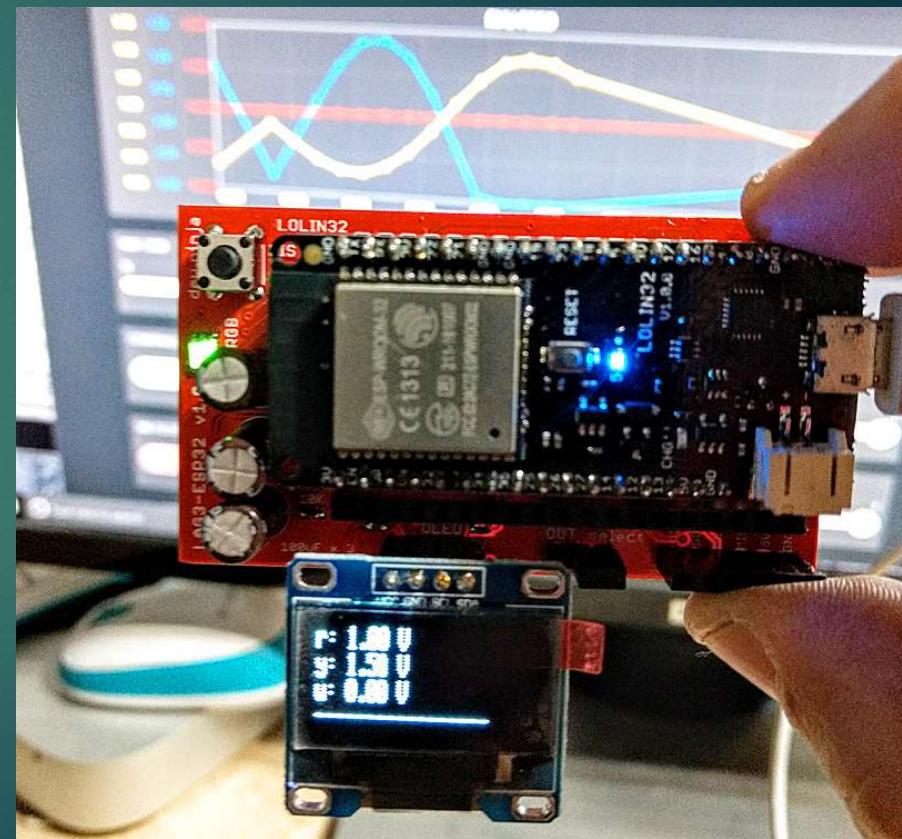


Session 1 : ESP32 Basics

IoT for Industrial Control workshop
Dept. of Physics, Faculty of Sciences
Naresuan University
June 26 – 27, 2021

Dr.Varodom Toochinda
Dept. of Mechanical Engineering
Kasetsart University

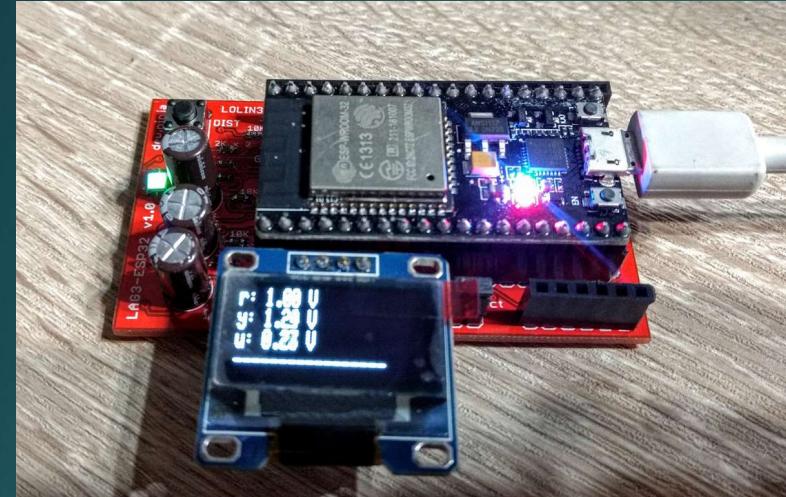


Outline

- ▶ ESP32 Arduino core and libraries installation
- ▶ Learn to program ESP32 using Arduino IDE and C language for ESP32 main components such as ADC, PWM
- ▶ Learn basics of external interrupt and timer
- ▶ Learn how to construct a command interpreter function
- ▶ Plotting experimental data
- ▶ Connect ESP32 to NETPIE 2020

Hardware and Software

- ▶ Hardware
 - ▶ NodeMCU-32S
 - ▶ LAG3-ESP32 by dew.ninja
- ▶ Software
 - ▶ Arduino IDE ver 1.8.13 + ESP32 core + libraries
 - ▶ CP2104 USB to serial driver
- ▶ Cloud platform
 - ▶ NETPIE 2020
- ▶ Notebook computer
 - ▶ Windows preferred. Setup might be problematic with some version of MAC-OSX



Hardware/Software

SETUP

lab1_4 | Arduino

dew.ninja

Boards Manager...

Arduino AVR Boards >

ESP32 Arduino >

ESP8266 Boards (2.7.4) >

AS

Python arrays

```
// use GPIO16 as output  
// use A3 as pin for analog input  
#include <Wire.h>  
#include <Adafruit_Sensor.h>  
#include <Adafruit_GFX.h>  
#include <Adafruit_SSD1306.h>  
#include <ESP8266WiFi.h>  
#include <PubSubClient.h>  
  
// Pin assignments  
const int SDA = 23, SCL = 22, BLED = 17; //  
const int DHTPIN = 10; // values from DHT sensor  
*****  
B led  
*****
```

ESP32 Dev Module

ESP32 Wrover Module

ESP32 Pico Kit

TinyPICO

S.ODI Ultra v1

MagicBit

Turta IoT Node

TTGO LoRa32-OLED V1

TTGO T1

TTGO T7 V1.3 Mini32

TTGO T7 V1.4 Mini32

XinaBox CW02

SparkFun ESP32 Thing

SparkFun ESP32 Thing Plus

u-blox NINA-W10 series (ESP32)

Widora AIR

Electronic SweetPeas - ESP320

Nano32

LOLIN D32

LOLIN D32 PRO

WEMOS LOLIN32

WEMOS LOLIN32 Lite

Dongsen Tech Pocket 32

WeMos WiFi&Bluetooth Battery

ESPea32

Noduino Quantum

Node32s

Hornbill ESP32 Dev

Hornbill ESP32 Minima

FireBeetle-ESP32

IntoRobot Fig

Onehorse ESP32 Dev Module

Adafruit ESP32 Feather

✓ NodeMCU-32S

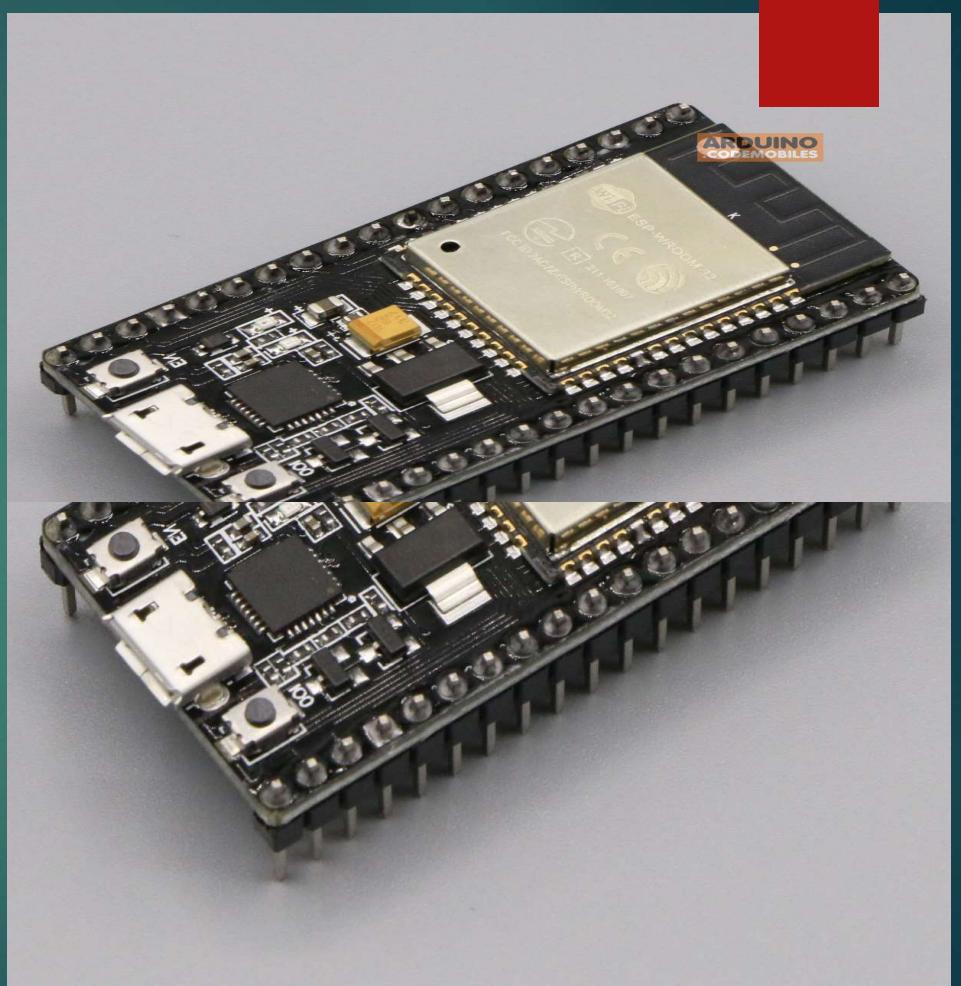
MH ET LIVE ESP32DevKIT

MH ET LIVE ESP32MiniKit

ESP32vn IoT Uno

NodeMCU-32S

- ▶ ESP32 SoC with integrated WiFi/Bluetooth (dual-core Tensilica Xtensa LX6 microprocessor)
- ▶ Clock speed 240 MHz
- ▶ 4 MB Flash
- ▶ Digital I/O pins : 26
- ▶ Analog input pins: 12
- ▶ 8-bit analog outputs (DAC) : 2
- ▶ SPI, I2C, UART and sensors (see datasheet)

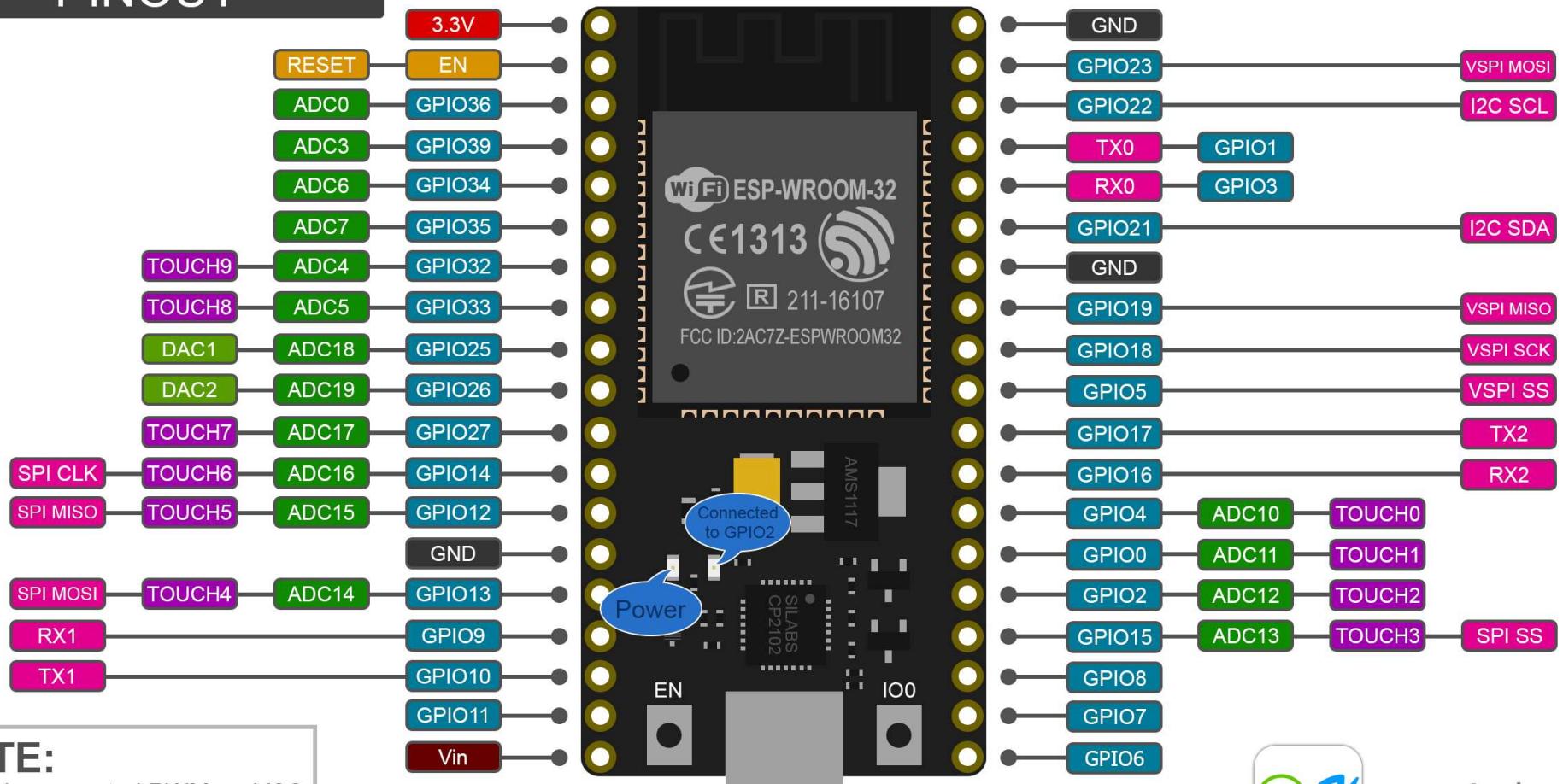




CC BY 4.0

NodeMCU-32S

PINOUT



NOTE:

All pin supported PWM and I2C
Pin current 6mA (Max. 12mA)



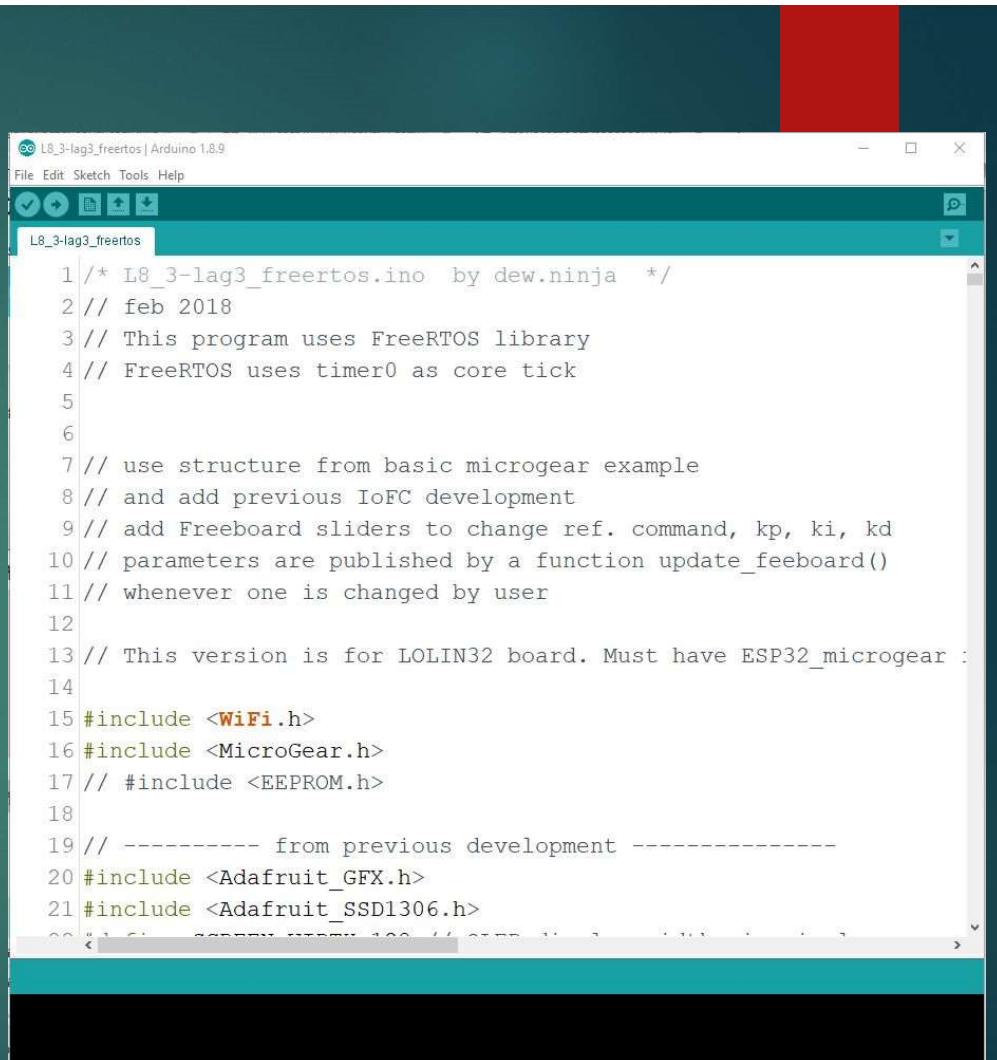
www.ioxhop.com

Use NodeMCU-32S with Arduino IDE

- ▶ Install Arduino IDE <https://www.arduino.cc/en/Main/Software>
- ▶ Install CP210x USB-to-serial driver
- ▶ Install ESP32 Arduino Core

Install Arduino IDE

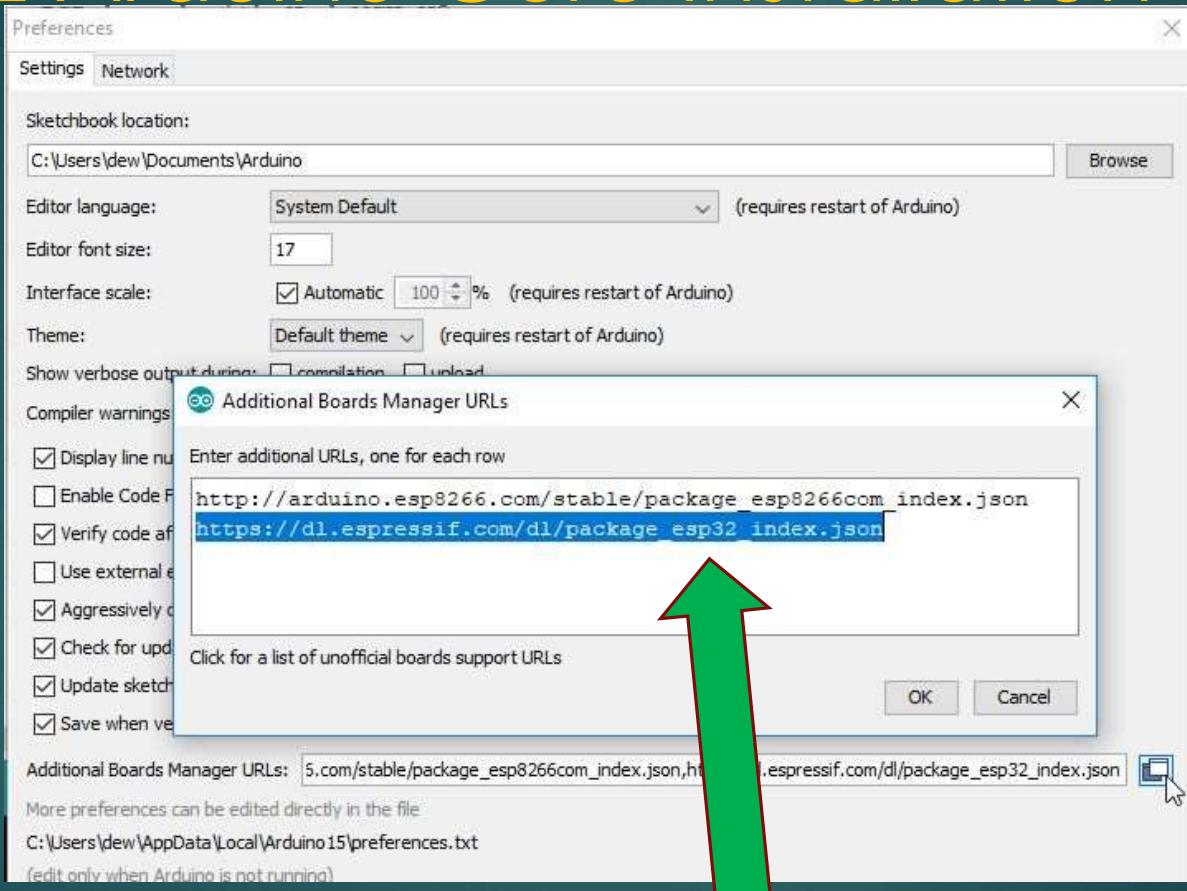
- ▶ Latest version (March 21) 1.8.13
- ▶ Download and run installer (or download zip file and extract to the desired directory)
- ▶ Install CP210x USB driver
- ▶ Check Tools->Board . There is no support for ESP32. We need to install Arduino Core for ESP32



The screenshot shows the Arduino IDE interface with a sketch named "L8_3-lag3_freertos" open. The code editor displays the following C++ code:

```
1 /* L8_3-lag3_freertos.ino by dew.ninja */
2 // feb 2018
3 // This program uses FreeRTOS library
4 // FreeRTOS uses timer0 as core tick
5
6
7 // use structure from basic microgear example
8 // and add previous IoFC development
9 // add Freeboard sliders to change ref. command, kp, ki, kd
10 // parameters are published by a function update_freeboard()
11 // whenever one is changed by user
12
13 // This version is for LOLIN32 board. Must have ESP32_microgear :
14
15 #include <WiFi.h>
16 #include <MicroGear.h>
17 // #include <EEPROM.h>
18
19 // ----- from previous development -----
20 #include <Adafruit_GFX.h>
21 #include <Adafruit_SSD1306.h>
22 #include <FreeRTOS.h>
23 #include <task.h>
24 #include <queue.h>
25 #include <math.h>
```

ESP32 Arduino Core Installation



https://dl.espressif.com/dl/package_esp32_index.json

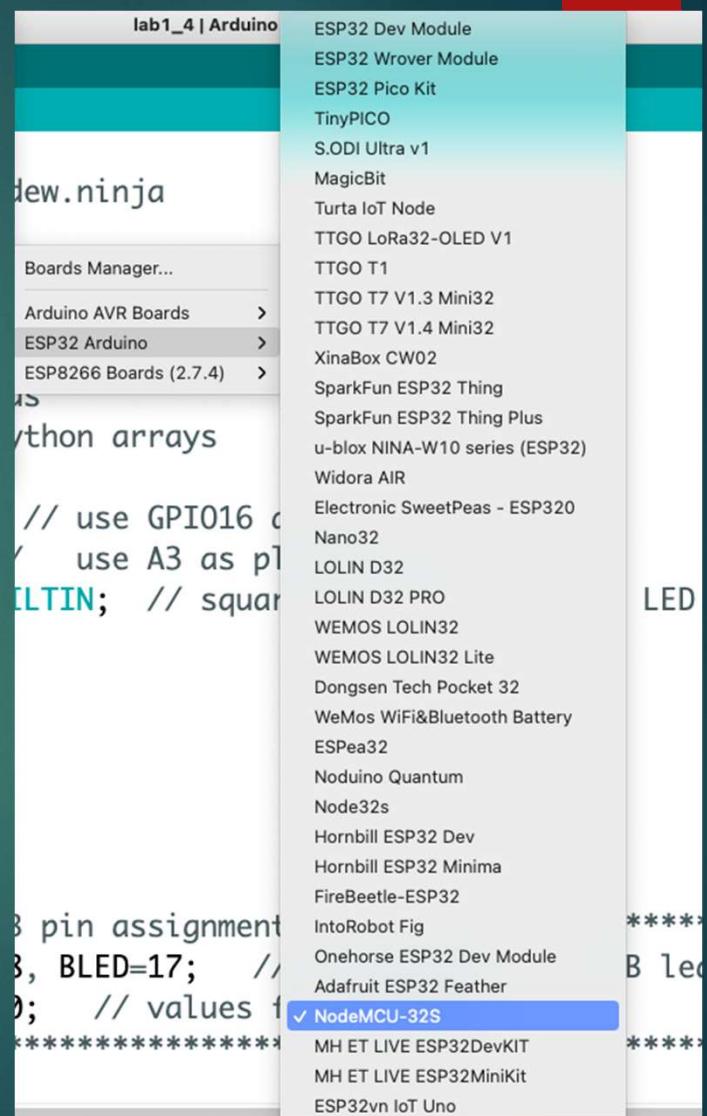
ESP32 Arduino Core Installation



✓ ติดตั้งสำเร็จ

After ESP32 Arduino Core is installed

Select Tools -> Board ->ESP32 Arduino -> NodeMCU-32S

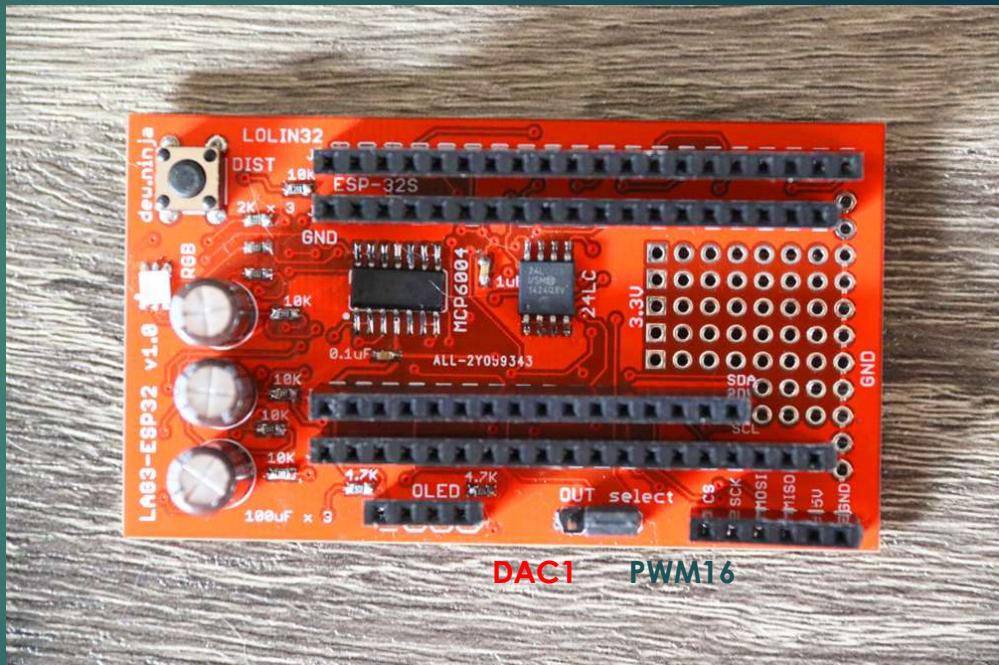


Install Library (use library manager)

- Pubsubclient for NETPIE 2020

LAG3-ESP32 board

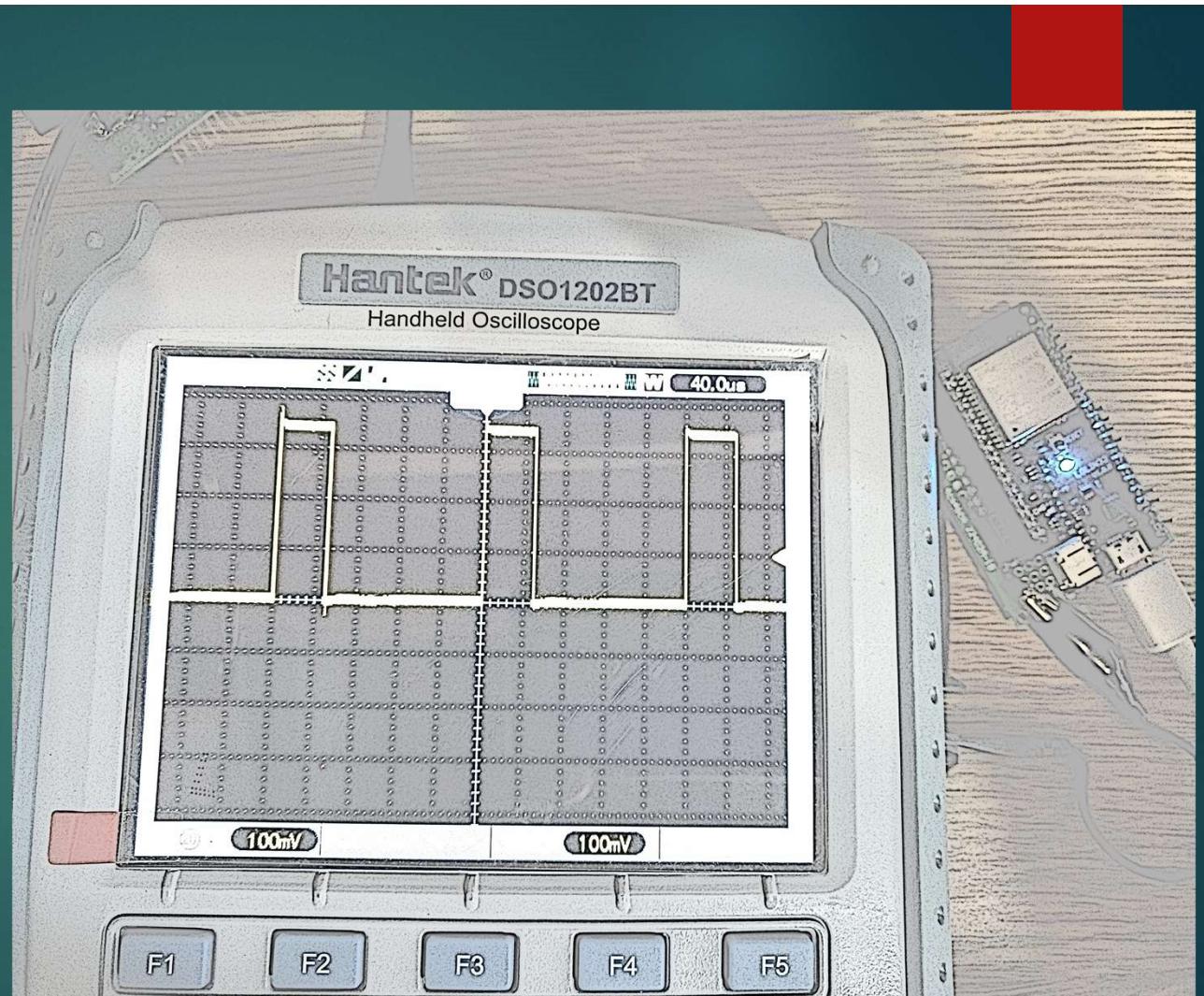
- ▶ 3-level cascade tank using RC circuit and op-amp
- ▶ Connector for OLED display
- ▶ RGB LED and EEPROM (optional)
- ▶ Can be used with WEMOS LOLIN32 or NODEMCU-32S (commercial ESP32 modules)
- ▶ DAC1/PWM16 outputs (selectable via jumper)



NodeMCU-32S pins used

GPIO	Name	Type	Function
39	ADC3	Analog IN	Plant output (Y)
32	ADC4	Analog IN	State variable (X2)
33	ADC5	Analog IN	State variable (X1)
25	DAC1	Analog OUT	Controller output (Analog)
16	PWM	OUT	Controller output (PWM)
22	SCL	OUT	I2C
21	SDA	OUT	I2C
19	PWMR	OUT	PWM for red LED
18	PWMG	OUT	PWM for green LED
17	PWMB	OUT	PWM for blue LED
5	LED	Digital OUT	On-board LED

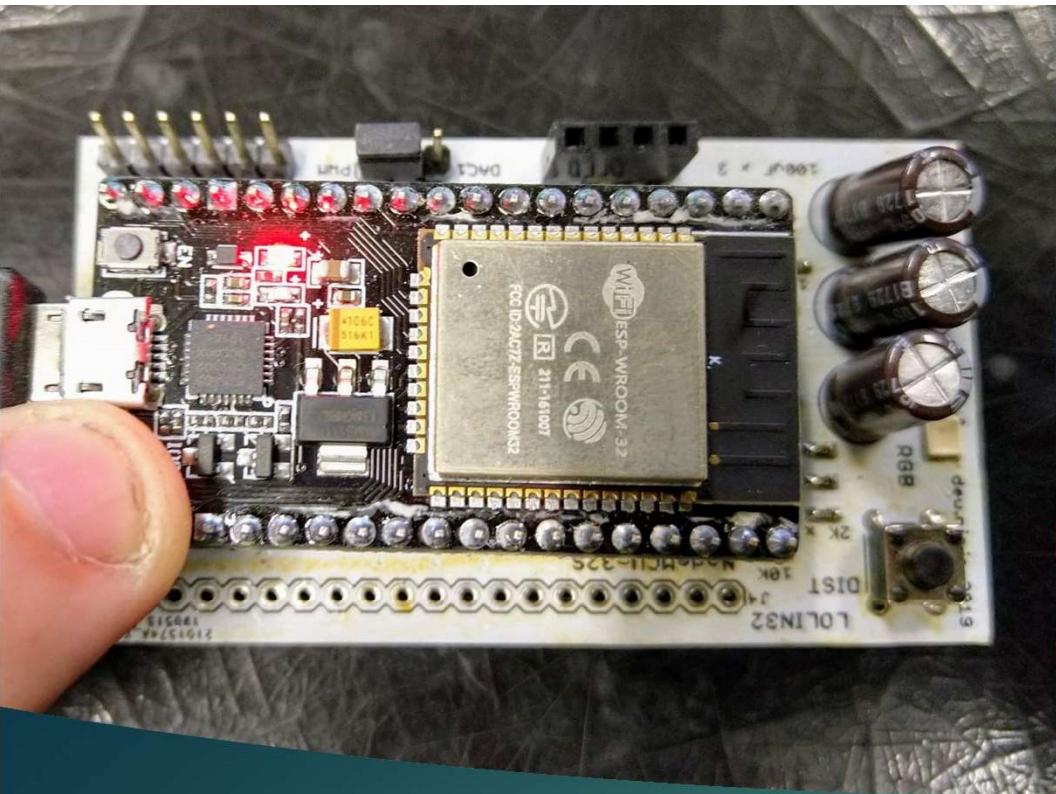
ESP32 basic module programming



Arduino program structure

```
setup() {  
    // Module initialization.  
    // run only once at  
    // beginning  
}  
  
loop() {  
    // run iteratively  
    user_func();  
}  
  
user_func() { // optional  
}
```

```
external_interrupt_function() {  
    // respond to external  
    //interrupt  
    //optional  
}  
  
timer_callback() {  
    //respond to timer interrupt  
    // optional  
}
```



Press button to upload code

```
12     r = parmvalfloat;
13     rold = r;    // save previous com
14   }
15   Serial.println("datamat = [");
16   datacnt = 1.    // set the flag +
```

```
loading...
etch uses 229844 bytes (17%) of program st
obal variables use 13580 bytes (4%) of dyn
ptool.py v3.0-dev
rial port /dev/cu.usbserial-0001
nnecting.....
```

Serial port communication

- ▶ Initialized by `Serial.begin()`, such as
 - ▶ `Serial.begin(115200);`
 - ▶ Other side must use same baudrate.
- ▶ Output string with `Serial.print()` or `Serial.println()`
- ▶ Read data with `Serial.readString()`
- ▶ Check data in buffer with `Serial.available()`
- ▶ Can use Serial Monitor/ Serial Plotter from Tools menu of Arduino IDE to monitor or send commands

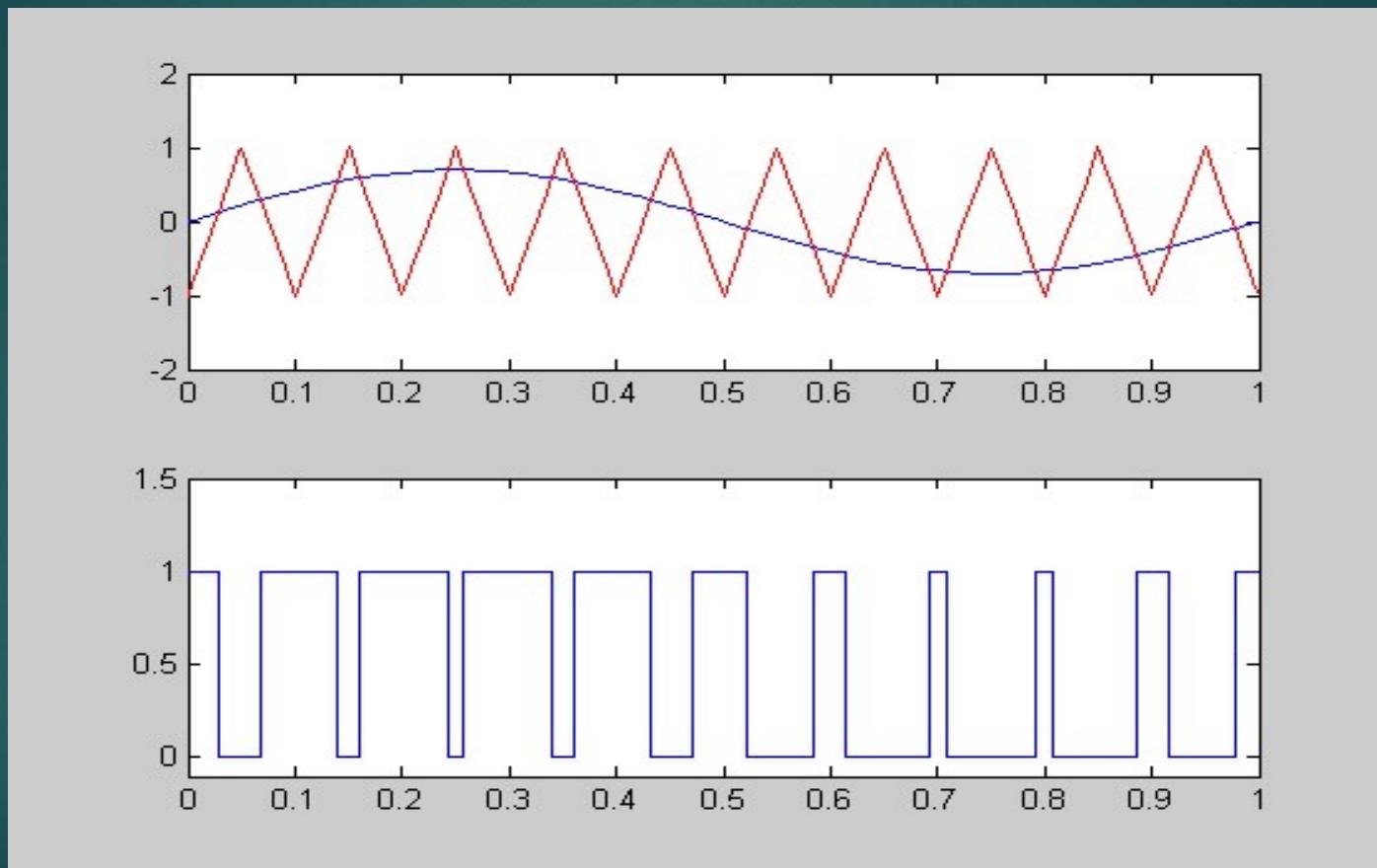
Analog inputs

- ▶ Maximum 16 channels
- ▶ Maximum voltage equals Vcc (3.3 V)
- ▶ 12-bit resolution (0 – 4095)
- ▶ Read data using `analogRead();`
- ▶ Can specify GPIO number or analog channel
 - ▶ `int adcval = analogRead(A0);`
 - ▶ `int adcval = analogRead(36);`

Analog outputs

- ▶ 8-bit DAC modules
- ▶ 2 channels : GPIO25 (DAC1) and GPIO26 (DAC2)
- ▶ Write function : `dacWrite()`;
- ▶ Can specify GPIO or DAC channels. For example, to send 1.65 volts out at pin DAC1
 - ▶ `dacWrite(25, 127);`
 - ▶ `dacWrite(DAC1, 127);`
- ▶ Limited output current. In practice, an op-amp buffer may be needed to supply more current.

PWM generation



PWM outputs



- ▶ Native ESP32 core does not have `analogWrite()` function (additional library is needed)
- ▶ Use `ledc()` , which must be setup with `ledcSetup()` ; ex.,
 - ▶ `ledcSetup(1, 5000, 12);` use timer 1 PWM frequency 5 KHz and 12-bit resolution
- ▶ Attach timer to GPIO using `ledcAttachPin(timer, pin)`
 - ▶ `ledcAttachPin(2,1);` attach timer 1 to GPIO2
- ▶ After setup, use `ledcWrite()` to write to PWM module (the first argument is timer number, not GPIO pin!)
 - ▶ `ledcWrite(1, 1023);` generate PWM with duty cycle 25%

Using analogWrite library

- ▶ Must install ESP32 analogWrite library
- ▶ `#include <analogWrite.h>`
- ▶ Set resolution in `setup()`
 - ▶ `analogWriteResolution(LED_BUILTIN, 12);`
- ▶ Output some value
 - ▶ `analogWrite(LED_BUILTIN, brightness);`

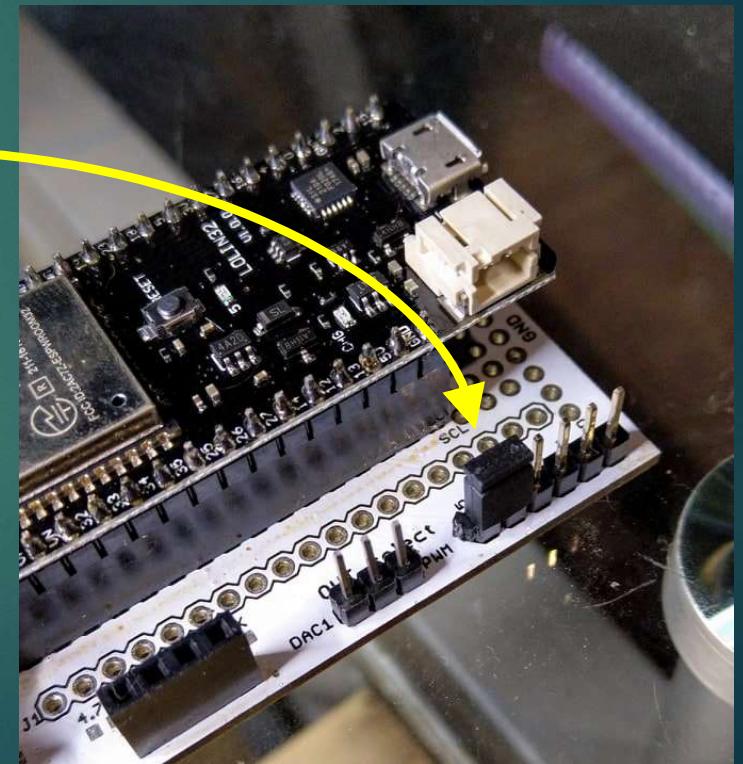
From my experiment on pin 15, the PWM waveform does not give expected result ?

External interrupt

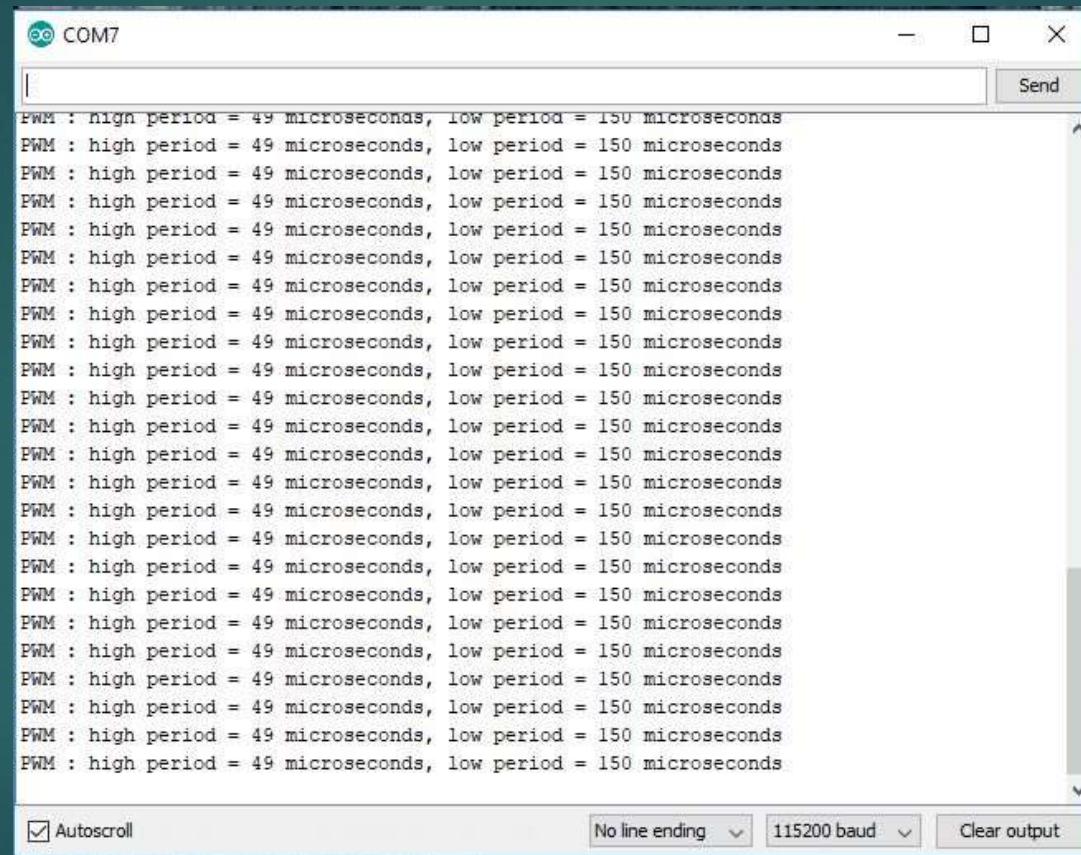
- ▶ Use `attachInterrupt()`
- ▶ `attachInterrupt(34, funcA, RISING);` setup GPIO34 such that when the logic level changes from 0 to 1 (rising edge), execute `funcA()`
- ▶ Choice of external interrupt events
 - ▶ `LOW` – when input has logic 0
 - ▶ `HIGH` – when input has logic 1
 - ▶ `CHANGE` – when input changes logic level
 - ▶ `RISING` – at rising edge of input
 - ▶ `FALLING` – at falling edge of input

Lab 1.1 : measure PWM periods without using an oscilloscope

- ▶ Assign PWM output to GPIO15
 - ▶ Use timer 1 PWM frequency 5 KHz
 - ▶ Connect GPIO15 to GPIO14
 - ▶ Setup GPIO14 to interrupt every logic change
 - ▶ Create PWM with duty cycle 25%
 - ▶ Use micros() to measure high and low periods



Lab 1.1 : Serial Monitor Output



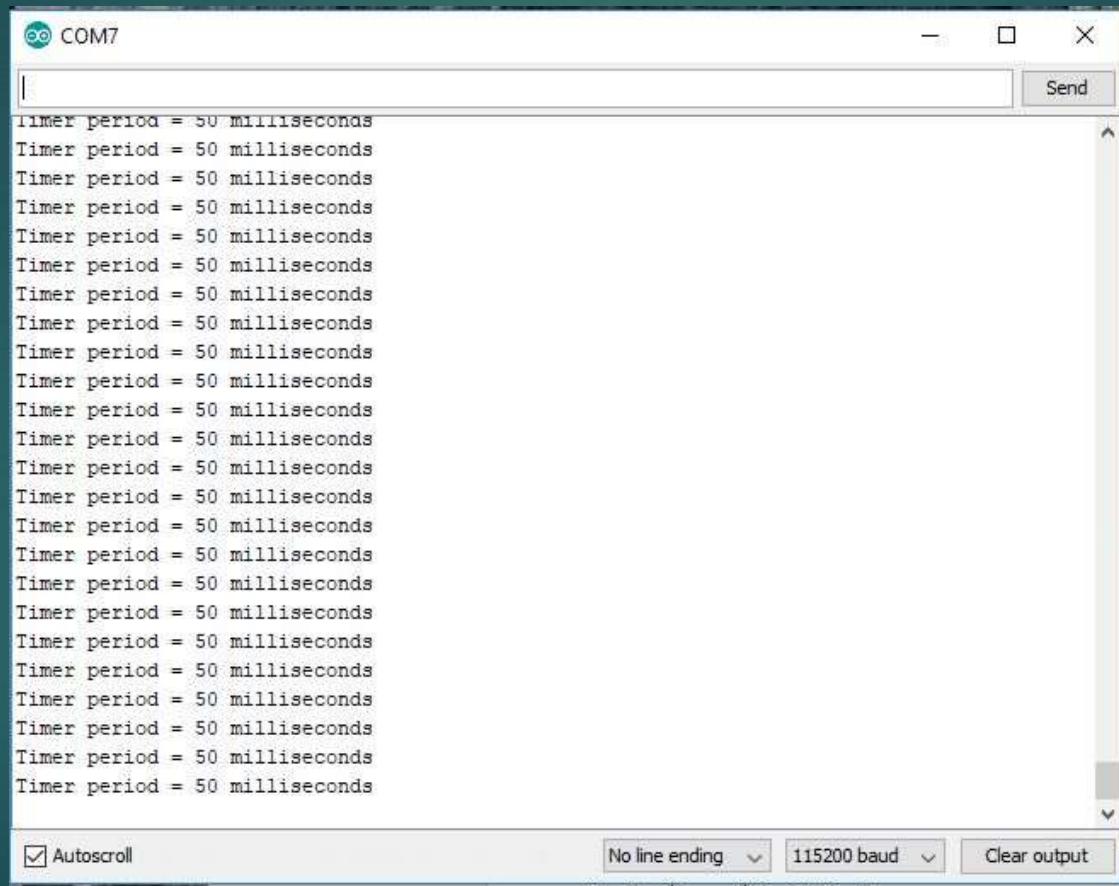
Using timer on ESP32

- ▶ Use hardware timer (can cause watchdog reset for long interrupt period)
- ▶ Setup using `timerBegin()`
- ▶ Write a callback and attach to timer using `timerAttachInterrupt()`
- ▶ Set interrupt period with `timerAlarmWrite()`
- ▶ Enable interrupt with `timerAlarmEnabled()`

Lab 1.2 : using a timer on ESP32

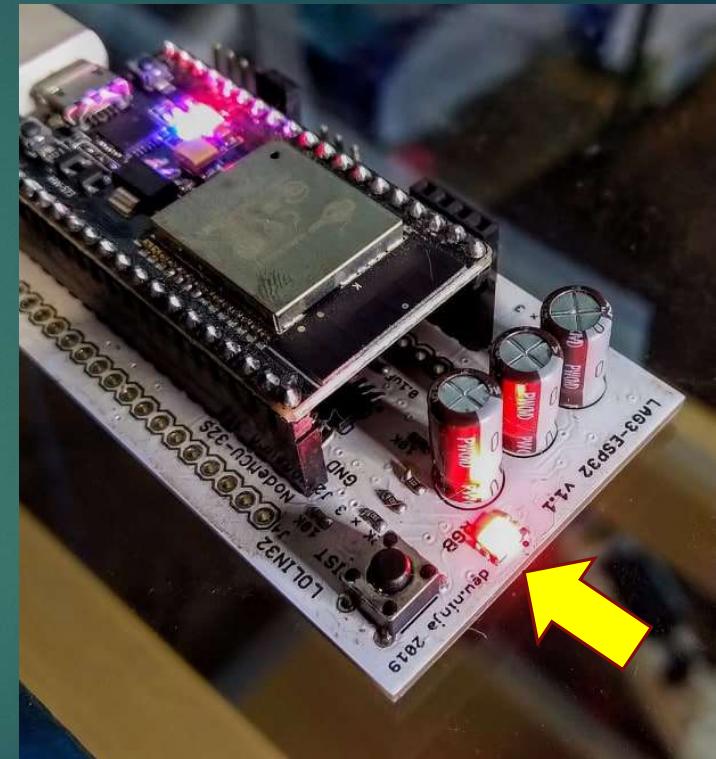
- ▶ Setup timer 0 to interrupt every 50 milliseconds
- ▶ Blink onboard LED on NodeMCU-32S
- ▶ Measure period with `millis()`
- ▶ Output result on Serial Monitor

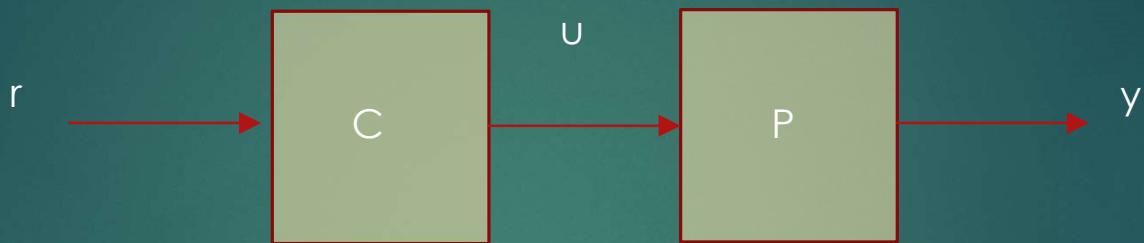
Lab 1.2 Serial Monitor Output



Exercise 1:

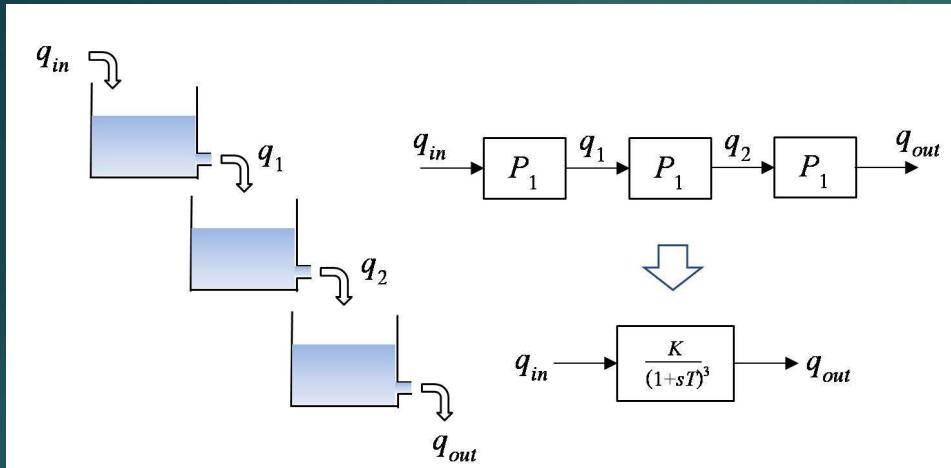
modify `LAB1_2.ino` to
blink red LED
independently from
on-board LED





OPEN-LOOP SYSTEM

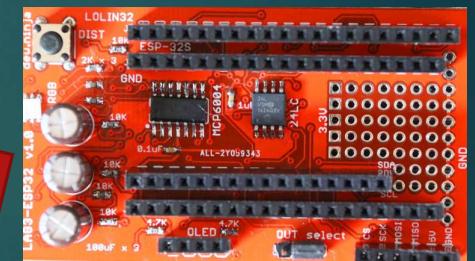
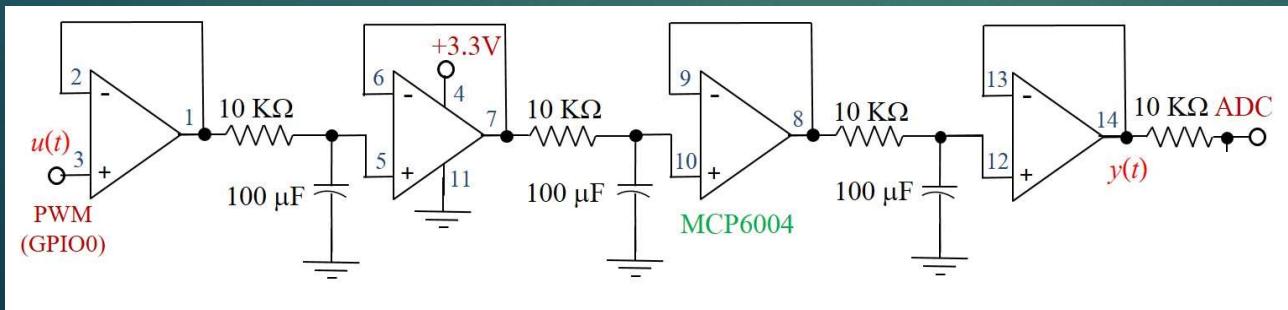
3 cascade tank model(LAG3)



normalized
transfer function

$$\frac{1}{(s+1)^3}$$

Simulation by electronic circuit



Lab 1.4 Command interpreter function

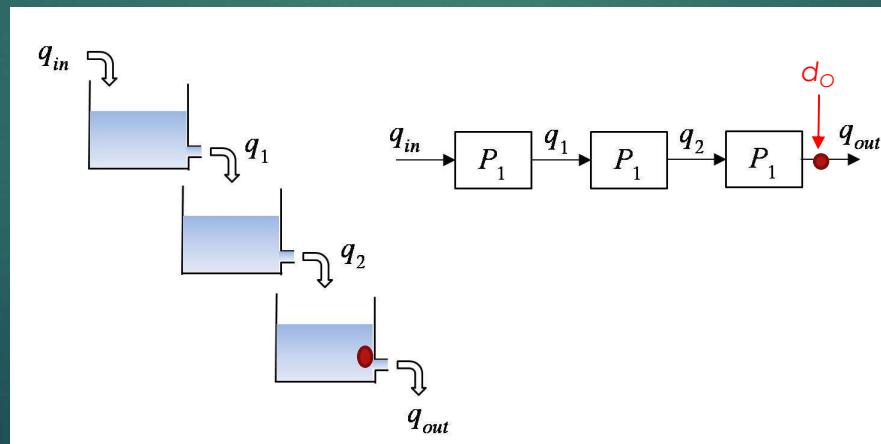
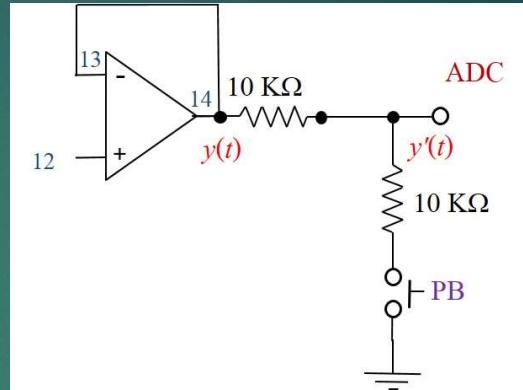
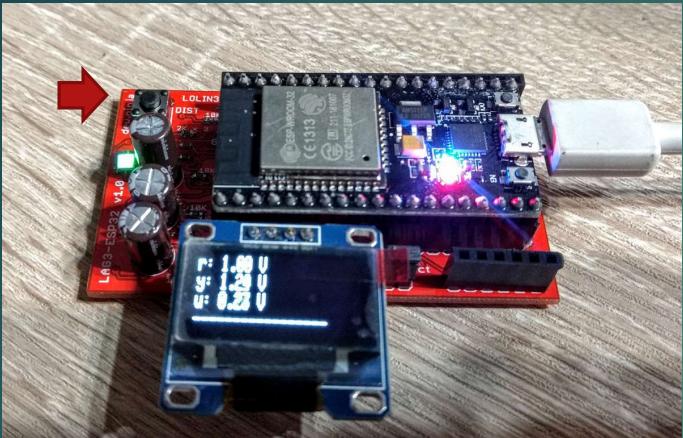
- ▶ Construct cmdInt() for the following commands
 - ▶ step=<value> : adjust reference input
 - ▶ datasize=<num> : specify number of data points
 - ▶ Other commands you may want to add, using format command=<parameter>

Test command via serial monitor

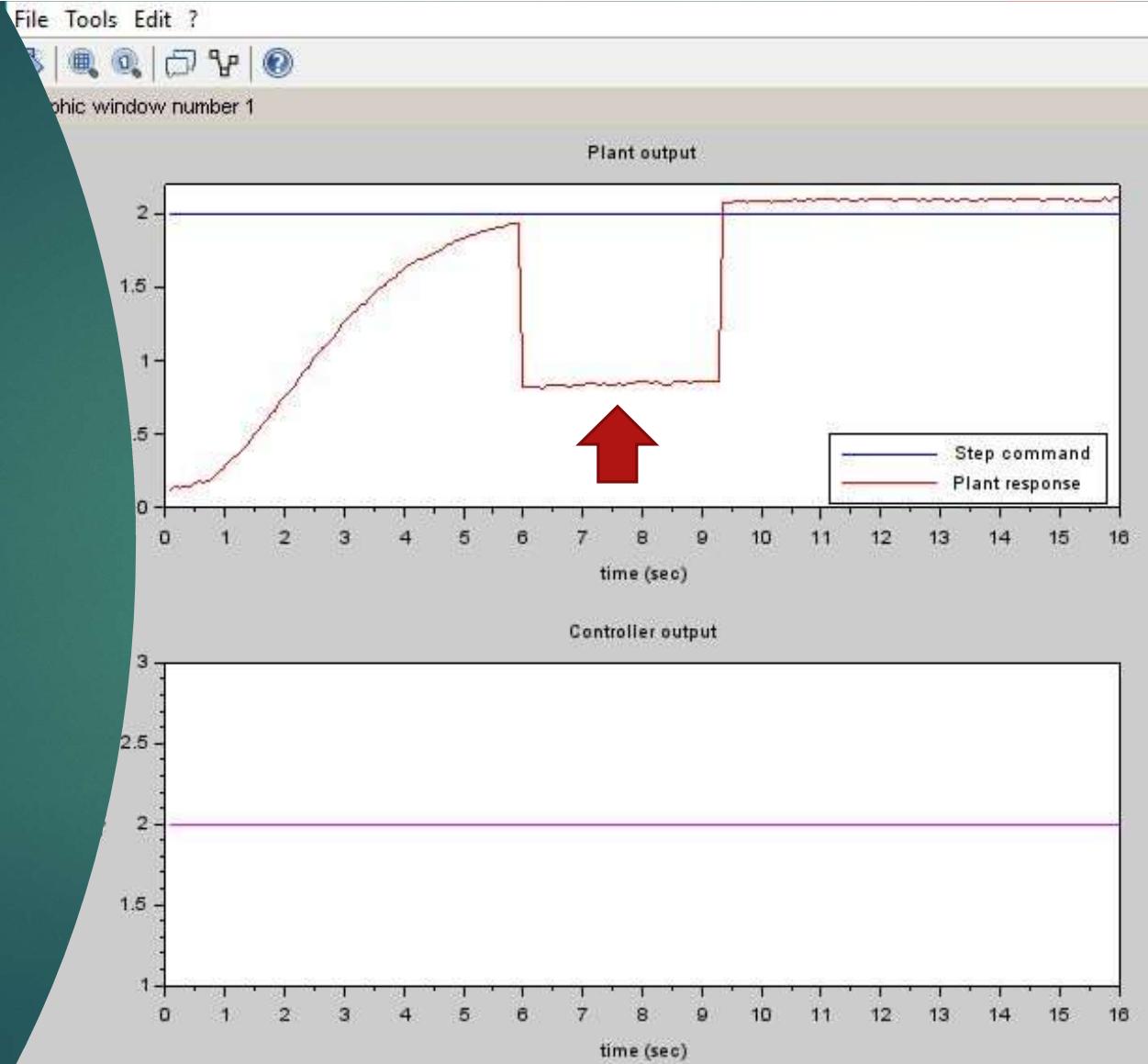
```
step=1.5|
Current datasize = 20
datamat =
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.05, 1.50;
1.50, 1.06, 1.50;
1.50, 1.06, 1.50;
1.50, 1.06, 1.50;
1.50, 1.07, 1.50;
1.50, 1.08, 1.50;
1.50, 1.08, 1.50;
1.50, 1.09, 1.50;
1.50, 1.10, 1.50;
1.50, 1.11, 1.50;
1.50, 1.12, 1.50;
1.50, 1.12, 1.50;
1.50, 1.13, 1.50;
1.50, 1.14, 1.50;
1.50, 1.16, 1.50;
];
```

can copy and paste to
MATLAB/Scilab for plotting

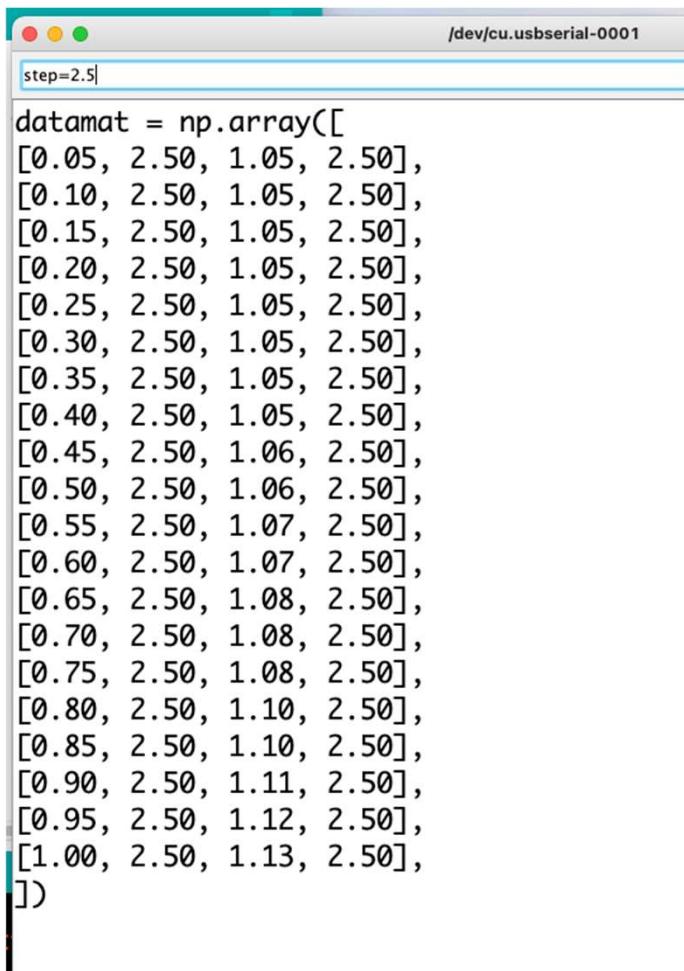
Output disturbance switch



When
disturbance
switch is
pressed

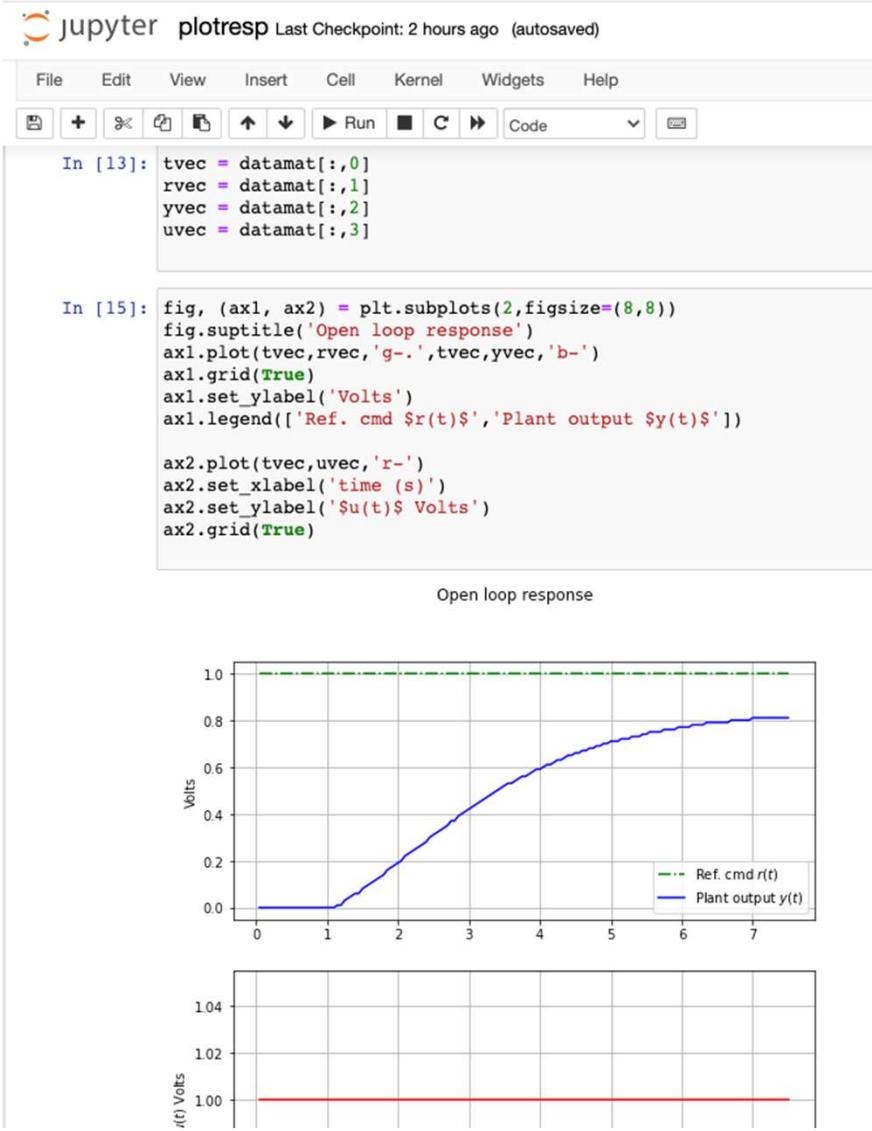


Output as numpy array



A screenshot of a terminal window titled "/dev/cu.usbserial-0001". The window contains the following text:

```
step=2.5
datamat = np.array([
[0.05, 2.50, 1.05, 2.50],
[0.10, 2.50, 1.05, 2.50],
[0.15, 2.50, 1.05, 2.50],
[0.20, 2.50, 1.05, 2.50],
[0.25, 2.50, 1.05, 2.50],
[0.30, 2.50, 1.05, 2.50],
[0.35, 2.50, 1.05, 2.50],
[0.40, 2.50, 1.05, 2.50],
[0.45, 2.50, 1.06, 2.50],
[0.50, 2.50, 1.06, 2.50],
[0.55, 2.50, 1.07, 2.50],
[0.60, 2.50, 1.07, 2.50],
[0.65, 2.50, 1.08, 2.50],
[0.70, 2.50, 1.08, 2.50],
[0.75, 2.50, 1.08, 2.50],
[0.80, 2.50, 1.10, 2.50],
[0.85, 2.50, 1.10, 2.50],
[0.90, 2.50, 1.11, 2.50],
[0.95, 2.50, 1.12, 2.50],
[1.00, 2.50, 1.13, 2.50],
])
```



Plot on Jupyter Notebook

What we have learnt from Lab 1

- ▶ Generate PWM output
- ▶ How to use external interrupt and timer
- ▶ Serial communication and command interpreter
- ▶ Drawback of open-loop control

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NETPIE 2020

From Makers Nation
Toward Smart Nation

Monitoring and control via NETPIE 2020



- ▶ Cloud platform developed by NECTEC
- ▶ Can use with various hardware such as ESP8266, ESP32, Raspberry PI, Android
- ▶ Latest version is NETPIE 2020
- ▶ Details can be read from <https://netpie.io>

Lab1_4_NETPIE.ino

- Add WiFi and internet connection code to Lab 1.4
- On NETPIE account, create a project and device
- Copy Client-ID, Username, Token information to Lab1_4_NETPIE.ino
- Publish r,y,u data to NETPIE shadow
- Create Freeboard and datasource
- Add 3 gauge widgets for r, y, u data
- Add a slider for ref. command adjustment

The screenshot shows a user interface for managing a 'Shadow' object. At the top, there are three tabs: 'Shadow' (which is selected and highlighted in blue), 'Schema', and 'Trigger'. Below the tabs is a toolbar with two icons (up and down arrows) and a 'Tree' dropdown menu. The main area is a tree view with the following structure:

- object {3}
 - u : 1.2
 - y : 1.05
 - r : 1.2

The text 'Select a node...' is displayed above the tree structure.

r,y,u data
on
NETPIE
Shadow

WIDGET

TYPE	Gauge	
TITLE	r	
VALUE	<code>datasources["datasource1"]["shadow"]["r"]</code>	DATASOURCE .JS EDITOR
UNITS	Volts	
MINIMUM	0	
MAXIMUM	3	

Gauge widget settings

Click on [+DATASOURCE] on the right and make selection

Slider settings

```
netpie["datasourcename"].publish("@msg/cmd", "step="+String(value))
```

TYPE: Slider

SLIDER CAPTION: r

FILLED COLOR: Grey

DISPLAY VALUE: YES

MIN VALUE: 0

MAX VALUE: 3

STEP: 0.1

INITIAL VALUE: 0

The default value set only the first time the widget is loaded.

AUTO UPDATED VALUE: `datasources["datasource1"]["shadow"]["r"]`

Slider will be updated upon the change of variables (e.g. other data sources).

ONSTART ACTION:

Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

ONSLIDE ACTION:

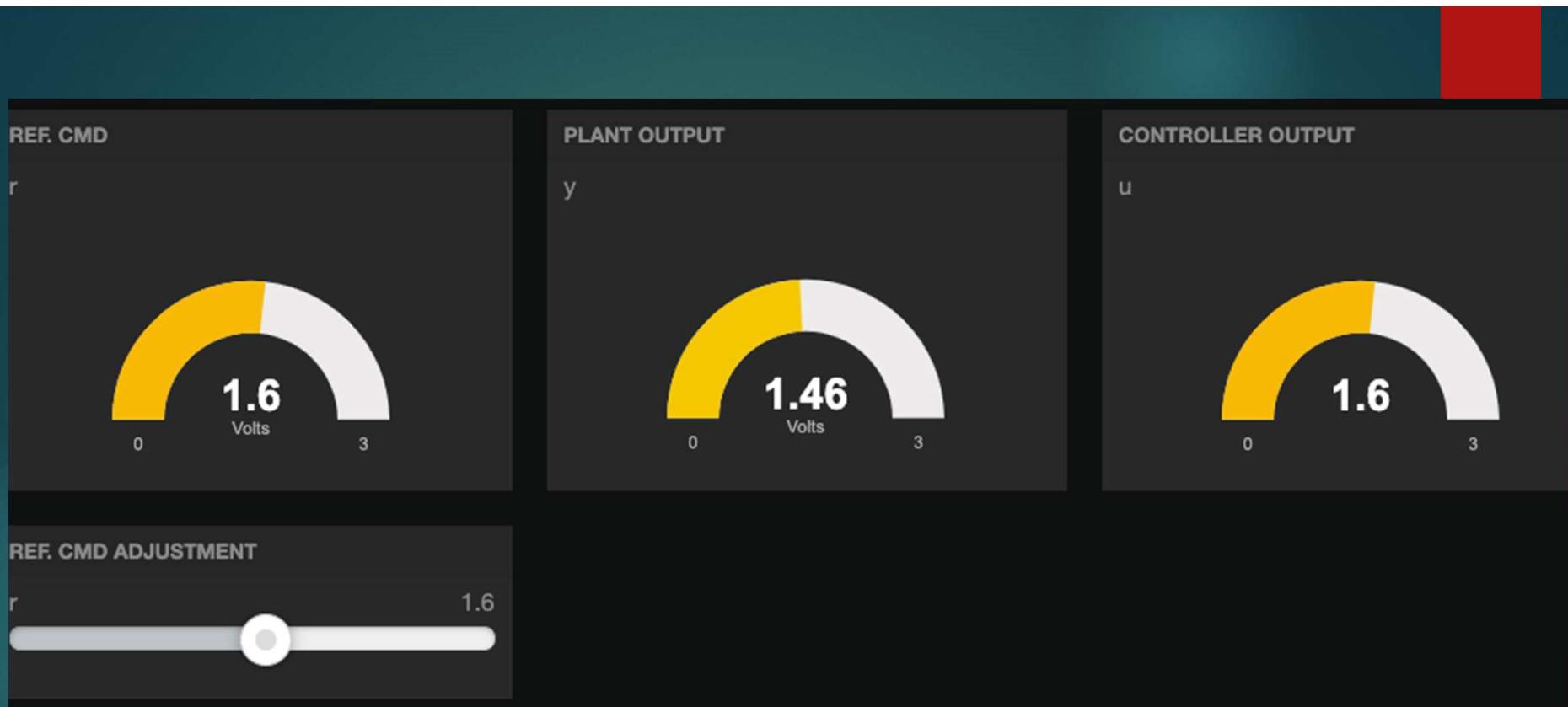
Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

ONSTOP ACTION: `netpie["datasource1"].publish("@msg/cmd", "step="+String(value))`

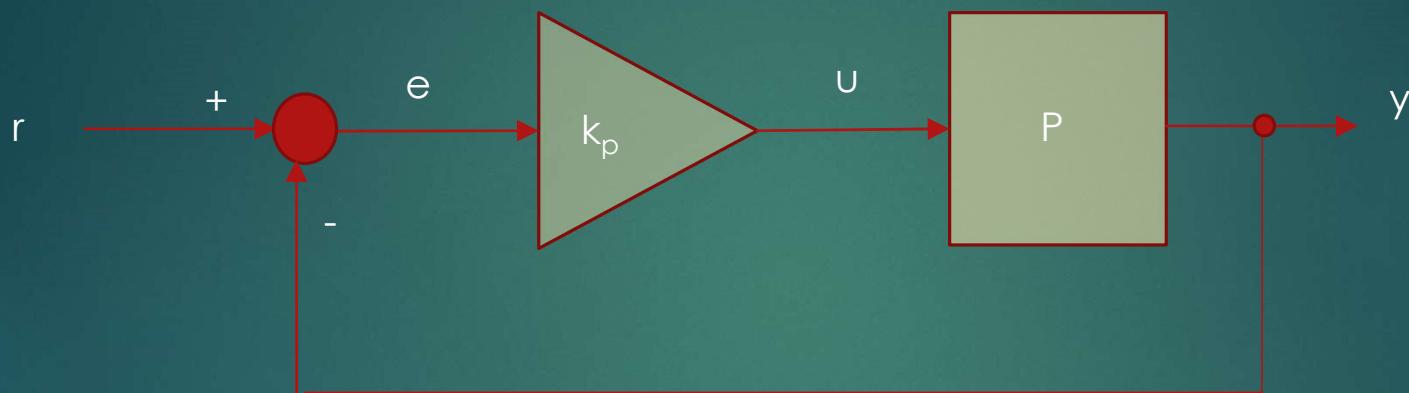
Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

JS CODE TO RUN AFTER A BUTTON IS CREATED:

SAVE CANCEL

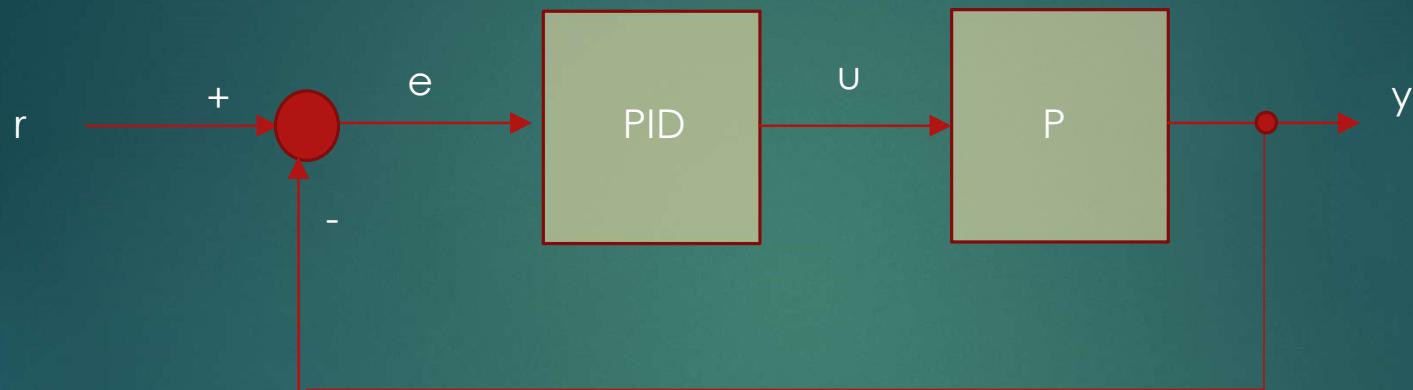


Freeboard Layout

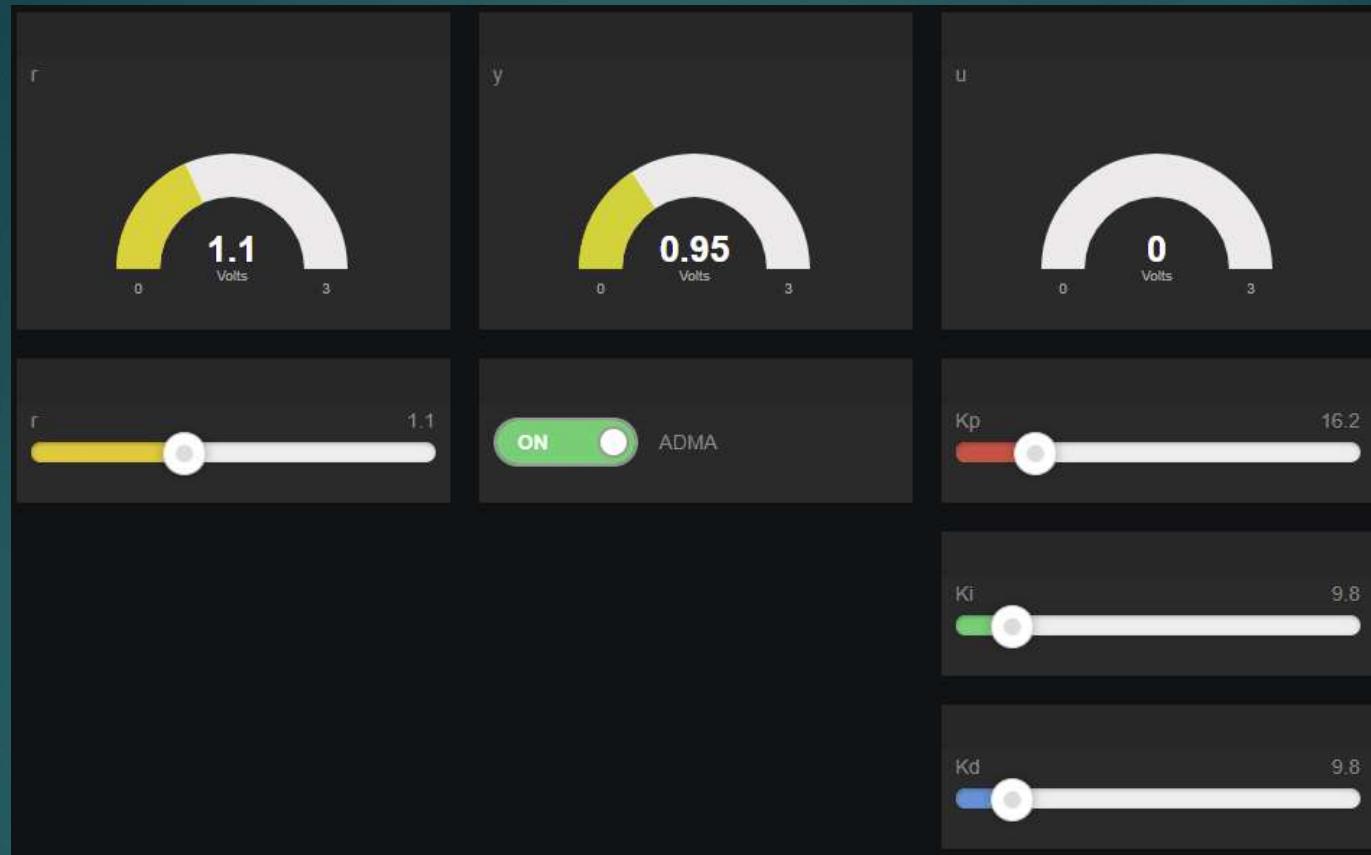


Exercise 2 : modify Lab1_4_NETPIE.ino to implement a proportional feedback. The gain k_p can be adjusted by a command and a slider in NETPIE 2020

Lab1_5_pid_NETPIE.ino

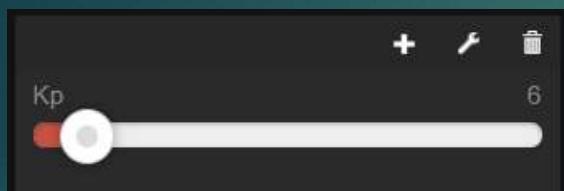


- PID controller is implemented in timer function
- Can adjust controller parameters via serial port and NETPIE 2020



Freeboard Layout

Kp slider setup example



WIDGET

A slider widget that can perform Javascript action.

TYPE: Slider

SLIDER CAPTION: Kp

FILLED COLOR: Red

DISPLAY VALUE: YES

MIN VALUE: 0

MAX VALUE: 100

STEP: 0.1

INITIAL VALUE: 0

The default value set only the first time the widget is loaded.

AUTO UPDATED VALUE: `datasources["piddatasource"]["shadow"]["kp"]` + DATASOURCE JS EDITOR

Slider will be updated upon the change of variables (e.g. other data sources).

ONSTART ACTION: + DATASOURCE JS EDITOR

Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

ONSLIDE ACTION: + DATASOURCE JS EDITOR

Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

ONSTOP ACTION: `netpie["piddatasource"].publish("@msg/cmd", "kp="+String(value))` + DATASOURCE JS EDITOR

Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

ONCREATED ACTION: + DATASOURCE JS EDITOR

Add some Javascript here. You can access to a slider attribute using variables 'value' and 'percent'.

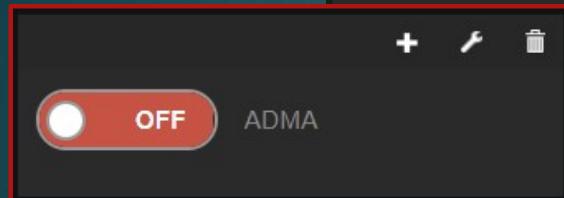
SAVE CANCEL

A yellow arrow points to the "ONSTOP ACTION" field in the configuration panel, highlighting the code entry area.

```
netpie["datasourcename"].publish("@msg/cmd", "kp="+String(value))
```

ADMA toggle button setup

A simple toggle widget that can perform javascript action.



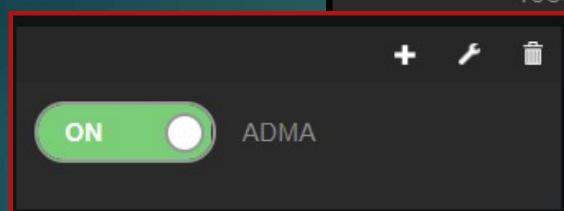
TYPE

Toggle

Caption

ADMA

▼



TOGGLE STATE

datasources["piddatasource"]["shadow"]["adma"]==1

+ DATASOURCE

JS EDITOR

ON TEXT

ON

OFF TEXT

OFF

ONTOGGLEON ACTION

netpie["piddatasource"].publish("@msg/cmd", "adma=on")

JS code to run when a toggle is switched to ON

ONTOGGLEOFF ACTION

netpie["piddatasource"].publish("@msg/cmd", "adma=off")

JS code to run when a toggle is switched to OFF

netpie["datasourcename"].publish("@msg/cmd", "adma=on"
netpie["datasourcename"].publish("@msg/cmd", "adma=off")

SAVE

CANCEL

Received
commands
shown on
serial monitor

```
Message arrived [@msg/cmd] kp=16.2
new kp = 16.20
PID coefficients updated
Message arrived [@msg/cmd] ki=9.8
new ki = 9.80
PID coefficients updated
Message arrived [@msg/cmd] kd=9.8
new kd = 9.80
PID coefficients updated
Message arrived [@msg/cmd] adma=off
ADMA set to OFF
Message arrived [@msg/cmd] adma=on
ADMA set to ON
```

Autoscroll Show timestamp

Newline

115200 baud

Clear output

References

- ▶ Books

- ▶ K.J. Astrom and T. Hagglund. Advanced PID Control. Instrumentation, Systems, and Automation Society, 2006.
- ▶ Varodom Toochinda. Feedback Control with Scilab and Arduino. dew.ninja, 2017.

- ▶ Websites

- ▶ <http://dewnijathai.blogspot.com>
- ▶ <https://netpie.io>

Thank You

