Write a Python Program to Solve N-Queen Problem without using Recursion.

```
def is safe(board, row, col, N):
    # Check if there is a queen in the same column
    for i in range(row):
        if board[i][col] == 1:
            return False
    # Check if there is a queen in the left diagonal
    for i, j in zip(range(row, -1, -1), range(col, -1, -1)):
        if board[i][j] == 1:
            return False
    # Check if there is a queen in the right diagonal
    for i, j in zip(range(row, -1, -1), range(col, N)):
        if board[i][j] == 1:
            return False
    return True
def print solution (board, N):
    for i in range(N):
        for j in range(N):
            print(board[i][j], end=" ")
        print()
def solve n queens(N):
    board = [[0 for in range(N)] for in range(N)]
    stack = []
    row, col = 0, 0
    while row < N:
        while col < N:
            if is safe(board, row, col, N):
                board[row][col] = 1
                stack.append(col)
                break
            col += 1
        if col == N:
            if not stack:
                break
            col = stack.pop()
```

Write a Python Program to implement the Backtracking approach to solve N Queen's problem

```
def print solution (board):
    for row in board:
        print(" ".join(row))
def is safe(board, row, col, N):
    # Check if there is a queen in the same column
    for i in range(row):
        if board[i][col] == 'O':
            return False
    # Check upper left diagonal
    for i, j in zip(range(row, -1, -1), range(col, -1, -1)):
        if board[i][j] == 'Q':
            return False
    # Check upper right diagonal
    for i, j in zip(range(row, -1, -1), range(col, N)):
        if board[i][j] == 'Q':
            return False
    return True
def solve n queens util (board, row, N):
    if row == N:
        # All queens are placed successfully, print the
solution
        print solution(board)
        print()
        return
    for col in range(N):
        if is safe(board, row, col, N):
            # Place the queen
            board[row][col] = 'Q'
            # Recur to place queens in the remaining rows
            solve n queens util(board, row + 1, N)
            # Backtrack: remove the queen from the current
            # position
```

```
board[row][col] = '.'

def solve_n_queens(N):
    # Initialize an empty chessboard
    board = [['.' for _ in range(N)] for _ in range(N)]
    solve_n_queens_util(board, 0, N)

# Example usage for N = 4
    solve_n_queens(4)
```

- . Q . .
- . . . Q
- Q . . .
- . . Q .
- . . Q .
- Q . . .
- . . . Q
- . Q . .

Write a Python Program to implement Min-Max Algorithm

```
import math
  def fun minmax(cd, node, maxt, scr, td):
      if cd==td:
          return scr[node]
      if (maxt):
          return
  max(fun minmax(cd+1,node*2,False,scr,td),fun minmax(cd+1,nod
  e*2+1, False, scr, td))
      else:
          return
  min(fun minmax(cd+1,node*2,True,scr,td),fun minmax(cd+1,node
  *2+1, True, scr, td))
  scr=[]
  x=int(input("enter the total no. of leaf node"))
  for i in range(x):
      y=int(input("enter the leaf value"))
      scr.append(y)
  td=math.log(len(scr),2)
  cd=int(input("enter the current depth value"))
  nodev=int(input("enter the node value"))
  maxt=True
  print("The answer is")
  answer=fun minmax(cd,nodev,maxt,scr,td)
  print(answer)
OUTPUT
  Enter the total no. of leaf node 8
  enter the leaf value 1
  enter the leaf value 2
  enter the leaf value 3
  enter the leaf value 4
  enter the leaf value 5
  enter the leaf value 6
  enter the leaf value 7
  enter the leaf value 8
  enter the current depth value 0
  enter the node value 0
  The answer is 6
```

Write a Python Program to implement Alpha-Beta Pruning Algorithm

```
maximum, minimum=1000, -1000
def fun alphabeta (d, node, maxt, v, A, B):
    if d==3:
       return v[node]
    if maxt:
        best=minimum
        for i in range (0,2):
             value=fun alphabeta(d+1, node*2+i, False, v, A, B)
            best=max(best, value)
            A=max(A, best)
            if B<=A:
                 break
        return best
    else:
        best=maximum
        for i in range (0,2):
            value=fun alphabeta(d+1, node*2+i, True, v, A, B)
            best=min(best, value)
            A=min(A,best)
            if B<=A:
                 break
        return best
scr=[]
x=int(input("enter the total no. of leaf node"))
for i in range(x):
    y=int(input("enter the leaf value"))
    scr.append(y)
d=int(input("enter the depth value"))
node=int(input("enter the node value"))
answer=fun alphabeta(d, node, True, scr, minimum, maximum)
print(answer)
```

```
enter the total no. of leaf node8 enter the leaf value1 enter the leaf value2 enter the leaf value3 enter the leaf value4 enter the leaf value5 enter the leaf value6 enter the leaf value7 enter the leaf value8 enter the depth value0 enter the node value0
```

Write a Python Program to implement Breadth First Search

```
from collections import deque
class Graph:
    def init (self):
        self.graph = {}
    def add edge(self, start, end):
        if start not in self.graph:
            self.graph[start] = []
        self.graph[start].append(end)
    def bfs(self, start):
        visited = set()
        queue = deque([start])
        while queue:
            current node = queue.popleft()
            if current node not in visited:
                print("Visiting node:", current node)
                visited.add(current node)
                neighbors = self.graph.get(current node, [])
                queue.extend(neighbor for neighbor in
neighbors if neighbor not in visited)
# Example usage:
graph = Graph()
graph.add edge('A', 'B')
graph.add_edge('A', 'C')
graph.add edge('B', 'D')
graph.add edge('C', 'E')
graph.add edge('D', 'E')
start node = 'A'
print(f"Breadth-First Search from {start node}:")
graph.bfs(start node)
```

OUTPUT Breadth-First Search from A: Visiting node: A Visiting node: B Visiting node: C Visiting node: D Visiting node: E

Write a Python Program to implement Depth First Search

SOURCE CODE

```
graph={
    'A':['B','C'],
    'B':['D','E'],
    'C':['F'],
    'D':[],
    'E':['F'],
    'F':[]
visited=set()  #set to keep track of visited nodes
def dfs(visited, graph, node):
                               #function for dfs
    if node not in visited:
        print(node)
        visited.add(node)
        for neighbour in graph[node]:
            #print("neighbour", neighbour)
            dfs(visited, graph, neighbour)
#driver code
print("The following is the depth first search")
                                     #function calling
dfs(visited, graph, 'A')
```

OUTPUT

```
The following is the depth first search A
B
D
E
F
C
```

Write a Python Program to implement Iterative Deepening Depth First search (IDDFS)

```
graph={
      'A':['B','C'],
      'B':['D','E'],
      'C':['G'],
       'D':[],
       'E':['F'],
       'F':[],
       'G':[]
  }
  def DFS(currentnode, destination, graph, maxdepth):
      print("checking for destination", currentnode)
      if currentnode==destination:
           return True
      if maxdepth<=0:
            return False
      for node in graph[currentnode]:
           if DFS (node, destination, graph, maxdepth-1):
               return True
      return False
  def iterativeDDFS(currentnode, destination, graph, maxdepth):
      for i in range (maxdepth):
           if DFS (currentnode, destination, graph, i):
               return True
      return False
  if not iterativeDDFS('A', 'E', graph, 4):
      print("path is not avilable")
  else:
      print("path exist")
OUTPUT
  checking for destination A
  checking for destination A
  checking for destination B
  checking for destination C
  checking for destination A
  checking for destination B
  checking for destination D
  checking for destination E
  path exist
```

Write a Python Program to implement Best First Search

```
from queue import PriorityQueue
class Graph:
   def init__(self):
        self.graph = {}
    def add edge(self, start, end, cost):
        if start not in self.graph:
            self.graph[start] = []
        self.graph[start].append((end, cost))
    def best first search(self, start, goal):
        visited = set()
        priority queue = PriorityQueue()
        priority queue.put((0, start))
        while not priority queue.empty():
            current cost, current node =
                 priority queue.get()
            if current node in visited:
                continue
            print("Visiting node:", current node)
            visited.add(current node)
            if current node == goal:
                print("Goal reached!")
                break
            neighbors = self.graph.get(current node, [])
            for neighbor, cost in neighbors:
                if neighbor not in visited:
                    priority queue.put((cost, neighbor))
# Example usage:
graph = Graph()
graph.add edge('A', 'B', 5)
graph.add_edge('A', 'C', 10)
graph.add edge('B', 'D', 3)
```

```
graph.add_edge('C', 'E', 7)

graph.add_edge('D', 'E', 2)

start_node = 'A'
goal_node = 'E'

print(f"Best-First Search from {start_node} to {goal_node}:")
graph.best_first_search(start_node, goal_node)
```

Best-First Search from A to E: Visiting node: A Visiting node: B Visiting node: D

Write a Python Program to implement A* Algorithm

```
import heapq
```

```
class Node:
    def init (self, row, col, cost, parent=None):
        self.row = row
        self.col = col
        self.cost = cost
        self.parent = parent
    def lt (self, other):
        return self.cost < other.cost
def heuristic (node, goal):
    # Example: Manhattan distance heuristic
    return abs(node.row - goal.row) + abs(node.col -
goal.col)
def astar(grid, start, goal):
    rows, cols = len(grid), len(grid[0])
    visited = set()
   pq = []
   heapq.heappush(pq, start)
   while pq:
        current = heapq.heappop(pq)
        if (current.row, current.col) == (goal.row,
goal.col):
            path = []
            while current:
                path.append((current.row, current.col))
                current = current.parent
            return path[::-1]
        visited.add((current.row, current.col))
        neighbors = [
            (current.row - 1, current.col),
            (current.row + 1, current.col),
            (current.row, current.col - 1),
            (current.row, current.col + 1)
```

```
for neighbor row, neighbor col in neighbors:
                if 0 \le \text{neighbor row} \le \text{rows and } 0 \le \text{neighbor row}
  neighbor col < cols and grid[neighbor row][neighbor col] ==</pre>
  0 and (neighbor row, neighbor col) not in visited:
                    neighbor = Node(neighbor row, neighbor col,
  current.cost + 1, current)
                    neighbor cost = neighbor.cost +
  heuristic (neighbor, goal)
                    heapq.heappush(pq, neighbor)
       return None
  # Example usage
  grid = [
       [0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
       [0, 1, 0, 1, 0],
       [0, 0, 0, 0, 0],
  1
  start = Node(0, 0, 0)
  goal = Node(3, 4, 0)
  path = astar(grid, start, goal)
  print("A* Path:", path)
OUTPUT
  A^* Path: [(0, 0), (1, 0), (2, 0), (3, 0), (3, 1), (3, 2),
  (3, 3), (3, 4)
```

Write a Python Program to implement AO* Algorithm

```
import heapq
class Node:
    def init (self, row, col, cost, parent=None):
        self.row = row
        self.col = col
        self.cost = cost
        self.parent = parent
    def lt (self, other):
        return self.cost < other.cost
def heuristic(node, goal):
    # Example: Manhattan distance heuristic
    return abs(node.row - goal.row) + abs(node.col -
goal.col)
def a star(grid, start, goal):
    rows, cols = len(grid), len(grid[0])
    visited = set()
    [] = pq
   heapq.heappush(pq, start)
   while pq:
        current = heapq.heappop(pq)
        if (current.row, current.col) == (goal.row,
goal.col):
            path = []
            while current:
                path.append((current.row, current.col))
                current = current.parent
            return path[::-1]
        visited.add((current.row, current.col))
        neighbors = [
            (current.row - 1, current.col),
            (current.row + 1, current.col),
            (current.row, current.col - 1),
            (current.row, current.col + 1)
```

```
for neighbor row, neighbor col in neighbors:
            if 0 <= neighbor row < rows and 0 <=
neighbor col < cols and grid[neighbor row][neighbor col] ==</pre>
0 and (neighbor row, neighbor col) not in visited:
                neighbor = Node(neighbor row, neighbor col,
current.cost + 1, current)
                neighbor cost = neighbor.cost +
heuristic (neighbor, goal)
                heapq.heappush(pq, neighbor)
    return None
def ao star(grid, start, goal, epsilon):
    best path = a star(grid, start, goal)
    while True:
        cost bound = best path[-1][0] + epsilon if best path
else float('inf')
        suboptimal path = a star with bound(grid, start,
goal, cost bound)
        if not suboptimal path or suboptimal path[-1][0] >=
cost bound:
            break
        best path = suboptimal path
    return best path
def a star with bound(grid, start, goal, cost bound):
    rows, cols = len(grid), len(grid[0])
    visited = set()
    pq = []
    heapq.heappush(pq, start)
   while pq:
        current = heapq.heappop(pq)
        if (current.row, current.col) == (goal.row,
goal.col):
            path = []
            while current:
                path.append((current.row, current.col))
                current = current.parent
            return path[::-1]
        visited.add((current.row, current.col))
        neighbors = [
            (current.row - 1, current.col),
```

```
(current.row + 1, current.col),
                (current.row, current.col - 1),
                (current.row, current.col + 1)
           1
           for neighbor row, neighbor col in neighbors:
               if 0 \le \text{neighbor row} \le \text{rows and } 0 \le \text{neighbor row}
  neighbor col < cols and grid[neighbor row][neighbor col] ==</pre>
  0 and (neighbor row, neighbor col) not in visited:
                    neighbor = Node(neighbor row, neighbor col,
  current.cost + 1, current)
                    neighbor cost = neighbor.cost +
  heuristic(neighbor, goal)
                    if neighbor cost < cost bound:</pre>
                        heapq.heappush(pq, neighbor)
      return None
  # Example usage
  grid = [
       [0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
      [0, 1, 0, 1, 0],
      [0, 0, 0, 0, 0],
  1
  start = Node(0, 0, 0)
  goal = Node(3, 4, 0)
  epsilon = 2
  result = ao star(grid, start, goal, epsilon)
  print("AO* Path:", result)
OUTPUT
  AO* Path: [(0, 0), (1, 0), (2, 0), (3, 0), (3, 1), (3, 2),
  (3, 3), (3, 4)
```

Write a Python Program to implement K-Nearest Neighbor Algorithm for data classification, choose dataset of your own choice

SOURCE CODE

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy score
# Load the Iris dataset
iris = datasets.load iris()
X = iris.data
y = iris.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
\# Initialize the K-Nearest Neighbors classifier with k=3
knn classifier = KNeighborsClassifier(n neighbors=3)
# Train the classifier
knn classifier.fit(X train, y train)
# Make predictions on the test set
y pred = knn classifier.predict(X_test)
# Calculate accuracy
accuracy = accuracy score(y test, y pred)
print("Accuracy:", accuracy)
# Example: Make a prediction for a new data point
new data point = [[5.0, 3.5, 1.5, 0.2]]
prediction = knn classifier.predict(new data point)
print ("Prediction for the new data point:",
iris.target names[prediction[0]])
```

OUTPUT

```
Accuracy: 1.0 Prediction for the new data point: setosa
```

Write a Python Program to implement Naïve Bayes Algorithm for data classification, choose dataset of your own choice

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.naive bayes import GaussianNB
from sklearn.metrics import accuracy score,
classification report
# Load the Iris dataset
iris = datasets.load iris()
X = iris.data
y = iris.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Naive Bayes classifier
naive bayes classifier = GaussianNB()
# Train the classifier
naive bayes classifier.fit(X train, y train)
# Make predictions on the test set
y pred = naive bayes classifier.predict(X test)
# Calculate accuracy
accuracy = accuracy score(y test, y pred)
print("Accuracy:", accuracy)
# Display classification report
print("Classification Report:\n",
classification report(y test, y pred))
# Example: Make a prediction for a new data point
new data point = [[5.0, 3.5, 1.5, 0.2]]
prediction = naive bayes classifier.predict(new data point)
print ("Prediction for the new data point:",
iris.target names[prediction[0]])
```

Accuracy: 1.0

Classification Report:

	precision	recall	f1-score	support
0	1.00	1.00	1.00	10
1	1.00	1.00	1.00	9
2	1.00	1.00	1.00	11
accuracy			1.00	30
macro avg	1.00	1.00	1.00	30
weighted avg	1.00	1.00	1.00	30

Prediction for the new data point: setosa

Write a Python Program to implement Decision Trees for data classification, choose data set of your own choice

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.tree import DecisionTreeClassifier
from sklearn.metrics import accuracy score,
classification report
from sklearn.tree import export text
# Load the Iris dataset
iris = datasets.load iris()
X = iris.data
y = iris.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Decision Tree classifier
decision tree classifier =
DecisionTreeClassifier(random state=42)
# Train the classifier
decision tree classifier.fit(X train, y train)
# Make predictions on the test set
y pred = decision tree classifier.predict(X test)
# Calculate accuracy
accuracy = accuracy score(y_test, y_pred)
print("Accuracy:", accuracy)
# Display classification report
print("Classification Report:\n",
classification report(y test, y pred))
# Display the Decision Tree rules
tree rules = export text(decision tree classifier,
feature names=iris.feature names)
print("Decision Tree Rules:\n", tree rules)
# Example: Make a prediction for a new data point
new data point = [[5.0, 3.5, 1.5, 0.2]]
```

```
prediction =
  decision tree classifier.predict(new data point)
  print ("Prediction for the new data point:",
  iris.target names[prediction[0]])
OUTPUT
  Accuracy: 1.0
  Classification Report:
                  precision recall f1-score
                                                    support
                                 1.00
              0
                      1.00
                                           1.00
                                                        10
              1
                      1.00
                                 1.00
                                           1.00
                                                         9
                      1.00
                                 1.00
                                           1.00
                                                        11
                                                        30
                                           1.00
      accuracy
                                           1.00
                                                        30
     macro avg
                      1.00
                                 1.00
                     1.00
                                 1.00
                                           1.00
                                                        30
  weighted avg
  Decision Tree Rules:
   |--- petal length (cm) <= 2.45
     |--- class: 0
  |--- petal length (cm) > 2.45
       \mid --- \text{ petal length (cm)} \mid <= 4.75
          \mid ---  petal width (cm) \leq 1.65
           | |--- class: 1
           |--- petal width (cm) > 1.65
              |--- class: 2
       --- petal length (cm) > 4.75
           |--- petal width (cm) \leq 1.75
               \mid --- \text{ petal length (cm)} \mid <= 4.95
              | |--- class: 1
               |--- petal length (cm) > 4.95
                   |--- petal width (cm) <= 1.55
                   | |--- class: 2
                   \mid --- \text{ petal width (cm)} > 1.55
                      |--- petal length (cm) \leq 5.45
                       | |--- class: 1
                      |--- petal length (cm) > 5.45
                      | |--- class: 2
             -- petal width (cm) > 1.75
               |--- petal length (cm) \leq 4.85
                   \mid --- \text{ sepal width (cm)} \mid <= 3.10
                  | |--- class: 2
                   |--- sepal width (cm) > 3.10
                  | |--- class: 1
               |--- petal length (cm) > 4.85
                   |--- class: 2
  Prediction for the new data point: setosa
```

Write a Python Program to implement Logistic Regression for data classification, choose dataset of your own choice

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.linear model import LogisticRegression
from sklearn.metrics import accuracy score,
classification report
# Load the Breast Cancer Wisconsin dataset
breast cancer = datasets.load breast cancer()
X = breast cancer.data
y = breast cancer.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Logistic Regression classifier
logistic regression classifier =
LogisticRegression(random state=42)
# Train the classifier
logistic regression classifier.fit(X train, y train)
# Make predictions on the test set
y pred = logistic regression classifier.predict(X test)
# Calculate accuracy
accuracy = accuracy score(y test, y pred)
print("Accuracy:", accuracy)
# Display classification report
print("Classification Report:\n",
classification report(y test, y pred))
# Example: Make a prediction for a new data point
new data point = [X test[0]] # Using the first data point
from the test set as an example
prediction =
logistic regression classifier.predict(new data point)
print ("Prediction for the new data point:", "Malignant" if
prediction[0] == 1 else "Benign")
```

```
Accuracy: 0.956140350877193
Classification Report:
              precision recall f1-score support
          0
                  0.97
                         0.91
                                     0.94
                                                 43
                  0.95
                           0.99
                                     0.97
                                                 71
          1
                                     0.96
                                                114
   accuracy
                 0.96
                         0.95
                                    0.95
                                                114
  macro avg
                0.96
                           0.96 0.96
                                                114
weighted avg
Prediction for the new data point: Malignant
/usr/local/lib/python3.8/dist-
packages/sklearn/linear model/ logistic.py:460:
ConvergenceWarning: lbfgs failed to converge (status=1):
STOP: TOTAL NO. of ITERATIONS REACHED LIMIT.
Increase the number of iterations (max iter) or scale the
data as shown in:
   https://scikit-
learn.org/stable/modules/preprocessing.html
Please also refer to the documentation for alternative
solver options:
   https://scikit-
learn.org/stable/modules/linear model.html#logistic-
regression
```

n iter i = check optimize result(

Write a Python Program to implement Support Vector Machines for data classification, choose dataset of your own choice

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.svm import SVC
from sklearn.metrics import accuracy score,
classification report
# Load the Iris dataset
iris = datasets.load iris()
X = iris.data
y = iris.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Support Vector Machines classifier
svm classifier = SVC(kernel='linear', C=1.0,
random state=42)
# Train the classifier
svm classifier.fit(X train, y train)
# Make predictions on the test set
y pred = svm classifier.predict(X test)
# Calculate accuracy
accuracy = accuracy_score(y_test, y_pred)
print("Accuracy:", accuracy)
# Display classification report
print("Classification Report:\n",
classification report(y test, y pred))
# Example: Make a prediction for a new data point
new data point = [[5.0, 3.5, 1.5, 0.2]]
prediction = svm classifier.predict(new data point)
print ("Prediction for the new data point:",
iris.target names[prediction[0]])
```

Accuracy: 1.0 Classification Report:

014001110401011	precision	recall	f1-score	support
0	1.00	1.00	1.00	10
1	1.00	1.00	1.00	9
2	1.00	1.00	1.00	11
accuracy			1.00	30
macro avg	1.00	1.00	1.00	30
weighted avg	1.00	1.00	1.00	30

Prediction for the new data point: setosa

Write a Python Program to implement Linear regression on a dataset of your own choice

```
from sklearn import datasets
from sklearn.model selection import train test split
from sklearn.linear model import LinearRegression
from sklearn.metrics import mean squared error, r2 score
import numpy as np
# Load the Boston Housing dataset
boston = datasets.load boston()
X = boston.data
y = boston.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Linear Regression model
linear regression model = LinearRegression()
# Train the model
linear regression model.fit(X train, y train)
# Make predictions on the test set
y pred = linear regression model.predict(X test)
# Calculate mean squared error and R^2 score
mse = mean squared error(y test, y pred)
r2 = r2 score(y test, y pred)
print("Mean Squared Error:", mse)
print("R^2 Score:", r2)
# Example: Make a prediction for a new data point
new data point = np.array([0.00632, 18.0, 2.31, 0, 0.538,
6.575, 65.2, 4.09, 1, 296, 15.3, 396.9, 4.98]).reshape(1,
1)
prediction = linear regression model.predict(new data point)
print ("Predicted Price for the new data point:",
prediction[0])
```

Accuracy: 1.0 Classification Report:

1 1.00 1.00 1.00 2 1.00 1.00 1.00 1 accuracy 1.00 3 macro avg 1.00 1.00 1.00 3	Classificación	precision	recall	f1-score	support
2 1.00 1.00 1.00 1 accuracy 1.00 3 macro avg 1.00 1.00 3	0	1.00	1.00	1.00	10
accuracy 1.00 3 macro avg 1.00 1.00 1.00 3	1	1.00	1.00	1.00	9
macro avg 1.00 1.00 1.00 3	2	1.00	1.00	1.00	11
3	accuracy			1.00	30
weighted avg 1.00 1.00 1.00 3	macro avg	1.00	1.00	1.00	30
	weighted avg	1.00	1.00	1.00	30

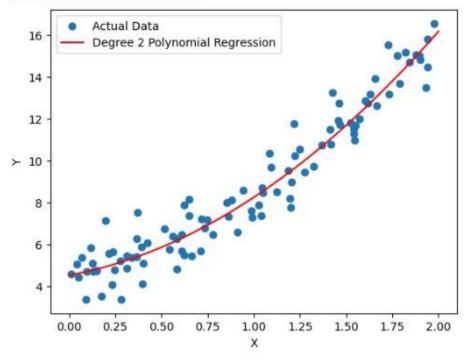
Prediction for the new data point: setosa

Write a Python Program to implement Polynomial Regression on a dataset of your own choice

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.model selection import train test split
from sklearn.preprocessing import PolynomialFeatures
from sklearn.linear model import LinearRegression
from sklearn.metrics import mean squared error, r2 score
# Generate a hypothetical dataset
np.random.seed(42)
X = 2 * np.random.rand(100, 1)
y = 4 + 3 * X + 1.5 * X**2 + np.random.randn(100, 1)
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Apply Polynomial Regression
degree = 2 # Degree of the polynomial
poly features = PolynomialFeatures (degree=degree,
include bias=False)
X train poly = poly features.fit transform(X train)
# Initialize and train the Polynomial Regression model
poly_regression_model = LinearRegression()
poly regression model.fit(X train poly, y train)
# Make predictions on the test set
X test poly = poly_features.transform(X_test)
y pred = poly regression model.predict(X test poly)
# Calculate mean squared error and R^2 score
mse = mean squared error(y test, y pred)
r2 = r2 score(y test, y pred)
print("Mean Squared Error:", mse)
print("R^2 Score:", r2)
# Plot the results
plt.scatter(X, y, label='Actual Data')
x plot = np.linspace(0, 2, 100).reshape(-1, 1)
```

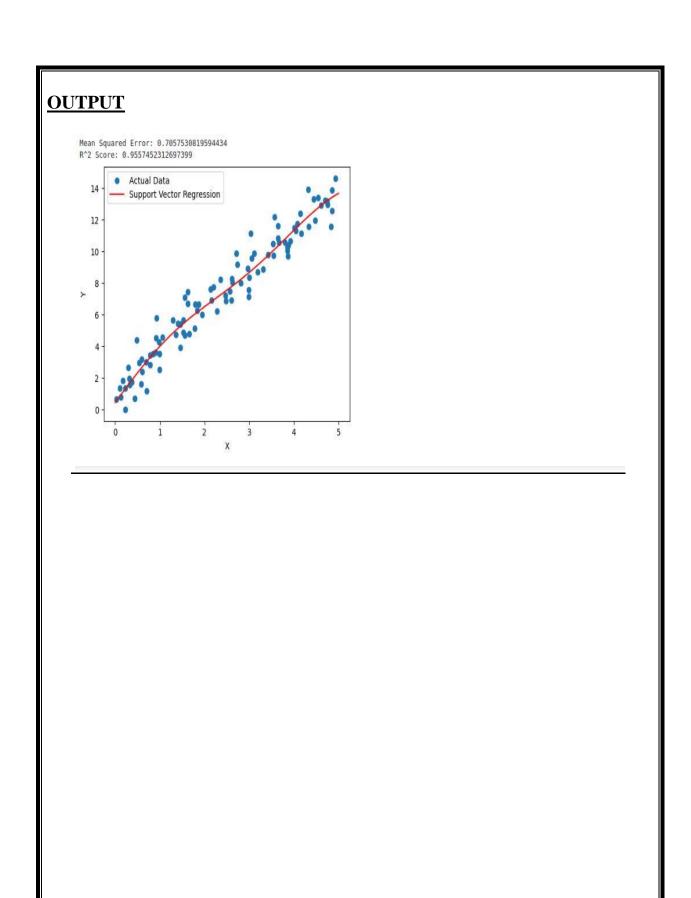
```
x_plot_poly = poly_features.transform(x_plot)
y_plot = poly_regression_model.predict(x_plot_poly)
plt.plot(x_plot, y_plot, color='red', label=f'Degree
{degree} Polynomial Regression')
plt.xlabel('X')
plt.ylabel('Y')
plt.legend()
plt.show()
```

Mean Squared Error: 0.6358406072820804 R^2 Score: 0.9511063423293336



Write a Python Program to implement Support Vector Regression on a dataset of your own choice

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.model selection import train test split
from sklearn.svm import SVR
from sklearn.metrics import mean squared error, r2 score
# Generate a hypothetical dataset
np.random.seed(42)
X = 5 * np.random.rand(100, 1)
y = 3 * X + np.sin(X) + np.random.randn(100, 1)
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Initialize the Support Vector Regression model
svr model = SVR(kernel='rbf', C=100, gamma=0.1, epsilon=0.1)
# Train the model
svr model.fit(X train, y train.ravel())
# Make predictions on the test set
y pred = svr model.predict(X test)
# Calculate mean squared error and R^2 score
mse = mean squared error(y test, y pred)
r2 = r2 score(y test, y_pred)
print("Mean Squared Error:", mse)
print("R^2 Score:", r2)
# Plot the results
plt.scatter(X, y, label='Actual Data')
x plot = np.linspace(0, 5, 100).reshape(-1, 1)
y plot = svr model.predict(x plot)
plt.plot(x plot, y plot, color='red', label='Support Vector
Regression')
plt.xlabel('X')
plt.ylabel('Y')
plt.legend()
plt.show()
```



Write a Python Program to implement Artificial Neural Network for data classification, choose dataset of your own choice

```
import numpy as np
import tensorflow as tf
from sklearn.datasets import load breast cancer
from sklearn.model selection import train test split
from sklearn.preprocessing import StandardScaler
from sklearn.metrics import accuracy score
# Load the breast cancer dataset
cancer = load breast cancer()
X = cancer.data
y = cancer.target
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Standardize the feature values
scaler = StandardScaler()
X train = scaler.fit transform(X train)
X test = scaler.transform(X test)
# Build the ANN model
model = tf.keras.Sequential([
    tf.keras.layers.Dense(32, activation='relu',
input shape=(X train.shape[1],)),
    tf.keras.layers.Dense(16, activation='relu'),
    tf.keras.layers.Dense(1, activation='sigmoid')
1)
model.compile(optimizer='adam', loss='binary crossentropy',
metrics=['accuracy'])
# Train the model
model.fit(X train, y train, epochs=50, batch size=32,
verbose=1)
# Evaluate the model on the test set
y pred prob = model.predict(X test)
y pred = np.round(y pred prob).flatten()
```

```
accuracy = accuracy score(y test, y pred)
 print("Accuracy:", accuracy)
 # Example: Make a prediction for a new data point
 new data point = np.array(X test[0]).reshape(1, -1)
 prediction prob = model.predict(new data point)
 prediction = np.round(prediction prob).flatten()[0]
 print("Prediction for the new data point:", prediction)
OUTPUT
 Epoch 1/50
 15/15 [============ ] - 1s 7ms/step - loss:
 0.7394 - accuracy: 0.4374
 Epoch 2/50
 0.4940 - accuracy: 0.7604
 Epoch 3/50
 0.3444 - accuracy: 0.9275
 Epoch 4/50
 15/15 [============ ] - Os 2ms/step - loss:
 0.2470 - accuracy: 0.9516
 Epoch 5/50
 0.1878 - accuracy: 0.9582
 Epoch 6/50
 0.1517 - accuracy: 0.9648
 Epoch 7/50
 15/15 [============= ] - Os 4ms/step - loss:
 0.1302 - accuracy: 0.9670
 Epoch 8/50
 15/15 [============ ] - Os 4ms/step - loss:
 0.1144 - accuracy: 0.9714
 Epoch 9/50
 15/15 [============= ] - Os 3ms/step - loss:
 0.1033 - accuracy: 0.9714
 Epoch 10/50
 0.0938 - accuracy: 0.9736
 Epoch 11/50
 0.0857 - accuracy: 0.9736
 Epoch 12/50
```

```
0.0794 - accuracy: 0.9780
Epoch 13/50
0.0744 - accuracy: 0.9802
Epoch 14/50
0.0701 - accuracy: 0.9890
Epoch 15/50
0.0660 - accuracy: 0.9868
Epoch 16/50
15/15 [============ ] - Os 3ms/step - loss:
0.0625 - accuracy: 0.9868
Epoch 17/50
0.0596 - accuracy: 0.9868
Epoch 18/50
0.0571 - accuracy: 0.9868
Epoch 19/50
15/15 [============= ] - Os 2ms/step - loss:
0.0549 - accuracy: 0.9890
Epoch 20/50
0.0525 - accuracy: 0.9890
Epoch 21/50
15/15 [============ ] - Os 2ms/step - loss:
0.0507 - accuracy: 0.9890
Epoch 22/50
0.0487 - accuracy: 0.9890
Epoch 23/50
15/15 [============= ] - Os 2ms/step - loss:
0.0473 - accuracy: 0.9890
Epoch 24/50
0.0453 - accuracy: 0.9890
Epoch 25/50
0.0440 - accuracy: 0.9890
Epoch 26/50
15/15 [============ ] - Os 3ms/step - loss:
0.0424 - accuracy: 0.9912
Epoch 27/50
0.0411 - accuracy: 0.9912
```

```
Epoch 28/50
0.0394 - accuracy: 0.9912
Epoch 29/50
0.0388 - accuracy: 0.9912
Epoch 30/50
0.0369 - accuracy: 0.9934
Epoch 31/50
0.0355 - accuracy: 0.9934
Epoch 32/50
15/15 [============ ] - Os 2ms/step - loss:
0.0347 - accuracy: 0.9934
Epoch 33/50
0.0330 - accuracy: 0.9934
Epoch 34/50
0.0321 - accuracy: 0.9934
Epoch 35/50
15/15 [============= ] - Os 3ms/step - loss:
0.0306 - accuracy: 0.9934
Epoch 36/50
0.0296 - accuracy: 0.9934
Epoch 37/50
15/15 [============= ] - Os 2ms/step - loss:
0.0286 - accuracy: 0.9934
Epoch 38/50
0.0275 - accuracy: 0.9934
Epoch 39/50
15/15 [============ ] - Os 3ms/step - loss:
0.0267 - accuracy: 0.9934
Epoch 40/50
0.0256 - accuracy: 0.9934
Epoch 41/50
0.0248 - accuracy: 0.9934
Epoch 42/50
15/15 [============ ] - Os 2ms/step - loss:
0.0243 - accuracy: 0.9934
Epoch 43/50
0.0234 - accuracy: 0.9934
```

```
Epoch 44/50
0.0224 - accuracy: 0.9934
Epoch 45/50
0.0215 - accuracy: 0.9934
Epoch 46/50
15/15 [============ ] - Os 3ms/step - loss:
0.0209 - accuracy: 0.9934
Epoch 47/50
0.0202 - accuracy: 0.9934
Epoch 48/50
0.0197 - accuracy: 0.9934
Epoch 49/50
0.0188 - accuracy: 0.9956
Epoch 50/50
0.0181 - accuracy: 0.9956
4/4 [========] - 0s 1ms/step
Accuracy: 0.9824561403508771
1/1 [======] - Os 12ms/step
Prediction for the new data point: 1.0
```

Write a Python Program to implement Feed Forward Neural Network on a given dataset for data classification, choose dataset of your own choice

```
import numpy as np
import tensorflow as tf
from sklearn.model selection import train test split
from sklearn.preprocessing import StandardScaler
from sklearn.datasets import make classification
from sklearn.metrics import accuracy score
# Generate a hypothetical dataset for binary classification
X, y = make classification(n samples=1000, n features=10,
n informative=8, n redundant=2, random state=42)
# Split the dataset into training and testing sets
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Standardize the feature values
scaler = StandardScaler()
X train = scaler.fit transform(X train)
X test = scaler.transform(X test)
# Build the FNN model
model = tf.keras.Sequential([
    tf.keras.layers.Dense(32, activation='relu',
input shape=(X train.shape[1],)),
    tf.keras.layers.Dense(16, activation='relu'),
    tf.keras.layers.Dense(1, activation='sigmoid')
])
model.compile(optimizer='adam', loss='binary crossentropy',
metrics=['accuracy'])
# Train the model
model.fit(X train, y train, epochs=50, batch size=32,
verbose=1)
# Evaluate the model on the test set
y pred prob = model.predict(X test)
y pred = np.round(y pred prob).flatten()
```

```
accuracy = accuracy score(y test, y pred)
 print("Accuracy:", accuracy)
 # Example: Make a prediction for a new data point
 new data point = np.random.rand(1, X train.shape[1]) #
 Replace this with your new data point
 prediction prob = model.predict(new data point)
 prediction = np.round(prediction prob).flatten()[0]
 print("Prediction for the new data point:", prediction)
OUTPUT
 Epoch 1/50
 25/25 [============= ] - Os 951us/step -
 loss: 0.6983 - accuracy: 0.5800
 Epoch 2/50
 0.6119 - accuracy: 0.6737
 Epoch 3/50
 0.5614 - accuracy: 0.7475
 Epoch 4/50
 25/25 [============= ] - Os 1ms/step - loss:
 0.5192 - accuracy: 0.7862
 Epoch 5/50
 25/25 [============ ] - Os 3ms/step - loss:
 0.4826 - accuracy: 0.8025
 Epoch 6/50
 0.4488 - accuracy: 0.8250
 Epoch 7/50
 0.4164 - accuracy: 0.8438
 Epoch 8/50
 0.3886 - accuracy: 0.8550
 Epoch 9/50
 25/25 [============= ] - Os 2ms/step - loss:
 0.3603 - accuracy: 0.8637
 Epoch 10/50
 0.3360 - accuracy: 0.8800
 Epoch 11/50
 0.3121 - accuracy: 0.8825
```

```
Epoch 12/50
0.2889 - accuracy: 0.8913
Epoch 13/50
0.2698 - accuracy: 0.9013
Epoch 14/50
25/25 [=========== ] - Os 2ms/step - loss:
0.2531 - accuracy: 0.9075
Epoch 15/50
25/25 [============= ] - Os 997us/step -
loss: 0.2397 - accuracy: 0.9175
Epoch 16/50
0.2260 - accuracy: 0.9187
Epoch 17/50
0.2146 - accuracy: 0.9212
Epoch 18/50
0.2052 - accuracy: 0.9262
Epoch 19/50
0.1995 - accuracy: 0.9275
Epoch 20/50
0.1909 - accuracy: 0.9300
Epoch 21/50
25/25 [============= ] - Os 962us/step -
loss: 0.1859 - accuracy: 0.9362
Epoch 22/50
0.1803 - accuracy: 0.9375
Epoch 23/50
25/25 [============= ] - Os 1ms/step - loss:
0.1749 - accuracy: 0.9425
Epoch 24/50
0.1691 - accuracy: 0.9450
Epoch 25/50
0.1656 - accuracy: 0.9450
Epoch 26/50
25/25 [=========== ] - Os 1ms/step - loss:
0.1619 - accuracy: 0.9463
Epoch 27/50
0.1581 - accuracy: 0.9425
```

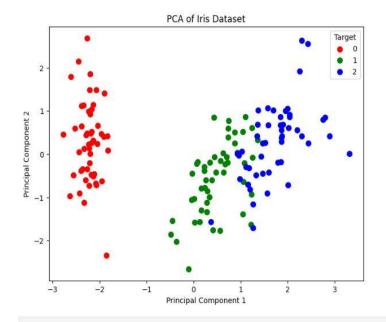
```
Epoch 28/50
0.1546 - accuracy: 0.9475
Epoch 29/50
25/25 [============= ] - Os 3ms/step - loss:
0.1523 - accuracy: 0.9450
Epoch 30/50
25/25 [============ ] - Os 3ms/step - loss:
0.1485 - accuracy: 0.9500
Epoch 31/50
0.1447 - accuracy: 0.9488
Epoch 32/50
25/25 [============= ] - Os 1ms/step - loss:
0.1420 - accuracy: 0.9488
Epoch 33/50
0.1400 - accuracy: 0.9488
Epoch 34/50
0.1369 - accuracy: 0.9488
Epoch 35/50
0.1350 - accuracy: 0.9488
Epoch 36/50
25/25 [========= ] - 0s 1000us/step -
loss: 0.1324 - accuracy: 0.9525
Epoch 37/50
25/25 [=========== ] - Os 2ms/step - loss:
0.1296 - accuracy: 0.9513
Epoch 38/50
0.1284 - accuracy: 0.9538
Epoch 39/50
25/25 [============= ] - Os 1ms/step - loss:
0.1246 - accuracy: 0.9563
Epoch 40/50
0.1229 - accuracy: 0.9563
Epoch 41/50
0.1198 - accuracy: 0.9575
Epoch 42/50
25/25 [============= ] - Os 949us/step -
loss: 0.1192 - accuracy: 0.9588
Epoch 43/50
0.1168 - accuracy: 0.9575
```

```
Epoch 44/50
0.1151 - accuracy: 0.9600
Epoch 45/50
0.1121 - accuracy: 0.9625
Epoch 46/50
25/25 [=========== ] - Os 3ms/step - loss:
0.1091 - accuracy: 0.9650
Epoch 47/50
0.1081 - accuracy: 0.9650
Epoch 48/50
25/25 [============= ] - Os 2ms/step - loss:
0.1065 - accuracy: 0.9638
Epoch 49/50
25/25 [=========== ] - Os 3ms/step - loss:
0.1044 - accuracy: 0.9663
Epoch 50/50
0.1028 - accuracy: 0.9688
7/7 [======== ] - Os 916us/step
Accuracy: 0.905
1/1 [=======] - Os 20ms/step
Prediction for the new data point: 0.0
```

Write a Python Program to implement Principal Component Analysis on a dataset of your own choice

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.decomposition import PCA
from sklearn.preprocessing import StandardScaler
# Load the Iris dataset
iris = datasets.load iris()
X = iris.data
y = iris.target
# Standardize the feature values
X standardized = StandardScaler().fit transform(X)
# Apply PCA
pca = PCA(n components=2)
principal components = pca.fit transform(X standardized)
# Create a DataFrame for visualization
df pca = pd.DataFrame(data=principal components,
columns=['Principal Component 1', 'Principal Component 2'])
df pca['Target'] = y
# Visualize the results
plt.figure(figsize=(8, 6))
targets = [0, 1, 2]
colors = ['r', 'q', 'b']
for target, color in zip(targets, colors):
    indices to keep = df pca['Target'] == target
    plt.scatter(df pca.loc[indices to keep, 'Principal
Component 1'],
                df pca.loc[indices to keep, 'Principal
Component 2'],
                c=color, s=50)
plt.title('PCA of Iris Dataset')
plt.xlabel('Principal Component 1')
plt.ylabel('Principal Component 2')
```

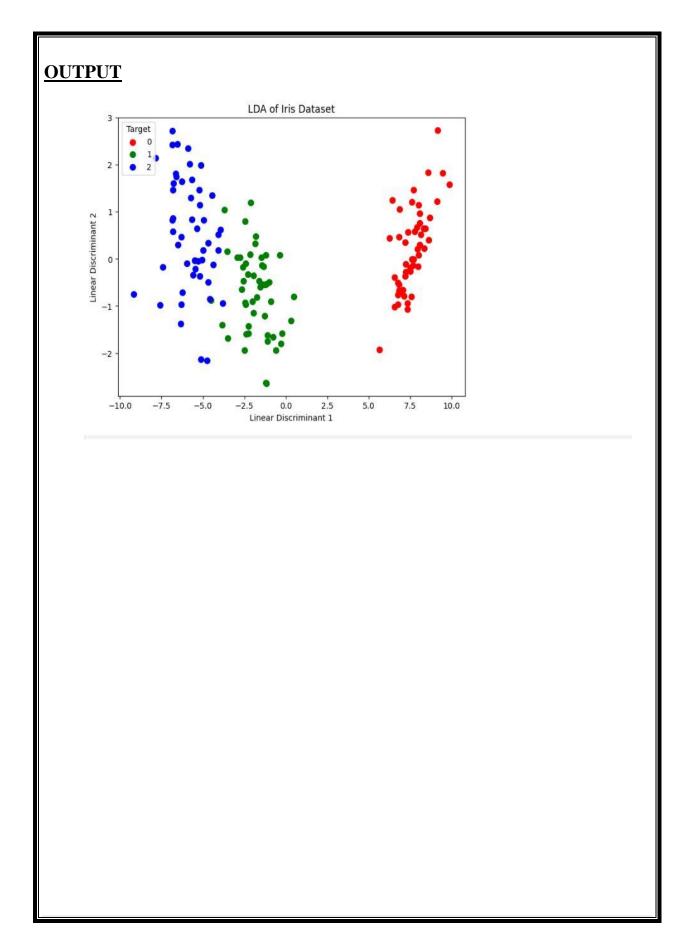
plt.legend(targets, title='Target')
plt.show()



Write a Python Program to implement Linear Discriminant Analysis on a dataset of your own choice

```
class Node:
    def init (self, state, cost, heuristic, parent=None):
        self.state = state
        self.cost = cost
        self.heuristic = heuristic
        self.parent = parent
def ida star search (initial state, heuristic, goal state):
    bound = heuristic(initial state, goal state)
    path = [Node(initial state, 0, bound)]
   while True:
        result, new bound = depth limited search (path,
goal state, heuristic, bound)
        if result == "found":
            return path
        if result == "not found":
            return None
        bound = new bound
def depth limited search (path, goal state, heuristic,
bound):
    node = path[-1]
    cost = node.cost + node.heuristic
    if cost > bound:
        return "not found", cost
    if node.state == goal state:
        return "found", bound
    min bound = float('inf')
    successors = get successors(node, goal state, heuristic)
    for successor in successors:
        if successor.cost + successor.heuristic > bound:
            min bound = min(min bound, successor.cost +
successor.heuristic)
        else:
            path.append(successor)
            result, new bound = depth limited search (path,
goal state, heuristic, bound)
```

```
if result == "found":
                return "found", bound
            min bound = min(min bound, new bound)
            path.pop()
    return "not found", min bound
def get successors (node, goal state, heuristic):
    # Example: Generating successors for a simple 8-puzzle
problem
    successors = []
    state = node.state
    # Code for generating successors based on the specific
problem
    # ...
   return successors
# Example usage
def eight puzzle heuristic(state, goal state):
    # Example: Manhattan distance heuristic for the 8-puzzle
problem
    # ...
# Specify your initial state, goal state, and heuristic
function
initial state = ...
goal state = ...
heuristic function = eight puzzle heuristic
result = ida star search(initial state, heuristic function,
goal state)
if result:
    print("IDA* Path:")
    for node in result:
        print("State:", node.state, "Cost:", node.cost,
"Heuristic:", node.heuristic)
else:
    print("No solution found.")
```



Write a Python Program to implement Apriori Algorithm on a dataset of your own choice

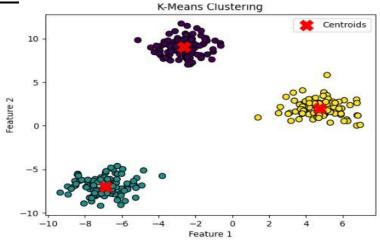
```
# Make sure to install mlxtend library
# You can install it using: pip install mlxtend
from mlxtend.preprocessing import TransactionEncoder
from mlxtend.frequent patterns import apriori,
association rules
import pandas as pd
# Sample retail dataset
dataset = [['Milk', 'Bread', 'Eggs'],
           ['Milk', 'Cheese'],
           ['Cheese', 'Bread', 'Butter'],
           ['Milk', 'Bread', 'Butter'],
           ['Eggs', 'Bread']]
# Convert the dataset into a transaction format
te = TransactionEncoder()
te ary = te.fit(dataset).transform(dataset)
df = pd.DataFrame(te ary, columns=te.columns)
# Apply Apriori algorithm
frequent itemsets = apriori(df, min support=0.4,
use colnames=True)
# Generate association rules
rules = association rules(frequent itemsets,
metric="confidence", min threshold=0.7)
# Display frequent itemsets
print("Frequent Itemsets:")
print(frequent itemsets)
# Display association rules
print("\nAssociation Rules:")
print(rules)
```

```
requent Itemsets:
  support itemsets
     0.6
0.4
0
               (Bread)
1
              (Cheese)
     0.4
                (Eggs)
3
    0.8
                (Milk)
    0.4 (Eggs, Bread)
0.4 (Bread, Milk)
4
5
    0.4 (Cheese, Milk)
6
Association Rules:
 antecedents consequents antecedent support consequent
support support \
    (Eggs)
           (Bread)
                                   0.4
0.6
      0.4
                                 0.4
1 (Cheese) (Milk)
0.8
       0.4
 confidence lift leverage conviction zhangs_metric
       1.0 1.666667 0.16 inf 0.666667
0
        1.0 1.250000 0.08
                                            0.333333
1
                                  inf
```

Write a Python Program to implement K-Means Algorithm on a dataset of your own choice

SOURCE CODE

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.cluster import KMeans
from sklearn.datasets import make blobs
# Generate a hypothetical dataset with three clusters
X, y = make blobs(n samples=300, centers=3, random state=42)
# Apply K-Means algorithm
kmeans = KMeans(n clusters=3, random state=42)
y kmeans = kmeans.fit predict(X)
# Visualize the results
plt.scatter(X[:, 0], X[:, 1], c=y kmeans, cmap='viridis',
edgecolor='k', s=50)
centers = kmeans.cluster centers
plt.scatter(centers[:, 0], centers[:, 1], c='red',
marker='X', s=200, label='Centroids')
plt.title('K-Means Clustering')
plt.xlabel('Feature 1')
plt.ylabel('Feature 2')
plt.legend()
plt.show()
```



Write a Python Program to implement DBSCAN Algorithm on a dataset of your own choice

SOURCE CODE

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.cluster import DBSCAN
from sklearn.datasets import make blobs
from sklearn.preprocessing import StandardScaler
# Generate a hypothetical dataset with varying densities
X, y = make blobs(n samples=300, centers=3, cluster std=1.0,
random state=42)
# Standardize the feature values
X = StandardScaler().fit transform(X)
# Apply DBSCAN algorithm
dbscan = DBSCAN(eps=0.5, min samples=5)
labels = dbscan.fit predict(X)
# Visualize the results
plt.scatter(X[:, 0], X[:, 1], c=labels, cmap='viridis',
edgecolor='k', s=50)
plt.title('DBSCAN Clustering')
plt.xlabel('Feature 1')
plt.ylabel('Feature 2')
plt.show()
```

