

Atmospheric Retrievals in a Modern Python Framework

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https://github.com/deweatherman

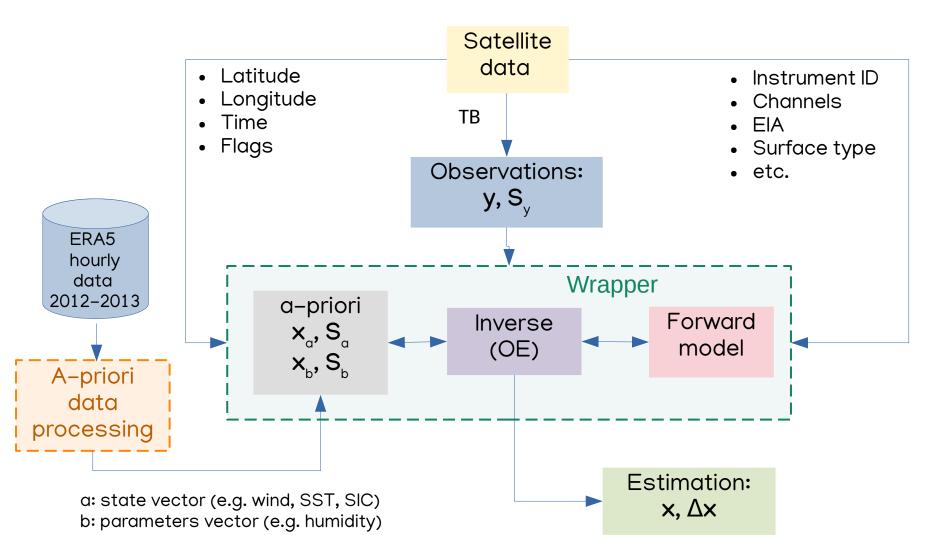




Today's story:

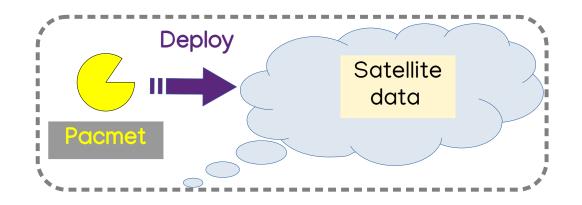
- > The main idea
- > From Observations to Atmosphere
- > Going at scale using Pangeo
- > Ongoing activities
- > Wrap up

The OE pipeline:



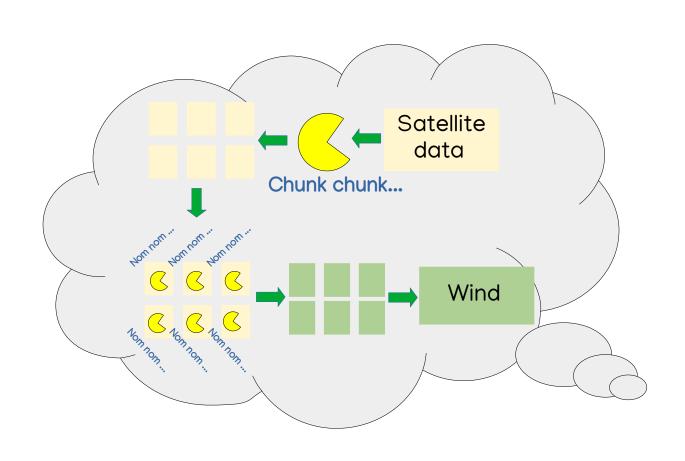


Data-centered framework:



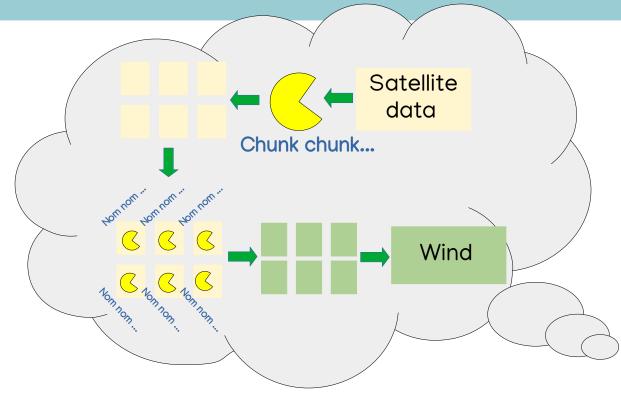
- > We want to process a bunch of data on a "cloud".
- > Data downstream is increasing with time, solution needs to scale up easily.
- > Software is modular; components are "easily" deployed.
- > Desirable: Interface with modern Machine Learning libraries possible.

Data-centered framework: wind example





Data-centered framework: caveats



- > Chunking is a logical operation, i.e. inexpensive*.
- > "Nom nom..." refers to the processing our *chunks* of data.
- Number of chunks do not need to be same as number of workers:

^{*}It generate tasks to be performed, this is not a 'live' operation, but the tasks are to be performed at some point.

The message, do not overdo with chunking.



Data Model and Data Formats

- We use xarray¹ as data interface.
- xarray follows the NetCDF data model (thus it follows CF conventions²):
 - > **Self-Describing.** A netCDF file includes information about the data it contains.
 - Portable. A netCDF file can be accessed by computers with different ways of storing integers, characters, and floating-point numbers.
 - Scalable. Small subsets of large datasets in various formats may be accessed efficiently through netCDF interfaces, even from remote servers.
 - > **Appendable.** Data may be appended to a properly structured netCDF file without copying the dataset or redefining its structure.
 - > Sharable. One writer and multiple readers may simultaneously access the same netCDF file.
 - > **Archivable.** Access to all earlier forms of netCDF data will be supported by current and future versions of the software.
- This is highly beneficial in terms of embracing FAIR principles.
- > xarray's API handles among others NetCDF, GRIB and zarr.
- xarray can be seen as a multidimensional Pandas and labeled Numpy.

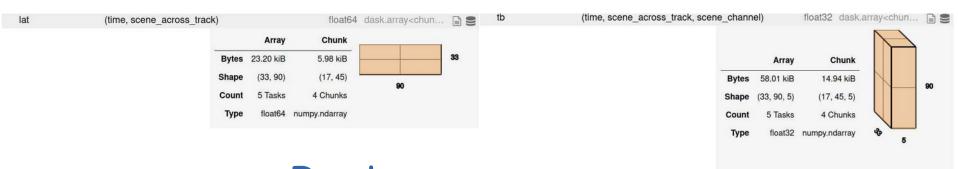
Data Model and Data Formats: examples

GRIB (ERA5)					NetCDF (*CMSA	CDF (*CMSAF-ish)	
xarray.Dataset				xarray.Dataset			
► Dimensions:	(time: 96, step: 2, isobaricInhPa: 37, latitude: 724, longitude: 1440)			- Dimensions:	(time: 45505, scene_across_track: 90, sc	ene_channel: 5)	
▼ Coordinates:				▼ Coordinates:			
number	0	int64 0		scene_across	(scene_across_track)	int32 1 5 9 13 17	34
time	(time)	datetime64[ns] 2014-01-01T0		scene_channel	(scene_channel)	int64 11 12 13 14	
step	(step)	timedelta64[ns] 06:00:00 18:0		time	(time)	datetime64[ns] 2014-09-09	
isobaricInhPa	(isobaricInhPa)	float64 1e+03 975.0 9		▼ Data variables:			
latitude	(latitude)	float64 90.0 89.75 89					
longitude	(longitude)	float64 -180.0 -179.8		lat	(time, scene_across_track)	float64 dask.array-	
valid_time	(time, step)	datetime64[ns] dask.array <ch< td=""><td></td><td>lon</td><td>(time, scene_across_track)</td><td>float64 dask.array</td><td></td></ch<>		lon	(time, scene_across_track)	float64 dask.array	
surface	0	float64 0.0		eia	(time, scene_across_track)	float32 dask.array	
▼ Data variables:				sft	(time, scene_across_track)	float32 dask.array	
				tb	(time, scene_across_track, scene_channel)	float32 dask.array	
t	(time, step, isobaricInhPa, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>global_channel</td><td>(scene_channel)</td><td>int32 dask.array</td><td></td></ch<>		global_channel	(scene_channel)	int32 dask.array	
q	(time, step, isobaricInhPa, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>channel_uncert</td><td>(scene_channel)</td><td>float32 dask.array-</td><td></td></ch<>		channel_uncert	(scene_channel)	float32 dask.array-	
u10n	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>wind</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td></td></ch<>		wind	(time, scene_across_track)	float32 dask.array	
v10n	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>wind_err</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td>chun 🖹 🍔</td></ch<>		wind_err	(time, scene_across_track)	float32 dask.array	chun 🖹 🍔
sp	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>chiSquareTest1</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td></td></ch<>		chiSquareTest1	(time, scene_across_track)	float32 dask.array	
t2m	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>chiSquareTest2</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td>chun 🖹 🍔</td></ch<>		chiSquareTest2	(time, scene_across_track)	float32 dask.array	chun 🖹 🍔
Ism	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>chiSquareTest3</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td></td></ch<>		chiSquareTest3	(time, scene_across_track)	float32 dask.array	
skt	(time, step, latitude, longitude)	float32 dask.array <ch< td=""><td></td><td>chiSquareTest4</td><td>(time, scene_across_track)</td><td>float32 dask.array</td><td>7</td></ch<>		chiSquareTest4	(time, scene_across_track)	float32 dask.array	7
▼ Attributes:				▼ Attributes:			May
GRIB_edition:	1						
GRIB_centre:	ecmf			title :	Environmental Scene 1		
GRIB_centreDe				comment :	feedhorn channels: h19, v19, v22		
GRIB_subCentre:	0			elevation_offset	0.4		
Conventions :	CF-1.7			azimuth_offset	-0.3		N
institution :	European Centre for Medium-Range Weather						22-
history :	2022-03-11T10:35 GRIB to CDM+CF via cfgrib "/home/mario/Data/Covariance_means/MARS	_api_data/ERA5_data/datasets/pro	files_				·135(

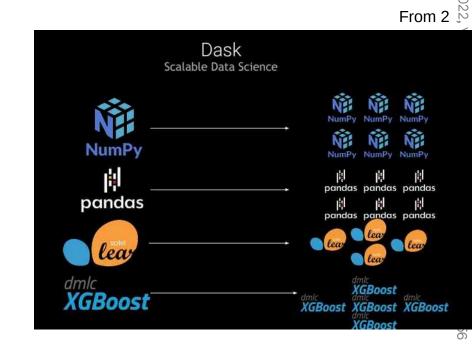
2014UC.grib", "filter_by_keys": {}, "encode_cf": ["parameter", "time", "geography", "verti



Big data, chunks and processing: Nom nom...



- xarray uses Dask¹ under the hood in order to handle big datasets
- Divide and conquer strategy: divide dataset in chunks and process



¹⁾ https://docs.dask.org/en/stable/

²⁾ https://www.nvidia.com/en-us/glossary/data-science/dask/



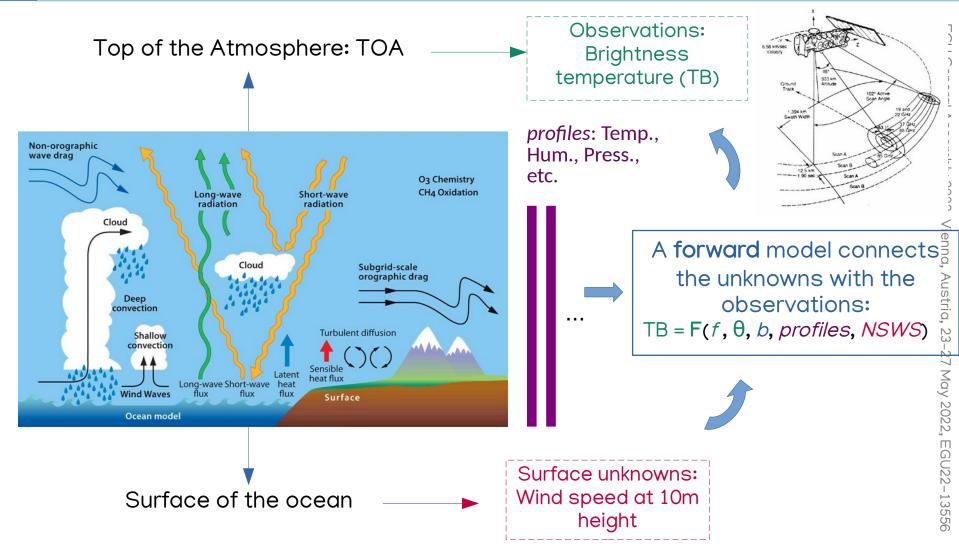
Our application: wind retrieval

- Wind retrievals using optimal estimation and radiometer observations:
 - We use pyOptimalEstimation for performing the retrieval (core computation); open source project (ME contributor).
 - We use pyResample (pyTroll) for re-sampling (when needed).
 - We use xarray + Dask for multi-dimensional labeled datasets handling¹ and high level parallelization².
 - We use RTTOV from NWPSAF as radiative transfer model (i.e. forward model).

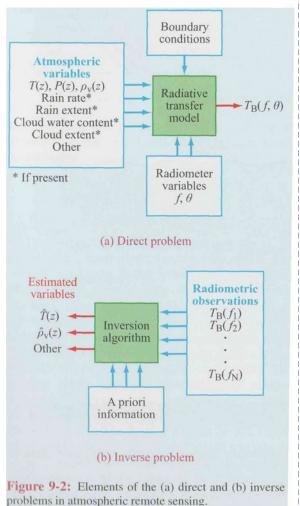
¹⁾ Handling includes Numpy and Pandas native support + Dask chunking



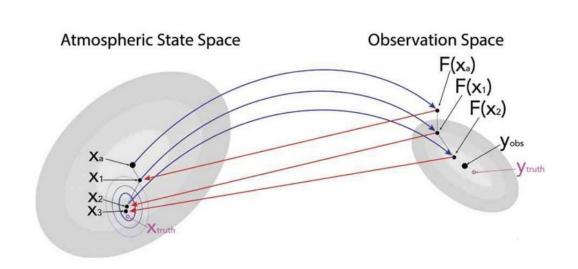
Wind retrievals: Radiative transfer (forward model)



Optimal Estimation (OE): inversion



From *



Estimated Atmospheric state:

$$\mathbf{x}_{i+1} = \mathbf{x}_a + (\mathbf{S}_a^{-1} + \mathbf{K}_i^{\mathrm{T}} \mathbf{S}_e^{-1} \mathbf{K}_i)^{-1} \mathbf{K}_i^{\mathrm{T}} \mathbf{S}_e^{-1} [\mathbf{y} - F(\mathbf{x}_i, \mathbf{b}) + \mathbf{K}_i (\mathbf{x}_i - \mathbf{x}_a)],$$

Forward model

Convergence criteria:

$$(\mathbf{x}_i - \mathbf{x}_{i+1})^{\mathrm{T}} \mathbf{S}_i^{-1} (\mathbf{x}_i - \mathbf{x}_{i+1}) \ll \operatorname{length}(\mathbf{x})$$

Uncertainty of the estimation:

$$\mathbf{S}_{i} = (\mathbf{S}_{i}^{-1} + \mathbf{K}_{i}^{\mathrm{T}} \mathbf{S}_{e}^{-1} \mathbf{K}_{i})^{-1}.$$

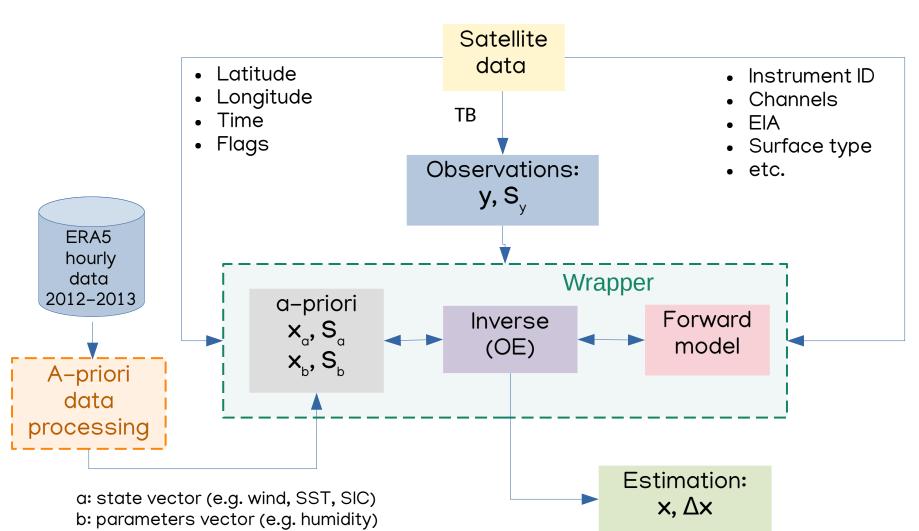
Scheme and equations from [1]

* F. Ulaby, D. Long, "Microwave Radar and Radiometric Remote Sensing", The University of Michigan Press, 2014.

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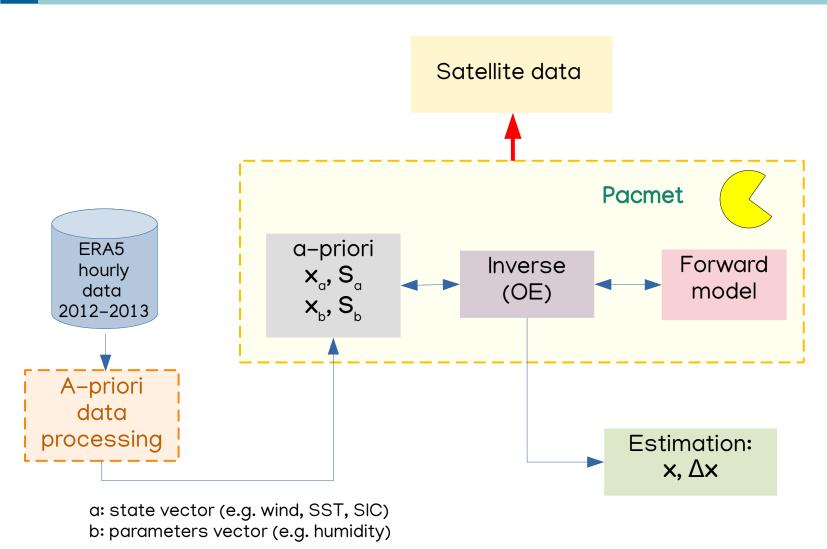
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The OE pipeline:





The OE pipeline:





How: Load in lazy format

xarray.Dataset					
 Dimensions: (time: 45505, scene_across_track: 90, scene_channel: 5) ▼ Coordinates: 					
scene_across	(scene_across_track)	int32	1 5 9 13 17 34		
scene_channel	(scene_channel)	int64	11 12 13 14 15		
time	(time)	datetime64[ns]	2014-09-09 2		
▼ Data variables:					
lat	(time, scene_across_track)	float64	dask.array <chun< th=""><th></th></chun<>		
lon	(time, scene_across_track)	float64	dask.array <chun< th=""><th></th></chun<>		
eia	(time, scene_across_track)	float32	dask.array <chun< th=""><th></th></chun<>		
sft	(time, scene_across_track)	float32	dask.array <chun< th=""><th></th></chun<>		
tb	(time, scene_across_track, scene_channel)	float32	dask.array <chun< th=""><th></th></chun<>		
global_channel	(scene_channel)	int32	dask.array <chun< th=""><th></th></chun<>		
channel_uncert	(scene_channel)	float32	dask.array <chun< th=""><th></th></chun<>		
wind	(time, scene_across_track)	float32	dask.array <chun< th=""><th></th></chun<>		
wind orr	/time come across track)	float22	dack array-chun		



How: what is this?

xarray.Dataset

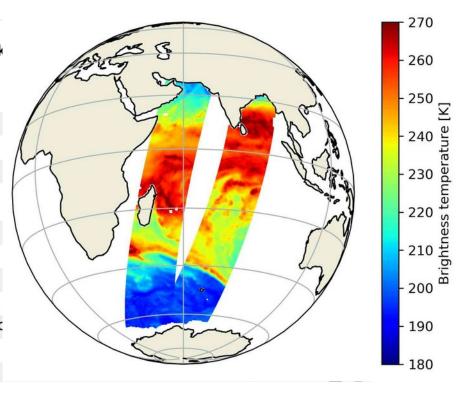
▶ Dimensions: (time: 45505, scene_across_track)

▼ Coordinates:

scene_across	(scene_across_track)
scene_channel	(scene_channel)
time	(time)

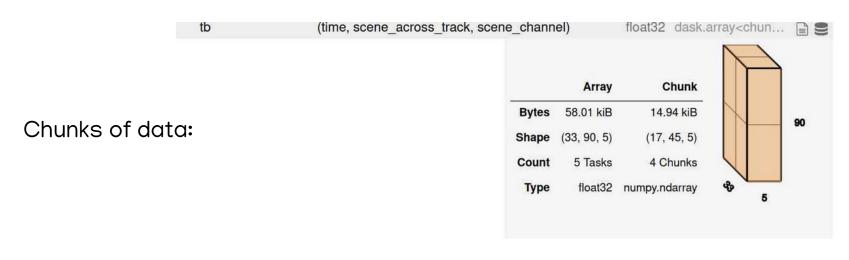
▼ Data variables:

lat	(time, scene_across_track)
lon	(time, scene_across_track)
eia	(time, scene_across_track)
sft	(time, scene_across_track)
tb	(time, scene_across_track, scene_c
global_channel	(scene_channel)
channel uncert	(scene channel)

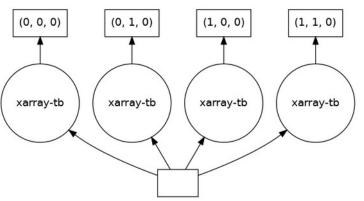




How: chunks and tasks, simple

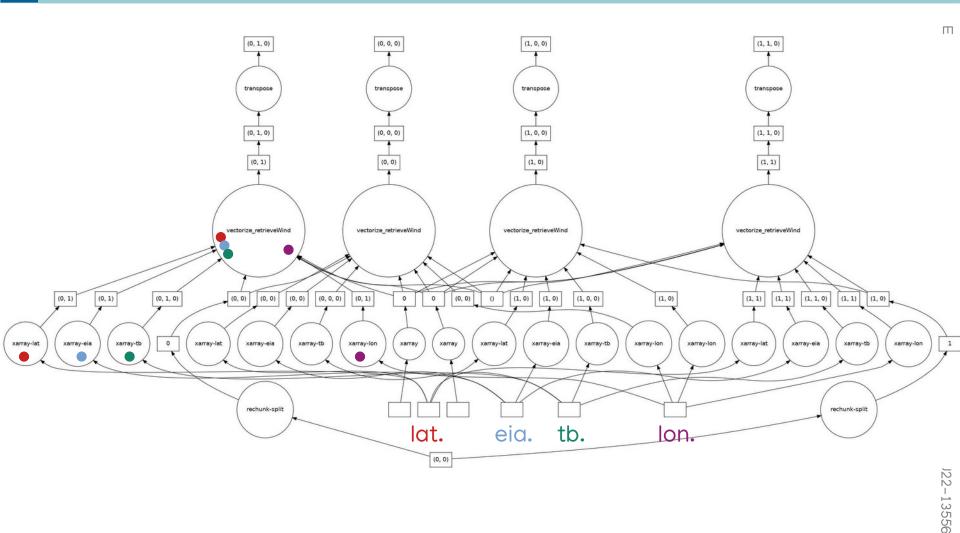


Graph of tasks:



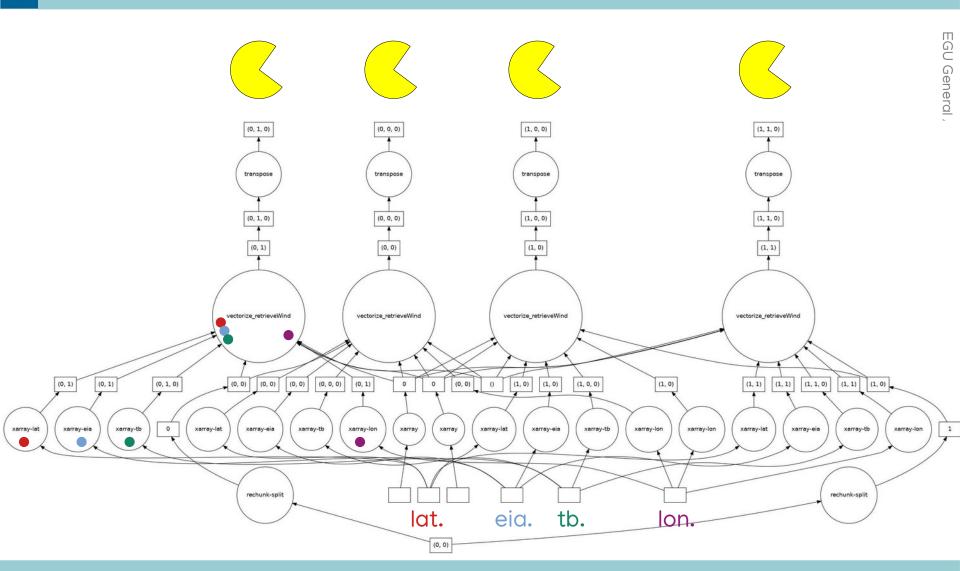


How: retrieval graph of tasks



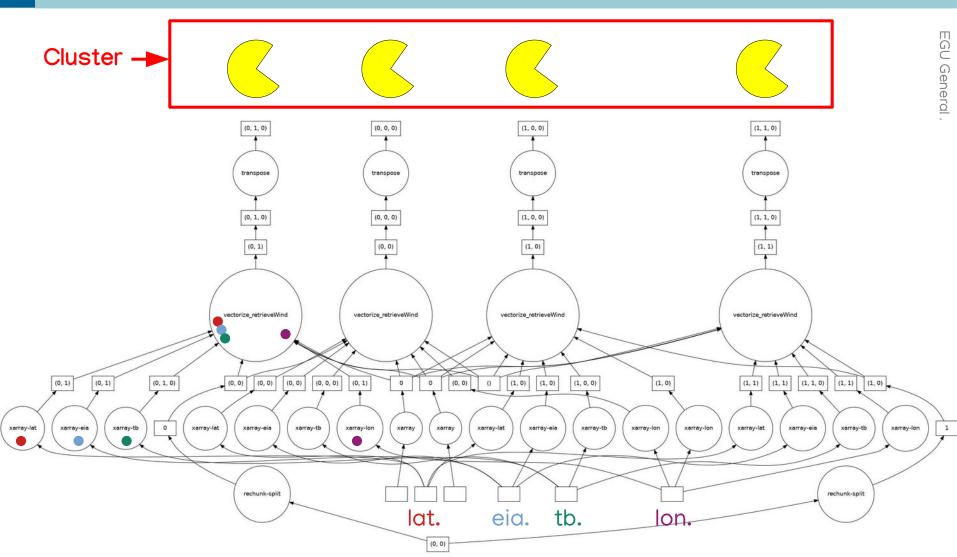


How: tasks scheduled among workers





How: tasks scheduled among workers





How: Computation clusters

- Dask offers a broad spectrum of cluster managers in its API:
 - > LocalCluster (i.e. your computer with all its workers)
 - SSHCluster (i.e. a cluster of computers connected through ssh)
 - CloudProvider (i.e. leveraging cloud native API's)
 - FargateCluster (AWS)
 - Elastic Compute Cloud, EC2 (AWS)
 - Elastic Container Service (AWS)
 - DropletCluster (DigitalOcean)
 - GCPCluster (Google Cloud)
 - AzureVMCluster (Microsoft Azure)



Some results:

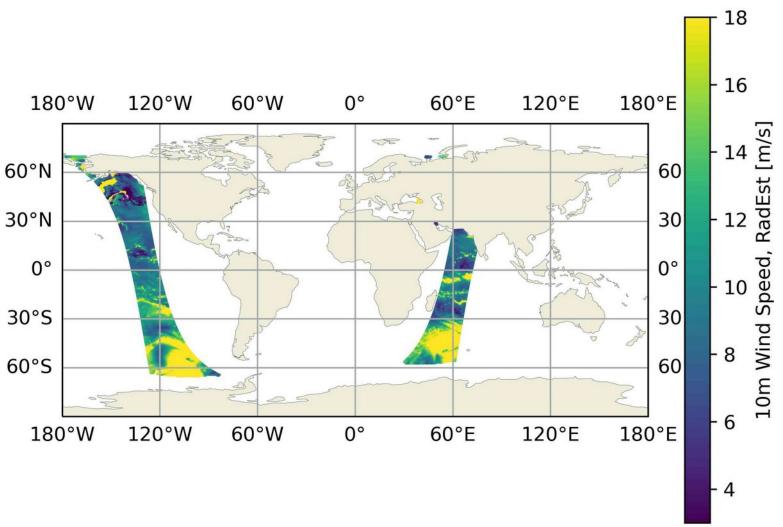
- ➤ Wind retrievals using CMSAF SSMIS (F16) Temperature Brightness (2 hours in September 2014).
- For testing purposes we use a-priori data computed using ERA5:
 - > Mean (x_a , x_b): Climatological mean (2012-2013)
 - > Covariance (S_a , S_b): natural variability in the dataset*.

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Some results: retrieved wind speed





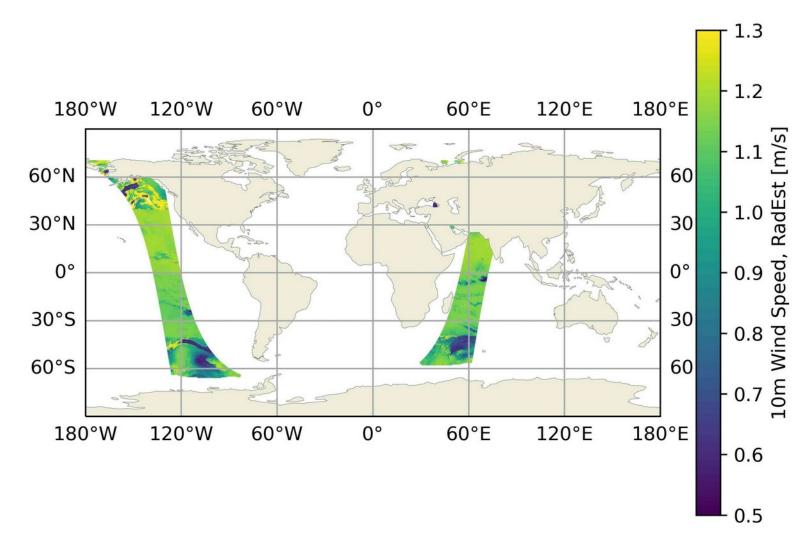


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Some results: uncertainty of retrieval







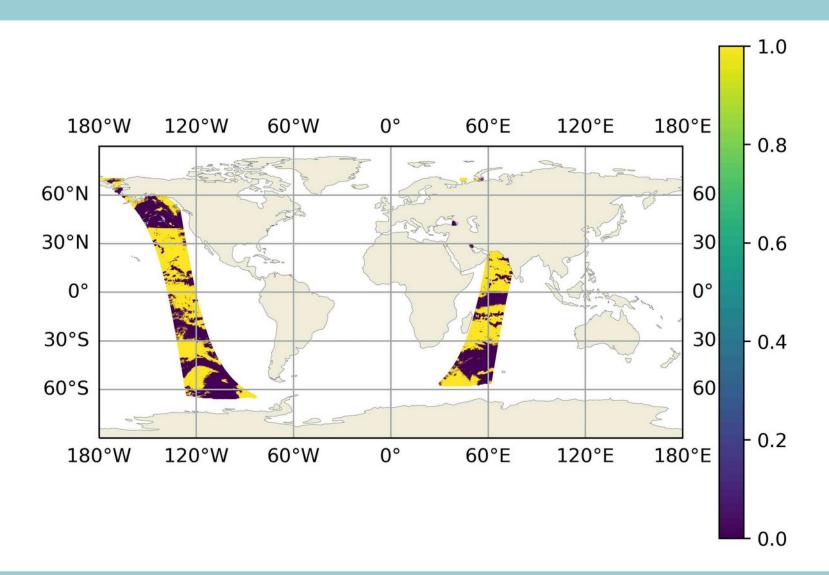


Statistical tests suite

- > It is desirable to have at hand tools to evaluate the quality of the retrievals.
- \succ Rodgers proposed a few diagnostics based on χ^2 testing (e.g. test whether or not a particular vector belongs to a given Gaussian distribution):
 - > T0, y_optimal vs Obs.: $(y_{op} y_{obs})$
 - > T1, Obs. vs y_prior: $(y_{obs} y_{q})$
 - > T2, y_optimal vs y_prior: (y_op y_a)
 - > T3, x_optimal vs x_prior: $(x_{op} x_a)$

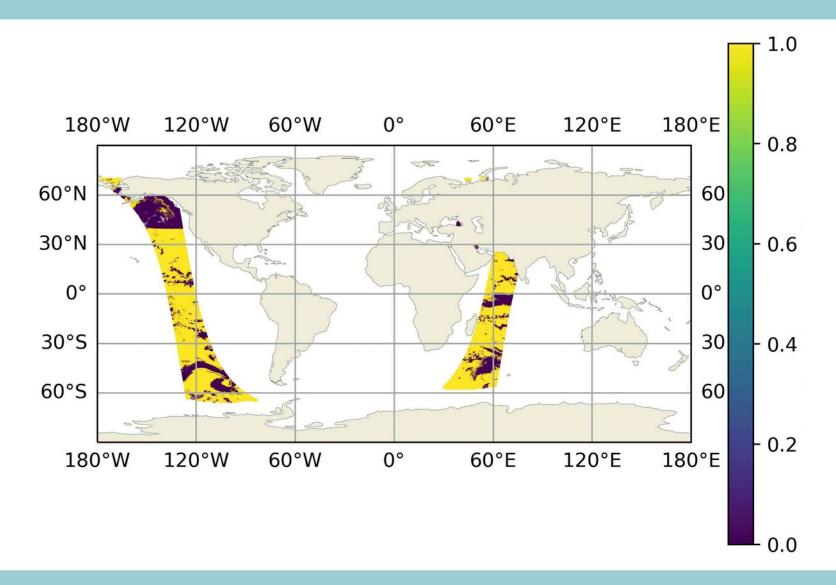


Some results: test (y_{op} - y_{obs})

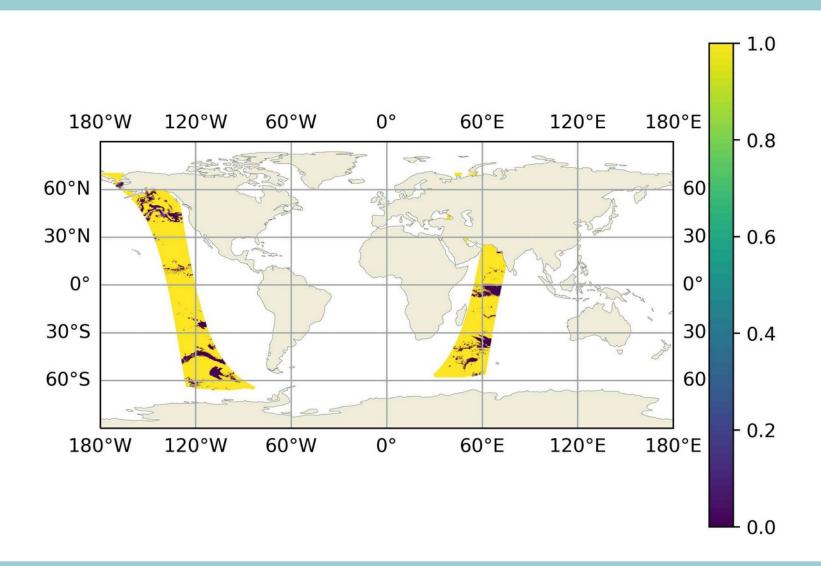


A WA

Some results: test (yobs - ya)

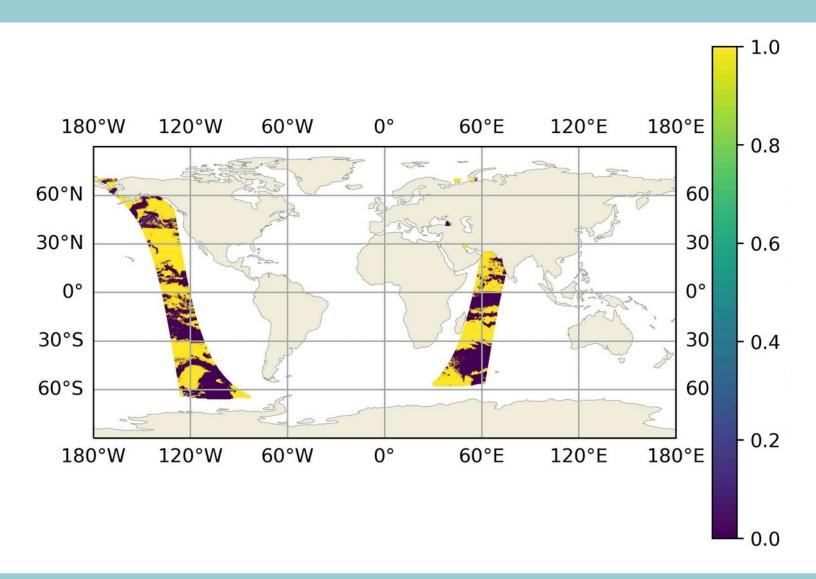


Some results: test (y_{op} - y_a)



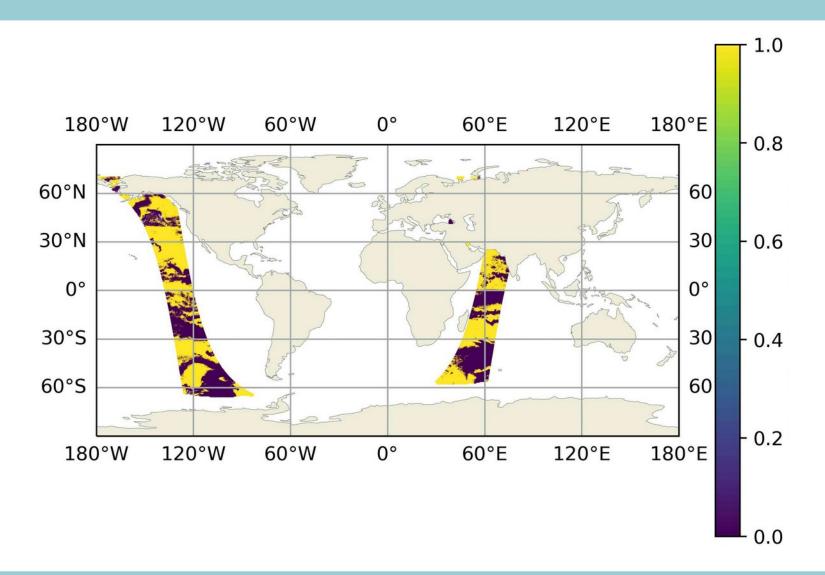


Some results: test (x_{op} - x_a)



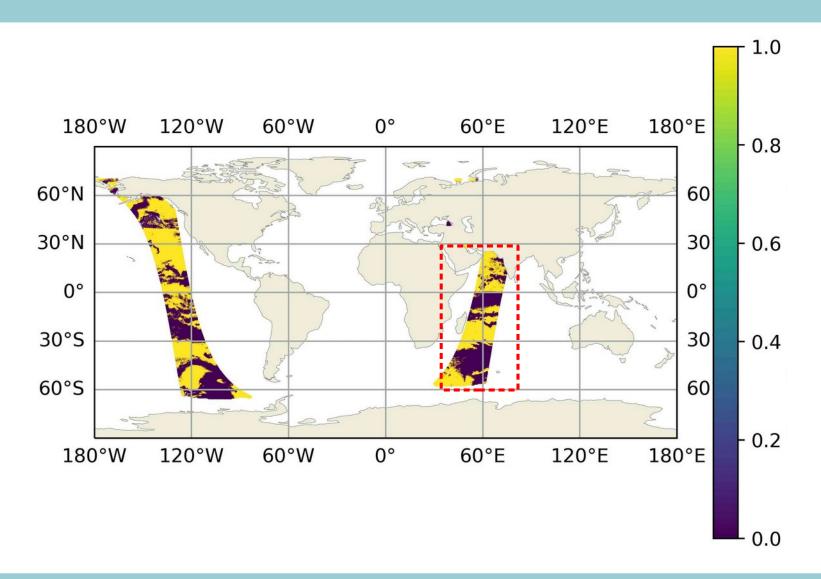


Some results: test (x_{op} - x_a)



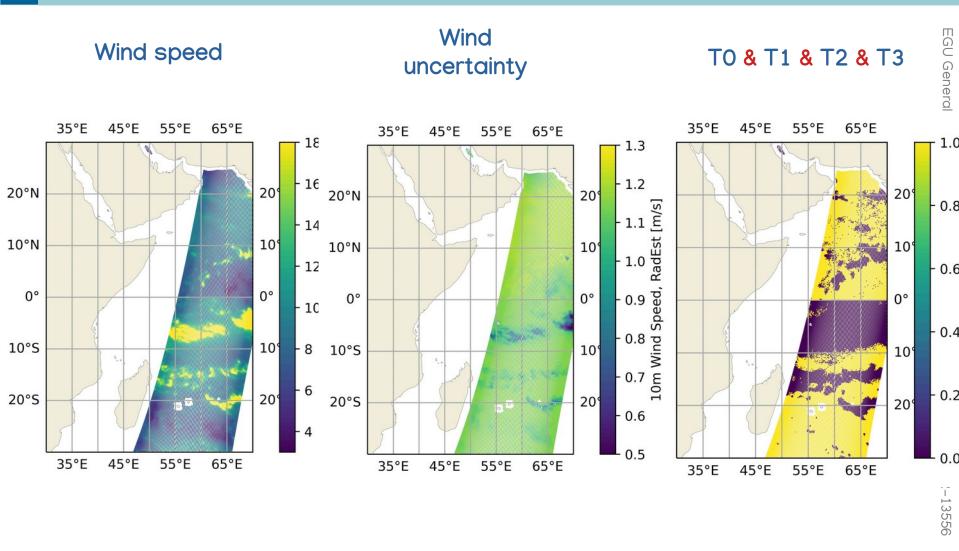


Some results: test (x_{op} - x_a)



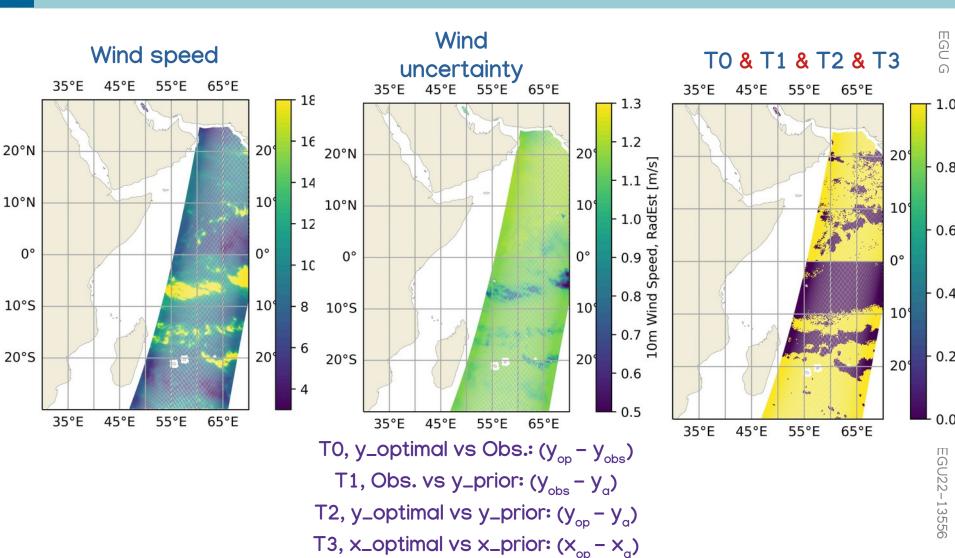


Some results: All pass





Some results: All pass





Work in progress:

> Containerization:

> Pack the whole "app" in a deploy-friendly container > Docker containers.

> Cloud resources:

> What and how to use > AWS.

> A-priori error covariances:

Properly estimate the error variability within the ERA5 dataset (e.g. forecast model error).

> Documentation:

- > Reports
- Markdown (for nicely documented code).



To conclude:

- > A classical physical retrievals scheme was recast using modern Python.
- The Pangeo stack is being actively used in order to facilitate the connection between low level algorithms and high level interfaces.
- > The Pangeo stack provides tools that can be integrated in a satellite observations processing pipeline and opens doors to high performance deployment in a straightforward manner.



References

[1] M. Maahn et al, "Optimal Estimation Retrievals and Their Uncertainties What Every Atmospheric Scientist Should Know", BAMS, Vol. 101, Issue 9, Sept. 2020

[2] C. D. Rodgers, "Inverse Methods for Atmospheric Sounding, Theory and Practice", World Scientific Pub., 2000.



Thanks!



Questions?

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https://github.com/deweatherman