## 06 - Divide and Conquer (part 1)

[KOMS119602] & [KOMS120403]

Design and Analysis of Algorithm (2021/2022)

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# Scheme of divide and conquer (DnC) algorithm

## The principal of divide-and-conquer algorithm

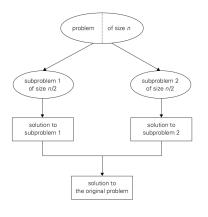
DIVIDE: breaking down the problem into two or more sub-problems that have the same or similar type, until these become simple enough to be solved directly. Ideally, the size of the sub-problems are equal.

CONQUER: solving each of the sub-problems, directly (if the size is small) or recursively (if the size is still big).

COMBINE: combining the solutions to the sub-problems to produce a solution to the original problem.

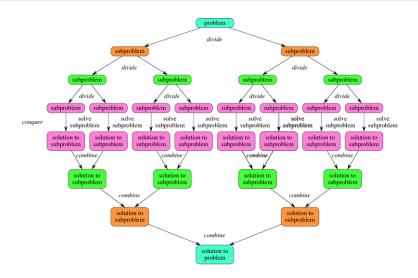
## The principal of divide-and-conquer algorithm

In the most typical case of divide-and-conquer, a problem's instance of size n is divided into two instances of size n/2.



source: book of Anany Levitin

## The principal of divide-and-conquer algorithm



 $source: \ https://cdn.kastatic.org/ka-perseus-images/db9d172fc33b90e905c1213b8cce660c228bb99c.png$ 

## Example of problems solvable by DnC algorithm

- Binary search
- Merge sort
- Quick sort
- Closest pair problem
- Onvex hull problem (haven't discussed yet)
- Matrix multiplication
- Strassen's algorithm
- 8 Karatsuba algorithm for fast multiplication
- Multiplication of two polynomials

## Divide and conquer vs Brute force

**Study case:** sum of array of integers

#### Problem |

Given an array containing n integers  $a_0, a_1, \dots, a_{n-1}$ . Find  $a_0 + a_1 + \dots + a_{n-1}$ .

Brute-force approach? add the element sequentially (one-by-one)

#### Divide-and-conquer:

- If n = 1, then return  $a_0$ ;
- If n > 1, then recursively do the following: divide into two sub-arrays, then compute the sum of each sub-array.

$$a_0 + a_1 + \cdots + a_{n-1} = (a_0 + \cdots + a_{\lfloor n/2 \rfloor - 1}) + (a_{\lfloor n/2 \rfloor} + \cdots + a_{n-1})$$

Which technique is more efficient?



## Divide and conquer vs Brute force

**Study case:** sum of array of integers

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Given an array containing n integers  $a_0, a_1, \dots, a_{n-1}$ . Find  $a_0 + a_1 + \dots + a_{n-1}$ .

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#### Divide-and-conquer:

- If n = 1, then return  $a_0$ ;
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$$a_0 + a_1 + \cdots + a_{n-1} = (a_0 + \cdots + a_{\lfloor n/2 \rfloor - 1}) + (a_{\lfloor n/2 \rfloor} + \cdots + a_{n-1})$$

Which technique is more efficient?

The brute force technique is better in this case.

## Divide and conquer vs Brute force

- DnC is probably the best-known general algorithm design technique.
- Not every divide-and-conquer algorithm is necessarily more efficient than (even) a brute-force solution.
- Often, the time spent on executing the DnC algorithm is significantly smaller than solving a problem by a different method.
- The DnC approach yields some of the most important and efficient algorithms in CS.

## Divide and conquer scheme

end for

10: end if11: end procedure

7:

8:

9: 10:

**Algorithm 1** General scheme of divide-and-conquer

DIVIDECONQUER( $P_i, n_i$ )

```
→ロト→部ト→重ト→重 りの○
```

Combine the solutions of  $P_1, \ldots, P_r$  to solution of P

# **DnC** analysis of time complexity

## Time complexity divide and conquer

$$T(n) = \begin{cases} g(n), & n \leq n_0 \\ T(n_1) + T(n_2) + \cdots + T(n_r) + f(n), & n \geq n_0 \end{cases}$$

- T(n): the time complexity of problem P (of size n)
- g(n): time complexity for SOLVE if n is small (i.e.  $n \le n_0$ )
- $T(n_1) + T(n_2) + \cdots + T(n_r)$ : time complexity to proceed each sub-problem
- f(n): time complexity to DIVIDE the problem and COMBINE the solution of each sub-problem



## Time complexity divide and conquer

An ideal situation is when the DIVIDE operation always produces two sub-problems of size half of the problem.

```
1: procedure DIVIDECONQUER(P: problem, n: integer)
       if n \leq n_0 then
2:
                                                      P is small enough
           Solve P
3:
4:
       else
           DIVIDE to 2 sub-problems P_1, P_2 of size n/2
5:
           DIVIDECONQUER(P_1, n/2)
6:
           DIVIDECONQUER(P_2, n/2)
7:
           Combine the solutions of P_1, P_2 to solution of P
8:
       end if
9.
10: end procedure
```

## Time complexity divide and conquer

If the instance is always divided into two sub-instances at each step, then:

$$T(n) = \begin{cases} g(n), & n \le n_0 \\ 2T(n/2) + f(n), & n \ge n_0 \end{cases}$$

More generally, if the instance is always divided into  $b \ge 1$  instances of equal size, where  $a \ge 1$  instances need to be solved, then the complexity is given by:

$$T(n) = aT(n/b) + f(n)$$

The order of growth of its solution T(n) depends on the values of the constants a and b and the order of growth of the function f(n).

# MinMax Problem: An example of DnC algorithm

## MinMax problem (1)

#### Problem

Given an array A of n integers. Find the min and max of the array simultaneously.

#### Example:

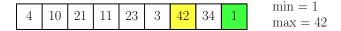


Figure: An array of integers, and the min & max of the array

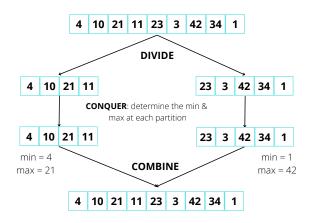
## MinMax problem (2)

### Algorithm 2 MinMax (brute-force)

```
1: procedure MINMAX1(A[0..n-1]: array, n: integer)
         min \leftarrow A[0]
 2:
                                                   Assign the first element as the minimum
         max \leftarrow A[0]
 3:
                                                     Assign the first element as the maximum
         for i \leftarrow 1 to n-1 do
 4:
             if A[i] < \min then
 5:
                  \min \leftarrow A[i]
 6.
 7:
             end if
             if A[i] > max then max \leftarrow A[i]
 8:
             end if
 9:
         end for
10:
11: end procedure
```

## MinMax problem (3)

The scheme of Minmax with divide-and-conquer

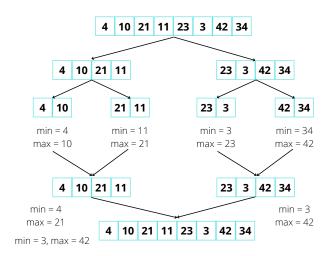


### **Algorithm 3** MinMax (DnC)

```
1: procedure MinMax2(input: A, i, j, output: min, max)
         if i = j then min \leftarrow A[i]; max \leftarrow A[i]
 2:
 3:
         else
 4:
              if i = j - 1 then
                                                                             The array has size 2
                  if A[i] < A[j] then min \leftarrow A[i]; max \leftarrow A[j]
 5:
 6:
                  else min \leftarrow A[i]; max \leftarrow A[i]
 7:
                  end if
 8:
              else
 9.
                  k \leftarrow (i+j) \operatorname{div} 2
                                                          Divide the array in the middle (position k)
10:
                  MINMAX2(A, i, k, min_1, max_1)
11:
                  MINMAx2(A, k + 1, j, min_2, max_2)
12:
                  if min_1 < min_2 then min \leftarrow min_1
13:
                  else min ← min<sub>2</sub>
                  end if
14:
15:
                  if max_1 < max_2 then max \leftarrow max_2
16:
                  else max \leftarrow max_1
17:
                  end if
18:
              end if
19.
         end if
20: end procedure
```

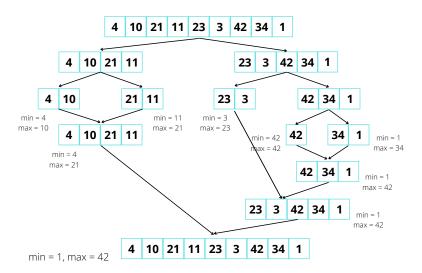
## MinMax problem (5)

#### Example:



## MinMax problem (6)

#### Example:



## MinMax problem (7): Time complexity

Compute the number of comparisons T(n)

$$T(n) = \begin{cases} 0 & \text{if } n = 1\\ 1 & \text{if } n = 2\\ 2 \cdot T(n/2) + 2 & \text{if } n > 2 \end{cases}$$

The explicit formula:

$$T(n) = 2 \cdot T(n/2) + 2$$

$$= 2 \cdot (2 \cdot T(n/4) + 2) + 2 = 4 \cdot T(n/4) + (4+2)$$

$$= 4 \cdot (2 \cdot T(n/8) + 2) + 4 + 2 = 8 \cdot T(n/8) + (8+4+2)$$

$$\vdots$$

$$= 2^{k-1} \cdot 1 + \sum_{i=1}^{k-1} 2^{i}$$

$$= 2^{k-1} + 2^{k} - 2$$

$$= n/2 + n - 2$$

$$= 3n/2 - 2 \in \mathcal{O}(n)$$

## MinMax problem (8): Time complexity

- Brute force MINMAX1: T(n) = 2n 2
- DnC MinMax2: T(n) = 3n/2 2

$$3n/2-2 < 2n-2 \Leftrightarrow \text{ for } n \geq 2$$

The MinMax problem is more efficient to solve with DnC algorithm. But, asymptotically, both algorithms do not differ too much.

## **DnC-based sorting algorithms**

## DnC-based sorting (1)

#### Review

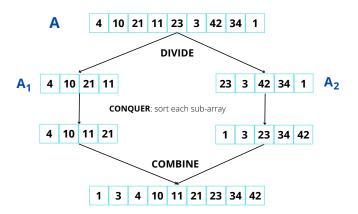
- Sorting problem: Given an ordorable array A[0..n 1] (of size n). The array A is sorted if the elements in A is ordered in an ascending or descending order.
- Recall that the brute-force-based sorting algorithms such as selection sort, bubble sort, and insertion sort have time complexity  $\mathcal{O}(n^2)$ .
- Can we produce a sorting algorithm with a better time complexity using DnC approach?

## DnC-based sorting (2)

#### Idea of DnC-based sorting procedures:

- If the array has size n = 1, then the array is sorted.
- If the array has size n > 1, then divide the array into two sub-arrays, then sort each sub-array.
- Merge the sorted sub-arrays into a sorted array. This is the result of the algorithm.

## DnC-based sorting (3): scheme



#### Algorithm 4 DnC-based Sorting scheme

```
1: procedure DNCSORT(A[0..n-1]: array, n: integer)
       if size(A) = 1 then
2:
3:
            return A
       end if
4.
       DIVIDE(A, A_1, A_2) of size n_1 and n_2 resp.
5:
                                                                   \triangleright n_2 = n - n_1
       DNCSORT(A_1, n_1)
6:
                                                                \triangleright A_1 = A[0..n_1 - 1]
       DNCSORT(A_2, n_2)
7:
                                                               \triangleright A_2 = A[n_1..n-1]
       COMBINE (A_1, A_2, A)
8:
9: end procedure
```

• DIVIDE and COMBINE procedures depend on the problem.

## DnC-based sorting (4)

#### Two approaches of DnC sorting algorithms

- Easy split/hard join
  - The Divide step of the array is computationally easy
  - The Combine step is computationally hard
  - Examples: Merge Sort, Insertion Sort
- Hard split/easy join
  - The **Divide** step of the array is computationally hard
  - The Combine step is computationally easy
  - Examples: Quick Sort, Selection Sort

## DnC-based sorting (5)

#### Example

Given an array A = [4, 12, 3, 9, 1, 21, 5, 1]

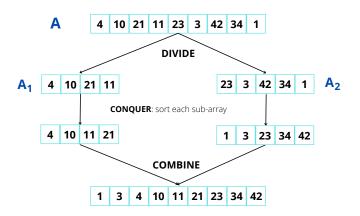
- 1. Easy split/hard join: A is split based on the elements' positions
  - Divide:  $A_1 = [4, 12, 3, 9]$  and  $A_2 = [1, 21, 5, 2]$
  - Sort:  $A_1 = [3, 4, 9, 12]$  and  $A_2 = [1, 2, 5, 21]$
  - Combine: A = [1, 2, 3, 4, 5, 9, 12, 21]
- **2.** Hard split/easy join: A is split based on the elements values
  - Divide:  $A_1 = [4, 2, 3, 1]$  and  $A_2 = [9, 21, 5, 12]$
  - Sort:  $A_1 = [1, 2, 3, 4]$  and  $A_2 = [5, 9, 12, 21]$
  - Combine: A = [1, 2, 3, 4, 5, 9, 12, 21]



## Merge Sort

## Merge Sort (1)

#### Basic idea:



## Merge Sort (2)

#### Algorithm:

Input: array A, integer n
Output: array A sorted

- If n = 1, then A is sorted
- ② If n > 1, then
  - **Divide:** split A into two parts, each of size  $\lfloor n/2 \rfloor$  and  $\lceil n/2 \rceil$
  - Conquer: recursively, implement MERGESORT in each sub-array
  - Merge: combine the sorted sub-arrays into the sorted array A

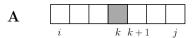
## Merge Sort (3)

#### **Algorithm 5** Merge Sort

```
1: procedure MERGESORT(A: ordorable array, i, j: integer)

    i: starting

    index, j: last index, initialization: i = 0, j = n - 1 (i.e. the whole array A)
         if i = j then
2:
                                                                                     \triangleright length(A) = 1
3:
              return A[i]
         end if
4:
5:
        k \leftarrow (i+j) \operatorname{div} 2
                                                                           Divide the array into two
6:
         MergeSort(A, i, k)
                                                                          Sort the sub-array A[i..k]
         MERGESORT(A, k + 1, j)
7:
                                                                       \triangleright Sort the sub-array A[k+1..i]
         Merge(A, i, k, j)
8:
                                             \triangleright Merge sorted A[i..k] and A[k+1..j] into the sorted A[i..j]
9: end procedure
```



#### **Algorithm 6** "Merge" in MERGESORT

```
1: procedure MERGE(A, i, k, j) \triangleright A[i..k] and A[k+1..j] are sorted (ascending)
 2: output: Array A[i..j] sorted (ascending)
 3: declaration
          B: temporary array to store the merged values
 5: end declaration
 6: p \leftarrow i; q \leftarrow k+1; r \leftarrow i
 7: while p \le k and q \le i do
                                           while the left-array and the right-array are not finished
         if A[p] < A[q] then
 8:
               B[r] \leftarrow A[p] \quad \triangleright \quad B is a temporary array to store the merged array; assign A[p] (of left
 9.
     array) to B
10:
              p \leftarrow p + 1
11:
         else
12:
              B[r] \leftarrow A[q]
                                                                   Assign A[a] (of right array) to B
13:
              q \leftarrow q + 1
     end if
14:
15:
     r \leftarrow r + 1
16: end while
                                                                     \triangleright At this point, p > k or q > j
```

1: **while** p < k **do**  $\triangleright$  If the left-array is not finished, copy the rest of left-array A to B (if any)

2:  $B[r] \leftarrow A[p]$ 

3:  $p \leftarrow p + 1$ 

4:  $r \leftarrow r + 1$ 

5: end while

6: **while**  $q \le j$  **do**  $\triangleright$  If the right-array is not finished, copy the rest of right-array A to B (if any)

7:  $B[r] \leftarrow A[q]$ 

8:  $q \leftarrow q + 1$ 

9:  $r \leftarrow r + 1$ 

10: end while

11: **for**  $r \leftarrow i$  **to** j **do** 

12:  $A[r] \leftarrow B[r]$ 

13: end for

14: return A

15: end procedure

Assign back all elements of B to A

Assign back an elements of B to A

A is in ascending order

Remark. the line numbering of the code is continued from the previous slide: 17, 18, 19, ...

### Merge Sort (4): Procedure MERGE example

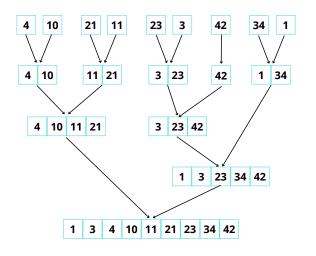


Figure: Example of MERGE procedure

## Merge Sort (5): Procedure MERGESORT example

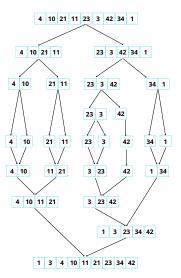


Figure: Example of MERGESORT procedure

## Merge Sort (4): Time complexity (TC)

Computing the TC of Merge Sort is similar to computing the TC of other recursive algorithms.

- The complexity of Merge Sort algorithm is measured from the number of comparisons of the elements in the array that is denoted by T(n).
- The number of comparisons is in  $\mathcal{O}(n)$ , or *cn* for some constant *c*.
  - (Here, we cannot compute exactly how many comparisons that we perform, because the MERGE procedure involves many operations.)
- So T(n) = 2T(n/2) + cn, for some constant c
- Hence:

$$T(n) = \begin{cases} 0, & n = 1 \\ 2T(n/2) + cn, & n > 1 \end{cases}$$



## Merge Sort (4): Time complexity

• The explicit function can be computed by iteratively substituting the function. For simplification, we compute the special case, when  $n = 2^k$  for some integer k.

$$T(n) = 2T(n/2) + cn$$

$$= 2(2T(n/4) + cn) + 3cn$$

$$= 4(2T(n/8) + cn) + 3cn$$

$$\vdots$$

$$= 2^{k}T(n/2^{k}) + kcn$$

Since  $n = 2^k$ , then  $k = \log_2 n$ . This yields:

$$T(n) = n \cdot T(1) + cn \cdot \log_2 n = 0 + cn \cdot \log_2 n \in \mathcal{O}(n \log n)$$

• This shows that Merge Sort has a better complexity  $(\mathcal{O}(n \log n))$  than the brute-force-based sorting algorithms  $(\mathcal{O}(n^2))$ .



# **Recursive Insertion Sort**

Special case of Merge Sort

## Insertion sort (1): Principal

- This is an easy split/hard join-sorting.
- We have seen an iterative version of Insertion Sort algorithm.
   We can also view it in a recursive way: it is a special case of Merge Sort.
- The array is split into two sub-arrays, where the first sub-array only consists of one element, and the second sub-array consists of n-1 elements.



### Insertion sort (2): Pseudocode

### **Algorithm 7** Recursive Insertion Sort

```
1: procedure InsertionSort(A: ordorable array, i, j: integers)
        output: A in ascending order
2:
3:
        if i < j then
                                                                             \triangleright size(A) > 1
             k \leftarrow i
4:
                                                      \triangleright A is split at position i (initialize as i = 0
             INSERTIONSORT(A, i, k)
5:
                                                                  sort the sub-array A[i..k]
             INSERTIONSORT (A, k + 1, j) \triangleright sort the sub-array A[k + 1...j]
6:
             MERGE(A, i, k, j) \triangleright merge the sub-array A[i..k] and A[k+1..j] into A[i..j]
7:
        end if
8:
9: end procedure
```

### Insertion sort (3): Pseudocode

Remark. Since the left sub-array is of size 1, then we may remove the INSERTIONSORT procedure for the left sub-array.

```
Algorithm 8 Insertion Sort
```

```
1: procedure InsertionSort(A: ordorable array, i, j: integers)
        output: A in ascending order
2:
        initialization: i \leftarrow 0, j \leftarrow n-1
3:
4.
        if i < j then
                                                                             \triangleright size(A) > 1
            k \leftarrow i
5:
                                                      \triangleright A is split at position i (initialize as i=0
             INSERTIONSORT(A, k + 1, j) \triangleright sort the sub-array A[k + 1..j]
6:
             MERGE(A, i, k, j) \triangleright merge the sub-array A[i] and A[k+1..j] into A[i..j]
7:
        end if
9: end procedure
```

Remark. The MERGE procedure can be replaced with the 'Insertion method' used in the iterative version.

### Insertion sort (4): Example

Example: Suppose that we want to sort the array A = [4, 10, 21, 11, 23, 3, 42, 34, 1].



Figure: The 'Divide' and 'Conquer' steps

### Insertion sort (5): Example

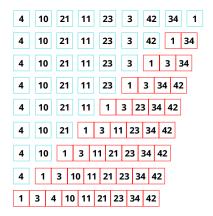


Figure: Applying the MERGE procedure

# Insertion sort (6): Time complexity

The recursive formula for the TC:

$$T(n) = \begin{cases} a, & n = 1 \\ T(n-1) + cn, & n > 1 \end{cases}$$

The explicit formula is obtained by recursive substitution:

$$T(n) = T(n-1) + cn$$

$$= (T(n-2) + c(n-1)) + cn = T(n-2) + (cn + c(n-1))$$

$$= (T(n-3) + c(n-2)) + (cn + c(n-1)) = T(n-3) + (cn + c(n-1) + c(n-2))$$

$$\vdots$$

$$= cn + c(n-1) + c(n-2) + \dots + 2c + a$$

$$= c\left(\frac{1}{2} \cdot (n-1)(n+2)\right)$$

$$= \frac{cn^2}{2} + \frac{cn}{2} + (a-c)$$

$$= \mathcal{O}(n^2) \quad \text{(same as in the iterative version)}$$

# **Quick Sort**

Click here

# **Recursive Selection Sort**

Special case of Quick Sort

## Selection sort (1): Principal

- This is a hard split/easy join-sorting.
- We have seen an iterative version of Selection Sort algorithm. We can also view it in a recursive way, as a special case of Quick Sort.
- The array is split into two sub-arrays, where the first sub-array only consists of one element, and the second sub-array consists of n-1 elements.



Remark. This method follows the Levitin's version of SelectionSort (by looking for the min element). In the other version (if we look for the max element), the right sub-array has size one and the left sub-array has size n-1.

### Selection sort (2): Pseudocode

Remark. Since the left sub-array is of size 1, then we do not need to recursive call INSERTIONSORT for the *left* sub-array.

### Algorithm 9 Recursive Selection Sort

```
1: procedure SelectionSort(A: ordorable array, i, j: integers)
2:
        input: array A[i..j]
       output: A[i...j] in ascending order
3:
       initialization: i \leftarrow 0, j \leftarrow n-1
4:
       if i < j then
5:
                                                                      \triangleright size(A) > 1
            PARTITION(A, i, j) \triangleright Partition the array into sub-arrays of size 1 and n-1
6:
            SELECTIONSORT(A, i + 1, j)
7:
                                                   Sort only the right sub-array
        end if
8:
9: end procedure
```

### Selection sort (3): Pseudocode

Remark. Since the left sub-array is of size 1, then we do not need to recursive call INSERTIONSORT for the *left* sub-array.

#### **Algorithm 10** Partition procedure

```
1: procedure Partition(A: ordorable array, i, j: integers)
                                                                                    \triangleright
   Partition A[i..j] by looking for the minimum element and assign it to A[i]
        idxMin \leftarrow i
2:
        for k \leftarrow i + 1 do to i
3:
            if A[k] < A[idxMin] then
4:
                 idxMin \leftarrow k
5:
            end if
6.
7:
        end for
        SWAP(A[i], A[idxMin])
8:
                                                             Exchange A[i] and A[idxMin]
9: end procedure
```

## Selection sort (4): Example

Suppose that we want to sort the array:

$$A = [4, 10, 21, 11, 23, 3, 42, 34, 1]$$

4	10	21	11	23	3	42	34 1
1	10	21	11	23	3	42	34 4
1	3	21	11	23	10	42	34 4
1	3	4	11	23	10	42	34 21
1	3	4	10	23	11	42	34 21
1	3	4	10	11	23	42	34 21
1	3	4	10	11	21	42	34 23
1	3	4	10	11	21	23	34 42
1	3	4	10	11	21	23	34 42
1	3	4	10	11	21	23	34 42

**X** Unsorted

X Sorted

X Current left sub-array



# Selection sort (4): Time complexity

The recursive formula for the TC:

$$T(n) = \begin{cases} a, & n = 1 \\ T(n-1) + cn, & n > 1 \end{cases}$$

The explicit formula is obtained by substitution (as in Insertion Sort):

$$T(n) = T(n-1) + cn$$

$$= (T(n-2) + c(n-1)) + cn = T(n-2) + (cn + c(n-1))$$

$$= (T(n-3) + c(n-2)) + (cn + c(n-1)) = T(n-3) + (cn + c(n-1) + c(n-2))$$

$$\vdots$$

$$= cn + c(n-1) + c(n-2) + \dots + 2c + a$$

$$= c\left(\frac{1}{2} \cdot (n-1)(n+2)\right)$$

$$= \frac{cn^2}{2} + \frac{cn}{2} + (a-c)$$

$$= \mathcal{O}(n^2) \quad \text{(same as in the iterative version)}$$

### Conclusion '

### What can we conclude from the four sorting algorithms?

Splitting the array into two **balanced** arrays (of size n/2 each) will result in the best algorithm performance (in the case of Merge Sort and Quick Sort, namely  $\mathcal{O}(n \log n)$ ).

While the **unbalanced** split (into 1 element and n-1 elements) results in poor algorithm performance (in the case of Insertion sort and Selection sort, namely  $\mathcal{O}(n^2)$ ).