

Satellite Application Facility for Numerical Weather Prediction

Document NWPSAF-MF-UD-003

Version 7.1 24 January 2012

AAPP DOCUMENTATION DATA FORMATS

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Doc ID: NWPSAF-MF-UD-003

Version: 7.1

Date: 24 January 2012

This documentation was developed within the context of the EUMETSAT Satellite Application Facility on Numerical Weather Prediction (NWP SAF), under the Cooperation Agreement dated 01 December 2006, between EUMETSAT and the Met Office, UK, by one or more partners within the NWP SAF. The partners in the NWP SAF are the Met Office, ECMWF, KNMI and Météo France.

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	Change record								
Version	Date	Author / changed by	Remarks						
4.0	April 03	T.Labrot	Creation for AAPP V4.0						
5.0	April 05	T.Labrot	Update for AAPP V5						
		N.Atkinson							
5.1	May 05	N.Atkinson	Incorporate updates following beta release 5.0						
6.0	June 06	T.Labrot	Update for AAPP V6						
6.1	Oct 07	N.Atkinson	Corrections to 1c/1d satellite IDs						
7.0	Oct 11	T.Labrot	Update for AAPP V7						
		N.Atkinson							
7.1	Jan 12	N.Atkinson	Corrections to MAIA3 variables						

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1. INTRODUCTION

This document describes the formats of the files that the AAPP user needs to do an AAPP run (e.g. an orbital prediction file, raw data level 0 file and a forecast file), and the formats of the files that an entire AAPP run produces. A general description of all the files is also available in the *AAPP software description document*, in the section named "Interfaces". The level 1b format definitions in AAPP closely follow the definitions in section 8 of the NOAA KLM User's Guide (http://www2.ncdc.noaa.gov:80/docs/klm/). Many fields are not initialised in AAPP.

2. FORMAT OF TBUS_YYYYMMDD.TXT FILE

The TBUS bulletins contain the relevant parameters for the navigation of the NOAA satellites. They are issued daily by NOAA. A TBUS bulletin is named tbus_yyyymmdd.txt for a TBUS bulletin received on the date yyyy/mm/dd.

The TBUS bulletin file format is a WMO format. Section 5.1 and Appendix A of the NOAA KLM User's Guide are assigned to TBUS bulletins (http://www2.ncdc.noaa.gov:80/docs/klm/)

(See also information in *tbus.5* (directory *AAPP/man/man5*) and in the paragraph "interfaces" of the *AAPP software description document*).

3. FORMAT OF TWO-LINE ELEMENT (TLE) FILE (TLE_YYYYMMDD_HHMN.TXT)

The TLE files contain the NORAD Two-Line Element sets. They are fully consistent with the SGP4 or SDP4 orbital extrapolation models. They are named tle_yyyymmdd_hhmn.txt, where yyy/mm/dd at time hh:mn is the reception date of the file.

The TLE files are available at http://www.celestrak.com or at http://www.space-track-org.

The TLE files are multi-satellite and contain 2 lines per satellite with several fields.

The TLE format is fully described at http://www.celestrak.com/ in the section "Frequently Asked Ouestions: Two-line Element Set Format".

The format is summarized here:

Line 1:

format

(i1,1x,i5,a1,1x,a8,1x,i2,f12.8,1x,f10.8,2(1x,f6.5,i2),1x,i1,1x,i4,i1)

line1_id - line number of element data tle_satnumber - satellite number (TLE)

tle_satclas - satellite classification

tle_intdes - International designator (3 parts)

year - Epoch last 2 digits of year

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```
day of year - Epoch day of year and fractional portion of day
   tle ftdmm
               - first time derivative of the mean motion
   tle_stdmm - second time derivative of the mean motion
   stdmm exp - ..... exponent
   tle_bstar - BSTAR drag term
   bstar_exp - ..... exponent
   tle_ephtype - ephemeris type
   tle elemnum - element number
   tle chksum1 - check sum line 1
Line 2
 format
 (i1,1x,i5,2(1X,F8.4),1X,F7.7,2(1X,F8.4),1X,F11.8,i5,i1)
   line2 id
              - line number of element data
   tle_satnumber - satellite number (TLE)
   tle_inclin - inclination
   tle rigasc - right ascension of the ascending node
   tle_eccent - eccentricity
   tle_argper - argument of perigee
   tle_meanano - mean anomaly
   tle meanmotion - mean motion
   tle_orbnum - orbit number at epoch
   tle_chksum2 - check sum line 2
```

(See also information in *tle.5* (directory *AAPP/man/man5*) and in the paragraph named "interfaces" of the *AAPP software description document*).

4. FORMAT OF SPOT-5 ELEMENT (SPM) FILE (SPM_YYYYMMDD_HHMN.TXT)

Important note: The use of SPM bulletins for METOP is being phased out. They will not be included for METOP-B, and will be withdrawn from the METOP-A Admin messages once METOP-B is operational. Users should instead migrate to the new Multi-Mission Administrative Messages (MMAM), which contains TLEs for both METOP and NOAA satellites. See the EUMETSAT web site for further information (Home > Data Access > Direct Dissemination > Multi-Mission Administrative Message).

The SPM files contain the EUMETSAT SPOT-5 Element sets. They are fully consistent with the SPOT orbital extrapolation models. They are named spm_yyyymmdd_hhmn.txt, where yyy/mm/dd at time hh:mn is the reception date of the file.

The SPM information is contained in the METOP ADMIN CCSDS packets. They are only valid for METOP satellites. The text file considered here is a human readable version of the binary Admin file.

The format is summarized here:

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All lines preceding the target header line are ignored in the decoding routines:

Target header line:

! Spot parameters epoch time MJD-2000

Line 1, free format:

day - epoch day MJD2000

sec - seconds of day
ms - micro-seconds

ms mero sec

order - order number [1, 2, 3] of bulletin in file

Line 3, free format:

Line 2, free format:

elem - 13 SPOT elements (degrees, days, km)

5. FORMAT OF RAW NOAA DATA LEVEL 0 FILE

The raw NOAA data level 0 format is closely connected to the hardware of each acquisition centre. It encloses unpacked HRPT minor frames. An HRPT minor frame is an array of 11090 words, made of the 10 bits HRPT words right justified in 16 bit words. The HRPT minor frame format is detailed in the NOAA KLM User's Guide – Section 4.1 for NOAA KLM satellites (http://www2.ncdc.noaa.gov:80/docs/klm/) and in the NOAA Polar Orbiter Data User's Guide – section 3.2 for pre-NOAA KLM satellites (http://www2.ncdc.noaa.gov/docs/podug/).

6. FORMAT OF RAW METOP DATA LEVEL 0 FILE

For METOP direct readout, the interface to AAPP is at "EPS Level 0". The user reception system is assumed to have the capability of receiving the METOP AHRPT data stream and converting to EPS Level 0 format as defined by EUMETSAT, with one file for one instrument. The level 0 contains the raw instrument data. It is described in the EUMETSAT documentation:

<u>http://www.eumetsat.int</u> Home → Data & Products → Resources: Document EPS:GGS.SPE.96167.

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7. FORMAT OF HRPT.L1B FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

HRPT.11a format = HRPT.11b format (in HRPT.11a, calibration and location fields are empty).

Header and record length

Header length = record length 22016 bytes (does not respect 1B NOAA size)

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENERAL	INFORMA	ATION
avh_h_siteid	С	3	1	Data set creation site ID
avh_h_blank	С	1	1	ASCII blank
avh_h_l1bversnb	I2	2	1	level 1b format version number
avh_h_l1bversyr	I2	2	1	level 1b format version year
avh_h_l1bversdy	I2	2	1	level 1b format version day of year
avh_h_reclg	I2	2	1	record length
avh_h_blksz	I2	2	1	reserved for block size
avh_h_hdrent	I2	2	1	count of header records in data set
avh_h_filler0	I2	2	3	Unassigned (no value)
avh_h_dataname	С	42	1	data set name
avh_h_prblkid	C	8	1	processing block identification
avh_h_satid	I2	2	1	Spacecraft identification code
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8=NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator
avh_h_instid	I2	2	1	instrument identification
avh_h_datatyp	I2	2	1	data type code

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				(1 = LAC; 2 = GAC; 3 = HRPT)
avh_h_tipsrc	I2	2	1	TIP source code
a in_in_inport	12	_	_	(0 = not applicable; 1 = GAC embedded;
				2 = stored; 3 = third CDA;
				4 = HRPT embedded)
avh_h_startdatajd	I4	4	1	start of data set day count from 00h,1 Jan
avii_ii_startdatajd	14	_	1	1950
avh_h_startdatayr	I2	2	1	start of data set year
Š	I2 I2	2	1	·
avh_h_startdatady		4		start of data set day of year
avh_h_startdatatime	I4	4	1	start of data set UTC time of day in
1 1 11 () 1	T.4	4	1	milliseconds
avh_h_enddatajd	I4	4	1	end of data set day count from 00h,1 Jan
	7.0			1950
avh_h_enddatayr	I2	2	1	end of data set year
avh_h_enddatady	I2	2	1	end of data set day of year
avh_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
avh_h_cpidsyr	I2	2	1	year of Last CPIDS Update
avh_h_cpidsdy	I2	2	1	Day of Year of Last CPIDS Update
avh_h_filler1	I2	2	4	Unassigned (no value)
	D A	ATA SET QU	ALITY	INDICATORS
avh_h_inststat1	I4	4	1	first instrument status
				bit 15 : motor/telemetry $(0 = off; 1 = on)$
				bit 14 : electronics/telemetry
				(0 = off; 1 = on)
				bit 13 : channel 1 status
				(0 = disable; 1 = enable)
				bit 12 : channel 2 status
				(0 = disable; 1 = enable)
				bit 11 : channel 3A status
				(0 = disable; 1 = enable)
				bit 10 : channel 3B status
				(0 = disable; 1 = enable)
				bit 9 : channel 4 status
				(0 = disable; 1 = enable)
				bit 8 : channel 5 status
				(0 = disable; 1 = enable)
avh_h_filler2	12	2	1	
		2 2	1	Unassigned (no value)
avh_h_statchreenb	I2		1	record number of status change
and himstates	T 4	4	1	(if 0, none occurred)
avh_h_inststat2	I4	4	1	second instrument status
1 1 1'	10	2	4	(if previous word is 0, no change)
avh_h_scnlin	I2	2	1	count of scan lines in this data set
avh_h_callocscnlin	I2	2	1	count of calibrated, Earth located scan
				lines in this data set
avh_h_misscnlin	I2	2	1	count of missing scan lines
avh_h_datagaps	I2	2	1	count of data gaps in this data set

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avh_h_okdatafr	I2	2	1	count of data frames without frame sync word errors
avh_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
avh_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in the input data
avh_h_timeseqerr	12	2	1	time sequence error (0 =none; otherwise the record number of the first occurrence)
avh_h_timeseqerrcode	I2	2	1	time sequence error code
avh_h_socclockupind	I2	2	1	socc clock update indicator (0 = none during this orbit; otherwise the record number of the first occurrence)
avh_h_locerrind	I2	2	1	Earth location error indicator (0 = none during this orbit; otherwise the record number of the first occurrence)
avh_h_locerrcode	I2	2	1	Earth location error code
avh_h_pacsstatfield	I2	2	1	PACS status bit field bit 15-3: spare bit 2: pseudo noise (0 = normal data; 1 = P/N data) bit 1: tape direction (0 = time decrementing) bit 0: data mode (0 = test data; 1 = flight data)
avh_h_pacsdatasrc	I2	2	1	PACS data source (0 = unused; 1 = Gilmore; 2 = Wallops; 3 = SOCC)
avh_h_filler3	I4	4	1	Unassigned (no value)
avh_h_spare1	С	8	1	spare (reserved for ingester)
avh_h_spare2	С	8	1	spare (reserved of the decommutation)
avh_h_filler4	I2	2	5	Unassigned (no value)
		CAL	IBRATIO	
avh_h_racalind	12	2	1	ramp/auto calibration indicators bit field bit 5: ramp non-linearity for GAC, LAC, and HRPT channel 5 bit 4: ramp non-linearity for GAC, LAC, and HRPT channel 4 bit 3: ramp non-linearity for GAC, LAC, and HRPT channel 3B bit 2: ramp non-linearity for GAC, LAC, and HRPT channel 3A bit 1: ramp non-linearity for GAC, LAC, and HRPT channel 2 bit 0: ramp non-linearity for GAC, LAC, and HRPT channel 1
avh_h_solarcalyr	I2	2	1	year of most recent solar channel

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				calibration
avh_h_solarcaldy	I2	2	1	day of year of most recent solar channel
avii_ii_solatealay	12	2	1	calibration
avh_h_pcalalgind	I2	2	1	primary calibration algorithm identification
avh_h_pcalalgopt	12 I2	2	1	primary calibration algorithm option
avii_ii_peaiaigopt	12	2	1	selected
avh_h_scalalgind	I2	2	1	secondary calibration algorithm
avii_ii_scalaigilid	12	2	1	identification
avh_h_scalalgopt	I2	2	1	
avii_ii_scalaigopt	12	2	1	secondary calibration algorithm option selected
avh_h_irttcoef	I2	2	6*4	
avii_ii_litticoei	12	2	0.4	IR Target Temperature Conversion Coefficients
				scaling factor of
				avh_h_irttcoef(1,*) = 10^2
				avh_h_irttcoef($(1, ^\circ) = 10^\circ 2$ avh_h_irttcoef($(2, ^\circ) = 10^\circ 5$
				avh_h_irttcoef(2,*) = 10° 3 avh_h_irttcoef(3,*) = 10° 8
				$avh_n = 10^{-8}$ $avh_n = 10^{-11}$
				$avh_n = 10^{-11}$ $avh_n = 10^{-11}$ $avh_n = 10^{-11}$
				$avh_h_irttcoef(6,*) = 10^{-14}$ $avh_h_irttcoef(6,*) = 10^{-17}$
avh_h_filler5	I4	4	2	Unassigned (no value)
		•	_	RE CONVERSION
avh_h_albcnv	<u>I4</u>	4	2*3	albedo conversion
u v n_n_ureen v				order of channels : 1, 2, 3A.
				for nochannel = 1 to 3A:
				10 ¹ x (albedo-radiance nochannel solar
				filtered irradiance in wavelength)
				10 ³ x (albedo-radiance nochannel
				equivalent filter width in wavelength)
avh_h_radtempcnv	<u>I4</u>	4	3*3	radiance to temperature conversion
				order of channels: 3B, 4, 5.
				for nochannel = $3B$ to 5 :
				10^2 x (temperature-radiance nochannel
				central wavenumber Ch3b)
				or 10^3 x (temperature-radiance nochannel
				central wavenumber Ch4,5)
				10^5 x (temperature-radiance nochannel
				constant 1)
				10^6 x (temperature-radiance nochannel
				constant 2)
				Note: prior to v5, constant 1 and constant 2
				contained the temp->radiance constants not
1 1 015			_	radiance->temp
avh_h_filler6	I4	4	3	Unassigned (no value)
1 1 1 1 1 1	-		/IGATION	
avh_h_modelid	C	8	1	Reference Ellipsoid Model ID
1 1 11 1			4	="GRS 80" in the actual version of AAPP
avh_h_nadloctol	I2	2	1	10 x (nadir Earth location tolerance in
				kilometers)

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avh_h_locbit	I2	2	1	Earth location bit field
				bit 0 : attitude error correction ($0 = not$
				corrected)
avh_h_filler7	I2	2	1	Unassigned (no value)
avh_h_rollerr	I2	2	1	10 ³ x (constant roll attitude error in
				degrees)
avh_h_pitcherr	I2	2	1	10 ³ x (constant pitch attitude error in
				degrees)
avh_h_yawerr	I2	2	1	10 ³ x (constant yaw attitude error in
				degrees)
avh_h_epoyr	I2	2	1	epoch year for orbit vector
avh_h_epody	I2	2	1	day of epoch year for orbit vector
avh_h_epotime	I4	4	1	Epoch UTC Time of day in milliseconds
				for Orbit Vector
avh_h_smaxis	I4	4	1	10^5 x (semi-major axis in kilometers)
avh_h_eccen	I4	4	1	10^8 x (eccentricity)
avh_h_incli	I4	4	1	10^5 x (inclination in degrees)
avh_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
avh_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending
				node in degrees)
avh_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
avh_h_xpos	I4	4	1	10^5 x (position vector x component in
				kilometers)
avh_h_ypos	I4	4	1	10^5 x (position vector y component in
				kilometers)
avh_h_zpos	I4	4	1	10^5 x (position vector z component in
				kilometers)
avh_h_xvel	I4	4	1	10^8 x (velocity vector x-dot component
				in kilometers/second)
avh_h_yvel	I4	4	1	10^8 x (velocity vector y-dot component
				in kilometers/second)
avh_h_zvel	I4	4	1	10 ⁸ x (velocity vector z-dot component
				in kilometers/second)
avh_h_earthsun	I4	4	1	10^6 x (Earth/sun distance ratio)
avh_h_filler8	I4	4	4	Unassigned (no value)
	ANA		1	CONVERSION
avh_h_pchtemp	I2	2	5	patch temperature coef
avh_h_reserved1	I2	2	1 1	(reserved) Unassigned (no value)
avh_h_pchtempext	I2	2	5	patch temperature extended coef.
avh_h_reserved2	I2	2	1 -	(reserved) Unassigned (no value)
avh_h_pchpow	I2	2	5	patch power coef
avh_h_reserved3	I2	2	1	(reserved) Unassigned (no value)
avh_h_rdtemp	I2	2	5	radiator temperature coef.
avh_h_reserved4	I2	2	1	(reserved) Unassigned (no value)
avh_h_bbtemp1	I2	2	5	black body temperature 1 coef.
avh_h_reserved5	I2	2	1	(reserved) Unassigned (no value)
avh_h_bbtemp2	I2	2	5	black body temperature 2 coef.

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avh_h_reserved6	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bbtemp3	I2	2	5	black body temperature 3 coef.		
avh_h_reserved7	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bbtemp4	I2 I2	$\frac{2}{2}$	5	black body temperature 4 coef.		
-	I2	2		<i>y</i> 1		
avh_h_reserved8	I2 I2		5	(reserved) Unassigned (no value)		
avh_h_eleccur		2		electronics current coef.		
avh_h_reserved9	I2	2	1	(reserved) Unassigned (no value)		
avh_h_motorcur	I2	2	5	motor current coef.		
avh_h_reserved10	I2	2	1	(reserved) Unassigned (no value)		
avh_h_earthpos	I2	2	5	earth shield position coef.		
avh_h_reserved11	I2	2	1	(reserved) Unassigned (no value)		
avh_h_electemp	I2	2	5	electronics temperature coef.		
avh_h_reserved12	I2	2	1	(reserved) Unassigned (no value)		
avh_h_chtemp	I2	2	5	cooler housing temperature coef.		
avh_h_reserved13	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bptemp	I2	2	5	baseplate temperature coef.		
avh_h_reserved14	I2	2	1	(reserved) Unassigned (no value)		
avh_h_mhtemp	I2	2	5	motor housing temperature coef.		
avh_h_reserved15	I2	2	1	(reserved) Unassigned (no value)		
avh_h_adcontemp	I2	2	5	A/D converter temperature coef.		
avh_h_reserved16	I2	2	1	(reserved) Unassigned (no value)		
avh_h_d4bvolt	I2	2	5	detector #4 bias voltage coef.		
avh_h_reserved17	I2	2	1	(reserved) Unassigned (no value)		
avh_h_d5bvolt	I2	2	5	detector #5 bias voltage coef.		
avh_h_reserved18	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bbtempchn3B	I2	2	5	black body temperature channel 3B coef.		
avh h reserved19	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bbtempchn4	I2	2	5	black body temperature channel 4 coef.		
avh_h_reserved20	I2	2	1	(reserved) Unassigned (no value)		
avh_h_bbtempchn5	I2	2	5	black body temperature channel 5 coef.		
avh_h_reserved21	12	2	1	(reserved) Unassigned (no value)		
avh_h_refvolt	I2	2	5	reference voltage coef.		
avh_h_reserved22	12	2	1	(reserved) Unassigned (no value)		
FILLER						
avh_h_filler9	I2	2	10664	filler bytes to equal data record length		
		_	10001	Unassigned (no value)		
i .			I			

One Data Record for one AVHRR scan line

Name in AAPP code	Type	Word Size in byte	Number of words	Meaning
SCAN LINE INFORMATION				
avh_scnlin	I2	2	1	Scan line number

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zero) bit 24: (1 = frame sync previously dropped lock) bit 23: (1 = flywheeling detected during this frame) bit 22: (1 = bit slippage detected during this frame) bit 9: tip parity in first minor frame bit 8: tip parity in second minor frame bit 7: tip parity in third minor frame bit 6: tip parity in fourth minor frame bit 5: tip parity in fifth minor frame bit 4: (1 = reflected sunlight detected channel 3B) bit 3: (1 = reflected sunlight detected channel 4) bit 2: (1 = reflected sunlight detected channel 5) bit 1: (1 = resync occurred on this frame) bit 0: (1 = pseudo noise occurred on this frame) avh_scnlinqual 14 4 1 Scan line quality flags	avh_scnlinyr	I2	2	1	Scan line year
avh_senlinbit 14	avh_scnlindy	I2	2	1	Scan line day of year
avh_senlinbit 12	avh_clockdrift	I2	2	1	satellite clock drift delta in milliseconds
bit 15 : (0 = ascending data; 1 = descending data) bit 14 : (1 = scan time corrected for clock drift) bit 13 : (1 = Earth location corrected for TIP attitude) bit 0 : channel 3 select (0 = 3A; 1 = 3B) avh_filler0 12 2 5 Unassigned (no value) QUALITY INDICATORS integer avh_qualind 14 4 1 quality indicator bit field bit 31 : (1 = do not use data for product generation) bit 30 : (1 = time sequence error detected in this frame) bit 29 : (1 = data gap precedes this frame) bit 28 : (1 = insufficient data for calibration) bit 27 : (1 = Earth location data not available) bit 26 : (1 = sync lock dropped during this frame) bit 25 : (1 = frame sync word error greater than zero) bit 24 : (1 = frame sync previously dropped lock) bit 23 : (1 = flywheeling detected during this frame) bit 25 : (1 = bit slippage detected during this frame) bit 25 : (1 = pray in first minor frame bit 8 : tip parity in fourth minor frame bit 6 : tip parity in fourth minor frame bit 6 : tip parity in fourth minor frame bit 6 : tip parity in fourth minor frame bit 6 : tip parity in fifth minor frame bit 6 : tip parity in fifth minor frame bit 6 : tip parity in fifth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 7 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 7 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 7 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame bit 6 : tip parity in furth minor frame	avh_scnlintime	I4	4	1	Scan line UTC time of day in milliseconds
avh_filler0 avh_filler0 avh_filler0 12 2 5 Unassigned (no value) QUALITY INDICATORS integer avh_qualind 14 1 4 1 quality indicator bit field bit 31: (1 = do not use data for product generation) bit 30: (1 = time sequence error detected in this frame) bit 29: (1 = data gap precedes this frame) bit 29: (1 = lath location data not available) bit 26: (1 = sync lock dropped during this frame) bit 25: (1 = frame sync word error greater than zero) bit 24: (1 = frame sync previously dropped lock) bit 23: (1 = flywheeling detected during this frame) bit 22: (1 = bit slippage detected during this frame) bit 20: (1 = parity in first minor frame bit 6: tip parity in first minor frame bit 6: tip parity in fourth minor frame bit 5: tip parity in firth minor frame bit 5: tip parity in firth minor frame bit 5: (1 = reflected sunlight detected channel 3B) bit 3: (1 = reflected sunlight detected channel 4) bit 2: (1 = reflected sunlight detected channel 5) bit 1: (1 = resync occurred on this frame) bit 0: (1 = pseudo noise occurred on this frame) bit 0: (1 = pseudo noise occurred on this frame) bit 0: (1 = pseudo noise occurred on this frame) bit 0: (1 = pseudo noise occurred on this frame)	avh_scnlinbit	I2	2	1	bit 15 : (0 = ascending data; 1 = descending data) bit 14 : (1 = scan time corrected for clock drift) bit 13 : (1 = Earth location corrected for TIP
avh_filler0 12 2 5 Unassigned (no value) QUALITY INDICATORS quality indicator bit field bit 31 : (1 = do not use data for product generation) bit 30 : (1 = time sequence error detected in this frame) bit 29 : (1 = data gap precedes this frame) bit 28 : (1 = insufficient data for calibration) bit 27 : (1 = Earth location data not available) bit 26 : (1 = sync lock dropped during this frame) bit 23 : (1 = frame sync word error greater than zero) bit 23 : (1 = frame sync previously dropped lock) bit 23 : (1 = bit slippage detected during this frame) bit 22 : (1 = bit slippage detected during this frame) bit 9 : tip parity in first minor frame bit 8 : tip parity in second minor frame bit 9 : tip parity in fourth minor frame bit 4 : (1 = reflected sunlight detected channel 38					
integer avh_qualind 14 4 1 quality indicator bit field bit 31 : (1 = do not use data for product generation) bit 30 : (1 = time sequence error detected in this frame) bit 29 : (1 = data gap precedes this frame) bit 28 : (1 = insufficient data for calibration) bit 27 : (1 = Earth location data not available) bit 26 : (1 = sync lock dropped during this frame) bit 25 : (1 = frame sync word error greater than zero) bit 24 : (1 = frame sync previously dropped lock) bit 23 : (1 = flywheeling detected during this frame) bit 22 : (1 = bit slippage detected during this frame) bit 9 : tip parity in first minor frame bit 8 : tip parity in second minor frame bit 7 : tip parity in firth minor frame bit 6 : tip parity in firth minor frame bit 5 : tip parity in fifth minor frame bit 4 : (1 = reflected sunlight detected channel 38) bit 3 : (1 = reflected sunlight detected channel 4) bit 2 : (1 = respected sunlight detected channel 5) bit 1 : (1 = respected sunlight detected channel 5) bit 1 : (1 = respected sunlight detected channel 6) bit 0 : (1 = pseudo noise occurred on this frame) bit 0 : (1 = pseudo noise occurred on this frame) bit 0 : (1 = pseudo noise occurred on this frame)	avh_filler0	I2	2	5	·
integer avh_qualind I4 I4 I4 I4 I4 I4 I4 I4 I4 I			QUALIT	TY INDIC	
avh_scnlinqual I4 4 1 Scan line quality flags	integer avh_qualind	I4			quality indicator bit field bit 31: (1 = do not use data for product generation) bit 30: (1 = time sequence error detected in this frame) bit 29: (1 = data gap precedes this frame) bit 28: (1 = insufficient data for calibration) bit 27: (1 = Earth location data not available) bit 26: (1 = sync lock dropped during this frame) bit 25: (1 = frame sync word error greater than zero) bit 24: (1 = frame sync previously dropped lock) bit 23: (1 = flywheeling detected during this frame) bit 22: (1 = bit slippage detected during this frame) bit 9: tip parity in first minor frame bit 8: tip parity in second minor frame bit 7: tip parity in third minor frame bit 6: tip parity in fourth minor frame bit 5: tip parity in fifth minor frame bit 4: (1 = reflected sunlight detected channel 3B) bit 3: (1 = reflected sunlight detected channel 4) bit 2: (1 = resync occurred on this frame) bit 0: (1 = pseudo noise occurred on this
	avh_scnlinqual	I4	4	1	

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				bit 31-24: spare bit 23: time field is bad but can probably be inferred from the previous good time bit 22: time field is bad and can't be inferred from the previous good time bit 21: this record starts a sequence that is inconsistent with previous time (i.e., there is a time discontinuity).this may or may not associated with a spacecraft clock update.(see bit 26 above) bit 20: start of a sequence that apparently repeats scan times that have been previously accepted. bit 19-16: spare Calibration Problem Code (all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap bit 13: scan line was not calibrated because of bad or insufficient PRT data bit 12: scan line was calibrated but with marginal PRT data bit 11: some uncalibrated channels on this scan (see channel indicators) bit 10: spare bit 09: spare bit 09: spare bit 09: spare bit 06: Earth location Problem Code (all bits set to 0 implies the earth location was normal) bit 07: not Earth located because of bad time bit 06: Earth location questionable because of questionable time code (see time problem flags above) bit 05: Earth location questionable only marginal agreement with reasonableness check bit 04: Earth location questionable fails reasonableness check bit 03-00: spare
avh_calqual	I2	2	3	calibration quality flags order of channels : 3B, 4, 5.

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			ı	
				bit 7: this channel is not calibrated
				bit 6 : this channel is calibrated but
				questionable
				bit 5 : not good blackbody count for scan line
				bit 4 : not good space view counts for scan
				line
				bit 3 : insufficient PRT data
				bit 2 : some bad blackbody view counts for
				this line
				bit 1 : some bad space view counts for this
				line
				bit 0 : some bad PRT data
avh_cbiterr	I2	2	1	count of bit errors in frame sync
avh_filler1	I4	4	2	Unassigned (no value)
avii_iiiici i	17	CALIBRAT		,
avh calvis	I4	4	5*3*3	Calibration coeff for the visible channel 1
avii_caivis	14	4	3.3.3	
				3 samples of coefficients:
				First index (i=1): operational set
				Second index (i=2): test set
				Third index (i=3): prelaunch set
				index number i:
				1: 10^10 x (slope 1)
				2 10^7 x (intercept 1)
				3 10^10 x (slope 2)
				4 10^7 x (intercept 2)
				5 intersection
				Calibration coeff for the visible channel 2
				The same 3 samples of coefficients
				Calibration coeff for the visible channel 3A
				The same 3 samples of coefficients
				The same 3 samples of coefficients
				Note: Because the "slope 2" for channel 3A
				can exceed the size of a signed 4-byte integer,
				from AAPP v7 onwards the software treats this
				as an unsigned integer, i.e. if it is negative the
				user should apply the 10^{-10} scaling and add
				11.
avh_calir	I4	4	3*2*3	0.4294967296 to the resulting slope value. Calibration coefficients for the IR channels
avii_caiii	14	4	3.7.2	
				Order of the channels: 3B, 4, 5
				2 samples of coefficients: operational set, test
				set
				Case 1. Only for the CMS and for data hafare
				Case 1: Only for the CMS and for data before
				the 27 January 1999 12 UTC (for archive data)
				10 ⁶ x (IR calibration nochannel coefficient 1,

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				operational)
				10 ⁶ x (IR calibration nochannel coefficient 2,
				operational)
				10 ⁶ x (IR calibration nochannel coefficient 3,
				operational)
				10 ⁶ x (IR calibration nochannel coefficient 1,
				test)
				10 ⁶ x (IR calibration nochannel coefficient 2,
				test)
				10 ⁶ x (IR calibration nochannel coefficient 3,
				test)
				If not case 1:
				10^9 x (IR calibration nochannel coefficient 1,
				operational)
				10 ⁶ x (IR calibration nochannel coefficient 2,
				operational)
				10 ⁶ x (IR calibration nochannel coefficient 3,
				operational)
				10^9 x (IR calibration nochannel coefficient 1,
				test)
				10 ⁶ x (IR calibration nochannel coefficient 2,
				test)
				10 ⁶ x (IR calibration nochannel coefficient 3,
				test)
avh_filler2	I4	4	3	the exponents of the IR calibration
uvii_iiiiei2	1.	·		coefficients.
				In AAPP, in the case 1 defined in the previous
				element, avh_filler2(1)=6
				avh_filler2(1)=6
				avh_filler2(1)=6
				in the case 1 defined in the previous
				element, avh_filler2(1)=9
				avh_filler2(1)=6
				$avh_filler2(1)=0$ $avh_filler2(1)=6$
		TAT A		
avila mayyetat	Τ.4		VIGATIO	
avh_navstat	I4	4	1	Navigation Status Bit Field
				bits 31-17: zero fill
				bit 16: Earth location corrected for TIP Euler
				Angles
				bits 15 - 12: Earth location indicator
				(0 = Earth location available;
				1 = user ephemeris files greater than 24
				hours old;
				2 = no Earth location available)
				bits 11 - 8: spacecraft attitude control
				(0 = operating in YGC or NOMINAL mode;
				1 = operating in another mode
	1	i		

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				2 = attitude exceeds nominal tolerance;
				3 = both 1 and 2)
				,
				bits 7 - 4: attitude SMODE
				(0 = NOMINAL mode;
				1 = rate nulling mode;
				2 = YGC mode;
				3 = search mode;
				4 = coast mode
				bits 3 - 0: attitude PWT1P\$AC
				(0 = NOMINAL mode/no test;
				1 = yaw axis test in progress;
				2 = roll axis test in progress;
				3 = pitch axis test in progress)
avh_attangtime	I4	4	1	Time associated with TIP Euler
				angles(seconds)
avh_rollang	I2	2	1	10^3xRoll Angle in Degrees
avh_pitchang	I2	2	1	10^3xPitch Angle in Degrees
avh_yawang	I2	2	1	10 ³ xYaw Angle in Degrees
avh_scalti	I2	2	1	10 x Spacecraft Altitude (MSL) in km in this
				scan line.
avh_ang	I2	2	3*51	set of 3 angles in degrees for point 25 to point
_				2025 every 40 points
				first angle: 10 ² x (solar zenith angle)
				second angle: 10 ² x (satellite zenith angle)
				third angle: 10^2 x (relative azimuth angle)
avh_filler3	I2	2	3	Unassigned (no value)
avh_pos	I4	4	2*51	lat/lon pair in degrees for point 25 to point
_1				2025 every 40 points
				first : 10 ⁴ x (latitude)
				second: 10^4 x (longitude)
				(North latitude and East longitude are positive)
avh filler4	I4	4	2	Unassigned (no value)
_	H	RPT MINOR	FRAME '	TELEMETRY
avh_telem	I2	2	103	telemetry data (HRPT minor frame format)
_				it corresponds to the 103 first 10 bit words
				from HRPT. They are packed three (10 bit)
				words in four bytes, right justified.
avh_filler5	I2	2	1	Unassigned (no value)
		AVHRR	SENSOR	
avh_hrpt or avh_video	I2	2	5*2048	Sensor Data, Band Interleaved by Pixel (BIP)
win_inpror win_indo		_	2 20.0	set of 5 channels every point
avh_filler6	I4	4	2	Unassigned (no value)
	l l			MAT SPECIFICATION BUT IT KEEPS THE
				DIGITAL TELEMETRY STRUCTURE
TODDIDILITI	J DUM)	TIP MINOI		
avh_tipmfhd	I2	2	7*5	the following sequence is repeated 5 times :
avii_upiiiiiu	12	2	' 3	words 1 to 3:
				bit 47-28 : TIP minor frame sync
				on 47-28. THE minior frame sync

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				bit 27-24 : satellite address
				bit 23 : command verification status
				bit 22-21 : TIP status
				bit 20-18 : TIP major frame counter
				bit 17-09 : dwell mode address
				bit 08-00 : TIP minor frame counter
				word 4 : command verification
				words 5 to 7:
				bit 47-40: 3.2 second digital B subcom1
				bit 39-32 : 32 second analog subcom
				bit 31-24: 16 second analog subcom
				bit 23-16: 1 second analog subcom
				bit 15-08: 3.2 second digital B subcom 2
				bit 07-00:16 second analog subcom 2
		CPU	TELEME	TRY
avh_cputel	C	6	2*5	
equivalent to				the following sequence is repeated 5 times :
avh_icputel	I2	2	6*5	first: CPU-A telemetry (words TIP 46-51)
				second : CPU-B telemetry (words TIP 96-101)
avh_filler7	I2	2	67	Unassigned (no value)

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8. <u>DIFFERENCES BETWEEN THE HRPT.L1B FORMAT OF NOAA AND</u> THE HRPT.L1B FORMAT OF AAPP

The comparison was done with:

- HRPT.11b format of NOAA version: NOAA KLM user's guide after amendments of September 24, 2001
- HRPT.11b format of NOAA version: AAPP version .3.3
- No change of HRPT.11b format between the AAPP version 3.3 and the AAPP version 4.

The first difference between AAPP HRPT 11b and NOAA HRPT 11b is:

AAPP has no missing record. It fills records even if scan lines are missing.

NOAA HRPT 11b can have missing records (do not use the module chk1btime – after the end of the decommutation task - with NOAA HRPT.11b)

Note: The names of parameters are those defined in the include avh1b.h

Despite the differences that are detailed below it is possible to convert the NOAA '16-bit unpacked' format – HRPT or LAC – to a format that is broadly compatible with AAPP as follows:

- 1. Strip off the trailing 512 bytes from each NOAA record (tool *hrpt1b_noaa.exe* in AAPP v5)
- 2. Re-calibrate using avhrcl, but without the Earth location option, i.e. avhrcl –c –s noaa...

Record Length

	HRPT.11b of AAPP	HRPT.11b of NOAA
Total number of header	1	1
record		
(avh_h_hdrent)		
Length of the header record	22016 bytes	15872 for packed datasets
		22528 for unpacked datasets
Length of a data record	22016 bytes	15872 for packed datasets
		22528 for unpacked datasets

Header Record

The differences are for the following variables:

avh_h_reclg: 22016 for AAPP

22528 for NOAA

avh_h_datatyp: always equal to 3 in AAPP (data type code always HRPT)

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avh_h_tipsrc: always equal to 4 in AAPP (TIP source code always stored AIP)

avh_h_inststat1: 2 possible values for AAPP for bits15-0

1111 1011 0000 0000 → channel 3a is enabled

or $1111\ 0111\ 0000\ 0000 \rightarrow$ channel 3b is enabled

avh_h_inststat2: 2 possible values for AAPP for bits15-0

1111 1011 0000 0000 → channel 3a is enabled

or 1111 0111 0000 0000 \rightarrow channel 3b is enabled

avh_h_callocscnlin: always equal to avh_h_scnlin in AAPP

avh_h_pcalalgind: always equal to 0 in AAPP

avh_h_pcalalgopt: always equal to 0 in AAPP

avh_h_scalalgind: always equal to 0 in AAPP

avh_h_scalalgopt: always equal to 0 in AAPP

avh_h_modelid: equal to GRS80 in AAPP

avh_h_nadloctol: always equal to 0 in AAPP

avh_h_locbit: bits15-1 always equal to 0 in AAPP

bit 0 equal 1 for attitude error correction

equal 0 if option of navigation is off in AAPP

avh_h_radtempcnv: prior to AAPP v5, this contained the temperature to radiance band

corrections coefs, whereas NESDIS 1b contains radiance to temperature.

AAPP and NESDIS are the same in AAPP v5 and later.

List of not initialised parameters in AAPP:

avh h instid

avh_h_pacsparityerr

avh_h_auxsyncerrsum

avh_h_timeseqerrcode

avh_h_socclockupind

avh_h_locerrind

avh_h_locerrcode

avh_h_pacsstatfield

avh_h_pacsdatasrc

avh_h_racalind

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```
avh_h_pchtemp(5)
```

 $avh_h_pchtempext(5)$

avh_h_chpow(5)

avh_h_rdtemp(5)

 $avh_h_btemp1(5)$

avh_h_bbtemp2(5)

avh_h_bbtemp3(5)

avh_h_bbtemp4(5)

avh_h_eleccur(5)

 $avh_h_motorcur(5)$

avh_h_earthpos(5)

avh_h_electemp(5)

avh_h_chtemp(5)

avh_h_bptemp(5)

avh_h_mhtemp(5)

avh_h_adcontemp(5)

avh_h_d4bvolt(5)

avh_h_d5bvolt(5)

avh_h_bbtempchn3b(5)

avh_h_bbtempchn4(5)

avh_h_bbtempchn5(5)

avh_h_refvolt(5)

All "blank", filler or reserved parameters:

avh_h_blksz

avh_h_filler0(3)

avh_h_filler1(4)

avh_h_filler2

avh_h_filler3

avh_h_spare1

avh_h_spare2

avh_h_filler4(5)

avh_h_filler5(2)

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avh_h_filler6(3) avh_h_filler7 avh_h_filler8(4) avh_h_reserved1,...,22

Data Record

The differences are for the following variables:

avh_scnlinbit: In AAPP, bits 1 and 0 are different from those of NOAA

AAPP: bits 1-0: channel 3 select with 0=3a, 1=3b, 2=transition NOAA: bits 1-0: channel 3 select with 0=3b, 1=3a, 2=transition

avh_qualind: bits 28,26,24,23,22,21,20,4,3,2,0 are not initialised in AAPP

bit 25 : AAPP : = 1 if frame sync. errors

NOAA : =1 if instrument status changed with this scan

bits 9-5 : AAPP : = 1 if TIP parity errors

NOAA: bit 9 zero fill

bit 8 : TIP parity error detected

bit 7-2: reflected sunlight detected ch3b, ch4, ch5

avh_scnlinqual: All the bits are set to zero in AAPP

avh_calvis(5,3,3): AAPP: Visible operational and visible test calibration coefficients

are always set to zero \rightarrow avh_calvis(*,1 or 2,*) = 0

Scaling factor are 10¹⁰ and 10⁷

NOAA: Scaling factor are 10⁷ and 10⁶

avh_calir(3,2,3): AAPP: The second set of coefficients are the mean coefficients of the sub-block

NOAA: The second set of coefficients are test coefficients

AAPP: Scaling factor are 10⁹, 10⁶, 10⁶

Note they are equal to 10^6 , 10^6 , 10^6

if (avh_h_siteid.eq.'CMS' .and. avh_h_startdatajd.lt.17923.5)

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NOAA: Scaling factor are 10⁶, 10⁶, 10⁶

avh_filler2(3): AAPP: It stores the 3 exponents of the scaling factor of avh_calir. Contains 9,6,6

NOAA: zero fill

avh_navstat: AAPP: bits 31-14 and bits 12-0 are set to zero

bit 13 = 1 if the scan line is not located

avh_hrpt(5,2048) and avh_video(5*2048):

For the NOAA 16-bit format the AAPP and NOAA sensor data are the same. For NOAA 10-bit format they are different:

AAPP: avh_hrpt and avh_video are integer*2 words and there is 5*2048 words

NOAA 10-bit: AVHRR sensor data words are integer*4 words and there is 3414 words

No digital B telemetry in AAPP format

No analog housekeeping data in AAPP format

But avh_tipmfhd(7,5) keeps the possibility to derive the analog and digital telemetry structure.

No clouds data from AVHRR in AAPP format

List of not initialised parameters in AAPP:

avh_calqual(3)

avh_cputel(2,5)

Filler parameters

avh_filler0(5)

avh_filler1(2)

avh_filler3(3)

avh_filler4(2)

avh_filler5

avh_filler6(2)

avh_filler7(191)

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9. FORMAT OF HIRS.L1B FILE, OUTPUT OF THE FIRST HIRS CALIBRATION ALGORITHM

(See also general information in the paragraph named "Interfaces" of the AAPP software description document)

HIRS.11a format = HIRS.11b format (in HIRS.11a, calibration and location fields are empty).

<u>Header and record length</u> Header length = record length

4608 bytes

Type

C = character

I1 = integer*1 or byte

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENERAL	INFORM	ATION
hrs_h_siteid	C	3	1	Data set creation site ID
hrs_h_blank	C	1	1	ASCII blank
hrs_h_l1bversnb	I2	2	1	level 1b format version number
hrs_h_l1bversyr	I2	2	1	level 1b format version year
hrs_h_l1bversdy	I2	2	1	level 1b format version day of year
hrs_h_reclg	I2	2	1	record length
hrs_h_blksz	I2	2	1	(reserved for block size)
hrs_h_hdrent	I2	2	1	count of header records in this data set
hrs_h_filler0	I2	2	3	Unassigned (no value)
hrs_h_dataname	C	42	1	data set name
hrs_h_prblkid	C	8	1	processing block identification
hrs_h_satid	I2	2	1	Spacecraft identification code
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8=NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator

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hrs_h_instid	I2	2	1	instrument ID
hrs_h_datatyp	I2	2	1	data type code
				5=HIRS
hrs_h_tipsrc	I2	2	1	TIP source code
1				0=not applicable; 1=GAC embedded;
				2=stored; 3=third CDA;
				4=HRPT embedded
hrs_h_startdatajd	I4	4	1	start of data set Julian Day(00h,1jan50)
hrs_h_startdatayr	I2	2	1	start of data set year
hrs_h_startdatady	I2	2	1	start of data set day of the year
hrs_h_startdatatime	I4	4	1	start of data set UTC time of day in
				milliseconds
hrs_h_enddatajd	I4	4	1	end of data set Julian Day(00h,1jan50)
hrs_h_enddatayr	I2	2	1	end of data set year
hrs_h_enddatady	I2	2	1	end of data set day of the year
hrs_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
hrs_h_cpidsyr	I2	2	1	year of last CPIDS Update
hrs_h_cpidsdy	I2	2	1	day of year of last CPIDS Update
hrs_h_filler1	I2	2	4	Unassigned (no value)
	DA	TA SET QU	JALITY 1	INDICATORS
hrs_h_inststat1	I4	4	1	instrument status
hrs_h_filler2	I2	2	1	Unassigned (no value)
hrs_h_statchrecnb	I2	2	1	record number of status change
				(if 0, none occurred)
hrs_h_inststat2	I4	4	1	second instrument status
				(if previous word is 0, no change)
hrs_h_scnlin	I2	2	1	count of scan lines in this data set
hrs_h_callocsclin	I2	2	1	count of calibrated, earth located scan lines
				in this data set
hrs_h_misscnlin	I2	2	1	count of missing scan lines
hrs_h_datagaps	I2	2	1	count of data gaps in this data set
hrs_h_okdatafr	I2	2	1	count of data frames without frame sync
				word errors
hrs_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
hrs_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in
,				the input data
hrs_h_timeseqerr	I2	2	1	time sequence error
				0=none
				otherwise the record number of the first
				occurrence
hrs_h_timeseqerrcode	I2	2	1	time sequence error code
hrs_h_socclockupind	I2	2	1	socc clock update indicator
				0=none during this orbit
				otherwise the record number of the first
				occurrence
hrs_h_locerrind	I2	2	1	Earth location error indicator

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				0=none during this orbit
				otherwise the record number of the first
				occurrence
hrs_h_locerrcode	I2	2	1	Earth location error code
hrs_h_pacsstatfield	I2	2	1	PACS status bit field
				bit 15-3 : spare (zero fill)
				bit 2 : pseudo noise 0=normal data
				1=P/N data
				bit 1: tape direction 0=time
				decrementing
				bit 0 : data mode 0=test data
				1=flight data
hrs_h_pacsdatasrc	I2	2	1	Pacs data source 0=unused
				1=Gilmore
				2=Wallops
				3=SOCC
hrs_h_filler3	I4	4	1	Unassigned (no value)
hrs_h_spare1	С	8	1	spare <reserved for="" ingester="" the=""></reserved>
hrs_h_spare2	C	8	1	spare <reserved decommutation="" of="" the=""></reserved>
hrs_h_filler4	I2	2	5	Unassigned (no value)
			LIBRATIO	
hrs_h_autocalind	I2	2	1	ramp/auto calibration indicators
				bit 0 : auto calibration override switch for HIRS/3
hrs_h_solarcalyr	I2	2	1	year of most recent solar ch. calib.
hrs_h_solarcaldy	I2	2	1	day of year of most recent solar channel
				calibration
hrs_h_calinf	I4	4	4*20	calibration information
				order of the channels:
				1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8,20, 10,
				14, 6, 5, 15, 12, 16, 9.
				10^6*(mean calibration slope of channel
				nochannel)
				10^6*(standard deviation of calibration
				slope)
				10^6*(b-sub-1 for channel nochannel) 10^6*(standard deviation of linear
				regression
				for b-sub-1 for channel nochannel)
hrs_h_filler5	I4	4	2	Unassigned (no value)
1115_11_1111015				CE CONVERSION
hrs_h_tempradenv	I4	4	3*19	temperature-radiance conversion
ms_n_cmpradenv	177	7	3 19	order of channels = $1,2,3,4,,18,19$
				for nochannel = 1 to 19:
				10 ⁶ x (nochannel central wavenumber
				for ch1 to ch 12)
				10 ⁵ x (nochannel central wavenumber
				for ch13 to ch 19)
				101 1110 10 1111)

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				10^6 x (nochannel constant 1)
				10^6 x (nochannel constant 2)
hrs_h_20solfiltirrad	I2	2	1	10 ⁶ x (albedo-radiance ch20 solar filtered irradiance)
hrs_h_20equifiltwidth	I2	2	1	10 ⁶ x (albedo-radiance ch 20 equivalent filter width)
hrs_h_filler6	I4	4	1	Unassigned (no value)
1115_11_111010			AVIGATIO	
hrs_h_modelid	С	8	1	Reference Ellipsoid Model ID
				="GRS 80" in the actual version of AAPP
hrs_h_nadloctol	I2	2	1	10*(nadir Earth location tolerance
				in kilometers)
hrs_h_locbit	I2	2	1	Earth location bit field
				bit 0: attitude error correction (0=not
				corrected)
hrs_h_filler7	I2	2	1	Unassigned (no value)
hrs_h_rollerr	I2	2	1	10 ³ x (constant roll attitude error (dg))
hrs_h_pitcherr	I2	2	1	10 ³ x (constant pitch attitude error (dg))
hrs_h_yawerr	I2	2	1	10 ³ x (constant yaw attitude error (dg))
hrs_h_epoyr	I2	2	1	epoch year for orbit vector
hrs_h_epody	I2	2	1	day of epoch year for orbit vector
hrs_h_epotime	I4	4	1	epoch UTC time of day in milliseconds for
•				orbit vector
hrs_h_smaxis	I4	4	1	10^5 x (semi-major axis in kilometers)
hrs_h_eccen	I4	4	1	10 ⁸ x (eccentricity)
hrs_h_incli	I4	4	1	10^5 x (inclination in degrees)
hrs_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
hrs_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending
				node in degrees)
hrs_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
hrs_h_xpos	I4	4	1	10^5 x (position vector X component in
_				km)
hrs_h_ypos	I4	4	1	10^5 x (position vector Y component in
				km)
hrs_h_zpos	I4	4	1	10^5 x (position vector Z component in
-				km)
hrs_h_xvel	I4	4	1	10 ⁸ x (velocity vector X-dot component in
				kilometers/seconds)
hrs_h_yvel	I4	4	1	10^8 x (velocity vector Y-dot component
hrs_h_zvel	I4	4	1	10 ⁸ x (velocity vector Z-dot component
				in kilometers/seconds)
hrs_h_earthsun	I4	4	1	10 ⁶ x (earth/sun distance ratio)
hrs_h_filler8	I4	4	4	Unassigned (no value)
	ANAI	LOG TEL	EMETRY (CONVERSION
hrs_h_rdtemp	I2	2	6	radiator temp.conversion coefficients
hrs_h_bptemp	I2	2	6	base plate temp. conv. coef.
hrs_h_eltemp	I2	2	6	electronics temp. conv. coef.

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hrs_h_pchtemp	I2	2	6	patch temp. conv. coef.
hrs_h_fhcc	I2	2	6	filter housing controller current conv. coef.
hrs_h_scnmtemp	I2	2	6	scan motor temperature conv. coef.
hrs_h_fwmtemp	I2	2	6	filter wheel motor temp. conv. coef.
hrs_h_p5v	I2	2	6	+5 VDC monitor conv. coef.
hrs_h_p10v	I2	2	6	+10 VDC TLM/DC/DC conv. conv.coef.
hrs_h_p75v	I2	2	6	+7.5 VDC TLM/DC/DC conv. conv. coef.
hrs_h_m75v	I2	2	6	-7.5 VDC TLM/DC/DC conv. conv. coef.
hrs_h_p15v	I2	2	6	+15 VDC monitor conv. coef.
hrs_h_m15v	I2	2	6	-15 VDC monitor conv. coef.
hrs_h_fwmcur	I2	2	6	filter wheel motor current conv. coef.
hrs_h_scmcur	I2	2	6	scan motor current conv. coef.
hrs_h_pchcpow	I2	2	6	patch controller power conv. coef.
hrs_h_filler9	I4	4	890	Unassigned (no value)

One Data Record for one HIRS scan line

Type	Word Size	Number	Meaning
	•		
1			
		1	scan line number
		1	scan line year
I2		1	scan line day of year
I2	2	1	satellite clock drift delta in milliseconds
I4	4	1	scan line UTC time of day in milliseconds
I2	2	1	scan line bit field
			bit 15 : =0 ascending dat
			=1 descending data
			bit 14 : =1 scan time corrected for clock drift
			bit 13-0 : <zero fill=""></zero>
I2	2	1	major frame count
I2	2	1	scan position number in 32 seconds cycle
I2	2	1	scan type code
			0 : Earth view
			1 : space view
			2 : cold black body view
			3 : main black body view
I4	4	2	Unassigned (no value)
	QUALIT	ΓΥ INDICA	ATORS
I4	4	1	quality indicator bit field
			if a bit is on(=1) then the statement is true.
			bit 31: do not use scan for product generation
			bit 30: time sequence error detected with this
			scan
	I2 I2 I2 I4 I2 I2 I2 I2	in byte SCAN LIN 12 2 12 2 12 2 12 2 14 4 12 2 12 2 14 2 12 2 12 2 14 4 12 2 14 4 12 2 14 4 14 4 QUALIT	In byte of words SCAN LINE INFORM I2 2 1 I2 2 1 I2 2 1 I2 2 1 I4 4 1 I2 2 1 I2 I2

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			bit 29: data gap precedes this scan bit 28: no calibration bit 27: no earth location bit 26: first good time following a clock update bit 25: instrument status changed with this scan bit 24-0: <zero fill=""></zero>
hrs_linqualflgs	I4	4	scan line quality flags if a bit is on(=1) then the statement is true time problem code: (all bits off implies the scan time is as expected) bit31-24: <zero fill=""> bit 23: time field is bad but can probably be inferred from the previous good time bit 22: time field is bad and can't be inferred from the previous good time bit 21: this record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update. (see bit 26 above) bit 20: start of a sequence that apparently repeats scan times that have been previously accepted. bits 19-16: <zero fill=""> calibration problem code: (Note these bits complement the channel indicators; all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap. bit 13: scan line was not calibrated because of bad or insufficient PRT data bit 12: scan line was calibrated but with marginal PRT data bit 11: some uncalibrated channels of this scan. See channel indicators. bit 10: uncalibrated due to instrument mode bits 9-8: <zero fill=""></zero></zero></zero>

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	1	<u> </u>	<u> </u>	E. d. L., C., and L.
				Earth location problem code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above)
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails
				reasonableness check
				bit 3-0: <zero fill=""></zero>
has showelfly	I2	2	20	
hrs_chqualflg	12	2	20	quality flag for each channel
				order of the channels:
				1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6,
				5, 15, 12, 16, 9.
				(all bits off implies a good calibration)
				bit 15-6: <zero fill=""></zero>
				bit 5: all bad blackbody counts for scan line
				bit 4: all bad space view counts for scan line
				bit 3: all bad PRTs counts for scan line
				bit 2: marginal blackbody view counts for
				this line
				bit 1: marginal space view counts for this
				line
				bit 0: marginal PRTs counts for scan line
hrs_mnfrqual	I1	1	64	minor frame quality indicators for nel 0 to 63
ms_mmqaar	11	1	0.	(for bits 7 through 1,if bit is on(=1) then
				statement is true)
				,
				bit $7:1$ = this frame suspect due to a time
				error hit 6 : 1 — this frame contains data can data
				bit 6:1 = this frame contains data gap data
				fill
				bit 5:1 = this frame contains TIP dwell data
				fill
				bit 4:1 = data suspect due to PACS QC
				error
				bit 3:1 = mirror locked during this frame
				bit $2:1 = mirror position error during this$
				frame
				bit 1:1 = mirror was moving during this
				frame
				bit 0: minor word odd parity bit
hrs_filler2	I4	4	4	Unassigned (no value)
CALIBRATION COEFFICIENTS				
hrs_calcof	I4	4	3*20	calibration coefficients
				order of the channels:
I	1	1	l	i e e e e e e e e e e e e e e e e e e e

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		T		T
				1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14,
				6, 5, 15, 12, 16, 9.
				- 10^12*the second one
				- 10^9*the first one
				- 10^6*the zeroth one
hrs_scalcof	I4	4	3*20	second calibration coefficients
				order of the channels:
				1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14,
				6, 5, 15, 12, 16, 9.
				- 10^12*the second one
				- 10^9*the first one
				- 10^6*the zeroth one
hrs_filler3	I4	4	3	Unassigned (no value)
			VIGATIO	<u> </u>
hrs_navstat	I4	4	1	navigation status bit field
	= -		=	bits15-12: earth location indicator
				0=earth location available
				1=user ephemerics files greater than 24hours
				old
				2=no earth location available
				bits11-08: spacecraft attitude control
				0=operating in YGC or nominal mode
				ž – –
				1=operating in another mode
				2=attitude exceeds nominal tolerance
				3=both 1 and 2
				bits07-04: attitude SMODE
				0=nominal mode
				1=rate nulling mode
				2=YGC mode
				3=search mode
				4=coast mode
				bits03-00: attitude PWT1\$AC
				0=nominal mode/no test
				1=yaw axis test in progress
				2=roll axis test in progress
				3=pitch axis test in progress
hrs_attangtime	I4	4	1	time associated angles (seconds)
hrs_rollang	I2	2	1	10 ³ xRoll angle in degrees
hrs_pitchang	I2	2	1	10^3xPitch angle in degrees
hrs_yawang	I2	2	1	10 ³ xYaw angle in degrees
hrs_scalti	I2	2	1	10*spacecraft altitude (MSL) in km
hrs_ang	I2	2	168	scan angles in degrees
				word1: 100*solar zenith angle, point 1
				word2: 100*satellite zenith angle, point 1
				word3: 100*local azimuth angle, point 1
				word4: 100*solar zenith angle, point 2
				word5: 100*satellite zenith angle, point 2
				word6: 100*local azimuth angle, point 2
				wordo. 100 100ai azimutii angie, point 2

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				word168: 100*solar zenith angle, point 56 word168: 100*satellite zenith angle, point 56 word168: 100*local azimuth angle, point 56
hrs_pos	I4	4	112	Earth location (north latitude and east longitude are positive) word1: 10^4*latitude in degrees, point 1 word2: 10^4*longitude in degrees, point 1 word3: 10^4*latitude in degrees, point 2 word4: 10^4*longitude in degrees, point 2
hrs_filler4	I4	4	2	word112: 10^4*longitude in degrees, point 56 Unassigned (no value)
1118_1111614	14		ATA ELEN	,
hrs elem	I2	2	24*64	element data
hrs_elem			24*64	for nel 0 to 63 word 1 bits 15-8 : scan encoder position bits 7-3 : electronic cal level indicator bits 2-0 : spare word 2 bits 15-13: spare bits 12-7 : channel 1 period monitor bits 6-1 : element number bit 0 : filter sync designator word 23 bits flag bit 15 : valid data flag bit 14 : odd bit parity bits 13-0 : spare word 24 zero fill for nel 0 to 55 word 3-22: radiometric channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9 for nel 56 word 3-22: positive calibration channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9 for nel 57 word 3-22: negative calibration channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9 for nel 58 word 3-7: internal warm target, temp sensor #1 (5 readings) word 8-12: internal warm target, temp sensor

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word 13-17: internal warm target, temp sensor #3 word 18-22: internal warm target, temp sensor #4 for nel 59 word 3-7: internal cold target, temp sensor #1
for nel 61 word 3-7: patch temp. (5 readings) word 8-12: 1st stage radiator
for nel 62 word 3 scan mirror temperature word 4 primary telescope temperature word 5 secondary telescope temperature word 6 HIRS baseplate temperature word 7 HIRS electronics temperature word 8 patch temperature full range word 9 scan motor temperature word 10 filter wheel motor temperature word 11 cooler housing temperature word 12 patch control power

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				1
				word 13 scan motor current
				word 14 filter motor current
				word 15 +15 VDC
				word 16 -15 VDC
				word 17 +7.5 VDC
				word 18 -7.5 VDC
				word 19 +10 VDC
				word 20 + 5 VDC
				word 21 analog ground
				word 22 analog ground
				word 22 mining ground
				for nel 63
				word 3 line counter
				word 4 first status word
				bits 15-8 : <zero fill=""></zero>
				bit 7: instrument on/off
				bit 6: scan motor on/off
				bit 5: filter wheel on/off
				bit 4: electronics on/off
				bit 3 : cooler heat on/off
				bit 2: internal warm target pos.
				bit 1: internal cold target pos.
				bit 0: space position
				word 5 second status word
				bits 15-8 : <zero fill=""></zero>
				bit 7 : nadir pos.
				bit 6 : calibration enable/disable
				bit 5 : cooler door release enable/disable
				bit 4 : cooler door open
				bit 3 : cooler door closed
				bit 2: filter housing heat on/off
				bit 1 : patch temp. control on/off
				bit 0: filter motor power high
				word 6 Data verification binary code
				word 7-22: spare
hrs_filler5	I4	4	3	Unassigned (no value)
			TAL B DA	
hrs_digbinvwbf	I2	2	1	invalid word bit flags
hrs_digitbwrd	I2	2	1	digital "B" data from TIP
				bit 15: instrument power
				bit 14: electronics power
				bit 13: filter motor power
				bit 12: scan motor power
				bit 11: cooler heater
				bit 10: filter housing heater
				bit 9 : cooler door release
				bit 8 : cooler window heater
				bit 7 : go to nadir position
			<u> </u>	O

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	1		T		
				bit 6 : calibration sequence	
				bit 5 : cooler door closed	
				bit 4 : cooler door fully open	
				bit 3 : filter motor power level	
				bit 2 : patch temperature controller	
				bit 1-0: <zero fill=""></zero>	
	ANALOG TELEMETRY				
hrs_aninvwbf	I4	4	1	invalid word bit flags	
				(if bit=1, associated telemetry word was not	
				updated during most recent minor frame cycle	
				– possibly due to lost frame)	
				bits 31-17 : <zero fill=""></zero>	
				bit 16: patch controller power (word 16)	
				bits 15-2 : words 15 through 2 (in order)	
				bit 1 : radiator temperature (word 1)	
				bit 0 : <zero fill=""></zero>	
hrs_anwrd	I1	1	16	Word 1 : Radiator temperature	
				Word 2 : Base Plate Temperature	
				Word 3 : Electronics Temperature	
				Word 4 : Patch Temperature	
				Word 5: Filter Housing Controller Current	
				Word 6 : Scan Motor Temperature	
				Word 7 : Filter Wheel Motor Temperature	
				Word 8: +5 VDC Monitor	
				Word 9: +10 VDC TLM/DC/DC Conv.	
				Word 10: +7.5 VDC TLM/DC/DC Conv.	
				Word 11: -7.5 VDC TLM/DC/DC Conv.	
				Word 12: +15 VDC Monitor	
				Word 13: -15 VDC Monitor	
				Word 13: 13 VDC Wollton Word 14: Filter Wheel Motor Current	
				Word 15: Scan Motor Current	
				Word 16: Sean Wood Current Word 16: Patch Controller Power	
			FILLER	mora to . I atom Controller I ower	
hrs filler6	I4	4	11	Unassigned (no value)	
1113_1111610	14	4	11	Onassigned (no value)	

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Date: 24 January 2012

10. FORMAT OF THE HIRS.L1B FILE, OUTPUT OF THE HIRS CALIBRATION ALGORITHM 4

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

HIRS.11a format = HIRS.11b format (in HIRS.11a, calibration and location fields are empty).

Header and record length
Header length = record length
4608 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
1 (00.000	- J P •	in byte	of words	
	I	GENERAL		ATION
hrs_h_siteid	С	3	1	Data set creation site ID
				CMS=Centre de Meteorologie
				spatiale/France
				DSS=Dundee Satellite Receiving
				Station/UK
				NSS=National Environmental Satellite
				Data and Information Service/USA
				UKM=United Kingdom Meteorological
				Office/UK
hrs_h_blank	C	1	1	ASCII blank
hrs_h_l1bversnb	I2	2	1	level 1b format version number
hrs_h_l1bversyr	I2	2	1	level 1b format version year
hrs_h_l1bversdy	I2	2	1	level 1b format version day of year
hrs_h_reclg	I2	2	1	record length
hrs_h_blksz	I2	2	1	(reserved for block size)
hrs_h_hdrent	I2	2	1	count of header records in this data set
hrs_h_filler0	I2	2	3	Unassigned (no value)
hrs_h_dataname	С	42	1	data set name
hrs_h_prblkid	С	8	1	processing block identification
hrs_h_satid	I2	2	1	Spacecraft identification code
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)

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	1		T	()10 1 1 17 ()10 1 1 16
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8=NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator
hrs_h_instid	I2	2	1	instrument ID
				301=s/n H301 (NOAA-L)
				302=s/n H302 (NOAA-K)
				303=s/n H303 (NOAA-M)
				304=s/n H304 (NOAA-N')
				305=s/n H305 (NOAA-N)
				306=s/n H306 (Metop-2)
				307=s/n H307 (Metop-1)
hrs_h_datatyp	I2	2	1	data type code
				5=HIRS
hrs_h_tipsrc	I2	2	1	TIP source code
				(NOAA: values defined below
				Metop: zero fill)
				0=unused, i.e., GAC/HRPT/LAC data;
				1=GAC embedded AMSU and TIP;
				2=stored TIP (STIP); 3=HRPT/LAC-
				embedded AMSU and TIP;
				4=stored AIP (SAIP)
hrs_h_startdatajd	I4	4	1	start of data set Julian Day(00h,1jan50)
hrs_h_startdatayr	I2	2	1	start of data set year
hrs_h_startdatady	I2	2	1	start of data set day of the year
hrs_h_startdatatime	I4	4	1	start of data set UTC time of day in
				milliseconds
hrs_h_enddatajd	I4	4	1	end of data set Julian Day(00h,1jan50)
hrs_h_enddatayr	I2	2	1	end of data set year
hrs_h_enddatady	I2	2	1	end of data set day of the year
hrs_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
hrs_h_cpidsyr	I2	2	1	year of last CPIDS Update
hrs_h_cpidsdy	I2	2	1	day of year of last CPIDS Update
hrs_h_fov1offset	I2	2	4	time offset for FOV 1 (ms)
hrs_h_instrtype	C	6	1	instrument type: 'HIRS/3' or 'HIRS/4'
<u>-</u>			ALITY I	NDICATORS
hrs_h_inststat1	I4	4	1	instrument status
	/	-		bits 31-16: zero fill
				bit 15: instrument power (0=off;1=on)
				bit 14: Electronics power (0=off;1=on)
				bit 13: Filter motor power (0=off;1=on)
				bit 12: Scan motor power (0=off;1=on)
				bit 11: Cooler heater (0=off;1=on)
				bit 10: Filter housing heater (0=off;1=on)
			I	10.1 modeling neuter (0-011,1-011)

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				bit 9: Cooler door release
				(0=disabled;1=enabled)
				bit 8: Cooler window heater (0=on;1=off)
				bit 7: Go to nadir position
				(0=no;1=yes/initiated)
				bit 6: Calibration sequence
				(0=disabled;1=enabled)
				bit 5: Cooler door closed (0=yes;1=no)
				bit 4: Cooler door fully open (0=yes;1=no)
				bit 3: Filter motor power level
				(0=normal;1=high)
				bit 2: Patch temperature controller
				(0=off;1=on)
				bit 1-0: <zero fill=""></zero>
hrs_h_filler1	I2	2	1	Unassigned (no value)
hrs_h_statchrecnb	I2	2	1	record number of status change
				(if 0, none occured)
hrs_h_inststat2	I4	4	1	second instrument status
				(if previous word is 0, no change)
hrs_h_scnlin	I2	2	1	count of scan lines in this data set
hrs_h_callocsclin	I2	2	1	count of calibrated, Earth located scan
				lines in this data set
hrs_h_misscnlin	I2	2	1	count of missing scan lines
hrs_h_datagaps	I2	2	1	count of data gaps in this data set
hrs_h_okdatafr	I2	2	1	count of data frames without frame sync
				word errors (NOAA)
				zero fill (Metop)
hrs_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
				(NOAA)
				zero fill (Metop)
hrs_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in
= = = = = = = = = = = = = = = = = = =				the input data (NOAA)
				zero fill (Metop)
hrs_h_timeseqerr	I2	2	1	time sequence error
ms_n_umeseqen	12	_	-	0=none
				otherwise the record number of the first
				occurrence
hrs_h_timeseqerrcode	I2	2	1	time sequence error code
ms_n_timeseqericode	12	2	1	if a bit is on(=1) then the statement is true
				bits 15-8: <zero fill=""></zero>
				bit 7: time field is bad but can probably be
				inferred from the previous good time
				bit 6: time field is bad and can't be inferred
				from the previous good time
				bit 5: this record starts a sequence that is
				inconsistent with previous times
				(i.e., there is a time discontinuity);may be
				associated with a spacecraft clock update

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				bit 4: start of a sequence that apparently repeats scan times that have been previously accepted bit3-0: <zero fill=""></zero>
hrs_h_socclockupind	I2	2	1	socc clock update indicator 0=none during this orbit otherwise the record number of the first occurrence
hrs_h_locerrind	I2	2	1	Earth location error indicator 0=none during this orbit otherwise the record number of the first occurrence
hrs_h_locerrcode	12	2	1	Earth location error code if a bit is on(=1) then the statement is true bit 15-8: <zero fill=""> bit 7: not Earth located because of bad time; Earth location fields zero-filled bit 6: Earth location questionable: questionable time code bit 5: Earth location questionable: Marginal agreement with reasonableness check bit 4: Earth location questionable: Fails reasonableness check bit 3-2: <zero fill=""> bit 1: not Earth located because of satellite in-plane maneuver(Metop) <zero fill="">(NOAA) bit 0: not Earth located because of satellite out-of-plane maneuver(Metop) <zero fill="">(NOAA)</zero></zero></zero></zero>
hrs_h_pacsstatfield	12	2	1	PACS status bit field NOAA: values defined below Metop: zero fill bits 15-3: spare (zero fill) bit 2: pseudo noise 0=normal data 1=pseudo noise data bit 1: tape direction 0=reverse playback (time decrementing) bit 0: data mode 0=test data 1=flight data
hrs_h_pacsdatasrc	I2	2	1	Pacs data source 0=unused 1=Fairbanks, AK 2=Wallops Is, VA 3=SOCC 4=Svalbard, Norway 5=Monterey, CA

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hrs_h_filler2	I4	4	1	Unassigned (no value)
hrs_h_spare1	С	8	1	spare <reserved for="" ingester="" the=""></reserved>
hrs_h_spare2	С	8	1	spare <reserved decommutation="" for="" the=""></reserved>
hrs_h_filler3	I2	2	5	Unassigned (no value)
		CAL	IBRATIO	N
hrs_h_autocalind	I2	2	1	ramp/auto calibration indicators
				bit 15-1: zero fill
				bit 0 : auto calibration override switch for
				HIRS/3-HIRS/4
				0=normal calibration sequence
				enabled during entire time period of this
				data set
				1=calibration sequence was disabled
				at some point during time period of this
				data set
hrs_h_solarcalyr	I2	2	1	year of most recent solar ch. calib.
hrs_h_solarcaldy	I2	2	1	day of year of most recent solar channel
				calibration
hrs_h_calinf	I4	4	4*20	calibration information
				order of the channels:
				1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10,
				14, 6, 5, 15, 12, 16, 9.
				10^6*(mean calibration slope of channel
				nochannel)
				10^6*(stantard deviation of calibration
				slope)
				10^6*(B1 for channel nochannel)
				10^6*(stantard deviation of linear
land la Cillan	I4	4	2	regression for B1 for channel nochannel)
hrs_h_filler5		•		Unassigned (no value)
	1	_		CE CONVERSION
hrs_h_tempradcnv	I4	4	3*19	temperature-radiance conversion
				order of channels = 1,2,3,4,,18,19 for nochannel = 1 to 19:
				10 ⁶ x (nochannel central wavenumber
				for ch1 to ch 12)
				10 ⁵ x (nochannel central wavenumber
				for ch13 to ch 19)
				10 ⁶ x (nochannel constant 1)
				10°6 x (nochannel constant 1) 10°6 x (nochannel constant 2)
hrs_h_20solfiltirrad	I2	2	1	10°2 x (albedo-radiance ch20 solar filtered
1115_11_20501111111111111111111111111111	12	2	1	irradiance)
				(Note scale factor different from pre-2005
				format)
			1	
hrs h 20equifiltwidth	I2	2	1	10^4 x (albedo-radiance ch 20 equivalent
hrs_h_20equifiltwidth	I2	2	1	10^4 x (albedo-radiance ch 20 equivalent filter width)
hrs_h_20equifiltwidth	I2	2	1	10^4 x (albedo-radiance ch 20 equivalent filter width) (Note scale factor different from pre-2005

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hrs_h_filler5	I4	4	1	Unassigned (no value)
		NA	VIGATION	N
hrs_h_modelid	C	8	1	Reference Ellipsoid Model ID
				="GRS 80" in the actual version of AAPP
hrs_h_nadloctol	I2	2	1	10*(nadir Earth location tolerance
				in kilometers)
hrs_h_locbit	I2	2	1	Earth location bit field
				bits 15-3: <zero fill=""></zero>
				bit 2: dynamic attitude error correction
				(0=not performed;1=performed)
				bit 1: reasonableness test
				(0=inactive; 1=active)
				bit 0: constant attitude error correction
				(0=not performed;1=performed)
hrs_h_filler6	I2	2	1	Unassigned (no value)
hrs_h_rollerr	I2	2	1	10 ³ x (constant roll attitude error (dg))
hrs_h_pitcherr	I2	2	1	10 ³ x (constant pitch attitude error (dg))
hrs_h_yawerr	I2	2	1	10^3 x (constant yaw attitude error (dg))
hrs_h_epoyr	I2	2	1	epoch year for orbit vector
hrs_h_epody	I2	2	1	day of epoch year for orbit vector
hrs_h_epotime	I4	4	1	epoch UTC time of day in milliseconds for
I				orbit vector
hrs_h_smaxis	I4	4	1	10^5 x (semi-major axis in kilometers)
hrs_h_eccen	I4	4	1	10^8 x (eccentricity)
hrs_h_incli	I4	4	1	10^5 x (inclination in degrees)
hrs_h_argper	I4	4	1	10 ⁵ x (argument of perigee in degrees)
hrs_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending
				node in degrees)
hrs_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
hrs_h_xpos	I4	4	1	10^5 x (position vector X component in
-				km)
hrs_h_ypos	I4	4	1	10^5 x (position vector Y component in
• •				km)
hrs_h_zpos	I4	4	1	10^5 x (position vector Z component in
•				km)
hrs_h_xvel	I4	4	1	10 ⁸ x (velocity vector X-dot component in
				kilometers/seconds)
hrs_h_yvel	I4	4	1	10^8 x (velocity vector Y-dot component
hrs_h_zvel	I4	4	1	10^8 x (velocity vector Z-dot component
				in kilometers/seconds)
hrs h earthsun	I4	4	1	10^6 x (Earth/sun distance ratio)
hrs_h_filler7	I4	4	4	Unassigned (no value)
_		LOG TELE	METRY (CONVERSION
				etors 10^(2, 2, 3, 3, 3, 5)
hrs_h_rdtemp		4	6	radiator temp.conversion coefficients
hrs_h_bptemp	I4	4	6	base plate temp. conv. coef.
hrs_h_eltemp	I4	4	6	electronics temp. conv. coef.

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np. conv. coef.
v. coef.
OC conv. conv.coef.
DC conv. conv. coef.
OC conv. coef.
nv. coef.
iv. coef.
rent conv. coef.
nv. coef.
er conv. coef.
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NN'and Metop
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IN' and Metop 6, 9, 14, 17, 21, 25)
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hrs_h_fwmcnttmp	I4	4	6	filter wheel motor temperature
Ins_n_twinchtinp	14	4	0	6 scaling factors 10^(6, 9, 14, 17, 21, 25)
hrs_h_chsgcnttmp	I4	4	6	cooler housing temperature
ins_n_ensgentinp	14	4	0	6 scaling factors 10 ^(6, 9, 14, 17, 21, 25)
hrs_h_conversions	I4	4	11	Conversion constants
IIIS_II_COIIVEISIOIIS	14	4	11	word1:10^9 x filter wheel housing heater
				current
				word2:10 x electronic calibration digital
				to analog converter
				word3: 10^17 x patch control power
				word4: 10 ⁹ x scan motor current
				word5: 10 ⁹ x filter motor current
				word6: 10 ⁸ x +15 VDC
				word7: 10 ⁸ x -15 VDC
				word8: 10 ⁸ x +7.5 VDC
				word9: 10 ⁸ x -7.5 VDC
				word10: 10 % x +10 VDC
				word11: 10^8 x +5 VDC
		LUNAR CO)NTAMIN	
hrs_h_moonscnlin	I2	2	1	count of scans with moon in space view
ms_n_moonsemm	12	2		= -1 if the detection algorithm for lunar
				contamination is turned off
				= 0 if the detection algorithm is turned on
				and no lunar-contaminated space view
				scans were found.
				=>0 if the detection algorithm is turned on
				and the value in this field represents the
				number of lunar-contaminated space view
				scans.
hrs_h_moonthresh	I2	2	1	100 x lunar angle threshold in degrees
		_		any space view whose lunar angle is less
				than this value is flagged as being "lunar
				contaminated" and is not used in the
				calibration.
	24-НС	UR AVERAG	E SPACE	VIEW COUNTS
hrs_h_avspcounts	I4	4	20	24-hour average space view counts for each
1				channel
				order of the channels:
				1,17,2,3,13,4,18,11,19,7,8,20,10,14,6,5,15,
				12,16,9
	MET	OP MANOEU	VRES IDE	ENTIFICATION
hrs_h_startmanyr	I2	2	1	start of manoeuvre year (4 digit year)
hrs_h_startmandy	I2	2	1	start of manoeuvre day of year
hrs_h_startmantime	I4	4	1	start of manoeuvre UTC time of day in
				milliseconds
hrs_h_endmanyr	I2	2	1	end of manoeuvre year (4 digit year)
hrs_h_endmandy	I2	2	1	end of manoeuvre day of year
hrs_h_endmantime	I4	4	1	end of manoeuvre UTC time of day in
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				milliseconds
hrs_h_deltav	I4	4	3	change in spacecraft velocity
hrs_h_mass	I4	4	2	spacecraft mass before and after
hrs_h_filler8	I2	2	1302	zero fill

One Data Record for one HIRS scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		SCAN LIN	NE INFOR	MATION
hrs_scnlin	I2	2	1	scan line number
				(cumulative, starting with 1)
hrs_scnlinyr	I2	2	1	scan line year
hrs_scnlindy	I2	2	1	scan line day of year
hrs_clockdrift	I2	2	1	satellite clock drift delta in milliseconds
hrs_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
hrs_scnlinf	I2	2	1	scan line bit field
				bit 15: satellite direction
				0=northbound
				1=southbound
				bit 14: clock drift correction
				0=not corrected
				1=scan time corrected for clock drift
				bits13-0: <zero fill=""></zero>
hrs_mjfrcnt	I2	2	1	major frame count for NOAA
				(cumulative, starting with 1)
				zero fill for Metop
hrs_scnpos	I2	2	1	scan position number in 32 seconds cycle
hrs_scntyp	I2	2	1	scan type code
				0 : Earth view
				1 : space view
				2 : cold black body view
				3 : main black body view
hrs_filler1	I4	4	2	Unassigned (no value)
		QUALI	TY INDICA	ATORS
hrs_qualind	I4	4	1	quality indicator bit field
_				if a bit is on(=1) then the statement is true.
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: insufficient data for calibration
				bit 27: Earth location data not available
				bit 26: first good time following a clock
			•	

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				update (nominally 0)
				bit 25: instrument status changed with this
				scan
				bit 24-0: <zero fill=""></zero>
hrs_linqualflgs	I4	4	1	scan line quality flags
				if a bit is on(=1) then the statement is true
				additional calibration problem code:
				bit 31: not calibrated because of satellite
				manoeuvre (METOP) zero fill (NOAA)
				bit 30-24: <zero fill=""></zero>
				time problem code :
				(all bits off implies the scan time is as
				expected)
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time field is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous times (i.e., there is
			a time discontinuity). This may or may not be	
				associated with a spacecraft clock update. (see
				bit 26 above)
			bit 20: start of a sequence that apparently	
				repeats scan times that have been previously
				accepted.
				bits 19-16: <zero fill=""></zero>
				calibration problem code:
				(Note these bits complement the channel
				indicators; all bits set to 0 indicates normal
				calibration)
				bit 15: scan line was not calibrated because
				of bad time
				bit 14: scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of
				bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bit 9: space view is lunar contaminated
				bit 8: lunar-contaminated space view scan
				was corrected (only applicable if bit 9 is set)

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		T		
				Earth location problem code (all bits set to 0 implies the Earth location was normal) bit 7: not Earth located because of bad time bit 6: Earth location questionable because of questionable time code (see time problem flags above) bit 5: Earth location questionable. Only marginal agreement with reasonableness check. bit 4: Earth location questionable. Fails reasonableness check bit 3-2: <zero fill=""> bit 1: Not calibrated because of in-plane manoeuvre (Metop) bit 0: Not calibrated because of out-of-plane manoeuvre (Metop)</zero>
hrs_chqualflg	I2	2	20	quality flag for each channel order of the channels: 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9. (all bits off implies a good calibration) bit 15-6: <zero fill=""> bit 5: all bad blackbody counts for scan line bit 4: all bad space view counts for scan line bit 3: all bad PRTs counts for scan line bit 2: marginal blackbody view counts for this line bit 1: marginal space view counts for this line bit 0: marginal PRTs counts for scan line</zero>
hrs_mnfrqual	С	1	64	minor frame quality indicators for nel 0 to 63 (for bits 7 through 1,if bit is on(=1) then statement is true) bit 7: 1 = this frame suspect due to a time error (NOAA) bit 6: 1 = this frame contains data gap data fill (NOAA) bit 5: 1 = this frame contains TIP dwell data fill (NOAA) bit 4: 1 = data suspect due to PACS QC error (NOAA) bit 3: 1 = mirror locked during this frame bit 2: 1 = mirror position error during this frame bit 1: 1 = mirror was moving during this frame

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				bit 0: minor word odd parity bit
hrs_filler2	I4	4	4	Unassigned (no value)
		CALIBRAT	ON COE	FFICIENTS
hrs_calcof	I4	4	3*20	calibration coefficients order of the channels: 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9 10^12*the second one - 10^9*the first one - 10^6*the zeroth one
hrs_scalcof	I4	4	3*20	second calibration coefficients order of the channels: 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9. - 10^12*the second one - 10^9*the first one - 10^6*the zeroth one
	<u> </u>	NA	VIGATIO)N
hrs_yawsteering	I2	2	3	computed yaw steering angles for METOP Yaw, pitch, roll (degrees)
hrs_totattcorr	I2	2	3	total applied attitude correction for METOP 1000* Yaw, pitch, roll (degrees)
hrs_navstat	I4	4	1	navigation status bit field (bits20-18 are Metop specific and will contain zero fill for NOAA) (bits11-0 are NOAA specific and will contain zero fill for Metop) bits31-21: <zero fill=""> bits20-19: yaw steering parameters usage indicator 0=no yaw steering correction 1=computed parameters from Metop data stream 2=measured parameters from Metop data stream 3=computed parameters from AELDS bit 18: Metop maneuver indicator 0=scan does not occur during a Metop in-plane or out-of-plane maneuver 1=scan, or some part of it, occurs during a maneuver bit 17: Earth location at the satellite subpoint is accurate and reasonable, i.e., is within tolerance defined by "nadir Earth location tolerance" in header 0=out of tolerance 1=in tolerance</zero>

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				bit 16 :Earth location corrected for Euler
				angles 0=false 1=true
				bits15-12: Earth location indicator
				0=Earth location available
				1=user ephemerics files greater than 24hours
				old
				2=no Earth location available
				bits11-08: spacecraft attitude control
				0=operating in YGC or nominal mode
				1=operating in another mode
				2=attitude exceeds nominal tolerance
				3=both 1 and 2
				bits07-04: attitude SMODE
				0=nominal mode
				1=rate nulling mode
				2=YGC mode
				3=search mode
				4=coast mode
				bits03-00: attitude PWT1\$AC
				0=nominal mode/no test
				1=yaw axis test in progress
				2=roll axis test in progress
				ž v
	T.4	4	1	3=pitch axis test in progress
hrs_attangtime	I4	4	1	time associated angles (seconds)
hrs_rollang	I2	2	1	10^3xRoll angle in degrees
hrs_pitchang	I2	2	1	10^3xPitch angle in degrees
hrs_yawang	I2	2	1	10 ³ xYaw angle in degrees
hrs_scalti	I2	2	1	10*spacecraft altitude (MSL) in km
hrs_ang	I2	2	168	scan angles in degrees
				word1: 100*solar zenith angle, point 1
				word2: 100*satellite zenith angle, point 1
				word3: 100*local azimuth angle, point 1
				word4: 100*solar zenith angle, point 2
				word5: 100*satellite zenith angle, point 2
				word6: 100*local azimuth angle, point 2
				1160 100% 1 24 1 2 66
				word168: 100*solar zenith angle, point 56
				word168: 100*satellite zenith angle, point 56
				word168: 100*local azimuth angle, point 56
hrs_pos	I4	4	112	Earth location
				(north latitude and east longitude are positive)
				word1: 10^4*latitude in degrees, point 1
				word2: 10^4*longitude in degrees, point 1
				word3: 10^4*latitude in degrees, point 2
				word4: 10^4*longitude in degrees, point 2
				word112: 10^4*longitude in degrees, point 56
	ii			

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hrs_moonang	I2	2	1	100*angle between moon and space view
hrs_filler4	I2	2	3	Unassigned (no value)
		HIRS	DATA ELE	
hrs_elem	12	2	24*64	element data for nel 0 to 63 word 1 bits 15-8: scan encoder position bits 7-3: electronic cal level indicator bits 2-0: spare word 2 bits 15-13: spare bits 12-7: channel 1 period monitor bits 6-1: element number bit 0: filter sync designator word 23 bits flag bit 15: valid data flag bit 14: odd bit parity bits 13-0: spare word 24 zero fill
				for nel 0 to 55 word 3-22: radiometric channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9 for nel 56 word 3-22: positive calibration channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9
				for nel 57 word 3-22: negative calibration channel no. 1, 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9
				for nel 58 word 3-7: internal warm target, temp sensor #1 (5 readings) word 8-12: internal warm target, temp sensor #2 word 13-17: internal warm target, temp sensor #3 word 18-22: internal warm target, temp sensor #4
				for nel 59 word 3-7: internal cold target, temp sensor #1 (5 readings) word 8-12 HIRS/4: Analog ground 3 word 8-12 HIRS/3: internal cold target, temp

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sensor #2
word 13-17 HIRS/4: Internal Warm Target,
=
temp Sensor #5
word 13-17 HIRS/3: internal cold target, temp
sensor #3
word 18-22 HIRS/4: Tertiary Telescope
Temperature Sensor
word 18-22 HIRS/3: internal cold target, temp
sensor #4
for nel 60
word 3-7: internal filter wheel housing, temp
sensor #1 (5 readings)
word 8-12: internal filter wheel housing, temp
sensor #2
word 13-17: internal filter wheel housing, temp
sensor #3
word 18-22: internal filter wheel housing, temp
sensor #4
for nel 61
word 3-7: patch temp (5 readings)
word 8-12: 1st stage radiator
word 13-17: filter wheel housing heater current
word 18-22: elec.cal.digital to analog converter
word to 22. electeding full to undrog converter
for nel 62
word 3 scan mirror temperature
word 4 primary telescope temperature
word 5 secondary telescope temperature
word 6 HIRS baseplate temperature
word 7 HIRS electronics temperature
word 8 patch temperature full range
word 9 scan motor temperature
word 10 filter wheel motor temperature
word 10 Ther wheel motor temperature word 11 cooler housing temperature
1
word 14 scan motor current
word 15 H15 VDC
word 15 +15 VDC
word 16 -15 VDC
word 17 +7.5 VDC
word 18 -7.5 VDC
word 19 +10 VDC
word 20 + 5 VDC
word 21 analog ground
word 22 analog ground

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			Т	T
				for nel 63
				word 3 line counter
				word 4 first status word
				bits 15-8 : <zero fill=""></zero>
				bit 7 : instrument on/off
				bit 6: scan motor on/off
				bit 5 : filter wheel on/off
				bit 4 : electronics on/off
				bit 3 : cooler heat on/off
				bit 2: internal warm target pos.
				bit 1: internal cold target pos.
				bit 0: space position
				word 5 second status word
				bits 15-8 : <zero fill=""></zero>
				bit 7 : nadir pos.
				bit 6: calibration enable/disable
				bit 5 : cooler door release enable/disable
				bit 4 : cooler door open
				bit 3 : cooler door closed
				bit 2: filter housing heat on/off
				bit 1: patch temp. control on/off
				bit 0: filter motor power high
				word 6 Data verification binary code
				word 7-22: spare
hrs_filler5	I4	4	3	Unassigned (no value)
IIIS_IIIICI3	14	<u> </u>	TAL B DA	
hrs_digitbupdatefg	I2	2	1	digital "B" telemetry update flags
ms_digitoupdateig	12	2	1	(if bit=0, associated telemetry item is up-to-
				-
				date. if bit=1, associated telemetry item was not updated during most recent telemetry
1	10	2	1	cycle-possibly due to lost frame)
hrs_digitbwrd	I2	2	1	digital "B" data from TIP
				bit 15: instrument power (0=off,1=on)
				bit 14: electronics power (0=off,1=on)
				bit 13: filter motor power (0=off,1=on)
				bit 12: scan motor power (0=off,1=on)
				bit 11: cooler heater (0=off,1=on)
				bit 10: filter housing heater (0=off,1=on)
				bit 9 : cooler door release
				(0=disabled,1=enabled)
				bit 8 : cooler window heater (0=on,1=off)
				bit 7 : go to nadir position
				(0=no,1=yes/initiated)
				bit 6 : calibration sequence
				(0=disabled,1=enabled)
				bit 5 : cooler door closed (0=yes,1=no)
				bit 4 : cooler door fully open (0=yes,1=no)
				bit 3 : filter motor power level

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				(0=normal,1=yes)
				bit 2 : patch temperature controller
				(0=off,1=on)
				bit 1-0: <zero fill=""></zero>
		ANALO	G TELEN	
hrs. analogundatafa	I4	4	1	
hrs_analogupdatefg	14	4	1	analog telemetry update flags
				(if bit=0, associated telemetry item is up-to-
				date. if bit=1, associated telemetry item was
				not updated during most recent telemetry
				cycle-possibly due to lost frame)
				bits 31-17 : <zero fill=""></zero>
				bit 16 : patch controller power
				bit 15: scan motor current
				bit 14: filter wheel motor current
				bit 13: -15VDC monitor
				bit 12: +15VDC monitor
				bit 11: -7.5 VDC TLM/DC/DC conv.
				bit 10: +7.5 VDC TLM/DC/DC conv.
				bit 9: +10V VDC TLM/DC/DC conv.
				bit 8: +5 VDC monitor
				bit 7: filter wheel motor temperature
				bit 6: scan motor temperature
				bit 5: filter housing controller current
				bit 4: patch temperature
				bit 3: electronics temperature
				bit 2: base plate temperature
				bit 1: radiator temperature
				bit 0: <zero fill=""></zero>
hrs_anwrd	С	1	16	Word 1 : Radiator temperature
<u>-</u>				Word 2 : Base Plate Temperature
				Word 3: Electronics Temperature
				Word 4 : Patch Temperature
				Word 5: Filter Housing Controller Current
				Word 6 : Scan Motor Temperature
				Word 7: Filter Wheel Motor Temperature
				Word 8: +5 VDC Monitor
				Word 9: +10 VDC TLM/DC/DC Conv.
				Word 10: +7.5 VDC TLM/DC/DC Conv.
				Word 11: -7.5 VDC TLM/DC/DC Conv.
				Word 12: +15 VDC Monitor
				Word 13: -15 VDC Monitor
				Word 14: Filter Wheel Motor Current
				Word 15: Scan Motor Current
				Word 15: Scan Motor Current Word 16: Patch Controller Power
			FILLED	word to . Fatch Controller Power
1 C:11 5	т.4	4	FILLER	II
hrs_filler5	I4	4	11	Unassigned (no value)

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11. FORMAT OF THE AMSUALLIB FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

AMSU-A.11a format = AMSU-A.11b format (in AMSU-A.11a, calibration and location fields are empty).

Header and record length
Header length = record length
2560 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
Name in AATT code	Type	in byte	of words	Witaning
		•	L INFORM	IATION
ama_h_siteid	С	3	1	Data set creation site ID
ama_h_blank	C	1	1	ASCII blank
ama_h_l1bversnb	I2	2	1	level 1b format version number
ama_h_l1bversyr	I2	2	1	level 1b format version year
ama_h_l1bversdy	I2	2	1	level 1b format version day of year
ama_h_reclg	I2	2	1	record length
ama_h_blksz	I2	2	1	blocksize
ama_h_hdrcnt	I2	2	1	count of header records in data set
ama_h_filler1	I2	2	3	filler
ama_h_dataname	С	42	1	data set name
ama_h_prblkid	С	8	1	processing block identification
ama_h_satid	I2	2	1	NOAA spacecraft identification code
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8= NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator
ama_h_instid	I2	2	1	AMSU-A instrument identification
				(Bits 15-8:AMSU-A2 ID - 2=EM, 6=PFM,

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Chits 7-0: AMSU-A1 ID - 1=EM, 5=PFM, 9=F1, 13=F2)		1	I		
ma_h_datatyp					10=F1, 14=F2)
ama_h_tipsrc					
12 2 1 TIP source code (0 = NAS; 1 = embedded; 2 = stored; 3 = third CDA)					
(0 = N/A; 1 = embedded; 2 = stored; 3 = third CDA)	ama_h_datatyp	I2	2	1	* -
ama_h_startdatajd	ama_h_tipsrc	I2	2	1	(0 = N/A; 1 = embedded; 2 = stored; 3 = third
ama_h_startdatayr 12 2 1 start of data set day of year ama_h_startdatatime 14 4 1 start of data set day of year ama_h_startdatatime 14 4 1 start of data set julian day (count from 00h 1 Jan 1950) ama_h_enddatajd 12 2 1 end of data set year ama_h_enddatatyr 12 2 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set UTC time of day in milliseconds ama_h_cpidsupdyr 12 2 1 year of last CPIDS update ama_h_cpidsupdyr 12 2 1 day of year of last cpids update ama_h_foller2 12 2 1 time offset for FOV 1 (ms) ama_h_filler2 12 2 filler ama2_h_iniststat1 14 4 1 AMSU-A2 instrument status <t< td=""><td>ama_h_startdatajd</td><td>I4</td><td>4</td><td>1</td><td>start of data set julian day</td></t<>	ama_h_startdatajd	I4	4	1	start of data set julian day
ama_h_startdatady 12 2 1 start of data set day of year ama_h_startdatatime 14 4 1 start of data set UTC time of day in milliseconds ama_h_enddatajd 14 4 1 end of data set julian day (count from 00h 1 Jan 1950) ama_h_enddatayr 12 2 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set UTC time of day in milliseconds ama_h_cpidsupdyr 12 2 1 year of last CPIDS update ama_h_cjouloufdy 12 2 1 day of year of last cpids update ama_h_fovloiffset 12 2 1 Redundant, but retain for compatibility ama_h_filler2 12 2 5 filler DATA SET QUALITY INDICATORS ama2_h_iniststat1 4 1 AMSU-A2 instrument status Bit 12:cold Cal pos msb	ama h startdatayr	I2	2	1	
ama_h_startdatatime	,	I2		1	•
(count from 00h 1 Jan 1950)		I4			start of data set UTC time of day in
ama_h_enddatady 12 2 1 end of data set day of year ama_h_enddatatime 14 4 1 end of data set UTC time of day in milliseconds ama_h_cpidsupdyr 12 2 1 year of last CPIDS update ama_h_cpidsupddy 12 2 1 day of year of last cpids update ama_h_fov1offset 12 2 1 Redundant, but retain for compatibility ama_h_ealparid C 2 1 Redundant, but retain for compatibility ama_h_filler2 12 2 5 filler DATA SET QUALITY INDICATORS ama2_h_inststat1 14 4 1 AMSU-A2 instrument status Bit 14:Cold Cal pos msb Bit 14:Cold Cal pos msb Bit 12:park nadir Bit 11:park cold Bit 11:park cold Bit 11:park cold Bit 12:park nadir Bit 3:sound Bit 4:survival heater on Bit 4:survival heater on	ama_h_enddatajd	I4	4	1	
ama_h_enddatatime 14 4 1 end of data set UTC time of day in milliseconds ama_h_cpidsupddy 12 2 1 year of last CPIDS update ama_h_cpidsupddy 12 2 1 day of year of last cpids update ama_h_fov1offset 12 2 1 time offset for FOV 1 (ms) ama_h_calparid C 2 1 Redundant, but retain for compatibility ama_h_filler2 12 2 5 filler DATA SET QUALITY INDICATORS ama2_h_inststat1 14 4 1 AMSU-A2 instrument status Bit 13:-15: Bit 14:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332 degrees) Bit 12:park nadir Bit 19:full scan Bit 9:full scan Bit 8-5: Bit 4: survival heater on Bit 3:module power Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0: comp motor Bit 0: Bit 0: comp motor Bit 0: comp motor Bit 1:scanner A2 power Bit 0: co	ama_h_enddatayr	I2	2	1	end of data set year
milliseconds	ama_h_enddatady	I2	2	1	end of data set day of year
ama_h_cpidsupddy I2 2 1 day of year of last cpids update ama_h_fov1offset I2 2 1 time offset for FOV 1 (ms) ama_h_calparid C 2 1 Redundant, but retain for compatibility ama_h_filler2 I2 2 5 filler DATA SET QUALITY INDICATORS ama2_h_inststat1 I4 4 1 AMSU-A2 instrument status Bit 13:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332 degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 4:strivival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred)</zero>	ama_h_enddatatime	I4	4	1	
ama_h_fov1offset 12 2 1 time offset for FOV 1 (ms) ama_h_calparid C 2 1 Redundant, but retain for compatibility ama_h_filler2 12 2 5 filler DATA SET QUALITY INDICATORS ama2_h_inststat1 I4 4 1 AMSU-A2 instrument status Bit 13:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 11:park nadir Bit 19:full scan Bit 9:full scan Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0: <zero fill=""> Bit 0:<zero fill=""> ama_h_filler3 12 2 1 filler ama2_h_statchrecnb 12 2 1 filler ama2_h_inststat2 14 4 1 AMSU-A2 second instrument status</zero></zero>	ama_h_cpidsupdyr	I2	2	1	year of last CPIDS update
ama_h_calparid C 2 1 Redundant, but retain for compatibility ama_h_filler2 12 2 5 filler DATA SET QUALITY INDICATORS ama2_h_inststat1 14 4 1 AMSU-A2 instrument status Bit 13:Cold Cal pos msb Bit 14:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 11:park cold Bit 10:park warm Bit 19:full scan Bit 8-5: Bit 8-5: Sit 1:scanne Bit 2:comp motor Bit 2:comp motor Bit 2:comp motor Bit 1:scanner A2 power Bit 0: Zero fill> Bit 1:scanner A2 power Bit 0: Zero fill> Amsuner A2 follower	ama_h_cpidsupddy	I2	2	1	day of year of last cpids update
Ama_h_filler2	ama_h_fov1offset	I2	2	1	time offset for FOV 1 (ms)
Manual	ama_h_calparid	С	2	1	Redundant, but retain for compatibility
DATA SET QUALITY INDICATORS	•	I2	2	5	· · ·
ama2_h_inststat1 I4 4 I AMSU-A2 instrument status Bit 31-15: <zero fill=""> Bit 14:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5:<zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 I filler ama2_h_statchrecnb I2 AMSU-A2 second instrument status</zero></zero></zero>		I	DATA SET	QUALITY	INDICATORS
Bit 31-15: <zero fill=""> Bit 14:Cold Cal pos msb Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5:<zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status</zero></zero></zero>	ama2 h inststat1	I4		1	
Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status</zero></zero>					Bit 31-15: <zero fill=""></zero>
Bit 13:Cold cal pos lsb (0=6.667, 1=8.333, 2=9.999, 3=13.332) degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status</zero></zero>					Bit 14:Cold Cal pos msb
(0=6.667, 1=8.333, 2=9.999, 3=13.332 degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status</zero></zero>					<u> </u>
degrees) Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 1 AMSU-A2 second instrument status</zero></zero>					<u>+</u>
Bit 12:park nadir Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 I filler ama2_h_statchrecnb I2 AMSU-A2 second instrument status</zero></zero>					
Bit 11:park cold Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 I filler ama2_h_statchrecnb I2 AMSU-A2 second instrument status</zero></zero>					
Bit 10:park warm Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero></zero>					<u> </u>
Bit 9:full scan Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero></zero>					
Bit 8-5: <zero fill=""> Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0:<zero fill=""> ama_h_filler3 I2 I2 Ifiller ama2_h_statchrecnb I2 AMSU-A2 second instrument status</zero></zero>					-
Bit 4:survival heater on Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero>					
Bit 3:module power Bit 2:comp motor Bit 1:scanner A2 power Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero>					
Bit 2:comp motor Bit 1:scanner A2 power Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero>					
Bit 1:scanner A2 power Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero>					<u>-</u>
Bit 0: <zero fill=""> ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 I AMSU-A2 second instrument status</zero>					<u> -</u>
ama_h_filler3 I2 2 1 filler ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status					-
ama2_h_statchrecnb I2 2 1 record number of status change (if 0, none occurred) ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status	ama h filler3	12	2	1	
ama2_h_inststat2		_			
ama2_h_inststat2 I4 4 1 AMSU-A2 second instrument status		12	_	•	_
	ama2 h inststat2	J4	4	1	
CHARACTER CONTRACTOR OF THE CONTRACTOR CONTR		1			(if previous word is 0, no change)

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ama1_h_inststat1	I4	4	1	AMSU-A1 instrument status Bit 31-15: <zero fill=""></zero>
				Bit 14:Cold Cal pos msb
				Bit 13:Cold cal pos lsb,
				(0=6.667, 1=8.333, 2=9.999, 3=13.332
				degrees)
				Bit 12:park nadir
				Bit 11:park cold
				Bit 10:park warm
				Bit 9:full scan,
				(if all zero, instrument is parked in warm cal)
				Bit 8-6: <zero fill=""></zero>
				Bit 5:module power connect
				Bit 4:survival heater on,
				Bit 3:phase lock loop (0=redundant,
				1=primary),
				Bit 2:scanner A1-2 power
				Bit 1:scanner A1-1 power
				Bit 0: <zero fill=""></zero>
ama_h_filler4	I2	2	1	filler
ama1_h_statchreenb	I2	2	1	record number of status change
				(if 0, none occurred)
ama1_h_inststat2	I4	4	1	AMSU-A1 second instrument status
				(if previous word is 0, no change)
ama_h_scnlin	I2	2	1	count of scan lines in this data set
ama_h_callocsclin	I2	2	1	count of calibrated, Earth located scan lines in
				this data set
ama_h_misscnlin	I2	2	1	count of missing scan lines
ama_h_datagaps	I2	2	1	count of data gaps in this data set
ama_h_okdatafr	I2	2	1	count of data frames without frame sync word
				errors
ama_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
ama_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in the
				input data
ama_h_timeseqerr	I2	2	1	time sequence error
				(0 = none; otherwise the record number of the)
				first occurrence)
ama_h_timeseqerrcode	I2	2	1	time sequence error code
				(taken from Scan Line Quality Flags, at the
				time of first occurrence)
ama_h_socclockupind	I2	2	1	socc clock update indicator
				($0 = \text{none during this orbit}$; otherwise the
				record number of the first occurrence)
ama_h_locerrind	I2	2	1	Earth location error indicator
				($0 = \text{none during this orbit}$; otherwise the
				record number of the first occurrence)
ama_h_locerrcode	I2	2	1	Earth location error code
				(taken from Scan Line Quality Flags, at the

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				time of first occurrence)
ama_h_pacsstatfield	I2	2	1	PACS Status Bit Field
1				bits 15-3 : zero fill
				bit 2 : pseudo noise (0=normal data; 1=P/N
				data)
				bit 1 : tape direction (0=time decrementing)
				bit 0 : data mode (0=test data, 1=flight data)
ama_h_pacsdatasrc	I2	2	1	PACS data source
1				0=unused, 1=Gilmore, 2=Wallops, 3=SOCC
ama_h_filler5a	I4	4	1	filler
ama_h_spare2	С	8	1	reserved for ingester
ama_h_spare3	С	8	1	reserved for decommutation
ama_h_filler5	I4	4	4	filler
		CALIBRA	ATION PA	ARAMETERS
ama_h_plloid	I2	2	1	filler
ama_h_tsensid	I2	2	3	Instrument temperature sensor ID
				A1-1, A1-2 and A2; 0=RF shelf, 1=RF Mux
ama_h_reftemp	I2	2	12	Instrument reference temps, RF Shelf
1				3 temperatures for A1-1, A1-2, A2 and A1-1
				PLLO#2
ama_h_muxtemp	I2	2	12	Instrument reference temps, RF Mux
-				3 temperatures for A1-1, A1-2, A2 and A1-1
				PLLO#2
ama_h_bias	I2	2	78	Calibration bias corrections
				Warm target bias at 3 temps and cold bias for
				15 channels,
				then warm target bias at 3 temps for Channels
				9-14 PLLO#2.
ama_h_nonlin	I4	4	63	Nonlinearity corrections
				At 3 temps for Ch 1-15 and Ch 9-14 PLLO#2.
ama_h_filler6	I4	4	4	filler
TE	MPERATU	RE TO RA	DIANCE	CONVERSION FACTORS
ama_h_temrad	I4	4	45	10^6*(Central wavenumber, Const1, Const2
				(slope)) for 15 channels
ama_h_filler7	I4	4	3	filler
			<u>NAVIGAT</u>	
ama_h_modelid	C	8	1	Reference Ellipsoid Model ID
				="GRS 80" in the actual version of AAPP
ama_h_nadloctol	I2	2	1	10 x (nadir Earth location tolerance in km)
ama_h_locbit	I2	2	1	Earth location bit field
				bits 15-3: <zero fill=""></zero>
				bit 2: dynamic attitudeerror correction (0=not
				performed)
				bit 1: reasonableness test active (0=inactive,
				1=active)
				bit 0: constant attitude error correction (0 =
				not performed)

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1- £110	12	2	1	£'11
ama_h_filler8	I2	2	1	filler
ama_h_rollerr	I2	2	1	10 ^{^3} x (constant roll attitude error, deg)
ama_h_pitcherr	I2	2	1	10 ^{^3} x (constant pitch attitude error, deg)
ama_h_yawerr	I2	2	1	10 ³ x (constant yaw attitude error in deg)
ama_h_epoyr	I2	2	1	epoch year for orbit vector
ama_h_epody	I2	2	1	day of epoch year for orbit vector
ama_h_epotime	I4	4	1	epoch UTC time of day in milliseconds for
				orbit vector
ama_h_smaxis	I4	4	1	10^6 x (semi-major axis in kilometers)
ama_h_eccen	I4	4	1	10^8 x (eccentricity)
ama_h_incli	I4	4	1	10^5 x (inclination in degrees)
ama_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
ama_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending node
				in degrees)
ama_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
ama_h_xpos	I4	4	1	10 ⁶ x (position vector x component in
				kilometers)
ama_h_ypos	I4	4	1	10 ⁶ x (position vector y component in
				kilometers)
ama_h_zpos	I4	4	1	10 ⁶ x (position vector z component in
				kilometers)
ama_h_xvel	I4	4	1	10 ⁸ x (velocity vector x-dot component
				in kilometers/second)
ama_h_yvel	I4	4	1	10 ⁸ x (velocity vector y-dot component
				in kilometers/second)
ama_h_zvel	I4	4	1	10 ⁸ x (velocity vector z-dot component
				in kilometers/second)
ama_h_earthsun	I4	4	1	10 ⁶ x (Earth/sun distance ratio)
ama_h_filler9	I4	4	4	filler
DIGITAL A	AND A	NALOG TEL	EMETRY	CONVERSION COEFFICIENTS
ama1_h_digacoef	I4	4	180	4 coefficients for:
				Scan motor A1-1; Scan motor A1-2; Horn A1-
				1; Horn A1-2; RF Mux A1-1; RF Mux A1-2;
				LO Chan 3-8 and 15; PLLO#2; PLLO#1;
				PLLO (Ref Osc); Mixer Chan 3-9 and 15;
				IF Amp Ch 11/14, 9, 10, 11; DC/DC
				convertor; IF Amp Ch 13, 14,12; RF Shelf A1-
				1 and A1-2; Det/Pre-amp; A1-1 warm load 1-4
				and centre; A1-2 warm load 1-4 and centre.
ama_h_filler10	I4	4	1	filler
ama1_h_analcoef	I4	4	54	Intercept and slope for 27 parameters
ama_h_filler11	I4	4	1	filler
ama2_h_digacoef	I4	4	76	4 coefficients for:
				Scan motor A2; Horn A2;
				RF Mux A2; Mixer/IF Amp Chan 1-2; LO
				Chan 1-2; Compensation motor, Subreflector,
				DC/DC convertor; RF Shelf; Det/Pre-amp; A2

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				warm load centre and 1-6.
ama_h_filler12	I4	4	1	filler
ama2_h_analcoef	I4	4	30	Intercept and slope for 15 parameters
ama_h_filler13	I4	4	2	filler
L	UNAR	CONTAMINA	TION COL	RRECTION (NESDIS)
ama_h_moonscnlin	I2	2	1	count of scans with Moon in space view
				(-1 = detection algorithm turned off)
ama_h_moondist	I2	2	1	100*average dist to Moon in Earth radii
ama_h_moonsunang	I2	2	1	100*angle between Moon and Sun in degrees
ama_h_filler14	I2	2	1	
METO	OP MAN	OEUVRES ID	ENTIFICA	ATION (zero fill for NOAA)
ama_h_startmanyr	I2	2	1	4 digit year
ama_h_startmandy	I2	2	1	Day of year
ama_h_startmantime	I4	4	1	Time of day in milliseconds
ama_h_endmanyr	I2	2	1	4 digit year
ama_h_endmandy	I2	2	1	Day of year
ama_h_endmantime	I4	4	1	Time of day in milliseconds
ama_h_deltav	I4	4	3	Change in velocity
ama_h_mass	I4	4	2	Spacecraft mass before and after
ama_h_filler15	I4	4	40	filler

One Data Record for one AMSU-A scan line

Name in AAPP code	Type	Word Size	Number	Meaning				
		in byte	of words					
	SCAN LINE INFORMATION							
ama_scnlin	I2	2	1	scan line number				
ama_scnlinyr	I2	2	1	scan line year				
ama_scnlindy	I2	2	1	scan line day of year				
ama_clockdrift	I2	2	1	satellite clock drift delta in milliseconds				
ama_scnlintime	I4	4	1	scan line UTC time of day in milliseconds				
ama_scnlinbit	I2	2	1	scan line bit field				
				Bit 15: 0=northbound, 1=southbound				
				Bit 14: 1=scan time corrected for clock drift				
				Bit 13-0: <zero fill=""></zero>				
ama_tipmf	I2	2	1	Major frame count				
ama_filler1	I4	4	2	filler				
ama_qualind	I4	4	1	quality indicator bit field				
ama_linqualflgs	I4	4	1	scan line quality				
ama_chqualfg	I2	2	16	Calibration quality flags for each channel (last				
				word zero fill)				
ama_filler2	I4	4	4	filler				

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		CALIBRAT	ION COE	FFICIENTS
ama_pmcal	I4	4	45	Primary calib. coeffs Second, first and zeroth order coefficients for 15 channels
ama_sdcal	I4	4	45	Secondary calib. coeffs Second, first and zeroth order coefficients for 15 channels
ama_filler3	I4	4	1	filler
			AVIGATIO	
ama_yawsteering	I2	2	3	computed yaw steering angles for METOP Yaw, pitch, roll (degrees)
ama_totattcorr	I2	2	3	Total applied attitude correction for METOP 1000* Yaw, pitch, roll (degrees)
ama_navstat	I4	4	1	navigation status bit field bits31-17: zero fill
				bit 16: 1=Earth location corrected for TIP Euler angles bits15-12: Earth location indicator 0=Earth location available 1=user ephemerics files greater than 24hours old 2=no Earth location available bits11-08: spacecraft attitude control 0=operating in YGC or nominal mode 1=operating in another mode 2=attitude exceeds nominal tolerance 3=both 1 and 2 bits07-04: attitude SMODE 0=nominal mode 1=rate nulling mode 2=YGC mode 3=search mode 4=coast mode bits03-00: attitude PWTIP\$AC 0=nominal mode/no test 1=yaw axis test in progress 2=roll axis test in progress 3=pitch axis test in progress
ama_attangtime	I4	4	1	time associated with TIP Euler angles (secs)
ama_rollang	I2	2	1	10^3*Roll angle in degrees
ama_pitchang	I2	2	1	10^3*Pitch angle in degrees
ama_yawang	I2	2	1	10^3*Yaw angle in degrees
ama_scalti ama_ang	I2 I2	2 2	90	10*spacecraft altitude (MSL) in km scan angles in degrees word1: 100*solar zenith angle, point 1 word2: 100*satellite zenith angle, point 1

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			1	
				word3: 100*local azimuth angle, point 1
				word4: 100*solar zenith angle, point 2
				word5: 100*satellite zenith angle, point 2
				word6: 100*local azimuth angle, point 2
				words. 100 local azimatii angie, point 2
				word88: 100*solar zenith angle, point 30
				word89: 100*satellite zenith angle, point 30
	T.4	4	60	word90: 100*local azimuth angle, point 30
ama_pos	I4	4	60	Earth location
				(north latitude and east longitude are positive)
				word1: 10^4*latitude in degrees, point 1
				word2: 10^4*longitude in degrees, point 1
				word3: 10^4*latitude in degrees, point 2
				word4: 10^4*longitude in degrees, point 2
				word60: 10^4*longitude in degrees, point 30
ama_filler4	I4	4	1	filler
		AMSU-A1 D	IGITAL A	TELEMETRY
ama1_sync	I2	2	1	Synchronization Sequence (hex FF)
ama1_id	I2	2	1	n.b. includes 3rd sync character
ama1_dhk	I2	2	2	Digital Housekeeping
ama1_earth_data	I2	2	17*30	4 position + 13 channels (3-15) at each antenna
wvw		_	1, 50	position
ama1_coldcal	I2	2	30	4 position + 13 channels(3-15) + 13 channels
umu1_cordear	12	2	50	repeat, cold view
ama1_temps	12	2	46	46 temperatures
ama1_warmcal	I2	$\frac{2}{2}$	30	4 position + 13 channels(3-15) + 13 channels
ama1_wamicai	12	2	30	•
om o 611 ou	I4	4	1	repeat, warm view
ama_filler5	14			filler
4 11 1	1 70	AMSU-A1 D		TELEMETRY
ama1_digbval	I2	2	1	Indicates validity of ama1_digb bits (0=valid)
ama1_digb	I2	2	1	Digital "B" Telemetry for AMSU-A1
ama_filler6	I4	4	1	filler
	AMSU	-A1 ANALOG	HOUSEK	EEPING DATA (TIP)
ama1_ahkval	I4	4	1	Each bit indicates validity of ama1_ahk word
				(0 = valid, 1 = invalid)
ama1_ahk	С	1	28	27 analogue words (word 28 is zero-fill)
ama_filler7	I4	4	1	filler
	l l	AMSU-A2 DI	IGITAL A	TELEMETRY
ama2_sync	I2	2	1	Synchronization Sequence (hex FF)
ama2_id	I2	2	1	n.b. includes 3rd sync character
ama2_dhk	12	2	2	Digital Housekeeping
ama2_earth_data	12 I2	2	4*30	2 position + 2 channels (1-2) at each antenna
amaz_carm_uata	12	<i>_</i>	4.30	position + 2 channels (1-2) at each antenna position
ama) aclded	10	2	6	1
ama2_coldcal	I2	2	6	2 position + 2 channels(1-2) + 2 channels
2 .	7.0		20	repeat, cold view
ama2_temps	I2	2	20	20 temperatures

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ama2_warmcal	I2	2	6	2 position + 2 channels(1-2) + 2 channels
				repeat, warm view
ama_filler8	I4	4	1	filler
		AMSU-A2 D	IGITAL B	TELEMETRY
ama2_digbval	I2	2	1	Indicates validity of ama2_digb (0=valid)
ama2_digb	I2	2	1	Digital "B" Telemetry for AMSU-A2
ama_filler9	I4	4	1	filler
	AMSU	-A2 ANALOG	HOUSEK	EEPING DATA (TIP)
ama2_ahkval	I4	4	1	Each bit indicates validity of ama2_ahk word
				(0 = valid, 1=invalid)
ama2_ahk	C	1	16	15 analogue words (word 16 is zero-fill)
LUNAR CONTA	MINAT	TION CORREC	CTION (NE	SDIS method using antenna patterns)
ama_mooncountcor	C	1	15	Raw count minus corrected (0 to 255)
ama_filler10	C	1	1	filler
ama_moonazimuth	I2	2	3	100*azimuth in deg for A1-1, A1-2, A2
ama_moonelev	I2	2	3	100*elevation in deg for A1-1, A1-2, A2
ama_filler11	I4	4	1	filler

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12. FORMAT OF THE AMSUB.L1B FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

AMSU-B.11a format = AMSU-B.11b format (in AMSU-B.11a, calibration and location fields are empty).

Header and record length

Header length = record length

3072 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning					
Traine in 71/11 Code	Турс	in byte	of words	Witaming					
	GENERAL INFORMATION								
amb_h_siteid	С	3	1	Data set creation site ID					
				CMS = Centre de MeteorologiSpatiale/France					
				NSS = NESDIS/USA					
				UKM = UK Met Office					
amb_h_blank	С	1	1	Zero fill					
amb_h_l1bversnb	I2	2	1	level 1b format version number					
amb_h_l1bversyr	I2	2	1	level 1b format version year					
amb_h_l1bversdy	I2	2	1	level 1b format version day of year					
amb_h_reclg	I2	2	1	logical record length					
amb_h_blksz	I2	2	1	blocksize					
amb_h_hdrcnt	I2	2	1	count of header records in data set					
amb_h_filler1	I2	2	3	Zero fill					
amb_h_dataname	С	42	1	data set name					
amb_h_prblkid	C	8	1	processing block identification					
amb_h_satid	I2	2	1	Spacecraft identification code					
				4=NOAA-15 (NOAA-K)					
				2=NOAA-16 (NOAA-L)					
				6=NOAA-17 (NOAA-M)					
amb_h_instid	I2	2	1	AMSU-B instrument identification					
amb_h_datatyp	I2	2	1	data type code					
				(11 = AMSU-B)					
amb_h_tipsrc	I2	2	1	TIP source code					
				(0 = N/A; 1 = embedded; 2 = stored; 3 = third					
				CDA; $4 = HRPT$ embedded)					

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amb h startdataid	I4	4	1	start of data sat julian day
amb_h_startdatajd	I2	2	1	start of data set julian day
amb_h_startdatayr	1			start of data set year
amb_h_startdatady	I2	2	1	start of data set day of year
amb_h_startdatatime	I4	4	1	start of data set UTC time of day in
	T.4			milliseconds
amb_h_enddatajd	I4	4	1	end of data set julian day
amb_h_enddatayr	I2	2	1	end of data set year
amb_h_enddatady	I2	2	1	end of data set day of year
amb_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
amb_h_cpidsupdyr	I2	2	1	year of last CPIDS update
amb_h_cpidsupddy	I2	2	1	day of year of last cpids update
amb_h_fov1offset	I2	2	1	time offset for FOV 1 (ms)
amb_h_calparid	С	2	1	Redundant, but retain for compatibility
amb_h_filler2	I2	2	5	Zero fill
	I	DATA SET		
amb_h_inststat1	I4	4	1	AMSU-B instrument status
amb_h_filler3	I2	2	1	Zero fill
amb_h_statchreenb	I2	2	1	record number of status change
	12		1	(if 0, none occurred)
amb_h_inststat2	I4	4	1	AMSU-B second instrument status
amo_n_mststat2	17	7	1	(if previous word is 0, no change)
amb_h_scnlin	I2	2	1	count of scan lines in this data set
amb_h_callocsclin	I2 I2	2	1	
amb_n_canoescm	12	2	1	count of calibrated, Earth located scan lines in this data set
and b missonlin	12	2	1	
amb_h_misscnlin	I2	2	1	count of missing scan lines
amb_h_datagaps	I2	2	1	count of data gaps in this data set
amb_h_okdatafr	I2	2	1	count of data frames without frame sync word
		_		errors
amb_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
amb_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in the
				input data
amb_h_timeseqerr	I2	2	1	time sequence error
				(0 = none; otherwise the record number of the)
				first occurrence)
amb_h_timeseqerrcode	I2	2	1	time sequence error code
amb_h_socclockupind	I2	2	1	socc clock update indicator
				($0 = \text{none during this orbit}$; otherwise the
				record number of the first occurrence)
amb_h_locerrind	I2	2	1	Earth location error indicator
				(0 = none during this orbit; otherwise the)
				record number of the first occurrence)
amb_h_locerrcode	I2	2	1	Earth location error code
amb_h_pacsstatfield	I2	2	1	PACS Status Bit Field
pacostatiioid		_	_	bits 15-3 : zero fill
				bit 2 : pseudo noise (0=normal data; 1=P/N
				data)
				uata)

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			1	
				bit 1 : tape direction (0=time decrementing)
amh h maadataana	12		1	bit 0 : data mode (0=test data, 1=flight data)
amb_h_pacsdatasrc	I2	2	1	PACS data source
amb b apara?	C	8	1	0=unused, 1=Gilmore, 2=Wallops, 3=SOCC reserved for ingester
amb_h_spare2	C	8	1	č
amb_h_spare3	I4	4	4	reserved for decommutation Zero fill
amb_h_filler4	14	<u> </u>		ARAMETERS
amb_h_tsensid	I2	2	1	Instrument temperature sensor ID
amo_n_ischsiu	12	<i>L</i>	1	(0 = Mixer Ch 18-20; $1 = Mixer Ch 16$)
amb_h_filler5	I2	2	1	Zero fill
amb_h_reftemp	I2 I2	2	3	Instrument reference temps (Mixer 18-20)
amb_h_reftemp2	I2 I2	2	3	Instrument reference temps (Mixer 16)
amb_h_bias	I2 I2	2	20	Calibration bias corrections
amb_h_nonlin	I4	4	15	Nonlinearity corrections
amb_h_filler6	I4 I4	4	4	Zero fill
	MPERATU	-		CONVERSION FACTORS
amb_h_temrad	I4	4	15	10^6*(Central wavenumber, const1 and
		•	15	const2)
amb_h_filler7	I4	4	4	Zero fill
danie_n_iniei /				TH LOCATION
amb_h_modelid	С	8	1	Reference Ellipsoid Model ID
				="GRS 80" in the actual version of AAPP
amb_h_nadloctol	I2	2	1	10 x (nadir Earth location tolerance in
				kilometers)
amb_h_locbit	I2	2	1	Earth location bit field
				bit 0 : constant attitude error correction (0 =
				not performed)
				bit 1 : reasonableness test (0= inactive,
				1=active)
				bit 2 : dynamic attitude error correction (0=not
				performed)
amb_h_filler8	I2	2	1	Zero fill
amb_h_rollerr	I2	2	1	10^3 x (constant roll attitude error in degrees)
amb_h_pitcherr	I2	2	1	10^3 x (constant pitch attitude error in degrees)
amb_h_yawerr	I2	2	1	10^3 x (constant yaw attitude error in degrees)
amb_h_epoyr	I2	2	1	epoch year for orbit vector
amb_h_epody	I2	2	1	day of epoch year for orbit vector
amb_h_epotime	I4	4	1	epoc UTC time of day in milliseconds for
1 1	T.4		4	orbit vector
amb_h_smaxis	I4	4	1	10^6 x (semi-major axis in kilometers)
amb_h_eccen	I4	4	1	10^8 x (eccentricity)
amb_h_incli	I4	4	1	10^5 x (inclination in degrees)
amb_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
amb_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending node in degrees)
amb_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)

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amb_h_xpos	I4	4	1	10^6 x (position vector x component in		
				kilometers)		
amb_h_ypos	I4	4	1	10^6 x (position vector y component in		
				kilometers)		
amb_h_zpos	I4	4	1	10^6 x (position vector z component in		
				kilometers)		
amb_h_xvel	I4	4	1	10^8 x (velocity vector x-dot component		
				in kilometers/second)		
amb_h_yvel	I4	4	1	10^8 x (velocity vector y-dot component in		
-				kilometers/second)		
amb_h_zvel	I4	4	1	10^8 x (velocity vector z-dot component in		
				kilometers/second)		
amb_h_earthsun	I4	4	1	10^6 x (Earth/sun distance ratio)		
amb_h_filler9	I4	4	4	Zero fill		
DIGITAL A	AND A	ANALOG TEI	LEMETRY	CONVERSION COEFFICIENTS		
amb_h_digacoef	I2	2	96	AMSU-B digital A coeffs		
amb_h_filler10	I4	4	4	Zero fill		
amb_h_analcoef	I4	4	72	AMSU-B analogue coeffs		
CORR	ECTIO	NS FOR S-BA	AND TRAN	SMITTER INTERFERENCE		
amb_h_filler11	I4	4	2	Zero fill		
amb_h_CountsCorr	I2	2	5*21*4	Normal bias		
amb_h_filler12	I4	4	2	Zero fill		
amb_h_txpow	I2	2	4			
amb_h_filler13	I4	4	2	Zero fill		
amb_h_NewCorr	I2	2	5*33*3	Anomalous bias		
LUNAR CONTAMINATION						
amb_h_monscnlin	I2	2	1	count of scans with moon in space view		
				(-1 = detection algorithm turned off)		
amb_h_moonthresh	I2	2	1	100 x lunar angle threshold in degrees		
		SI	PARE WO			
amb_h_filler14	I2	2	107	Zero fill		
	1	1	1			

One Data Record for one AMSU-B scan line

Name in AAPP code	Type	Word Size	Number	Meaning		
		in byte	of words			
SCAN LINE INFORMATION						
amb_scnlin	I2	2	1	scan line number		
amb_scnlinyr	I2	2	1	scan line year		
amb_scnlindy	I2	2	1	scan line day of year		
amb_clockdrift	I2	2	1	satellite clock drift delta in milliseconds		
amb_scnlintime	I4	4	1	scan line UTC time of day in milliseconds		
amb_scnlinbit	I2	2	1	scan line bit field		

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	1 1			Bit 15: 0=northbound, 1=southbound
				Bit 14: 1=scan time corrected for clock drift
				Bit 13-0: <zero fill=""></zero>
and times	12	2	1	
amb_tipmf	I2	2	1	Major frame count
amb_filler1	I4	4	2	Zero fill
amb_qualind	I4	4	1	quality indicator bit field
amb_linqualflgs	I4	4	1	scan line quality
amb_chqualflg	I2	2	5	Calibration quality flags for each channel
amb_filler2	I2	2	9	Zero fill
		CALIBRAT	ION COE	EFFICIENTS
amb_pmcal	I4	4	15	Primary calib. coeffs
				Second, first and zeroth order coefficients for
				5 channels
amb_sdcal	I4	4	15	Secondary calib. coeffs
				Second, first and zeroth order coefficients for
				5 channels
amb_filler3	I2	2	5	Zero fill
			VIGATIO	
amb_totattcorr	I2	2	3	Total applied attitude correction
				1000*yaw, pitch, roll (degrees)
amb_navstat	I4	4	1	navigation status bit field
anio_navstat		·	1	bit 17: Nadir Earth location OK (see
				amb_h_nadloctol) (1=true)
				bit 16: Earth location corrected for Euler
				angles (1=true)
				bits 15-12: Earth location indicator
				0=Earth location available
				1=user ephemerics files greater than 24hours old
				2=no Earth location available
				bits11-08: spacecraft attitude control
				0=operating in YGC or nominal mode
				1=operating in another mode
				2=attitude exceeds nominal tolerance
				3=both 1 and 2
				bits07-04: attitude SMODE
				0=nominal mode
				1=rate nulling mode
				2=YGC mode
				3=search mode
				4=coast mode
				bits03-00: attitude PWT1\$AC
				0=nominal mode/no test
				1=yaw axis test in progress
				2=roll axis test in progress
			<u> </u>	3=pitch axis test in progress
amb_attangtime	I4	4	1	time associated angles (seconds)
amb_rollang	I2	2	1	10^3*Roll angle in degrees

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amb_pitchang	I2	2	1	10^3*Pitch angle in degrees
amb_yawang	I2	2	1	10^3*Yaw angle in degrees
amb_scalti	I2	2	1	10*spacecraft altitude (MSL) in km
amb_ang	I2	2	270	scan angles in degrees
				word1: 100*solar zenith angle, point 1
				word2: 100*satellite zenith angle, point 1
				word3: 100*local azimuth angle, point 1
				word4: 100*solar zenith angle, point 2
				word5: 100*satellite zenith angle, point 2
				word6: 100*local azimuth angle, point 2
				wordo. 100 Total azimaan angie, point 2
				word268: 100*solar zenith angle, point 90
				word269: 100*satellite zenith angle, point 90
				word270: 100 satellite zeinth angle, point 90 word270: 100*local azimuth angle, point 90
amh nac	I4	4	180	Earth location
amb_pos	14	'1	100	(north latitude and east longitude are positive)
				word1: 10^4*latitude in degrees, point 1
				0 1
				word2: 10^4*longitude in degrees, point 1 word3: 10^4*latitude in degrees, point 2
				C 1
				word4: 10^4*longitude in degrees, point 2
1	10	2	4	word180: 10^4*longitude in degrees, point 90
amb_moonang	I2	2	4	100*angle (deg) between moon and each space
		ANACTI	D CENIC	view
1 1 1	10		-B SENSO	
amb_earth_data	I2	2	540	Word1: shaft position for FOV1
				Word2: scene counts FOV1, channel 16
				Word3: scene counts FOV1, channel 17
				Word4: scene counts FOV1, channel 18
				Word5: scene counts FOV1, channel 19
				Word6: scene counts FOV1, channel 20
				Word7: shaft position for FOV2
				Word540: scene counts FOV90, channel 20
amb_filler5	I4	4	2	Zero fill
			1	TION DATA
amb_coldcal	I2	2	24	Word1: shaft position for space view 1
				Word2: counts for space view 1, channel 16
				Word3: counts for space view 1, channel 17
				Word4: counts for space view 1, channel 18
				Word5: counts for space view 1, channel 19
				Word6: counts for space view 1, channel 20
				Word7: shaft position for space view 2
				Word24: counts for space view 4, channel 20
amb_warmcal	I2	2	24	Word1: shaft position for target view 1
				Word2: counts for target view 1, channel 16
				Word3: counts for target view 1, channel 17
	1		<u> </u>	

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				Word4: counts for target view 1, channel 18 Word5: counts for target view 1, channel 19 Word6: counts for target view 1, channel 20
				Word7: shaft position for target view 2 Word24: counts for target view 4, channel 20
amb_filler6	I4	4	2	Zero fill
		AMSU-B DI	GITAL A	TELEMETRY
amb_digaval	I4	4	1	Invalid data bit flags
amb_filler7	I4	4	1	Zero fill
amb_diga	I2	2	2	digital data words A01 and A02
amb_temps	I2	2	24	digital data words A03 through A26
amb_filler8	I4	4	3	Zero fill
		AMSU-B A	NALOG T	ELEMETRY
amb_ahkval	I4	4	1	Invalid analogue data bit flags
amb_ahk	I2	2	27	Added STX and SARR information
			FILLERS	
amb_filler9	I2	2	1	Zero fill
amb_filler10	I4	4	67	Zero fill

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13. FORMAT OF THE MHS.L1B FILE

MHS.11a format = MHS.11b format (in MHS.11a, calibration and location fields are empty).

<u>Header and record length</u> Header length = record length 3072 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number of	Meaning				
		in byte	words					
GENERAL INFORMATION								
mhs_h_siteid	С	3	1	Data set creation site ID				
				CMS = Centre de Meteorologie				
				Spatiale/France				
				NSS = NESDIS/USA				
				UKM = UK Met Office				
mhs_h_blank	C	1	1	Zero fill				
mhs_h_l1bversnb	I2	2	1	level 1b format version number				
mhs_h_l1bversyr	I2	2	1	level 1b format version year				
mhs_h_l1bversdy	I2	2	1	level 1b format version day of year				
mhs_h_reclg	I2	2	1	logical record length				
mhs_h_blksz	I2	2	1	blocksize				
mhs_h_hdrcnt	I2	2	1	count of header records in data set				
mhs_h_filler1	I2	2	3	Zero fill				
mhs_h_dataname	C	42	1	data set name				
mhs_h_prblkid	C	8	1	processing block identification				
mhs_h_satid	I2	2	1	Spacecraft identification code:				
				7=NOAA-18 (NOAA-N)				
				8=NOAA-19 (NOAA-N')				
				11=Metop-B (Metop-1)				
				12=Metop-A (Metop-2)				
				13=Metop-C (Metop-3)				
				14=Metop simulator				
mhs_h_instid	I2	2	1	MHS instrument identification				
				(0 = EM, 1 = PFM (NOAA-N), 2 = FM2				
				(NOAA-N'), 3 = FM3 (Metop-1) (TBC), 4				
				= FM4 (Metop-3) (TBC), $5 =$ FM5 (Metop-				
				(2) (TBC))				

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		I		
mhs_h_datatyp	I2	2	1	data type code
				(12 = MHS)
mhs_h_tipsrc	I2	2	1	TIP source code
				(0 = unused, i.e. GAC/HRPT/LAC data; 1 =
				GAC-embedded AMSU and TIP; 2 = stored
				TIP; 3 = HRPT-embedded AMSU and TIP;
				4 = stored AIP (SAIP)
mhs_h_startdatajd	I4	4	1	start of data set julian day starting from 0 at
				00h, 1 Jan 1950.
mhs_h_startdatayr	I2	2	1	start of data set year, 4 digits.
mhs_h_startdatady	I2	2	1	start of data set day of year
mhs_h_startdatatime	I4	4	1	start of data set UTC time of day in
				milliseconds
mhs_h_enddatajd	I4	4	1	end of data set julian day
mhs_h_enddatayr	I2	2	1	end of data set year
mhs_h_enddatady	I2	2	1	end of data set day of year
mhs_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
mhs_h_cpidsupdyr	I2	2	1	year of last CPIDS update
mhs_h_cpidsupddy	I2	2	1	day of year of last cpids update
mhs_h_fov1offset	I2	2	1	time offset for FOV 1 (ms)
mhs_h_filler2	I2	2	5	Zero fill
		DATA SET Q		
mhs_h_inststat1	I4	4	1	MHS instrument status
			1	Bits 31-24: as for mhs_mode
				Bits 23-00: as for mhs_switchstat
mhs_h_filler3	I2	2	1	Zero fill
mhs_h_statchreenb	I2	2	1	record number of status change
inis_n_statemeene	12	_	1	(if 0, none occurred)
mhs_h_inststat2	I4	4	1	MHS second instrument status
	1	'	1	(if previous word is 0, no change)
mhs_h_scnlin	I2	2	1	count of scan lines in this data set
mhs_h_callocsclin	12	2	1	count of scali lines in this data set
mis_n_canoesemi	12	2	1	in this data set
mhs_h_misscnlin	I2	2	1	count of missing scan lines
mhs_h_datagaps	12	2	1	count of data gaps in this data set
mhs_h_moonscnlin	I2	2	1	count of data gaps in this data set
IIIIs_II_IIIOOIIsCIIIII	12	۷	1	(-1 = detection algorithm turned off)
mhs_h_okdatafr	I2	2	1	
liins_n_okdatair	12	2	1	count of data frames without frame sync word errors
mbs b massmanityrann	12	2	1	
mhs_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
mhs_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in
1 1	10		1	the input data
mhs_h_timeseqerr	I2	2	1	time sequence error
				(0 =none; otherwise the record number of
1 1	10			the first occurrence)
mhs_h_timeseqerrcode	I2	2	1	time sequence error code

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mhs_h_socclockupind	I2	2	1	socc clock update indicator		
imis_ii_socciockapina	12	_	1	(0 = none during this orbit; otherwise the)		
				record number of the first occurrence)		
mhs_h_locerrind	I2	2	1	earth location error indicator		
				(0 = none during this orbit; otherwise the)		
				record number of the first occurrence)		
mhs_h_locerrcode	I2	2	1	Earth location error code		
mhs_h_pacsstatfield	I2	2	1	PACS Status Bit Field		
				bits 15-3 : zero fill		
				bit 2 : pseudo noise (0=normal data; 1=P/N		
				data)		
				bit 1 : tape direction (0=time		
				decrementing) bit 0 : data mode (0=test data, 1=flight		
				data)		
mhs_h_pacsdatasrc	I2	2	1	PACS data source		
mis_n_paesdatasre	12	2	1	0=unused, 1=Gilmore, 2=Wallops,		
				3=SOCC		
mhs_h_spare2	С	8	1	reserved for ingester		
mhs_h_spare3	С	8	1	reserved for decommutation		
mhs_h_filler4	I2	2	8	Zero fill		
CALIBRATION PARAMETERS						
mhs_h_tsensid	I2	2	1	Instrument temperature sensor ID		
				0 = primary (LO H5 temperature [QBS5])		
				1 = secondary (LO H1 temperature		
1 1 (*11 5"	10	2	1	[QBS1])		
mhs_h_filler5	I2 I2	2 2	6	Zero fill		
mhs_h_reftemp	12	2	0	Instrument reference temps, min, nominal, max (primary and secondary)		
mhs_h_bias	I2	2	35	Calibration bias corrections. For each of 5		
IIIIS_II_DIAS	12	2	33	channels:		
				Warm load temp corr (at 3 instr temps)		
				Cold space temp corr (for 4 profiles)		
mhs_h_nonlin	I4	4	30	Nonlinearity corrections. For each LO (LO		
				A and LO B):		
				For each of 5 channels:		
				Nonlin correction at 3 instr temps		
				(min,nom,max)		
mhs_h_filler6	I4	4	4	Zero fill		
				NVERSION FACTORS		
mhs_h_temrad	I4	4	15	10^6*(Central wavenumber, const1 and		
mhs_h_filler7	I4	4	4	zero fill		
IIIIIS_II_IIIICI /		<u> </u>	1			
mhs_h_modelid	С	8	1	Reference Ellipsoid Model ID		
iiiiis_ii_iiiouciiu		G	1	Terefeliee Empsola Wodel ID		
mhs_h_nadloctol	I2	2	1	10 x (nadir Earth location tolerance in		
<u> </u>		<u> </u>		(

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				kilometers)
mhs_h_locbit	I2	2	1	Earth location bit field Bit 2: dynamic
		_	_	attitude error correction (0=not performed,
				1=performed)
				Bit 1: reasonableness test (0=inactive,
				1=active)
				Bit 0 : constant attitude error correction (0
				= not performed, 1=performed)
mhs_h_filler8	I2	2	1	Zero fill
mhs_h_rollerr	12	2	1	10^3 x (constant roll attitude error in
			_	degrees)
mhs_h_pitcherr	I2	2	1	10^3 x (constant pitch attitude error in
rr_p.ve.re		_	_	degrees)
mhs_h_yawerr	I2	2	1	10 ³ x (constant yaw attitude error in
iiiis_ii_juweii		2	1	degrees)
mhs_h_epoyr	I2	2	1	epoch year for orbit vector
mhs_h_epody	I2	2	1	day of epoch year for orbit vector
mhs_h_epotime	I4	4	1	epoc UTC time of day in milliseconds for
mis_ii_epotime		•	1	orbit vector
mhs_h_smaxis	I4	4	1	10^6 x (semi-major axis in kilometers)
mhs_h_eccen	I4	4	1	10°8 x (eccentricity)
mhs_h_incli	I4	4	1	10^5 x (eccentreity) 10^5 x (inclination in degrees)
mhs_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
mhs_h_rascnod	I4	4	1	10 ⁵ x (right ascension of the ascending
nins_n_raschou	14	-	1	node in degrees)
mhs_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
mhs_h_xpos	I4	4	1	10 ⁶ x (position vector x component in
nins_n_xpos	14	-	1	kilometers)
mhs_h_ypos	I4	4	1	10 ⁶ x (position vector y component in
nins_n_ypos	14	-	1	kilometers)
mhs_h_zpos	I4	4	1	10 ⁶ x (position vector z component in
nins_n_zpos	14	-	1	kilometers)
mhs_h_xvel	I4	4	1	10 ⁸ x (velocity vector x-dot component
IIIIIS_II_X VCI	14	4	1	in kilometers/second)
mhs_h_yvel	I4	4	1	10 ⁸ x (velocity vector y-dot component in
IIIIS_II_y vci	14	-	1	kilometers/second)
mhs_h_zvel	I4	4	1	10 ⁸ x (velocity vector z-dot component in
IIIIS_II_ZVCI	14	4	1	kilometers/second)
mhs h earthsun	I4	4	1	10^6 x (Earth/sun distance ratio
mms_n_earmsun	14	4	1	relative to the mean distance of 1AU)
mba h fillan0	I4	1	4	
mhs_h_filler9		4 ENT AND D	4 ESISTANCE	Zero fill
	CURE, CURRI		_	
mhs_h_therm	I4	4	5	5 coefficients for the 24 thermistors
mhs_h_filler10	I4	4	4	Zero fill
mhs_h_currcoef	I4	4	12	Current sensors
1 1	**	4	40	2 coeffs for each of 6 current sensors
mhs_h_prtcoef	I4	4	40	Cal target PRTs: resistance to temperature

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			T	TE DIE 4 1 DIE D
				For PIE-A and PIE-B,
				4 coefficients for each of 5 PRTs
mhs_h_survival	I4	4	6	Survival volts to temperature conversion
				Same coefficients for all 3 sensors
				Note 1 volt = 0.02 counts
mhs_h_antpos	I4	4	1	Antenna degrees per count
				Value = $10^8 \times 0.00703125$
mhs_h_refres	I4	4	6	10^4 x reference resistance in ohms
				PIE-A 3 channels, PIE-B 3 channels
		THR	ESHOLDS	
mhs_h_moonthresh	I2	2	1	100 x lunar angle threshold in degrees
RFI COR	RECTION	, AS FOR AMS	SU-B, OR Z	ERO FILL IF NOT NEEDED
mhs_h_CountsCorr	I2	2	5*21*4	Normal bias, ordered by channel, FOV,
				transmitter
mhs_h_filler11	I2	2	4	Zero fill
mhs_h_txpow	I2	2	4	10*Mean power in counts
mhs_h_filler12	I2	2	5	Zero fill
	ME'	TOP MANOEU	JVRES IDE	ENTIFICATION
mhs_h_startmanyr	I2	2	1	4 digit year
mhs_h_startmandy	I2	2	1	Day of year
mhs_h_startmantime	I4	4	1	Time of day in milliseconds
mhs_h_endmanyr	I2	2	1	4 digit year
mhs_h_endmandy	I2	2	1	Day of year
mhs_h_endmantime	I4	4	1	Time of day in milliseconds
mhs_h_delav	I4	4	3	Change in velocity
mhs_h_mass	I4	4	2	Spacecraft mass before and after
		SPA	RE WORD	S
mhs_h_filler13	I2	2	642	

One Data Record for one MHS scan line

Name in AAPP code	Type	Word Size	Number	Meaning				
		in byte	of words					
SCAN LINE INFORMATION								
mhs_scnlin	I2	2	1	scan line number				
mhs_scnlinyr	I2	2	1	scan line year				
mhs_scnlindy	I2	2	1	scan line day of year				
mhs_clockdrift	I2	2	1	satellite clock drift delta in				
				milliseconds				
mhs_scnlintime	I4	4	1	scan line UTC time of day in				
				milliseconds				
mhs_scnlinbit	I2	2	1	scan line bit field				
				Bit 15: 0=northbound, 1=southbound				
				Bit 14: 0=not corrected, 1=scan time				

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			1	
				corrected for clock drift
				Bit 13-0: <zero fill=""></zero>
mhs_tipmf	I2	2	1	Major frame count
mhs_coarsetime	I4	4	1	Coarse MHS on board time (OBT)
				(Time since last reset to zero)
mhs_finetime	I2	2	1	Fine MHS OBT. Fraction of second
				since last
				increment of coarse time. Res 2^-16
				sec, range 0-65535
mhs_modeflg	C	1	1	MHS mode flag: 3=scan, 4=fixed view.
				Rest are empty science data.
mhs_filler1	C	1	1	Zero fill
		QUALI	TY INDI	CATORS
mhs_qualind	I4	4	1	quality indicator bit field
				bit 31: do not use for product generation
				bit 30: time sequence error detected within this
				scan
				bit 29: data gap precedes this scan
				bit 28: insufficient data for calibration
				bit 27: Earth location data not available
				bit 26: first good time following clock update
				bit 25: instrument status changed with this scan
				bit 24-5: zero fill
mhs_linqualflgs	I4	4	1	scan line quality
				bit 31: time field bad; probably inferred from
				previous good time
				bit 30: time field bad; can't be inferred from
				previous good time
				bit 29: time discontinuity
				bit 28: repeats scan times previously accepted
				bit 27-19: zero fill
				bit 18: not calibrated because of satellite
				manoeuvre (Metop)
				bit 17: one of more space views moon
				contaminated
				bit 16: moon-contaminated scan able to be
				calibrated
				bit 15: not calibrated because of bad time
				bit 14: calibrated using fewer than preferred no
				of scan lines
				bit 13: not calibrated because of bad or
				insufficient PRT data
				bit 12: calibrated with marginal PRT data
				bit 11: some uncalibrated channels
				bit 10: uncalibrated due to instrument mode
				bit 09: questionable calibration: antenna
				position error space view
				bit 08: questionable calibration: antenna

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				bit 17: Nadir Earth location OK (see
				mhs_h_nadloctol) (1=true)
				bit 16: Earth location corrected for Euler angles
				(1=true)
				bits15-12: Earth location indicator
				0=Earth location available
				1=user ephemerics files greater than 24hours
				old
				2=no Earth location available
				bits11-08: spacecraft attitude control
				0=operating in YGC or nominal mode
				1=operating in another mode
				2=attitude exceeds nominal tolerance
				3=both 1 and 2
				bits07-04: attitude SMODE
				0=nominal mode
				1=rate nulling mode
				2=YGC mode
				3=search mode
				4=coast mode
				bits03-00: attitude PWTIP\$AC
				0=nominal mode/no test
				1=yaw axis test in progress
				2=roll axis test in progress
				3=pitch axis test in progress
mhs_attangtime	I4	4	1	time associated with Euler angles (seconds)
mhs_rollang	I2	2	1	10 ³ *Roll angle in degrees
mhs_pitchang	I2	2	1	10 ³ *Pitch angle in degrees
mhs_yawang	I2	2	1	10 ³ *Yaw angle in degrees
mhs_scalti	I2	2	1	10*spacecraft altitude (MSL) in km
mhs_ang	I2	2	270	scan angles in degrees
				word1: 100*solar zenith angle, point 1
				word2: 100*satellite zenith angle, point 1
				word3: 100*local azimuth angle, point 1
				word4: 100*solar zenith angle, point 2
				word5: 100*satellite zenith angle, point 2
				word6: 100*local azimuth angle, point 2
				word268: 100*solar zenith angle, point 90
				word269: 100*satellite zenith angle, point 90
				word270: 100*local azimuth angle, point 90
mhs_pos	I4	4	180	Earth location
				(north latitude and east longitude are positive)
				word1: 10^4*latitude in degrees, point 1
				word2: 10^4*longitude in degrees, point 1
				word3: 10^4*latitude in degrees, point 2
				word4: 10^4*longitude in degrees, point 2

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				word180: 10^4*longitude in degrees, point 90
mhs_moonang	I2	2	4	100*angle (deg) between moon and each space
mins_moonang		2	7	view
		MH	S SENSO	
mhs_earth_data	I2	2	540	90 x [position, counts(H1-H5)]
mhs_filler4	I4	4	2	Zero fill
IIIIIS_IIIICI4	14		1	FION DATA
mha aaldaal	I2	2	24	
mhs_coldcal				4 x [position, counts(H1-H5)]
mhs_warmcal	I2	2	24	4 x [position, counts(H1-H5)]
mhs_filler5	I4	4	2	Zero fill
1 4 1		MHS POS		LIDITY FLAGS
mhs_earthval	C	1	12	0= position OK. 1 bit per FOV
				FOV1-8 = Word 1 bits 0-7, etc.
1 1		1	1	FOV89-90 = Word 12 bits 0-1
mhs_spaceval	C	1	1	Bits 0-3
mhs_targval	C	1	<u> </u>	Bits 0-3
, ,		MHS FULL	<u>HOUSEKI</u>	EEPING DATA
mhs_mode	C	1	1	bits 7-4: 3=scan, 4=fixed view
				bit 3: 0=PIE-A, 1=PIE-B
				bits 2-0: Subcomm code (for telemetry packet
			_	data)
mhs_fault	C	1	5	Word 1-4 Telecommand acknowledgement
				Word 5 Fault code:
				bits 7-3: Fault in PSU current, thermistor,
				switch, processor, motor
				bit 2: DC offset error (change in DC offset
				required)
				bit 1: scan control error
			_	bit 0: ref clock error
mhs_switchstat	C	1	3	Word 1:
				bit 7: H4 backend (0=off, 1=on)
				bit 6: H3 backend (0=off, 1=on)
				bit 5: H3/H4 LO selected (0=A, 1=B)
				bit 4: H3/H4 front-end (0=off, 1=on)
				bit 3: H2 LO selected (0=A, 1=B)
				bit 2: H2 front-end (0=off, 1=on)
				bit 1: H1 LO selected (0=A, 1=B)
				bit 0: H1 front-end (0=off, 1=on)
				Word 2:
				bit 7: PROM (1=failed ON)
				bit 6: sig proc / scan electronics (0=off, 1=on)
				bit 5: Aux heaters (0=off, 1=on)
				bit 4: Scan mech operational heaters (0=off,
				1=on)
				bit 3: Receiver operational heaters (0=off,
				1=on)
				bit 2: Rx CV (0=off, 1=on)
				bit 1: H5 LO selected (0=A, 1=B)

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			I	1', 0 11" ' (0 66.4
				bit 0: H5 receiver (0=off, 1=on)
				Word 3: Flywheel Drive Mechanism (FDM) and
				Reflector Drive Mech (RDM)
				bit 7/6: FDM/RDM motor current trip status
				(0=enabled, 1=disabled)
				bit 5/4: FDM/RDM motor supply (0=off,
				1=on)
				bit 3/2: FDM/RDM motor sensors selected
				(0=A, 1=B)
				bit 1/0: FDM/RDM zero position sensors
				(0=A, 1=B)
mhs_temps	C	1	24	Range 0-255 for 24 thermistors
				Word 1-4: LO temps H1, H2, H3/H4, H5
				Word 5-8: Mixer temps H1, H2, H3/H4, H5
				Word 9-10: Quasi optic baseplate #1, #2
				Word 11-12: IF baseplate #1, #2
				Word 13-14: Scan mechanism core, housing
				Word 15-16: RDM, FDM Scan Sensor Head
				Module
				Word 17-19: Structure 1, 2, 3
				Word 20: Processor module
				Word 20: 1 rocessor module Word 21: Main DC/DC convertor
				Word 22-23: Scan Control Electronics RDM,
				FDM
				Word 24: RF DC/DC convertor
mhs_current	C	1	6	6 current sensors
mhs_filler6	C	1	<u>l</u>	Zero fill
			S STATUS	
mhs_stat	C	1	1	bit 7: DC offset valid (1=all channels OK)
				bit 6: Scan control valid (1=all views OK)
				bit 5-4: Scan profile (0=nominal, 1/2=alternate,
				3=manual)
				bit 3-0: <unused></unused>
mhs_filler7	С	1	7	Zero fill
	1	SIGNAL P	ROCESSIN	G STATUS
mhs_dcoffset	С	1	5	DC offset, channels H1 to H5
mhs_chvalflgs	С	1	1	Channel validity
				bits 7-3: H1-H5 valid (all samples within ADC
				dynamic range)
				bits 2-0: SPE MUX code
mhs_chgains	С	1	3	Gains
mms_cngams		1	3	
				Word 1: H1 & H2 (bits 7-5 & 4-2)
				Word 2: H3 & H4 (bits 7-5 & 4-2)
1 (*11 ()				Word 3: H5 (bits 7-5)
mhs_filler8	C	ODCE EE	7	Zero fill
	1		MPERATU	
	1/3			
mhs_obctprt mhs_refrescts	I2 I2	2 2	5 3	PRT counts Reference resistor counts (upper, mid, lower)

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mhs_filler9	I2	2	1	Zero fill			
mhs_obcttemp	I4	4	5	Computed temperatures (mK)			
mhs_filler10	C	1	46	Zero fill			
MHS DISCRETE TELEMETRY (digb/analog)							
mhs_discrete	C	1	6	6 status words, 1 or 0			
mhs_survtemp	I2	2	3	3 Survival temps (receiver, electronics, scan)			
mhs_stx	I2	2	9	STX 1-4 status, STX1-3 power, SARR A&B			
				power			
mhs_ahkval	I4	4	1	bits 0-17: 1 if item is up to date			
mhs_filler11	I2	2	102	Zero fill			

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14. FORMAT OF THE MSU.L1B FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

MSU.11a format = MSU.11b format (in MSU.11a, calibration and location fields are empty).

<u>Header and record length</u> Header length = record length

1024 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENER	AL INFOR	RMATION
msu_h_siteid	С	3	1	Data set creation site ID
				CMS = Centre de MeteorologiSpatiale/France
				NSS = NESDIS/USA
				UKM = UK Met Office
msu_h_blank	C	1	1	ASCII blank
msu_h_l1bversnb	I2	2	1	level 1b format version number
msu_h_l1bversyr	I2	2	1	level 1b format version year
msu_h_l1bversdy	I2	2	1	level 1b format version day of year
msu_h_reclg	I2	2	1	reserved for logical record length
msu_h_blksz	I2	2	1	reserved for block size
msu_h_hdrcnt	I2	2	1	Count of header record in this data set
msu_h_filler0	I2	2	3	zero fill
msu_h_dataname	C	42	1	data set name
msu_h_prblkid	C	8	1	processing block identification
msu_h_satid	I2	2	1	Spacecraft identification code:
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8=NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator

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msu_h_instid	I2	2	1	MSU instrument identification
msu_h_datatyp	I2	2	1	data type code
				(6 = MSU)
msu_h_tipsrc	I2	2	1	TIP source code
1				(0 = not applicable; 1 = GAC embedded; 2 =
				stored; 3 = third CDA; 4 = HRPT embedded)
msu_h_startdatajd	I4	4	1	start of data set julian day
msu_h_startdatayr	I2	2	1	start of data set year
msu_h_startdatady	I2	2	1	start of data set day of year
msu_h_startdatatime	I4	4	1	start of data set UTC time of day in
				milliseconds
msu_h_enddatajd	I4	4	1	end of data set julian day
msu_h_enddatayr	I2	2	1	end of data set year
msu_h_enddatady	I2	2	1	end of data set day of year
msu_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
msu_h_cpidsyr	I2	2	1	year of Last CPIDS Update
msu_h_cpidsdy	I2	2	1	day of Year of Last CPIDS Update
msu_h_filler1	I2	2	4	Zero fill
	D	ATA SET Q	UALITY	INDICATORS
msu_h_inststat1	I4	4	1	instrument status
msu_h_filler2	I2	2	1	zero fill
msu_h_statchrecnb	I2	2	1	record number of status change (if 0, none
				occurred)
msu_h_inststat2	I4	4	1	second instrument status
				(if previous word is 0, no change)
msu_h_scnlin	I2	2	1	count of scan lines in this data set
msu_h_callocsclin	I2	2	1	count of calibrated, Earth located scan lines in
				this data set
msu_h_misscnlin	I2	2	1	count of missing scan lines
msu_h_datagaps	I2	2	1	count of data gaps in this data set
msu_h_okdatafr	I2	2	1	count of data frames without frame sync word
				errors
msu_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
msu_h_auxsyncerrsum	I2	2	1	sum of all auxiliary sync errors detected in the
				input data
msu_h_timeseqerr	I2	2	1	time sequence error
				(0 =none; otherwise the record number of the
				first occurrence)
msu_h_timeseqerrcode	I2	2	1	time sequence error code
msu_h_socclockupind	I2	2	1	socc clock update indicator
				(0 = none during this orbit; otherwise the)
				record number of the first occurrence)
msu_h_locerrind	I2	2	1	Earth location error indicator
				(0 = none during this orbit; otherwise the)
				record number of the first occurrence)
msu_h_locerrcode	I2	2	1	Earth location error code

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msu_h_pacsstatfield	I2	2	1	PACS status bit field
msu_n_paesstatrietu	12	2	1	bit 15-3 : spare
				bit 2 : pseudo noise (0 = normal data; 1 =
				P/N data)
				bit 1: tape direction $(0 = time)$
				decrementing)
				bit 0 : data mode (0 = test data; 1 = flight
				data)
msu_h_pacsdatasrc	I2	2	1	PACS data source
insu_ii_pueseuusie		_		(0 = unused; 1 = Gilmore; 2 = Wallops; 3 =
				SOCC)
msu_h_filler3	I4	4	1	zero fill
msu_h_spare1	С	8	1	spare (reserved for ingester)
msu_h_spare2	С	8	1	spare (reserved of the decommutation)
msu_h_filler4	I2	2	5	zero fill
	<u> </u>	CA	LIBRATI	ON
msu_h_racalind	I2	2	1	ramp/auto calibration indicators bit field
msu_h_calinf	I4	4	4*4	calibration information for nochannel 1 to 4 :
				?? x (mean calibration slope nochannel)
				?? x (standard deviation calibration slope
				nochannel)
				?? x (b-sub-1 nochannel)
				?? x (standard deviation of linear regression
				for b-sub-1 nochannel)
	RADIAN	NCE TO TE	MPERAT	URE CONVERSION
msu_h_nolincor	I4	4	3*4	nonlinearity correction coefficients for
				nochannel 1 to 4:
				10^12 x (second order term nochannel (zero
				in 1A data))
				10 ⁶ x (first order term nochannel (zero in
				1A data))
				10 ⁶ x (zeroth order term nochannel (zero in
				1A data))
msu_h_prttores	I4	4	2	PRT count to resistance coefficients
				?? x (first one K0 (Ohm) (zero in 1A data))
				?? x (second one K1 (Ohm) (zero in 1A data))
msu_h_iwttotemp	I4	4	3*4	Internal Warm Target PRT Resistance to
				temperature (K) coefficients for term in PRT
				1A, PRT 2A, PRT 1B,PRT 2B:
				10^12 x (second order term (zero in 1A data))
				10 ⁶ x (first order term (zero in 1A data))
			1	10^6 x (zeroth order term (zero in 1A data)
msu_h_censperes	I4	4	4	centroid of spectral response functions for
				nochannel 1 to 4:
				10 ⁴ x (nochannel (cm-1)(zero in 1A data))
msu_h_radspa	I4	4	4	Radiance of space for nochannel 1 to 4:
				10 ⁶ x (radiance of space nochannel(cm-
	1			1)(zero in 1A data))

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msu_h_filler5	I4	4	3	zero fill
		ľ	NAVIGATIO	ON
msu_h_modelid	С	1	8	Reference Ellipsoid Model ID
				="GRS 80" in the actual version of AAPP
msu_h_nadloctol	I2	2	1	10 x (nadir Earth location tolerance in
				kilometers)
msu_h_locbit	I2	2	1	Earth location bit field
				bit 0 : attitude error correction $(0 = not)$
				corrected)
msu_h_filler6	I2	2	1	zero fill
msu_h_rollerr	I2	2	1	10 ³ x (constant roll attitude error in degrees)
msu_h_pitcherr	I2	2	1	10 ³ x (constant pitch attitude error in degrees)
msu_h_yawerr	I2	2	1	10 ³ x (constant yaw attitude error in degrees)
msu_h_epoyr	I2	2	1	epoch year for orbit vector
msu_h_epody	I2	2	1	day of epoch year for orbit vector
msu_h_epotime	I4	4	1	epoc UTC time of day in milliseconds for orbit
				vector
msu_h_smaxis	I4	4	1	10^5 x (semi-major axis in kilometers)
msu_h_eccen	I4	4	1	10^8 x (eccentricity)
msu_h_incli	I4	4	1	10^5 x (inclination in degrees)
msu_h_argper	I4	4	1	10^5 x (argument of perigee in degrees)
msu_h_rascnod	I4	4	1	10^5 x (right ascension of the ascending node
				in degrees)
msu_h_manom	I4	4	1	10^5 x (mean anomaly in degrees)
msu_h_xpos	I4	4	1	10^5 x (position vector x component in
				kilometers)
msu_h_ypos	I4	4	1	10^5 x (position vector y component in
				kilometers)
msu_h_zpos	I4	4	1	10^5 x (position vector z component in
				kilometers)
msu_h_xvel	I4	4	1	10^8 x (velocity vector x-dot component in
				kilometers/second)
msu_h_yvel	I4	4	1	10^8 x (velocity vector y-dot component in
				kilometers/second)
msu_h_zvel	I4	4	1	10^8 x (velocity vector z-dot component in
				kilometers/second)
msu_h_earthsun	I4	4	1	10^6 x (Earth/sun distance ratio)
msu_h_filler7	I2	2	272	zero fill

One Data Record for one MSU scan line

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Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
	1		NE INFOR	
msu_scnlin	I2	2	1	scan line number
msu_scnlinyr	I2	2	1	scan line year
msu_scnlindy	I2	2	1	scan line day of year
msu_clockdrift	I2	2	1	satellite clock drift delta in ms
msu_scnlintime	I4	4	1	scan line UTC time of day in ms
msu_scnlinbit	I2	2	1	scan line bit field bit 15: (0 = ascending data; 1 = descending data) bit 14: (1 = scan time corrected for clock drift) bit 13: (1 = Earth location corrected for TIP attitude)
msu_mjfrcnt	I2	2	1	major frame count
msu_scnpos	I2	2	1	scan position number in 32 seconds
msu_filler1	I2	2	5	zero fill
	1 1		TY INDICA	•
msu_qualind	I4	4	1	quality indicator bit field in all of the following if the bit is on (i.e., if it is set to 1) then the statement is true. Otherwise it is false. General bit 31: do not use scan for product generation bit 30: time sequence error detected with this scan (see below) bit 29: data gap precedes this scan bit 28: no calibration (see below) bit 26: first good time following a clock update bit 25: instrument status changed with this scan bit 24: spare Time Problem Code (All bits off implies the scan time is as expected.) bit 23: time field is bad but can probably be inferred from the previous good time. bit 21: this record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update. (See bit 26 above) bit 20: start of a sequence that apparently repeats scan times that have been previously

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				accepted.
				TIP Problem Code
				bit 19: TIP synch error
				bit 18: TIP minor or major frame sequence
				error
				bit 17: TIP status error
				bit 16: TIP parity error
				Calibration Problem Code
				(Note these bits compliment the channel
				indicators; all bits set to 0 indicates normal
				calibration.)
				<i>'</i>
				bit 15: Scan line was not calibrated because
				of bad time.
				bit 14: Scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: Scan line was not calibrated because
				of bad or insufficient PRT data.
				bit 12: Scan line was calibrated but with
				marginal PRT data.
				bit 11: Some uncalibrated channels on this
				scan. (See channel indicators.)
				bit 10: Uncalibrated due to instrument mode.
				bit 09: spare
				bit 08: spare
				Earth Location Problem Code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 07: Not Earth located because of bad time.
				bit 06: Earth location questionable because of
				questionable time code. (See time problem
				flags above.)
				bit 05: Earth location questionable only
				marginal agreement with reasonableness
				check.
				bit 04: Earth location questionable fails
				reasonableness check.
		_		bit 03-00: spare
msu_scnlinqual	I2	2	4	quality flag for nochannel 1 to 4:
				(all bits off implies a good calibration)
				bit 7: spare
				bit 6: spare
				bit 5: No good blackbody counts for scan line
				bit 4: No good space view counts for scan
				line
				bit 3: No good PRTs for this line
				bit 2: Some bad blackbody view counts for
	<u> </u>	<u> </u>		on 2. Dome out officeroody view counts for

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			1	dain time
				this line
				bit 1: Some bad space view counts for this
				line
				bit 0: Some bad PRT temps on this line
msu_filler2	I2	2	8	zero fill
	,	CALIBRAT		
msu_pmcal	I4	4	3*4	primary calibration for nochannel 1 to 4:
				?? x (chn nochannel second order term, a2)
				?? x (chn nochannel first order term, a1)
				?? x (chn nochannel zeroth order term, a0)
msu_sdcal	I4	4	3*4	secondary calibration for nochannel 1 to 4:
				?? x (chn nochannel second order term, a2)
				?? x (chn nochannel first order term, a1)
				?? x (chn nochannel zeroth order term, a0)
	·	N/A	VIGATIO)N
msu_navstat	I4	4		Navigation Status Bit Field
				bits 15 - 12: earth location indicator
				(0 = earth location available; 1 = user
				ephemeris files greater than 24 hours old; 2 =
				no earth location available)
				bits 11 - 8: spacecraft attitude control
				(0 = operating in YGC or NOMINAL mode;
				1 = operating in another mode; $2 = $ attitude
				exceeds nominal tolerance; 3 = both 1 and 2)
				bits 7 - 4: attitude SMODE
				(0 = NOMINAL mode; 1 = rate nulling mode;
				2 = YGC mode; $3 = search mode$; $4 = coast$
				mode)
				bits 3 - 0: attitude PWT1P\$AC
				(0 = NOMINAL mode/no test; 1 = yaw axis
				test in progress; 2 = roll axis test in progress;
				3 = pitch axis test in progress)
msu_attangtime	I4	4		Time associated with attitude angles(seconds)
msu_rollang	I2	2		10^3 xRoll Angle in Degrees
msu_pitchang	I2	2		10^3 xPitch Angle in Degrees
msu_yawang	I2	$\frac{2}{2}$		10^3 xYaw Angle in Degrees
msu_yawang	12	2		10 3 x 1 aw Angle in Degrees
msu_scalti	I2	2	1	Spacecraft Altitude (MSL) in km in this scan
msu_scaru	12	2	1	line)
msu_ang	I2	2	3*11	set of 3 angles in degrees
msu_ang	12	2	3 11	first angle : 10 ² x (solar zenith angle)
				second angle: 10 ² x (satellite zenith angle)
				third angle : $10^2 x$ (sateline zeinth angle)
msu_filler3	I2	2	1	zero fill
	I4	4	2*11	lat/lon pair in degrees for point 1 to point 11
msu_pos	14	4	2.11	every point
				first: 10^4 x (latitude)
			l .	second : 10^4 x (longitude)

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				(North latitude and East longitude are positive)		
msu_filler4	I2	2	8	zero fill		
MSU DATA (as from TIP minor frame)						
msu_data	I2	2	112	First to last MSU words for scan line		
msu_filler5	I2	2	230	zero fill		

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Date: 24 January 2012

15. FORMAT OF THE DCS.L1B FILE

Header and record length
Header length = record length
10752 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENERA	L INFORM	IATION
dcs_h_siteid	С	3	1	Data set creation site ID
dcs_h_blank	С	1	1	ASCII blank
dcs_h_l1bversnb	I2	2	1	level 1b format version number
dcs_h_l1bversyr	I2	2	1	level 1b format version year
dcs_h_l1bversdy	I2	2	1	level 1b format version day of year
dcs_h_reclg	I2	2	1	reserved for logical record length
dcs_h_blksz	I2	2	1	reserved for block size
dcs_h_hdrcnt	I2	2	1	count of header records in data set
dcs_h_filler0	I2	2	3	Zero fill
dcs_h_dataname	C	42	1	data set name
dcs_h_prblkid	C	8	1	processing block identification
dcs_h_satid	I2	2	1	Spacecraft identification code:
				4=NOAA-15 (NOAA-K)
				2=NOAA-16 (NOAA-L)
				6=NOAA-17 (NOAA-M)
				7=NOAA-18 (NOAA-N)
				8=NOAA-19 (NOAA-N')
				11=Metop-B (Metop-1)
				12=Metop-A (Metop-2)
				13=Metop-C (Metop-3)
				14=Metop simulator
dcs_h_instid	I2	2	1	instrument identification
dcs_h_datatyp	I2	2	1	data type code
dcs_h_tipsrc	I2	2	1	TIP source code
				(0 = not applicable; 1 = GAC embedded; 2 =
				stored; 3 = third CDA; 4 = HRPT embedded)
dcs_h_startdatajd	I4	4	1	start of data set day count from 00h,1 Jan 1950
dcs_h_startdatayr	I2	2	1	start of data set year
dcs_h_startdatady	I2	2	1	start of data set day of year

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Γ	1 1		T .	T
dcs_h_startdatatime	I4	4	1	start of data set UTC time of day in
				milliseconds
dcs_h_enddatajd	I4	4	1	end of data set day count from 00h,1 Jan 1950
dcs_h_enddatayr	I2	2	1	end of data set year
dcs_h_enddatady	I2	2	1	end of data set day of year
dcs_h_enddatatime	I4	4	1	end of data set UTC time of day in
				milliseconds
dcs_h_cpidsyr	I2	2	1	year of Last CPIDS Update
dcs_h_cpidsdy	I2	2	1	Day of Year of Last CPIDS Update
dcs_h_filler1	I4	4	2	filler
	D	ATA SET Q	UALITY 1	NDICATORS
dcs_h_inststat	I4	4	1	instrument status
dcs_h_statchreenb	I2	2	1	record number of status change (if 0, none
				occurred)
dcs_h_scnlin	I2	2	1	count of scan lines in this data set
dcs_h_datagaps	I2	2	1	count of data gaps in this data set
dcs_h_okdatafr	I2	2	1	count of data frames without frame sync word
		_		errors
dcs_h_pacsparityerr	I2	2	1	count of PACS detected TIP parity errors
dcs_h_auxsyncerrsum	I2	2	1	Sum of all auxiliary sync errors detected in the
acs_n_aansyncerisam		_		input data.
dcs_h_pacsstatfield	I2	2	1	PACS status bit field
des_n_paesstatifeid		_		bit 15-3 : spare
				bit 2 : pseudo noise (0 = normal data; 1 =
				P/N data)
				bit 1: tape direction $(0 = time)$
				decrementing)
				bit 0 : data mode (0 = test data; 1 = flight
				data)
dcs_h_pacsdatasrc	I2	2	1	PACS data source
des_n_paesdataste		_		(0 = unused; 1 = Gilmore; 2 = Wallops; 3 =
				SOCC)
dcs_h_spare1	С	8	1	spare (reserved for ingester)
dcs_h_spare2	C	8	1	spare (reserved of the decommutation)
dcs_h_filler2	I4	4	4	filler
des_n_imerz		NALOG TELI		CONVERSION
dcs_h_ancnv	I4	4	5*9	conversion coefficients for analog
des_n_anenv	1-7	7		housekeeping telemetry
				(five consecutive 16-bit words per telemetry
				field)
				word 1 - 5: type 1 telemetry transfer
				coefficients
				word 6 - 10: type 2 telemetry transfer
				coefficients
				word 11 - 15: type 3 telemetry transfer
				coefficients
				word 16 - 20: type 4 telemetry transfer
			1	word to 20, type + telementy transfer

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doe h fillow?	12	2	5202	word 21 - 25: type 5 telemetry transfer coefficients word 26 - 30: type 6 telemetry transfer coefficients word 31 - 35: type 7 telemetry transfer coefficients word 36 - 40: type 8 telemetry transfer coefficients word 41 - 45: type 9 telemetry transfer coefficients
dcs_h_filler3	12	2	5202	filler

Data Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
	F]	RAME INFOI	RMATION	STRUCTURE
dcs_mjfrcnt	I2	2	1	major frame count
dcs_mjfryr	I2	2	1	major frame year
dcs_mjfrdy	I2	2	1	major frame day of year
dcs_clockdrift	I2	2	1	satellite clock drift delta in milliseconds
dcs_mjfrtime	I4	4	1	scan line UTC time of day in milliseconds
dcs_mjfbf	I2	2	1	major frame bit field
dcs_filler1	I2	2	5	filler
		QUALIT	TY INDICA	ATORS
dcs_qualind	I4	4	1	quality indicator bit field
dcs_mjfqf	I4	4	1	major frame quality flags
dcs_filler2	I4	4	2	filler
		DCS MIN	OR FRAM	E DATA
dcs_data	I4	4	320*8	DCS minor frame data
dcs_filler3	I4	4	1	filler
		DIGITAI	L B TELEN	METRY
dcs_digbinvwbf	I2	2	1	invalid word bit flags
dcs_digbtlm	I2	2	1	digital B telemetry
				bit 15: relay A status
				bit 14: relay B status
				bit 13: DRU 1
				bit 12: DRU 2
				bit 11: DRU 3
				bit 10: DRU 4
				bit 9: DRU 5
				bit 8: DRU 6
				bit 7: DRU 7

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				bit 6: DRU 8 bit 5: Memory Overflow bit 4: DCS Time Code (MSB) bit 3: Pseudo message status
				bit 2: spare bit 1: spare
				bit 0: spare
dcs_filler4	I4	4	1	filler
		ANALO	G TELEN	METRY
dcs_aninvwbf	I2	2	1	invalid word bit flags
dcs_analog	I2	2	8	analog telemetry
				(16 8-bit words)
				word 1: RPU temperature (use type 1 transfer
				coefficients)
				word 2: SPU-A temperature (use type 1
				transfer coefficients)
				word 3: SPU-B temperature (use type 1
				transfer coefficients)
				word 4: converter voltage +5V (use type 2
				transfer coefficients)
				word 5: converter voltage +12V (use type 3 transfer coefficients)
				word 6: converter voltage -5V (use type 4
				transfer coefficients)
				word 7: converter voltage -12V (use type 5
				transfer coefficients)
				word 8: converter temperature (use type 1
				transfer coefficients)
				word 9: USO oven temperature (use type 6
				transfer coefficients)
				word 10: USO thermal regulation (use type 7
				transfer coefficients)
dcs_filler5	I2	2	221	filler

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16. FORMAT OF THE HIRS.L1C FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
1664*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name IN AAPP code	Type	Word Size	Number	Meaning
	- J P C	in byte	of words	
		· ·	L INFORM	IATION
hrs1c_h_site	С	3	1	dataset creation site ID
hrs1c_h_cfill1	С	1	1	zero fill
hrs1c_h_1bsite	С	3	1	creation site for original 1B data
hrs1c_h_cfill2	С	1	1	zero fill
hrs1c_h_versnb	I4	4	1	level 1c format version number
hrs1c_h_versyr	I4	4	1	level 1c format version year
hrs1c_h_versdy	I4	4	1	level 1c format version day of year
hrs1c_h_hdrent	I4	4	1	count of header records in this data set
hrs1c_h_satid	I4	4	1	satellite identification
				.15=NOAA-15 (NOAA-K)
				16=NOAA-16 (NOAA-L)
				17=NOAA-17 (NOAA-M)
				18=NOAA-18 (NOAA-N)
				19=NOAA-19 (NOAA-N')
				1=Metop-B (Metop-1)
				2=Metop-A (Metop-2)
				3=Metop-C (Metop-3)
				4=Metop simulator
hrs1c_h_instrument	I4	4	1	instrument code (5=HIRS)
hrs1c_h_satht	I4	4	1	nominal satellite altitude, km*10
hrs1c_h_period	I4	4	1	nominal orbit period (seconds)
hrs1c_h_startorbit	I4	4	1	orbit number (at start of file)
hrs1c_h_startdatayr	I4	4	1	start of data set year
hrs1c_h_startdatady	I4	4	1	start of data set day of the year
hrs1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)

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hrs1c_h_endorbit	I4	4	1	orbit number (at end of file)
hrs1c_h_enddatayr	I4	4	1	end of data set year
hrs1c_h_enddatady	I4	4	1	end of data set day of the year
hrs1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
hrs1c_h_scnlin	I4	4	1	count of scan lines in this data set
hrs1c_h_misscnlin	I4	4	1	count of missing scan lines
hrs1c_h_spare	I4	4	1	spare
TEMPE	RATUR	E TO RADIA	NCE CON	VERSION COEFFICIENTS
hrs1c_h_tempradenv	I4	4	3*19	order of channels = $1,2,3,4,,18,19$
				for nochannel = 1 to 19:
				10^6 x (nochannel central wavenumber)
				10 ⁶ x (nochannel constant 1)
				10 ⁶ x (nochannel constant 2)
				(scaling factor for wavenumber changes to
				10^5 for channels 13-19 inclusive)
hrs1c_h_20solfiltirrad	I4	4	1	10 ⁶ x (albedo-radiance ch20 solar filtered
				irradiance,W/m2)
hrs1c_h_20equifiltwidth	I4	4	1	10^6 x (albedo-radiance ch 20 equivalent filter
_				width cm^-1)
hrs1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 3 for METOP-1)
hrs1c_h_filler	I4	4	1583	zero fill

One Data Record for one HIRS scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
hrs1c_scnlin	I4	4	1	scan line number
hrs1c_scnlinyr	I4	4	1	scan line year
hrs1c_scnlindy	I4	4	1	scan line day of year
hrs1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
hrs1c_mjfrcnt	I4	4	1	major frame count
hrs1c_qualind	I4	4	1	quality indicator bit field
				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update

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				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
hrs1c_scanqual	I4	4	1	scan line quality flags
_ 1				time problem code
				(all bits off implies the scan time is as
				expected)
				bit 31-24: spare <zero fill=""></zero>
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time field is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous times (i.e., there is a
				time discontinuity). This may or may not be
				associated with a spacecraft clock update. (see
				bit 26 above)
				bit 20: start of a sequence that apparently
				repeats scan times that have been previously
				accepted.
				bits 19-16: spare
				calibration problem code
				(all bits set to 0 indicates normal calibration)
				bit 15: scan line was not calibrated because of bad time
				bit 14: scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of
				bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bits 9 and 8: spare
				Earth location problem code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above)
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails

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				reasonableness check
				bit 3-0: spare
hrs1c_chanqual	I4	4	20	quality flag for each channel with the channels in the order 1,2,3,,20. (all bits off implies a good calibration) bit 31-6: spare
				bit 5-0: TBD (to be defined)
hrs1c_instrtemp	I4	4	1	HIRS baseplate temperature (K*100)
hrs1c_spare1	I4	4	2	spare
hrs1c_latlon	I4	4	2*56	lat/lon in degrees for Hnfovs first : 10^4 x (latitude) second : 10^4 x (longitude)
hrs1c_angles	I4	4	4*56	scan angles for Hnfovs first: 10^2 x (local zenith angle) second: 10^2 x (local azimuth angle) third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle)
hrs1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
hrs1c_spare2	I4	4	2	spare
hrs1c_btemps	I4	4	20*56	BT data for Hnfovs 10^2 x scene brightness temperature (K) for channels 1-19 10^2 x radiance Wm-2sr-1(cm-1)-1 for channel 20
hrs1c_dataqual	I4	4	56	quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used bit 29-21: spare <zero fill=""> bit 20-1: bit n set to 1 if brightness temperature in channel n is physically unreasonable or has not been calculated due to calibration problems. bit 0: set if all channels missing</zero></zero>
hrs1c_filler	I4	4	119	zero fill

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17. FORMAT OF THE AMSUALLIC FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
768*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		Gene	ral informa	tion
ama1c_h_site	C	3	1	dataset creation site ID
ama1c_h_cfill1	С	1	1	filler
ama1c_h_1bsite	C	3	1	creation site for original 1B data
ama1c_h_cfill2	С	1	1	filler
ama1c_h_versnb	I4	4	1	level 1c format version number
ama1c_h_versyr	I4	4	1	level 1c format version year
ama1c_h_versdy	I4	4	1	level 1c format version day of year
ama1c_h_hdrcnt	I4	4	1	count of header records in this data set
ama1c_h_satid	I4	4	1	satellite identification:
				.15=NOAA-15 (NOAA-K)
				16=NOAA-16 (NOAA-L)
				17=NOAA-17 (NOAA-M)
				18=NOAA-18 (NOAA-N)
				19=NOAA-19 (NOAA-N')
				1=Metop-B (Metop-1)
				2=Metop-A (Metop-2)
				3=Metop-C (Metop-3)
				4=Metop simulator
ama1c_h_instrument	I4	4	1	instrument code
				(10=AMSU-A)
ama1c_h_satht	I4	4	1	nominal satellite altitude, km*10
ama1c_h_period	I4	4	1	nominal orbit period (seconds)
ama1c_h_startorbit	I4	4	1	orbit number (at start of file)
ama1c_h_startdatayr	I4	4	1	start of data set year
ama1c_h_startdatady	I4	4	1	start of data set day of the year

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ama1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
ama1c_h_endorbit	I4	4	1	orbit number (at end of file)
ama1c_h_enddatayr	I4	4	1	end of data set year
ama1c_h_enddatady	I4	4	1	end of data set day of the year
ama1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
ama1c_h_scnlin	I4	4	1	count of scan lines in this data set
ama1c_h_misscnlin	I4	4	1	count of missing scan lines
ama1c_h_vnantennacorr	I4	4	1	version number, antenna corrections
ama1c_h_spare	I4	4	1	spare
TEMPE	RATUR	E TO RADIA	NCE CON	VERSION COEFFICIENTS
ama1c_h_tempradcnv	I4	4	3*15	order of channels = $1,2,3,4,,15$
				for nochannel = 1 to 15:
				10^6 x (nochannel central wavenumber)
				10 ⁶ x (nochannel constant 1)
				10^6 x (nochannel constant 2)
ama1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 3 for METOP-1)
ama1c_h_filler	I4	4	700	filler

One Data Record for one AMSU-A scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
ama1c_scnlin	I4	4	1	scan line number
ama1c_scnlinyr	I4	4	1	scan line year
ama1c_scnlindy	I4	4	1	scan line day of year
ama1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
ama1c_qualind	I4	4	1	quality indicator bit field
_				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
ama1c_scanqual	I4	4	1	scan line quality flags
				time problem code

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(all bits off implies the scan time is as expected)

bit 31-24: spare <zero fill>

bit 23: time field is bad but can probably be inferred from the previous good time

bit 22: time field is bad and can't be inferred from the previous good time

bit 21: this record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update. (see bit 26 above)

bit 20: start of a sequence that apparently repeats scan times that have been previously accepted.

moon problem code

bit 19: Moon in AMSU-A2 space view corrected

bit 18: Moon in AMSU-A1 space view corrected

bit 17: Moon in AMSU-A2 space view uncorrected

bit 16: Moon in AMSU-A1 space view uncorrected

calibration problem code

(all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time

bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap.

bit 13: scan line was not calibrated because of bad or insufficient PRT data

bit 12: scan line was calibrated but with marginal PRT data

bit 11: some uncalibrated channels of this scan. See channel indicators.

bit 10: uncalibrated due to instrument mode bits 9 and 8: spare

Earth location problem code

(all bits set to 0 implies the Earth location was normal)

bit 7: not Earth located because of bad time bit 6: Earth location questionable because of

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				questionable time code (see time problem flags
				above)
				<i>'</i>
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails
				reasonableness check
				bit 3: Earth location questionable because of
				antenna position check
				bit 2-0: spare
ama1c_chanqual	I4	4	15	quality flag for each channel with the channels
amare_enanquar	17	7	13	in the order 1,2,3,,15.
				(all bits off implies a good calibration)
				bit 31-6: spare
				bit 5: No good blackbody counts for scan
				line
				bit 4: No good space view counts for scan
				line
				bit 3: No good PRTs for this line
				bit 2: Some bad blackbody view counts for
				this line
				bit 1: Some bad space view counts for this
				line
				bit 0: Some bad PRT temps on this line
ama1c_instrtemp1	I4	4	1	AMSU-A1 RF shelf temp (K*100)
ama1c_instrtemp2	I4	4	1	AMSU-A2 RF shelf temp (K*100)
ama1c_mstremp2 ama1c_spare1	I4	4	2	1 \
1		4		spare
ama1c_latlon	I4	4	2*30	lat/lon in degrees for Anfovs
				first : 10 ⁴ x (latitude)
				second: 10 ⁴ x (longitude)
ama1c_angles	I4	4	4*30	scan angles for Anfovs
				first: 10 ² x (local zenith angle)
				accord. 1000 v. (local assumption at a)
				second: 10 ² x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
				third: 10^2 x (solar zenith angle)
ama1c_scalti	I4	4	1	`
ama1c_scalti ama1c_spare2	I4 I4	4 4	1 2	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10
ama1c_spare2	I4	4	2	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare
	+			third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs
ama1c_spare2	I4	4	2	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K),
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15
ama1c_spare2	I4	4	2	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view:
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view: (all bits off implies acceptable data)
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""></zero>
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used</zero>
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used bit 29-16: spare <zero fill=""></zero></zero>
ama1c_spare2 ama1c_btemps	I4 I4	4 4	2 15*30	third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle) sat altitude above reference ellipsoid, km*10 spare BT data for Anfovs 10^2 x scene brightness temperature (K), channels 1-15 quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used</zero>

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				unreasonable or has not been calculated due to
				calibration problems.
				bit 0: set if all channels missing
ama1c_filler	I4	4	80	filler

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18. FORMAT OF THE AMSUB.L1C AND MHS.L1C FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

<u>Header and record length</u> Header length = record length 1152*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Name	Word Size	Number	Meaning
		in byte	of words	
		GENERA	L INFORM	IATION
amb1c_h_site	С	3	1	dataset creation site ID
amb1c_h_cfill1	C	1	1	filler
amb1c_h_1bsite	C	3	1	creation site for original 1B data
amb1c_h_cfill2	С	1	1	filler
amb1c_h_versnb	I4	4	1	level 1c format version number
amb1c_h_versyr	I4	4	1	level 1c format version year
amb1c_h_versdy	I4	4	1	level 1c format version day of year
amb1c_h_hdrent	I4	4	1	count of header records in this data set
amb1c_h_satid	I4	4	1	satellite identification:
				.15=NOAA-15 (NOAA-K)
				16=NOAA-16 (NOAA-L)
				17=NOAA-17 (NOAA-M)
				18=NOAA-18 (NOAA-N)
				19=NOAA-19 (NOAA-N')
				1=Metop-B (Metop-1)
				2=Metop-A (Metop-2)
				3=Metop-C (Metop-3)
				4=Metop simulator
amb1c_h_instrument	I4	4	1	instrument code
				(11=AMSU-B; 12=MHS)
amb1c_h_satht	I4	4	1	nominal satellite altitude, km*10
amb1c_h_period	I4	4	1	nominal orbit period (seconds)
amb1c_h_startorbit	I4	4	1	orbit number (at start of file)
amb1c_h_startdatayr	I4	4	1	start of data set year
amb1c_h_startdatady	I4	4	1	start of data set day of the year
amb1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)

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amb1c_h_endorbit	I4	4	1	orbit number (at end of file)
amb1c_h_enddatayr	I4	4	1	end of data set year
amb1c_h_enddatady	I4	4	1	end of data set day of the year
amb1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
amb1c_h_scnlin	I4	4	1	count of scan lines in this data set
amb1c_h_misscnlin	I4	4	1	count of missing scan lines
amb1c_h_vnantennacorr	I4	4	1	version number, antenna corrections
amb1c_h_spare	I4	4	1	spare
TEMPE	RATUR	E TO RADIA	NCE CON	VERSION COEFFICIENTS
amb1c_h_tempradenv	I4	4	3*5	order of channels = $1,2,3,4,5$
				for nochannel = 1 to 5:
				10 ⁶ x (nochannel central wavenumber)
				10^6 x (nochannel constant 1)
				10^6 x (nochannel constant 2)
amb1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 3 for METOP-1)
amb1c_h_filler	I4	4	1114	filler

One Data Record for one AMSU-B/MHS scan line

Name in AAPP code	Name	Word Size	Number	Meaning
		in byte	of words	
amb1c_scnlin	I4	4	1	scan line number
amb1c_scnlinyr	I4	4	1	scan line year
amb1c_scnlindy	I4	4	1	scan line day of year
amb1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
amb1c_qualind	I4	4	1	quality indicator bit field
				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
amb1c_scanqual	I4	4	1	scan line quality flags
				time problem code
				(all bits off implies the scan time is as

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	-		T	
				expected) bit 31-24: spare <zero fill=""> bit 23: time field is bad but can probably be inferred from the previous good time bit 22: time field is bad and can't be inferred from the previous good time bit 21: this record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update. (see bit 26 above) bit 20: start of a sequence that apparently repeats scan times that have been previously accepted. bits 19-16: spare calibration problem code (all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines</zero>
				bit 22: time field is bad and can't be inferred
				1
				<u> </u>
				_
				_
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bits 9 and 8: spare
				Earth location problem code (all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above) bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails
				reasonableness check
				bit 3: Earth location questionable because of antenna position check
				bit 2-0: spare
amb1c_chanqual	I4	4	5	quality flag for each channel with the channels
*				in the order 1,2,3,4,5.

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				(all bits off implies a good calibration)
				bit 31-6: spare
				bit 5: No good blackbody counts for scan
				line
				line
				bit 3: No good PRTs for this line
				bit 2: Some bad blackbody view counts for
				this line
				bit 1: Some bad space view counts for this
				line
				bit 0: Some bad PRT temps on this line
amb1c_instrtemp	I4	4	1	AMSU-B Mixer chan 18-20 temp (K*100)
amb1c_spare1	I4	4	2	spare
amb1c_latlon	I4	4	2*90	lat/lon in degrees for Bnfovs
				first : 10 ⁴ x (latitude)
				second: 10^4 x (longitude)
amb1c_angles	I4	4	4*90	scan angles for Bnfovs
				first: 10^2 x (local zenith angle)
				second: 10 ² x (local azimuth angle)
				third: 10 ² x (solar zenith angle)
				fourth: 10^2 x (solar azimuth angle)
amb1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
amb1c_spare2	I4	4	2	spare
amb1c_btemps	I4	4	5*90	BT data for Bnfovs
				10^2 x scene brightness temperature (K),
				channels 1-5
amb1c_dataqual	I4	4	90	quality control word for the data in each field
1				of view:
				(all bits off implies acceptable data)
				bit 31: spare <zero fill=""></zero>
				bit 30: set if secondary calibration used
				bit 29-6: spare <zero fill=""></zero>
				bit 5-1: bit n set to 1 if brightness temperature
				in channel n is physically unreasonable or has
				not been calculated due to calibration
				problems.
				bit 0: set if all channels missing
amb1c_filler	I4	4	55	spare
amore_mici	17	-T		spuic

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19. FORMAT OF THE MSU.L1C FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
128*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Name	Word Size	Number	Meaning	
		in byte	of words	S	
GENERAL INFORMATION					
msu1c_h_site	С	3	1	dataset creation site ID	
msu1c_h_cfill1	С	1	1	filler	
msu1c_h_1bsite	С	3	1	creation site for original 1B data	
msu1c_h_cfill2	С	1	1	filler	
msu1c_h_versnb	I4	4	1	level 1c format version number	
msu1c_h_versyr	I4	4	1	level 1c format version year	
msu1c_h_versdy	I4	4	1	level 1c format version day of year	
msu1c_h_hdrent	I4	4	1	count of header records in this data set	
msu1c_h_satid	I4	4	1	satellite idendification (e.g. 14 for NOAA-14)	
msu1c_h_instrument	I4	4	1	instrument code	
				(6=MSU)	
msu1c_h_satht	I4	4	1	nominal satellite altitude, km*10	
msu1c_h_period	I4	4	1	nominal orbit period (seconds)	
msu1c_h_startorbit	I4	4	1	orbit number (at start of file)	
msu1c_h_startdatayr	I4	4	1	start of data set year	
msu1c_h_startdatady	I4	4	1	start of data set day of the year	
msu1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)	
msu1c_h_endorbit	I4	4	1	orbit number (at end of file)	
msu1c_h_enddatayr	I4	4	1	end of data set year	
msu1c_h_enddatady	I4	4	1	end of data set day of the year	
msu1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)	
msu1c_h_scnlin	I4	4	1	count of scan lines in this data set	
msu1c_h_misscnlin	I4	4	1	count of missing scan lines	
msu1c_h_spare1	I4	4	1	spare	
msu1c_h_spare2	I4	4	1	spare	

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TEMPERATURE TO RADIANCE CONVERSION COEFFICIENTS				
msu1c_h_tempradcnv	I4	4	3*4	order of channels = $1,2,3,4$
				for nochannel = 1 to 4:
				10 ⁶ x (nochannel central wavenumber)
				10 ⁶ x (nochannel constant 1)
				10^6 x (nochannel constant 2)
msu1c h filler	I4	4	94	filler

One Data Record for one MSU scan line

Type	Word Size	Number	Meaning
	in byte	of words	
	4	1	scan line number
I4	4	1	scan line year
I4	4	1	scan line day of year
		1	scan line UTC time of day in milliseconds
		1	major frame count
I4	4	1	quality indicator bit field
			In all of the following, if the bit is on (= is set
			to 1) then the statement is true. Otherwise it is
			false.
			general
			bit 31: do not use scan for product generation
			bit 30: time sequence error detected with this
			scan
			bit 29: data gap precedes this scan
			bit 28: no calibration
			bit 27: no Earth location
			bit 26: first good time following a clock
			update
			bit 25: instrument status changed with this
			scan
			bit 24-0: spare <zero fill=""></zero>
I4	4	1	scan line quality flags
			time problem code
			(all bits off implies the scan time is as
			expected)
			bit 31-24: spare <zero fill=""></zero>
			bit 23: time field is bad but can probably be
			inferred from the previous good time
			bit 22: time field is bad and can't be inferred
			from the previous good time
			bit 21: this record starts a sequence that is
			inconsistent with previous times (i.e., there is a
	I4 I4 I4 I4 I4 I4	in byte I4	in byte of words I4 4 1 I4 4 1

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msu1c_chanqual	I4	4	4	time discontinuity). This may or may not be associated with a spacecraft clock update. (see bit 26 above) bit 20: start of a sequence that apparently repeats scan times that have been previously accepted. TIP Problem Code (All bits off implies no errors.) bit 19: TIP synch error bit 18: TIP minor or major frame sequence error bit 16: TIP parity error calibration problem code (all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap. bit 13: scan line was not calibrated because of bad or insufficient PRT data bit 12: scan line was calibrated but with marginal PRT data bit 11: some uncalibrated channels of this scan. See channel indicators. bit 10: uncalibrated due to instrument mode bits 9 and 8: spare Earth location problem code (all bits set to 0 implies the Earth location was normal) bit 7: not Earth located because of bad time bit 6: Earth location questionable because of questionable time code (see time problem flags above) bit 5: Earth location questionable. Only marginal agreement with reasonableness check. bit 4: Earth location questionable. Fails reasonableness check bit 3-0: spare quality flag for each channel
msure_enanquar	17	7	7	with the channels in the order 1,2,3,4 (all bits off implies a good calibration) bit 31-6: spare bit 5: No good blackbody counts for scan line

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				bit 4: No good space view counts for scan line bit 3: No good PRTs for this line bit 2: Some bad blackbody view counts for this line bit 1: Some bad space view counts for this line
				bit 0: Some bad PRT temps on this line
msu1c_spare1	I4	4	3	spare
msu1c_latlon	I4	4	2*11	lat/lon in degrees for Mnfovs(11) first : 10^4 x (latitude) second : 10^4 x (longitude)
msu1c_angles	I4	4	2*11	scan angles for Mnfovs(11) first: 10^2 x (local zenith angle) second: 10^2 x (local azimuth angle)
msu1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
msu1c_spare2	I4	4	1	spare
msu1c_btemps	I4	4	4*11	BT data for Mnfovs(11) 10^2 x scene brightness temperature (K) for channels 1-4
msu1c_dataqual	I4	4	11	quality control word for the data in each field of view: !(all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used bit 29-5: spare <zero fill=""> bit 4-1: bit n set to 1 if brightness temperature in channel n is physically unreasonable or has not been calculated due to calibration problems. bit 0: set if all channels missing</zero></zero>
msu1c_filler	I4	4	34	filler

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20. FORMAT OF THE IASI L1C FILE

Header and record length
Header length = record length
545981*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

iasi1c_h_site iasi1c_h_cfill1 iasi1c_h_1bsite iasi1c_h_cfill2 iasi1c_h_versnb iasib1c_h_versyr iasi1c_h_versdy	C C C	in byte GENERA 3 1 3	of words L INFORM 1	IATION dataset creation site ID
iasi1c_h_cfill1 iasi1c_h_1bsite iasi1c_h_cfill2 iasi1c_h_versnb iasib1c_h_versyr	C C C	3	1	
iasi1c_h_cfill1 iasi1c_h_1bsite iasi1c_h_cfill2 iasi1c_h_versnb iasib1c_h_versyr	C C C	1		dataset creation site ID
iasi1c_h_1bsite iasi1c_h_cfill2 iasi1c_h_versnb iasib1c_h_versyr	C C		1	
iasi1c_h_cfill2 iasi1c_h_versnb iasib1c_h_versyr	С	3	1	filler
iasi1c_h_versnb iasib1c_h_versyr		S	1	creation site for original 1B data
iasib1c_h_versyr		1	1	filler
· · · · · · · · · · · · · · · · · · ·	I4	4	1	level 1c format version number
incile h voredy	I4	4	1	level 1c format version year
lastic_ii_versuy	I4	4	1	level 1c format version day of year
iasi1c_h_hdrcnt	I4	4	1	count of header records in this data set
iasi1c_h_satid	I4	4	1	satellite identification:
				1=Metop-1
				2=Metop-2
				3=Metop-3
				4=Metop simulator
iasi1c_h_instrument	I4	4	1	instrument code
				(13=IASI)
iasi1c_h_satht	I4	4	1	nominal satellite altitude, km*10
iasi1c_h_period	I4	4	1	nominal orbit period (seconds)
iasi1c_h_startorbit	I4	4	1	orbit number (at start of file)
iasi1c_h_startdatayr	I4	4	1	start of data set year
iasi1c_h_startdatady	I4	4	1	start of data set day of the year
iasi1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
iasi1c_h_endorbit	I4	4	1	orbit number (at end of file)
iasi1c_h_enddatayr	I4	4	1	end of data set year
iasi1c_h_enddatady	I4	4	1	end of data set day of the year
iasi1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
iasi1c_h_scnlin	I4	4	1	count of scan lines in this data set
iasi1c_h_misscnlin	I4	4	1	count of missing scan lines
iasi1c_h_spare	I4	4	2	spare
iasi1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 3 for METOP-1)

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	- 4		4.0	
iasi1c_h_startchan	14	4	10	Start channel for scaling definition
iasi1c_h_endchan	I4	4	10	End channel for scaling definition
iasi1c_h_scalefactor	I4	4	10	Radiance = scalrad*10^-scalefactor
iasi1c_h_filler	I4	4	545508	filler

One Data Record for one IASI scan line

Name in AAPP code	Name	Word Size in byte	Number of words	Meaning
iasi1c_scnlin	I4	4	1	scan line number
iasi1c_granule	I4	4	1	Granule number
iasi1c_scnlinyr	I4	4	1	scan line year
iasi1c_scnlindy	I4	4	1	scan line day of year
iasi1c_scnlintime	I4	4	30	scan line UTC time of day in milliseconds
iasi1c_GQisFlagQual	I4	4	4*30	Bit 0: GQisFlagQual summary flag for all
_				bands (1=anomaly)
				Bit 1: anomaly in band 1
				Bit 2: anomaly in band 2
				Bit 3: anomaly in band 3
				Bit 4: hardware
				Bit 5: Band 1 affected by spikes
				Bit 6: Band 2 affected by spikes
				Bit 7: Band 3 affected by spikes
				Bit 8: NZPD and complex calibration error
				Bit 9: On-board general quality flag
				Bit 10: Overflow/underflow
				Bit 11: Spectral calibration error
				Bit 12: Radiometric post-calibration error
				Bit 13: GQisFlagQual summary flag for all
				bands (same as bit 0)
				Bit 14: Missing sounder data
				Bit 15: Missing IIS data
				Bit 16: Missing AVHRR data
iasi1c_GQisQualIndex	I4	4	1	NEDT estimated/expected
iasi1c_GQisQualIndexL	I4	4	1	IIS/AVHRR co-registration uncertainty
oc				
iasi1c_GQisQualIndexR	I4	4	1	NEDT estimated/expected radiometric
ad				
iasi1c_GQisQualIndexSp	I4	4	1	NEDT estimated/expected spectral
ect				
iasi1c_GQisSysTecSond	I4	4	1	
Qual				
iasi1c_latlon	I4	4	2*4*30	lat/lon in degrees
				first : 10 ⁴ x (latitude)

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	<u> </u>			second: 10^4 x (longitude)
iasi1c_angles	I4	4	4*4*30	scan angles
lastic_aligies	14	4	4.4.30	first: 10 ² x (local zenith angle)
				,
				second: 10^2 x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
111-1141	T.4	4	1	fourth: 10^2 x (solar azimuth angle)
iasib1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
iasi1c_scalrad	I2	2	8700*4*3	Scaled radiance
			0	
iasi1c_avhcombination	I4	4	1	1 bit for each channel
iasi1c_avhrrmean	I4	4	6*7*4*30	Mean radiance for 6 channels, 7 classes
iasi1c_avhmeanscalefact	I4	4	6*7*4*30	Factor scales
or				
iasi1c_avhrrsdev	I4	4	6*7*4*30	Std dev radiance for 6 channels, 7 classes
iasi1c_avhsdevscalefacto	I4	4	6*7*4*30	Factor scales
r				
iasi1c_avhrrfrac	I4	4	7*4*30	10 ⁶ x Fraction in each class
iasi1c_avhrrCGy	I4	4	7*4*30	10 ⁶ x Y angular position of centre of gravity
iasi1c_avhrrCGz	I4	4	7*4*30	10 ⁶ x Z angular position of centre of gravity
V2.0: New variables from	IASI 10	C EPS format vo	ersion 8.0 (4	20 words)
iasi1c_GIacVarImagIIS	I4	4	30	10 ⁶ x Variance of IIS image W/(m ² sr m ⁻
_				
iasi1c_GIacAvgImagIIS	I4	4	30	10^6 x Average of IIS image W/(m^2 sr m^-1)
iasi1c_GEUMAvhrr1BC	I4	4	4*30	Cloud fraction
ldFrac				
iasi1c_GEUMAvhrr1BL	I4	4	4*30	Land fraction
andFrac		-		
iasi1c_GEUMAvhrr1BQ	I4	4	4*30	Bits 0-6: percentage snow/ice
ual				Bit 7: 0 if AVHRR is OK
				1 then bits 0-6 show the number of bad
				AVHRR pixels (0-126)
				11 1 11 (t) pixels (0 120)

21. FORMAT OF THE CRIS L1C FILE

 $cris_1cnpc = 1$

```
Header and record length
Header length = record length
array_size_cris1c = (11 + cris_1cnfor + cris_1cnband*cris_1cnfov +
(13 + 2*cris_1cnband + cris_1cnchan + cris_1cnpc)*cris_1cnfov*cris_1cnfor) * 4 bytes
361058*4 bytes by default

with
cris_1cnfor = 30    ! Number of fields of regard (scan pos)
cris_1cnband = 3    ! Number of bands
cris_1cnfov = 9    ! Number of fields of view
cris_1cnchan = 1317! Max number of channels in format
```

! Number of PCs in format (at least 1)

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array_size_cris1cspare =

& array_size_cris1c - 36 - cris_1cnchan - 4*cris_1cnband

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Name	Word Size	Number	Meaning
		in byte	of words	
	I	- V	L INFORM	MATION
cris1c_h_site	С	3	1	dataset creation site ID
cris1c_h_cfill1	С	1	1	filler
cris1c_h_1bsite	С	3	1	creation site for original 1B data
cris1c_h_cfill2	С	1	1	filler
cris1c_h_versnb	I4	4	1	level 1c format version number
cris1c_h_versyr	I4	4	1	level 1c format version year
cris1c_h_versdy	I4	4	1	level 1c format version day of year
cris1c_h_hdrcnt	I4	4	1	count of header records in this data set
cris1c_h_satid	I4	4	1	satellite id in series (1 for NPP)
cris1c_h_instrument	I4	4	1	WMO instrument identifier: 620=CrIS
cris1c_h_satht	I4	4	1	nominal satellite altitude, km*10
cris1c_h_period	I4	4	1	nominal orbit period (seconds)
cris1c_h_startorbit	I4	4	1	orbit number (at start of file)
cris1c_h_startdatayr	I4	4	1	start of data set year
cris1c_h_startdatady	I4	4	1	start of data set day of the year
cris1c_h_startdatatime	I4	4	1	start of data set UTC time of day(ms)
cris1c_h_endorbit	I4	4	1	orbit number (at end of file)
cris1c_h_enddatayr	I4	4	1	end of data set year
cris1c_h_enddatady	I4	4	1	end of data set day of the year
cris1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
cris1c_h_scnlin	I4	4	1	count of scan lines in this data set
cris1c_h_misscnlin	I4	4	1	count of missing scan lines
cris1c_h_spare	I4	4	2	Spare
cris1c_h_wmosatid	I4	4	1	WMO satellite id (224 for NPP)
cris1c_h_spare1	I4	4	1	spare
cris1c_h_centre	I4	4	1	WMO id of reception centre
cris1c_h_subcentre	I4	4	1	WMO id of reception subcentre
CrIS variables				
cris1c_h_recwords	I4	4	1	Size of record in integer*4 words
cris1c_h_nfov	I4	4	1	Number of FOVs
cris1c_h_nfor	I4	4	1	Number of FORs

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aniala h mhand	I4	1	1	Number of bonds
cris1c_h_nband		4	1	Number of bands
cris1c_h_startw	I4	4	cris_1cnba	First wavenumber *1E2
			nd	
cris1c_h_endw	I4	4	cris_1cnba	Last wavenumber *1E2
			nd	
cris1c_h_startchan	I4	4	cris_1cnba	First channel in band
			nd	
cris1c_h_endchan	I4	4	cris_1cnba	Last channel in band
			nd	
cris1c_h_eigvn	I4	4	1	Version number of eigenvectors
cris1c_h_npc	I4	4	1	Number of PCs in format
cris1c_h_npcused	I4	4	1	Number of PCs used
cris1c_h_chanvn	I4	4	1	Version number of channel selection
cris1c_h_nchan	I4	4	1	Number of channels in format
cris1c_h_nchanused	I4	4	1	Number of channels used
cris1c_h_channels	I4	4	cris_1cnch	List of CrIS channels
			an	range 1 to 1317
cris1c_h_spare2	I4	4	cris_1cnch	spare
			an	

One Data Record for one CRIS scan line

Name in AAPP code	Type	Word Size in byte	Number of words	Meaning
cris1c_scnlin	I4	4	1	scan line number
cris1c_scnlinyr	I4	4	1	scan line year
cris1c_scnlindy	I4	4	1	scan line day of year
cris1c_scnlintime	I4	4	cris_1cnfo	scan line UTC time of day (ms)
			r	
cris1c_latlon	I4	4	2*cris_1cn	first : 10 ⁴ x (latitude)
			fov*cris_1	second: 10 ⁴ x (longitude)
			cnfor	
cris1c_angles	I4	4	4*cris_1cn	first: 10^2 x (local zenith angle)
			fov*cris_1	second: 10 ² x (local azimuth angle)
			cnfor	third: 10^2 x (solar zenith angle)
				fourth: 10 ² x (solar azimuth angle)
cris1c_satxyz	I4	4	3	x,y,z of satellite at mid-scan
cris1c_ascdesc	I4	4	1	ascending / descending orbit qualifier
cris1c_orbit	I4	4	1	orbit number
cris1c_scalti	I4	4	1	satellite altitude
cris1c_surfht	I4	4	cris_1cnfo	surface height
			v*cris_1cn	_
			for	
cris1c_landfrac	I4	4	cris_1cnfo	land fraction
			v*cris_1cn	

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			for	
cris1c_landsea	I4	4	cris_1cnfo	land/sea qualifier
_ · · · · <u>_</u> · · · · · · · · ·			v*cris_1cn	1
			for	
cris1c_cloudcover	I4	4	cris_1cnfo	cloud cover (percent)
ensite_ensuaes ver		•	v*cris_1cn	percent)
			for	
cris1c_cloudtopht	I4	4	cris_1cnfo	height of top of cloud (m)
ons re_ors water		•	v*cris_1cn	in gin or top or troub (in)
			for	
cris1c_radianceflgs	I4	4	cris_1cnfo	radiance flags
eris re_radianeerigs		•	v*cris_1cn	!Bit(1=MS)
			for	1 Clear path
				2 Partly cloudy path
				3 Cloudy path
				4 Apodized
				5 Unapodized
				6 Reconstructed
				7 Cloud cleared
				8-14 Reserved
				All 15 Missing value
cris1c_scanqualflgs	I4	4	1	Bit(1=MS)
criste_seanquarigs	1	•	1	Gap in Raw Data Record (RDR) data
				detected (i.e., missing scan(s) preceding the
				current scan)
				2 Recorded time is not in sequence (i.e.,
				the scan start time is out of sequence)
				3 Lamda monitored calculation cannot be
				updated
				4 The measured temperatures of any
				instrument components (e.g., beam-splitter,
				scan mirror, scan baffle, etc.) are outside the
				allowable ranges
				5 At least one of the monitored
				instrument temperatures has drifted more than
				a specified tolerance value
				6-12 Reserved
				All 13 Missing value
cris1c_calqualflgs	I4	4	cris_1cnba	
cristc_caiquairigs	17	7	nd*cris_1c	Lunar intrusion on first deep space
			nfov	view (see Note)
			IIIOV	2 Lunar intrusion on second deep space
				view (see Note)
				3-8 Reserved
				All 9 Missing value
cris1c_fovqualflgs	I4	4	cris_1cnba	Bit(1=MS)
cristc_rovquarings	14	4	nd*cris_1c	1 ' '
			<u> </u>	Degraded SDR quality
			nfov*cris_	2 Invalid SDR quality

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			T 4 2	
			1cnfor	3 Invalid SDR geolocation information
				4 Degraded radiometric calibration
				5 Invalid radiometric calibration
				6 Degraded spectral calibration
				7 Invalid spectral calibration
				8 Fringe count error detected and
				corrected
				9 Day/night indicator
				10 Invalid RDR data
				Significant fringe count error detected
				Bit trim failed
				13-18 Reserved
				All 19 Missing value
cris1c_geolocqual	I4	4	1	Nominal
	1 1	•	1	1 Missing at most a small gap of altitude and
				Ephemeris data
				2 Missing more than a small gap of altitude
				and Ephemeris data, but no more than a
				granule boundary
				, ·
				3 Missing more than a granule boundary of
				altitude and Ephemeris data
				4-14 Reserved
. 1 11,	T4	4	. 1 6	15 Missing
cris1c_quality	I4	4	cris_1cnfo	
			v*cris_1cn	
			for	2 Very suspect
				3 Unusable
cris1c_scores	I4	4	cris_1cnpc	PC scores
			*cris_1cnf	
			ov*cris_1c	
			nfor	
cris1c_logfit	I4	4	cris_1cnba	Log Reconstruction Scores
			nd*cris_1c	
			nfov*cris_	
			1cnfor	
cris1c_radiance	I4	4	cris_1cnfo	Radiance
			v*cris_1cn	Wm-2sr-1cm *1E7
			for*cris_1	
			cnchan	
	1 1		Ciiciiuii	

22. FORMAT OF THE ATMS.L1C FILE

Header and record length

Header length = record length

array_size_atms1c = (8 + 3*atms_1cnchan + 7*atms_1cnfov + 2*atms_1cnchan*atms_1cnfov)*4 bytes

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= 4970*4 bytes by default

with

 $atms_1cnchan = 22$

atms_1cnfov = 96

array_size_atms1cspare = array_size_atms1c - 30 - 8*atms_1cnchan

<u>Type</u>

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number	Meaning
	- 3 P	in byte	of words	
		v	L INFORM	IATION
atms1c_h_site	С	3	1	1D dataset creation site ID
atms1c_h_cfill1	С	1	1	filler
atms1c_h_1bsite	С	3	1	creation site for original 1B data
atms1c_h_cfill2	С	1	1	filler
atms1c_h_versnb	I4	4	1	level 1c format version number
atms1c_h_versyr	I4	4	1	level 1c format version year
atms1c_h_versdy	I4	4	1	level 1c format version day of year
atms1c_h_hdrcnt	I4	4	1	level 1c format version day of year
atms1c_h_satid	I4	4	1	satellite id (1 for NPP)
atms1c_h_instrument	I4	4	1	WMO instrument identifier: 621=ATMS
atms1c_h_satht	I4	4	1	nominal satellite altitude, km*10
atms1c_h_period	I4	4	1	nominal orbit period (seconds)
atms1c_h_startorbit	I4	4	1	orbit number (at start of file)
atms1c_h_startdatayr	I4	4	1	start of data set year
atms1c_h_startdatady	I4	4	1	start of data set day of the year
atms1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
atms1c_h_endorbit	I4	4	1	orbit number (at end of file)
atms1c_h_enddatayr	I4	4	1	end of data set year
atms1c_h_enddatady	I4	4	1	end of data set day of the year
atms1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
atms1c_h_scnlin	I4	4	1	count of scan lines in this data set
atms1c_h_misscnlin	I4	4	1	count of missing scan lines
atms1c_h_vnantennacorr	I4	4	1	version number, antenna corrections
atms1c_h_spare	I4	4	1	Spare
temperature-radiance conv	ersion c	oefficients		
atms1c_h_tempradcnv	I4	4	3*atms_1c	order of channels = 1,2,3,4,,22
			nchan	for nochannel = 1 to 22:

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	I		T	T
				10^6 x (nochannel central wavenumber)
				10 ⁶ x (nochannel constant 1)
				10^6 x (nochannel constant 2)
atms1c_h_bandwidth	I4	4	atms_1cnc	
			han	
atms1c_h_nchan	I4	4	1	
atms1c_h_nfov	I4	4	1	
atms1c_h_nchanused	I4	4	1	
atms1c_h_recwords	I4	4	1	Words in record
atms1c_h_wmosatid	I4	4	1	WMO satellite id (224 for NPP)
atms1c_h_centre	I4	4	1	WMO id of reception centre
atms1c_h_subcentre	I4	4	1	WMO id of reception subcentre
The following variables ch	naracteris	se any image pr	ocessing	
atms1c_h_beamversion	I4	4	1	User defined (see atms_beamwidth.dat)
atms1c_h_beamwidth	I4	4	atms_1cnc	FFT manipulation: deg*1E3
			han	
atms1c_h_cutoff	I4	4	atms_1cnc	FFT manipulation: fraction*1E3
			han	-
atms1c_h_nxaverage	I4	4	atms_1cnc	Simple averaging
			han	
atms1c_h_nyaverage	I4	4	atms_1cnc	Simple averaging
			han	
atms1c_h_filler	I4	4	array_size	filler
			_atms1csp	
			are	

One Data Record for one ATMS scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
atms1c_scnlin	I4	4	1	scan line number
atms1c_scnlinyr	I4	4	1	scan line year
atms1c_scnlindy	I4	4	1	scan line day of year
atms1c_scnlintime	I4	4	atms_1cnf	scan line UTC time of day in milliseconds
			ov	
atms1c_orbit	I4	4	1	
atms1c_granulequal	I4	4	1	granule quality flags
				Bit(1=MS of 16 bits)
				1-5 Reserved
				6 The No. 1-No.7 health checks failed
				7 The No. 8-No.15 health checks failed
				8 The No. 16-No.23 health checks failed
				9 The No. 24-No.31 health checks failed
				The No. 32-No.39 health checks failed
				The No. 40-No.47 health checks failed

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				12 The No. 48-No.55 health checks failed 13 The No. 56-No.63 health checks failed 14 The No. 64-No.70 health checks failed 15 Quadratic correction applied to the radiometric transfer function for non-linearity correction All 16 Missing value
atms1c_scanqual	I4	4	1	scan line quality flags Bit(1=MS of 20 bits) 1-6 Reserved 7 Divide-by-zero condition or computation loop failed to converge in the K/Ka and V (KAV) Band PRT 8 Divide-by-zero condition or computation loop failed to converge in the WG Band PRT 9 Divide-by-zero condition or computation loop failed to converge in the K/Ka, V, W, G Band Receiver Shelf PRT K temperature computation 10 Out of range condition for the K/Ka and V Band PRT 11 Out of range condition for the WG Band PRT 12 KAV PRT temperature inconsistency 13 WG PRT temperature inconsistency 14 Time Sequence Error 15 Data Gap - Missing scan(s) preceding the current scan 16 KAV PRT Sufficiency - Insufficient KAV PRT data are available 17 WG PRT Sufficiency - Insufficient WG PRT data are available 18 Space View antenna position error 19 Blackbody antenna position error All 20 Missing value
atms1c_geolocqual	I4	4	1	geolocation quality Value 0 Nominal - altitude and Ephemeris data available 1 Missing at most a small gap of altitude and Ephemeris data 2 Missing more than a small gap of altitude and Ephemeris data, but no more than a granule boundary 3 Missing more than a granule boundary of altitude and Ephemeris data 4-14 Reserved 15 Missing

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atura 1 a alta un avval	14	1		avality floor for each shown al
atms1c_chanqual	I4	4		quality flag for each channel
			han	Bit(1=MS of 12 bits)
				1-2 Reserved
				3 Moon in Space View
				4 Gain Error - The lowest blackbody
				count is smaller than or equal to the highest
				space view count in a scan
				5 Calibration With Fewer Than Preferred
				Samples
				6 Space View Data Sufficiency Check -
				Insufficient space view samples are available
				7 Blackbody View Data Sufficiency
				Check - Insufficient blackbody view samples
				are available
				8 Out of range condition for the Space
				View
				9 Out of range condition for the
				BlackBody View
				10 Space view inconsistency
				11 BlackBody view inconsistency
				All 12 Missing value
atms1c_latlon	I4	4	2*atms_1c	-
_			nfov	first : 10 ⁴ x (latitude)
				second: 10 ⁴ x (longitude)
atms1c_angles	I4	4	4*atms_1c	
			nfov	first: 10^2 x (local zenith angle)
				second: 10^2 x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
				fourth: 10^2 x (solar azimuth angle)
atms1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
atms1c nedtcold	I4	4	atms_1cnc	Cold view NEDT K*100
		-	han	
atms1c_nedtwarm	I4	4	atms_1cnc	Warm view NEDT K*100
		•	han	11221111
atms1c_anttemps	I4	4	atms_1cnc	Antenna temps *100
		•	han*atms_	
			1cnfov	
atms1c_btemps	I4	4	atms_1cnc	BT *100
amino re_otompo		•	han*atms_	
			1cnfov	
			TCIIIOV	

23. FORMAT OF THE AVH.L1C FILE AND AVH.L1D FILE

The same format for a AVH level 1c file and the AVH level 1d file

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Header and record length
Header length = record length
29808*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENERA	L INFORM	AATION
avh1c_h_site	С	3	1	dataset creation site ID
avh1c_h_cfill1	С	1	1	filler
avh1c_h_1bsite	С	3	1	creation site for original 1B data
avh1c_h_cfill2	С	1	1	filler
avh1c_h_versnb	I4	4	1	level 1c format version number
avh1c_h_versyr	I4	4	1	level 1c format version year
avh1c_h_versdy	I4	4	1	level 1c format version day of year
avh1c_h_hdrcnt	I4	4	1	count of header records in this data set
avh1c_h_satid	I4	4	1	satellite id (e.g. 14 for NOAA-14)
avh1c_h_instrument	I4	4	1	instrument identification (1=AVHRR)
avh1c_h_satht	I4	4	1	nominal satellite altitude, km*10
avh1c_h_period	I4	4	1	nominal orbit period (seconds)
avh1c_h_startorbit	I4	4	1	orbit number (at start of file)
avh1c_h_startdatayr	I4	4	1	avh1c_h_startdatayr
avh1c_h_startdatady	I4	4	1	start of data set day of the year
avh1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
avh1c_h_endorbit	I4	4	1	orbit number (at end of file)
avh1c_h_enddatayr	I4	4	1	end of data set year
avh1c_h_enddatady	I4	4	1	end of data set year
avh1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
avh1c_h_scnlin	I4	4	1	count of scan lines in this data set
avh1c_h_misscnlin	I4	4	1	count of missing scan lines
avh1c_h_callocscnlin	I4	4	1	count of calibrated, earth located scan lines in
				this data set
avh1c_h_datagaps	I4	4	1	count of data gaps in this data set
avh1c_h_datatyp	I4	4	1	data type code
				(1 = LAC; 2 = GAC; 3 = HRPT)
avh1c_h_infilename	С	68	1	input file name (allow pfs name)
avh1c_h_wmosatid	I4	4	1	WMO satellite id (3 for METOP-1)
CALIBRATION INFORI	MATION			
avh1c_h_cpidsyr	I4	4	1	year of Last CPIDS Update

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14 1 11 1	T.4	4	1	D CM CI CDIDCH I
avh1c_h_cpidsdy	I4	4	1	Day of Year of Last CPIDS Update
NAVIGATION INFORM	ATION			
avh1c_h_rollerr	I4	4	1	10 ³ x (constant roll attitude error in degrees)
avh1c_h_pitcherr	I4	4	1	10 ³ x (constant pitch attitude error in degrees)
avh1c_h_yawerr	I4	4	1	10 ³ x (constant yaw attitude error in degrees)
RADIANCE TO TEMPE	RATUR	E CONVERSIO	N	
avh1c_h_albcnv	I4	4	2*avh1c_	albedo conversion
			mxvischn	order of channels : 1, 2, 3A.
				for nochannel = 1 to 3A:
				10^1 x (albedo-radiance nochannel solar
				filtered irradiance in wavelength)
				10 [^] 3 x (albedo-radiance nochannel equivalent
				filter width in wavelength)
avh1c_h_radtempcnv	I4	4	3*avh1c_	radiance to temperature conversion
			mxirchn	order of channels : 3B, 4, 5.
				for nochannel = 3B to 5:
				10^2 x (temperature-radiance nochannel
				central wavenumber Ch3b)
				or 10 [^] 3 x (temperature-radiance nochannel
				central wavenumber Ch4,5)
				10^5 x (temperature-radiance nochannel
				constant 1)
				10 ⁶ x (temperature-radiance nochannel
				constant 2)
avh1c_h_filler(7391)	I4	4	7391	Filler <zero fill=""></zero>

One Data Record for one AVHRR scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
avh1c_scnlin	I4	4	1	scan line number
avh1c_scnlinyr	I4	4	1	scan line year
avh1c_scnlindy	I4	4	1	scan line day of year
avh1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
avh1c_clockdrift	I4	4	1	satellite clock drift delta in milliseconds
avh1c_scnlinbit	I4	4	1	scan line bit field
				bit 15 : (0 = ascending data; 1 = descending
				data)
				bit 14 : (1 = scan time corrected for clock drift)
				bit 13 : (1 = earth location corrected for TIP
				attitude)
				bit 0 : channel 3 select $(0 = 3A; 1 = 3B)$
avh1c_spare0	I4	4	2	<zero fill=""></zero>
QUALITY INDICATORS	S			
avh1c_qualind	I4	4	1	quality indicator bit field

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				bit 31 : (1 = do not use data for product
				generation)
				bit 30 : (1 = time sequence error detected in
				this frame)
				bit 29 : (1 = data gap precedes this frame)
				bit 28 : (1 = insufficient data for calibration)
				bit 27 : (1 = earth location data not available)
				bit 26: (1 = sync lock dropped during this
				frame)
				bit 25 : (1 = frame sync word error greater than
				zero)
				bit 24 : (1 = frame sync previously dropped
				lock)
				bit 23 : (1 = flywheeling detected during this
				frame)
				bit 22 : (1 = bit slippage detected during this
				frame)
				bit 9: tip parity in first minor frame
				bit 8: tip parity in second minor frame
				bit 7: tip parity in third minor frame
				± ± •
				bit 6: tip parity in fourth minor frame
				bit 5: tip parity in fifth minor frame
				bit 4 : (1 = reflected sunlight detected channel
				(3B)
				bit 3: (1 = reflected sunlight detected channel
				4)
				bit 2: (1 = reflected sunlight detected channel
				5)
				bit 1: (1 = resync occurred on this frame)
				bit $0: (1 = pseudo noise occurred on this)$
				frame)
avh1c_scnlinqual	I4	I4	1	scan line quality flags
aviire_seminquui		11	1	sean mie quanty mags
				Time Problem Code
				Time Troblem Code
				hit 21 24 copara
				bit 31-24: spare
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time filed is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous time (i.e., there is a
				time discontinuity).this may or may not
				associated with a spacecraft clock update.(see
				bit 26 above)
				bit 20: start of a sequence that apparently
				repeats scan times that have been previously
				accepted.
	l			accepted.

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		1		1
				bit 19-16 : spare
				Calibration Problem Code
				(all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap bit 13: scan line was not calibrated because of bad or insufficient PRT data bit 12: scan line was calibrated but with marginal PRT data bit 11: some uncalibrated channels on this scan (see channel indicators) bit 10: spare bit 09: spare bit 09: spare Earth location Problem Code
				(all bits set to 0 implies the earth location was normal)
				bit 07 : not earth located because of bad time bit 06 : earth location questionable because of questionable time code
				(see time problem flags above)
				bit 05 : earth location questionable only marginal agreement with reasonableness check
				bit 04 : earth location questionable fails
				reasonnableness check
auhla aclausi	I4	4	ovhla	bit 03-00 : spare
avh1c_calqual	14	4	avh1c_mx irchn	calibration quality flags
			1101111	order of channels : 3B, 4, 5.
				(all bits off implies a good calibration)
				bit 7: this channel is not calibrated
				bit 6 : this channel is calibrated but
				questionable
				bit 5: not good blackboody count for scan line
				bit 4 : not good space view counts for scan line bit 3 : insufficient PRT data
				bit 2 : some bad blackboody view counts for
				this line
				bit 1 : some bad space view counts for this line

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				bit 0 : some b	ad PRT data
avh1c_spare1	I4	4	2	<zero fill=""></zero>	
NAVIGATION					
avh1c_scalti	I4	4	1	10 x Spacecra	aft Altitude (MSL) in km in this
				scan line	, , , , , , , , , , , , , , , , , , , ,
avh1c_ang	I4	4	3*51		s in degrees for point 25 to point
		-		2025 every 40	
				•	10^2 x (solar zenith angle)
					e: 10^2 x (satellite zenith angle)
				_	10^2 x (relative azimuth angle)
avh1c_pos	I4	4	2*51		degrees for point 25 to point
_1				2025 every 40	
				first : 10^4 x	
					x (longitude)
					e and East longitude are positive)
avh1c_spare2	I4	4	2	<zero fill=""></zero>	<u> </u>
AVHRR SENSOR DATA				I	
avh1c_btemps	I2	2	avh1c_mx	avh1c mxpix	= 2048 for pixel in line
_ 1			hrpchn*av		chn = 5 for channels every pixel
			h1c_mxpi	albedo	! 100*%
			_ x	IRchannels	! 100*K
AVHRR CLOUD MASK					
avh1c_maskind	I4	4	1	cloud mask de	one =1
avh1c_mask	I2	2	avh1c_mx	avh1c_mxpix	= 2048 for pixel in line
			pix	avh1c_mxhrp	chn = 5 for channels every pixel
				bits 15-14:	0 Night
					1 Twilight
					2 Day
					3 Sunglint
				bit 13:	1 sea
					0 land or coast
				bit 12 :	1 cloudy
					0 clear
				bit 11 :	1 blackbody (only filled if
					bit12 = 1)
				bits 10-6:	
				0	non-processed: containing no
				data or corrup	
				1	cloud free land no
					by snow/ice covered surface, no
					by clouds; but contamination
				by thin dust/v	olcanic clouds not checked
				$\frac{2}{3}$	cloud free sea no contamination
					overed surface, no contamination
				•	it contamination by thin
					clouds not checked
				3	land contaminated by snow

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				A	and another in stad large and the
				4	sea contaminated by snow/ice
				5	very low and cumuliform clouds
				6	very low and stratiform clouds
				7	low and cumuliform clouds
				8	low and stratiform clouds
				9	medium and cumuliform clouds
				10	medium and stratiform clouds
				11	high opaque and cumuliform
				clouds	
				12	high opaque and stratiform
				clouds	ingii opaque ana stratiforni
				13	very high opaque and
				cumuliform of	
				14	very high opaque and stratiform
				clouds	
				15	high semitransparent thin clouds
				16	high semitransparent meanly
				thick clouds	
				17	high semitransparent thick
				clouds	
				18	high semitransparent above low
				or medium cl	
				19	fractional clouds (sub-pixel
				water clouds)	· · · · · · · · · · · · · · · · · · ·
				20	undefined (undefined by CMa)
				bit 5: 0	Ts background : climatology used
				1	Ts background : forecast used
				bits 4-3:	0 WV content : AMSU used
					1 WV content : forecast used
					2 WV content climatology
				hi4 0 1	used
				bit 2-1:qualit	•
					same CMa, 1= bad data,
					different CMa, 3= coast
				bit 0: for ma	arine cloudy =1, clear=0
avh1c_tsurf	I2	2	avh1c_mx	retrieved tem	perature in C*100
			pix		!if clear:
				retrieved SST	(sea) ot Tsurf(land)
					!if cloudy and
				blackbody: cl	loud top temperature
					!0=missing
				values	Č
			1	1	

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avh1c_spare3	I4	4	10	<zero fill=""></zero>

24. FORMAT OF THE MWTS.L1C FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
300*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number	Meaning
	1 J P C	in byte	of words	Training .
			ral informa	tion
mwts1c_h_site	C	3	1	dataset creation site ID
mwts1c_h_cfill1	С	1	1	filler
mwts1c_h_1bsite	С	3	1	creation site for original 1B data
mwts1c_h_cfill2	C	1	1	filler
mwts1c_h_versnb	I4	4	1	level 1c format version number
mwts1c_h_versyr	I4	4	1	level 1c format version year
mwts1c_h_versdy	I4	4	1	level 1c format version day of year
mwts1c_h_hdrent	I4	4	1	count of header records in this data set
mwts1c_h_satid	I4	4	1	satellite identification:
				1=FY3A
				2=FY3B
mwts1c_h_instrument	I4	4	1	instrument code
				15=MWTS
mwts1c_h_satht	I4	4	1	nominal satellite altitude, km*10
mwts1c_h_period	I4	4	1	nominal orbit period (seconds)
mwts1c_h_startorbit	I4	4	1	orbit number (at start of file)
mwts1c_h_startdatayr	I4	4	1	start of data set year
mwts1c_h_startdatady	I4	4	1	start of data set day of the year
mwts1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
mwts1c_h_endorbit	I4	4	1	orbit number (at end of file)
mwts1c_h_enddatayr	I4	4	1	end of data set year
mwts1c_h_enddatady	I4	4	1	end of data set day of the year
mwts1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
mwts1c_h_scnlin	I4	4	1	count of scan lines in this data set

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				1
mwts1c_h_misscnlin	I4	4	1	count of missing scan lines
mwts1c_h_vnantennacor	I4	4	1	version number, antenna corrections
r				
mwts1c_h_spare	I4	4	1	spare
TEMPE	RATUR	E TO RADIA	NCE CON	VERSION COEFFICIENTS
mwts1c_h_tempradcnv	I4	4	3*4	order of channels = 1,2,3,4
				for nochannel = 1 to 4:
				10 ⁶ x (nochannel central wavenumber)
				10^6 x (nochannel constant 1)
				10^6 x (nochannel constant 2)
mwts1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 520 for FY-3A)
mwts1c_h_filler	I4	4	265	filler

One Data Record for one MWTS scan line

Name in AAPP code	Name	Word Size	Number	Meaning
		in byte	of words	
mwts1c_scnlin	I4	4	1	scan line number
mwts1c_scnlinyr	I4	4	1	scan line year
mwts1c_scnlindy	I4	4	1	scan line day of year
mwts1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
mwts1c_qualind	I4	4	1	quality indicator bit field
				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
mwts1c_scanqual	I4	4	1	scan line quality flags
_				time problem code
				(all bits off implies the scan time is as
				expected)
				bit 31-24: spare <zero fill=""></zero>
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time field is bad and can't be inferred
L			l .	

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bit 21: this record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update. (see bit 26 above) bit 20: start of a sequence that apparently repeats sean times that have been previously accepted. moon problem code bit 19: spare bit 18: Moon in MWTS space view, corrected bit 17: spare bit 16: Moon in MWTS space view, uncorrected calibration problem code (all bits set to 0 indicates normal calibration) bit 15: scan line was not calibrated because of bad time bit 14: scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap. bit 13: scan line was not calibrated because of bad or insufficient PRT data bit 11: some uncalibrated but with marginal PRT data bit 11: some uncalibrated channels of this sean. See channel indicators. bit 10: uncalibrated due to instrument mode bits 9 and 8: spare Earth location problem code (all bits set to 0 implies the Earth location was normal) bit 7: not Earth location questionable because of questionable time code (see time problem flags above) bit 5: Earth location questionable. Only marginal agreement with reasonableness check. bit 4: Earth location questionable. Pails reasonableness check. bit 4: Earth location questionable because of antenna position check bit 2-0: spare mwts1c_chanqual 14 4 4 quality flag for each channel with the channels			<u> </u>		
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mwts1c_chanqual I4 4 quality flag for each channel with the channels					=
	mwts1c changual	T4	4	4	1
				-	in the order 1,2,3,4.

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	(all bits off implies a good calibration)
	bit 31-6: spare
	bit 5: No good blackbody counts for scan
	line
	bit 4: No good space view counts for scan
	line
	bit 3: No good PRTs for this line
	bit 2: Some bad blackbody view counts for
	this line
	bit 1: Some bad space view counts for this
	line
	bit 0: Some bad PRT temps on this line
nwts1c_instrtemp1 I4 4 1	MWTS1 RF shelf temp (K*100)
nwts1c_instrtemp2 I4 4 1	MWTS2 RF shelf temp (K*100)
nwts1c_spare1	spare
nwts1c_latlon I4 4 2*15	lat/lon in degrees for fovs
	first : 10 ⁴ x (latitude)
1 0 14 1 2015	second: 10^4 x (longitude)
14 4 2*15 awts1c_surface	Height/type
	first: surface height (metres)
	second : surface type (0=sea, 1=mixed,
	2=land)
nwts1c_angles I4 4*90	scan angles for fovs
	first: 10 ² x (local zenith angle)
	second: 10^2 x (local azimuth angle) third: 10^2 x (solar zenith angle)
	fourth: 10^2 x (solar zeinuf angle)
nwts1c_scalti I4 4 1	sat altitude above reference ellipsoid, km*10
14 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	<u> </u>
14 4 4*15 14 14 15	Spare BT data for fovs
Twiste_biemps 14 4 13	10 ² x scene brightness temperature (K),
	channels 1-4
pwts1c htman IA 4 5*15	
1wt510_0tiliap	
pwts1c datagual I4 4 15	
iwisio_dataquai ii i	
	<u> </u>
	not been calculated due to calibration
	bit 0: set if all channels missing
nwts1c_filler I4 4 13	spare
nwts1c_btmap I4 4 5*15 nwts1c_dataqual I4 4 15	Mapped BT data (MWHS) 10^2 x scene brightness temperature (K), channels 1-4 quality control word for the data in each field of view: (all bits off implies acceptable data) bit 31: spare <zero fill=""> bit 30: set if secondary calibration used bit 29-4: spare <zero fill=""> bit 4-1: bit n set to 1 if brightness temperatur in channel n is physically unreasonable or has not been calculated due to calibration problems.</zero></zero>

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25. FORMAT OF THE MWHS.L1C FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
300*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number	Meaning
	Type	in byte	of words	- Wildering
		- U	ral informa	tion
mwhs1c_h_site	С	3	1	dataset creation site ID
mwhs1c_h_cfill1	С	1	1	filler
mwhs1c_h_1bsite	С	3	1	creation site for original 1B data
mwhs1c_h_cfill2	С	1	1	filler
mwhs1c_h_versnb	I4	4	1	level 1c format version number
mwhs1c_h_versyr	I4	4	1	level 1c format version year
mwhs1c_h_versdy	I4	4	1	level 1c format version day of year
mwhs1c_h_hdrent	I4	4	1	count of header records in this data set
mwhs1c_h_satid	I4	4	1	satellite identification:
				1=FY3A
				2=FY3B
mwhs1c_h_instrument	I4	4	1	instrument code
				16=MWHS
mwhs1c_h_satht	I4	4	1	nominal satellite altitude, km*10
mwhs1c_h_period	I4	4	1	nominal orbit period (seconds)
mwhs1c_h_startorbit	I4	4	1	orbit number (at start of file)
mwhs1c_h_startdatayr	I4	4	1	start of data set year
mwhs1c_h_startdatady	I4	4	1	start of data set day of the year
mwhs1c_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
mwhs1c_h_endorbit	I4	4	1	orbit number (at end of file)
mwhs1c_h_enddatayr	I4	4	1	end of data set year
mwhs1c_h_enddatady	I4	4	1	end of data set day of the year
mwhs1c_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
mwhs1c_h_scnlin	I4	4	1	count of scan lines in this data set
mwhs1c_h_misscnlin	I4	4	1	count of missing scan lines
mwhs1c_h_vnantennacor	I4	4	1	version number, antenna corrections
r				
mwhs1c_h_spare	I4	4	1	spare

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TEMPERATURE TO RADIANCE CONVERSION COEFFICIENTS				
mwhs1c_h_tempradenv	I4	4	3*5	order of channels = $1,2,3,4,5$
				for nochannel = 1 to 5:
				10 ⁶ x (nochannel central wavenumber)
				10^6 x (nochannel constant 1)
				10^6 x (nochannel constant 2)
mwhs1c_h_wmosatid	I4	4	1	WMO satellite id (e.g. 520 for FY-3A)
mwhs1c_h_filler	I4	4	1162	filler

One Data Record for one MWTS scan line

Name in AAPP code	Name	Word Size in byte	Number of words	Meaning
mwhs1c_scnlin	I4	4	1	scan line number
mwhs1c_scnlinyr	I4	4	1	scan line year
mwhs1c_scnlindy	I4	4	1	scan line day of year
mwhs1c_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
mwhs1c_qualind	I4	4	1	quality indicator bit field
mwnsre_quamia	17	7	1	In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
mwhs1c_scanqual	I4	4	1	scan line quality flags
				time problem code
				(all bits off implies the scan time is as
				expected)
				bit 31-24: spare <zero fill=""></zero>
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time field is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous times (i.e., there is a
				time discontinuity). This may or may not be
				associated with a spacecraft clock update. (see

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		T	T	
				bit 26 above)
				bit 20: start of a sequence that apparently
				repeats scan times that have been previously
				accepted.
				moon problem code
				bit 19: spare
				bit 18: Moon in MWHS space view, corrected
				bit 17: spare
				bit 16: Moon in MWHS space view,
				uncorrected
				calibration problem code
				(all bits set to 0 indicates normal calibration)
				bit 15: scan line was not calibrated because of
				bad time
				bit 14: scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of
				bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bits 9 and 8: spare
				Earth location problem code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above)
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails
				reasonableness check
				bit 3: Earth location questionable because of
				antenna position check
				bit 2-0: spare
mwhs1c_chanqual	I4	4	5	quality flag for each channel with the channels
				in the order 1,2,3,4,5.
				(all bits off implies a good calibration)
				bit 31-6: spare
				bit 5: No good blackbody counts for scan
				line
				bit 4: No good space view counts for scan

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				line
				bit 3: No good PRTs for this line
				bit 2: Some bad blackbody view counts for
				this line
				bit 1: Some bad space view counts for this
				line
				bit 0: Some bad PRT temps on this line
mwhs1c_instrtemp	I4	4	1	MWHS instrument temp (K*100)
mwhs1c_spare1	I4	4	2	spare
mwhs1c_latlon	I4	4	2*90	lat/lon in degrees for fovs
				first : 10 ⁴ x (latitude)
				second: 10 ⁴ x (longitude)
mwhs1c_angles	I4	4	4*90	scan angles for fovs
_				first: 10 ² x (local zenith angle)
				second: 10 ² x (local azimuth angle)
				third: 10 ² x (solar zenith angle)
				fourth: 10 ² x (solar azimuth angle)
mwhs1c_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
mwhs1c_spare2	I4	4	2	spare
mwhs1c_btemps	I4	4	5*90	BT data for fovs
				10^2 x scene brightness temperature (K),
				channels 1-5
mwhs1c_dataqual	I4	4	90	quality control word for the data in each field
				of view:
				(all bits off implies acceptable data)
				bit 31: spare <zero fill=""></zero>
				bit 30: set if secondary calibration used
				bit 29-4: spare <zero fill=""></zero>
				bit 5-1: bit n set to 1 if brightness temperature
				in channel n is physically unreasonable or has
				not been calculated due to calibration
				problems.
				bit 0: set if all channels missing
mwhs1c_filler	I4	4	7	spare

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26. FORMAT OF THE HIRS.L1D FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length
Header length = record length
3968*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
		GENERA	L INFORM	MATION
hrs1d_h_site	C	3	1	1D dataset creation site ID
hrs1d_h_cfill1	C	1	1	filler
hrs1d_h_1bsite	C	3	1	creation site for original 1B data
hrs1d_h_cfill2	С	1	1	filler
hrs1d_h_versnb	I4	4	1	level 1d format version number
hrs1d_h_versyr	I4	4	1	level 1d format version year
hrs1d_h_versdy	I4	4	1	level 1d format version day of year
hrs1d_h_hdrcnt	I4	4	1	count of header records in this data set
hrs1d_h_satid	I4	4	1	satellite identification:
				.15=NOAA-15 (NOAA-K)
				16=NOAA-16 (NOAA-L)
				17=NOAA-17 (NOAA-M)
				18=NOAA-18 (NOAA-N)
				19=NOAA-19 (NOAA-N')
				1=Metop-B (Metop-1)
				2=Metop-A (Metop-2)
				3=Metop-C (Metop-3)
				4=Metop simulator
hrs1d_h_grid	I4	4	1	code for instrument grid
_ = =&				(5=HIRS)
hrs1d_h_satht	I4	4	1	nominal satellite altitude, km*10
hrs1d_h_period	I4	4	1	nominal orbit period (seconds)
hrs1d_h_startorbit	I4	4	1	orbit number (at start of dataset)
hrs1d_h_startdatayr	I4	4	1	start of data set year
hrs1d_h_startdatady	I4	4	1	start of data set day of the year

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IΛ	Λ	1	start of data set UTC time of day (ms)			
		1	orbit number (at end of dataset)			
			end of data set year			
			end of data set year end of data set day of the year			
			end of data set UTC time of day (ms)			
			count of scan lines in this data set			
			count of missing scan lines			
			ATOVPP version number (test vns = 9000+)			
14	4	1	instruments present (bit0=HIRS, bit1=MSU, bit3=AMSU-A, bit4=AMSU-B or MHS, bit5=AVHRR)			
I4	4	1	WMO satellite id (e.g. 3 for METOP-1)			
I4	4	1	spare			
RE TO	RADIANCE	CONVERS	SION COEFFICIENTS (Planck function)			
I4	4	3*19	order of channels = HIRS 1,2,3,4,,18,19 (1,*) = 10^6 x (central wavenumber) (scaling factor for wavenumber changes to 10^5 for channels 13-19 inclusive) (2,*) = 10^6 x (constant 1) (3,*) = 10^6 x (constant 2)			
I4	4	1	10^6 x (albedo-radiance ch20 solar filtered irradiance W/m2)			
I4	4	1	10^6 x (albedo-radiance ch 20 equivalent filter width cm^-1)			
I4	4	1	spare			
PERAT	URE TO RAI	DIANCE (CONVERSION COEFFICIENTS (Planck			
		function)				
I4	4	3*20	order of channels = AMSU-A 1-15, AMSU-B 1-5 (1,*) = 10^6 x (central wavenumber) (2,*) = 10^6 x (constant 1) (3,*) = 10^6 x (constant 2)			
PRE-PROCESSING INFORMATION						
	PRE-PROCES	SING INF				
I4	PRE-PROCES 4	SING INF				
			size of data batches processed within ATOVPP (seconds - see ATOVPP documentation) mapping method used for BTs (1=nearest neighbour, 2=bilinear interpolation,			
I4	4	1	size of data batches processed within ATOVPP (seconds - see ATOVPP documentation) mapping method used for BTs (1=nearest neighbour, 2=bilinear interpolation, 3=spatial averaging) vn no HIRS limb/emiss correction			
I4 I4	4	1	size of data batches processed within ATOVPP (seconds - see ATOVPP documentation) mapping method used for BTs (1=nearest neighbour, 2=bilinear interpolation, 3=spatial averaging) vn no HIRS limb/emiss correction (=0 if data not corrected) vn no HIRS cloud detection/correction			
I4 I4 I4	4 4	1 1	size of data batches processed within ATOVPP (seconds - see ATOVPP documentation) mapping method used for BTs (1=nearest neighbour, 2=bilinear interpolation, 3=spatial averaging) vn no HIRS limb/emiss correction (=0 if data not corrected) vn no HIRS cloud detection/correction (=0 if not done) vn no AMSU-A limb/emiss correction			
I4 I4 I4 I4	4 4 4	1 1 1 1	size of data batches processed within ATOVPP (seconds - see ATOVPP documentation) mapping method used for BTs (1=nearest neighbour, 2=bilinear interpolation, 3=spatial averaging) vn no HIRS limb/emiss correction (=0 if data not corrected) vn no HIRS cloud detection/correction (=0 if not done)			
	I4 RE TO I4 I4 I4 I4 PERAT	I4 4 PERATURE TO RAI	I4 4 1 I4 4 3*19 I4 4 1 PERATURE TO RADIANCE (function) 1			

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				(C A TONIDI)
				(from ATOVIN)
hrs1d_h_Bcorrvn	I4	4	1	vn no AMSU-B/MHS limb/emiss correction
				(=0 if data not corrected)
hrs1d_h_Bpcpvn	I4	4	1	vn no AMSU-B/MHS precip/scatter detection
				(=0 if not done)
hrs1d_h_Bantenna	I4	4	1	vn no, AMSU-B/MHS antenna corrections
				(from ATOVIN)
hrs1d_h_Ascat	I4	4	1	threshold value for AMSU-A scattering index
hrs1d_h_ACrosby	I4	4	1	threshold value for AMSU-A logistic precip
hrs1d_h_AB89	I4	4	1	threshold value for AMSU-A/AMSU-B or
				MHS 89GHz differences
hrs1d_h_spare3	I4	4	3809	spare

One Data Record for one HIRS scan line

Name in AAPP code	Type	Word Size in byte	Number of words	Meaning
hrs1d_scnlin	I4	4	1	scan line number
hrs1d_scnlinyr	I4	4	1	scan line year
hrs1d_scnlindy	I4	4	1	scan line day of year
hrs1d_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
hrs1d_qualind	I4	4	1	quality indicator bit field
				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no HIRS calibration
				bit 27: no Earth location
				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
1 11 1	T.4	4	1	bit 24-0: spare <zero fill=""></zero>
hrs1d_scanqual	I4	4	1	scan line quality flags
				time problem code
				(all bits off implies the scan time is as
				expected)
				bit 31-24: spare <zero fill=""></zero>
				bit 23: time field is bad but can probably be
				inferred from the previous good time

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			1	
				bit 22: time field is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous times (i.e., there is a
				time discontinuity). This may or may not be
				associated with a spacecraft clock update. (see
				bit 26 above)
				bit 20: start of a sequence that apparently
				repeats scan times that have been previously
				accepted.
				bits 19-16: spare
				calibration problem code
				(all bits set to 0 indicates normal calibration)
				bit 15: scan line was not calibrated because of
				bad time
				bit 14: scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of
				bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bits 9 and 8: spare
				Earth location problem code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above)
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness
				check.
				bit 4: Earth location questionable. Fails
				reasonableness check
				bit 3-0: spare
hrs1d_instrtemp	I4	4	1	HIRS baseplate temperature (K*100)
hrs1d_instrtempa1	I4	4	1	AMSU-A1 RF shelf temp (K*100)
hrs1d_instrtempa2	I4	4	1	AMSU-A2 RF shelf temp (K*100)
hrs1d_instrtempb	I4 I4	<u> </u>	1	AMSU-B/MHS mixer ch 18-20 temp (K*100)
msru_msutempo	14	4	1	(all from the nearest scanlines)
hrold operat	T.A	Λ	2	
hrs1d_spare1	I4	4		spare
hrs1d_latlon	I4	4	2*56	lat/lon in degrees for Hnfovs
				first : 10 ⁴ x (latitude)

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				second: 10^4 x (longitude)
hrs1d_surface	I4	4	2*56	height/type for Hnfovs
		-		first : surface height (metres)
				second : surface type (0=sea, 1=mixed,
				2=land)
hrs1d_angles	I4	4	4*56	scan angles for Hnfovs
		•		first: 10 ² x (local zenith angle)
				second: 10 ² x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
				fourth: 10 ² x (solar azimuth angle)
hrs1d_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
hrs1d_spare2	I4	4	2	spare
hrs1d_btemps	I4	4	(20+15+5)	10^2 x scene brightness temperature (K) for
_ 1			*56	channels HIRS 1-20, AMSU-A 1-15, AMSU-
				B 1-5
				10^2 x radiance Wm-2sr-1(cm-1)-1 for
				channel HIRS 20
hrs1d_avhrr	I4	4	13*56	AVHRR parameters in HIRS fov.
				For mode=1 in avh2hirs_atovs.F:
				Word 1: percentage of clear AVHRR pixels
				Words 2-6: mean albedo (%*100) or brightness
				temperature (K*100), AVHRR channels 1-5 Words 7-11: mean clear albedo (%*100) or
				brightness temperature (K*100), channels 1-5
				Word 12: std dev chan 4, all pixels (K*100)
				Word 13: std dev chan 4, clear pixels (K*100)
				For mode=2 in avh2hirs_atovs.F:
				Word 1: percentage of clear AVHRR pixels
				Word 2: surface temperature (K*100)
				Word 3: climatological temperature or t2m (K*100) Words 4-6: mean brightness temperature channels 3-
				5 (K*100)
				Word 7: percentage of pixels that are black body
				Word 8: cloud top temperature (K*100)
				Word 9: standard deviation of cloud top T (K*100)
				Word 10: mean chan 4, clear pixels (K*100) Word 11: mean chan 5, clear pixels (K*100)
				Word 12: std dev chan 4, all pixels (K*100)
				Word 13: std dev chan 4, clear pixels (K*100)
			CESSING C	•
hrs1d_hirsqual	I4	4	56	HIRS quality control word for each field of
				view:
				(all bits off implies acceptable data)
				[user-defined:
				bit 31: spare <zero fill=""></zero>
				bit 30: set if secondary calibration used (see
				calflg)
				bit 29-22: spare <zero fill=""></zero>
				bit 21: HIRS cloud test (TBD)
]
				bit 20-1: bit n set to 1 if brightness

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				temperature in HIRS channel n is physically
				unreasonable or has not been calculated due to
				calibration problems.
				bit 0: bad or missing data (in any or all
				channels)
hrs1d_prepro	I4	4	7*56	values from pre-processing
пізта_рієріо			7*30	(1,*): pre-processing quality control word with flags all bits off implies acceptable data) bit 31: set if AMSU-A surface types not all the same bit 30: set if AMSU-A used secondary calibration bit 29: set if AMSU-B/MHS used secondary calibration bit 28: set if AMSU-B/MHS data missing bit 27: flag for cloud cost set for any mapped AMSU-A bit 26: scattering flag set for any mapped AMSU-A (only set over the sea) bit 25: logistic precipitation probability test calculated from AMSU-A data mapped to HIRS grid bit 24: Grody light rainfall test calculated on HIRS grid bit 23: mismatch between AMSU-A/AMSU-B or MHS 89GHz values (any AMSU-A) bit 22: mismatch between surface type from topography dataset and from pre-processing (any AMSU-A) bit 21: fewer AMSU mapping co-locations than expected bit 20-4: spare <zero fill=""></zero>
				bit 3: set when AVHRR channel 3 is albedo not brightness temp
				bit 2: flag for cloud cost (recalculated on HIRS grid)
				bit 1: flag for scattering index (recalculated
				on HIRS grid)
				bit 0: set if AMSU-A & AMSU-B/MHSdata
				missing
				(2,*) estimated surface type from the pre-
				processing:
				1 = Bare young ice (i.e. new ice, no snow)
				2 = Dry land (i.e. dry with or without
				significant vegetation)

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				3 = Dry snow (i.e. snow with water less than 2%, over land) 4 = Multi-year ice (i.e. old ice with snow [assumed dry] cover) 5 = Sea (i.e. open water, no islands, ice-free, WS=0 to 14m/s) 6 = Wet forest (i.e. established forest with wet canopy) 7 = Wet land (i.e. non-forested land with a wet surface) 8 = Wet snow (i.e. snow with water content > 2%, over land or ice)
				9 = Desert
				(3,*) cost fn from PPASURF surface identification (*100)
				(4,*) scattering index (*100)
				(5,*) logistic precipitation probability (*100)
				(6,*) spare
				(7,*) spare
hrs1d_filler	I4	4	89	filler

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27. FORMAT OF THE AMSU-B.L1D FILE

Header and record length
Header length = record length
3072*4 bytes

Type

C = character

I2 = integer*2

I4 = integer*4

Name in AAPP code	Type	Word Size	Number of words	Meaning			
in byte of words GENERAL INFORMATION							
amb1d_h_site	С	3	1	1D dataset creation site ID			
amb1d_h_cfill1	C	1	1	filler			
amb1d_h_1bsite	С	3	1	creation site for original 1B data			
amb1d_h_cfill2	С	1	1	filler			
amb1d_h_versnb	I4	4	1	level 1d format version number			
amb1d_h_versyr	I4	4	1	level 1d format version year			
amb1d_h_versdy	I4	4	1	level 1d format version day of year			
amb1d_h_hdrent	I4	4	1	count of header records in this data set			
amb1d_h_satid	I4	4	1	satellite idendification:			
				.15=NOAA-15 (NOAA-K)			
				16=NOAA-16 (NOAA-L)			
				17=NOAA-17 (NOAA-M)			
				18=NOAA-18 (NOAA-N)			
				19=NOAA-19 (NOAA-N')			
				1=Metop-B (Metop-1)			
				2=Metop-A (Metop-2)			
				3=Metop-C (Metop-3)			
				4=Metop simulator			
amb1d_h_grid	I4	4	1	code for instrument grid			
				(5=HIRS; 6=MSU; 10=AMSU-A; 11=AMSU-			
				B)			
amb1d_h_satht	I4	4	1	nominal satellite altitude, km*10			
amb1d_h_period	I4	4	1	nominal orbit period (seconds)			
amb1d_h_startorbit	I4	4	1	orbit number (at start of dataset)			
amb1d_h_startdatayr	I4	4	1	start of data set year			
amb1d_h_startdatady	I4	4	1	start of data set day of the year			
amb1d_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)			
amb1d h endorbit	I4	4	1	orbit number (at end of dataset)			

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amb1d_h_enddatayr	I4	4	1	end of data set year		
amb1d_h_enddatady	I4	4	1	end of data set day of the year		
amb1d_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)		
amb1d_h_scnlin	I4	4	1	count of scan lines in this data set		
amb1d_h_misscnlin	I4	4	1	count of missing scan lines		
amb1d_h_atovppvn	I4	4	1	ATOVPP version number (test vns = 9000+)		
amb1d_h_instruments	I4	4	1	instruments present (bit0=HIRS, bit1=MSU,		
				bit3=AMSU-A, bit4=AMSU-B or MHS,		
				bit5=AVHRR)		
amb1d_h_wmosatid	I4	4	1	WMO satellite id (e.g. 3 for METOP-1)		
amb1d_h_spare1	I4	4	1	spare		
AMSU(-A&B) TEMPERATURE TO RADIANCE CONVERSION COEFFICIENTS (Planck						
			function)			
amb1d_h_amsPlanck	I4	4	3*20	order of channels = AMSU-A 1-15, AMSU-B		
				1-5		
				$(1,*) = 10^6 x$ (central wavenumber)		
				$(2,*) = 10^6 x \text{ (constant 1)}$		
				$(3,*) = 10^6 x \text{ (constant 2)}$		
		PRE-PROCES	SING INF	ORMATION		
amb1d_h_Bcorrvn	I4	4	1	vn no AMSU-B/MHS limb/emiss correction		
				(=0 if data not corrected)		
amb1d_h_Bpcpvn	I4	4	1	vn no AMSU-B/MHS precip/scatter detection		
				(=0 if not done)		
amb1d_h_spare2	I4	4	2218	spare		

One Data Record for one AMSU-B/MHS scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
amb1d_scnlin	I4	4	1	scan line number
amb1d_scnlinyr	I4	4	1	scan line year
amb1d_scnlindy	I4	4	1	scan line day of year
amb1d_scnlintime	I4	4	1	scan line UTC time of day in milliseconds
amb1d_qualind	I4	4	1	quality indicator bit field
				In all of the following, if the bit is on (= is set
				to 1) then the statement is true. Otherwise it is
				false.
				general
				bit 31: do not use scan for product generation
				bit 30: time sequence error detected with this
				scan
				bit 29: data gap precedes this scan
				bit 28: no AMSU-B calibration
				bit 27: no Earth location

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				bit 26: first good time following a clock
				update
				bit 25: instrument status changed with this
				scan
				bit 24-0: spare <zero fill=""></zero>
amb1d_scanqual	I4	4	1	scan line quality flags
amora_scanquar		•	1	time problem code
				(all bits off implies the scan time is as
				expected)
				bit 31-24: spare <zero fill=""></zero>
				bit 23: time field is bad but can probably be
				inferred from the previous good time
				bit 22: time field is bad and can't be inferred
				from the previous good time
				bit 21: this record starts a sequence that is
				inconsistent with previous times (i.e., there is a
				time discontinuity). This may or may not be
				associated with a spacecraft clock update. (see
				bit 26 above)
				bit 20: start of a sequence that apparently
				repeats scan times that have been previously
				accepted.
				bits 19-16: spare
				calibration problem code
				(all bits set to 0 indicates normal calibration)
				bit 15: scan line was not calibrated because of
				bad time
				bit 14: scan line was calibrated using fewer
				than the preferred number of scan lines
				because of proximity to start or end of data set
				or to a data gap.
				bit 13: scan line was not calibrated because of
				bad or insufficient PRT data
				bit 12: scan line was calibrated but with
				marginal PRT data
				bit 11: some uncalibrated channels of this
				scan. See channel indicators.
				bit 10: uncalibrated due to instrument mode
				bits 9 and 8: spare
				Earth location problem code
				(all bits set to 0 implies the Earth location was
				normal)
				bit 7: not Earth located because of bad time
				bit 6: Earth location questionable because of
				questionable time code (see time problem flags
				above)
				bit 5: Earth location questionable. Only
				marginal agreement with reasonableness

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			check. bit 4: Earth location questionable. Fails reasonableness check bit 3-0: spare
14	4	1	AMSU-B/MHS instrument temp (K*100)
			spare
I4	4	2*90	lat/lon in degrees for Hnfovs first : 10^4 x (latitude) second : 10^4 x (longitude)
I4	4	2*90	height/type for Hnfovs first : surface height (metres) second : surface type (0=sea, 1=mixed, 2=land)
I4	4	4*90	scan angles for Hnfovs first: 10^2 x (local zenith angle) second: 10^2 x (local azimuth angle) third: 10^2 x (solar zenith angle) fourth: 10^2 x (solar azimuth angle)
I4	4	1	sat altitude above reference ellipsoid, km*10
I4	4	2	spare
I4	4	20*90	10^2 x scene brightness temperature (K) for channels AMSU-A 1-15, AMSU-B 1-5
	PRE-PROC		OUTPUTS values from nearest AMSU-A
			(1,*): pre-processing quality control word with flags all bits off implies acceptable data) bit 31: spare bit 30: set if AMSU-B/MHS used secondary calibration bit 29: set if AMSU-A used secondary calibration bit 28: set if AMSU-A data missing bit 27: maximum probability scheme cloud flag bit 26: scattering test (only set over the sea) bit 25: logistic precipitation probability test bit 24: Grody light rainfall test bit 23: mismatch between AMSU-A/AMSU-B or MHS 89GHz values bit 22: mismatch between surface type from topography dataset and from pre-processing bit 21: spare values from the AMSU-B or MHS:
	I4 I4 I4 I4	I4 4 PRE-PROC	I4 4 2 I4 4 2*90 I4 4 2*90 I4 4 4*90 I4 4 1 I4 4 2 I4 4 2 I4 4 20*90 PRE-PROCESSING

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from that in surrounding fovs (PPMEDIAN) bit 19: scattering test (only set over the sea) - using AMSU-B 89GHz channel bit 18: mismatch between AMSU-A/B 89GHz values bit 17: AMSU-B quality control flag 1 bit 16: AMSU-B quality control flag 2 bit 15: AMSU-B quality control flag 3 bit 14: AMSU-B quality control flag 4 bit 13-1: spare bit 0: bad or missing data (in any or all AMSU-B channels)
(2,*) estimated AMSU-A surface type: 1 = Bare young ice (i.e. new ice, no snow) 2 = Dry land (i.e. dry with or without significant vegetation) 3 = Dry snow (i.e. snow with water less than 2%, over land) 4 = Multi-year ice (i.e. old ice with snow [assumed dry] cover) 5 = Sea (i.e. open water, no islands, ice-free, WS=0 to 14m/s) 6 = Wet forest (i.e. established forest with wet canopy) 7 = Wet land (i.e. non-forested land with a wet surface) 8 = Wet snow (i.e. snow with water content > 2%, over land or ice) 9 = Desert
(3,*) cost fn from PPASURF surface identification (*100)
(4,*) scattering index (*100) (recalculated with AMSU-B 89GHz)
(5,*) microwave cirrus index (*1000) (range is +/-200)
(6,*) NWC-SAF scattering index and precipitation probabilities: bit 16-31: scattering index * 100 (K), (range -327.78 K to +327.67 K)
Precipitation probabilities are scaled to 4 bits: 15 = probability of 1.0. bit 0-3: Prob 0-0.1mm/h bit 4-7: Prob 0.1-0.5mm/h

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	bit 8-11: Prob 0.5-5.0 mm/h
	bit 12-15: Prob >5mm/h
	Note: if all four probabilities are zero, they
	could not be calculated.

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28. FORMAT OF THE IASILL1D FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length

Header length = record length

(6377 + 15*iasi_1dnchan + 30*iasi_1dnpc)*4 bytes (default 19587*4 bytes)

where iasi_1dnchan is the number of channels required (default 366), and iasi_1dnpc is the number of Principal Component scores required (default 300).

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning			
		in byte	of words				
GENERAL INFORMATION							
iasi1d_h_site	C	3	1	1D dataset creation site ID			
iasi1d_h_cfill1	C	1	1	filler			
iasi1d_h_1bsite	C	3	1	creation site for original 1B data			
iasi1d_h_cfill2	C	1	1	filler			
iasi1d_h_versnb	I4	4	1	level 1d format version number			
iasi1d_h_versyr	I4	4	1	level 1d format version year			
iasi1d_h_versdy	I4	4	1	level 1d format version day of year			
iasi1d_h_hdrcnt	I4	4	1	count of header records in this data set			
iasi1d_h_satid	I4	4	1	satellite identification:			
				1=Metop-1			
				2=Metop-2			
				3=Metop-3			
				4=Metop simulator			
iasi1d_h_grid	I4	4	1	code for instrument grid			
				(12=IASI)			
iasi1d_h_satht	I4	4	1	nominal satellite altitude, km*10			
iasi1d_h_period	I4	4	1	nominal orbit period (seconds)			
iasi1d_h_startorbit	I4	4	1	orbit number (at start of dataset)			
iasi1d_h_startdatayr	I4	4	1	start of data set year			
iasi1d_h_startdatady	I4	4	1	start of data set day of the year			
iasi1d_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)			
iasi1d_h_endorbit	I4	4	1	orbit number (at end of dataset)			
iasi1d_h_enddatayr	I4	4	1	end of data set year			
iasi1d_h_enddatady	I4	4	1	end of data set day of the year			

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iasi1d_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
iasi1d_h_scnlin	I4	4	1	count of scan lines in this data set
iasi1d_h_misscnlin	I4	4	1	count of missing scan lines
iasi1d_h_atovppvn	I4	4	1	ATOVPP version number (test vns = 9000+)
iasi1d_h_instruments	I4	4	1	instruments present (bit0=HIRS, bit1=MSU,
				bit3=AMSU-A, bit4=AMSU-B or MHS,
				bit5=AVHRR, bit6=IASI)
iasi1d_h_wmosatid	I4	4	1	WMO satellite id (3 for METOP-1, 4 for
				METOP-2, 5 for METOP-3))
iasi1d_h_spare1	I4	4	1	spare
		IASI	VARIABI	LES)
iasi1d_h_startchan	I4	4	10	Start channel for scaling definition
iasi1d_h_endchan	I4	4	10	End channel for scaling definition
iasi1d_h_scalefactor	I4	4	10	Radiance = scalrad*10^-scalefactor
iasi1d_h_eigvn	I4	4	1	Version number of eigenvectors
iasi1d_h_npc	I4	4	1	Number of PCs in format
iasi1d_h_npcused	I4	4	1	Number of PCs used
iasi1d_h_chanvn	I4	4	1	Version number of channel selection
iasi1d_h_nchan	I4	4	1	Number of channels in format
iasi1d_h_nchanused	I4	4	1	Number of channels used
iasi1d_h_channels	I4	4	300	List of IASI channels
				range 1 to 8461
AMSU(-A&B) TEM	1PERAT	URE TO RAI	DIANCE (CONVERSION COEFFICIENTS (Planck
			function)	
iasi1d_h_amsPlanck	I4	4	3*20	order of channels = AMSU-A 1-15, MHS 1-5
				$(1,*) = 10^6 x$ (central wavenumber)
				$(2,*) = 10^6 x \text{ (constant 1)}$
				$(3,*) = 10^6 x \text{ (constant 2)}$
		PRE-PROCES	SING INF	
iasi1d_h_dT	I4	4	1	size of data batches processed within ATOVPP
				(seconds - see ATOVPP documentation)
iasi1d_h_mapBTmode	I4	4	1	mapping method used for BTs
				(1=nearest neighbour, 2=bilinear interpolation,
				3=spatial averaging)
iasi1d_h_Acorrvn	I4	4	1	vn no AMSU-A limb/emiss correction
				(=0 if data not corrected)
iasi1d_h_Apcpvn	I4	4	1	vn no AMSU-A precip/scatter detection
				(=0 if not done)
iasi1d_h_Aantenna	I4	4	1	vn no, AMSU-A antenna corrections
				(from ATOVIN)
iasi1d_h_Bcorrvn	I4	4	1	vn no MHS limb/emiss correction
				(=0 if data not corrected)
iasi1d_h_Bpcpvn	I4	4	1	vn no.MHS precip/scatter detection
				(=0 if not done)
iasi1d_h_Bantenna	I4	4	1	vn no, MHS antenna corrections
				(from ATOVIN)
iasi1d_h_Ascat	I4	4	1	threshold value for AMSU-A scattering index

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iasi1d_h_ACrosby	I4	4	1	threshold value for AMSU-A logistic precip
iasi1d_h_AB89	I4	4	1	threshold value for AMSU-A/AMSU-B or
				MHS 89GHz differences
iasi1d_h_cloudtests	I4	4	1	Cloud tests used (0 if none)
iasi1d_h_recperscan	I4	4	1	Records per scan: 1 or 4
iasi1d_h_fovmode	I4	4	1	0 = full resolution
				1 to $4 = $ fixed detector
				5+ = other methods (TBD)
iasi1d_h_spare2	I4	4	[19153]	spare: size depends on number of chans/scores

One Data Record for one IASI scan line

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
iasi1d_scnlin	I4	4	1	scan line number
iasi1d_scnlinyr	I4	4	1	scan line year
iasi1d_scnlindy	I4	4	1	scan line day of year
iasi1d_scnlintime	I4	4	30	scan line UTC time of day in milliseconds
iasi1d_instrtempa1	I4	4	1	AMSU-A1 RF shelf temp (K*100)
iasi1d_instrtempa2	I4	4	1	AMSU-A2 RF shelf temp (K*100)
iasi1d_instrtempb	I4	4	1	AMSU-B mixer ch 18-20 temp (K*100)
				(all from the nearest scanlines)
iasi1d_spare1	I4	4	2	spare
iasi1d_latlon	I4	4	2*30	lat/lon in degrees
				first : 10 ⁴ x (latitude)
				second: 10^4 x (longitude)
iasi1d_surface	I4	4	2*30	height/type
				first : surface height (metres)
				second: surface type (0=sea, 1=mixed,
				2=land)
iasi1d_angles	I4	4	4*30	scan angles
				first: 10 ² x (local zenith angle)
				second: 10^2 x (local azimuth angle)
				third: 10 ² x (solar zenith angle)
				fourth: 10^2 x (solar azimuth angle)
iasi1d_scalti	I4	4	1	sat altitude above reference ellipsoid, km*10
iasi1d_spare2	I4	4	2	spare
		AMSU-A+M	HS MAPPE	
iasi1d_btemps	I4	4	(15+5)*30	
				AMSU-A 1-15, MHS 1-5
				10^2 x radiance Wm-2sr-1(cm-1)-1 for
				channel HIRS 20
iasi1d_iasiqual	I4	4	30	Quality control word for each field of view:
				(all bits off implies acceptable data)

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			Ţ	
				[user-defined:
				bit 23-4: bit n set to 1 if brightness
				temperature in AMSU-A+MHS channel n-3 is
				physically unreasonable or has not been
				calculated due to calibration problems.
				bit 3-1: bit n set to 1 if data for IASI detector
				n are bad
				bit 0: bad or missing data (in any or all
				channels)
iasi1d_prepro	I4	4	7*30	values from pre-processing
				(1,*): pre-processing quality control word
				with flags
				all bits off implies acceptable data)
				bit 31: set if AMSU-A surface types not all
				the same
				bit 30: set if AMSU-A used secondary
				calibration
				bit 29: set if MHS used secondary calibration
				bit 28: set if MHS data missing
				bit 27: flag for cloud cost set for any mapped
				AMSU-A
				bit 26: scattering flag set for any mapped
				AMSU-A (only set over the sea)
				bit 25: logistic precipitation probability test
				calculated from AMSU-A data mapped to
				HIRS grid
				bit 24: Grody light rainfall test calculated on
				HIRS grid
				bit 23: mismatch between AMSU-A/MHS
				89GHz values (any AMSU-A)
				bit 22: mismatch between surface type from
				topography dataset and from pre-processing
				(any AMSU-A)
				bit 21: fewer AMSU mapping co-locations
				than expected
				bit 20-4: spare <zero fill=""></zero>
				bit 3: set when AVHRR channel 3 is albedo
				not brightness temp
				bit 2: flag for cloud cost (recalculated on
				HIRS grid)
				bit 1: flag for scattering index (recalculated
				on HIRS grid)
				bit 0: set if AMSU-A & MHSdata missing
				(2,*) estimated surface type from the pre-
				processing:
				1 = Bare young ice (i.e. new ice, no snow)

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				2 = Dry land (i.e. dry with or without significant vegetation) 3 = Dry snow (i.e. snow with water less than 2%, over land) 4 = Multi-year ice (i.e. old ice with snow [assumed dry] cover) 5 = Sea (i.e. open water, no islands, ice-free, WS=0 to 14m/s) 6 = Wet forest (i.e. established forest with wet canopy) 7 = Wet land (i.e. non-forested land with a wet surface) 8 = Wet snow (i.e. snow with water content > 2%, over land or ice) 9 = Desert (3,*) cost fn from PPASURF surface identification (*100) (4,*) scattering index (*100)
				(6,*) spare
				(7,*) spare
iasi1d_emiss	I4	4	13*30	13 emissivity parameters
		I	ASI DATA	
iasi1d_GQisFlagQual	I4	4	30	1=some anomaly
iasi1d_GQisQualIndex	I4	4	1	NEDT estimated/expected
iasi1d_GQisQualIndexL oc	I4	4	1	IIS/AVHRR co-registration uncertainty
iasi1d_GQisQualIndexR ad	I4	4	1	NEDT estimated/expected radiometric
iasi1d_GQisQualIndexS pect	I4	4	1	NEDT estimated/expected spectral
iasi1d_GQisSysTecSond Qual	I4	4	1	
iasi1d_scalrad	I4	4	[300]*30	Scaled radiance (default 300 channels)
iasi1d_scores	I4	4	[300]*30	PC scores (default 300 scores)
iasi1d_logfit	I4	4	3*30	Reconstruction Scores for 3 bands
iasi1d_FOV	I4	4	30	30 values in range 1 to 120
		AV	HRR DAT	
iasi1d_avhcombination	I4	4	1	1 bit for each channel
iasi1d_avhrrmean	I4	4	6*7*30	Scaled mean radiance for 6 channels, 7 classes
iasi1d_avhrrsdev	I4	4	6*7*30	Scaled Std Dev for 6 channels, 7 classes
iasi1d_avhmeanscalefact	I2	2	6*7*30	
or				

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iasi1d_avhsdevscalefacto	I2	2	6*7*30			
r						
iasi1d_avhrrfrac	I4	4	7*30	10^6 x Fraction in each class		
iasi1d_avhrrCGy	I4	4	7*30	10 ⁶ x Y angular position of centre of gravity		
				(deg)		
iasi1d_avhrrCGz	I4	4	7*30	10^6 x Z angular position of centre of gravity		
				(deg)		
CLOUD FLAG (user defined)						
iasi1d_cloudflag	I4	4	10*30			

29. FORMAT OF THE CRIS.L1D FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length

Header length = record length

array_size_cris1d = (11 + cris_1dnfor*(53 + cris_1dnchanatms + cris_1dnchan +

& cris_1dnpc + 2*cris_1dnband + 2*cris_1dnchanviirs)

& + 2*cris_1dnchanatms) *4 bytes (default 12835*4 bytes)

where

cris_1dnfor = 30 Number of FORs present in 1d cris_1dnchanatms = 22 Number of ATMS channels

cris_1dnchan = 300 Number of channel slots present in 1d cris_1dnpc = 1 Number of Principal Components present

cris_1dnband = 3 Number of bands

cris_1dnchanviirs = 22 Number of VIIRS channels in format

cris_1dnchanatms = 22 Number of ATMS channels

array_size_cris1dspare =

& array_size_cris1d - 49 - cris_1dnchan - 7*cris_1dnchanatms

& -4*cris 1dnband - 2*cris 1dnchanviirs)

Type

C = character

I2 = integer*2

I4 = integer*4

Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	

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GENERAL INFORMATION						
cris1d_h_site	С	3	1	1D dataset creation site ID		
cris1d_h_cfill1	C	1	1	filler		
cris1d_h_1bsite	C	3	1	creation site for original 1B data		
cris1d_h_cfill2	C	1	1	filler		
cris1d_h_versnb	I4	4	1	level 1d format version number		
cris1d_h_versyr	I4	4	1	level 1d format version year		
•	I4 I4	4 4	-			
cris1d_h_versdy	I4 I4	4	1 1	level 1d format version day of year count of header records in this data set		
cris1d_h_hdrent				satellite id in series (1 for NPP)		
cris1d_h_satid	I4 I4	4 4	1	,		
cris1d_h_grid	14	4	1	code for instrument grid (5=HIRS; 6=MSU; 10=AMSU-A; 11=AMSU-B; 12=IASI; 13=ATMS; 14=CrIS)		
cris1d_h_satht	I4	4	1	nominal satellite altitude, km*10		
cris1d_h_period	I4	4	1	nominal orbit period (seconds)		
cris1d_h_startorbit	I4	4	1	orbit number (at start of file)		
cris1d_h_startdatayr	I4	4	1	start of data set year		
cris1d_h_startdatady	I4	4	1	start of data set day of the year		
cris1d_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)		
cris1d_h_endorbit	I4	4	1	orbit number (at end of file)		
cris1d_h_enddatayr	I4	4	1	end of data set year		
cris1d_h_enddatady	I4	4	1	end of data set day of the year		
cris1d_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)		
cris1d_h_scnlin	I4	4	1	count of scan lines in this data set		
cris1d_h_misscnlin	I4	4	1	count of missing scan lines		
cris1d_h_atovppvn	I4	4	1	ATOVPP version number (test vns = 9000+)		
cris1d_h_instruments	I4	4	1	instruments present (bit0=HIRS, bit1=MSU, bit3=AMSU-A, bit4=AMSU-B, bit5=AVHRR, bit 6=IASI, bit7=ATMS, bit8=CrIS)		
cris1d_h_wmosatid	I4	4	1	WMO satellite id (224 for NPP)		
cris1d_h_spare1	I4	4	1	spare		
cris1d_h_centre	I4	4	1	WMO id of reception centre		
cris1d_h_subcentre	I4	4	1	WMO id of reception subcentre		
CrIS variables						
cris1d_h_recwords	I4	4	1	Size of record in integer*4 words		
cris1d_h_nfov	I4	4	1	Number of FOVs		
cris1d_h_nfor	I4	4	1	Number of FORs		
cris1d_h_nband	I4	4	1	Number of bands		
cris1d_h_startw	I4	4	cris_1dnba nd	First wavenumber *1E2		
cris1d_h_endw	I4	4	cris_1dnba nd	Last wavenumber *1E2		
cris1d_h_startchan	I4	4	cris_1dnba nd	First channel in band		
cris1d_h_endchan	I4	4	cris_1dnba nd	Last channel in band		

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cris1d_h_eigvn	I4	4	1	Version number of eigenvectors
cris1d_h_npc	I4	4	1	Number of PCs in format
-	I4 I4	4	1	Number of PCs used
cris1d_h_npcused	I4 I4	4		Version number of channel selection
cris1d_h_chanvn			1	
cris1d_h_nchan	I4	4	1	Number of channels in format
cris1d_h_nchanused	I4	4	1	Number of channels used
cris1d_h_channels	I4	4	_	List of cris channels range 1 to 8461
			nd	
ATMS variables		Т.	Г	
cris1d_h_atmsbeamversi	I4	4	1	User defined (see atms_beamwidth.dat)
on				
cris1d_h_atmsbeamwidt	I4	4	cris_1dnch	FFT manipulation: deg*1E3
h			anatms	
cris1d_h_atmscutoff	I4	4	cris_1dnch	FFT manipulation: fraction*1E3
			anatms	
cris1d_h_atmsnxaverage	I4	4	cris_1dnch	Simple averaging:
			anatms	
cris1d_h_atmsnyaverage	I4	4	cris_1dnch	Simple averaging:
			anatms	
ATMS temperature-radian	ice conv	ersion coefficies	nts (Planck f	function)
cris1d_h_atmsPlanck	I4	4	3* Simple	$(1,*) = 10^6 x$ (central wavenumber)
				$(2,*) = 10^6 x \text{ (constant 1)}$
				$(3,*) = 10^6 x \text{ (constant 2)}$
Pre-processing information	n	l	I	
cris1d_h_dT	I4	4	1	size of data batches processed within ATOVPP
cris1d_h_mapBTmode	I4	4	1	mapping method used for BTs (1=nearest
				neighbour, 2=bilinear interpolation)
cris1d_h_Acorrvn	I4	4	1	vn no ATMS limb/emiss correction (=0 if data
		·	_	not corrected)
cris1d_h_Apcpvn	I4	4	1	vn no ATMS precip/scatter detection (=0 if not
onsid_n_ipop		·	_	done)
cris1d_h_Aantenna	I4	4	1	vn no, ATMS antenna corrections
cris1d_h_Ascat	I4	4	1	threshold value for ATMS scattering index
cris1d_h_ACrosby	I4	4	1	threshold value for ATMS logistic precip
cris1d_h_cloudtests	I4	4	1	Cloud tests used (0 if none)
cris1d_h_recperscan	I4	4	1	Records per scan: 1 to 9
cris1d h fovmode	I4 I4	4	1	0 = full resolution
CHS1u_H_IOVIHOUE	14	+	1	Others TBD
VIIDC				Ouicis IDD
VIIRS	14	Λ	1	number of VIIDS changels in format
cris1d_h_nviirschan	I4	4	1	number of VIIRS channels in format
cris1d_h_nviirschanused	I4	4	1	number of channels used
cris1d_h_viirschans(cris	I4	4	cris_1dnch	Channel numbers
_1dnchanviirs)			anviirs	
cris1d_h_viirsbands	I4	4	cris_1dnch	Band numbers
			anviirs	5=M, 6=I, 7-DN
cris1d_h_spare2	I4	4	array_size	spare
			_cris1dspa	

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One Data Record for one CRIS scan line

Name in AAPP code	Type	Word Size in byte	Number of words	Meaning
General information	-	•		
cris1d_scnlin	I4	4	1	scan line number
cris1d_scnlinyr	I4	4	1	scan line year
cris1d_scnlindy	I4	4	1	scan line day of year
cris1d_scnlintime	I4	4	cris_1dnfor	scan line UTC time of day (ms)
cris1d_latlon	I4	4	2*cris_1dnf	lat/lon in degrees
			or	first : 10 ⁴ x (latitude)
				second: 10 ⁴ x (longitude)
cris1d_angles	I4	4	4*cris_1dnf	scan angles
			or	first: 10^2 x (local zenith angle)
				second: 10 ² x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
				fourth: 10 ² x (solar azimuth angle)
cris1d_satxyz	I4	4	3	x,y,z of satellite at mid-scan
cris1d_ascdesc	I4	4	1	ascending / descending orbit qualifier
cris1d_orbit	I4	4	1	orbit number
cris1d_scalti	I4	4	1	satellite altitude
cris1d_surfht	I4	4	cris_1dnfor	surface height
cris1d_landfrac	I4	4	cris_1dnfor	land fraction
cris1d_landsea	I4	4	cris_1dnfor	land/sea qualifier
cris1d_cloudcover	I4	4	cris_1dnfor	cloud cover (percent)
cris1d_cloudtopht	I4	4	cris_1dnfor	
cris1d_surface	I4	4	3*	Surfelev output
			cris_1dnfor	first : surface height (metres)
				second: surface type (0=sea, 1=mixed,
				2=land)
				third : land fraction (percent)
ATMS mapped to CrIS				
cris1d_nedtcoldatms	I4	4	cris_1dncha	
			natms	
cris1d_nedtwarmatms	I4	4	cris_1dncha	
			natms	
cris1d_btemps	I4	4	cris_1dncha	10^2 x scene brightness temperature (K) for
			natms*cris_	ATMS channels
			1dnfor	
cris1d_crisqual	I4	4	cris_1dnfor	Quality control word for each field of view:
				(all bits off implies acceptable data)
				! bit 27-4: bit n set to 1 if brightness
				156

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				· · · · · · · · · · · · · · · · · · ·
				temperature in
				ATMS channel n-3 is physically unreasonable
				or has not been calculated due to calibration
				problems.
				bit 3-1: bit n set to 1 if data for CrIS detector n
				are bad
				bit 0: bad or missing data (in any or all
				channels)
aria1d manna	Τ.4	1	8*	,
cris1d_prepro	I4	4	_	values from pre-processing
			cris_1dnfor	(1,*): pre-processing quality control word
				with flags(all bits off implies acceptable data)
				bit 31: set if ATMS surface types not all the
				same
				bit 30-28: spare
				bit 27: flag for cloud cost set for any mapped
				ATMS
				bit 26: scattering flag set for any mapped
				ATMS(only set over the sea)
				bit 25: logistic precipitation probability test
				calculated from ATMS data mapped to CrIS
				grid
				bit 24: Grody light rainfall test calculated on
				CrIS grid
				bit 23: spare
				bit 22: mismatch between surface type from
				topography dataset and from pre-processing
				(any ATMS)
				bit 21: fewer ATMS mapping co-locations than
				expected
				* -
				bit 20-4: spare <zero fill=""></zero>
				bit 3: spare
				bit 2: flag for cloud cost (recalculated on CrIS
				grid)
				bit 1: flag for scattering index (recalculated on
				CrIS grid)
				bit 0: set if ATMS data missing
				, and the second
				(2,*) estimated surface type from the pre-
				processing:
				1 = Bare young ice (i.e. new ice, no snow)
				2 = Dry land (i.e. dry with or without
				significant vegetation)
				3 = Dry snow (i.e. snow with water less than
				2%, over land)
				4 = Multi-year ice (i.e. old ice with snow
				[assumed dry] cover)
				5 = Sea (i.e. open water, no islands, ice-free,
				WS=0 to 14m/s)

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				6 = Wet forest (i.e. established forest with wet canopy) 7 = Wet land (i.e. non-forested land with a wet surface) 8 = Wet snow (i.e. snow with water content > 2%, over land or ice) 9 = Desert (3,*) cost fn from PPASURF surface identification (*100) (4,*) scattering index (*100) (5,*) cirrus index (*100) (6,*) logistic precipitation probability (*100) (7,*) NWC-SAF (Bennartz) scattering index (K) (8,*) NWC-SAF (Bennartz) precipitation probabilities
cris1d_emiss	I4	4	13* cris_1dnfor	13 emissivity parameters
CrIS data			ciis_iuiiioi	I
cris1d_radianceflgs	I4	4	cris_1dnfor	radiance flags Bit(1=MS) 1 Clear path 2 Partly cloudy path 3 Cloudy path 4 Apodized 5 Unapodized 6 Reconstructed 7 Cloud cleared 8-14 Reserved All 15 Missing value
cris1d_scanqualflgs	I4	4	1	scan quality flags Bit(1=MS) 1 Gap in Raw Data Record (RDR) data detected (i.e., missing scan(s) preceding the current scan) 2 Recorded time is not in sequence (i.e., the scan start time is out of sequence) 3 Lamda monitored calculation cannot be updated 4 The measured temperatures of any instrument components (e.g., beam-splitter, scan mirror, scan baffle, etc.) are outside the allowable ranges 5 At least one of the monitored instrument temperatures has drifted more than a specified tolerance value 6-12 Reserved All 13 Missing value

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cris1d_calqualflgs	I4	4	cris_1dnba	1 * *
				Come for all EOV/C 1 to 0 but the and date
			nd*cris_1d	Same for all FOVS 1 to 9, but thinned data
			nfor	may have
				different FOVs within a record
				Bit(1=MS of 9 bits)
				1Lunar intrusion on first deep space view
				2Lunar intrusion on second deep space view
				3-8 Reserved
				All 9 Missing value
cris1d_fovqualflgs	I4	4	cris_1dnba	FOV quality
			nd*cris_1d	Bit(1=MS of 19 bits)
			nfor	1Degraded SDR quality
			mor	2Invalid SDR quality
				3Invalid SDR geolocation information
				4Degraded radiometric calibration
				5Invalid radiometric calibration
				6Degraded spectral calibration
				7Invalid spectral calibration
				8Fringe count error detected and corrected
				9Day/night indicator
				10Invalid RDR data
				11Significant fringe count error detected
				12Bit trim failed
				13-18 Reserved
				All 19 Missing value
cris1d_geolocqual	I4	4	1	Geolocation quality
crista_geolocquar	17	7	1	Value
				0 Nominal
				1 Missing at most a small gap of altitude and
				Ephemeris data
				2 Missing more than a small gap of altitude
				and Ephemeris data, but no more than a
				granule boundary
				3 Missing more than a granule boundary of
				altitude and Ephemeris data
				4-14 Reserved
				15 Missing
cris1d_quality	I4	4	cris_1dnba	Value
one quality	11	•	nd,cris_1dn	
			for	1 Suspect
			101	<u> </u>
				2 Very suspect
	T.4		104 1 1	3 Unusable
cris1d_cloudflag	I4	4	10*cris_1d	CrIS cloud flag (user defined)
			nfor	
CrIS radiance and PC score			_	
cris1d_FOV	I4	4	cris_1dnfor	Č
				I
cris1d_scores	I4	4	cris_1dnpc *cris_1dnfo	PC scores

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			1	
			r	
cris1d_logfit	I4	4	3*cris_1dnf	Reconstruction Scores for 3 bands
			or)	
cris1d_radiance	I4	4	cris_1dnfor	Radiance
			*cris_1dnc	Wm-2sr-1cm *1E7
			han	
VIIRS				
cris1d_viirsradiance	I4	4	cris_1dncha	
			nviirs *	
			cris_1dnfor	
cris1d_viirsreflectance	I4	4	cris_1dncha	
			nviirs *	
			cris_1dnfor	

One Data Record for one ATMS scan line

Name in AAPP code	Type	Word Size	Number of	Meaning
		in byte	words	
General information				
atms1d_scnlin	I4	4	1	scan line number
atms1d_scnlinyr	I4	4	1	scan line year
atms1d_scnlindy			1	scan line day of year
atms1d_scnlintime			atms_1dnfo	UTC time of day in milliseconds
			V	
atms1d_orbit				
atms1d_granulequal				granule quality flags
atms1d_scanqual				scan line quality flags
atms1d_geolocqual				geolocation quality
atms1d_chanqual			atms_1dnch	quality flag for each channel
			an	
atms1d_latlon			2*atms_1d	
			nfov	first : 10 ⁴ x (latitude)
				second: 10^4 x (longitude)
atms1d_surface			2*atms_1d	height/type
			nfov	first : surface height (metres)
				second: surface type (0=sea, 1=mixed,
				2=land)
atms1d_landfrac			2*atms_1d	first : AMSU-A-like channels (percent)
			nfov	second: AMSU-B-like channels (percent)
atms1d_angles			4*atms_1d	scan angles
			nfov	first: 10^2 x (local zenith angle)
				second: 10^2 x (local azimuth angle)
				third: 10^2 x (solar zenith angle)
				fourth: 10^2 x (solar azimuth angle)

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atms1d_scalti		sat altitude above reference ellipsoid, km*10
Data		<u> </u>
atms1d_nedtcold	atms_1dnch an	Cold view NEDT K*100
atms1d_nedtwarm	atms_1dnch an	Warm view NEDT K*100
atms1d_btemps	atms_1dnch an*atms_1d nfov	10^2 x scene brightness temperature (K)
atms1d_atmsqual	atms_1dnfo	Quality control word for each field of view: (all bits off implies acceptable data) bit 27-4: bit n set to 1 if brightness temperature in ATMS channel n-3 is physically unreasonable or has not been calculated due to calibration problems. bit 3-1: reserved bit 0: bad or missing data (in any or all channels)
Pre-processing output		· · · · · · · · · · · · · · · · · · ·
atms1d_prepro	8*atms_1d nfov	(1,*): pre-processing quality control word, atmsqc(all bits off implies acceptable data) bit 31: set if ATMS BTs considered contaminated due e.g. to precip or surface type bit 30: spare bit 29: spare bit 28: spare bit 27: maximum probability scheme cloud flag bit 26: scattering test (only set over the sea) bit 25: Crosby logistic precipitation probability test bit 24: Grody light rainfall test bit 23: spare bit 22: mismatch between surface type from topography dataset and from pre-processing bit 21: spare <zero fill=""> bit 20: spare bit 19: scattering test (only set over the sea) - using ATMS 89GHz channel bit 18: spare bit 17: spare bit 15: spare bit 16: spare bit 17: spare bit 17: spare bit 18: spare spare bit 18: spare spare bit 18: spare spare bit 18: spare spar</zero>

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1 = Bare young ice (i.e. new ice, no snow)
2 = Dry land (i.e. dry with or without
significant vegetation)
3 = Dry snow (i.e. snow with water less than
2%, over land)
4 = Multi-year ice (i.e. old ice with snow
[assumed dry] cover)
5 = Sea (i.e. open water, no islands, ice-free,
WS=0 to 14m/s)
6 = Wet forest (i.e. established forest with wet
canopy)
7 = Wet land (i.e. non-forested land with a wet
surface)
8 = Wet snow (i.e. snow with water content >
2%, over land or ice)
9 = Desert
(3,*) cost fn from PPASURF surface
identification
(4,*) scattering index (89GHz)
(5,*) cirrus index (*100)
(6,*) logistic precipitation probability (*100)
(7,*) NWC-SAF (Bennartz) scattering index
(K)
(8,*) NWC-SAF (Bennartz) precipitation
probabilities
1 12

30. FORMAT OF THE ATMS.L1D FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Header and record length

Header length = record length

array_size_atms1d = 8 + 3*atms_1dnchan + atms_1dnfov*(20 + atms_1dnchan) *4 bytes (default 12104*4 bytes)

where

 $atms_1dnchan = 22$

 $atms_1dnfov = 96$

array_size_atms1dspare = array_size_atms1d - 37 - 8*atms_1dnchan

Type

C = character

I2 = integer*2

I4 = integer*4

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Header Record

Name in AAPP code	Type	Word Size	Number	Meaning
		in byte	of words	
	, ,		L INFORM	
atms1d_h_site	C	3	1	1D dataset creation site ID
atms1d_h_cfill1	C	1	1	filler
atms1d_h_1bsite	C	3	1	creation site for original 1B data
atms1d_h_cfill2	C	1	1	filler
atms1d_h_versnb	I4	4	1	level 1d format version number
atms1d_h_versyr	I4	4	1	level 1d format version year
atms1d_h_versdy	I4	4	1	level 1d format version day of year
atms1d_h_hdrcnt	I4	4	1	count of header records in this data set
atms1d_h_satid	I4	4	1	satellite id (e.g. 14 for NOAA-14)
atms1d_h_grid	I4	4	1	code for instrument grid
				(5=HIRS; 6=MSU; 10=AMSU-A; 11=ATMS)
atms1d_h_satht	I4	4	1	nominal satellite altitude, km*10
atms1d_h_period	I4	4	1	nominal orbit period (seconds)
atms1d_h_startorbit	I4	4	1	orbit number (at start of dataset)
atms1d_h_startdatayr	I4	4	1	start of data set year
atms1d_h_startdatady	I4	4	1	start of data set day of the year
atms1d_h_startdatatime	I4	4	1	start of data set UTC time of day (ms)
atms1d_h_endorbit	I4	4	1	orbit number (at end of dataset)
atms1d_h_enddatayr	I4	4	1	end of data set year
atms1d_h_enddatady	I4	4	1	end of data set day of the year
atms1d_h_enddatatime	I4	4	1	end of data set UTC time of day (ms)
atms1d_h_scnlin	I4	4	1	count of scan lines in this data set
atms1d_h_misscnlin	I4	4	1	count of missing scan lines
atms1d_h_atovppvn	I4	4	1	ATOVPP version number (test vns = 9000+)
atms1d_h_instruments	I4	4	1	instruments present (bit0=HIRS, bit1=MSU,
				bit3=AMSU-A, bit4=ATMS, bit5=AVHRR,
				bit6=IASI, bit7=ATMS, bit8=CrIS)
atms1d_h_Aantenna	I4	4	1	vn no, ATMS antenna corrections
atms1d_h_planck	I4	4	3*atms_1d	ATMS temperature-radiance conversion
			nchan	coefficients (Planck function)
				$(1,*) = 10^6 x$ (central wavenumber)
				$(2,*) = 10^6 x \text{ (constant 1)}$
				$(3,*) = 10^6 x \text{ (constant 2)}$
atms1d_h_bandwidth	I4	4	atms_1dnc	
			han	
atms1d_h_nchan	I4	4	1	
atms1d_h_nfov	I4	4	1	
atms1d_h_nchanused	I4	4	1	
atms1d_h_recwords	I4	4	1	Words in record

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			1					
atms1d_h_wmosatid	I4	4	1	WMO sat ID (224 for NPP)				
atms1d_h_centre	I4	4	1	WMO id of reception centre				
atms1d_h_subcentre	I4	4	1	WMO id of reception subcentre				
The following variables ch	The following variables characterise any image processing (see atms_beamwidth)							
atms1d_h_beamversion	I4	4	1	User defined (see atms_beamwidth.dat)				
atms1d_h_beamwidth	I4	4	atms_1dnc	FFT manipulation: deg*1E3				
			han					
atms1d_h_cutoff	I4	4	atms_1dnc	FFT manipulation: fraction*1E3				
			han					
atms1d_h_nxaverage	I4	4	atms_1dnc	simple averaging:				
			han					
atms1d_h_nyaverage	I4	4	atms_1dnc	simple averaging:				
			han					
Pre-processing information	n							
[user-defined:								
atms1d_h_dT	I4	4	1	size of data batches processed within ATOVPP				
				(seconds - see ATOVPP documentation)				
atms1d_h_Acorrvn	I4	4	1	vn no ATMS limb/emiss correction				
				(=0 if data not corrected)				
atms1d_h_Apcpvn	I4	4	1	vn no ATMS precip/scatter detection				
				(=0 if not done)				
atms1d_h_Ascat	I4	4	1	threshold value for ATMS scattering index				
atms1d_h_Acirr	I4	4	1	threshold value for cirrus index				
atms1d_h_ACrosby	I4	4	1	threshold value for ATMS logistic precip				
atms1d_h_spare2	I4	4	array_size	spare				
_			_atms1dsp					
			are					

31. FORMAT OF THE TBUS_NOAAXX.INDEX FILE

Summary information taken in *tbus.5* (directory *AAPP/man/man5*) (See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

Named tbus_noaaxx.index where xx is the number of the satellite (Historical index file one for each satellite)

Format:

First line: character # in the first column,

a blank in the second column,

the satellite name in columns 3 to 8 (format a6).

Second line: character % in the first column,

the name of the fields present in the following lines

Following lines: contains several fields:

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epoch_time f orbit fwerr bkerr time_string argos format f15.9,1x,i1,1x,i5,2f7.2,1x,a22,1x,a

with:

epoch_time : TBUS Part IV epoch time in CNES julian days (day 0=01/01/50 0h)

f : quality flag (0 = OK)

orbit : orbit number

fwer : forward extrapolation error (km/day) bwer : backward extrapolation error (km/day)

time_string : character string corresponding to epoch_time

tbus : TBUS bulletin filename relative to DIR_DATA_TBUS

Notes: For a good use of the navigation software the tbus index files must be sorted after each new tbus ingest. Example of the sort command:

sort -u -o TBUS INDEX.sort +0b -3b TBUS INDEX

32. FORMAT OF THE TLE_SSSXX.INDEX FILE

Resume information taken in *tle.5* (directory *AAPP/man/man5*) (See also general information in the paragraph 3.3.2 of the *AAPP software description document*)

Named tle_sssxx.index where xx is the number of the sss satellite (Historical index file one for each satellite)

Format:

First line: character # in first column

a blank in second column

the satellite name in columns 3 to 8

(format a6).

Second line: character % in first column

the name of the fields present in the following lines

Following lines: contains several fields:

epoch_time f orbit fwerr bkerr time_string tle format f15.9,1x,i1,1x,i5,2f7.2,1x,a22,1x,a

with:

epoch_time epoch time in CNES julian days (day 0=01/01/50 0h)

f quality flag (0 = OK)

orbit orbit number

fwer forward extrapolation error (km/day)
bwer backward extrapolation error (km/day)
time_string character string corresponding to epoch_time

tle TLE bulletin filename relative

Notes: For a good use of the navigation software the tle index files must be sorted after each new tle ingest. Example of the sort command:

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sort -u -o TLE_INDEX.sort +0b -3b TLE_INDEX

33. FORMAT OF THE SPM_SSSXX.INDEX FILE

Named spm_sssxx.index where xx is the number of the sss satellite (Historical index file one for each satellite)

Format:

First line: character # in first column

a blank in second column

the satellite name in columns 3 to 8

(format a6).

Second line: character % in first column

the name of the fields present in the following lines

Following lines: contains several fields:

epoch_time order f orbit fwerr bkerr time_string spm format f15.9,1x,i1,1x,i1,1x,i5,2f7.2,1x,a22,1x,a

with:

epoch_time epoch time in CNES julian days (day 0=01/01/50 0h)

order order number of bulletin in file [1,2,3]

f quality flag (0 = OK)

orbit orbit number

fwer forward extrapolation error (km/day) bwer backward extrapolation error (km/day)

time_string character string corresponding to epoch_time

spm SPM bulletin filename relative

Notes: For a good use of the navigation software the spm index files must be sorted after each new spm ingest. Example of the sort command:

sort -u -o SPM_INDEX.sort +0b -3b SPM_INDEX

34. FORMAT OF THE CLKERR_NOAAXX.TXT FILE

Resume information taken in *clockerror.5* (directory *AAPP/man/man5*) (See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

A clock error file is an historical file relative to one satellite which contains the TBUS part IV clock information: clock error, clock error rate, clock error after last correction and next clock correction.

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Only the parameters which have been considered as valid by the command thusing are stored in the file.

Each clock error file is named clerr_noaaxx.txt where xx is the number of the satellite.

First line: character # in the first column,

a blank in the second column,

the satellite name in columns 3 to 8 (format a6).

Several comment lines: character % in the first column,

a blank or several blanks

comments

Following lines: contains several fields:

type date value date_string format a4,i6,f8.3,2x,a8

with:

type : one of the following: bias = bias of clock

cerr for clock error

last for last clock correction next for next clock correction

rate for error rate

null for clock error assigned to 0

date : CNES julian day for the measure (day 0 = 01/01/50 Oh)

value: measured value

date string: character string corresponding to date

Notes: For a good use of the files they must be sorted after each new thus ingest. Example of the sort command:

sort -u -o CLOCK_ERROR.sort +0b -2b CLOCK_ERROR

The "null" parameter can be introduced manually in the clock error file. All orbits following that date will have a null clock error and ierr =0.

null must be used when the tbus values are dubious and removed when tbus values are considered valid.

All the thus values are stored during the dubious period (but not used)

For correct use off line, the erroneous values must be eliminated when removing the null parameter.

The "bias" parameter can be introduced manually in the clock error file when the TBUS values present a systematic error (which has been true for Noaa16 in 2001). The bias is applied starting at a given date. To suppress it, introduce a 0 bias at a new date. For a correct use off-line do not remove the bias lines.

35. FORMAT OF THE SATPOS_NOAAXX_YYMMDD.TXT FILE

Summary information taken in *satpos*.5 (directory *AAPP/man/man5*) (See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

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The satpos file contains the satellite position and velocity vectors on a limited duration (typically one day) with a time step of about 2 mn. The file is relative to one satellite and one station.

The satpos file "normalized" name is: satpos_ssssxx_yyyymmdd.txt where:

ssss is the platform name and xx the satellite number yyyymmdd year month day of the first position velocity vector in the file

Some dummy lines can exist at the beginning of the file.

A line with the string #SATPOS indicates the actual beginning of the file.

Real first line: #SATPOS

21 header lines:

line	format	meaning
1 st header line	('satellite ',a6)	NOAA name of the satellite
2 nd header line	('ground station ',a)	Ground station name
3 rd header line	('start date ',a22)	Start date
4 th header line	('number of days ',f6.2)	Number of days (real value)
5 th header line	('time step (s) ',f6.2)	Time step (sec)
6 th header line	('orbital bulletin ',a)	Type of orbital bulletin (TBUS)
7 th header line	('search criteria ',i2)	Bulletin search criteria (0 is normal mode)
8 th header line	('orbital elem. file ',a)	Name of the TBUS file used for the
		calculations
9 th header line	('tbus epoch time ',a22)	Epoch time (dd/mm/yy hh:mm:ss.sss)
10 th header line	('semi-major axis ',f10.4)	Semi-major axis (km)
11 th header line	('eccentricity ',f10.9)	Eccentricity
12 th header line	('inclination ',f10.5)	Inclination (deg)
13 th header line	('perigee argument ',f10.5)	Perigee argument (deg)
14 th header line	('right ascension ',f10.5)	Right ascension (deg)
15 th header line	('mean anomaly ',f10.5)	Mean anomaly (deg)
16 th header line	('x,y,z ',3(f10.4,1x))	x,y,z (km)
17 th header line	('vx,vy,vz ',3(f10.7,1x))	vx,vy,vz (km/sec)
18 th header line	('station latitude ',f10.4)	Ground station geographical latitude (deg)
19 th header line	('station longitude ',f10.4)	Ground station geographical
		longitude(deg)
20 th header line	('station altitude ',f10.4)	Ground station altitude (km)
21 th header line	('stat. minimum site ',f10.4)	Ground station minimum site (deg)

Field description line:

one line describing the following fields

Several data lines:

format of one data line = (i8,3f10.3,3f10.6,i6,2i4)

Format	Meaning		
I8	step number		

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f10.3	position vector in Greenwich ref. frame (km): x coordinate
f10.3	position vector in Greenwich ref. frame (km): y coordinate
f10.3	position vector in Greenwich ref. frame (km): z coordinate
f10.6	velocity vector in Greenwich ref. frame (km/sec) vx coordinate
f10.6	velocity vector in Greenwich ref. frame (km/sec) vy coordinate
f10.6	velocity vector in Greenwich ref. frame (km/sec) vz coordinate
i6	orbit number
i4	satellite in daylight or nighttime conditions (-1=non calculated, 0=daylight, 1=nighttime, 2=penombra)
i4	Satellite seen from the station (0=yes, 1=no)

36. FORMAT OF THE MONAVHR.TXT FILE

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

One line added at each AAPP run. format of one data line =

(a5,1x,a1,f11.4,3i5,7f11.7,2f9.2,4f6.1,4f5.1,4f5.1,4f5.1,3f6.1,3f5.1,3

6f6.1,6f5.1,6f5.1,6f5.1)

Type

C : character I4 : integer 4 R : real

DP: double precision

Name in AAPP code	Type	Format	Meaning	
orbnum	C*5	a5	Orbit number.	
		1x	Blank	
typorb	C*1	a1	Orbit type: ascending 'a' descending 'd'	
ij	DP	f11.4	Julian start instant for output	
stat_cnt	I4	i5	Total number of values to compute the	
			mean of the thermistor counts	
stat_ch3a	I4	i5	Total number of sub-block with 3a	
			channel	
stat_ch3b	I4	i5	Total number of sub-block with 3b	
			channel	
k1mean(3)	R	3f11.7	Mean of 1 st coefficients of each sub-	
			block	
k2mean(3)	R	3f11.7	Mean of 2 nd coefficients of each sub-	

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			block
k3mean(3)	R	1f11.7,2f9.2	Mean of 3 rd coefficients of each sub- block
cthmean(4)	R	4f6.1	Mean thermistors counts for each thermistor.
pcthinf(4)	R	4f5.1	Percent of thermistor count values below a min value.
pcthsup(4)	R	4f5.1	Percent of thermistor values above a max value.
pcthrej(4)	R	4f5.1	Percent of thermistor count values rejected
bbmean(3)	R	3f6.1	mean target view counts for the 3 IR channels
bbsig(3)	R	3f5.1	Mean of standard deviation of target view counts for the 3 IR channel.
pbbinf(3)	R	3f5.1	Percent of target view counts values below a min value
pbbsup(3)	R	3f5.1	Percent of target view counts values above a max value
pbbrej(3)	R	3f5.1	Percent of target view counts values rejected.
spmean(6)	R	6f6.1	Mean of standard deviation of space view counts for the 3 IR channel.
spsig(6)	R	6f5.1	Mean of standard deviation of space view counts for the 3 IR channel.
pspinf(6)	R	6f5.1	Percent of space view counts values below a min value
pspsup(6)	R	6f5.1	Percent of space view counts values above a max value
psprej(6)	R	6f5.1	Percent of space view counts values rejected.

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37. FORMAT OF THE MONHIRS.TXT FILE

(See also general information in the paragraph named "interfaces" of the AAPP software description document)

One line added at each AAPP run.

format of one data line =

(a5,1x,a1,f11.4,i2,20f5.2,20f14.10,20f14.6,20f5.2,20f13.10,20f13.10,4f9.2,4f9.6,4f5.2,19f9.2,19f6.3,19f5.2,19f5.

Type

C : character I4 : integer 4 R : real

DP: double precision

Name in AAPP code	Type	Format	Meaning
orbnum	C*5	a5	Orbit number.
		1x	Blank
typorb	C*1	a1	Orbit type: ascending 'a' descending 'd' orbit.
ij		f11.4	Julian start instant.
calib	I4	i2	Number of calibration cycles in the orbit (maximum 4 in AAPP).
calibcoefmn(20,3)	DP	20f5.2,20f14.10,20f14.6	Array of the means of calibration coefficients (intercept, slope and third coef) for all the orbit
calibcoefstd(20,3)	DP	20f5.2,20f13.10,20f13.10	Array of the standard deviations of calibration coefficients (intercept, slope and third coef) for all the orbit.
prtmnstat(4)	DP	4f9.2	Array of the means of PRT readings for each PRT.
prtstdstat(4)	DP	4f9.6	Array of the standard deviations of PRT readings for each PRT.
prtejecstat(4)	DP	4f5.2	100*percentage of ejected PRT readings for each PRT.
spmnstat(19)	DP	19f9.2	Array of the means of filtered radiant signal output counts for all the space lines of the orbit and for each IR channel.
spstdstat(19)	DP	19f6.3	Array of the standard deviations of filtered radiant signal output counts for all the space lines of the orbit and for each IR channel.
spmisstat(19)	R	19f5.2	100*percentage of missing radiant signal output counts for all the space lines of the orbit and for each IR channel.
spinfstat(19)	R	19f5.2	100*percentage of radiant signal output counts inferior to the low limit for all the

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			space lines of the orbit and for each IR channel.
spsupstat(19)	R	19f5.2	100*percentage of radiant signal output counts superior to the high limit for all the space lines of the orbit and for each IR channel.
spejecstat(19)	R	19f5.2	100*percentage of radiant signal output counts exceeding mean+/-coef*standard deviation for all the space lines of the orbit and for each IR channel.
iwtmnstat(19)	DP	19f9.2	Array of the means of filtered radiant signal output counts for all the internal warm target(IWT) lines of the orbit and for each IR channel.
iwtstdstat(19)	DP	19f6.3	Array of the standard deviations of filtered radiant signal output counts for all the internal warm target(IWT) lines of the orbit and for each IR channel.
iwtmisstat(19)	R	19f5.2	100*percentage of missing radiant signal output counts for all the internal warm target(IWT) lines of the orbit and for each IR channel.
iwtinfstat(19)	R	19f5.2	100*percentage of radiant signal output counts inferior to the low limit for all the internal warm target(IWT) lines of the orbit and for each IR channel.
iwtsupstat(19)	R	19f5.2	100*percentage of radiant signal output counts superior to the high limit for all the internal warm target(IWT) lines of the orbit and for each IR channel.
iwtejecstat(19)	R	19f5.2	100*percentage of radiant signal output counts exceeding mean+/-coef*standard deviation for all the internal warm target(IWT) lines of the orbit and for each IR channel.

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38. FORMAT OF THE HIRS_HISTORIC.TXT FILE

ASCII file

Contains data about calibration cycles.

One file for several calibration cycles, for several orbits.

The maximum of calibration cycles that is possible to write in the file is defined by the parameter *hrs_mxcalibhisto* in the include file *hcalibhisto_algoV4.h*. (hrs_mxcalibhisto=10000 in the initial version of AAPP 5.0).

A script was developed to manage the hirs_historic.txt file: hirs_historic_file_manage.ksh The purpose of the script is :

When the \${HIST} file has a number of lines greater than \${HIST_SIZE_HIGH, it is copied to \${HIST}.0 file.

If \${HIST}.0 file alreday exists, it is moved to \${HIST}.1.

\${HIST}.\${HIST_NMAX} can be stored.

The final part of \${HIST} is remained in \${HIST}. The final part is defined from the first line with the chain 'HIRS CALIB INFO' after having remained the last \${HIST_SIZE_LOW} lines of \${HIST} to the last line of \${HIST}.

At each orbit run, if the calibration cycle is qualified for at least one channel, then the 70 following lines are written in the hirs_historic.txt file:

Type

C : character L : logical I2 : integer 2 I4 : integer 4 R : real

DP: double precision

Line Nb	Name in AAPP code	Type	Format	Meaning
110			(77777 6 6 1 7 7 7 7 7 7 7 7 7 7 7 7 7 7	
1			'HIRS CALIB INFO'	
2			'!'	
3			'! satellite, date, orbit number'	
4	scname	C*6	Free	NOAA name (ex noaa16)
5	hscnlinyr	I2	'(1x,2i4,i10)'	Year, day of year, time day
	hscnlindy	I2		(milliseconds) of the space view
	hscnlintime	I4		line
6	orbnum	I4	Free	Number of the orbit
7			'! ascending descending (0/1)'	
8	ascdsc	I4	Free	0 if ascending
				1 if descending
9			'! solar zenith angle'	
10	(hang(82,spl) +	I2	Free	Value of the solar zenith angle

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	hang(85,spl))/2/100.			at the nadir
11			'! latitude at nadir'	
12	(hpos(55,spl) + hpos(57,spl))/2./10000.	I4	Free	Value of latitude at the nadir
13			.i.	
14			'! calib cycle number, total cycles'	
15	k calib	I4 I4	Free	Value of the number of the calib cycle Value of the total number of the calib cycle
16			'! total path scan lines '	
17	hscnlin	I2	Free	Total number of the scan lines in the orbit
18			'! qualified channels'	
19	qualified	L	'(2012)'	For each of the 20 HIRS channels: T if the calib cycle is qualified F if the calib cycle is not qualified
20			'! space line number '	
21	splintab	I4	Free	Number of the space view line
22			'! warm target line number'	
23	iwtlintab	I4	Free	Number of the IWT view line
24			'! moon contamination flag'	
25	mooncontaflag	L	'(12)'	Value of the moon contamination flag; Always F in this AAPP version 5.0
26			'! telescope temps (prim, sec, ter)'	
27	ptt stt ttt	R R R	Free	Values of the 3 temperatures
28			'! filter wheel temp'	
29	fwt	R	Free	Value of the temperature. =0. in this version of AAPP 5.0
30			'! base plate temp'	
31	bbt	R	Free	Value of the temperature. =0. in this version of AAPP 5.0
32			.i.	
33			'! calibration intercept '	
34	calibcoef0	DP	'(10e15.6)'	BB or raw calibration intercept at this calib cycle For channels 1 to 10
35	calibcoef0	DP	'(10e15.6)'	BB or raw calibration intercept at this calib cycle For channels 11 to 20

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36			'! calibration slope '	
37	calibcoef0	DP	'(10e15.6)'	BB or raw calibration slope at this calib cycle For channels 1 to 10
38	calibcoef0	DP	'(10e15.6)'	BB or raw calibration slope at this calib cycle For channels 11 to 20
39			'! calibration 2snd order '	
40	calibcoef0	DP	'(10e15.6)'	Calibration 2 nd order coefficient at this calib cycle For channels 1 to 10 =0. in this version of AAPP 5.0
41	calibcoef0	DP	'(10e15.6)'	Calibration 2 nd order coefficient at this calib cycle For channels 11 to 20 =0. in this version of AAPP 5.0
42			'!'	
43			'! space target '	
44			'! mean, stdev, good, missing, lower than limit, higher than limit, rejected'	
45	spentmn	DP	'(19f7.1)'	For the space view line For each of the 19 IR HIRS channels, - Mean of the output counts
46	spentstd	DP	'(19f7.2)'	For the space view line For each of the 19 IR HIRS channels, - Standard deviation of the output counts
47	spgoodent	I4	'(19i7)'	For the space view line For each of the 19 IR HIRS channels, - Total number of good output counts used to compute the mean (max value 48)
47	spmisscnt	I4	'(19i7)'	For the space view line For each of the 19 IR HIRS channels, - Total number of missing output counts.
48	spinfcnt	14	'(19i7)'	For the space view line For each of the 19 IR HIRS channels, - Total number of lower output counts than limit
49	spsupent	I4	'(19i7)'	For the space view line

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	1	Т	T	<u> </u>
				For each of the 19 IR HIRS
				channels,
				- Total number of higher output
				counts than limit
50	spejeccnt	I4	'(19i7)'	For the space view line
	1 3			For each of the 19 IR HIRS
				channels,
				- Total number of rejected
				output counts
51			'!'	output counts
52			'! warm target '	
53			'! mean, stdev, good, missing	
33			_	
			lower than limit, higher than	
		DD	limit, rejected'	E 4 1777 ' 1'
54	iwtcntmn	DP	'(19f7.1)'	For the IWT view line
1				For each of the 19 IR HIRS
				channels,
				- Mean of the output counts
55	iwtentstd	DP	'(19f7.2)'	For the IWT view line
				For each of the 19 IR HIRS
				channels,
				- Standard deviation of the
				output counts
56	iwtgoodent	I4	'(19i7)'	For the IWT view line
				For each of the 19 IR HIRS
				channels,
				- Total number of good output
				counts used to compute the
				mean
				(max value 48)
57	iwtmisscnt	I4	'(19i7)'	For the IWT view line
31	1 W UIII SSCIIL	14	(1917)	
				For each of the 19 IR HIRS
				channels,
				- Total number of missing
			1/401=	output counts.
58	iwtinfcnt	I4	'(19i7)'	For the IWT view line
				For each of the 19 IR HIRS
				channels,
				- Total number of lower output
				counts than limit
59	iwtsupent	I4	'(19i7)'	For the IWT view line
	_			For each of the 19 IR HIRS
				channels,
				- Total number of higher output
				counts than limit
60	iwtejeccnt	I4	'(19i7)'	For the IWT view line
	1 11 to jocolit	**	(1711)	For each of the 19 IR HIRS
				channels,
				challicis,

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				- Total number of rejected output counts
61			'!'	
62			'! PRTs '	
63			'! temp, mean, stdev, initial, good, rejected'	
64	tmp	DP	'(5f9.3)'	5 values of the temperatures got from the 5 PRTs.
65	prtmean	DP	'(5f9.2)'	Mean of the output count readings of the 5 PRTs
66	prtstd	DP	'(5f9.2)'	Standard deviation of the output count readings of the 5 PRTs
67	datanb	I4	'(5i9)'	Initial number of the output count readings used for each of the 5 PRTs
68	goodprt	I4	'(5i9)'	Total number of the good output count readings used to compute the means for each of the 5 PRTs
69	ejecprt	I4	'(5i9)'	Total number of the rejected output count readings for each of the 5 PRTs
70			'!'	

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39. FORMAT OF THE HIRS_B1ASLOPE.TXT FILE

ASCII file of 22 lines

Type

I4 : integer 4 R : real

Line Nb	Name in AAPP code	Type	Format	Meaning
1	уууу,	I4,	'(1x,i4,1x,i2.2,1x,i2.2)	Year, month, day of the reference date
	mm,	I4,	'	
	dd	I4		
2	hh,	I4,	'(1x,i2.2,1x,i2.2)'	Time of the reference date
	mn	I 4		
3	nbhour	I4	'(1x,i2.2)'	Number of hours to define the period of
				the data that will be used
1 line for each	ic,	I4,	Free	Number of the channel
of the 19 IR	avgslope(ic),	R,		Average slope of the channel ic
channels	stdevavgslope(ic),	R,		Standard deviation of the average slope
	b1(ic),	R,		B1 values for all conditions
	b1n(ic),	R,		B1 values for night conditions
	b1d(ic)	R		B1 values for day light conditions

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Version: 7.1

Date: 24 January 2012

40. FORMAT OF THE MONMSU.TXT FILE

(See also general information in the paragraph named "interfaces" of the AAPP software description document)

One line added at each AAPP run.

format of one data line =

(a5,1x,a1,f11.4,f10.4,f9.6,i3,3f7.2,f10.4,f9.6,i3,3f7.2,f7.2,f10.4,f9.6,i3,3f7.2,f10.4,f9.6,i3,3f7.2,f10.4,f9.6,i3,3f7.2,f10.4,f9.6,i3,2f7.2,f10.4,f9.6,i3,2f7.2,f10.4,f9.6,i3,2f7.2,f10.4,f9.6,i3,3f7.2,f10.4

Type

C : character I4 : integer 4 R : real

DP: double precision

Name in AAPP code	Type	Format	Meaning
orbnum	C*5	a5	Orbit number.
		1x	Blank
typorb	C*1	a1	Orbit type: ascending 'a' descending 'd'
			orbit.
ij	DP	f11.4	Julian start instant.
talomn	DP	f10.4	Mean of the low calibration reference
			points for electronic system A
talodev	DP	f9.6	Standard deviation of the low calibration
			reference points for electronic system A
talonb	I4	i3	Total number of values included good
			ones, bad ones (inf, sup, other ejected
			values)
gtalopct	R	f7.2	Percent of good values.
inftalopct	R	f7.2	Percent of values inferior to a min limit.
suptalopct	R	f7.2	Percent of values superior to a max. limit
tahimn	DP	f10.4	Mean of the high calibration reference
			points for electronic system A
tahidev	DP	f9.6	Standard deviation of the high calibration
			reference points for electronic system A
tahinb	I4	i3	Total number of values included good
			ones, bad ones (inf, sup, other ejected
			values)
gtahipct	R	f7.2	Percent of good values
inftahipct	R	f7.2	Percent of values inferior to a min limit.
suptahipct	R	f7.2	Percent of values superior to a max. limit
talohipct	R	f7.2	Percent of cases with the high calibration
			reference point inferior to the low one.

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tblomn	DP	f10.4	Mean of the low calibration reference
			points for electronic system B
tblodev	DP	f9.6	Standard deviation of the low calibration
			reference points for electronic system B
tblonb	I4	i3	Total number of values included good
			ones, bad ones (inf, sup, other ejected
			values)
gtblopct	R	f7.2	Percent of good values
inftblopct	R	f7.2	Percent of values inferior to a min limit
suptblopct	R	f7.2	Percent of values superior to a max limit
tbhimn	DP	f10.4	Mean of the high calibration reference
			points for electronic system B
tbhidev	DP	f9.6	Standard deviation of the high calibration
			reference points for electronic system B
tbhinb	I4	i3	Total number of values included good
tomino			ones, bad ones (inf, sup, other ejected
			values)
gtbhipct	R	f7.2	Percent of good values
inftbhipct	R	f7.2	Percent of values inferior to a min limit
suptbhipct	R	f7.2	Percent of values superior to a max limit
tblohipct	R	f7.2	Percent of cases with the high calibration
tolompet	K	17.2	
mut 1 amm	DP	f10.4	reference point inferior to the low one. Mean of PRT 1A count values
prt1amn			
prt1adev	DP	f9.6	Standard deviation of the PRT 1A count
41 1	T.4	:2	values.
prt1anb	I4	i3	Total number of PRT 1A values included
.1		67.0	good ones and bad ones (missing).
gprt1apct	R	f7.2	Percent of good PRT 1A values
misprt1apct	R	f7.2	Percent of missing PRT 1A values
prt1bmn	DP	f10.4	Mean of PRT 1B count values
prt1bdev	DP	f9.6	Standard deviation of the PRT 1B count
			values.
prt1bnb	I4	i3	Total number of PRT 1B values included
			good ones and bad ones (missing).
gprt1bpct	R	f7.2	Percent of good PRT 1B values
misprt1bpct	R	f7.2	Percent of missing PRT 1B values
prt2amn	DP	f10.4	Mean of PRT 2A count values
prt2adev	DP	f9.6	Standard deviation of the PRT 2A count
			values
prt2anb	I4	i3	Total number of PRT 2A values included
			good ones and bad ones (missing).
gprt2apct	R	f7.2	Percent of good PRT 2A values
misprt2apct	R	f7.2	Percent of missing PRT 2A values
prt2bmn	DP	f10.4	Mean of PRT 2B count values
prt2bdev	DP	f9.6	Standard deviation of the PRT 2B count
P1.2000			values
prt2bnb	I4	i3	Total number of PRT 2B values included
p1120110	14	1.0	Total number of TKT 2D values illeluded

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			good ones and bad ones (missing)
gprt2bpct	R	f7.2	Percent of good PRT 2B values
misprt2bpct	R	f7.2	Percent of missing PRT 2B values
spcntmn(1)	DP	f10.4	Mean of the space view counts for channel 1
spcntdev(1)	DP	f9.6	Standard deviation of the space view counts for the channel 1
spnb(1)	I4	i3	Total number of space view counts, good ones and bad ones, channel 1
gsppct(1)	R	f7.2	Percent of good space view counts, channel 1
missppct(1)	R	f7.2	Percent of missing space view counts, channel 1
ejectsppct(1)	R	f7.2	Percent of rejected space view counts, channel 1
spcntmn(2)	DP	f10.4	Mean of the space view counts for channel 2
spcntdev(2)	DP	f9.6	Standard deviation of the space view counts for the channel 2
spnb(2)	I4	i3	Total number of space view counts, good ones and bad ones, channel 2
gsppct(2)	R	f7.2	Percent of good space view counts, channel 2
missppct(2)	R	f7.2	Percent of missing space view counts, channel 2
ejectsppct(2)	R	f7.2	Percent of rejected space view counts, channel 2
spcntmn(3)	DP	f10.4	Mean of the space view counts for channel 3
spcntdev(3)	DP	f9.6	Standard deviation of the space view counts for the channel 3
spnb(3)	I4	i3	Total number of space view counts, good ones and bad ones, channel 3
gsppct(3)	R	f7.2	Percent of good space view counts, channel 3
missppct(3)	R	f7.2	Percent of missing space view counts, channel 3
ejectsppct(3)	R	f7.2	Percent of rejected space view counts, channel 3
spcntmn(4)	DP	f10.4	Mean of the space view counts for channel 4
spcntdev(4)	DP	f9.6	Standard deviation of the space view counts for the channel 4
spnb(4)	I4	i3	Total number of space view counts, good ones and bad ones, channel 4
gsppct(4)	R	f7.2	Percent of good space view counts, channel 4

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missppct(4)	R	f7.2	Percent of missing space view counts, channel 4
aia atampat(1)	D	£7.2	
ejectsppct(4)	R	f7.2	Percent of rejected space view counts, channel 4
tgcntmn(1)	DP	f10.4	Mean of the target view counts for
			channel 1
tgcntdev(1)	DP	f9.6	Standard deviation of the target view counts for the channel 1
tgnb(1)	I4	i3	Total number of target view counts, good ones and bad ones, channel 1
gtgpct(1)	R	f7.2	Percent of good target view counts,
			channel 1
mistgpct(1)	R	f7.2	Percent of missing target view counts, channel 1
aiaattanat(1)	R	f7.2	Percent of rejected target view counts,
ejecttgpct(1)	K	17.2	channel 1
tgcntmn(2)	DP	f10.4	Mean of the target view counts for
,			channel 2
tgcntdev(2)	DP	f9.6	Standard deviation of the target view
			counts for the channel 2
tgnb(2)	I4	i3	Total number of target view counts, good
			ones and bad ones, channel 2
gtgpct(2)	R	f7.2	Percent of good target view counts,
			channel 2
mistgpct(2)	R	f7.2	Percent of missing target view counts,
			channel 2
ejecttgpct(2)	R	f7.2	Percent of rejected target view counts,
			channel 2
tgcntmn(3)	DP	f10.4	Mean of the target view counts for
			channel 3
tgcntdev(3)	DP	f9.6	Standard deviation of the target view
			counts for the channel 3
tgnb(3)	I4	i3	Total number of target view counts, good
			ones and bad ones, channel 3
gtgpct(3)	R	f7.2	Percent of good target view counts,
		CT 0	channel 3
mistgpct(3)	R	f7.2	Percent of missing target view counts, channel 3
ejecttgpct(3)	R	f7.2	Percent of rejected target view counts,
ejectigpet(3)	I K	17.2	channel 3
tgcntmn(4)	DP	f10.4	Mean of the target view counts for
tgcittiiii(4)		110.4	channel 4
tgcntdev(4)	DP	f9.6	Standard deviation of the target view
igeniue v (4)		19.0	counts for the channel 4
tgnb(4)	I4	i3	Total number of target view counts, good
igiio(+)	14		ones and bad ones, channel 4
gtgpct(A)	D	f7 2	
gtgpct(4)	R	f7.2	Percent of good target view counts,

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			channel 4
mistgpct(4)	R	f7.2	Percent of missing target view counts,
			channel 4
ejecttgpct(4)	R	f7.2	Percent of rejected target view counts,
			channel 4

41. FORMAT OF THE MONAMSUA.TXT FILE

This file is empty for the version 7 of AAPP and previous versions

42. FORMAT OF THE MONAMSUB.TXT FILE

This file is empty for the version 7 of AAPP and previous versions

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43. FORECAST IN ASCII FORMAT OR IN GRIB FORMAT

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

For maia2.1

Two formats are available for the forecast file: ASCII and the standard meteorological format GRIB. To run AAPP with a GRIB forecast file, the ECMWF GRIB API library is needed, and the location of the GRIB library must be specified when AAPP is built (see Installation Guide).

If GRIB file is used:

- Update the variable FORECAST_FORMAT in ATOVS_ENV7 to the value "grib"

If ASCII file is used:

Update the variable FORECAST_FORMAT in ATOVS_ENV7 to the value "ascii"

For maia3

Only format GRIB is available for the forecast file:

The ECMWF GRIB API library is needed, and the location of the GRIB library must be specified when AAPP is built (see Installation Guide).

Check you have in ATOVS_ENV7: MAIA3_FORECAST_FORMAT='grib'

44. <u>FIELDS DESIRABLE IN THE FORECAST FILE IN GRIB FORMAT FOR</u> MAIA2.1 AND MAIA3

Necessary ones:

- The air 2m temperature (°K),
- The surface pressure (hPa)
- The altitude (m)
- The temperature (°K) and humidity (%) profiles on pressure levels

Better in addition

- The altitude (m)
- The precipitable water vapor (100*g /cm2)

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45. <u>FIELDS DESIRABLE AND FORMAT FOR A FORECAST FILE IN ASCII</u> <u>FOR MAIA2.1</u>

The files contain one header describing the grid for all the fields which are inside, and for all fields 3 subheader lines and the values in 20i4 or 16i5 format

Header of 7 li	<u>nes</u>		
-line 1	grid_type	ch*12	type of data (analysis or forecast)
-line 2	grid_name	ch*12	reference name of the grid
-line 3	grid_refdate	i4,i2,i2,2x,i2	reference date and time of the fields:
			year, month, day, hour
-line 4	nb_hours_for	ecast i3	number of hours for the forecast
			the date time of validity of the fields will be
			grid_refdate + nb_hours_forecast
			For analysis nb_hours_forecast is 0
-line 5	lat1, lon1	2f10.3	latitude and longitude of the first grid point
			latitudes north are positive
			longitudes east are positive
-line 6	step_lat, step_	lon 2f10.3	latitude longitude increment between 2 grid nodes
			step_lat should be negative (North to South)
			step_lon should be positive (West to East)
-line 7	nbl, nbp	2i10	number of lines and pixels of the grid
			lines are in the north-south direction
			pixels are in the west-east direction
For each field	•		
-line 1	_	ter*12	parameter name, one of the following:
			T = temperature
			HU = humidity
			P = pressure
			ALTITUDE = altitude over sea level
-line 2	charac	ter*12	level type one of the following:
			ISOBARE
			SURFACE

MER = sea level

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HAUTEUR = altitude above surface

-line 3 integer i8 level value with respect to the level type

ex: 850 with level type ISOBARE means 850hPa

ex: 10 with level type HAUTEUR means 10m above

surface

-line 4 to n integer values of the field in an array of (pixels, lines)

where pixels are on a parallel and lines on a meridian

 $latitude \ of \ array(i,j) \ = lat1 + (step_lat * (j-1))$

longitude of array $(i,j) = lon1 + (step_lon * (i-1))$

format 20i4 unless format 16i5 for Z and P

storage units are: temperatures are K * 10

pressures are hPa*10

humidity in percentage * 10

land-sea in percentage

altitude in meters

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46. FORMAT OF THE MAPQUAL_NOAA*XX***.TXT FILE**

(See also general information in the paragraph named "interfaces" of the *AAPP software description document*)

One line added at each AAPP run. format of one data line = (i4,2i3.2,i6.5,57f5.2)

Type

C : character I4 : integer 4

R : real

DP: double precision

Type	Format	Meaning
I4	i4	Year.
I4	i3.2	Month
I4	i3.2	Day
I4	i6.5	Orbit number at the start of dataset
R	f5.2	Global standard deviation of the
		differences (HIRS channel 8 – AVHRR channel 4),
	56650	No difference between pixels
К	3013.2	Standard deviation of the differences (HIRS channel 8 – AVHRR channel 4), for each column of pixels.
	I4 I4 I4 I4	I4 i4 I4 i3.2 I4 i3.2 I4 i6.5 R f5.2