

## 14. Random Variable and Probability Functions

- Random Variable
- Discrete distribution (p.m.f.)
- Continuous distribution (p.d.f. and c.d.f.)
- expected value

### 1. Random Variable:

#### Definition

Given a random experiment with an outcome space  $S$ ,  
a function  $X$  that assigns one and only one real number  
 $X(s) = x$  to each element  $s$  in  $S$  is called a  
random variable. i.e.

$$\begin{array}{ccc} s & \xrightarrow{X} & x = X(s) \\ s \in S & & x \in \mathbb{R} \end{array}$$

How to understand this?

- r.v.  $X$  represents all the outcomes from an experiment
- If the outcomes are numerical, keep them how they are.
- If the outcomes are categorical, assign real numbers. (Encoding)

Type of Random Variables (Data) :

Discrete { Numerically Discrete : outcomes of rolling a die  
Binary : outcome is Yes or No ( $\rightarrow$  1 or 0)  
Categorical : outcome is mutually exclusive labels  
Ordinary : categorical data that admits a natural ordering

Continuous - Outcomes that maps naturally on a real number

line. Height, weight, Age, Time  
or any numerical measurements that  
can not be concluded with limited  
number of categories.

Remark: All statistical / machine learning methods are using  
math equations. you need a NUMBER to represent  
your data to plug in.

## 2. Probability Distribution.

When performing a random experiment, what's gonna happen?

- Possible Outcomes ( r.v.  $X$  and its values)
- chance of each outcome ( probability)

A probability distribution fully describe the outcomes of an experiment

by giving

$$- x \in \{ x: X(s) = x, s \in S \}$$

$$- \text{p.m.f or p.d.f. } f(x)$$

### 3. Discrete Distribution

For a r.v.  $X$  that has discrete values  $\{x\}$ ,

the probability mass function (p.m.f.)

$$f(x) = P(X = x)$$

that satisfies:

$$(a) \quad f(x) > 0, \quad x \in S_x$$

$$(b) \quad \sum_{x \in S_x} f(x) = 1$$

$$(c) \quad P(X \in A) = \sum_{x \in S_A} f(x)$$

Ex 1. Roll a die twice and let  $X$  equal the larger outcome when different or the common value when the same, give the distribution of  $X$ .

- Possible values (outcomes) of  $X$ :

$$S = \{1, 2, 3, 4, 5, 6\}$$

- p.m.f of each  $x \in S$ .

$$f(x) = P(X=x)$$

$$f(1) = P(X=1) = \frac{1}{36}$$

$$f(2) = P(X=2) = \frac{3}{36}$$

$$f(3) = P(X=3) = \frac{5}{36}$$

$$f(4) = P(X=4) = \frac{7}{36}$$

$$f(5) = P(X=5) = \frac{9}{36}$$

$$f(6) = P(X=6) = \frac{11}{36}$$

The distribution of  $X$ :

$x$	1	2	3	4	5	6
$f(x)$	$\frac{1}{36}$	$\frac{3}{36}$	$\frac{5}{36}$	$\frac{7}{36}$	$\frac{9}{36}$	$\frac{11}{36}$

or the p.m.f. of the distribution of  $X$  is:

$$f(x) = \frac{2x-1}{36}, \quad x = 1, 2, 3, 4, 5, 6$$

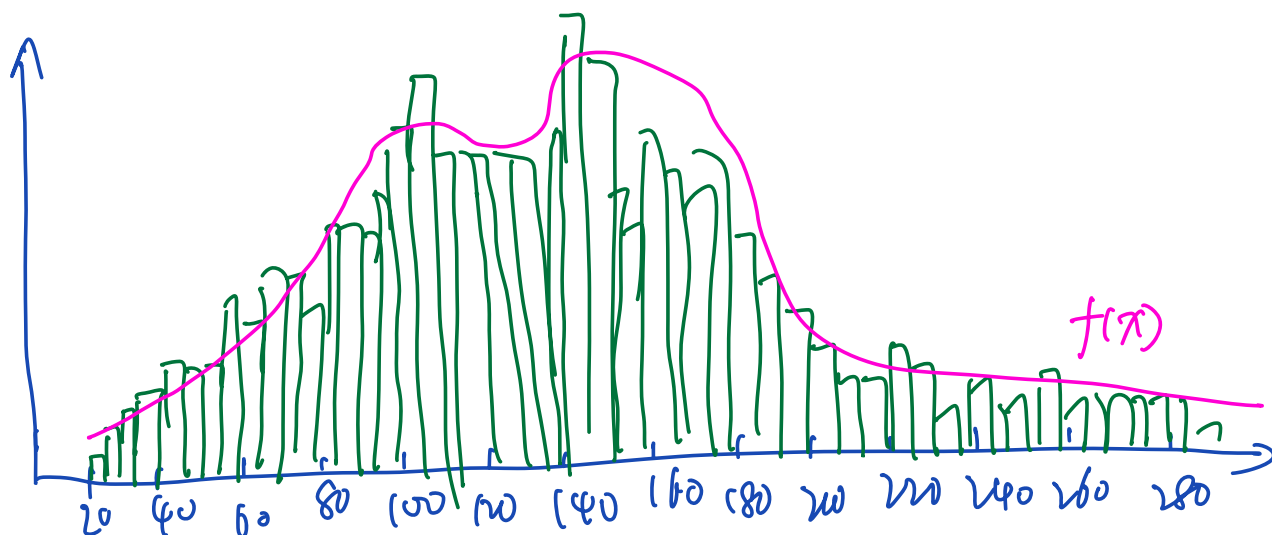
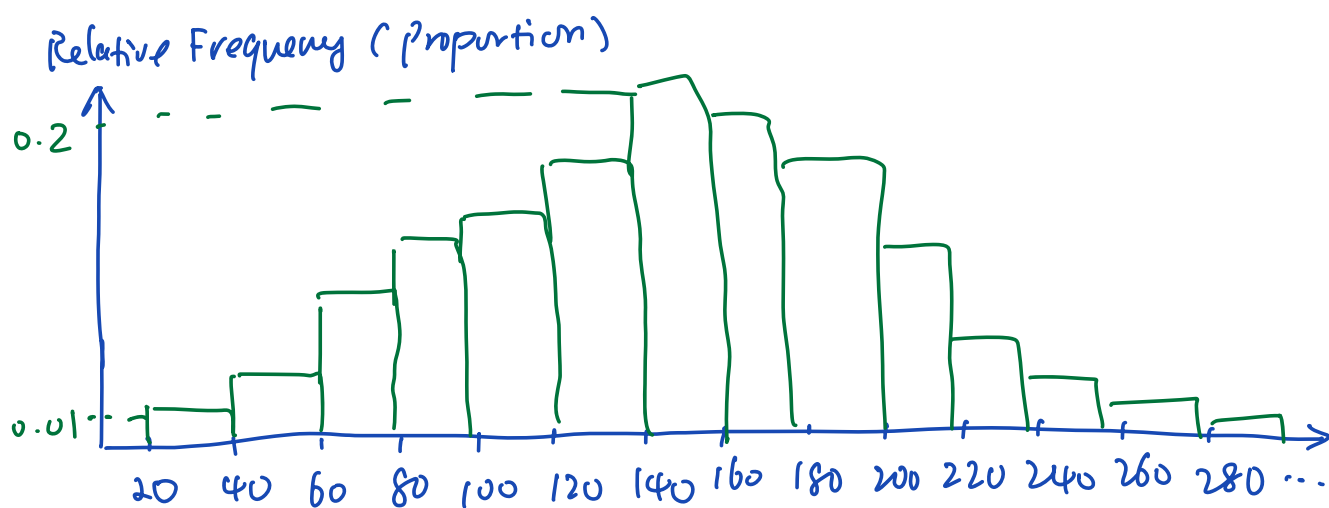
#### 4. Continuous Distribution

**Ex 2** Consider the distribution of human weights

— we know the values are more or less

continuous in a range

— can we give  $P(X=a)$  for some  $a$ ?



$$P(a \leq X \leq b) = \int_a^b f(x) dx$$

For a r.v.  $X$  that has continuous distribution,  
the probability density function (p.d.f.) is  
an integrable function  $f(x)$  satisfying:

$$(a) \quad f(x) > 0$$

$$(b) \quad \int_S f(x) = 1$$

$$(c) \quad \forall (a, b) \subseteq S, \text{ then}$$

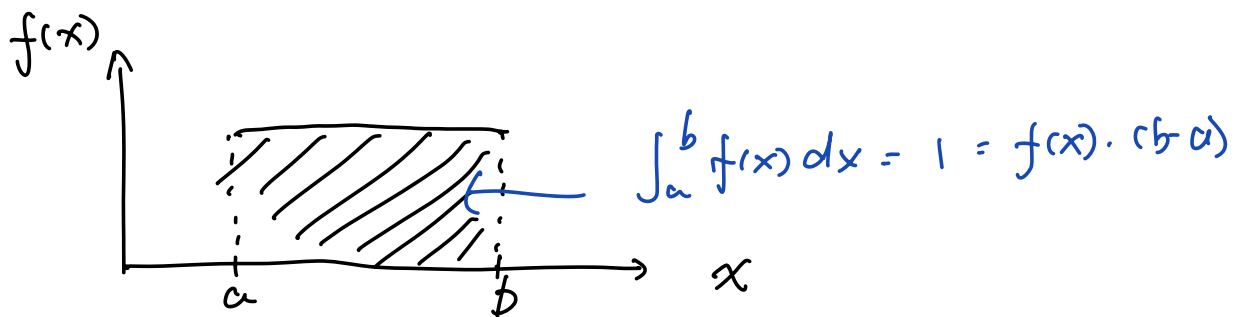
$$P(a < X < b) = \int_a^b f(x) dx$$

In rare cases, you can figure out the p.d.f. directly:

Ex 3 Uniform distribution

Let r.v.  $X$  denote the outcome when a point is selected at random from an interval  $[a, b]$  and the prob. that each point get picked is the

same:



$$f(x) = \frac{1}{b-a}, \quad a \leq x \leq b$$

But most cases, the commonly used continuous distribution are pre-defined to try to match the shape of different data. (Instead of giving a experiment, figure out a new distribution). Those



pre-decisions rely on some characteristics that could help decide the shape / behavior of the data.

We call them parameters of a distribution.

### 5. Expected Value

Informally, expected value is the mean of the outcomes when repeating the experiment infinitely many times (sample mean of a sample size  $n \rightarrow \infty$ )

Mathematically, this can be found using

- all the possible outcomes
- prob. of each outcome

Def. The expected value of a r.v.  $X$  is  $E(X)$  or  $\mu$   
— when  $X$  is discrete, and with p.m.f.  $f(x)$

$$E(X) = \sum_{x \in S} x \cdot f(x)$$

— when  $X$  is continuous and with p.d.f.  $f(x)$

$$E(X) = \int_S x \cdot f(x) dx$$

Ex 4 Bernoulli Distribution:

$X$  is the outcome of a random experiment

that has binary outcomes.:

$x$	0	1
$f(x)$	$1-p$	$p$

parameter that  
decides the

bernoulli distribution

$$\begin{aligned}\text{Expected value } E(x) &= \sum x \cdot f(x) \\ &= 0 \cdot (1-p) + 1 \cdot p \\ &= p\end{aligned}$$

Revisite Ex 3 Uniform distribution

$$\begin{aligned}E(x) &= \int_a^b x \cdot f(x) dx \\ &= \int_a^b x \cdot \frac{1}{b-a} dx \\ &= \frac{x^2}{2(b-a)} \Big|_a^b\end{aligned}$$

$$= \frac{b^2 - a^2}{2(b-a)}$$

$$= \frac{a+b}{2}$$

Properties of expected value (IMPORTANT!)

(i) For a function of the r.v.  $X$ ,

i.e.  $u(X)$ ,

$$E(u(X)) = \sum u(x) \cdot f(x)$$

$$\text{or} \\ = \int_S u(x) f(x) dx$$

Ex: Bernoulli( $p$ ) or  $b(1, p)$ .

$$E(X^2) = \sum x^2 \cdot f(x)$$

$$= (0)^2 \cdot (1-p) + (1)^2 \cdot (p)$$

$$= p$$

(2) If  $c$  is a constant,  $E(c) = c$

proof:

$$E(c) = \sum c \cdot f(x)$$

$$= c \cdot \sum f(x)$$

$$= c \cdot 1$$

$$= c$$

(3)  $E[c \cdot u(x)] = c \cdot E(u(x))$

proof?

(4)  $E[c_1 u_1(x) + c_2 u_2(x)]$

$$= C_1 E(u_1(x)) + C_2 E(u_2(x))$$

b. c.d.f.

The cumulative distribution function (c.d.f.) is another way to present the information on probability in a distribution:

$$F(x) = P(X \leq x)$$

discrete  
↓

$$= \begin{cases} \sum_{t \leq x} P(X=t) = \sum_{t \leq x} f(t) \\ \int_{-\infty}^x f(t) dt \end{cases}$$

↑  
continuous

• For  $x$  values for which  $F'(x)$  exists,  $F'(x) = f(x)$

### Revisit Ex. 3 Uniform distribution

$$X \sim \text{Uniform}[a, b]$$

so far we have:

$$\text{p.d.f. } f(x) = \frac{1}{b-a}, \quad x \in [a, b]$$

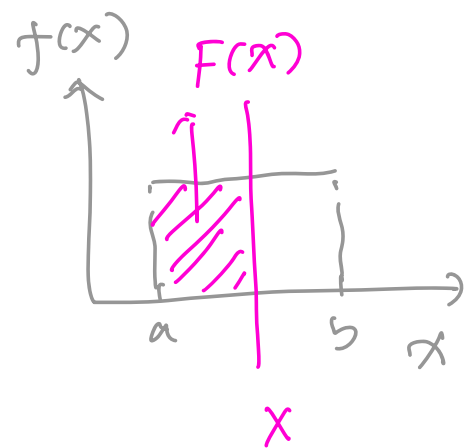
$$\text{expected value } \mu = \frac{a+b}{2}$$

$$F(x) = \int_{-\infty}^x f(t) dt$$

$$= \int_a^x \frac{1}{b-a} dt$$

$$= \left. \frac{t}{b-a} \right|_a^x$$

$$= \frac{x-a}{b-a}$$



C.d.f.  $F(x) = \frac{x-a}{b-a}$ ,  $x \in [a, b]$

### Properties of c.d.f.

(1)  $F$  is a non-decreasing function, i.e.

$$\text{if } s \leq t, \quad F(s) \leq F(t)$$

$$(2) \quad \lim_{t \rightarrow -\infty} F(t) = 0$$

$$(3) \quad \lim_{t \rightarrow \infty} F(t) = 1$$

Application Simulate data from given distribution

• Idea: If  $F(x) = P(X \leq x) = p$

$$\text{then } x = F^{-1}(p)$$



known  
c.d.f  
and its inverse

any given prob.  
 $\in [0, 1]$

To simulate data of size  $n$  from given distribution (c.k.a. given c.d.f.)

(1) given  $n$  random numbers from  $[0, 1]$ :

$p_1, p_2, \dots, p_n$  (with replacement)

(2) for each  $p_i$ ,  $x_i = F^{-1}(p_i)$

### Inverse Transformation Sampling

For a r.v.  $X$  with c.d.f.  $F_X(\cdot)$ , and

r.v.  $U \sim \text{Uniform } [0, 1]$

$F_x^{-1}(U) \sim \text{the distribution of } X$

[Ex] Discrete Case -  $F^{-1}$  is not well-defined

We want to generate (simulate) a  
sample of  $(X)$  from a random variable

that follows the distribution:

$$f(x) = \frac{4-x}{6}, \quad x=1, 2, 3$$

From previous class, we know

$$F_x(x) = \begin{cases} 0 & x < 1 \\ \frac{1}{2} & 1 \leq x < 2 \\ \frac{5}{6} & 2 \leq x < 3 \\ 1 & x \geq 3 \end{cases}$$

- generate  $p \sim \text{Uniform}(0, 1]$

- if  $\left\{ \begin{array}{l} 0 < p < \frac{1}{2}, \text{ fail} \\ \frac{1}{2} \leq p < \frac{5}{6}, \text{ generate sample } x=1 \\ \frac{5}{6} \leq p < 1, \text{ generate } x=2 \\ p=1, \text{ generate } x=3 \end{array} \right.$

## Ex Continuous Case

$$X \sim \exp(\lambda = 2) \quad , \quad f(x) = 2e^{-2x} \quad , \quad x \geq 0$$

$$F_X(x) = 1 - e^{-2x}$$

- generate  $p \sim \text{Uniform}(0, 1)$

$$- X = F_X^{-1}(p) = - \frac{\ln(1-p)}{2}$$