# QoS-aware Mobile Edge Computing System: Multi-user Multi-server Scenario

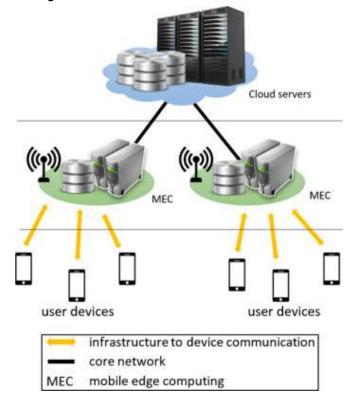
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## **Abstract**

- \* Mobile Edge Computing (MEC) System
  - Provide computational resources at the edge of RAN.
- \* Construct a QoS-aware MEC system
  - \* Task offloading
  - \* Resource Allocation
  - Load Distribution



# **System Model**

#### **\*** Three major parts:

#### \* Multiuser system

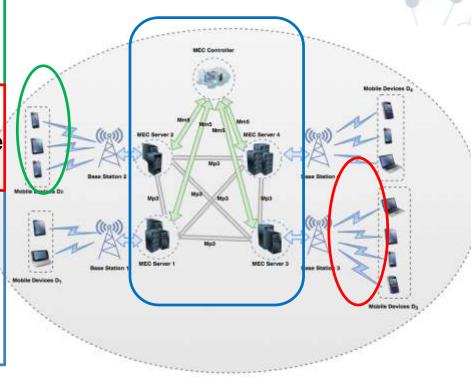
+ Each base station serves a different number of mobile devices.

#### Multi-channel system

Each base station provides multiple sub-channels.

#### \* Multi-server system

- Servers are controlled by our MEC Controller.
- Servers are interconnected with each other.



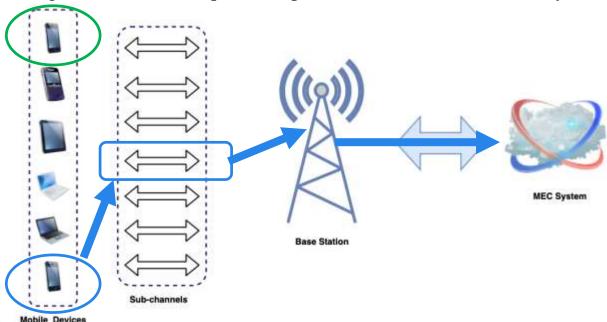
## **Problem Description**

#### \* Offloading Decision Problem

\* Each device can select either *local execution* or **remote execution** (*offloading*).

#### **\* Resource Allocation**

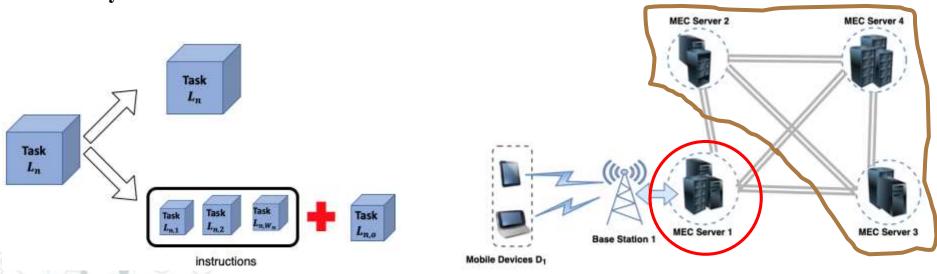
- \* Each offloading device should pick one sub-channel to transmit its task.
- \* Each offloading device should acquire computational resources on MEC system for execution.



# **Problem Description – (cont.)**

#### **\*** Load Distribution

- \* MEC servers can divide a task into some instructions.
  - + There will be one additional instruction for gathering the output results.
- \* Each task or instruction can be executed on *Local MEC Server* or be further distributed to other servers (*Nearby MEC Server*)
  - **Local MEC Server**: the server directly connected to the BS which serves the device.
  - + Nearby MEC Server: the server connected with Local MEC Server.



## **Definition of QoS**

\* The QoS in our work is related to the following three features:

## \* Execution Delay

Lower execution delay implies better QoS.

## \* Delay Tolerance

→ Different tasks have different delay tolerance.

## \* Residual Energy

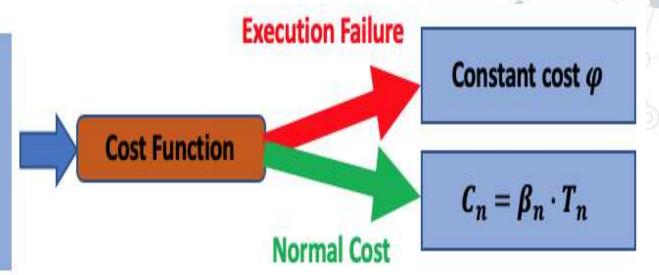
Many mobile devices do not have much energy to run applications.

## **Cost Function**

#### **\* Cost function:**

Completion time:  $T_n$ Delay tolerance:  $T_n^{max}$ Energy consumption:  $E_n$ 

Residual energy:  $E_n^R$ 



- \* The lower the cost is, the better QoS is achieved.
- \* The cost of failed task  $\varphi$  is much greater than normal cost.
- \* The weight  $\beta_n$  is negatively correlated with delay tolerance.

## **Proposed Algorithm**

\* Three steps in our algorithm:

Inside each MEC Server

**Devices Classification & Priority Assignment Radio Resource Allocation Among multiple MEC Servers** 

Load Distribution & Computation Resource Allocation

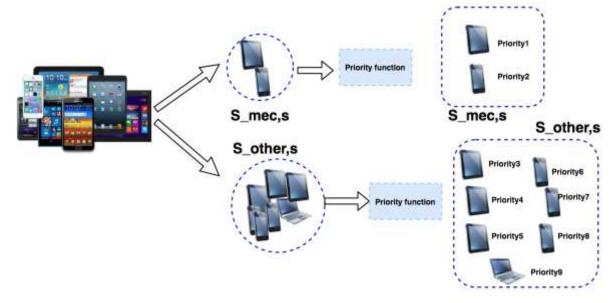
## **Devices Classification & Priority Determination**

#### \* Devices Classification

- \* Two subsets:  $S_{mec,s}$  and  $S_{other,s}$
- \* The devices belong to  $S_{mec,s}$  don't have enough resources or energy.

## \* Priority Determination

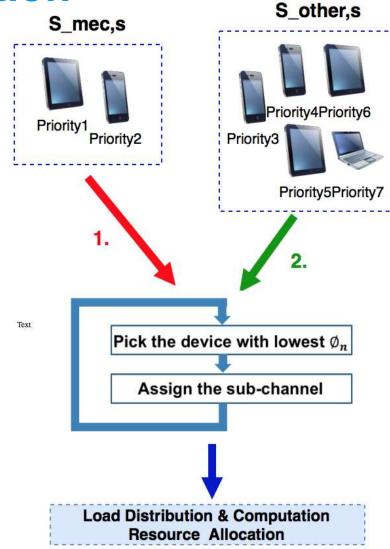
\* The devices with lower  $\emptyset_n$  values have higher priority to offload their tasks.



## **Radio Resource Allocation**

### \* Radio Resource Allocation

- \* Firstly, assign sub-channels to the devices in  $S_{mec,s}$
- \* After assignment for  $S_{mec,s}$ , we'll next consider  $S_{other,s}$ .



## **Load Distribution & Computation Resource Allocation**

#### \* Load Distribution

- (1) Full Task Assignment: Assign tasks to their Local MEC Server in ascending order of  $\Delta_n$
- (2) Full Task Distribution: Distribute unserved tasks to other server with adequate resources.
- (3) Partial Task Distribution: Divide unserved tasks into small instruction and distribute them to server with adequate resources.

#### \* Computation Resource Allocation

\* Adopt Lagrange Multiplier.

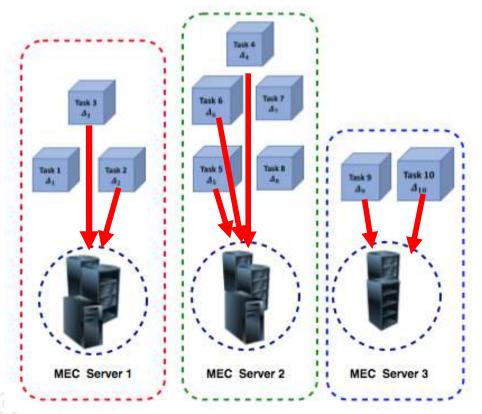
## **Load Distribution – sub-step 1**

## \* Full Task Assignment

lpha First, assigning tasks to their Local MEC Server in ascending order of  $\Delta_n$ 

 $\Delta_n$  is the minimum required resources to complete the task within its delay

tolerance.



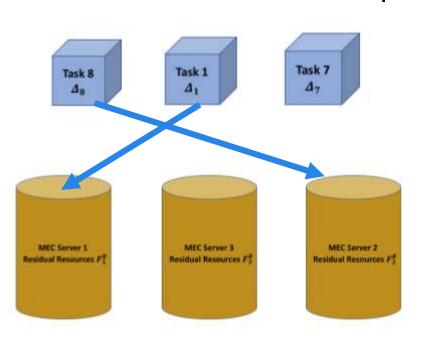
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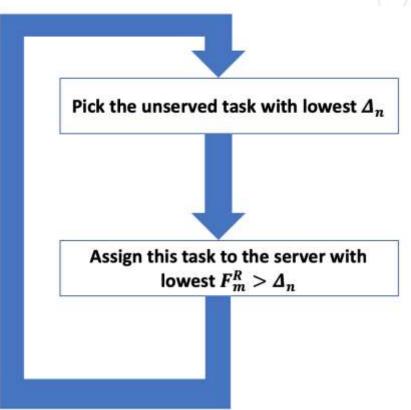
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## Load Distribution – sub-step 2

#### **\* Full Task Distribution**

\* After assignment in each server, we'll distribute unserved tasks to other servers with adequate resources.

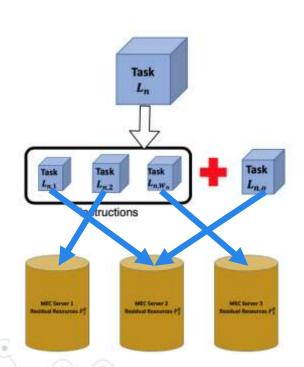


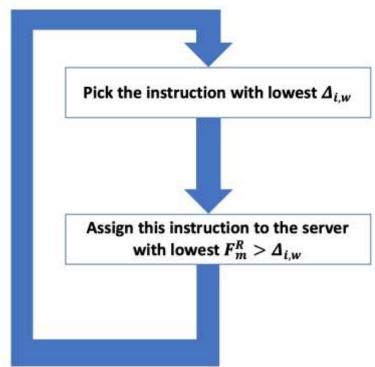


## **Load Distribution – sub-step 3**

#### \* Partial Task Distribution

\* After Full Task Distribution, MEC will divide unserved tasks into instructions and distributed them to servers with adequate resources.





## **Load Distribution & Computation Resource Allocation**

#### \* Load Distribution

- (1) Full Task Assignment: Assign tasks to their Local MEC Server in ascending order of  $\Delta_n$
- (2) Full Task Distribution: Distribute unserved tasks to other server with adequate resources.
- (3) Partial Task Distribution: Divide unserved tasks into small instruction and distribute them to server with adequate resources.

### **\* Computation Resource Allocation**

\* Adopt Lagrange Multiplier.

# **Simulation Settings**

#### **\* Scenario:**

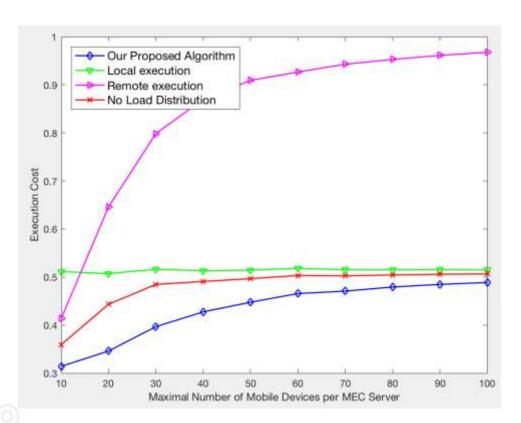
- $\gg$  Number of the BSs M=5
- \* Number of the sub-channel H = 15

#### **\* Comparison schemes:**

- **\*** Local execution
  - Tasks would be executed only on local mobile device
- **Remote execution** 
  - → Tasks would be always offloaded to MEC system.
- **No Load Distribution** 
  - Tasks would be executed on local mobile devices or their Local MEC Server.

# **Simulation Results** (Execution Cost)

- \* Execution cost of a task is defined by our cost function.
- \* Following Uniform Distribution  $unif\{x-10,x\}, x=maximal\ number.$



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# **Simulation Results** (User Satisfaction)

\* User satisfaction: The percentage of complete tasks.

