Source demo segmentation

Right Arm

Parallel: pick cube
Ref object: blue cube

Parallel: place cube
Ref object: tray

Coordination: lift tray
Ref object: tray

Full Demo

Left Arm
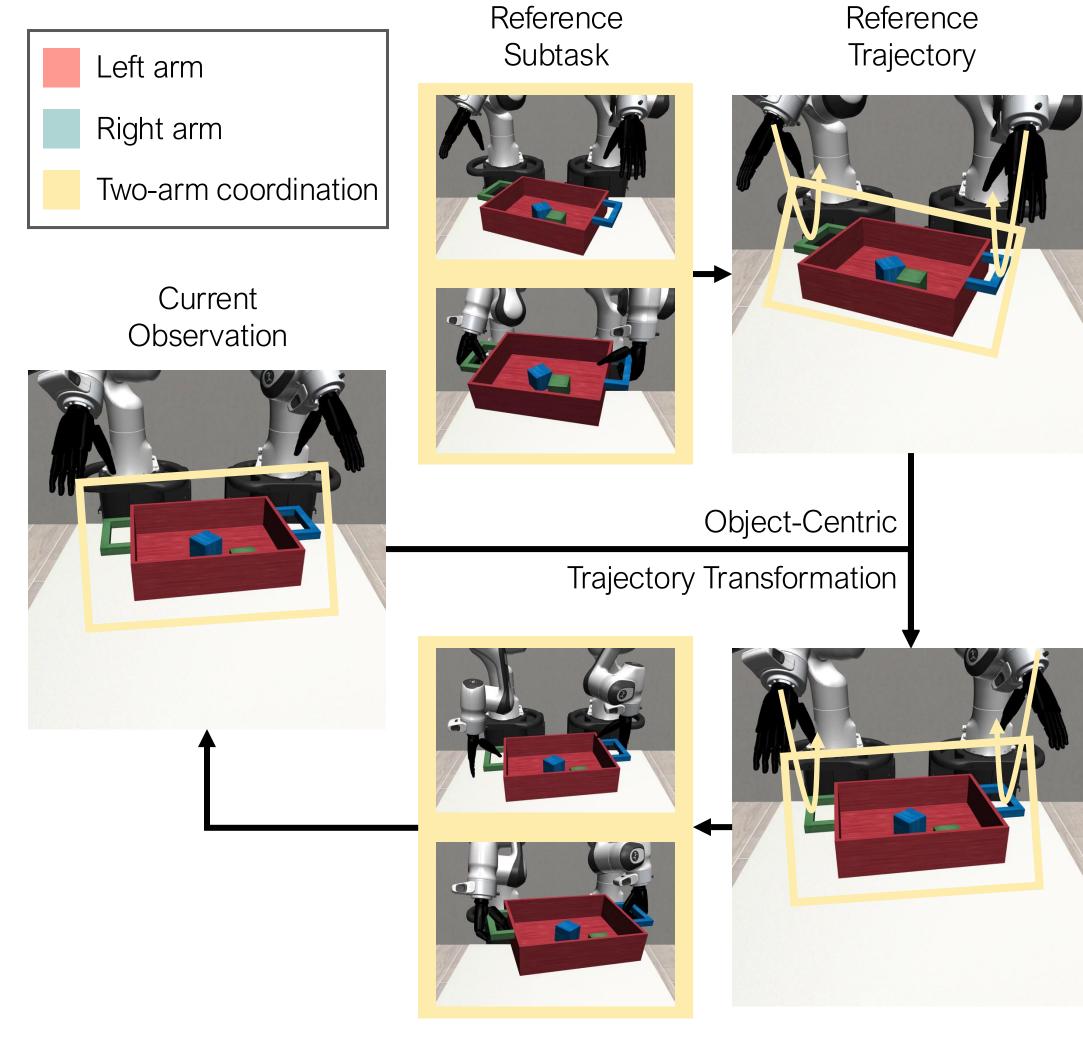
Parallel: pick cube
Ref object: green cube

Parallel: place cube
Ref object: tray

Coordination: lift tray
Ref object: tray

New trajectory generation and execution

Left arm
Right arm
Two-arm coordination

Reference Subtask

Reference Trajectory

Current Observation

Object-Centric Trajectory Transformation

Executed Trajectory

Generated Trajectory