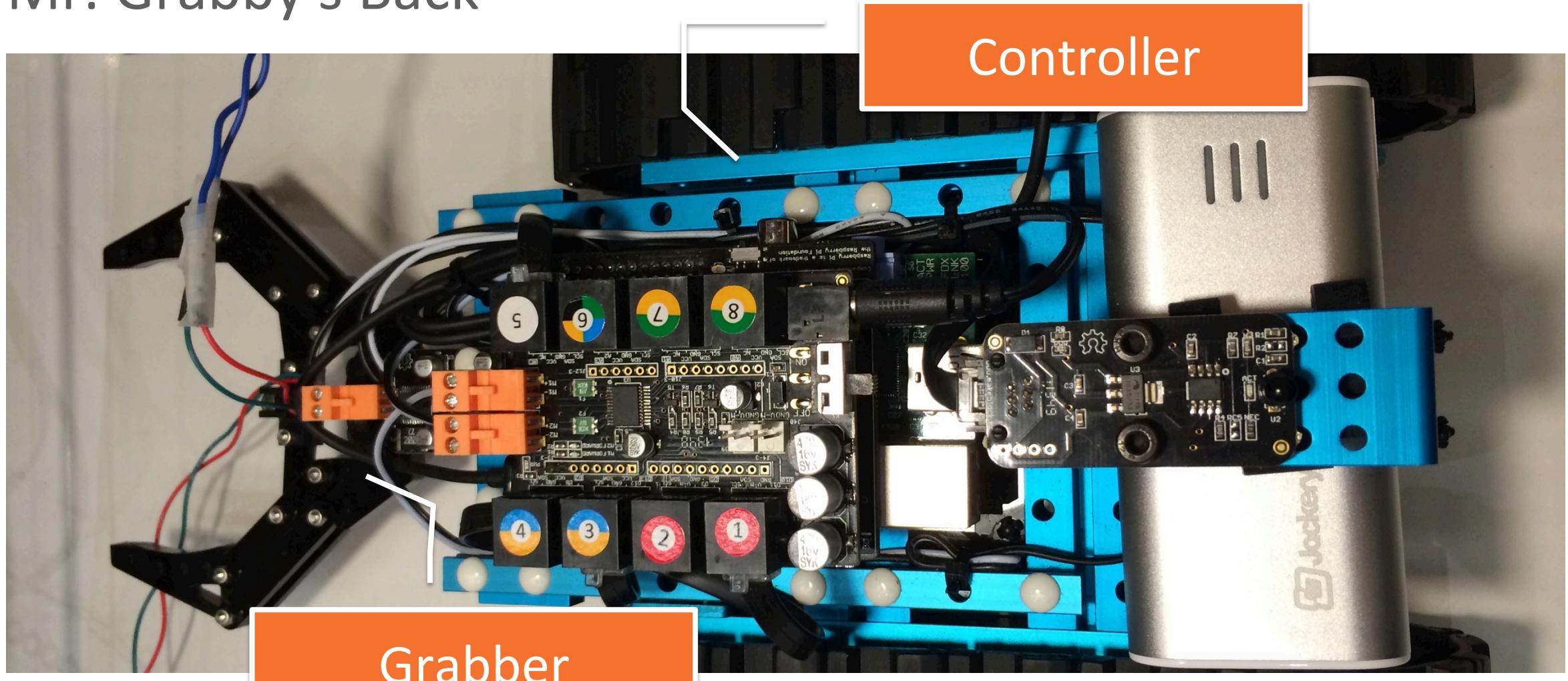


<https://www.flickr.com/photos/pasukaru76/8278458818/>  
<https://www.flickr.com/photos/fallentomato/5656700432/>

# Meet Mr. Grabby



# Mr. Grabby's Back

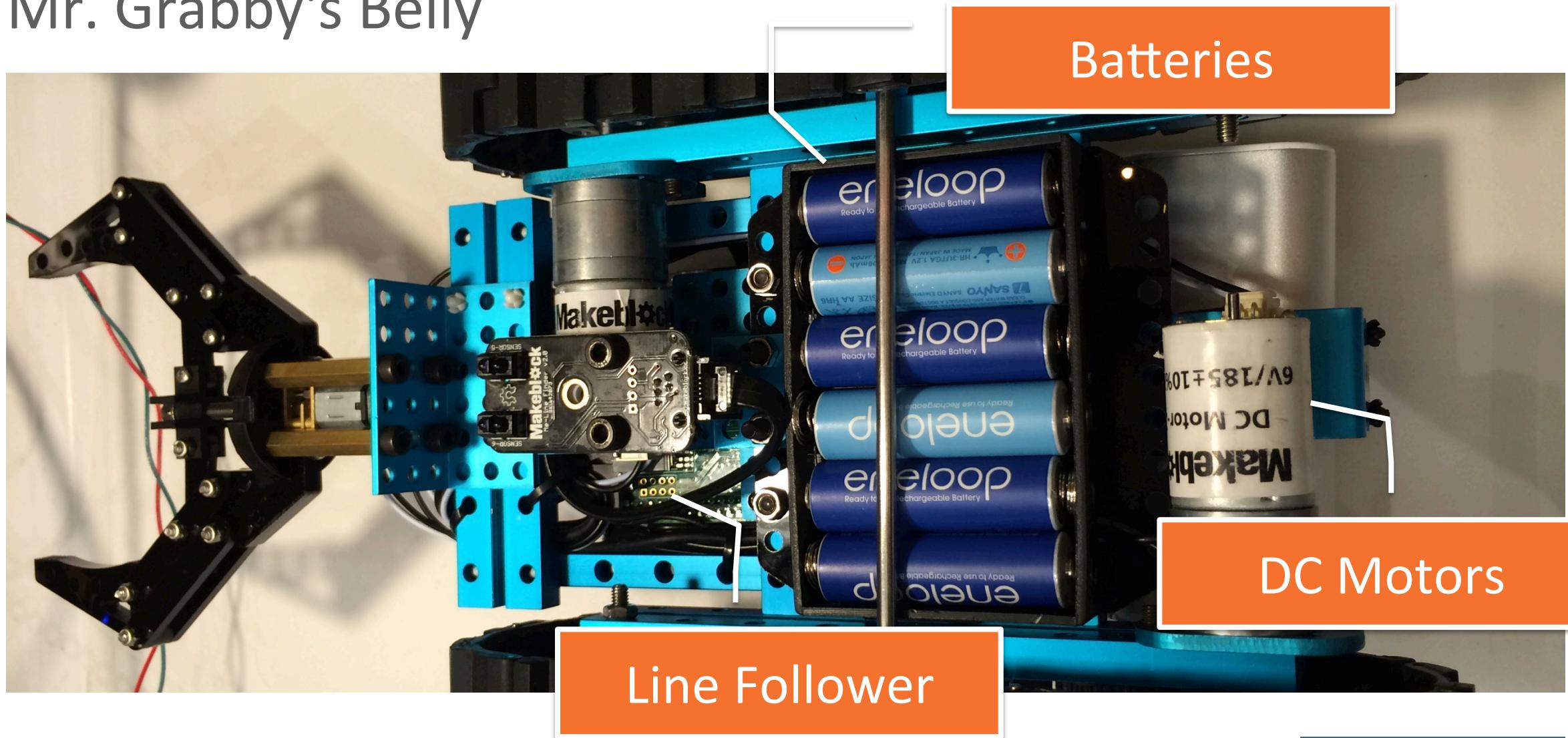


# Controller

- Raspberry Pi
- Cooking Hacks Shield
- MakeBlocks ME Base Shield



# Mr. Grabby's Belly



# How Line Followers Work

- Infrared LED
  - Bounced light off the ground
- Infrared Luminosity Sensor
  - Detects reflected light



# Getting GPIO

```
gpio = GpioFactory.getInstance();
lineFollowA = gpio.provisionDigitalInputPin(
    RaspiPin.GPIO_13, "LineFollowA");
lineFollowB = gpio.provisionDigitalInputPin(
    RaspiPin.GPIO_14, "LineFollowA");
startGPIO();

boolean leftSensor = lineFollowA.getState().isHigh();
boolean rightSensor = lineFollowB.getState().isHigh();
```

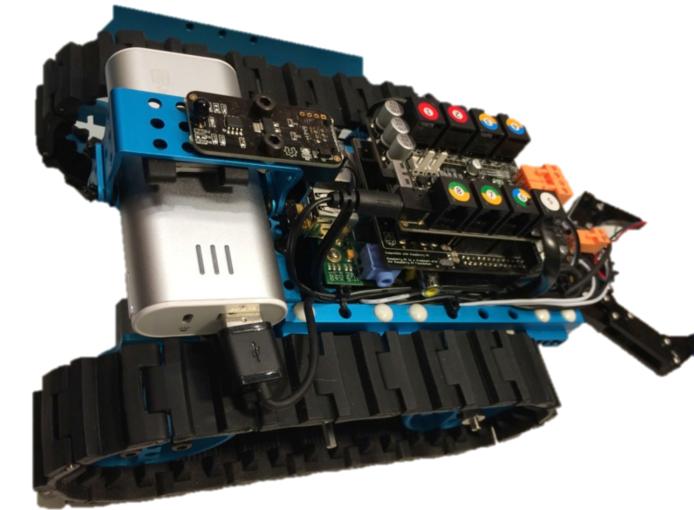
# Line Following Algorithm

```
if (leftSensor && rightSensor) { //we are lost  
    doDrive(lineLocation);  
} else if (!leftSensor && !rightSensor) { //on the line  
    lineLocation = Drive.forward; doDrive(Drive.forward);  
} else if (!leftSensor && rightSensor) { //off the right  
    lineLocation = Drive.left; doDrive(Drive.forward);  
} else if (leftSensor && !rightSensor) { //off the left  
    lineLocation = Drive.right; doDrive(Drive.forward);  
}
```

# Make your own Mr. Grabby

- MakeBlock Advanced Robotics Kit
  - MakeBlock ME Base Shield
  - Cooking Hacks Shield
  - USB Battery (1A)
- 
- Code here:

<https://github.com/steveonjava/LineFollower>



# IoT Magic



# Wearable Raspberry Pi

## IoT Magic Hat

- ODROID-W
  - Raspberry Pi clone
- NFC/RFID Sensor
  - Adafruit PN532 chipset
- RFID Playing Cards
  - Mifare Ultralight tags embedded





# RFID/NFC Reader Configuration

- Pi configuration
  - I2C, SPI, or UART
- NFC configuration
  - libnfc to interface with the NFC reader.
  - pcscd to expose rfid readers to Java SE
  - idfnfc to bridge libnfc to idfnfc
- Java hacking
  - smartio API that is already a part of the JRE.

# Getting a Card Terminal

```
TerminalFactory factory = TerminalFactory.getDefault();
CardTerminals terminals = factory.terminals();
List<CardTerminal> list = terminals.list();
CardTerminal cardTerminal = list.get(0);
```

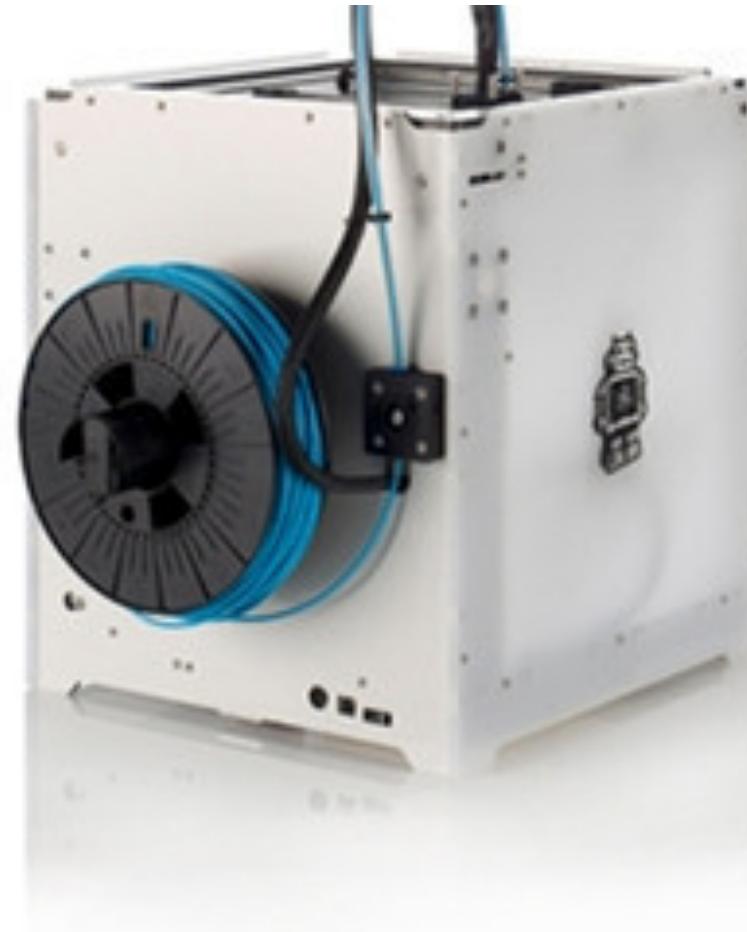
# Waiting for a Card

```
while (true) {  
    cardTerminal.waitForCardPresent(0);  
    handleCard(cardTerminal);  
    cardTerminal.waitForCardAbsent(0);  
}
```

## Read Data

```
card = cardTerminal.connect("*");
CardChannel channel = card.getBasicChannel();
CommandAPDU command = new CommandAPDU(getAddress());
ResponseAPDU response = channel.transmit(command);
byte[] uidBytes = response.getData();
```

# Ultimaker 2



**ultimaker<sup>2</sup>**

ultimaker

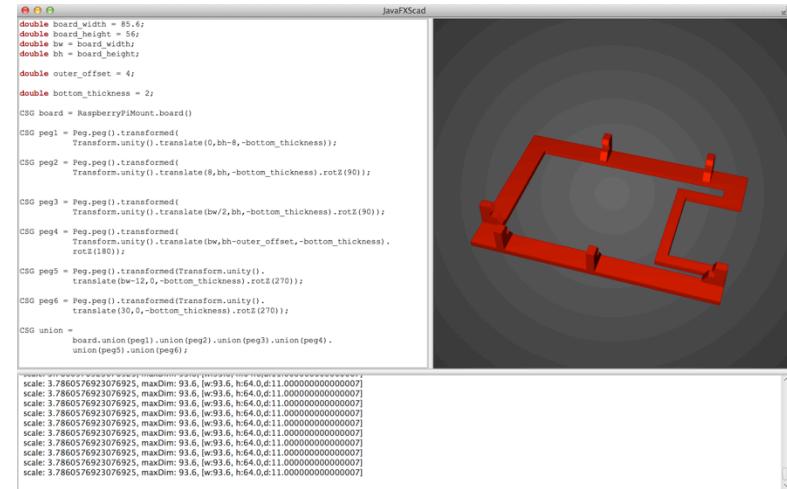


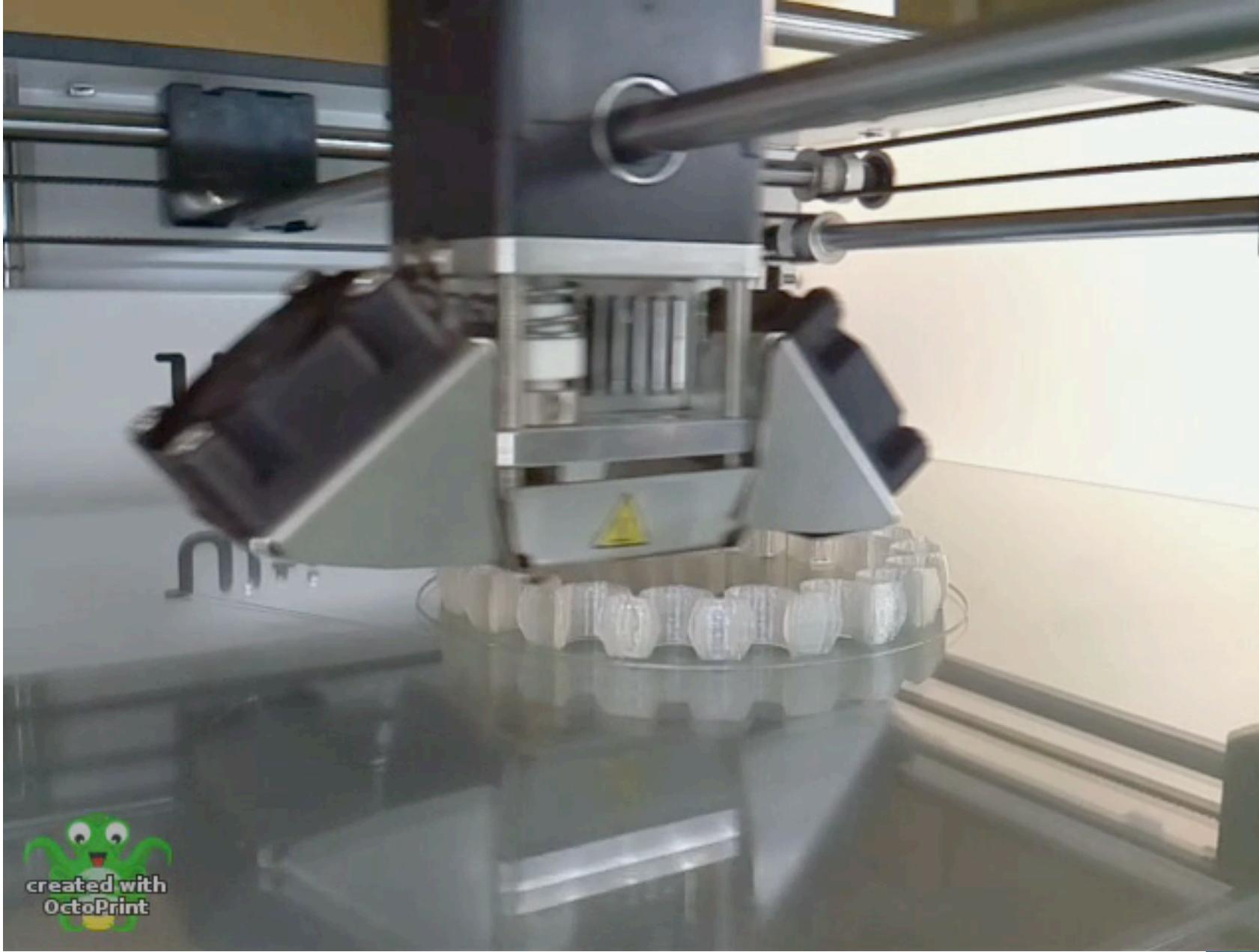
# Java Constructive Geometry (JCSG / JFXScad)

- Create geometries from pure Java code
- Visualize with a JavaFX user interface
- Generate STL files for 3D printing
- Project sites:

<https://github.com/miho/JCSG>

<https://github.com/miho/JFXScad>





# New Book Announcement

- Raspberry Pi with Java



Stephen Chin

tweet: @steveonjava

blog: <http://steveonjava.com>

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